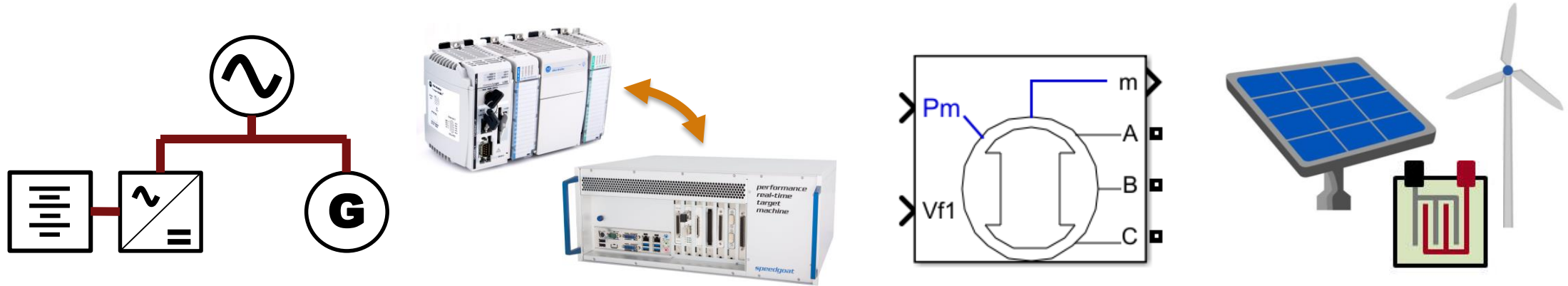


# Modeling Distributed and Renewable Systems

## *Introduction to Simulation with Simscape Power Systems*



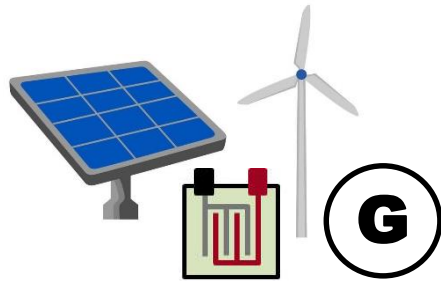
**Jonathan LeSage, PhD**

**Senior Application Engineer - Energy and Automation**  
**MathWorks, Inc.**

# Renewable/Microgrid Series Topics

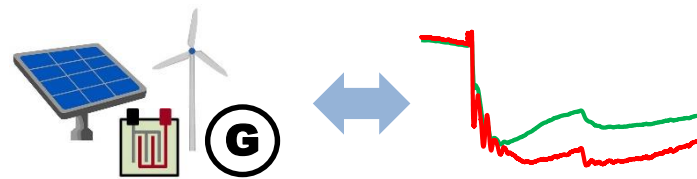
## Distributed and Renewable Systems

*Modeling and Simulation*



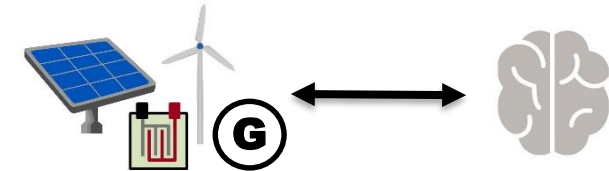
## Addressing Validation Requirements

*Integrated Workflows*



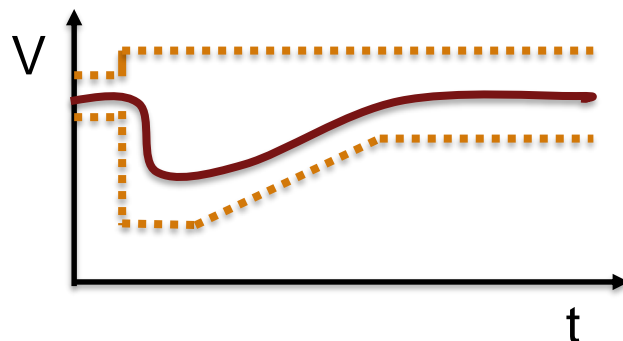
## Energy Management Systems

*Supervisory Control Design*



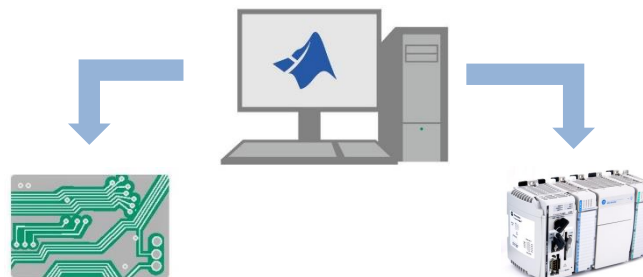
## Testing Grid Codes and IEEE Standards

*Validating Controls*



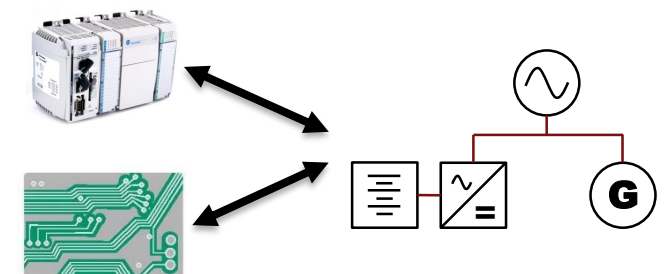
## Deploy Vendor Agnostic Algorithms

*C and PLC Code Generation*

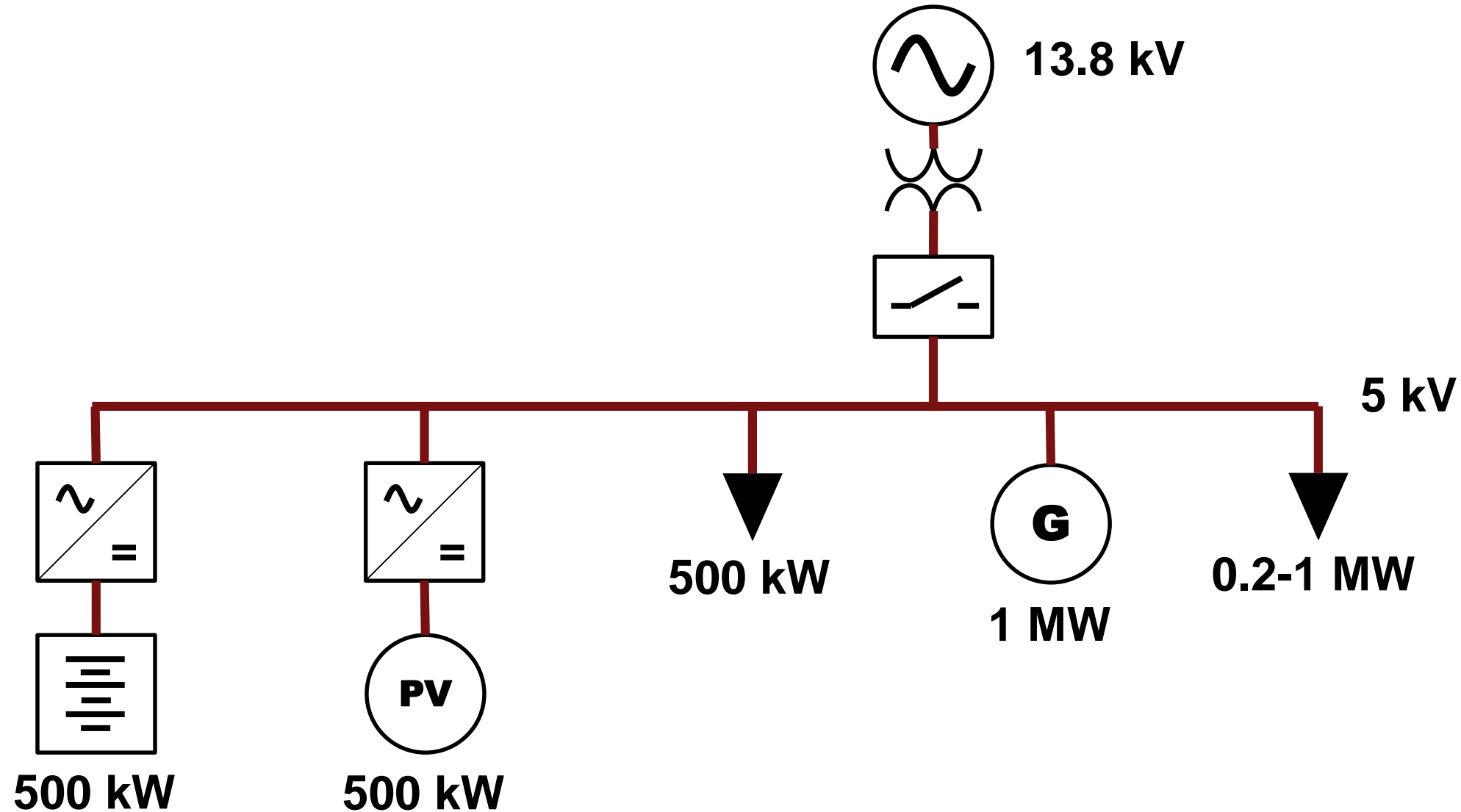


## Grid Integration Studies

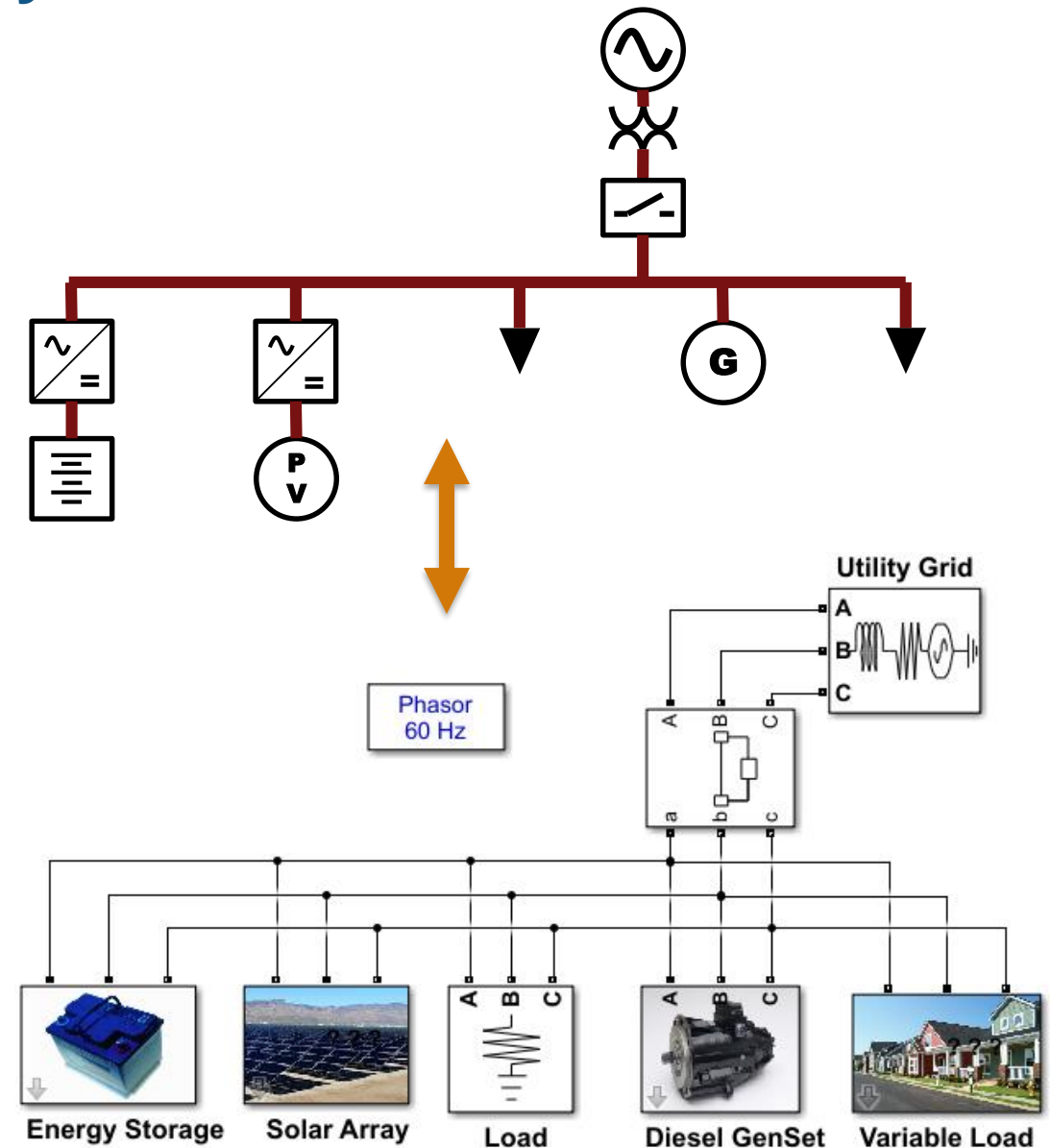
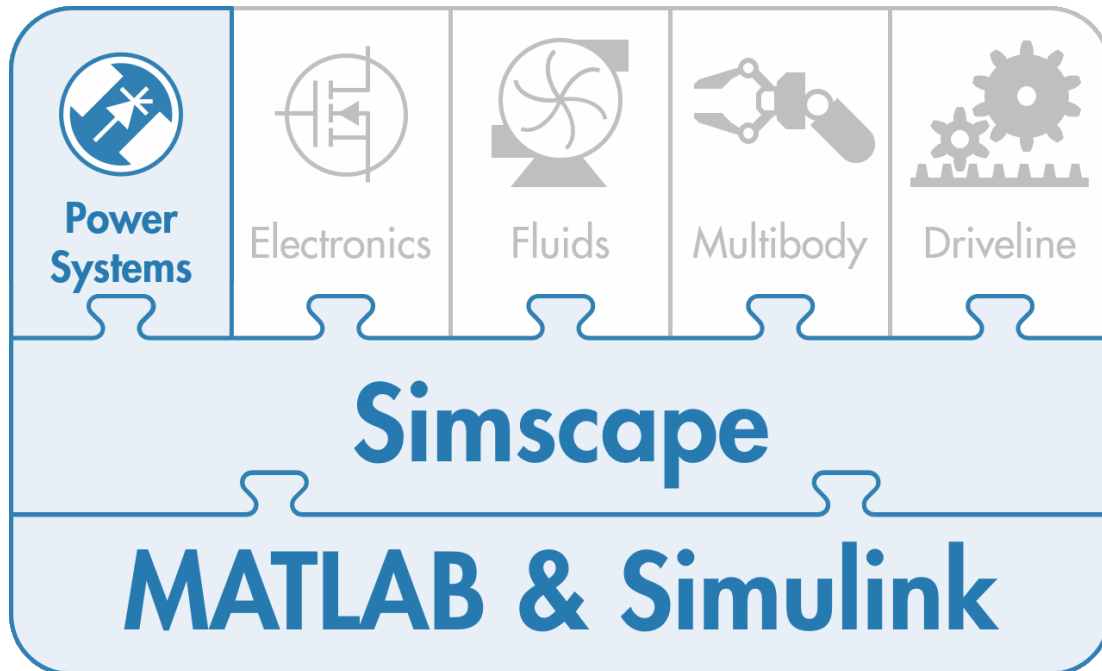
*Real-Time Testing of Controllers*



## Example Microgrid One-Line Diagram



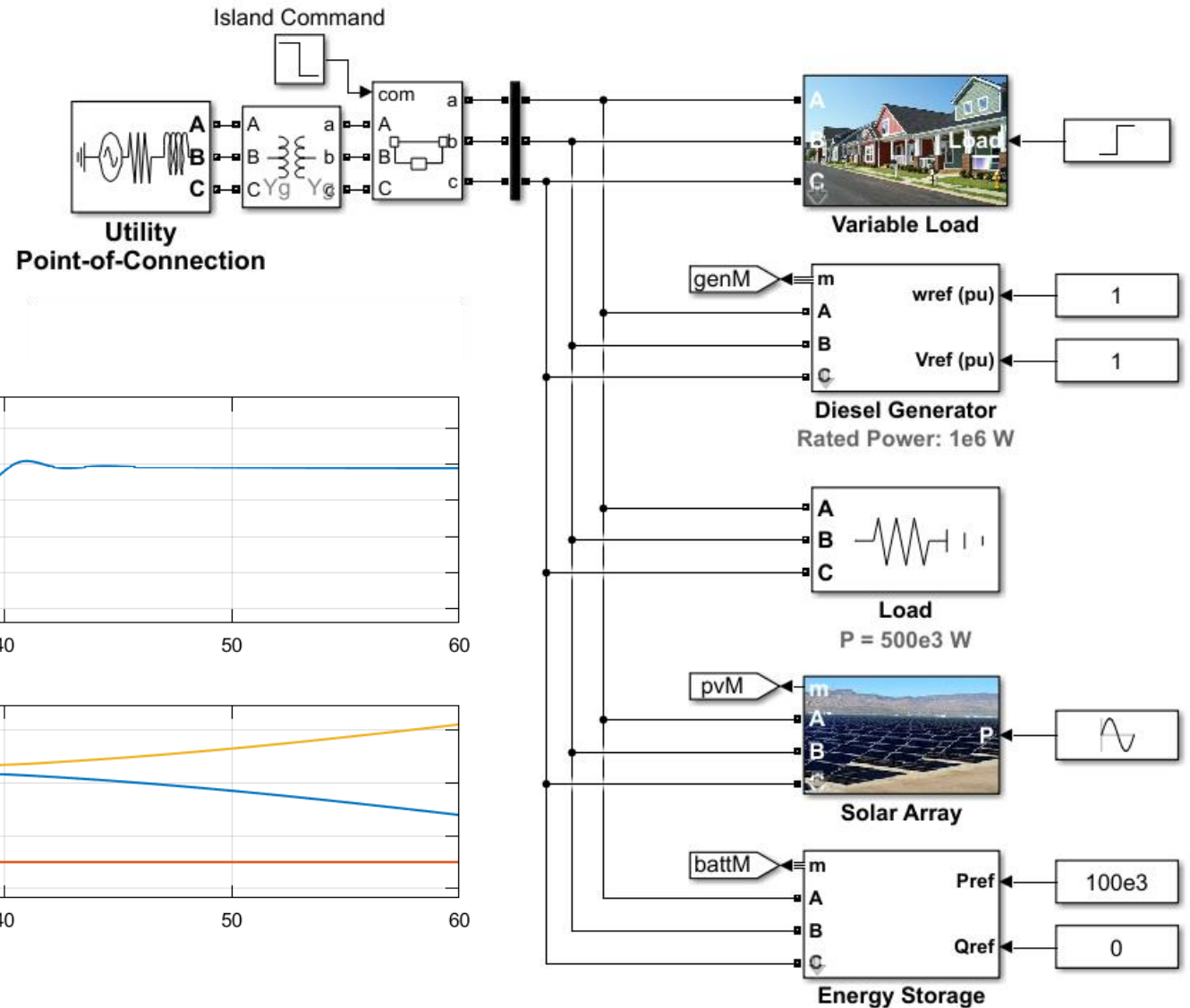
# Introduction to Simscape Power Systems



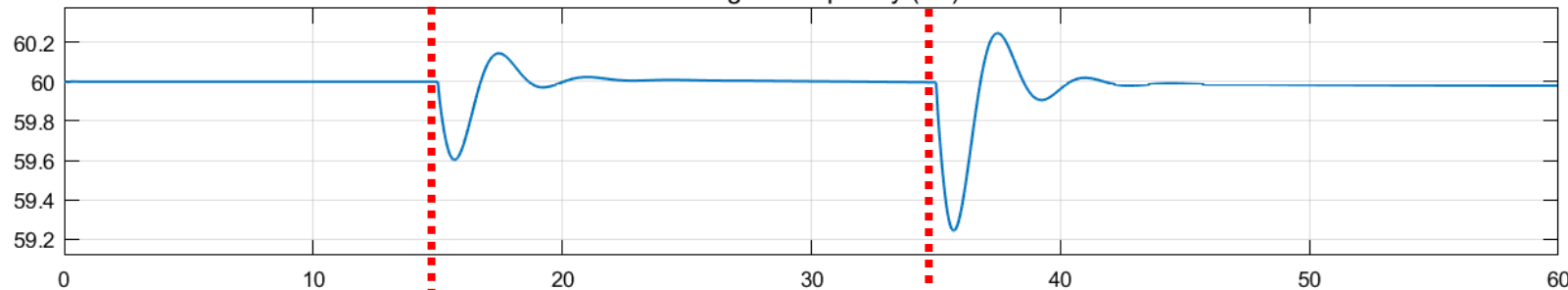
# Implementing Microgrid One-Line Diagram in Simulink

Island Microgrid  
at 15 seconds

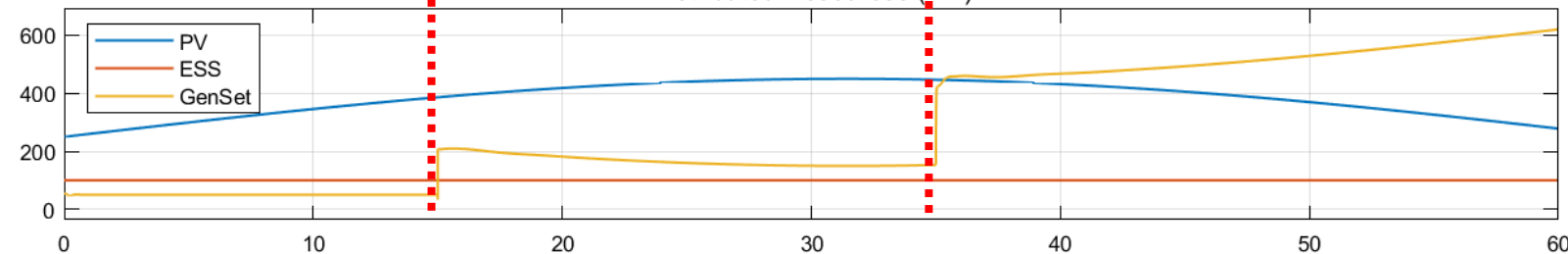
Add 300 kW Load  
at 35 seconds



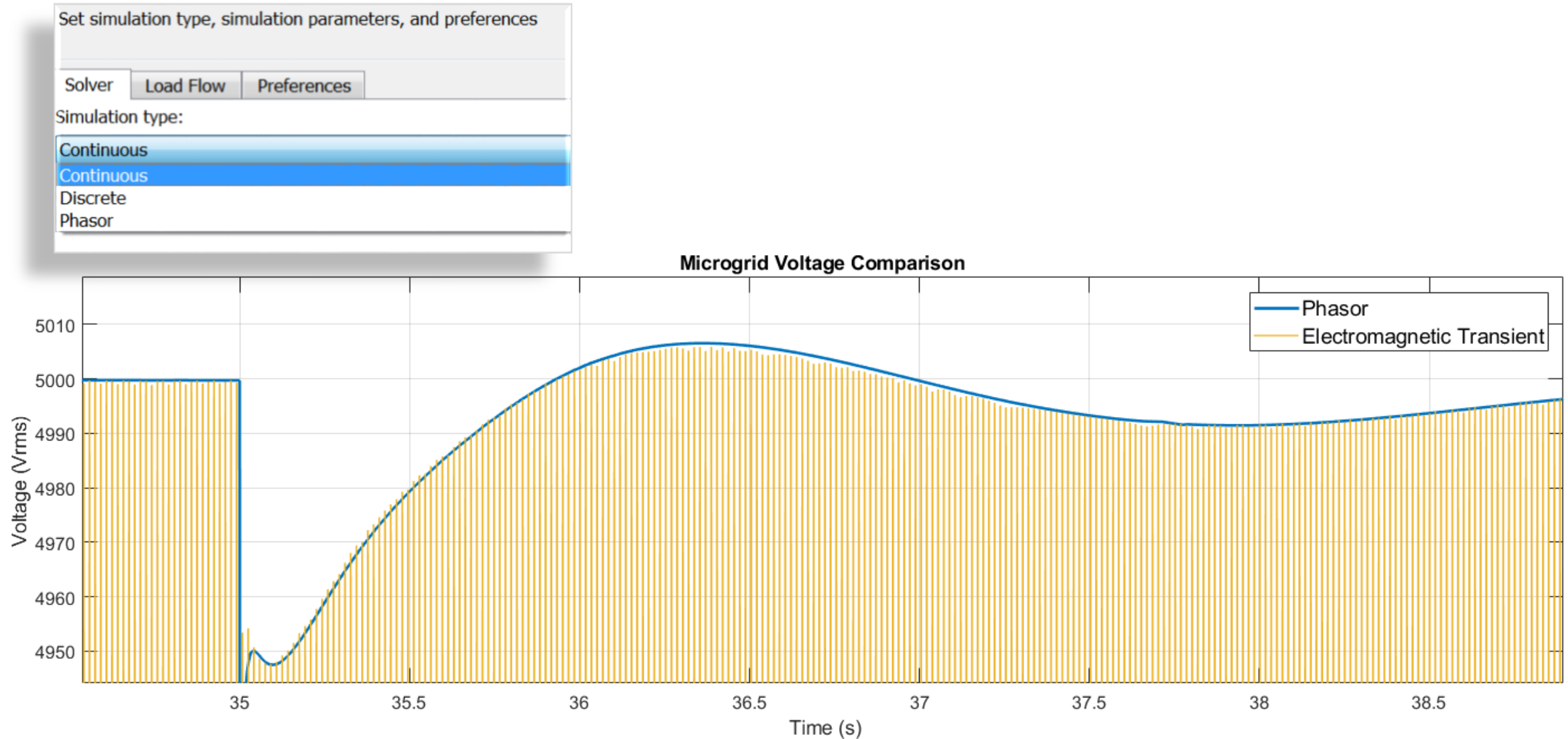
Microgrid Frequency (Hz)



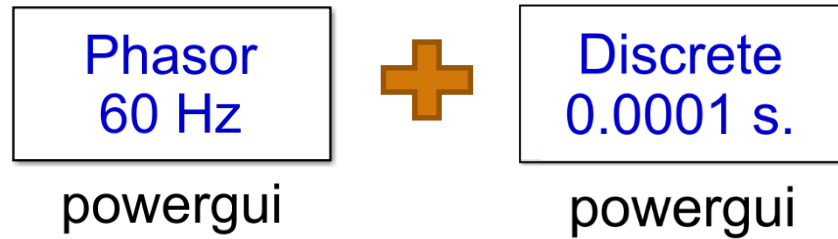
Distributed Resources (kW)



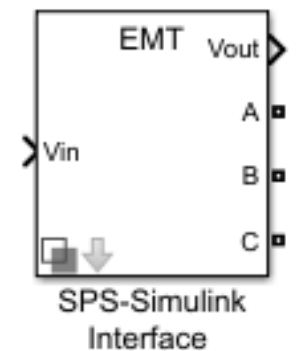
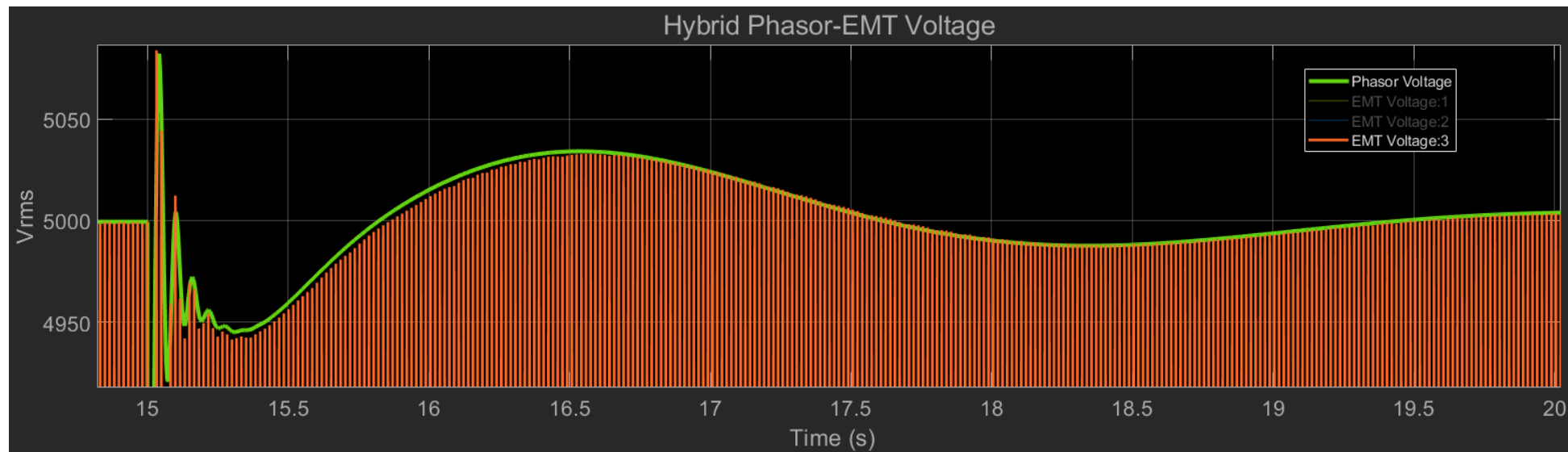
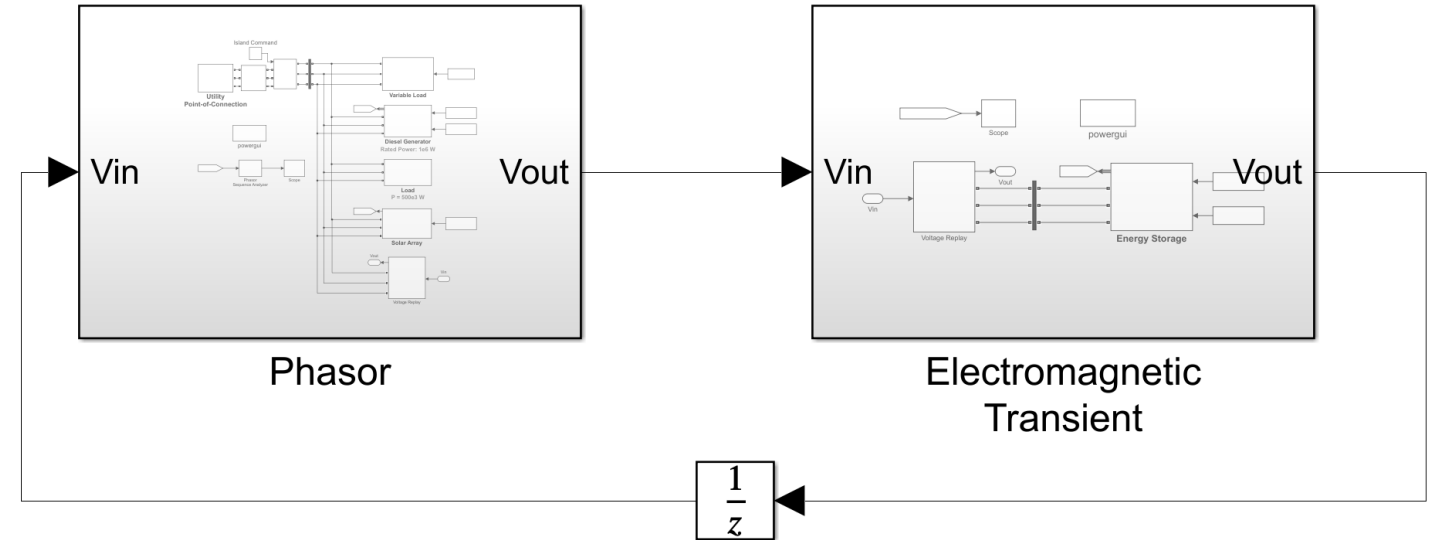
# Phasor and Electromagnetic Transient Comparison



# Hybrid Phasor-EMT Simulation



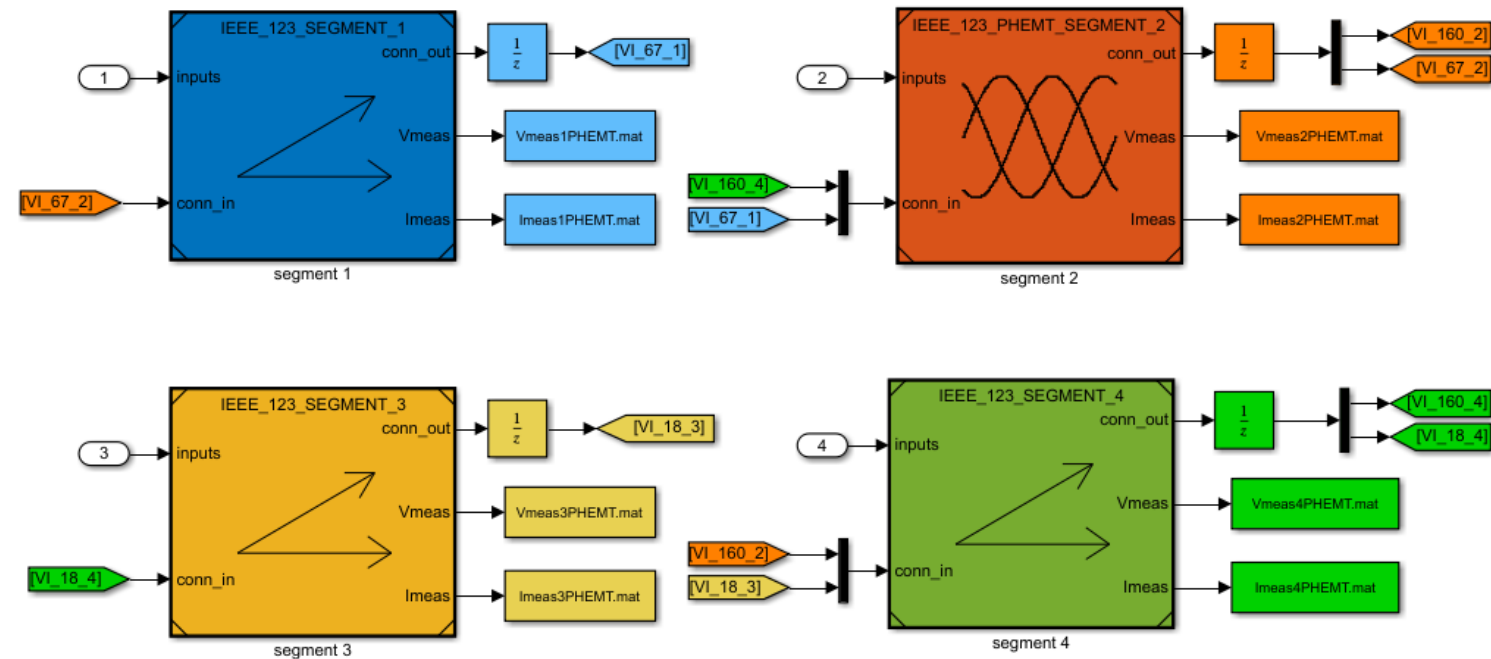
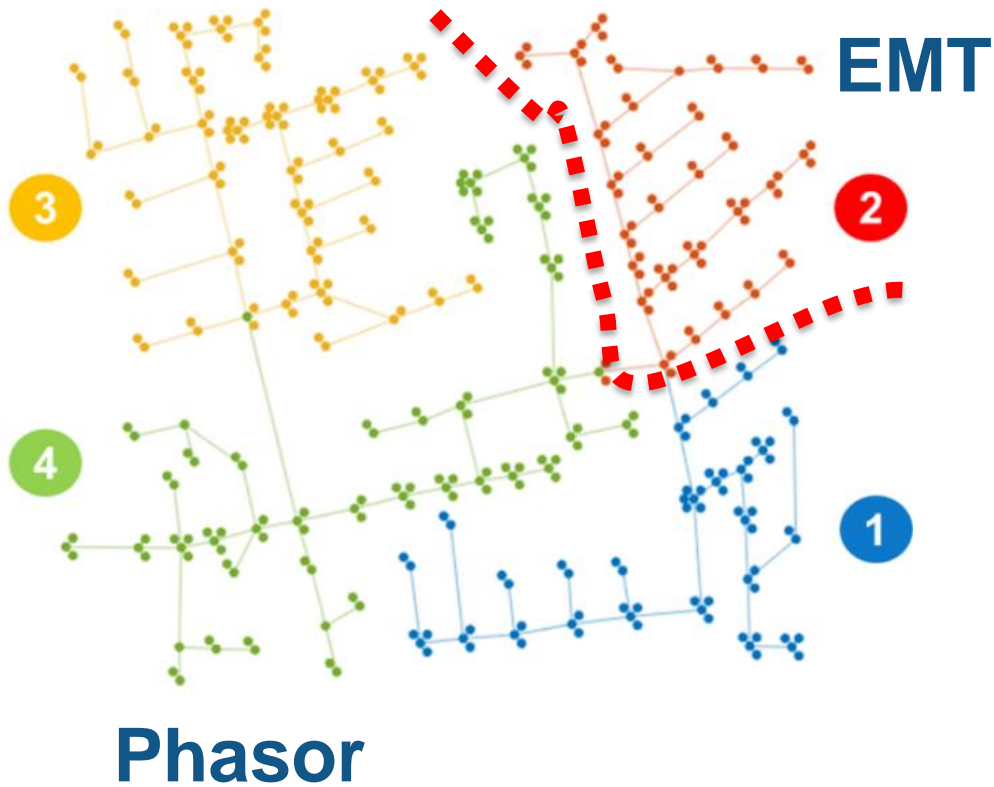
Different “powergui”  
settings per subsystem





# Hybrid Phasor-EMT Simulation

Scaling up simulation size – IEEE 123 Node Distribution Feeder with Hybrid Phasor-EMT

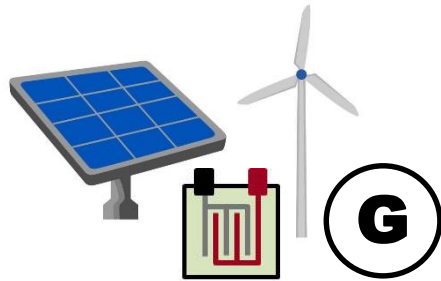




# Renewable/Microgrid Series Topics

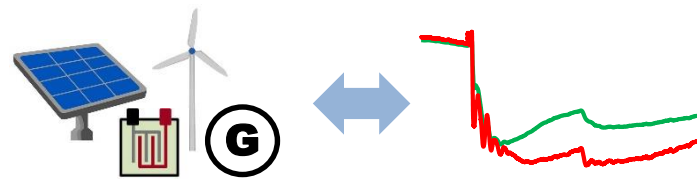
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*Modeling and Simulation*



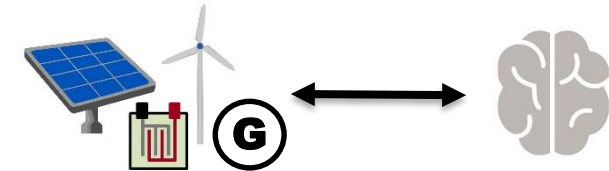
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*Integrated Workflows*



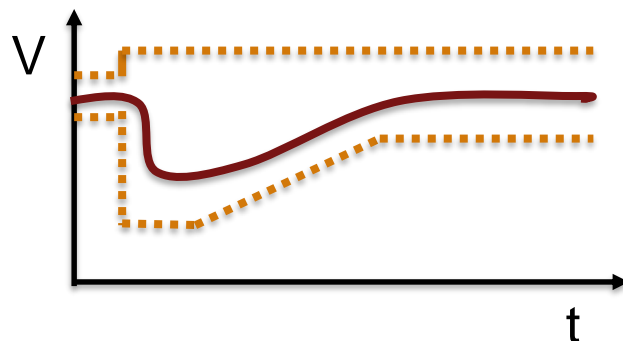
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*Supervisory Control Design*



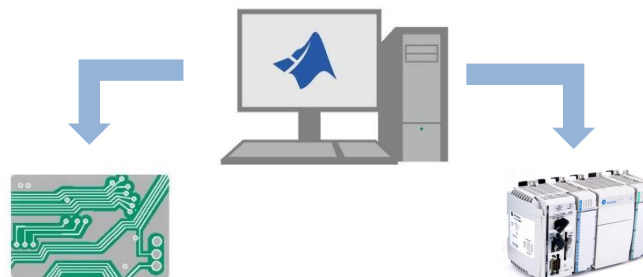
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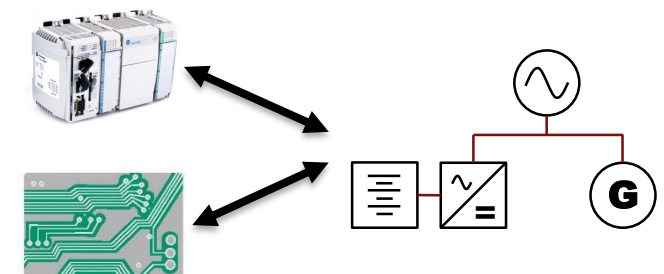
## Deploy Vendor Agnostic Algorithms

*C and PLC Code Generation*



## Grid Integration Studies

*Real-Time Testing of Controllers*



# Deployment to Real-Time target

Configuration Parameters: simpleMicrogrid\_RealTime/Configuration (Active)

Search

- Solver
- Data Import/Export
- Optimization
- Diagnostics
- Hardware Implementation
- Model Referencing

Simulation time

Start time: 0.0

Solver options

Type: Fixed-step

Target selection

System target file: slrt.tlc

Language: C

Description: Simulink Real-Time

Build process

