Equivariant Graph Neural Networks

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Outline

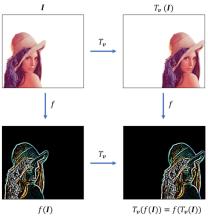
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- 4 Invariant and Equivariant Graph Networks

2 Mathematical Background

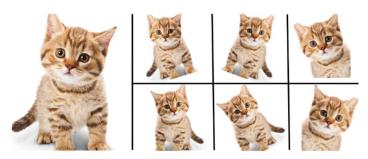
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- Our neural networks can operate on data of many types.
- We often work with images, text, audio, graphs and more.
- These data types have different structures and qualities, and we would like to build architectures that best suit them.

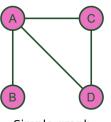


A cat is a cat no matter how you look at it.



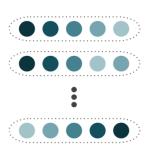
• It is acceptable to assume that being invariant to the rotation of the cat is a good property for a classification network.

• Our focus today is on sets and graph data.



Simple graph

	Α	В	С	D
Α	0	1	1	1
В	1	0	0	0
C	1	0	0	1
D	1	0	1	0



Construction of an Equivariant Neural Network

- When contructing an equivariant neural network, two things should always be considered:
 - The symmetries of the data: What inherent structure should our model be oblivious to?
 - ② The space of functions learnable by the network:

 Are we fully utilizing the space of functions that are equivariant

- 2 Mathematical Background
- Open Sets

4 Invariant and Equivariant Graph Networks

The Permutation Group S_n

- The permutation group S_n is the group of all permutations of n elements.
- It has n! elements, representing the n! ways to order n elements.
- Given a set $X = \{x_1, x_2, \dots, x_n\}$, a permutation $\pi \in S_n$ is a bijection $\pi : X \to X$
- e.g. $x = (x_1, x_2, x_3)$, and $\pi = (1, 2, 3) \in S_3$ is the permutation that maps $1 \to 2$, $2 \to 3$ and $3 \to 1$.
- We denote the **action** of π on x as $\pi x = (x_3, x_1, x_2)$.

Permutation Invariance

• Let $H \leq S_n$ be a subgroup of the symmetric group.

• $f: \mathbb{R}^n \to \mathbb{R}$ is *H*-invariant if $f(x) = f(\pi x)$ for all $\pi \in H$.

$$f[\bigcirc \bigcirc \bigcirc \bigcirc \bigcirc \bigcirc] = [0.15 \ 0.1 \ 0.05 \ 0.8]$$

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Permutation Equivariance

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Permutation of a Set

- Assume our set is $X = \{x_1, x_2, \dots, x_n\}$.
- We can represent X as a matrix $X \in \mathbb{R}^{n \times d}$.
- Any permutation $g \in S_n$ can be represented as a permutation matrix $\mathbf{P} \in \mathbb{R}^{n \times n}$,
- The action of g on X is then **P**X.
- An invariant neural network is a function $f: \mathbb{R}^{n \times d} \to \mathbb{R}^{d'}$ such that f(X) = f(PX).
- An equivariant neural network is a function $f: \mathbb{R}^{n \times d} \to \mathbb{R}^{n \times d'}$ such that $\mathbf{P}f(X) = f(\mathbf{P}X)$.



Permutation of a Graph

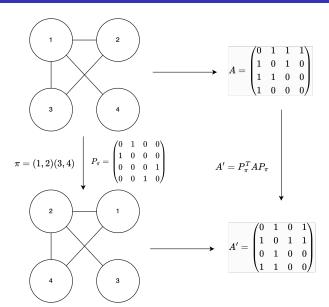
• Our data is now a graph adjacency matric $A \in \mathbb{R}^{n \times n}$.

• A permutation matrix $P \in \mathbb{R}^{n \times n}$ acts on the adjacency matrix A.

• The action of **P** on A is:

$$P^TAP$$

Permutation of a Graph



Equivariant Network Construction

Theorem

Let L be a linear equivariant layer, and let f be a neural network constructed be stacking L and non-linearities σ . Then f is permutation equivariant.

Proof.

Let x be a set of n elements, and let $g \in S_n$ be a permutation.

$$f(gx) = L(\sigma(L(\sigma(\ldots L(gx)\ldots)))) = L(\sigma(L(\ldots g\sigma(L(x))\ldots))) = \ldots$$
$$gL(\sigma(L(\sigma(\ldots L(x)\ldots)))) = gf(x)$$



Invariant Network Construction

Theorem

Let f be an equivariant neural network and let ϕ be a permutation invariant function. Then $h = \phi(f(x))$ is a permutation invariant neural network.

Proof.

Let x be a set of n elements, and let $g \in S_n$ be a permutation.

$$h(gx) = \phi(f(gx)) = \phi(gf(x)) = \phi(f(x)) = h(x)$$



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Deep Sets

- A seminal work in the field of equivariant neural networks.
- Recall the two properties we mentioned earlier (symmetries of the data and the space of functions learnable by the network).
- DeepSets is an architecture that is equivariant to set permutations and is maximally expressive in the space of permutation equivariant functions.
- We are going to see the construction and prove it satisfies equivariance and expressiveness.

- We saw a general structure of an invariant and equivariant network.
- ullet To fill in the details, we need to define the equivariant layer L and the invariant function ϕ .

Definition

Consider a set $x = \{x_1, x_2, \dots, x_n\}$, where $x_i \in \mathbb{R}$. Define its representation $\mathbf{x} = (x_1, \dots, x_n) \in \mathbb{R}^n$.

A DeepSets layer is defined as

$$L(x) = \lambda I x + x \mathbf{1}$$



Definition

Consider a set $x = \{x_1, x_2, \dots, x_n\}$, where $x_i \in \mathbb{R}$.

A DeepSets layer is defined as

$$L(x) = \lambda Ix + x1$$

Theorem

A DeepSets layer is permutation equivariant.

Proof.

Let x be a set of n elements, and let $g \in S_n$ be a permutation.

$$L(gx) = \lambda I(gx) + (gx)\mathbf{1} = g(\lambda Ix) + x\mathbf{1} = gL(x)$$



Theorem

Any linear equivariant layer is of the shape $L(x) = \lambda Ix + x1$.

Proof (through example).

Let $\mathbf{x} = x_1, x_2, x_3$ be a set, $W \in \mathbb{R}^{3\times 3}$, and $L(x) = W\mathbf{x}$ such that L is

equivariant,
$$W = \begin{pmatrix} a & b & c \\ d & e & f \\ g & h & i \end{pmatrix}$$
 Consider permutation $g = (2,3) \in S_3$.

Note that
$$g\left(W\begin{pmatrix}x_1\\x_2\\x_3\end{pmatrix}\right)_1=(Wx)_1=(Wgx)_1=\left(W\begin{pmatrix}x_1\\x_3\\x_2\end{pmatrix}\right)_1$$
 from

equivariance.



Proof (through example) - continued.

The previous equation can be written as:

$$ax_1 + bx_2 + cx_3 = ax_1 + bx_3 + cx_2$$

This should hold for any choice of $\mathbf{x} \Rightarrow b = c$, d = f, g = h. For the permutation $\sigma = (1, 3, 2)$:

$$W(\sigma x) = W \begin{pmatrix} x_2 \\ x_3 \\ x_1 \end{pmatrix} = \begin{pmatrix} ax_2 + bx_3 + bx_1 \\ dx_2 + ex_3 + dx_1 \\ fx_2 + fx_3 + ix_1 \end{pmatrix}$$

$$\sigma W \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = (1,3,2) \begin{pmatrix} ax_1 + bx_2 + bx_3 \\ dx_1 + ex_2 + dx_3 \\ fx_1 + fx_2 + ix_3 \end{pmatrix} = \begin{pmatrix} dx_1 + ex_2 + dx_3 \\ fx_1 + fx_2 + ix_3 \\ ax_1 + bx_2 + bx_3 \end{pmatrix} \stackrel{!}{=} W \begin{pmatrix} x_2 \\ x_3 \\ x_1 \end{pmatrix}$$

Proof (through example) - continued.

We can use the same logic to show that a = e = i,

$$b = c = d = f = g = h = i$$

We get that all values in the diagonal must be equal and all values in the off-diagonal must be equal, and W must have the form:

$$W = \begin{pmatrix} a & b & b \\ b & a & b \\ b & b & a \end{pmatrix}$$



DeepSets Network

- We have an initial layer L, which we proved is equivariant.
- A deep sets invariant network is now constructed as:

$$f(x) = \phi(L\sigma(L\sigma(...L\sigma(L(x))...)))$$
 where $\phi(x) = \sum_{i=1}^{n} x_i$

- ullet It is easy to see that ϕ is permutation invariant, and thus f is permutation invariant.
- ullet For a classification network, take some classification module ho (e.g. an MLP), and define the final network as:

$$h(x) = \rho(f(x))$$

DeepSets Network

• Notice that the network is only defined for sets with elements in \mathbb{R} .

• We can extend this to a set $X = \{x_1, x_2, \dots x_n\} \subset \mathbb{R}^d$ with representation $\mathbf{X} \in \mathbb{R}^{n \times d}$ by defining L as:

$$L(x) = \mathbf{X} W_1 + \mathbf{1} \mathbf{1}^T \mathbf{X} W_2$$

 This keeps the general structure of the layer: a linear transformation of the distinct elements of the set summed with the mean of the set.

DeepSets Expressivity

- We have shown that the *DeepSets* network is permutation invariant.
- We now want to show that it is maximally expressive in the space of permutation invariant functions.
- We show outline for the proof, showing DeepSets can separate any two sets that are not equal.

Theorem

Let $x, y \in \mathbb{R}^{n \times d}$ s.t $x \neq gy$ $\forall g \in S_n$. Then there exists a DeepSets network that separates x and y, namely $F(x; \theta) \neq F(y; \theta)$.

DeepSets Expressivity

Proof outline:

- Consider distinct rows of x, y.
- Onstruct input output pairs using standard basis elements (one hot encodings of the elements in the set).
- **3** In each layer $L(x) = \mathbf{X} W_1 + \mathbf{1} \mathbf{1}^T \mathbf{X} W_2$, set $W_2 = 0$, collapsing our network to a standard MLP.
- According to a result of the universal approximation theorem, we can learn a one to one mapping between the input and output pairs.
- Output for each set the sum of the output pairs.
- For each set, we computed the hitogram of its elements, which is a unique representation of the set.

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• We saw a simple, maximally expressive equivariant network for sets.

We now want to extend this to graphs.

 Recall the action of the permutation matrix *P* on the adjacency matrix *A* is:

$$P^TAP$$

• Let's use this to define a linear invariant layer $L \in \text{Hom}(\mathbb{R}^{n \times n}, \mathbb{R})$. We want to satisfy the following:

$$L(\mathbf{P}^{\mathsf{T}}A\mathbf{P})=L(A)$$

It's hard from this to understand the conditions on L.

 Recall the action of the permutation matrix *P* on the adjacency matrix *A* is:

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$$L(\mathbf{P}^{\mathsf{T}}A\mathbf{P})=L(A)$$

- It's hard from this to understand the conditions on L.
- We define an equivalent condition by column stacking the adjacency matrix to get a vector, and then looking at L's matrix representation: $\mathbf{L} \in \mathbb{R}^{1 \times n^2}$.

$$Lvec(\mathbf{P}^T A \mathbf{P}) = Lvec(A)$$

• We now introduce a crucial property of the Kronecker product:

$$\operatorname{vec}(XAY) = Y^T \otimes X \operatorname{vec}(A)$$

• Using this, the previous condition can be written as:

$$L(P^T \otimes P^T) \text{vec}(A) = L \text{vec}(A)$$

For this condition to hold for all A, we need L to satisfy:

$$L(P^T \otimes P^T) = L$$

• transposing the equation, and with severe abuse of notation $(L^T = \text{vec}(L))$, we finally get:

$$(P \otimes P) \text{vec}(L) = \text{vec}(L)$$



- After some work and moderate logic jumps, we got a condition for a permutation invariant linear layer L.
- Developing the condition for an equivariant layer $L \in \mathbb{R}^{n^2 \times n^2}$ is very similar:

$$Lvec(\mathbf{P}^T A \mathbf{P}) = \mathbf{P}^T Lvec(A) \mathbf{P}$$

Using the Kronecker product property, we get:

$$L(P^T \otimes P^T)$$
vec $(A) = (P^T \otimes P^T)L$ vec (A)

• This should hold for every A, so we get:

$$L(P^T \otimes P^T) = (P^T \otimes P^T)L$$



• $(P^T \otimes P^T)$ is an $n^2 \times n^2$ permutation matrix, and its inverse is $(P \otimes P)$.

$$(P \otimes P)L(P^T \otimes P^T) = L$$

Once again using the Kronecker product property, we get:

$$vec(L) = vec(P \otimes P)L(P^T \otimes P^T) = (P \otimes P) \otimes (P \otimes P)vec(L)$$
$$= (P \otimes P \otimes P \otimes P)vec(L)$$

- The previous conditions are developed for a matrix $A \in \mathbb{R}^{n^2}$ expressing the relations between pairs of nodes.
- We can extend this to a matrix $A \in \mathbb{R}^{n^k}$ expressing the relations between every k tuple of nodes.
- for invariant layers $L \in \mathbb{R}^{1 \times n^k}$:

$$P^{\otimes k} \operatorname{vec}(L) = \operatorname{vec}(L)$$

• for equivariant layers $L \in \mathbb{R}^{n^k \times n^k}$:

$$P^{\otimes 2k}L = \operatorname{vec}(L)$$

- We developed conditions for a permutation invariant and equivariant linear layer *L*. Call these the Fixed Point Equations.
- Unfortunately, compared to the simple structure of the *DeepSets*layer, these equations are less intepretable. Let's try and make some
 sense of them.
- The condition we got is one that determines the values of the entries of L. We want to understand what entries of L should be equal.
- For an invariant layer $L \in \mathbb{R}^{1 \times n^k}$, $L_{i_1,i_2,...,i_k}$ is the weight which multiplies entry $A_{i_1,i_2,...,i_k}$.

• The Fixed Point Equation for an invariant layer is:

$$P^{\otimes k} \operatorname{vec}(L) = \operatorname{vec}(L)$$

 The k-th permutation matrix permutes the k-th dimension of the input.

$$P^{\otimes k} \operatorname{vec}(L)_{i_1,\dots i_k} = \operatorname{vec}(L)_{\sigma(i)_1,\dots \sigma(i)_k}$$

- This partitions the entries of *L* into equivalence classes, where all entries in the same class are equal.
- For k = 2 we get 2 equivalence classes:

$$L_{i,j}$$
 where $i \neq j$ and $L_{i,i}$



- For an equivariant layer $L \in \mathbb{R}^{1 \times n^k}$, $L_{i_1,i_2,...,i_k,j_1,j_2,...,j_k}$ is the weight which multiplies entry $A_{i_1,i_2,...,i_k}$ and sends it to entry $j_1,j_2,...,j_k$ of the output.
- The Fixed Point Equation for an equivariant layer is:

$$P^{\otimes 2k} \operatorname{vec}(L) = \operatorname{vec}(L)$$

• The k-th permutation matrix permutes the k-th dimension of the input.

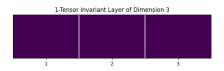
$$P^{\otimes 2k} \operatorname{vec}(L)_{i_1, i_2, \dots, i_k, j_1, j_2, \dots, j_k} = \operatorname{vec}(L)_{\sigma(i)_1, \dots \sigma(i)_k, \sigma(j)_1, \dots \sigma(j)_k}$$

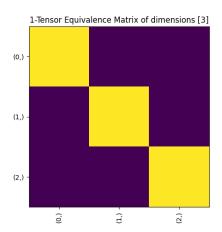
- Once again, this partitions the entries of *L* into equivalence classes.
- For k = 2 we get 15 equivalence classes:

$$\{\{1\}\{2\}\{3\}\{4\}\}, \{\{1,2\}\{3\}\{4\}\}, \{\{1\}\{2,3\}\{4\}\}\dots \{\{1,2,3,4\}\}$$

In general, the number of equivalence classes is Bell((2)k) for an (equivariant) invariant layer of order k

- Did you notice somthing similar to the DeepSets layer?
- The construction of the *DeepSets* layer is identicle to the construction of an equivariant layer of order 1.
- We managed to generalize the equivariant layer to higher orders of node connectivity.
- We also managed to generalize the invariant layer to higher orders of node connectivity.





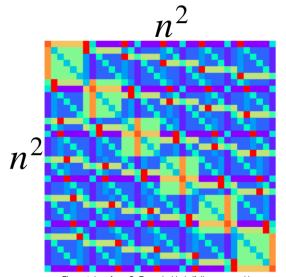


Figure taken from S. Ravanbakhsh (follow-up work)

 Let's extend the construction of the equivariant layer even further, changing between the connectivity order, adding node features, and a bias term.

 We skip a few steps, but it makes sense that the bias term should satisfy the same fixed point equation as the linear term.

$$\mathbf{P}^{T\otimes k}\mathrm{vec}(\mathbf{C})=\mathrm{vec}(\mathbf{C})$$

The main idea is that every pair of k-hyperedges which permute under some permutation should have the same bias term.

- We can also consider node features.
- The input to the layer now includes a set of *n d*-dimensional vectors.
- This is exactly the input to the *DeepSets* layer, we already know how to construct an equivariant layer for this input.
- The input to our layer is now the k-connectivity of each node, concatenated with it's feature:

$$A \in \mathbb{R}^{n^k \times d}$$

 The new general formulation, changing both the connectivity order and the feature dimensionality, is:

$$L: \mathbb{R}^{n^k \times d} \to \mathbb{R}^{n^{k'} \times d'}$$



 We intoduce some new notation, please bare with us as we will use some Nifnufey Yadaim.

- We saw certain entries of the layer matrix L are equal. In DeepSets our connectivity is of order 1, so we got 2 equivalence classes. In the standard graph case, our connectivity is of order 2, so we got 15 equivalence classes.
- These equivalence classes are completely disjoint, meaning every entry in the linear layer belongs to exactly one equivalence class.

- Let μ be some equivalence class of indices. We denote by \mathbf{M}^{μ} the binary tensor which is 1 at the indices in μ and 0 elsewhere.
- Denote by ${\bf B}^\mu, {\bf C}^\mu$ the linear layer and bias term of the layer, respectively.
- For an invariant layer $L: \mathbb{R}^{n^k \times d} \to \mathbb{R}^{n^1 \times d'}$, this defines a set of dd'Bell(k) + d' binary tensors.
- For an equivariant layer $L: \mathbb{R}^{n^k \times d} \to \mathbb{R}^{n^{k'} \times d'}$, this defines a set of dd'Bell(k+k') + d'Bell(k') binary tensors.

The full charactarization of the space of invariant and equivariant layers is:

invariant:
$$\mathbf{B}_{\boldsymbol{a},i,i'}^{\lambda,j,j'} = \begin{cases} 1 & \boldsymbol{a} \in \lambda, \ i=j, \ i'=j' \\ 0 & \text{otherwise} \end{cases} ; \quad \mathbf{C}_{i'}^{j'} = \begin{cases} 1 & i'=j' \\ 0 & \text{otherwise} \end{cases}$$
 (9a)

equivariant:
$$\mathbf{B}_{\boldsymbol{a},i,\boldsymbol{b},i'}^{\mu,j,j'} = \begin{cases} 1 & (\boldsymbol{a},\boldsymbol{b}) \in \mu, \ i=j, \ i'=j' \\ 0 & \text{otherwise} \end{cases}; \quad \mathbf{C}_{\boldsymbol{b},i'}^{\lambda,j'} = \begin{cases} 1 & \boldsymbol{b} \in \lambda, \ i'=j' \\ 0 & \text{otherwise} \end{cases}$$
(9b)

$$L(\mathbf{A})_{i'} = \sum_{\boldsymbol{a},i} \mathbf{T}_{\boldsymbol{a},i,i'} \mathbf{A}_{\boldsymbol{a},i} + \mathbf{Y}_{i'}; \quad \mathbf{T} = \sum_{\lambda,j,j'} w_{\lambda,j,j'} \mathbf{B}^{\lambda,j,j'}; \mathbf{Y} = \sum_{j'} b_{j'} \mathbf{C}^{j'}$$
(10a)

$$L(\mathbf{A})_{\mathbf{b},i'} = \sum_{\mathbf{a},i} \mathbf{T}_{\mathbf{a},i,\mathbf{b},i'} \mathbf{A}_{\mathbf{a},i} + \mathbf{Y}_{\mathbf{b},i'}; \quad \mathbf{T} = \sum_{\mu,j,j'} w_{\mu,j,j'} \mathbf{B}^{\mu,j,j'}; \mathbf{Y} = \sum_{\lambda,j'} b_{\lambda,j'} \mathbf{C}^{\lambda,j'}$$
(10b)

• Turns out the set of these binary tensors \mathbf{B}^{μ} is an orthogonal basis for the space of equivariant linear layers $L: \mathbb{R}^{n^k} \to \mathbb{R}^{n^{k'}}$

• We won't show this, but we can prove the space of invariant/equivariant layers is of dimension Bell(k')/Bell(k+k').

 The proof idea is showing the set of linear transformations is orthogonal and of the same dimension as the space of functions, making it a full basis.

- To recap what we saw so far:
- We saw the full construction linear layers which operate on graphs of a general degree of connectivity.
- Our construction supports changing between different levels of connectivity, adding node features and changing between the dimension of these features.
- The construction is also extreamly efficient. It is linear in the number of dimensions and does no depend on the number of nodes, only on the connectivity order.

• We now need to prove the two properties of the network: equivariance and expressiveness.

• Wait a minute, do we really need to prove these properties?

- Equivariance is a direct result of the construction of the layer. The layer is constructed to satisfy the Fixed Point Equation, which is the condition for equivariance.
- Expressiveness is also a direct result of the construction of the layer.
 The layer is constructed to be a full basis for the space of equivariant functions.
- Just like DeepSets, we can now construct a network which is both equivariant and maximally expressive in the space of equivariant functions.
- Our layers are efficient, expressive, and constrained to the space of equivariant functions.
- This allows for very efficient learning, and should also result in great generalization. The key here is a strong inductive bias.

As researchers, we should present results that suit us, not those which make us look bad (these GPUs are not going to pay for themselves).

Table 1: Comparison to baseline methods on synthetic experiments.

	1						<u> </u>						
	Symmetric projection			Diagonal extraction			Max singular vector				Trace		
# Layers	1	2	3	1	2	3	1	2	3	4	1	2	3
Trivial predictor	4.17	4.17	4.17	0.21	0.21	0.21	0.025	0.025	0.025	0.025	333.33	333.33	333.33
Hartford et al.	2.09	2.09	2.09	0.81	0.81	0.81	0.043	0.044	0.043	0.043	316.22	311.55	307.97
Ours	1E-05	7E-06	2E-05	8E-06	7E-06	1E-04	0.015	0.0084	0.0054	0.0016	0.005	0.001	0.003

 In previous lectures, we saw that a popular way to measure the expressivity of a GNN is by looking at the Weisfeiler-Lehman (WL) test.

- In previous lectures, we saw that a popular way to measure the expressivity of a GNN is by looking at the Weisfeiler-Lehman (WL) test.
- The WL test is a graph isomorphism test that is known to be able to distinguish between non-isomorphic graphs.
- We want to show that for some k, our k-order networks can distinguish between non-isomorphic graphs just as well as the k-WL test.

• In Maron et al. (2019), the authors show that the k-order equivariant network is able to distinguish between non-isomorphic graphs just as well as the k-WL test.

- In Maron et al. (2019), the authors show that the *k*-order equivariant network is able to distinguish between non-isomorphic graphs just as well as the *k*-WL test.
- The model proposed is much more efficient than *k*-GNNs which are also equivalent to the *k*-WL test.

Thank You!