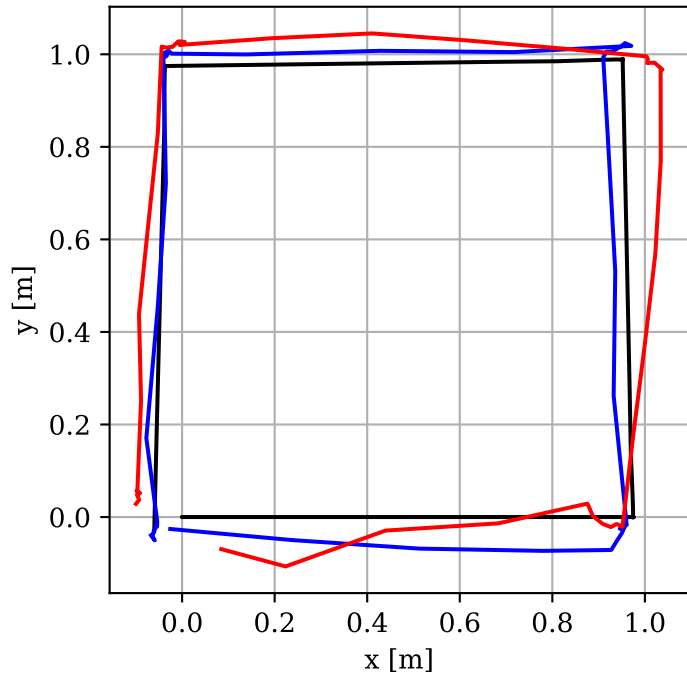
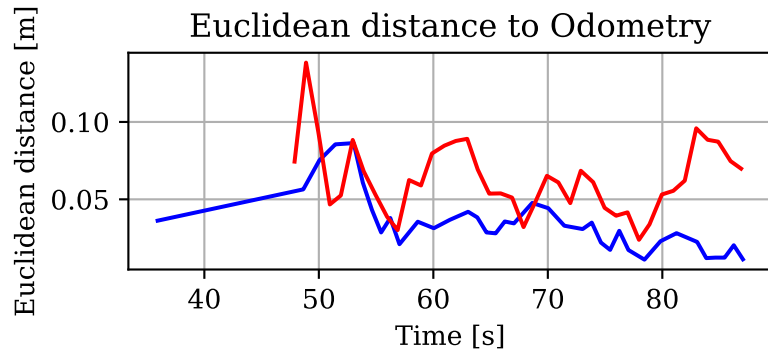


### Trajectory comparison



### Euclidean distance to Odometry



### Angle error compared to Odometry

