

Implementation of Algorithms for Right-Sizing Data Centers

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Outline

Motivation

Problem

Model

Algorithms

Results

Future work

Motivation

- data centers use between 1% and 3% of global energy¹, which is estimated to increase²

¹Arman Shehabi et al. *United States Data Center Energy Usage Report*. Tech. rep. Lawrence Berkeley National Laboratory, June 2016.

²Nicola Jones. “How to stop data centres from gobbling up the world’s electricity”. In: *Nature* 561.7722 (2018), pp. 163–167.

³Josh Whitney and Pierre Delforge. *Data Center Efficiency Assessment*. Natural Resources Defense Council, Aug. 2014.

⁴Luiz André Barroso and Urs Hölzle. “The case for energy-proportional computing”. In: *Computer* 40.12 (2007), pp. 33–37.

Motivation

- data centers use between 1% and 3% of global energy¹, which is estimated to increase²
- most data centers are statically provisioned, leading to average utilization levels between 12% and 18%³

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Motivation

- data centers use between 1% and 3% of global energy¹, which is estimated to increase²
- most data centers are statically provisioned, leading to average utilization levels between 12% and 18%³
- typically servers operate at energy efficiency levels between 20% and 30%⁴

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- data centers use between 1% and 3% of global energy¹, which is estimated to increase²
- most data centers are statically provisioned, leading to average utilization levels between 12% and 18%³
- typically servers operate at energy efficiency levels between 20% and 30%⁴
- when idling, servers consume half of their peak power⁴

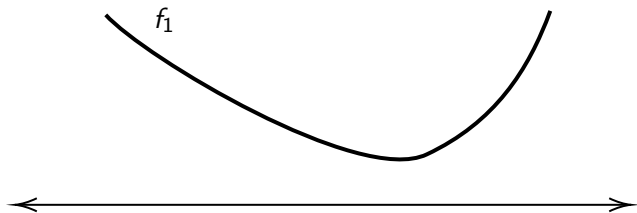
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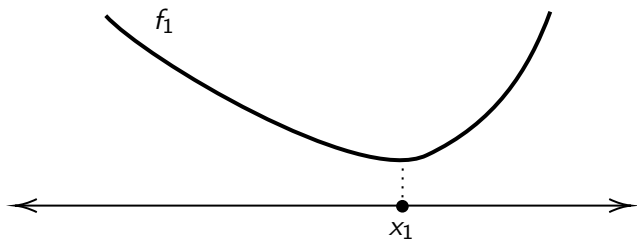
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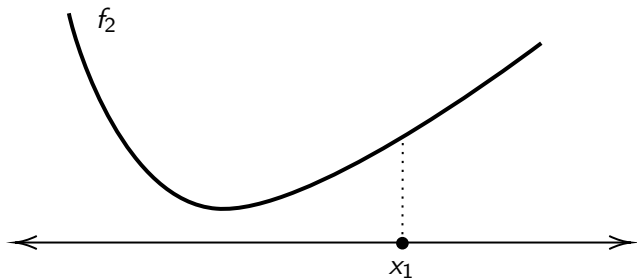
Problem



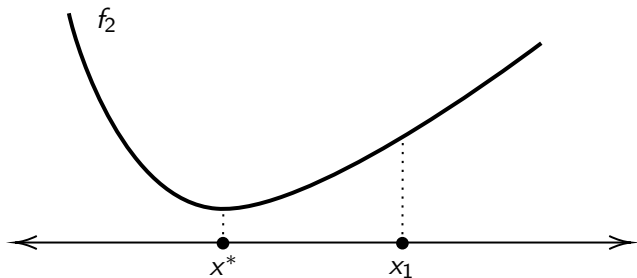
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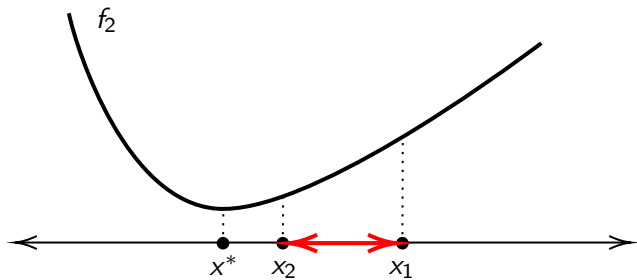
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Problem



Model

What is the cost of operating a data center with $x_t \in \mathbb{N}_0$ active servers and under load $\lambda_t \in \mathbb{N}_0$?

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What is the cost of operating a data center with $x_t \in \mathbb{N}_0$ active servers and under load $\lambda_t \in \mathbb{N}_0$?

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Model

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- How to distribute jobs across the active servers?
Distribute evenly across all servers of the same type⁵.

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Consisting of energy costs and the revenue loss incurred by a delayed processing of jobs.

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Movement costs are on the order of operating an idling server for 1-4 hours⁶.

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Algorithms for one dimension

problem	algorithm	results
fractional		
integral		

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⁸Nikhil Bansal et al. "A 2-competitive algorithm for online convex optimization with switching costs". In: *Approximation, Randomization, and Combinatorial Optimization. Algorithms and Techniques (APPROX/RANDOM 2015)*. Schloss Dagstuhl-Leibniz-Zentrum fuer Informatik. 2015.

⁹Lachlan Andrew et al. "A tale of two metrics: Simultaneous bounds on competitiveness and regret". In: *Conference on Learning Theory*. PMLR. 2013, pp. 741–763.

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Algorithms for one dimension

problem	algorithm	results
fractional	Lazy Capacity Provisioning ⁷	3-competitive
integral		

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Algorithms for one dimension

problem	algorithm	results
fractional	Lazy Capacity Provisioning ⁷	3-competitive
	Memoryless ⁸	3-competitive
integral		

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Algorithms for one dimension

problem	algorithm	results
fractional	Lazy Capacity Provisioning ⁷	3-competitive
	Memoryless ⁸	3-competitive
	Probabilistic ⁸	2-competitive
integral		

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Algorithms for one dimension

problem	algorithm	results
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	Probabilistic ⁸	2-competitive
	Randomly Biased Greedy ⁹ , $\theta \geq 1$	$(1 + \theta)$ -competitive, $\mathcal{O}(\max\{T/\theta, \theta\})$ -regret
integral		

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integral	Lazy Capacity Provisioning ¹⁰	3-competitive
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Algorithms for multiple dimensions

problem	algorithm	results
integral; linear, time-indep. cost		
integral; hom. load		
fractional; α -loc. polyhedral costs; ℓ_2 movement		
fractional; prediction window		

¹¹Susanne Albers and Jens Quedenfeld. “Algorithms for Energy Conservation in Heterogeneous Data Centers.”. In: *CIAC*. 2021, pp. 75–89.

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Algorithms for multiple dimensions

problem	algorithm	results
integral; linear, time-indep. cost	Lazy Budgeting ¹¹ (deterministic)	$2d$ -competitive
integral; hom. load		
fractional; α -loc. polyhedral costs; ℓ_2 movement		
fractional; prediction window		

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	Lazy Budgeting ¹¹ (randomized)	$\approx 1.582d$ -competitive
integral; hom. load		
fractional; α -loc. polyhedral costs; ℓ_2 movement		
fractional; prediction window		

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integral; hom. load	Lazy Budgeting ¹²	$(2d + 1 + \epsilon)$ -competitive
fractional; α -loc. polyhedral costs; ℓ_2 movement		
fractional; prediction window		

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fractional; α -loc. polyhedral costs; ℓ_2 movement	Primal OBD ¹³	$3 + \mathcal{O}(1/\alpha)$ -competitive
fractional; prediction window		

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	Dual OBD ¹³	$\mathcal{O}(\sqrt{T})$ -regret
fractional; prediction window		

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fractional; α -loc. polyhedral costs; ℓ_2 movement	Primal OBD ¹³	$3 + \mathcal{O}(1/\alpha)$ -competitive
	Dual OBD ¹³	$\mathcal{O}(\sqrt{T})$ -regret
fractional; prediction window	RHC ¹⁴	$(1 + \mathcal{O}(1/w))$ -competitive in $1d$

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fractional; prediction window	RHC ¹⁴	$(1 + \mathcal{O}(1/w))$ -competitive in 1d
	AFHC ¹⁴	$(1 + \mathcal{O}(1/w))$ -competitive

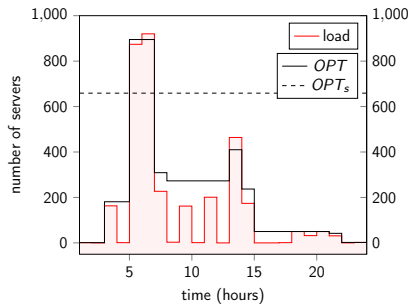
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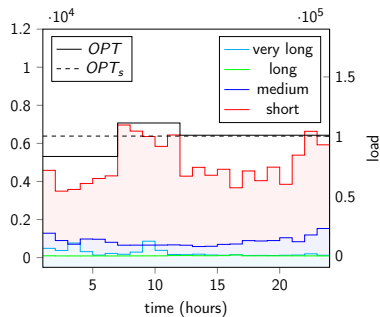
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Traces



(a) LANL Mustang



(b) Alibaba

Performance metrics

- normalized cost: $c(ALG)/c(OPT)$

Performance metrics

- normalized cost: $c(ALG)/c(OPT)$
- cost reduction:

$$\frac{c(OPT_s) - c(ALG)}{c(OPT_s)}$$

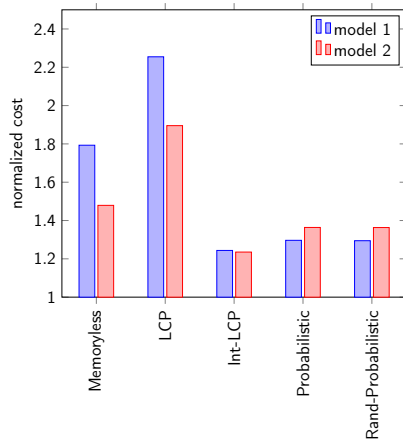
Performance metrics

- normalized cost: $c(ALG)/c(OPT)$
- cost reduction:

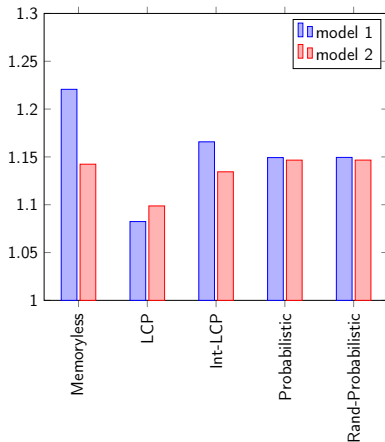
$$\frac{c(OPT_s) - c(ALG)}{c(OPT_s)}$$

- static/dynamic ratio: $c(OPT_s)/c(OPT)$

Results in one dimension

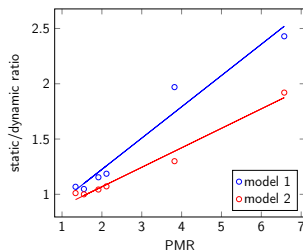


(a) LANL Mustang

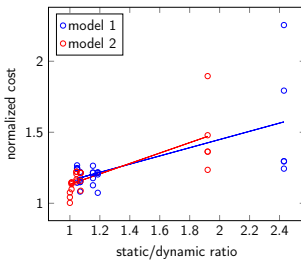
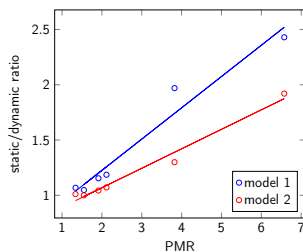


(b) Alibaba

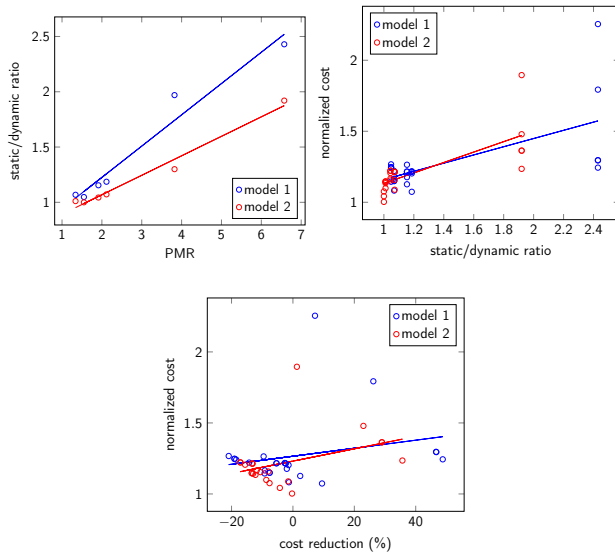
Results in one dimension



Results in one dimension



Results in one dimension



Other results

Multiple dimensions

- lazy budgeting algorithms perform nearly optimally (normalized cost $\in [1.05, 1.25]$), without consideration of revenue loss

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- robust to imperfect (realistic) predictions

Future work

- compare performance to algorithms for convex body chasing

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- performance of algorithms in other applications

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- compare performance to algorithms for convex body chasing
- performance of algorithms in other applications
- better algorithms to make use of predictions

Thanks for your attention! Questions?

Problem

Smoothed online convex optimization (or *convex function chasing*)¹⁵:

¹⁵Minghong Lin et al. "Dynamic right-sizing for power-proportional data centers". In: *IEEE/ACM Transactions on Networking* 21.5 (2012), pp. 1378–1391.

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Smoothed online convex optimization (or *convex function chasing*)¹⁵:

Given a convex decision space $\mathcal{X} \subset \mathbb{R}^d$, a norm $\|\cdot\|$ on \mathbb{R}^d , and a sequence F of non-negative convex functions $f_t : \mathcal{X} \rightarrow \mathbb{R}_{\geq 0}$

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$$\sum_{t=1}^T f_t(x_t) + \|x_t - x_{t-1}\|$$

is minimized where T is the time horizon and $x_0 = 0$.

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- fundamental incompatibility between competitive ratio and regret even for linear hitting costs in one dimension