

Rigid Body Kinematics II – Problem 3

For the train wheel shown, find the velocity of the piston at A relative to the track and the angular velocity of the push arm AB when the velocity of the train is $V_o = 80 \text{ fps}$. Assume no slip.

Scalar Solution

STEP 1: CLASSIFY motion

PISTON - TRANSLATION

ARM AB - GPM

WHEEL - GPM

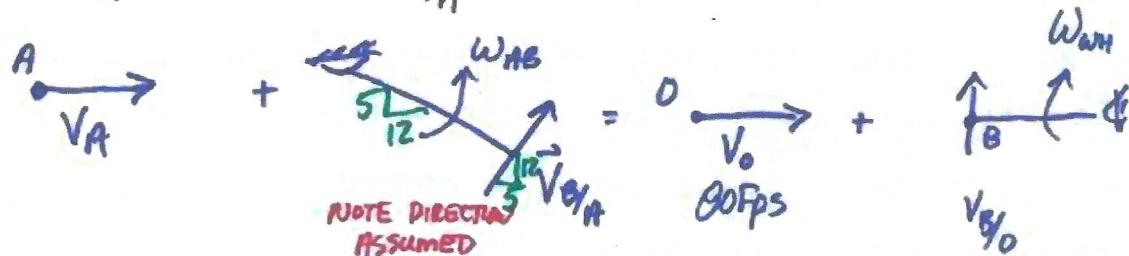
STEP 2: WRITE RELATIVE VELOCITY EQUATION

$$\vec{V}_B = \vec{V}_A + \vec{V}_{B/A} = \vec{V}_o + \vec{V}_{B/O}$$

2 POINTS ON SAME BODY (A+B)

STEP 3: DRAW KINEMATIC DIAGRAMS

$$\vec{V}_A + \vec{V}_{B/A} = \vec{V}_o + \vec{V}_{B/O}$$



STEP 4: WRITE SCALAR EQUATIONS

$$(x) \rightarrow V_A + \frac{5}{13} V_{B/A} = 80 + 0 \quad \begin{matrix} 2 \text{ EQUATIONS} \\ 3 \text{ UNKNOS} \end{matrix}$$

$$(y) \uparrow 0 + \frac{12}{13} V_{B/A} = 0 + V_{B/O}$$

NO SLIP WHEEL

$$V_o = \omega_{WH} r_{WH} \Rightarrow 80 = \omega_{WH}(2) \quad \omega_{WH} = 40 \text{ rps} \rightarrow$$

$$(x) \rightarrow V_A + \frac{5}{13} (\omega_{AB})(6.5) = 80$$

$$(y) \uparrow \frac{12}{13} (\omega_{AB})(6.5) = \omega_{WH}(r_{WH}) = 40(1.5)$$

$$\underline{\underline{\omega_{AB} = 10 \text{ rps}}}$$

$$\underline{\underline{V_A = 55 \text{ Fps}}} \rightarrow$$

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For the train wheel shown, find the velocity of the piston at A relative to the track and the angular velocity of the push arm AB when the velocity of the train is $V_0 = 80 \text{ fps}$. Assume no slip.

Vector Solution

1. CLASSIFY MOTION

PISTON - TRANS

ARM AB - GPM

WHEEL - GPM

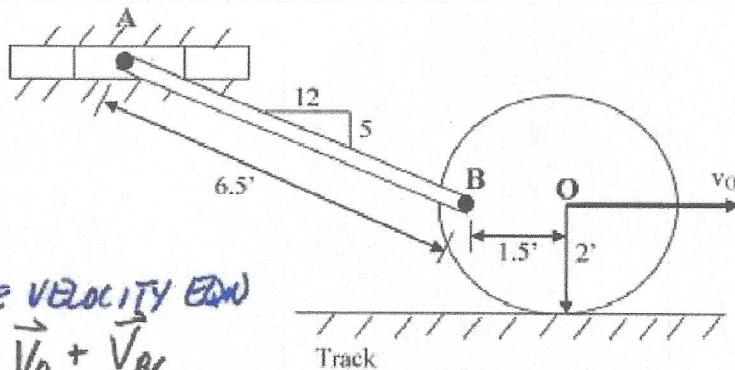
2. WRITE RELATIVE VELOCITY EQU

$$\vec{V}_B = \vec{V}_A + \vec{V}_{B/A} = \vec{V}_0 + \vec{V}_{B/O}$$

RAFA

$$\vec{V}_{B/A} = \vec{\omega}_{AB} \times \vec{r}_{BA}$$

$$\vec{V}_{B/O} = \vec{\omega}_{OB} \times \vec{r}_{BO}$$



3. WRITE VECTOR EQU

$$[V_A \ 0 \ 0] + [0 \ 0 \ \omega_{AB}] \times [6 \ -2.50] = [80 \ 0 \ 0] + [0 \ 0 \ -\omega_{WH}] \times [1500]$$

$$[V_A \ 0 \ 0] + 2.5\omega_{AB} [6\omega_{AB} \ 0] = [80 \ 0 \ 0] + [6 \ 1.5\omega_{WH} \ 0]$$

$$[2.5\omega_{AB} + V_A, 6\omega_{AB}, 0] = [80 \ 1.5\omega_{WH} \ 0]$$

NEED ω_{WH}

NO SLIP WHEEL

$$\vec{V}_0 = \vec{\omega}_{WH} \times \vec{r}_{WH} \Rightarrow [80 \ 0 \ 0] = [0 \ 0 \ -\omega_{WH}] \times [0 \ 2 \ 0]$$

$$[80 \ 0 \ 0] = [2\omega_{WH} \ 0 \ 0]$$

$$\omega_{WH} = 40 \text{ rps} \Rightarrow$$

$$6\omega_{AB} = 1.5\omega_{WH} = 1.5(40) \quad \omega_{AB} = 10 \text{ rps} \Rightarrow$$

$$2.5\omega_{AB} + V_A = 80 \quad V_A = 80 - (2.5(10)) = 55 \text{ fps} \Rightarrow$$