12/26/2017 **Udacity Reviews**





PROJECT

Kidnapped Vehicle

A part of the Self-Driving Car Engineer Program

PROJECT REVIEW

CODE REVIEW 8

NOTES

SHARE YOUR ACCOMPLISHMENT! 🍏 📻

Meets Specifications

Congratulations on completing this C++ project! You should be satisfied with what you have achieved.

Best of luck with the PID project and the rest of Term 2!

In case you are interested, this is a paper Sebastian Thrun authored on particle filters and how they could be used to perform robot localisation.

NB: The nature of this project and rubric means that elements of this review will be similar or identical to the reviews for other students. Please rest assured that I have looked through all of the code you have written and submitted looking for issues with your implementation and places where I could suggest improvements.

Accuracy

This criteria is checked automatically when you do ./run.sh in the terminal. If the output says "Success! Your particle filter passed!" then it means you've met this criteria.

Your particle filter completes a successful run in the simulator. Nicely one!

