

The R-INLA package

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R-INLA: some history

- In the beginning there was

GMRFlib

A C library for fast computations for GMRFs.

- GMRFlib begot

INLA

A C library for fast approximate inference, accessed through .ini files.

- After much wailing and gnashing of teeth there came

R-INLA

which takes R code and writes an appropriate .ini file for the INLA C-program to read.

Obtaining R-INLA

Because of (among other things) the structure with .ini files and an external C library, R-INLA is not on CRAN.

For easy installation instructions, see

<http://www.r-inla.org/download>

The easiest way is probably to open R and write

```
source("http://www.math.ntnu.no/inla/givemeINLA.R")
```

Bayesian structured additive regression models

R-INLA supports hierarchical GMRF models of the following type:

$$y_j | \eta_j, \boldsymbol{\theta}_1 \sim \pi(y_j | \eta_j, \boldsymbol{\theta}_1), \quad j \in J$$

$$\eta_i = \alpha + \mathbf{z}_i^T \boldsymbol{\beta} + \sum_{\gamma} f_{\gamma}(c_{\gamma,i}) + \mathbf{u}_i, \quad i \in I$$

$$\boldsymbol{\theta} = (\boldsymbol{\theta}_1, \boldsymbol{\theta}_2) \sim \pi(\boldsymbol{\theta}), \quad (\text{priors for hyperparameters})$$

where $J \subset I$ and

α : Intercept

$\boldsymbol{\beta}$: linear effects of covariates \mathbf{z}

$\{f_{\gamma}(\cdot)\}$: Non-linear/smooth effects of covariates \mathbf{c}_{γ}

\mathbf{u} : Unstructured error terms

$\mathbf{x} = \{\alpha, \boldsymbol{\beta}, \{f_{\gamma}(\cdot)\}, \mathbf{u}\}$ has a Gaussian prior.

η : enters the likelihood through a known link function $g(\cdot)$.

Examples where models like this are used

- Dynamic linear models
- Stochastic volatility models
- Generalised linear (mixed) models
- Generalised additive (mixed) models
- Spline smoothing
- Semiparametric regression
- Space-varying (semiparametric) regression models
- Disease mapping
- Log-Gaussian Cox-processes
- Model-based geostatistics
- Spatio-temporal models
- Survival analysis
- +++

The structure of an R program using INLA

There are essentially three parts to an INLA program:

- ① The data organisation
- ② The *formula*—notation inherited from R's native `glm` function
- ③ The call to the INLA program.

The inla function

```
> result <- inla(  
  formula,    #This describes your latent field  
  family = "gaussian", #The likelihood distribution.  
  data = dat #A list or dataframe  
  #This is all that's needed for a basic call  
  
  verbose = TRUE, # I use this a lot!  
  keep = FALSE, #Keeps the output  
  
  #Then there are some "control statements"  
  #that allow you to customise some things  
  control.predictor=list(A = ObservationMatrix)  
  )
```

formula: Specifying the latent field

$$\eta_i = \alpha + \mathbf{z}_i^T \boldsymbol{\beta} + \sum_{\gamma} f_{\gamma}(c_{\gamma,i}) + \mathbf{u}_i$$

The latent field is specified using the “standard” R method

`formula = y ~ 1 + covariate + f(...).`

- y is the name of your data in the data frame.
- The `f` function contains the random effect specifications.
- An intercept is fitted *automatically*! Use `-1` in your formula to avoid it.
- The fixed effects (covariates) are taken as i.i.d. normal with a common prior. (This can be changed)

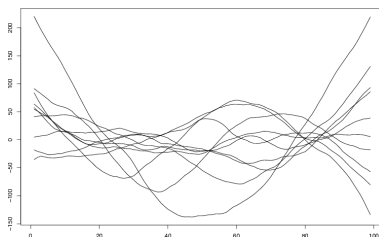
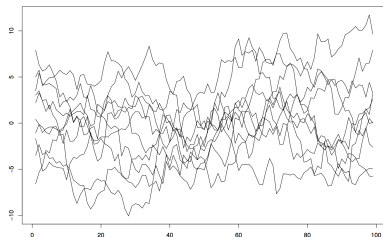
Examples of random effects: Random walks

A random walk (RW) process for “smooth effects” can be used with

```
formula = Y ~ ... + f(covariate, model="rw")
```

A second-order random walk (RW2) for even “smoother” effects can be used with

```
formula = Y ~ ... + f(covariate, model="rw2")
```



SPDE models in INLA

The SPDE models have been incorporated into the INLA package.

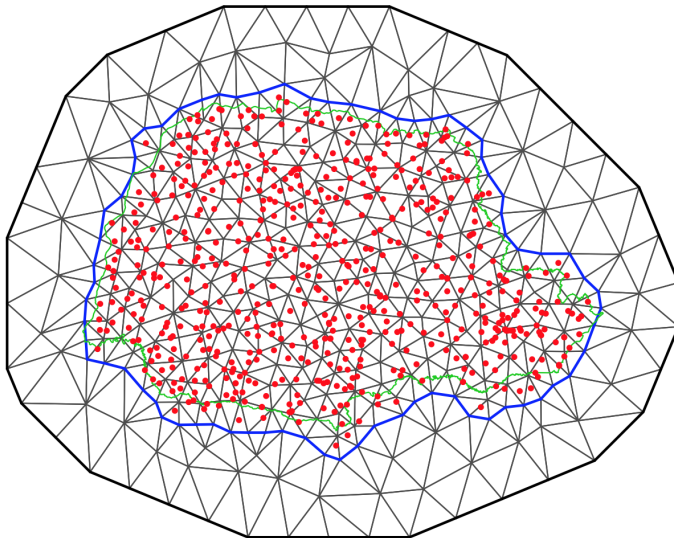
- This means that they work well with INLA!
- But they also work outside of INLA

To specify an SPDE model we need to

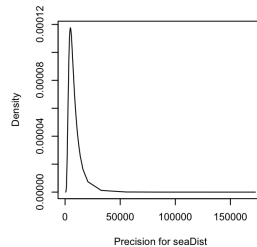
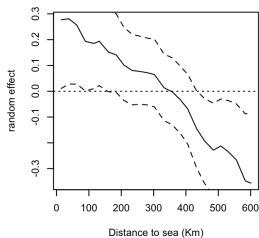
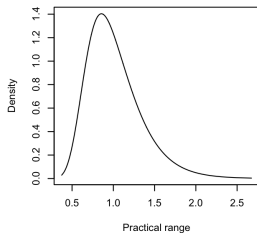
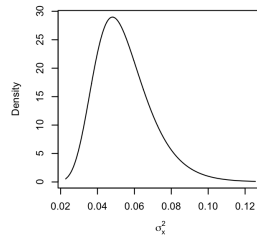
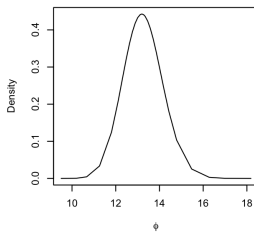
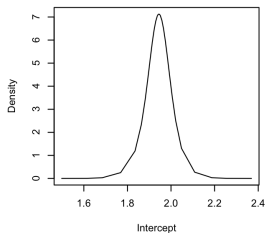
- ① Create the mesh for the model.
- ② Construct the observation matrix that links the measurement locations to the mesh locations.
- ③ Create an `spde` object.

After this, the SPDE model is used like any other random effect model in the formula, using `f(locations, model="spde")`

The mesh



Posteriors for hyperparameters



Kriging results: Gamma (left) and Gaussian (right)

