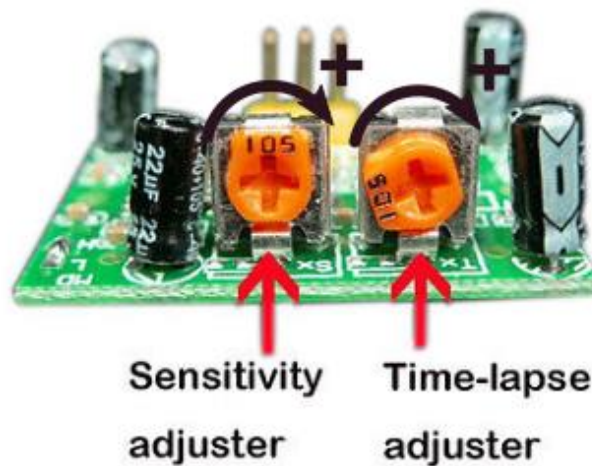
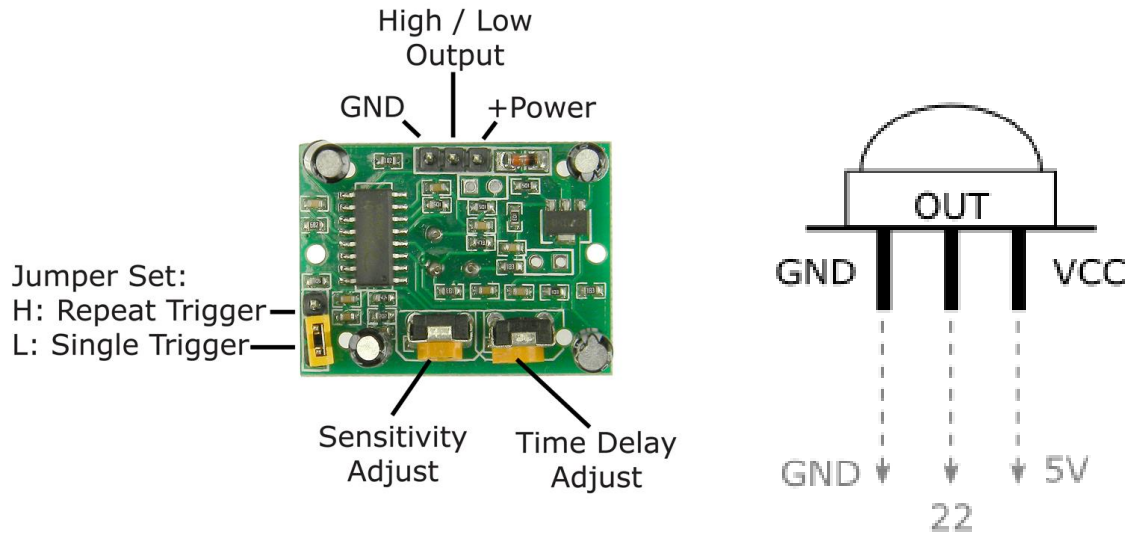


# Raspberry Pi Sensors

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# HC-SR501

PIR (Passive Infra-red) motion sensor



This motion sensor outputs **HIGH** when motion is detected, **LOW** otherwise.

The following code sample only works if you set the jumper to **Repeat Trigger**.

# motion.py

```
import time
from RPi import GPIO

GPIO.setmode(GPIO.BCM)

motion = 22

GPIO.setup(motion, GPIO.IN)

def motion_changed(channel):
    if GPIO.input(channel): ❶
        print('Somebody')
    else:
        print('Nobody')

GPIO.add_event_detect(motion,
                      GPIO.BOTH, ❷
                      callback=motion_changed) ❸

while True:
    time.sleep(1)
```

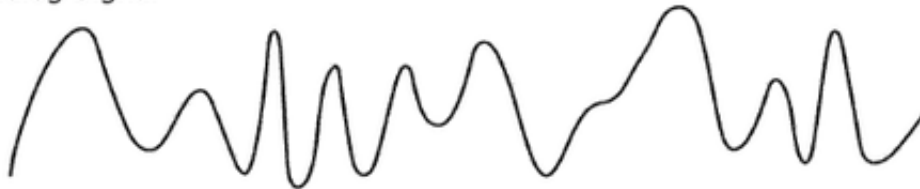
- ❶ Have to check whether it is currently HIGH or LOW because ...
- ❷ We are catching both rising and falling edges.
- ❸ No **bouncetime** needed because motion sensor's output has been smoothed by its internal circuit.

Raspberry Pi is a digital computer, and a digital computer only knows two numbers: 1 and 0.

A lot of physical quantities, e.g. temperature, humidity, wind speed, etc., are smooth-varying numbers. They can take on values such as 25.6, 98.76, or 33.3333333333. These are called analog quantities.

For Raspberry Pi to understand analog quantities, a sensor has to convert those analog quantities to digital signals.

Analog Signal



Digital Signal

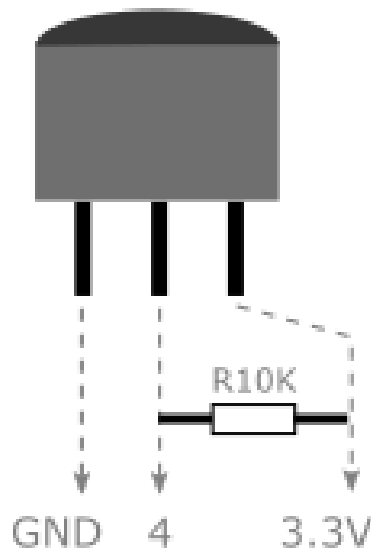


There are many digital "languages". Widely used are 1-wire, I2C, and SPI. You have to configure Raspberry Pi to speak the sensor's "language" before they can communicate.

# DS18B20

temperature sensor

First, we try a temperature sensor. Wire it up according to the diagram below. You will need a 10K pull-up resistor.



It speaks the 1-wire protocol. We have to enable 1-wire on Raspberry Pi.

# Enable 1-wire

```
$ sudo nano /boot/config.txt
```

```
dtoverlay=w1-gpio
```

```
$ sudo reboot
```

```
$ lsmod | grep w1
```

```
$ cd /sys/bus/w1/devices  
$ ls
```

Add this line. It causes Linux to load the 1-wire modules.

Check whether the 1-wire modules are loaded. If not, check previous steps.

What do you see?

## Use the sensor package

```
$ sudo apt-get update
$ sudo apt-get upgrade
```

Install software for I2C:

```
$ sudo apt-get install i2c-tools python3-smbus
```

Install software for SPI:

```
$ sudo apt-get install python3-dev
$ sudo pip3 install spidev
```

Finally, install the sensor package:

```
$ sudo pip3 install sensor
```

```
$ python3
```

```
>>> from sensor.DS18B20 import DS18B20
>>> ds = DS18B20('28-ZZZZZZZZZ')
>>> ds.temperature()
```

What do you see? How do you access different units of the temperature?

```
>>> t = ds.temperature()
>>> t.C
28.937
>>> t.F
84.0866
```

The **sensor** package supports all sensors we are going to use in this course.

Next, we try to display the temperature on an LCD, which speaks the **I2C** protocol. We have to enable I2C on Raspberry Pi.

# Enable I2C

```
$ sudo nano /etc/modules
```

```
i2c-dev
```

```
$ sudo nano /boot/config.txt
```

```
dtoverlay=i2c_arm=on
```

```
$ sudo reboot
```

```
$ lsmod | grep i2c
```

Add this line

Add this line. It causes Linux to load the I2C modules.

Check whether the I2C modules are loaded. If not, check previous steps.

```
$ i2cdetect -y 1
```

	0	1	2	3	4	5	6	7	8	9	a	b	c	d	e	f
00:				--	--	--	--	--	--	--	--	--	--	--	--	--
10:	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--
20:	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--
30:	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--
40:	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--
50:	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--
60:	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--
70:	--	--	--	--	--	--	--	--								

Nothing is on the I2C bus, because nothing has been attached yet.



# HTU21D

humidity and temperature sensor

**Wiring:** nearly identical to LCD1602, except that supply voltage is 3.3V.

```
$ i2cdetect -y 1
```

What is the sensor's address?

```
$ python3
```

```
>>> from sensor.HTU21D import HTU21D
```

```
>>> htu = HTU21D(1, ??address??)
```

```
>>> h = htu.humidity()
```

```
>>> h.RH
```

```
>>> t = htu.temperature()
```

```
>>> t.C
```

# BMP180

pressure and temperature sensor

**Wiring:** nearly identical to LCD1602, except that supply voltage is 3.3V.

```
$ i2cdetect -y 1
```

What is the sensor's address?

```
$ python3
```

```
>>> from sensor.BMP180 import BMP180
```

```
>>> bmp = BMP180(1, ??address??)
```

```
>>> p = bmp.pressure()
```

```
>>> p.hPa
```

```
>>> t = bmp.temperature()
```

```
>>> t.C
```

```
# Look up mean sea level pressure from local observatory.  
# 1009.1 hPa is only for example.
```

```
>>> a = p.altitude(msl=1009.1)
```

```
>>> a.m
```

# Deal with Analog Signals

All sensors we have used so far convert analog quantities to a digital format, so Raspberry Pi can read the numbers readily. **What if we got a sensor that speaks analog signals?**

For example, a **TMP36** temperature sensor outputs a varying voltage proportional to the temperature measured.

Another example is a **photoresistor**, whose resistance changes with light intensity.

How could Raspberry Pi read these non-digital values?

The solution is to insert an **analog-to-digital converter (ADC)** between the sensor and the Pi.



For this course, we are going to detect light intensity using a photoresistor coupled with an ADC chip, either MCP3004 or MCP3008.

# Enable SPI

MCP3004/MCP3008 speaks SPI with Raspberry Pi.

```
$ sudo nano /boot/config.txt
```

```
dtoverlay=spi=on
```

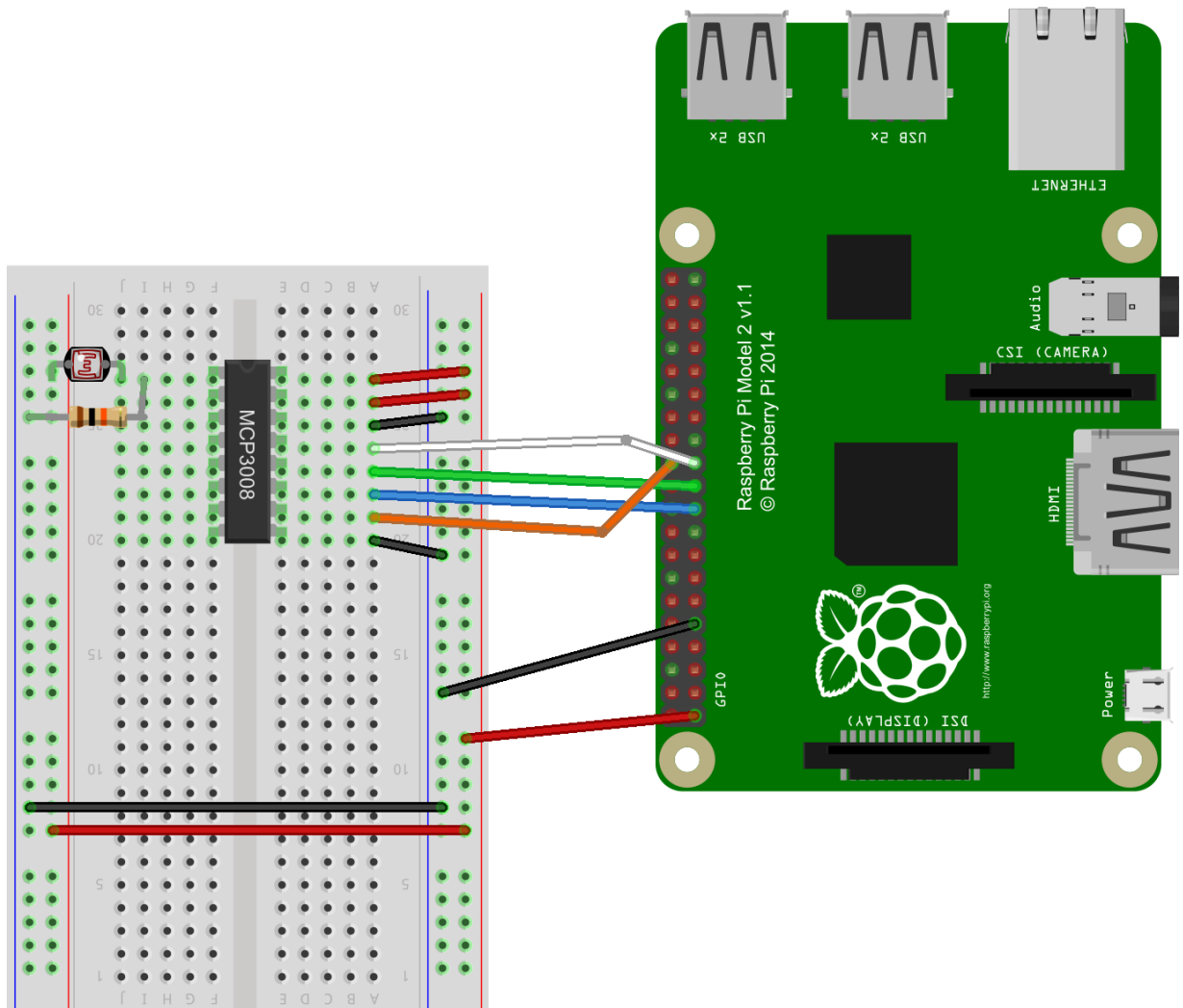
```
$ sudo reboot
```

```
$ lsmod | grep spi
```

Add this line. It causes Linux to load the SPI modules.

Check whether the SPI modules are loaded. If not, check previous steps.

# Photoresistor and MCP3008

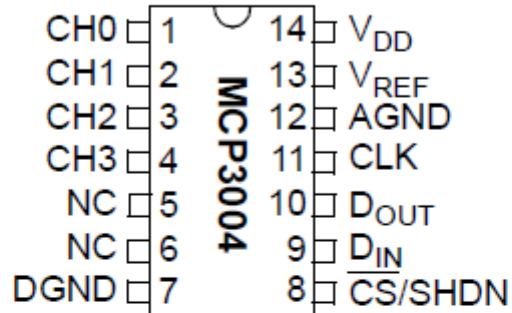


fritzing

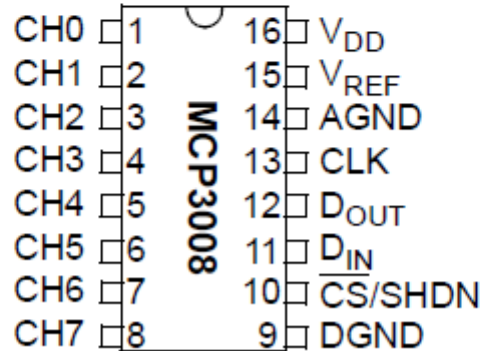
- the ADC uses a chip select of 0
- the reference voltage is 3.3V
- the photoresistor and 10K resistor form a voltage divider, and the result is tapped by channel 0
- as the photoresistor's resistance changes, channel 0's voltage also changes.

## Package Types

### PDIP, SOIC, TSSOP



### PDIP, SOIC



The pinouts of MCP3004 and MCP3008 are very similar. The sensor package, while explicitly supporting MCP3004, can be used to read MCP3008 as well.





















**\$ python3**

```
>>> from sensor.MCP3004 import MCP3004
>>> mcp = MCP3004(bus=0, addr=0, vref=3.3)
>>> mcp.voltage(0) # read channel 0
```

Varying the light intensity, you should notice the voltage changes too.



## Raspberry Pi B+ J8 Header

<i>Pin#</i>	<i>NAME</i>		<i>NAME</i>	<i>Pin#</i>
01	3.3v DC Power		DC Power 5v	02
03	GPIO02 (SDA1 , I2C)		DC Power 5v	04
05	GPIO03 (SCL1 , I2C)		Ground	06
07	GPIO04 (GPIO_GCLK)		(TXD0) GPIO14	08
09	Ground		(RXD0) GPIO15	10
11	GPIO17 (GPIO_GEN0)		(GPIO_GEN1) GPIO18	12
13	GPIO27 (GPIO_GEN2)		Ground	14
15	GPIO22 (GPIO_GEN3)		(GPIO_GEN4) GPIO23	16
17	3.3v DC Power		(GPIO_GEN5) GPIO24	18
19	GPIO10 (SPI_MOSI)		Ground	20
21	GPIO09 (SPI_MISO)		(GPIO_GEN6) GPIO25	22
23	GPIO11 (SPI_CLK)		(SPI_CE0_N) GPIO08	24
25	Ground		(SPI_CE1_N) GPIO07	26
27	ID_SD (I2C ID EEPROM)		(I2C ID EEPROM) ID_SC	28
29	GPIO05		Ground	30
31	GPIO06		GPIO12	32
33	GPIO13		Ground	34
35	GPIO19		GPIO16	36
37	GPIO26		GPIO20	38
39	Ground		GPIO21	40

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