

CLASSIFICATION OF ENVIRONMENTAL SOUND USING IOT SENSORS

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INTRODUCTION

JON NORDBY

Internet of Things specialist

- B.Eng in **Electronics**
- 9 years as **Software developer. Embedded + Web**
- M. Sc in **Data Science**

Now:

- CTO at Soundsensing
- Machine Learning Consultant



soundsensing

What we do

Noise Monitoring for outdoor and indoor environments

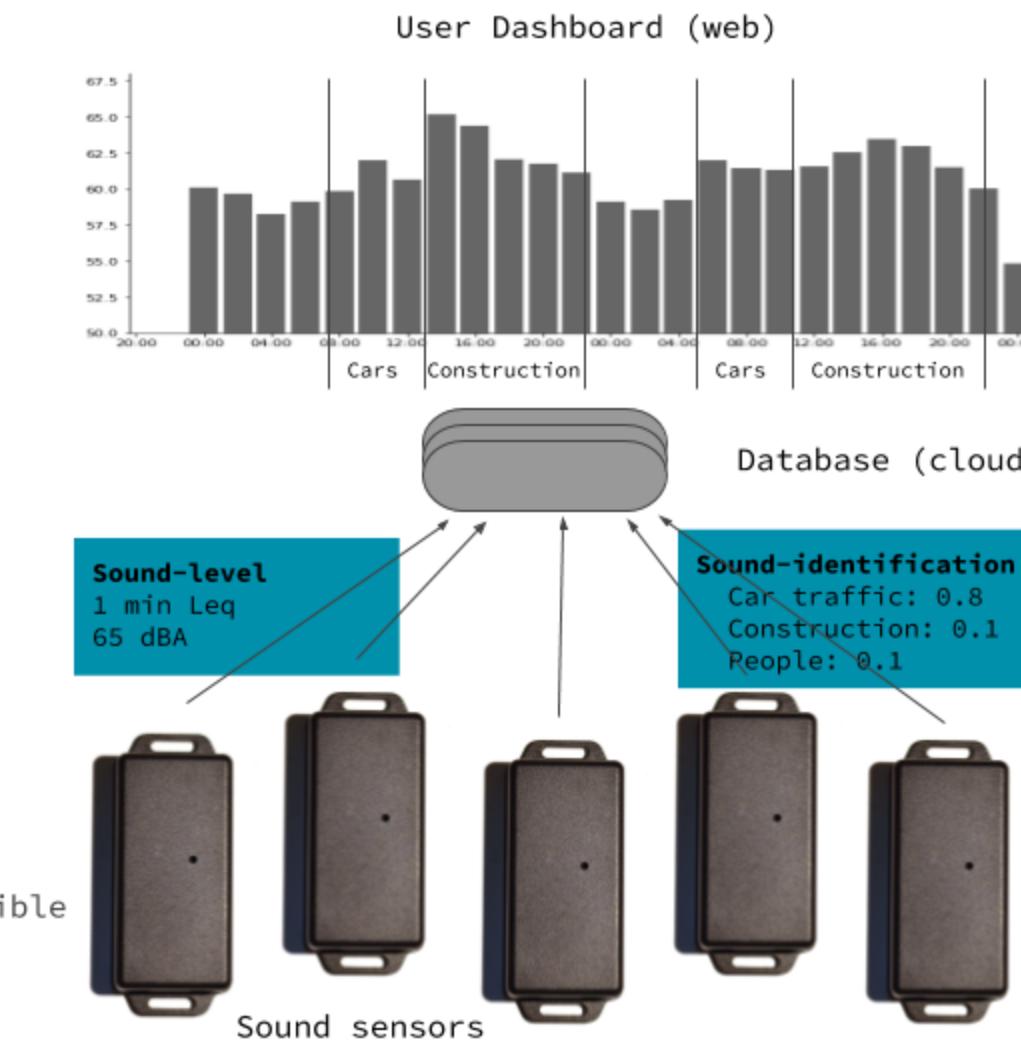
- Smart cities
- Workspaces/offices
- Hotels/AirBnB
- Music venues

Designed for Privacy:

Sound is not transmitted or stored.
- only the noise information

Our R&D focus

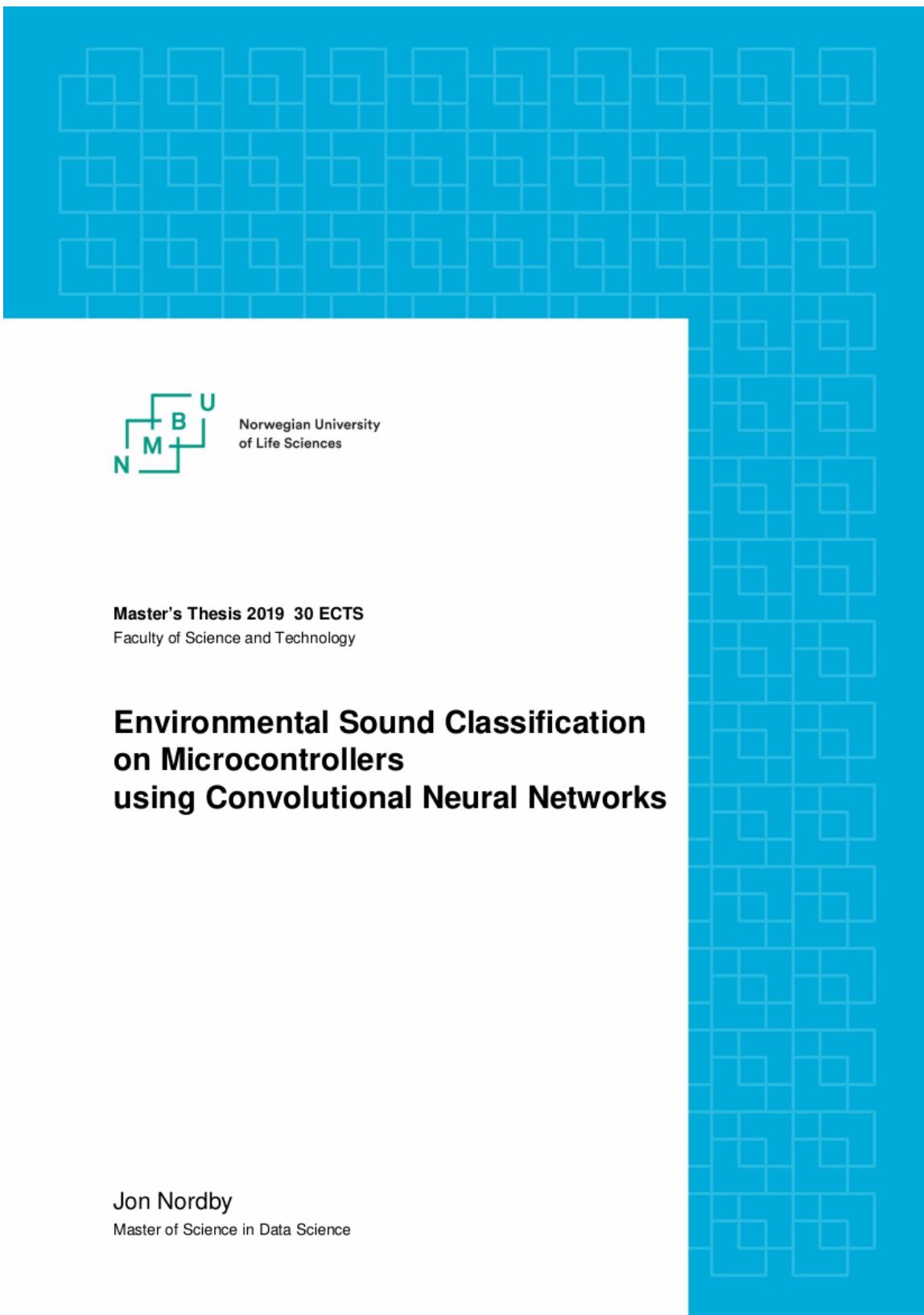
How to provide the best information possible about noise using IoT sensors and machine learning



Pilot projects with customers Now - 2020

THESIS

*Environmental Sound Classification on Microcontrollers using Convolutional
Neural Networks*



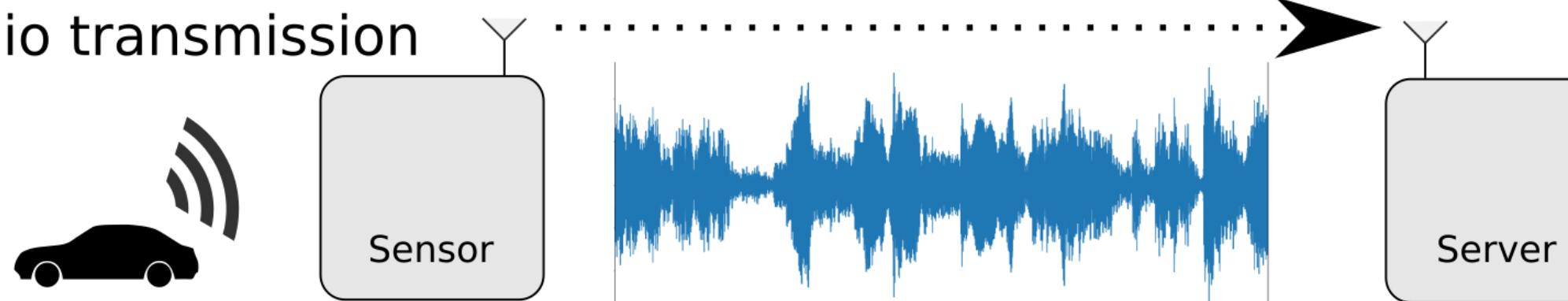
Report & Code: <https://github.com/jonnor/ESC-CNN-microcontroller>

WIRELESS SENSOR NETWORKS

- Want: Wide and dense coverage
- Need: Sensors need to be low-cost
- Opportunity: Wireless reduces costs
- Challenge: Power consumption

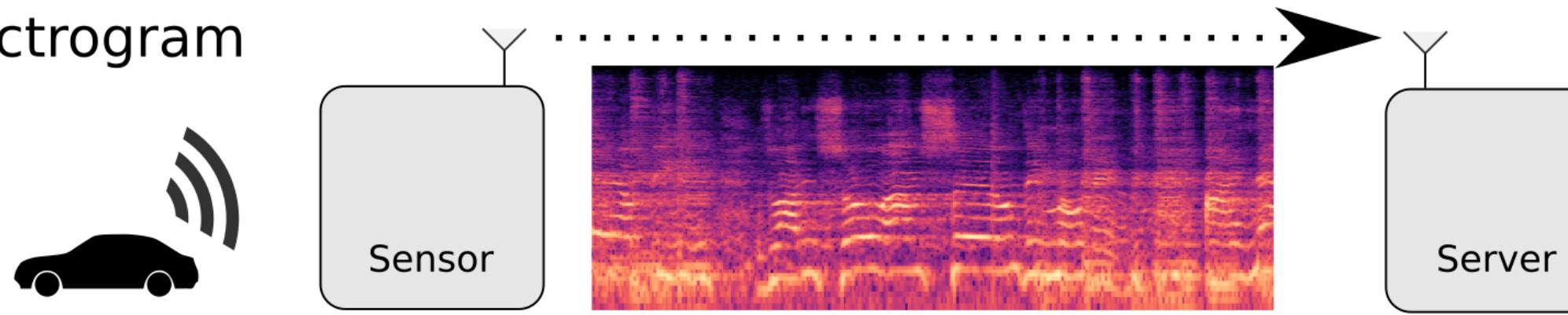
SENSOR NETWORK ARCHITECTURES

A) Audio transmission



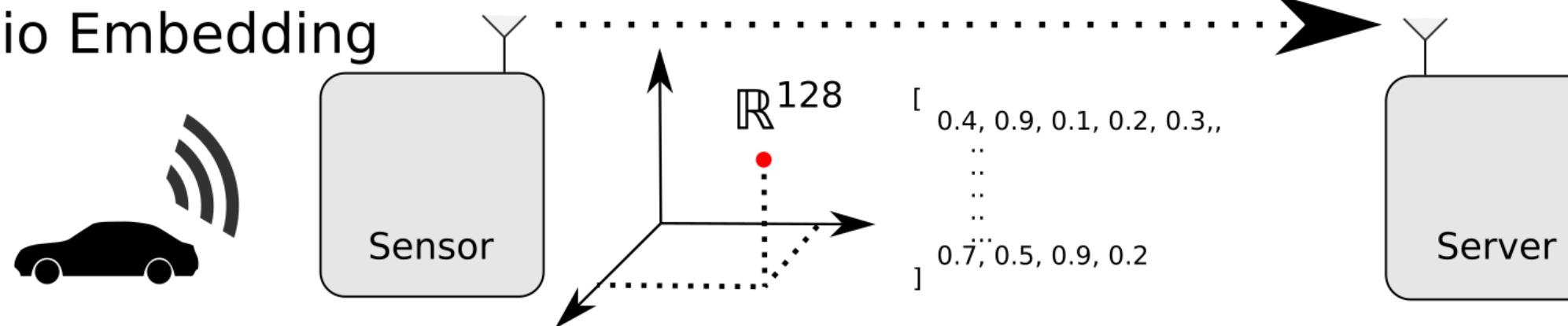
Airconditioner	0.11
Engine idling	0.05
Car horn	0.88
Children playing	0.22
Dog barking	0.12
Siren	0.09
Street Music	0.30
Drillling	0.07
Jackhammer	0.04

B) Spectrogram



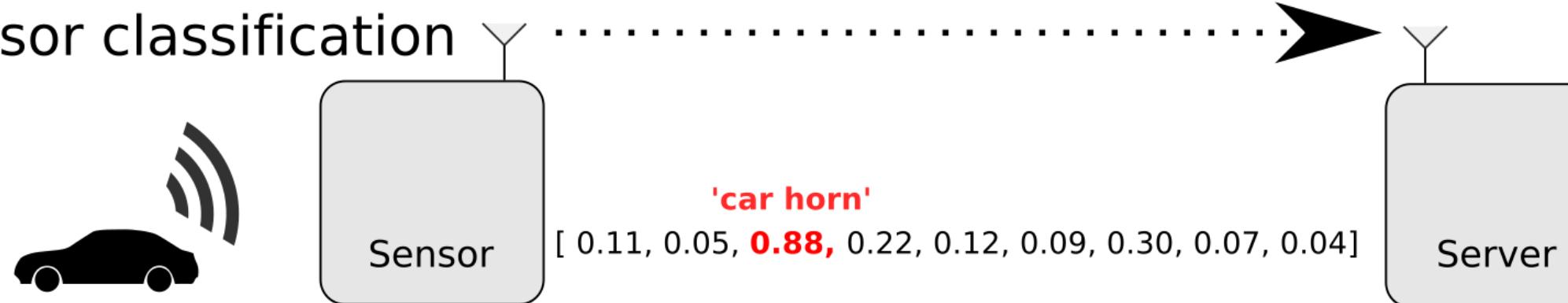
Airconditioner	0.11
Engine idling	0.05
Car horn	0.88
Children playing	0.22
Dog barking	0.12
Siren	0.09
Street Music	0.30
Drillling	0.07
Jackhammer	0.04

C) Audio Embedding



Airconditioner	0.11
Engine idling	0.05
Car horn	0.88
Children playing	0.22
Dog barking	0.12
Siren	0.09
Street Music	0.30
Drillling	0.07
Jackhammer	0.04

D) Sensor classification



Airconditioner	0.11
Engine idling	0.05
Car horn	0.88
Children playing	0.22
Dog barking	0.12
Siren	0.09
Street Music	0.30
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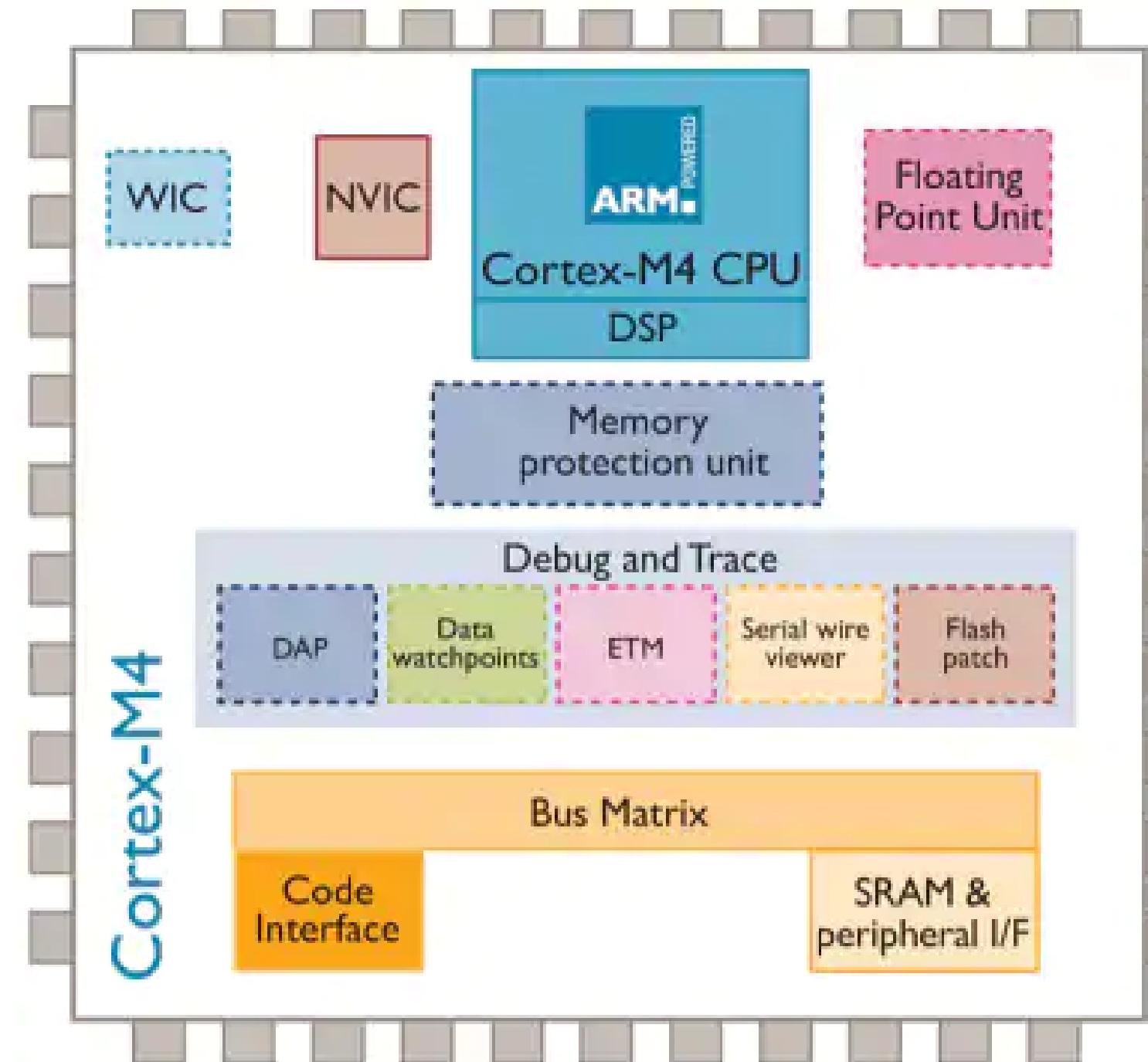
AUDIO MACHINE LEARNING ON LOW- POWER SENSORS

WHAT DO YOU MEAN BY LOW-POWER?

Want: 1 year lifetime for palm-sized battery

Need: <1mW system power

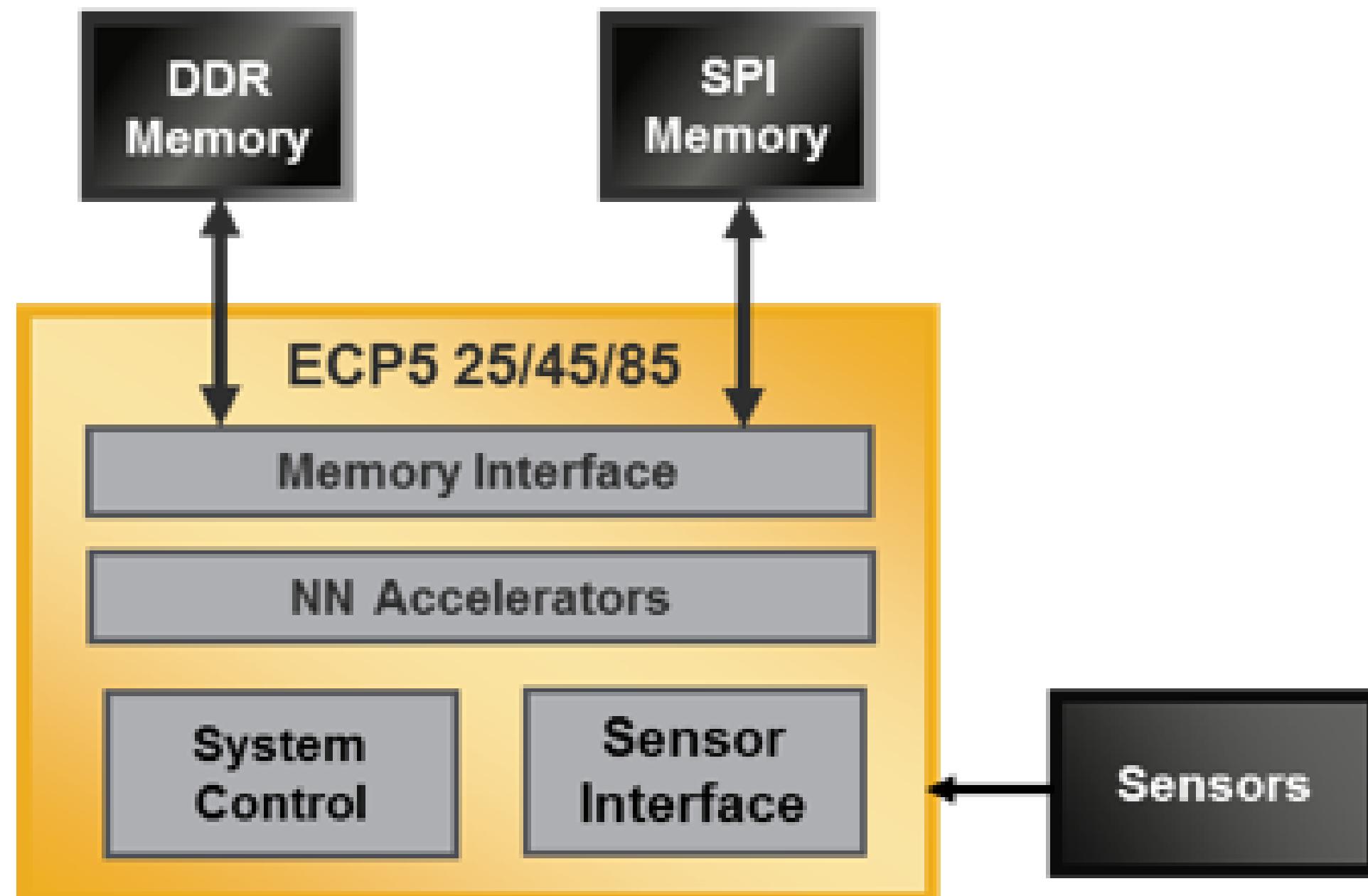
GENERAL PURPOSE MICROCONTROLLER



STM32L4 @ 80 MHz. Approx 10 mW.

- TensorFlow Lite for Microcontrollers (Google)
- ST X-CUBE-AI (ST Microelectronics)

FPGA

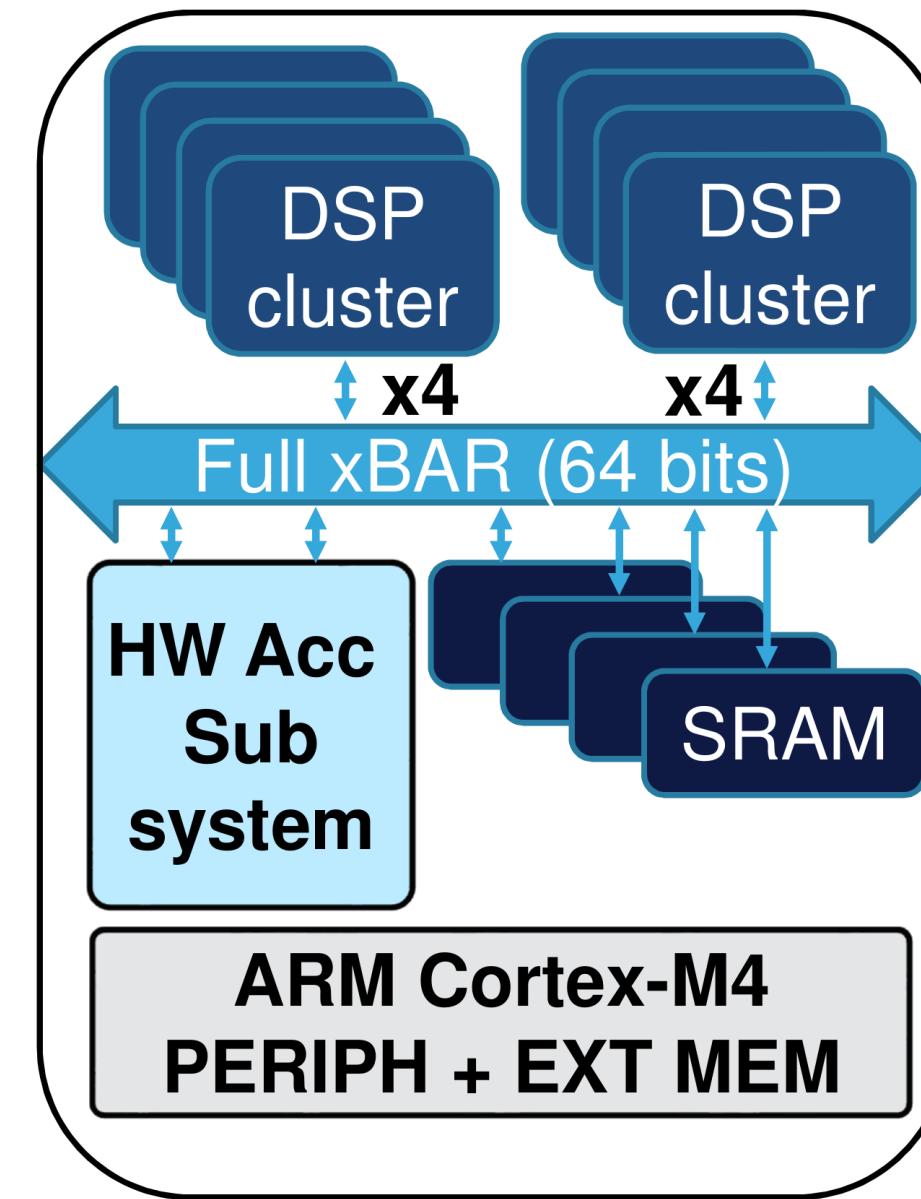


Lattice ICE40 UltraPlus with Lattice sensAI

Human presence detection. VGG8 on 64x64 RGB image, 5 FPS: 7 mW.

Audio ML approx 1 mW

NEURAL NETWORK CO-PROCESSORS



Project Orlando (ST Microelectronics), expected 2020

2.9 TOPS/W. AlexNet, 1000 classes, 10 FPS. 41 mWatt

Audio models probably < 1 mWatt.

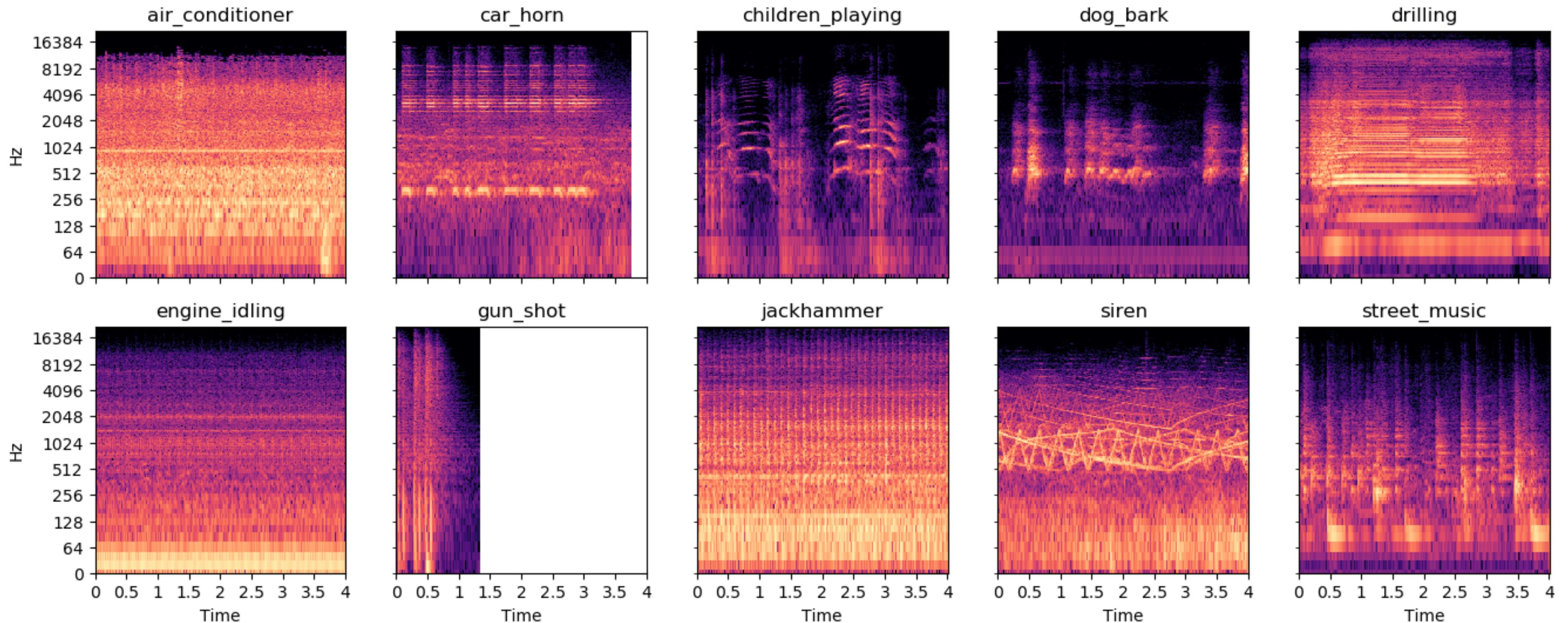
ON-EDGE CLASSIFICATION OF NOISE

ENVIRONMENTAL SOUND CLASSIFICATION

*Given an audio signal of environmental sounds,
determine which class it belongs to*

- Widely researched. 1000 hits on Google Scholar
- Datasets. Urbansound8k (10 classes), ESC-50, AudioSet (632 classes)
- 2017: Human-level performance on ESC-50

URBANSOUND8K



EXISTING WORK

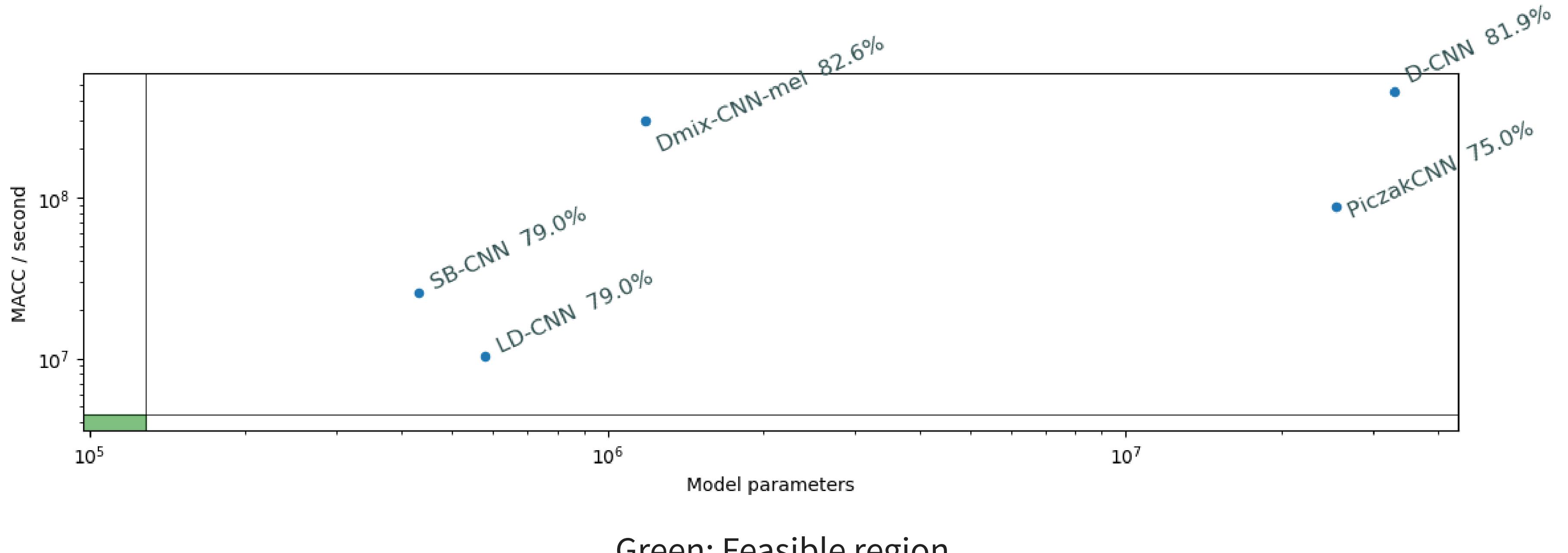
- Convolutional Neural Networks dominate
- Techniques come from image classification
- Mel-spectrogram input standard
- End2end models: getting close in accuracy
- “Edge ML” focused on mobile-phone class HW
- “Tiny ML” (sensors) just starting

MODEL REQUIREMENTS

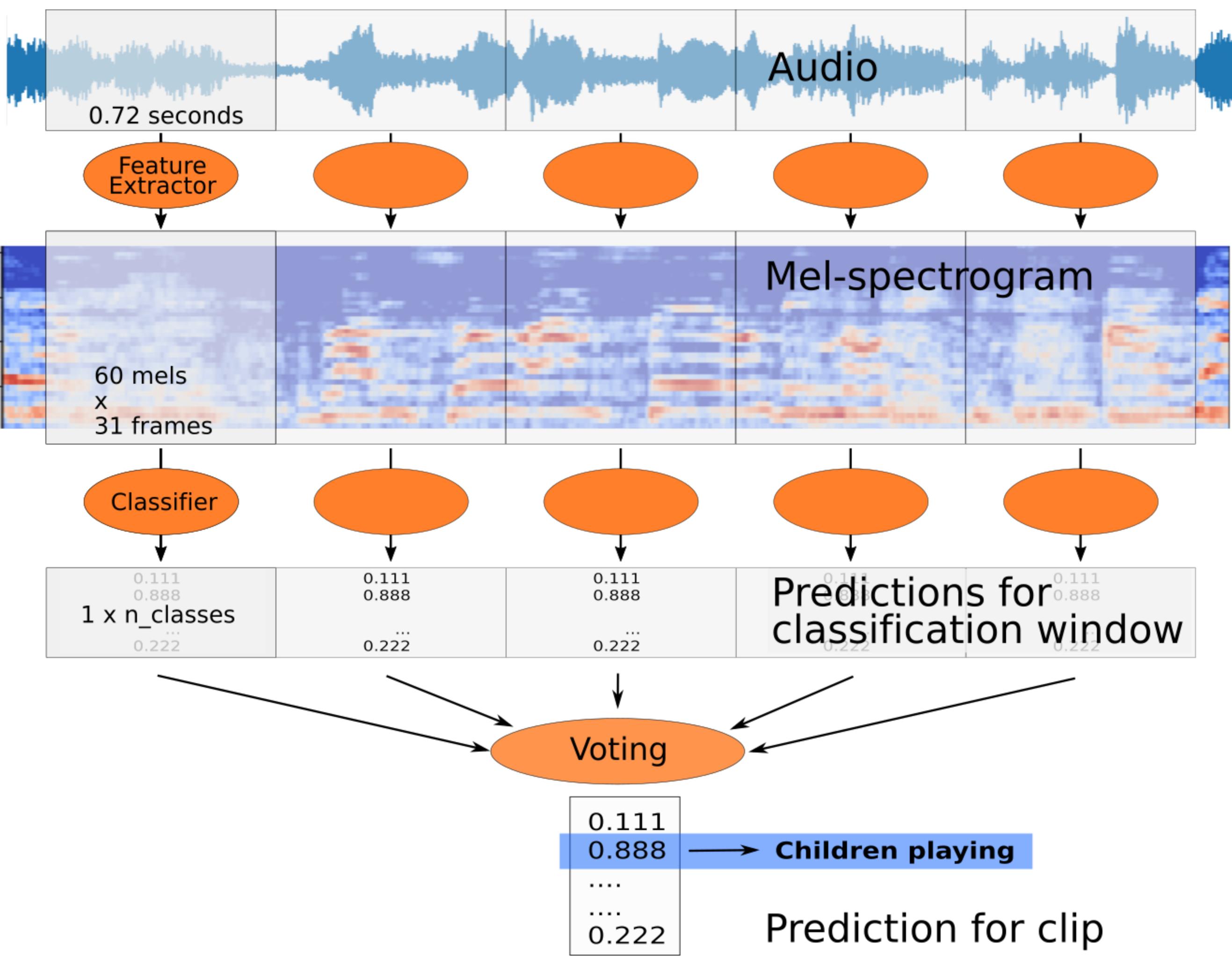
With 50% of STM32L476 capacity:

- 64 kB RAM
- 512 kB FLASH memory
- 4.5 M MACC/second

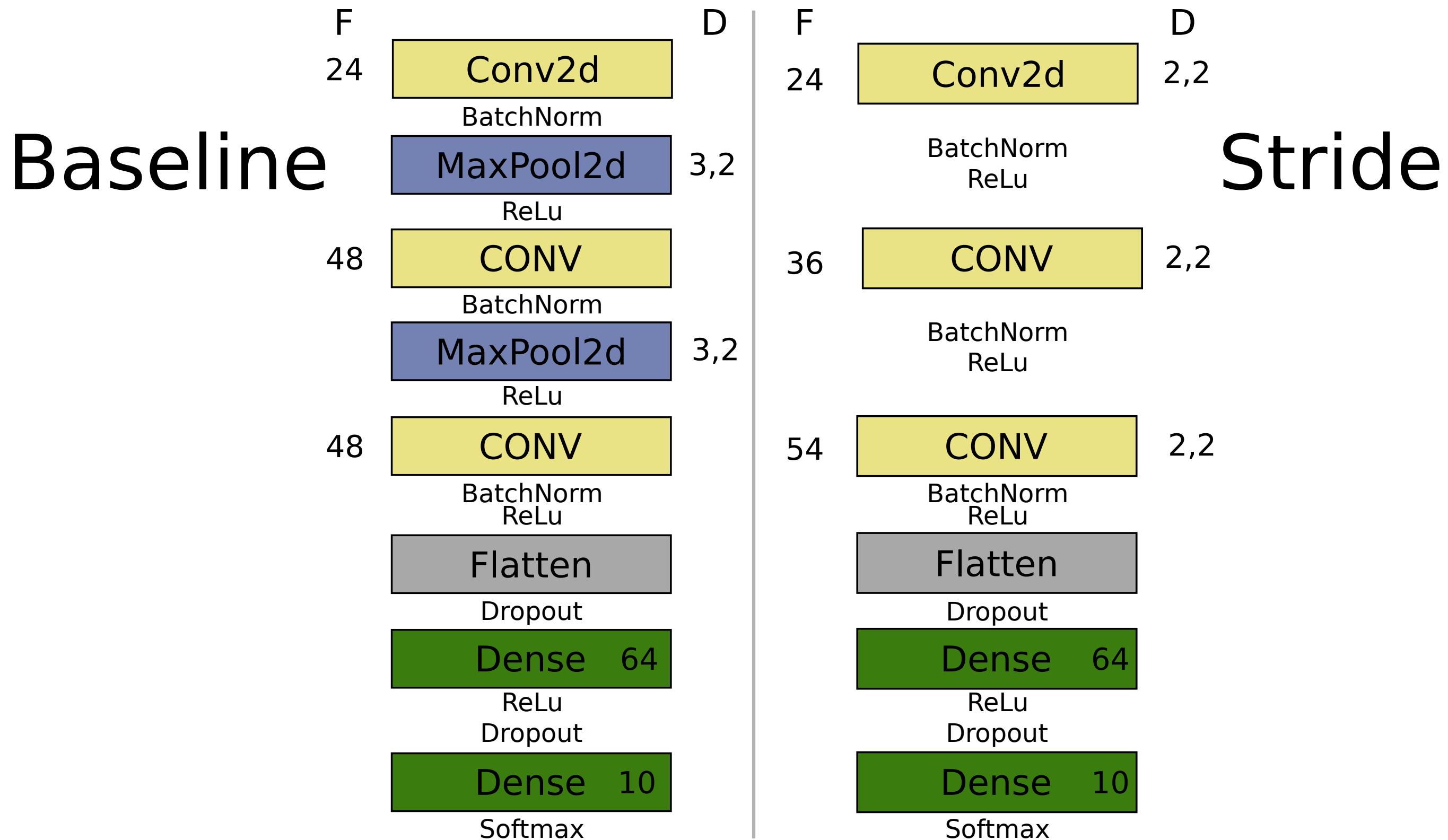
EXISTING MODELS



eGRU: running on ARM Cortex-M0 microcontroller, accuracy 61% with **non-standard** evaluation



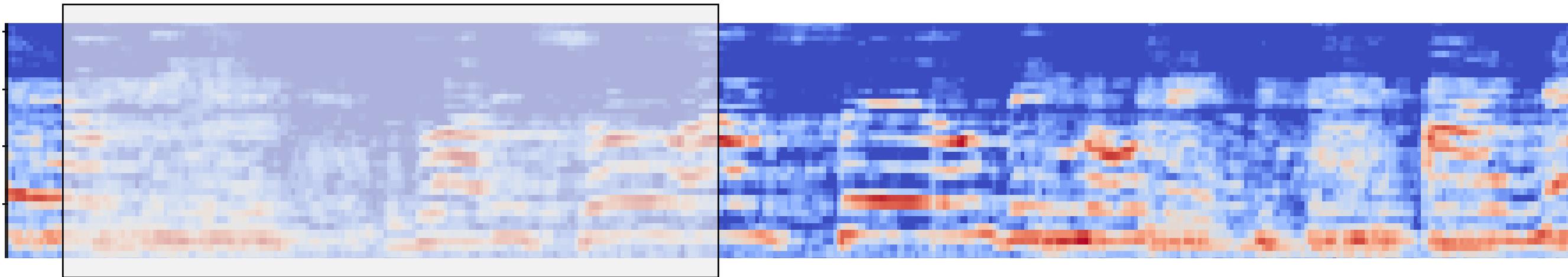
MODELS



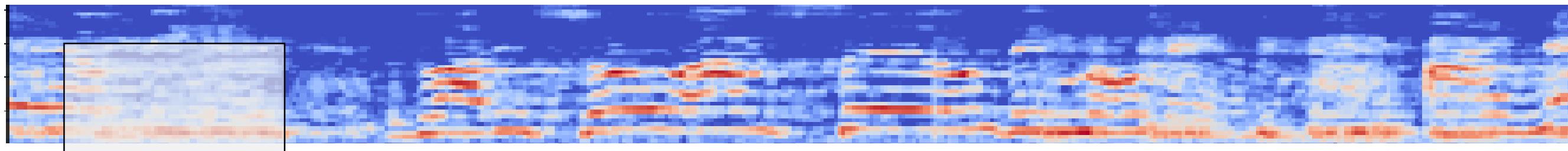
STRATEGIES FOR SHRINKING CONVOLUTIONAL NEURAL NETWORK

REDUCE INPUT DIMENSIONALITY

44.1kHz, 2 seconds, 128x128

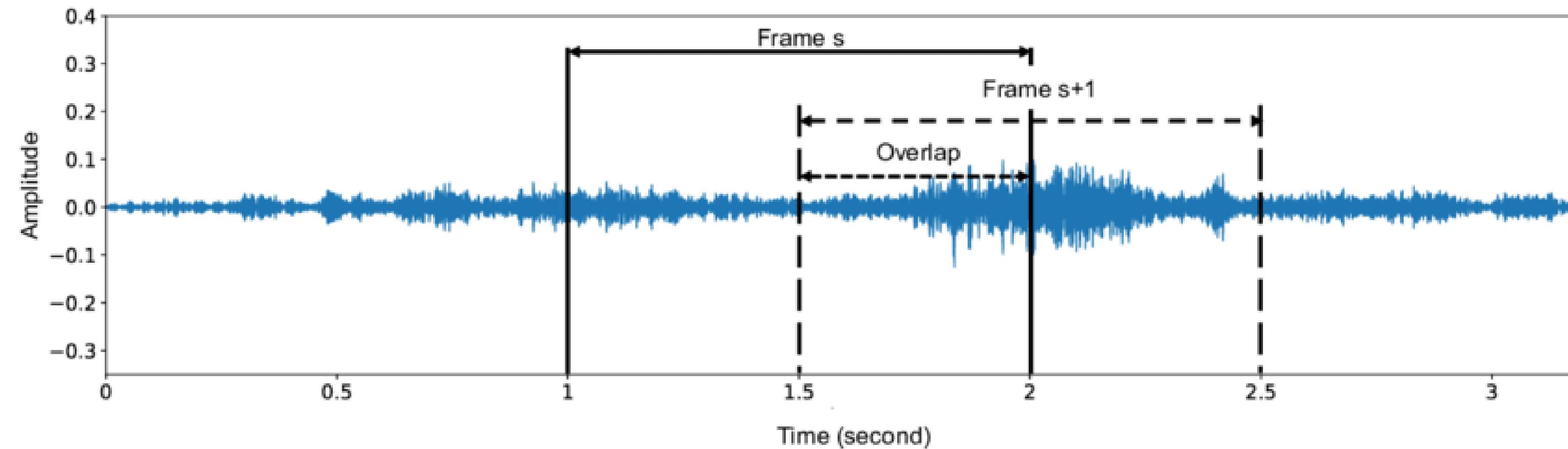


16kHz, 0.75 seconds, 32x32



- Lower frequency range
- Lower frequency resolution
- Lower time duration in window
- Lower time resolution

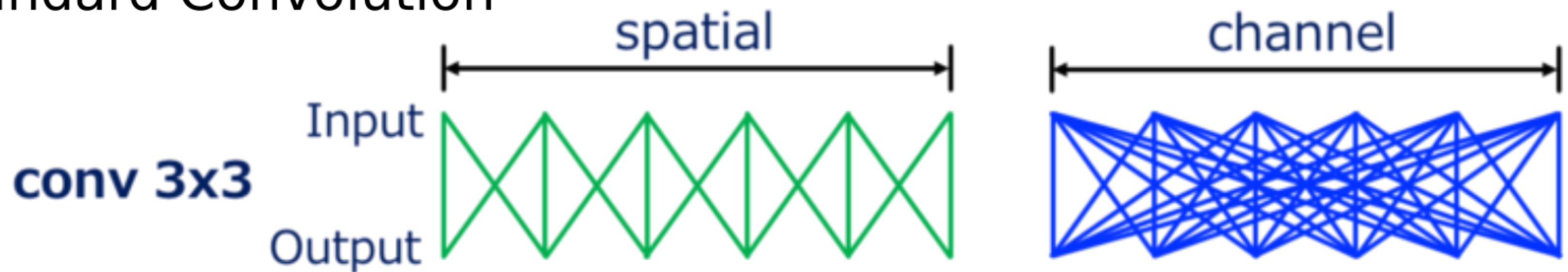
REDUCE OVERLAP



Models in literature use 95% overlap or more. 20x penalty in inference time!
Often low performance benefit. Use 0% (1x) or 50% (2x).

DEPTHWISE-SEPARABLE CONVOLUTION

Standard Convolution



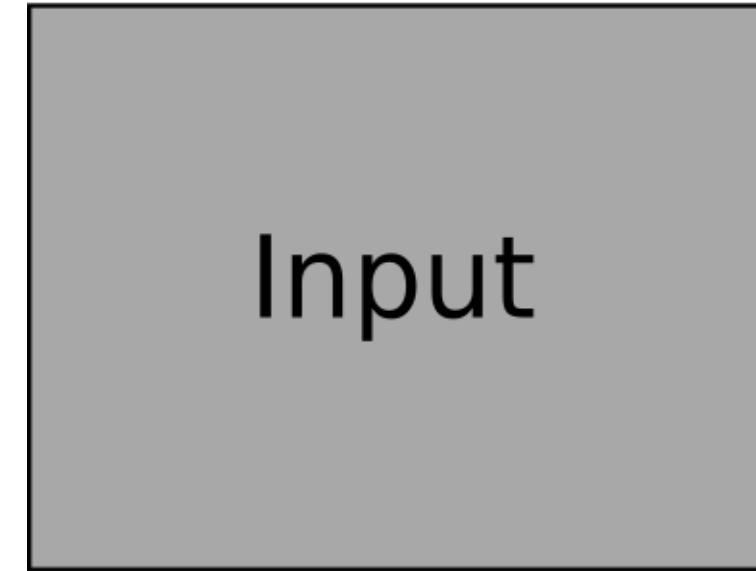
Depthwise Separable Convolution



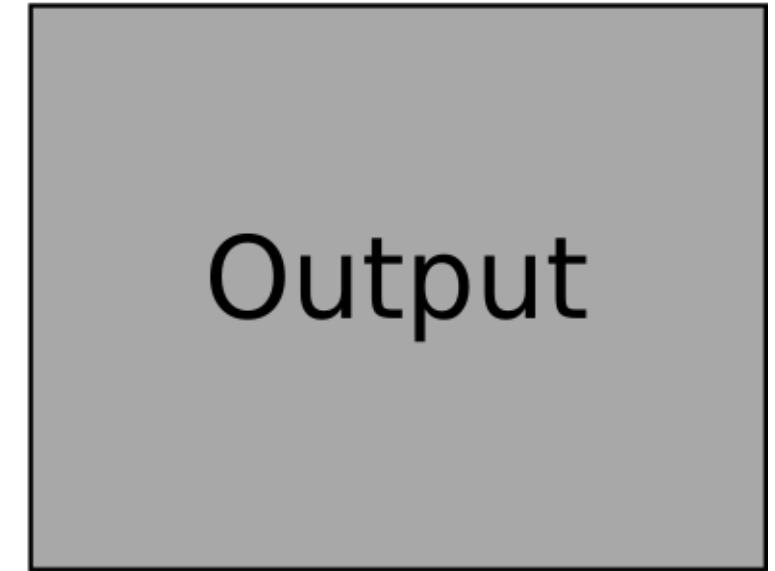
SPATIALLY-SEPARABLE CONVOLUTION

Standard Convolution

3x3
convolution



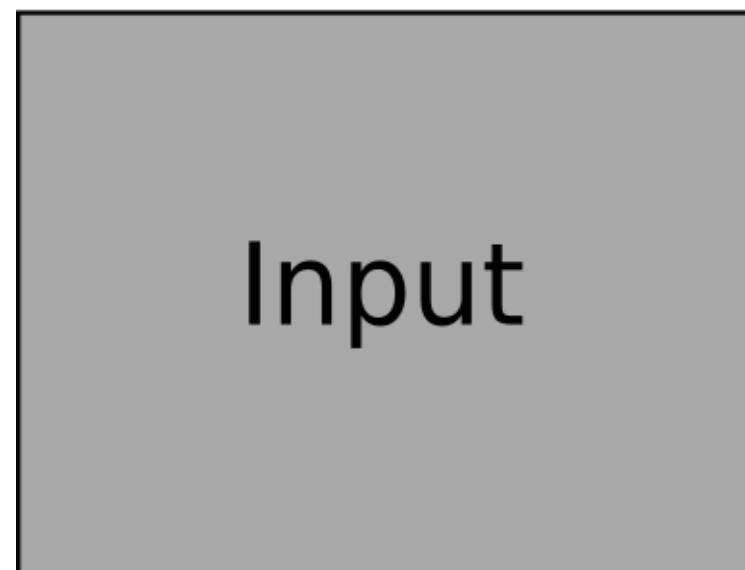
$$\begin{bmatrix} 1 & 0 & -1 \\ 2 & 0 & -2 \\ 1 & 0 & -1 \end{bmatrix}$$



Output

Spatially Separable Convolution

3x1
convolution



$$\begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$$

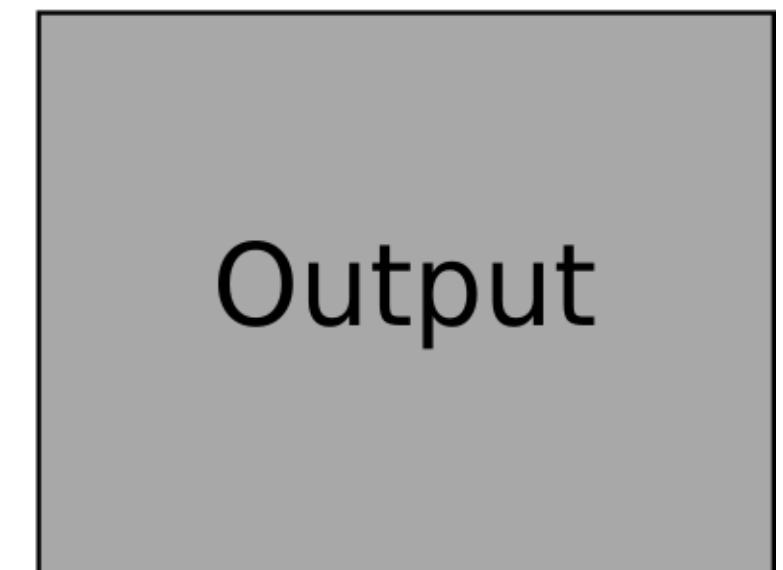


Intermediate

1x3
convolution



$$[+1 \ 0 \ -1]$$



Output

DOWNSAMPLING USING MAX-POOLING

7	2	5	1
3	6	5	8
4	4	4	1
6	3	7	2



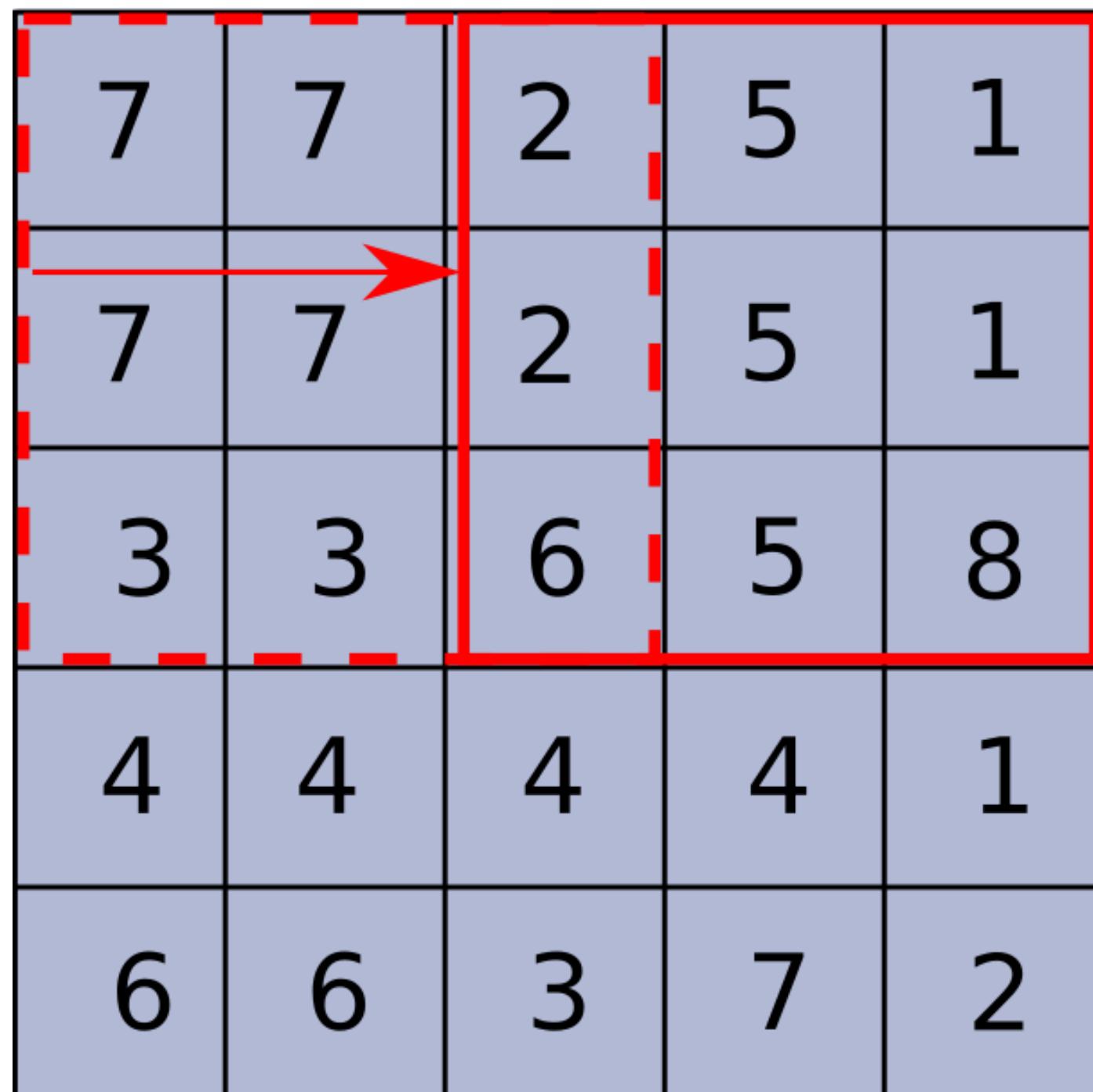
Maxpool
2x2 filter
2x2 stride

7	8
6	7

Wasteful? Computing convolutions, then throwing away 3/4 of results!

DOWNSAMPLING USING STRIDED CONVOLUTION

stride: 2



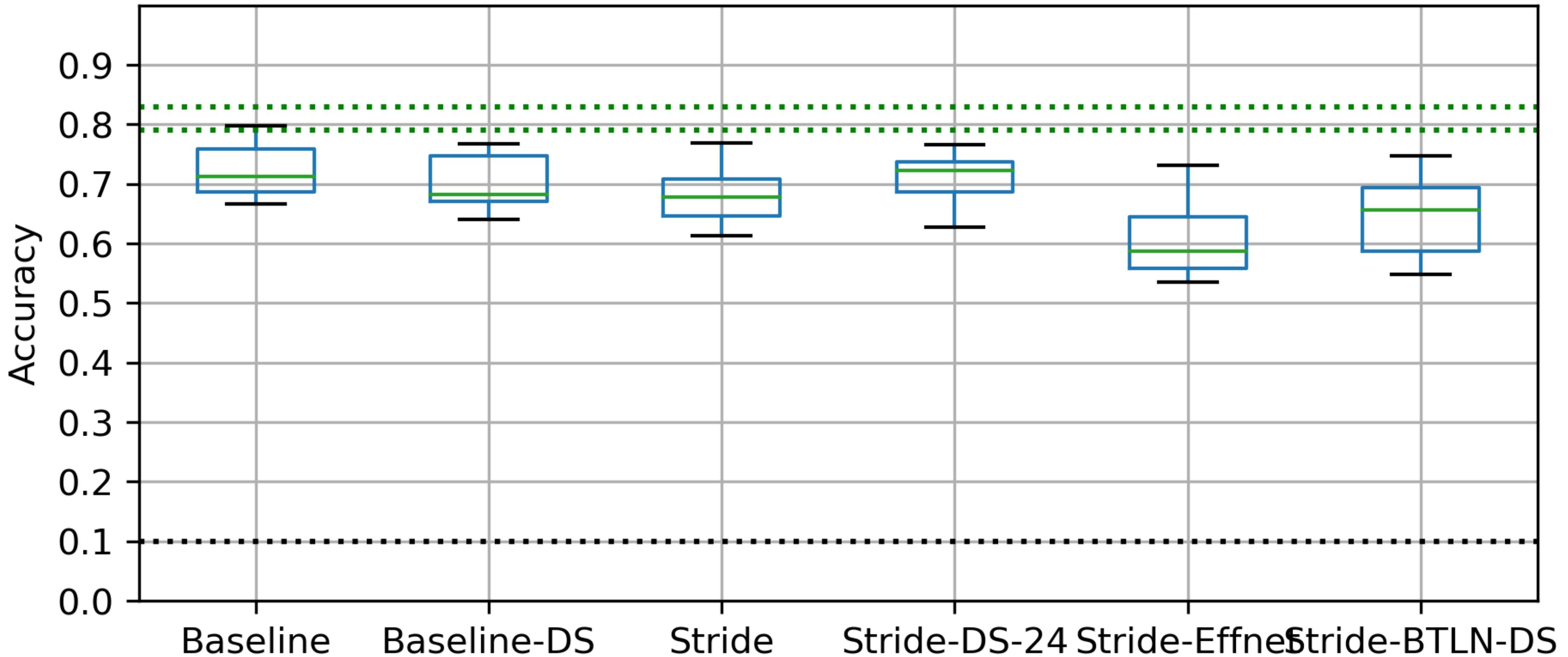
5x5 input

* 3x3 filter = 2x2 output

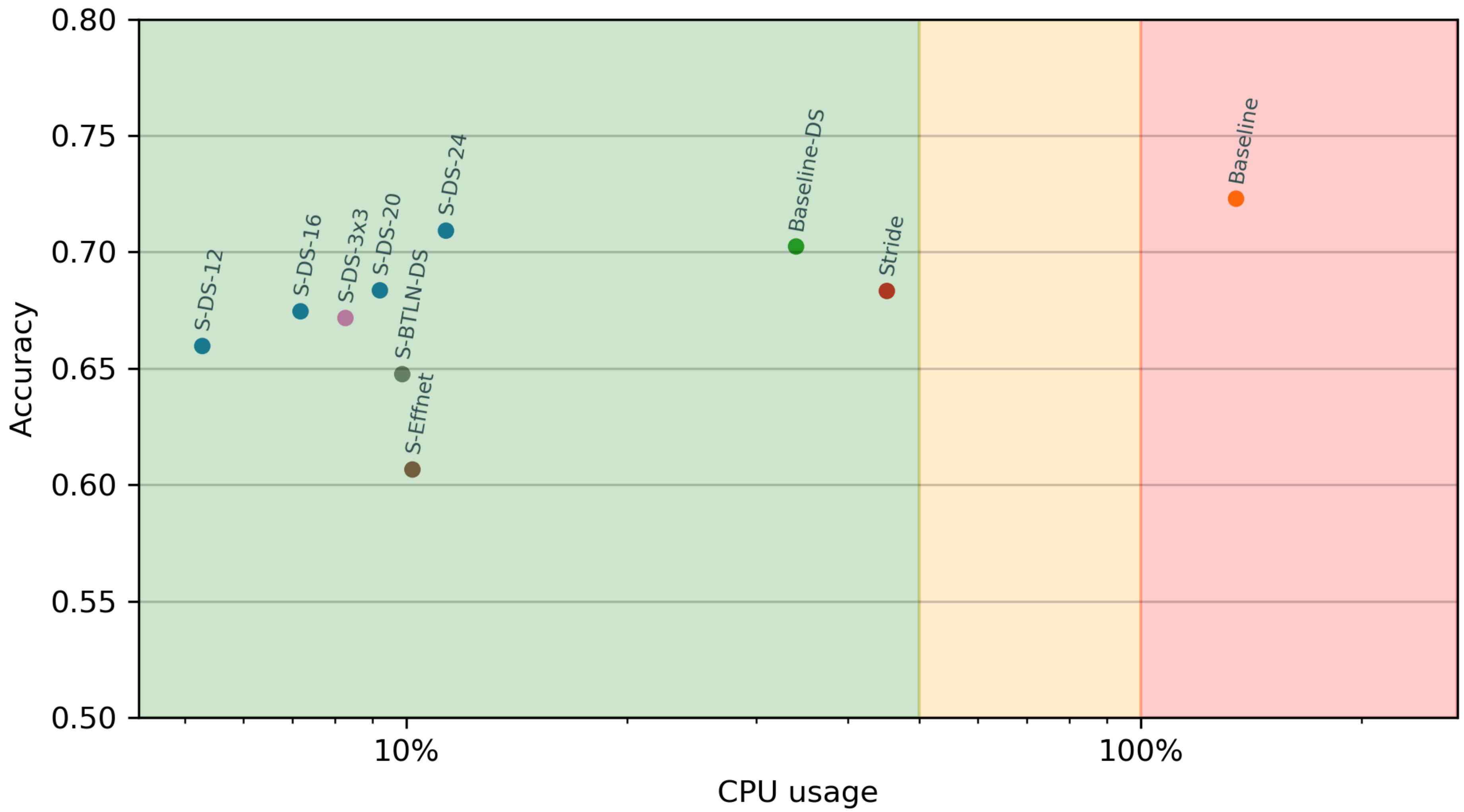
The diagram shows a 3x3 filter with values [1, 1, 1; 0, 0, 0; -1, -1, -1]. This filter is applied to the 5x5 input matrix with a stride of 2. The result is a 2x2 output matrix with values [1, 1; 0, 0], where the top-left element is highlighted with a red border.

1	1	1
0	0	0
-1	-1	-1

MODEL COMPARISON



PERFORMANCE VS COMPUTE



QUANTIZATION

Inference can often use 8 bit integers instead of 32 bit floats

- 1/4 the size for weights (FLASH) and activations (RAM)
- 8bit SIMD on ARM Cortex M4F: 1/4 the inference time
- Supported in X-CUBE-AI 4.x (July 2019)

CONCLUSIONS

- Able to perform Environmental Sound Classification at $\sim 10\text{mW}$ power,
- Using *general purpose microcontroller*, ARM Cortex M4F
- Best performance: 70.9% mean accuracy, under 20% CPU load
- Highest reported Urbansound8k on microcontroller (over eGRU 62%)
- Best architecture: Depthwise-Separable convolutions with striding
- Quantization enables 4x bigger models (and higher perf)
- With dedicated Neural Network Hardware

FURTHER RESEARCH

WAVEFORM INPUT TO MODEL

- Preprocessing. Mel-spectrogram: **60** milliseconds
- CNN. Stride-DS-24: **81** milliseconds
- With quantization, spectrogram conversion is the bottleneck!
- Convolutions can be used to learn a Time-Frequency transformation.

Can this be faster than the standard FFT? And still perform well?

ON-SENSOR INFERENCE CHALLENGES

- Reducing power consumption. Adaptive sampling
- Efficient training data collection in WSN. Active Learning?
- Real-life performance evaluations. Out-of-domain samples

WRAPPING UP

SUMMARY

- Noise pollution is a growing problem
- Wireless Sensor Networks can used to quantify
- Noise Classification can provide more information
- Want high density of sensors. Need to be low cost
- On-sensor classification desirable for power/cost and privacy

MORE RESOURCES

Machine Hearing. ML on Audio

- github.com/jonnor/machinehearing

Machine Learning for Embedded / IoT

- github.com/jonnor/embeddedml

Thesis Report & Code

- github.com/jonnor/ESC-CNN-microcontroller

QUESTIONS

?

Email: jon@soundsensing.no

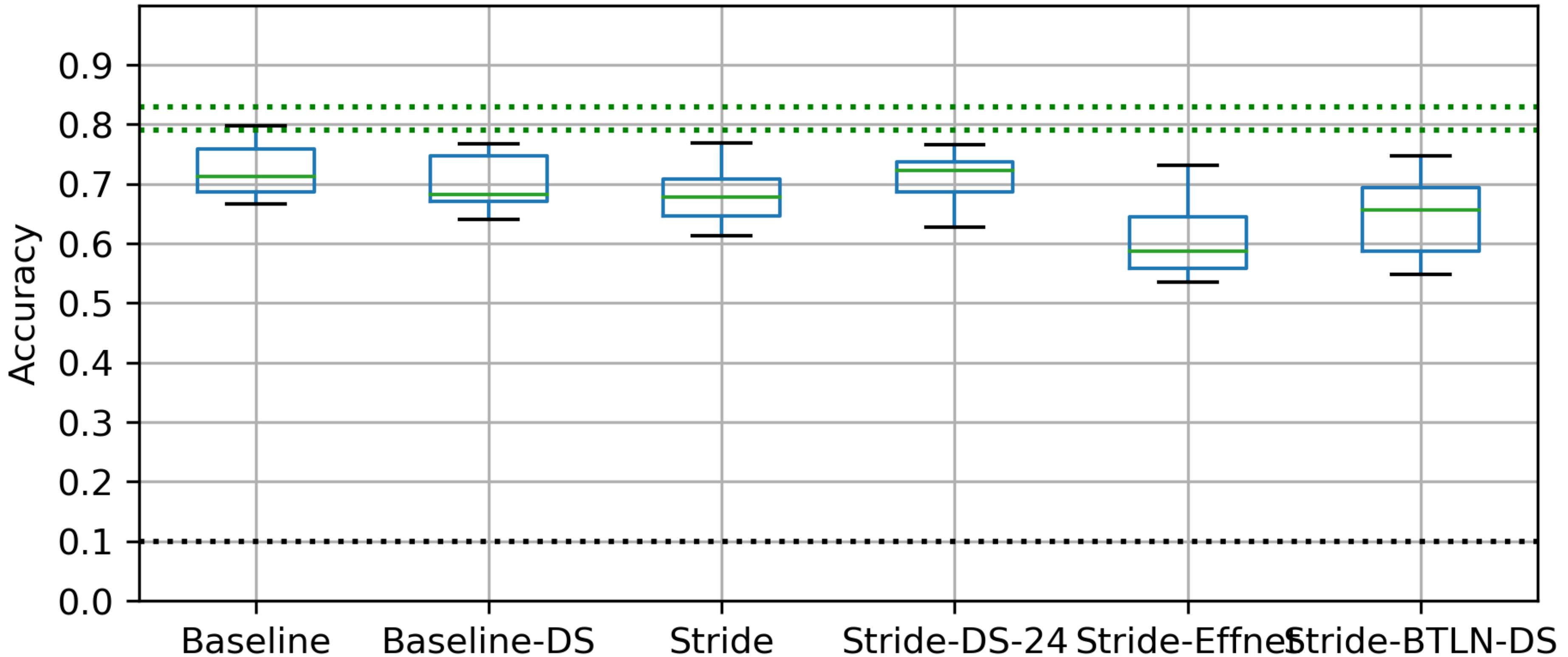
COME TALK TO ME!

- Noise Monitoring sensors. Pilot projects for 2020?
- Environmental Sound, Wireless Sensor Networks for Audio. Research partnering?
- “On-edge” / Embedded Device ML. Happy to advise!

Email: jon@soundsensing.no

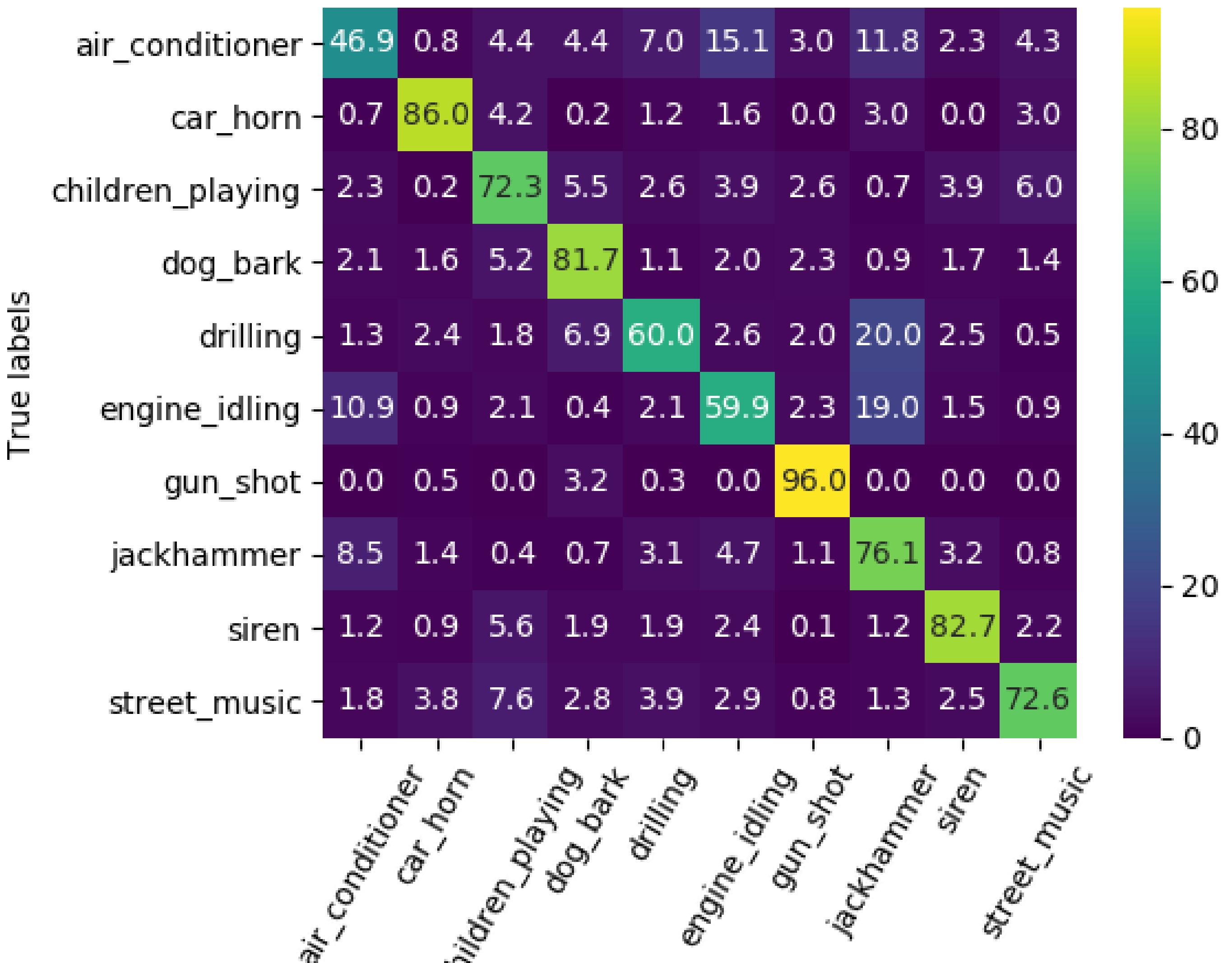
THESIS RESULTS

MODEL COMPARISON



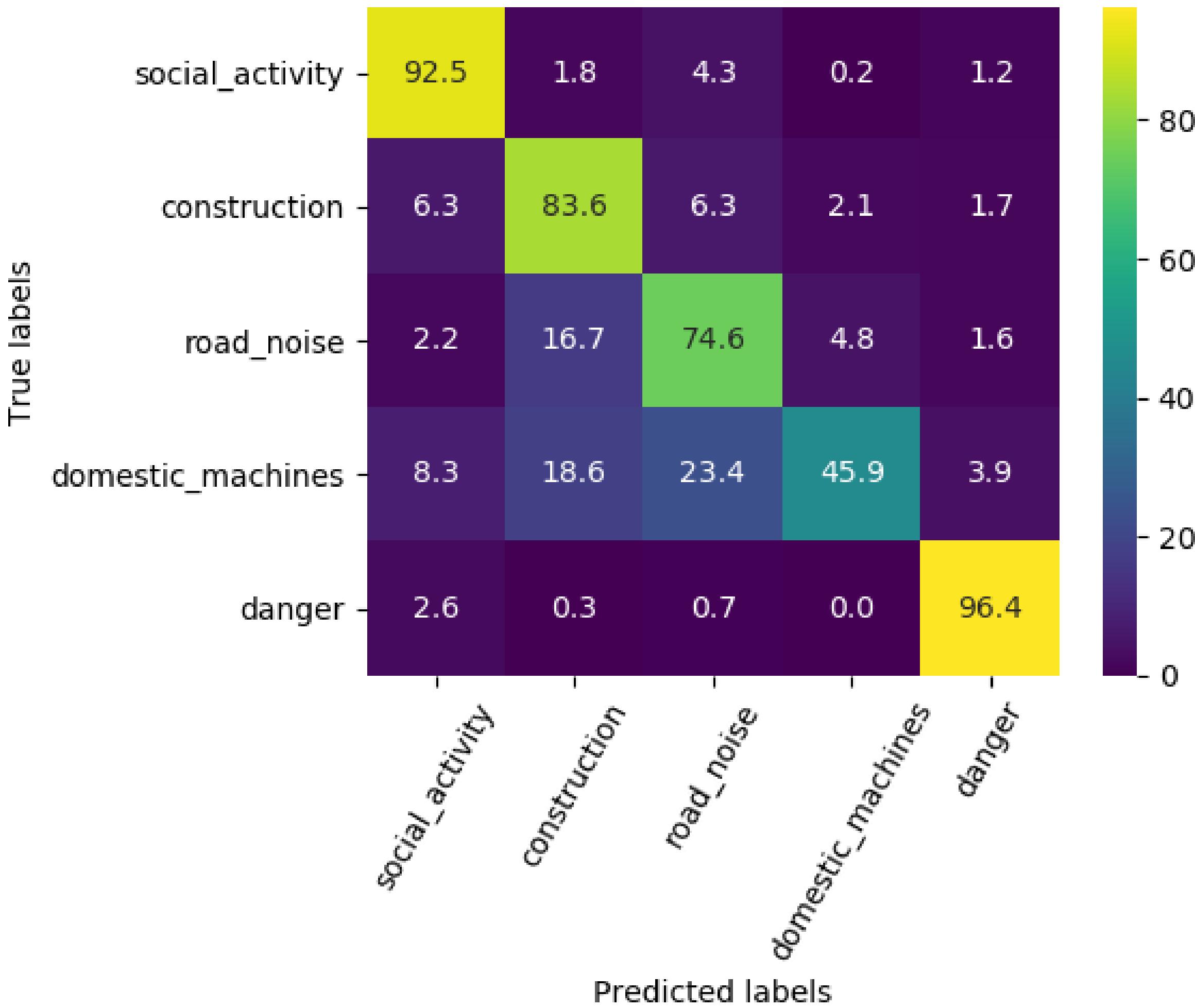
LIST OF RESULTS

Model	CPU use	Accuracy	FG Accuracy	BG Accuracy
Baseline	971 ms	72.3% \pm 4.6	78.3% \pm 7.1	60.5% \pm 7.7
Baseline-DS	244 ms	70.2% \pm 4.7	76.1% \pm 7.5	58.6% \pm 8.2
Stride	325 ms	68.3% \pm 5.2	74.1% \pm 6.6	56.6% \pm 8.0
Stride-BTLN-DS	71 ms	64.8% \pm 7.1	69.5% \pm 8.2	55.3% \pm 8.9
Stride-DS-12	38 ms	66.0% \pm 6.0	72.6% \pm 6.5	53.3% \pm 9.1
Stride-DS-16	51 ms	67.5% \pm 5.6	73.3% \pm 7.7	56.2% \pm 8.3
Stride-DS-20	66 ms	68.4% \pm 5.2	75.0% \pm 7.4	55.2% \pm 10.0
Stride-DS-24	81 ms	70.9% \pm 4.3	75.8% \pm 6.3	61.8% \pm 6.8
Stride-DS-3x3	59 ms	67.2% \pm 6.5	73.0% \pm 7.4	55.8% \pm 9.1
Stride-Effnet	73 ms	60.7% \pm 6.6	66.9% \pm 7.9	48.7% \pm 8.3

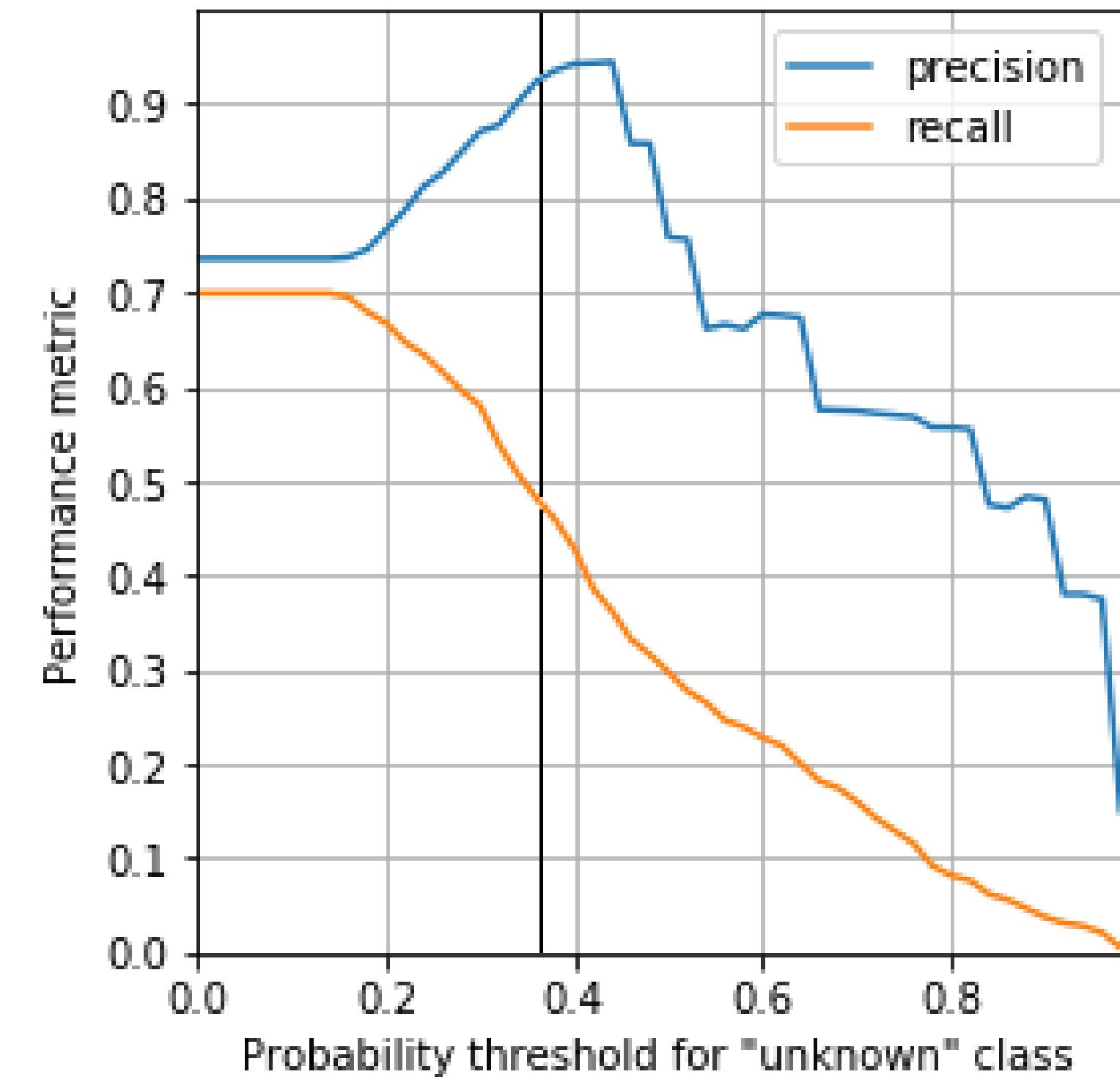
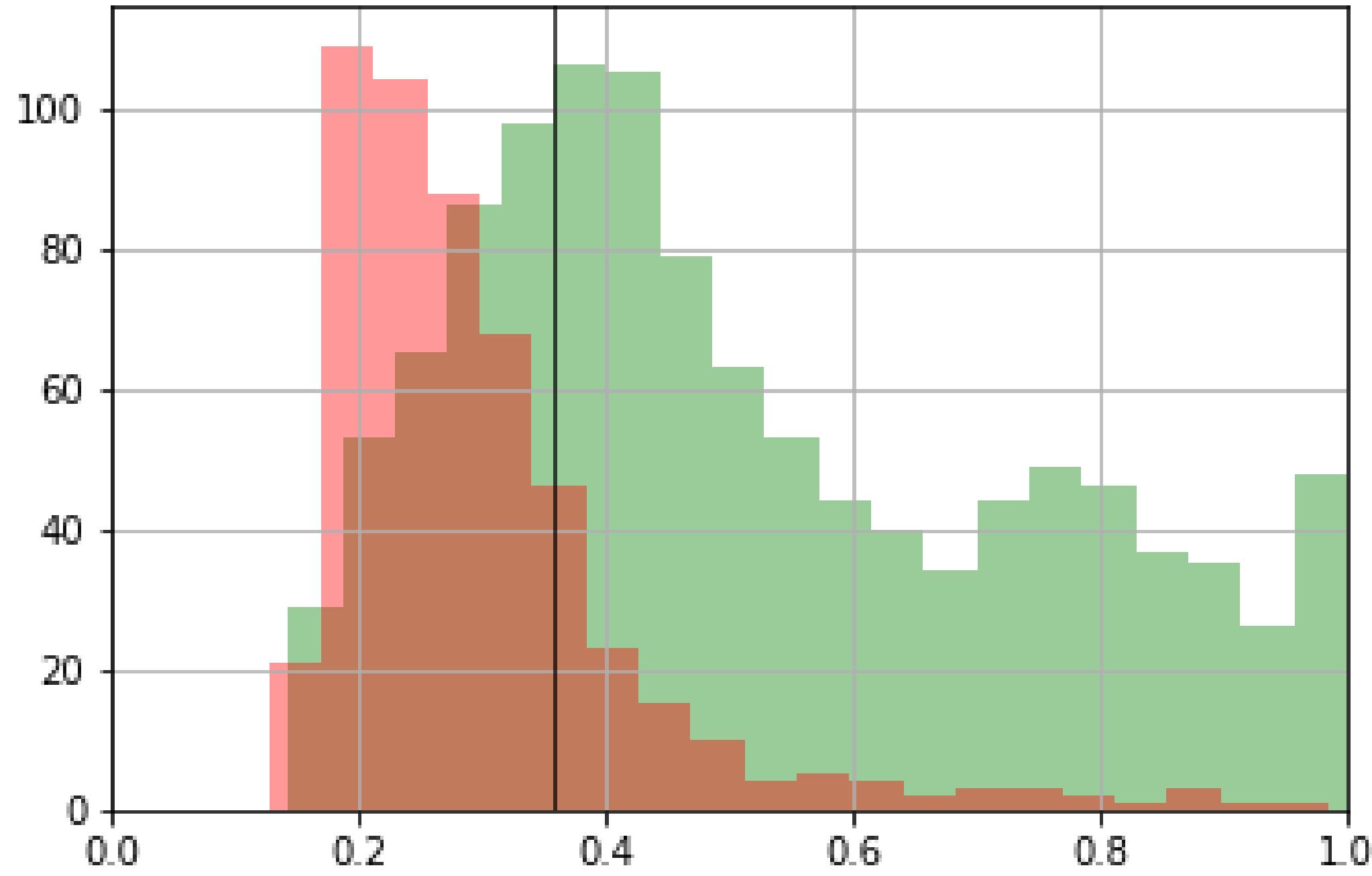


Predicted labels

GROUPED CLASSIFICATION



UNKNOWN CLASS



EXPERIMENTAL DETAILS

ALL MODELS

Model	Downsample	Convolution	L	F	MACC	RAM	FLASH
Baseline	maxpool 3x2	standard	3	24	10185 K	35 kB	405 kB
Baseline-DS	maxpool 3x2	DS	3	24	1567 K	55 kB	96 kB
Stride	stride 2x2	standard	3	22	2980 K	55 kB	372 kB
Stride-BTLN-DS	stride 2x2	BTLN-DS	3	22	445 K	47 kB	80 kB
Stride-DS-12	stride 2x2	DS	3	12	208 K	27 kB	88 kB
Stride-DS-16	stride 2x2	DS	3	16	291 K	36 kB	118 kB
Stride-DS-20	stride 2x2	DS	3	20	380 K	45 kB	149 kB
Stride-DS-24	stride 2x2	DS	3	24	477 K	54 kB	180 kB
Stride-DS-3x3	stride 2x2	DS	4	24	318 K	54 kB	95 kB
Stride-Effnet	stride 2x2	Effnet	3	22	468 K	47 kB	125 kB

METHODS

Standard procedure for Urbansound8k

- Classification problem
- 4 second sound clips
- 10 classes
- 10-fold cross-validation, predefined
- Metric: Accuracy

TRAINING SETTINGS

Samplerate (Hz)	22050
Melfilter bands	60
FFT length (samples)	1024
FFT hop (samples)	512
Classification window	31
Minibatch size	400
Epochs	100
Training samples/epoch	30000
Validation samples/epoch	5000
Learning rate	0.005
Nesterov momentum	NaN

TRAINING

- NVidia RTX2060 GPU 6 GB
- 10 models x 10 folds = 100 training jobs
- 100 epochs
- 3 jobs in parallel
- 36 hours total

EVALUATION

For each fold of each model

1. Select best model based on validation accuracy
2. Calculate accuracy on test set

For each model

- Measure CPU time on device

YOUR MODEL WILL TRICK YOU

And the bugs can be hard to spot

FAIL: INTEGER TRUNCATION

features: Fix integer truncation

Especially combined with meanstd normalization
which makes range (-3,3),
this accidentally removed a lot of details

```
----- microesc/features.py -----
index 9d16d2a..6d9ca59 100644
@@ -152,7 +154,7 @@ def load_sample(sample, settings, feature_dir, window_frames,
    if window_frames is None:
        padded = mels
    else:
-        padded = numpy.full((n_mels, window_frames), 0)
+        padded = numpy.full((n_mels, window_frames), 0.0, dtype=float)
        inp = mels[:, 0:min(window_frames, mels.shape[1])]
        padded[:, 0:inp.shape[1]] = inp
```

FAIL. DROPOUT LOCATION

models: Fix Dropout location

Surprised this was able to train at all before,
as whole classes must have been dropped

Training and validation loss now follow eachother much more closely

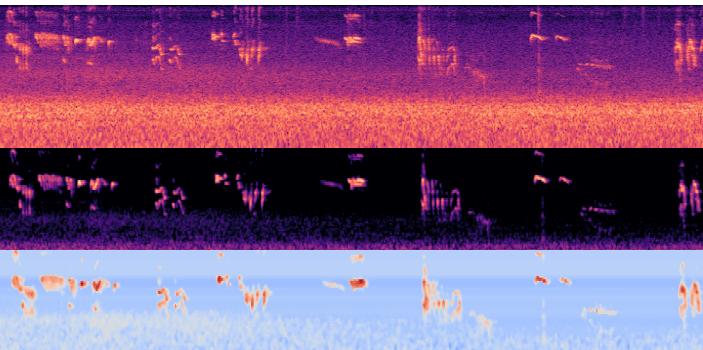
```
----- microesc/models/sbcnn.py -----
index 2e95242..3986bcf 100644
@@ -98,12 +98,12 @@ def backend_densel(x, n_classes, fc=64, regularization=0.001, dropout=0.5):
    """""

    x = Flatten()(x)
+   x = Dropout(dropout)(x)
    x = Dense(fc, kernel_regularizer=l2(regularization))(x)
    x = Activation('relu')(x)
-   x = Dropout(dropout)(x)

-   x = Dense(n_classes, kernel_regularizer=l2(regularization))(x)
    x = Dropout(dropout)(x)
+   x = Dense(n_classes, kernel_regularizer=l2(regularization))(x)
    x = Activation('softmax')(x)
    return x
```

BACKGROUND

MEL-SPECTROGRAM



NOISE POLLUTION

Reduces health due to stress and loss of sleep

In Norway

- 1.9 million affected by road noise (2014, SSB)
- 10'000 healthy years lost per year (Folkehelseinstituttet)

In Europe

- 13 million suffering from sleep disturbance (EEA)
- 900'000 DALY lost (WHO)

NOISE MAPPING

Simulation only, no direct measurements

