Category Theory Introduction

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In the far future, I will try to do differential geometry stuff involving category theory. Probably will involve algebraic topology in some sense of the word (the two subjects are connected, or so I hear. Also, with a toe in the Vakil online AG course, I will update these notes if I consider any ideas.

1 Initial Motivation

A lot of structural results about different objects, like groups, vector spaces, sets, etc. have similarities. We can make these precise because it turns out that the thing that is in common between them happens to be correctly formulated when you consider objects in question and maps between them.

Consider, for example, the notion of a product (of sets). Normally, if U and V are sets, then we define this by

$$U\times V=\{(u,v)\mid u\in U,v\in V\}.$$

But no one is stopping us from defining

$$U \times V = \{(v, u) \mid v \in V, u \in U\}.$$

This doesn't really seem to matter that much, as there is an obvious bijection between the two. We will now make this precise using the language of category theory.

Notice that from the set $U \times V$ we get two canonical products π_1 and π_2 , the projection maps to the first and second coordinate, respectively. If we defined $U \times V$ using the alternative definition we let π_1 and π_2 be the swapped projection maps. Note that if $p \in U \times V$ and we know the elements $\pi_1(p)$ and $\pi_2(p)$, we can recover p. So π_1 and π_2 can be seen to define $U \times V$, in the following precise sense:

Definition 1. A **product** is a set P, along with maps $\pi_1: P \to U$, $\pi_2: P \to V$ such that for any set P' with maps $\mu_1: P' \to U$ and $\mu_2: P' \to V$ these maps factor uniquely through P. That is, given μ_1 and μ_2 there exists a unique map $\phi: P' \to P$ such that $\mu_1 = \pi_1 \circ \phi$, $\mu_2 = \pi_2 \circ \phi$. So a product is essentially a diagram (insert diagram here). Usually π_1 and π_2 are left implicit.

Returning to the canonical example of $U \times V$ with canonical projection maps. If I have two maps $\mu_1: P \to U$, and $\mu_2: P \to V$, then there is a unique map $\mu: P \to U \times V$ which satisfies the conditions in the definition, namely, the map $p \mapsto (\mu_1(p), \mu_2(p))$. This is because from the equation $\pi_1 \circ \mu = \mu_1$ we obtain for all $p \in P$

$$\pi_1(\mu(p)) = \mu_1(p) \implies \mu(p) = (\mu_1(p), y)$$

for some $y \in V$ and similarly we obtain

$$\mu(p) = (x, \mu_2(p))$$

which shows that the claimed map is the unique map involved.

Now suppose that we have two products (P_1, π_i) and (P_2, μ_i) on N and M. If we let ϕ_i be the unique maps obtained by factoring from P_i , respectively, we get that $\phi_1 \circ \phi_2$ has the property that

$$\phi_1 \circ \phi_2 \circ \mu_i = \phi_1 \circ \pi_i = \mu_i$$
.

But the identity map on P_2 has the same property, so $\phi_1 \circ \phi_2 = Id_{P_2}$ (by the uniqueness of the factoring map). Similarly, $\phi_2 \circ \phi_1 = Id_{P_1}$, so we can conclude that they are inverses of each other and P_1 and P_2 have a canonical bijection between their product structure.

Why exactly do we care, though? It is because if we are working in another category, such as the category of vector spaces or differentiable manifolds, the exact same argument will work in those categories modulo terminology, because all we have used were the "arrows" between the objects being considered in question. This will motivate our introduction into exploring category theory a little bit more (hopefully).

2 Introduction to Categories

Question 1. What is a category? What exactly are we trying to generalize?

To attack the heart of this question, first we need to answer the sort of situation that we would like to generalize. The short answer is that we would like to generalize the following: we have a collection of structures and we would like to characterize the "structure preserving maps" between them. This concept in general gives us nice ways of generalizing certain structures and theorems that feel *similar*.

In any reasonable mathematical structure, we have a concept of *composing* maps. For example, suppose A, B, and C are any 3 sets. Then given a set mapping $f: A \to B$ and $q: B \to C$ we can define a composite function $(q \circ f): A \to C$.

Really, this is all a category is. Conceived in the 20th century, categories were created to formalize reasoning generally about structures and structure preserving maps between them.

Definition 2. A category C is a mathematical structure consisting of the following two objects:

- A class of *objects*, denoted by Ob(C),
- A class of arrows.

The arrows have the following properties:

- For every arrow f of \mathcal{C} associated with it are a source object A and target object B. We denote these by s(f) and t(f), respectively. We will write $f: A \to B$ to mean the obvious thing.
- For any arrows $f: A \to B$ and $g: B \to C$ there exists an arrow $g \circ f: A \to C$, an arrow with source A and target C. We call the circle operator composition.
- Given any object A there exists a so called identity morphism $1_A: A \to A$.

The arrows have to satisfy the following properties:

- For morphisms $f: W \to X$, $g: X \to Y$, and $h: Y \to Z$, we have that $(h \circ g) \circ f = h \circ (g \circ f)$.
- For any morphism $f: A \to B$ we have that $1_B \circ f = f \circ 1_A = f$.

From this great generality of a mathematical structure, we might think about some elementary consequences of the definitions.

Proposition 1. The identity morphism (synonymous with arrow) for an object A in a category C is unique.

Proof. Trivial, in the sense that the proof is completely standard. If you don't know how to do this you might not have enough mathematical maturity yet to read this document. \Box

We document some simple examples of categories:

Example 1. Consider the class of **monoids**: mathematical structures restricted by closure under multiplication and associativity, with the existence of an identity element. Then the category \mathcal{M} of all monoids and monoid homomorphisms forms a simple example of a category.

Example 2. Consider the class of all pre-ordered sets (not totally ordered). If we consider the monotone maps between these sets, we form another simple example of a category.

Example 3. Here's the first example of a category that does not involve multiple structures and maps between them: consider any group or monoid K. We consider the category \mathcal{C} with one object * and we define each arrow to be an element of K. That is $\forall k \in K$ we have an arrow $k: A \to A$. Since K has an identity we have identity. In fact the category definition basically follows from the associativity and identity of K itself.

Example 4. In a similar sense a partially ordered set of elements forms a category. We need to add identity elements for each element in the poset, but otherwise the only other arrows are the ones we can define from an order relation.

There are examples of categories for most structures.