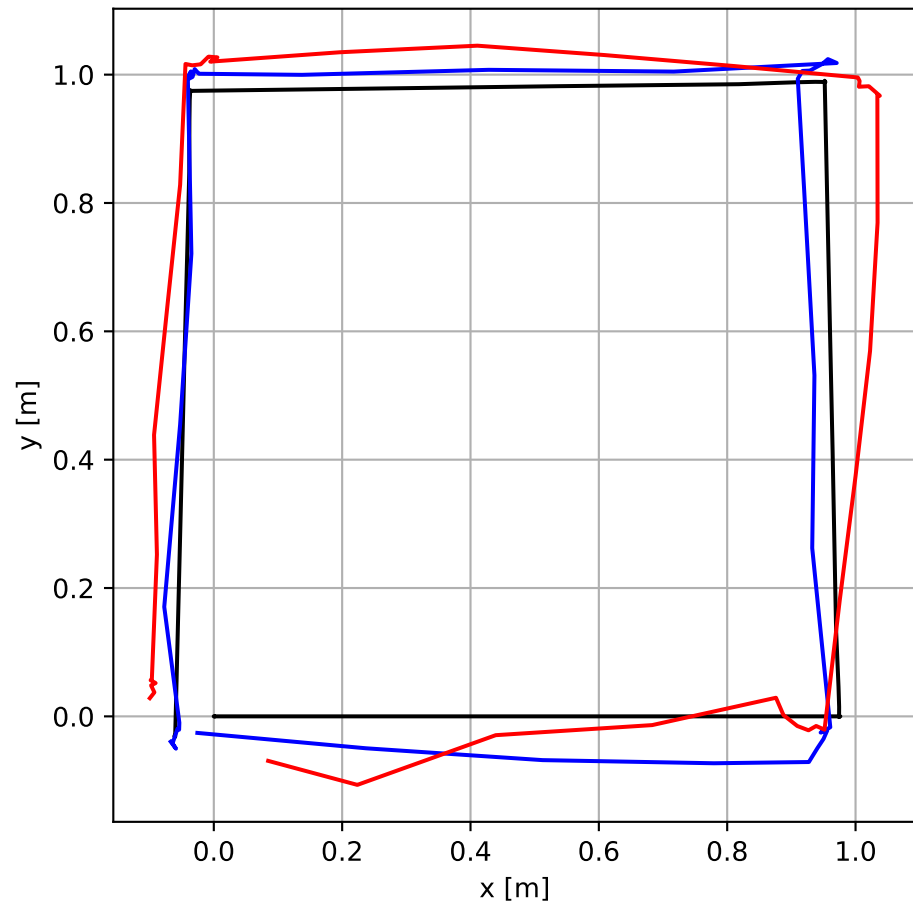
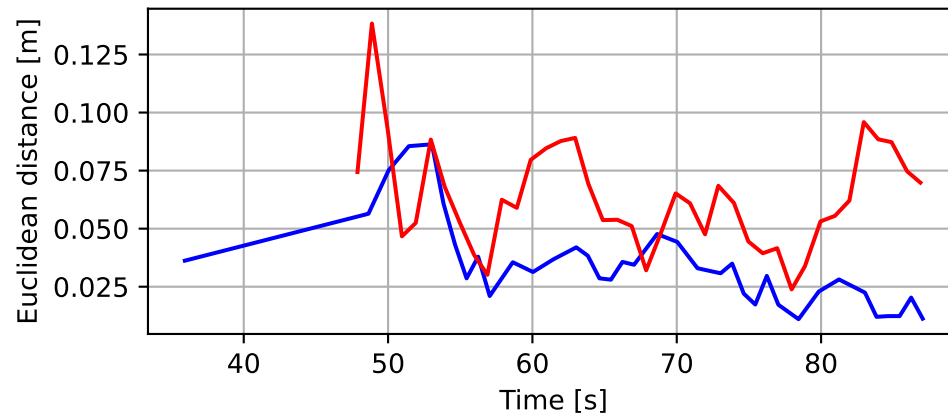


Trajectory comparison



Euclidean distance to Odometry



Angle error compared to Odometry

