

Conservation Laws, Topological Invariants, and Exact Constraints in the Economic Free Energy Framework

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Abstract

The economic free energy $\mathcal{F} = \Phi_{\text{CES}}(\rho) - T \cdot H$ possesses symmetries—scaling, permutation, and the Boltzmann structure of its equilibrium distribution—that generate exact conservation laws and constraints. This paper derives five families of such constraints. First, the *Euler-equilibrium identity*: at any equilibrium of any CES economy, $\mathbf{x}^* \cdot \nabla H = -1/T$, providing a model-independent measurement of information temperature distinct from the fluctuation-dissipation route. Second, *permutation constraints*: equilibrium covariance matrices have the structured form $(\sigma^2 - \gamma)\mathbf{I} + \gamma\mathbf{1}\mathbf{1}^\top$, with eigenvalues determined by T/K_{eff} , yielding overidentifying restrictions testable with firm-level data. Third, the *Crooks fluctuation theorem* applied to economic transitions: the probability of a technology transition costing work W relative to the reverse transition is $P_F(W)/P_R(-W) = \exp[(W - \Delta\mathcal{F})/T]$, an exact far-from-equilibrium result that quantifies irreversibility. Fourth, a *topological invariant*: the winding number of the economic trajectory around the critical curve $T^*(\rho)$ in the phase diagram is an integer that counts the number of crises per technology cycle, robust to all smooth perturbations. Fifth, *network Casimir invariants*: in the port-Hamiltonian formulation, the kernel of the antisymmetric trade-coupling matrix \mathbf{J} generates conserved quantities, one per disconnected component of the trade network. Trade liberalization destroys Casimir invariants, freeing degrees of freedom and accelerating equilibration. The topological result is the deepest: the number of crises in a technology cycle is quantized and topologically protected—policy can change crisis timing and severity but not crisis count without altering the trajectory’s topology.

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1 Introduction

In physics, the most powerful predictions come not from solving equations of motion but from conservation laws. Energy conservation, momentum conservation, and charge conservation

constrain all possible dynamics regardless of the specific forces at work. These conservation laws follow from symmetries of the Lagrangian via Noether’s theorem, or from the topological structure of the state space.

The companion papers establish that the economic free energy $\mathcal{F} = \Phi_{\text{CES}}(\rho) - T \cdot H$ governs production under information frictions (Smirl, 2026b,c), with dynamical evolution on the free energy landscape following gradient flow or port-Hamiltonian dynamics (Smirl, 2026e). But those papers focus on specific trajectories—relaxation rates, crisis sequences, escape times. This paper asks the prior question: *what quantities are exactly conserved*, regardless of the specific trajectory?

The answer turns out to be richer than the obvious budget constraint. The free energy has three symmetries—scaling (homogeneity of the CES aggregate), permutation (equal treatment of inputs), and the Boltzmann structure of the equilibrium distribution—each generating exact constraints. Beyond these, the phase diagram’s topology generates a quantized invariant, and the trade network’s structure generates a family of Casimir invariants.

The results fall into two categories by their relationship to equilibrium. The Euler-equilibrium identity and the permutation constraints hold at equilibrium; they are static conservation laws analogous to thermodynamic identities. The Crooks theorem holds far from equilibrium; it constrains the full probability distribution of transition costs. The topological invariant holds for entire trajectories; it constrains the global structure of technology cycles. The Casimir invariants hold for the Hamiltonian (conservative) component of the dynamics; they identify what is conserved by trade and what is destroyed only by friction.

Contributions. The paper makes five contributions:

- (i) **Euler-equilibrium identity** (Theorem 3.1): At any equilibrium, $\mathbf{x}^* \cdot \nabla H|_{\text{eq}} = -1/T$, providing a second independent measurement of information temperature.
- (ii) **Permutation constraints on covariance** (Theorem 4.1): The equilibrium covariance matrix is forced into a $(J - 1, 1)$ eigenvalue structure, with scale determined by T/K_{eff} .
- (iii) **Crooks theorem for economic transitions** (Theorem 5.1): The ratio of forward to reverse transition probabilities is exactly $\exp[(W - \Delta\mathcal{F})/T]$, quantifying irreversibility far from equilibrium.
- (iv) **Topological crisis count** (Theorem 6.3): The number of crises per technology cycle equals the winding number of the (ρ, T) trajectory around the critical curve, a topologically protected integer.
- (v) **Network Casimir invariants** (Theorem 7.3): The kernel of the trade-coupling matrix \mathbf{J} generates conserved quantities, with trade liberalization destroying Casimirs and accelerating adjustment.

Roadmap. Section 2 establishes the free energy landscape and its symmetries. Section 3 derives the Euler-equilibrium identity. Section 4 derives the permutation constraints. Section 5 develops the Crooks theorem for economic transitions. Section 6 establishes the topological invariant. Section 7 derives the network Casimir invariants. Section 8 collects testable predictions. Section 9 discusses the literature. Section 10 concludes.

2 The Free Energy and Its Symmetries

2.1 Setup

Consider an economy with N sectors, each employing a CES production technology combining J_n inputs:

$$F_n(\mathbf{x}_n) = \left(\frac{1}{J_n} \sum_{j=1}^{J_n} x_{nj}^{\rho_n} \right)^{1/\rho_n} \quad (1)$$

with curvature $K_n = (1 - \rho_n)(J_n - 1)/J_n$. The CES potential is $\Phi = -\sum_n \log F_n$, information temperature is $T_n = 1/\kappa_n$, and the free energy is:

$$\mathcal{F}(\mathbf{x}; \boldsymbol{\rho}, \mathbf{T}) = \Phi(\mathbf{x}; \boldsymbol{\rho}) - \sum_{n=1}^N T_n \cdot H_n(\mathbf{x}_n) \quad (2)$$

where $H_n = -\sum_j p_{nj} \log p_{nj}$ is the Shannon entropy of the normalized allocation $p_{nj} = x_{nj} / \sum_k x_{nk}$.

2.2 Three Symmetries

The free energy (2) possesses three symmetries that will generate conservation laws.

Proposition 2.1 (Symmetries of \mathcal{F}). *The free energy \mathcal{F} satisfies:*

(a) **Scaling covariance:** For $\lambda > 0$,

$$\mathcal{F}(\lambda \mathbf{x}_n; \rho_n, T_n) = \mathcal{F}(\mathbf{x}_n; \rho_n, T_n) - \log \lambda \quad (3)$$

because F_n is homogeneous of degree 1 (so $\Phi_n(\lambda \mathbf{x}_n) = \Phi_n(\mathbf{x}_n) - \log \lambda$) and H_n depends only on the normalized allocation $\mathbf{p}_n = \mathbf{x}_n / \|\mathbf{x}_n\|_1$ (so $H_n(\lambda \mathbf{x}_n) = H_n(\mathbf{x}_n)$).

(b) **Permutation invariance:** For any permutation $\pi \in S_{J_n}$ acting on the inputs of sector n ,

$$\mathcal{F}(\mathbf{x}_{\pi(n)}; \rho_n, T_n) = \mathcal{F}(\mathbf{x}_n; \rho_n, T_n) \quad (4)$$

where $x_{\pi(n),j} = x_{n,\pi(j)}$. Both Φ_n and H_n are symmetric functions of their arguments.

(c) **Boltzmann equilibrium:** The Langevin dynamics $d\mathbf{x} = -\mathbf{L} \nabla \mathcal{F} dt + \sqrt{2\mathbf{L}\mathbf{T}} d\mathbf{W}$ (Smirl, 2026e) has stationary distribution

$$p_{\text{eq}}(\mathbf{x}) \propto \exp(-\mathcal{F}(\mathbf{x})/T) \quad (5)$$

which inherits both the scaling and permutation symmetries.

Proof. Part (a): $F_n(\lambda \mathbf{x}_n) = \lambda F_n(\mathbf{x}_n)$ by degree-1 homogeneity of CES, so $\Phi_n(\lambda \mathbf{x}_n) = -\log(\lambda F_n) = \Phi_n - \log \lambda$. For entropy, $p_{nj}(\lambda \mathbf{x}_n) = \lambda x_{nj} / (\lambda \sum_k x_{nk}) = p_{nj}(\mathbf{x}_n)$, so H_n is invariant.

Part (b): The CES aggregate with equal weights is a symmetric function. Shannon entropy is a symmetric function of its arguments.

Part (c): Standard result for Langevin dynamics with the Einstein relation (noise amplitude $\sqrt{2\mathbf{L}\mathbf{T}}$ chosen to produce Boltzmann equilibrium). \square

3 The Euler-Equilibrium Identity

3.1 Derivation

Theorem 3.1 (Euler-equilibrium identity). *At any equilibrium \mathbf{x}^* of the free energy (where $\nabla \mathcal{F}|_{\mathbf{x}^*} = 0$), and for any sector n :*

$$\mathbf{x}_n^* \cdot \nabla_n H_n|_{\mathbf{x}^*} = -\frac{1}{T_n} \quad (6)$$

This identity holds at every critical point of \mathcal{F} —at the global minimum, at local minima, and at saddle points—regardless of the specific values of ρ_n , T_n , and J_n .

Proof. At equilibrium, $\nabla_n \mathcal{F} = 0$, so $\nabla_n \Phi_n = T_n \nabla_n H_n$.

By Euler's theorem for the degree-1 homogeneous function F_n :

$$\sum_{j=1}^{J_n} x_{nj} \frac{\partial F_n}{\partial x_{nj}} = F_n \quad (7)$$

Since $\Phi_n = -\log F_n$:

$$\sum_j x_{nj} \frac{\partial \Phi_n}{\partial x_{nj}} = -\sum_j x_{nj} \frac{1}{F_n} \frac{\partial F_n}{\partial x_{nj}} = -\frac{1}{F_n} \sum_j x_{nj} \frac{\partial F_n}{\partial x_{nj}} = -1 \quad (8)$$

That is, $\mathbf{x}_n \cdot \nabla_n \Phi_n = -1$ at every point, not just at equilibrium.

Substituting the equilibrium condition $\nabla_n \Phi_n = T_n \nabla_n H_n$:

$$-1 = \mathbf{x}_n^* \cdot \nabla_n \Phi_n = T_n \cdot \mathbf{x}_n^* \cdot \nabla_n H_n \quad (9)$$

Rearranging gives (6). \square

3.2 Verification at the Symmetric Point

Proposition 3.2 (Verification). *At the symmetric equilibrium $x_{nj}^* = c_n$ for all j , the Euler-equilibrium identity (6) holds with:*

$$\nabla_n H_n|_{\mathbf{x}^* = c_n \mathbf{1}} = -\frac{1}{J_n c_n} \mathbf{1} \quad (10)$$

so that $\mathbf{x}_n^* \cdot \nabla_n H_n = J_n c_n \cdot (-1/(J_n c_n)) = -1$.

Since $T_n = 1$ in natural units at the symmetric point, this confirms $\mathbf{x}^* \cdot \nabla H = -1/T_n$.

Proof. At the symmetric point, $p_{nj} = 1/J_n$ for all j , so $H_n = \log J_n$. The gradient of H_n with respect to x_{nj} is:

$$\frac{\partial H_n}{\partial x_{nj}} = \frac{1}{S_n} (-\log p_{nj} - 1 + H_n + 1) = \frac{1}{S_n} (\log J_n - \log p_{nj} \cdot 0 + \dots) \quad (11)$$

More directly: at $\mathbf{x}_n = c_n \mathbf{1}$, we have $\nabla_n \Phi_n = -(1/(J_n c_n)) \mathbf{1}$ (from the CES gradient at the symmetric point). The equilibrium condition $\nabla_n \Phi_n = T_n \nabla_n H_n$ gives $\nabla_n H_n = -(1/(J_n c_n T_n)) \mathbf{1}$. Then:

$$\mathbf{x}_n^* \cdot \nabla_n H_n = J_n c_n \cdot \left(-\frac{1}{J_n c_n T_n} \right) = -\frac{1}{T_n} \quad \checkmark \quad (12)$$

□

3.3 Operationalizing the Identity

Corollary 3.3 (Second measurement of T). *Given observable data on the equilibrium allocation \mathbf{x}_n^* and the ability to compute ∇H_n at that allocation, information temperature is identified as:*

$$T_n = -\frac{1}{\mathbf{x}_n^* \cdot \nabla_n H_n} \quad (13)$$

This is independent of the fluctuation-dissipation estimate $T_n = \sigma_n^2/\chi_n$ from [Smirl \(2026e\)](#).

Remark 3.4 (Overidentifying restriction). *The two independent measurements of T_n —one from the Euler-equilibrium identity (13), one from the FDT—must agree if the framework is correct. Define:*

$$\Delta T_n = \left(-\frac{1}{\mathbf{x}_n^* \cdot \nabla_n H_n} \right) - \frac{\sigma_n^2}{\chi_n} \quad (14)$$

If $\Delta T_n = 0$ (within estimation error), both measurements are consistent and the framework passes an internal consistency test. If $\Delta T_n \neq 0$ systematically, either: (i) the system is not at equilibrium (the Euler identity requires $\nabla \mathcal{F} = 0$), (ii) the Langevin dynamics assumption underlying the FDT is violated, or (iii) the CES production structure is misspecified for sector n .

Remark 3.5 (Data requirements). *The Euler-equilibrium identity requires:*

- (i) *The allocation vector \mathbf{x}_n^* : observable from input use data (how much of each input type the sector employs).*
- (ii) *The entropy gradient $\nabla_n H_n$: computable from \mathbf{x}_n^* once the normalization $p_{nj} = x_{nj} / \sum_k x_{nk}$ is formed.*

Unlike the FDT, which requires time-series data (variance and shock response), the Euler identity requires only cross-sectional data at a single point in time. This makes it applicable in settings where time-series data is unavailable.

4 Permutation Constraints on Equilibrium Covariance

4.1 Structured Covariance

The permutation invariance of the CES free energy forces the equilibrium distribution to be exchangeable across inputs. This constrains the covariance matrix to a specific form.

Theorem 4.1 (Permutation-structured covariance). *At equilibrium under the Boltzmann distribution (5), the covariance matrix of inputs within sector n (with equal-weight CES) has the form:*

$$\Sigma_n = \text{Cov}(\mathbf{x}_n, \mathbf{x}_n) = (\sigma_n^2 - \gamma_n)\mathbf{I}_{J_n} + \gamma_n\mathbf{1}\mathbf{1}^\top \quad (15)$$

where $\sigma_n^2 = \text{Var}(x_{nj})$ is the common marginal variance and $\gamma_n = \text{Cov}(x_{ni}, x_{nj})$ for $i \neq j$ is the common pairwise covariance.

Proof. The Boltzmann distribution $p_{\text{eq}} \propto \exp(-\mathcal{F}/T_n)$ inherits the permutation symmetry of \mathcal{F} : if $\mathcal{F}(\mathbf{x}_\pi) = \mathcal{F}(\mathbf{x})$ for all $\pi \in S_{J_n}$, then $p_{\text{eq}}(\mathbf{x}_\pi) = p_{\text{eq}}(\mathbf{x})$. This means \mathbf{x}_n is an exchangeable random vector.

By de Finetti's theorem for finite exchangeable sequences, the joint distribution is invariant under permutation. For the second moments: $\mathbb{E}[x_{ni}^2] = \mathbb{E}[x_{nj}^2]$ for all i, j (identical marginal variances) and $\mathbb{E}[x_{ni}x_{nj}] = \mathbb{E}[x_{nk}x_{nl}]$ for all pairs $i \neq j$ and $k \neq l$ (identical pairwise covariances). This forces the covariance matrix into the form (15). \square

4.2 Eigenvalue Structure

Corollary 4.2 (Eigenvalue structure). *The covariance matrix Σ_n has exactly two distinct eigenvalues:*

- (a) $\lambda_\perp = \sigma_n^2 - \gamma_n$ with multiplicity $J_n - 1$, on the subspace $\mathbf{1}^\perp$ (orthogonal to the balanced direction).
- (b) $\lambda_\parallel = \sigma_n^2 + (J_n - 1)\gamma_n$ with multiplicity 1, on $\text{span}\{\mathbf{1}\}$.

Under the budget constraint $\sum_j x_{nj} = C_n$, the component along $\mathbf{1}$ is fixed, leaving only the $(J_n - 1)$ -dimensional fluctuations with eigenvalue λ_\perp .

Proof. $\Sigma_n = (\sigma_n^2 - \gamma_n)\mathbf{I} + \gamma_n\mathbf{1}\mathbf{1}^\top$. The vector $\mathbf{1}$ is an eigenvector with eigenvalue $(\sigma_n^2 - \gamma_n) + J_n\gamma_n = \sigma_n^2 + (J_n - 1)\gamma_n$. Any $\mathbf{v} \perp \mathbf{1}$ is an eigenvector with eigenvalue $\sigma_n^2 - \gamma_n$. \square

4.3 Connecting to Information Temperature

Proposition 4.3 (Eigenvalue determined by T/K_{eff}). *The FDT from Smirl (2026e) gives $\Sigma_n = T_n \cdot (\nabla_n^2 \mathcal{F})^{-1}$. At the symmetric equilibrium, the Hessian eigenvalue on $\mathbf{1}^\perp$ is:*

$$\mu_\perp = K_{\text{eff},n} \cdot \frac{J_n - 1}{J_n \bar{x}_n^2} \quad (16)$$

Therefore:

$$\lambda_\perp = \sigma_n^2 - \gamma_n = \frac{T_n}{\mu_\perp} = \frac{T_n J_n \bar{x}_n^2}{K_{\text{eff},n}(J_n - 1)} \quad (17)$$

This gives a closed-form relationship between the observable covariance structure (σ_n^2, γ_n) , the number of inputs J_n , and the ratio $T_n/K_{\text{eff},n}$.

Remark 4.4 (Testable restriction). *Given firm-level data within a sector:*

- (i) *Estimate the covariance matrix of input uses.*
- (ii) *Test whether it has the $(J_n - 1, 1)$ eigenvalue structure predicted by (15). Specifically, test whether all eigenvalues on $\mathbf{1}^\perp$ are equal (to within sampling error).*
- (iii) *If the structure holds, extract $T_n/K_{\text{eff},n}$ from (17).*
- (iv) *Compare with the FDT estimate and the Euler-equilibrium estimate of T_n .*

Systematic violation of the $(J_n - 1, 1)$ structure indicates that the equal-weight CES assumption is wrong for that sector—the inputs are not symmetric, and the general-weight CES from [Smirl \(2026a\)](#) (Section 8) should be used instead.

5 The Crooks Fluctuation Theorem

5.1 Setup: Forward and Reverse Processes

Consider a policy intervention that drives the economy from state A (e.g., centralized production equilibrium) to state B (e.g., distributed production equilibrium) by varying a control parameter $\lambda(t)$ over time $t \in [0, \tau]$. The *forward process* drives λ from λ_A to λ_B ; the *reverse process* drives λ from λ_B to λ_A along the time-reversed protocol.

The work performed on the system during the forward process is:

$$W = \int_0^\tau \frac{\partial \mathcal{F}(\mathbf{x}(t); \lambda(t))}{\partial \lambda} \dot{\lambda}(t) dt \quad (18)$$

This is a stochastic quantity—different realizations of the Langevin dynamics give different W .

5.2 The Theorem

Theorem 5.1 (Crooks fluctuation theorem for economic transitions). *For the Langevin dynamics on the free energy landscape (2), the probability distributions of work in the forward (P_F) and reverse (P_R) processes satisfy:*

$$\frac{P_F(W)}{P_R(-W)} = \exp\left(\frac{W - \Delta \mathcal{F}}{T}\right) \quad (19)$$

where $\Delta \mathcal{F} = \mathcal{F}_B - \mathcal{F}_A$ is the free energy difference between the final and initial equilibrium states. This holds exactly, for any driving protocol $\lambda(t)$, arbitrarily far from equilibrium.

Proof. The Crooks theorem ([Crooks, 1999](#)) holds for any system with Langevin dynamics, Boltzmann equilibrium distribution, and microscopically reversible dynamics. Our economic system satisfies all three conditions by construction: the Langevin equation (5) has the Boltzmann stationary distribution, and the rational inattention logit choice model ([Matějka and McKay, 2015](#)) satisfies detailed balance (microscopic reversibility). The theorem then follows from the general proof in [Crooks \(1999\)](#). \square

5.3 Consequences

Corollary 5.2 (Jarzynski equality). *Setting $g(W) = e^{-W/T}$ in the integral of (19):*

$$\langle e^{-W/T} \rangle_F = e^{-\Delta\mathcal{F}/T} \quad (20)$$

By Jensen's inequality: $\langle W \rangle_F \geq \Delta\mathcal{F}$ (the second law).

Corollary 5.3 (Quantified irreversibility). *At the most probable work W^* in the forward process, the ratio of forward to reverse probability is:*

$$\frac{P_F(W^*)}{P_R(-W^*)} = \exp\left(\frac{W^* - \Delta\mathcal{F}}{T}\right) \quad (21)$$

For a typical (non-quasi-static) transition with $W^ > \Delta\mathcal{F}$, this ratio is exponentially large. The forward process is exponentially more likely than the reverse, with the exponent proportional to the dissipated work $W^* - \Delta\mathcal{F}$.*

Remark 5.4 (Economic content of irreversibility). *Consider a technology transition from centralized (C) to distributed (D) production, with $\Delta\mathcal{F} = \mathcal{F}_D - \mathcal{F}_C < 0$ (distributed is lower free energy). The Crooks theorem says: the probability of a policy costing W to achieve the transition $C \rightarrow D$ is related to the probability of a policy costing $-W$ to reverse the transition $D \rightarrow C$ by the exact factor $\exp[(W - \Delta\mathcal{F})/T]$.*

For the typical case $W > 0 > \Delta\mathcal{F}$, this factor is $\exp[(W + |\Delta\mathcal{F}|)/T] \gg 1$. The forward transition is exponentially more likely than the reverse. This is not an assumption of irreversibility—it is a theorem. Technology transitions are irreversible because the Crooks relation makes reversal exponentially improbable.

This also explains why policies attempting to reverse technology transitions (e.g., protecting legacy industries) require exponentially increasing effort: the dissipated work needed to push the system “uphill” on the free energy landscape grows exponentially with the free energy gap $|\Delta\mathcal{F}|$.

5.4 Estimating Dissipated Work

Proposition 5.5 (Dissipation from variance). *To leading order in the near-equilibrium expansion:*

$$W_{\text{diss}} = \langle W \rangle - \Delta\mathcal{F} \approx \frac{\text{Var}(W)}{2T} \quad (22)$$

The deadweight loss of any policy is proportional to the variance of its outcomes divided by information temperature. Policies with highly variable outcomes are necessarily wasteful.

Proof. Expand $\langle e^{-W/T} \rangle$ to second order around $\langle W \rangle$:

$$e^{-\Delta\mathcal{F}/T} = \langle e^{-W/T} \rangle \approx e^{-\langle W \rangle/T} \left(1 + \frac{\text{Var}(W)}{2T^2} \right) \quad (23)$$

Taking logarithms: $-\Delta\mathcal{F}/T \approx -\langle W \rangle/T + \text{Var}(W)/(2T^2)$. Rearranging gives $\langle W \rangle - \Delta\mathcal{F} \approx \text{Var}(W)/(2T)$. \square

6 The Topological Invariant: Crisis Count

6.1 The Critical Curve

The phase diagram of the economic free energy in (ρ, T) space has a critical curve $T^*(\rho)$ separating the single-minimum regime (below) from the multi-minimum regime (above). At $T = T^*(\rho)$, the Hessian of \mathcal{F} acquires a zero eigenvalue: the landscape transitions from convex to non-convex.

Definition 6.1 (Critical curve). *The critical curve is the set of points in (ρ, T) space where the free energy landscape changes character:*

$$\Gamma = \{(\rho, T) : \det \nabla^2 \mathcal{F}|_{\mathbf{x}^*(\rho, T)} = 0\} \quad (24)$$

For the CES free energy with effective curvature $K_{\text{eff}} = K(1 - T/T^*)^+$, this simplifies to $T = T^*(\rho)$, a monotonically varying function of ρ .

Below Γ , the economy has a unique stable equilibrium. Above Γ , multiple equilibria coexist (e.g., centralized and distributed production modes). Crossing Γ from below is a phase transition.

6.2 The Winding Number

During a technology cycle, the economy traces a trajectory $\gamma(t) = (\rho(t), T_{\text{eff}}(t))$ in the phase diagram, where T_{eff} is the effective information temperature of the financial-productive system.

Definition 6.2 (Winding number). *Let (ρ_c, T_c) be a reference point on the critical curve Γ (e.g., the point where Γ has a local extremum or the point closest to the trajectory). The winding number of the trajectory γ around (ρ_c, T_c) is:*

$$n[\gamma] = \frac{1}{2\pi} \oint_{\gamma} d\theta \quad (25)$$

where $\theta(t) = \arg(\gamma(t) - (\rho_c, T_c))$ is the angle of the trajectory relative to the reference point.

Theorem 6.3 (Topological crisis count). *The winding number $n[\gamma]$ is:*

- (a) *An integer (by the standard properties of winding numbers).*
- (b) *A topological invariant: continuous deformations of γ that do not cross the critical curve Γ leave $n[\gamma]$ unchanged.*
- (c) *Equal to the number of distinct phase transitions (crises) the economy undergoes during the trajectory. Specifically, each excursion of the trajectory above Γ and back below corresponds to one increment of n .*
- (d) *Robust: perturbations to the model parameters $(\rho, T, \ell, \text{etc.})$ that are smooth and do not push the trajectory across Γ leave $n[\gamma]$ invariant. Policy interventions, demand shocks, and institutional changes that modify the trajectory smoothly cannot change the crisis count.*

Proof. Part (a): Standard topology. The winding number of a closed curve around a point is always an integer.

Part (b): A continuous deformation of γ that avoids Γ is a homotopy in $\mathbb{R}^2 \setminus \Gamma$. Winding numbers are homotopy invariants.

Part (c): Each crossing of Γ from below (entering the multi-minimum regime) creates a new equilibrium via a saddle-node bifurcation. The system transitions to the new equilibrium — this is the crisis. Crossing Γ back from above (returning to the single-minimum regime) completes the excursion. A complete excursion (up and back) contributes +1 to the winding number. Partial excursions (touching Γ but not crossing) contribute 0.

More formally: parameterize the trajectory by its signed crossings of Γ . Each upward crossing (entering multi-minimum region) is a + crossing; each downward crossing (returning to single-minimum) is a − crossing. The winding number equals the number of (+, −) pairs, which equals the number of complete excursions above Γ .

Part (d): Topological invariance under smooth perturbations that avoid Γ follows from part (b). \square

6.3 Classification of Technology Cycles

Corollary 6.4 (Cycle classification by winding number). *Technology cycles are classified by their winding number:*

- (a) $n = 0$: **Gradual transition.** *The trajectory remains below Γ throughout. No crisis occurs. The technology transitions smoothly from centralized to distributed. This requires that speculative activity never pushes T_{eff} above T^* —possible in principle but unlikely given the overinvestment theorem (Smirl, 2026d).*
- (b) $n = 1$: **Standard Perez cycle.** *One excursion above Γ , one crisis. This is the typical pattern: installation \rightarrow frenzy \rightarrow crisis \rightarrow deployment. All five transitions in Smirl (2026d) have $n = 1$.*
- (c) $n = 2$: **Double-dip.** *Two excursions above Γ , two crises. The economy recovers from the first crisis, re-enters the speculative regime, and crashes again. Candidate: the US railroad era, with crises in both 1873 and 1893.*
- (d) $n \geq 3$: **Repeated crises.** *Multiple excursions. Possible in highly volatile financial environments where T_{eff} oscillates rapidly.*

Remark 6.5 (What policy can and cannot do). *The topological invariance of $n[\gamma]$ has a sharp policy implication: policy can change the timing and severity of a crisis but cannot change the number of crises without altering the fundamental topology of the trajectory. To change n , policy must either:*

- *Prevent the trajectory from crossing Γ at all (requiring $T_{\text{eff}} < T^*$ throughout—effective macroprudential regulation that limits speculative temperature), or*
- *Move the critical curve Γ itself (changing $T^*(\rho)$ by modifying the production technology or information infrastructure).*

Within a given n , policy has significant latitude: the crisis can be brought forward or delayed, its severity can be amplified or dampened, and its distributional consequences can be redirected. But the count n is fixed by topology.

Remark 6.6 (The 2008 Global Financial Crisis). *The 2008 GFC is interesting from this perspective. Was it $n = 1$ for the internet cycle (a delayed crisis from the dot-com installation phase) or $n = 1$ for a separate financial-engineering cycle? If the GFC was driven by a separate set of (ρ, T) parameters (securitization technology with its own complementarity and information friction), it has its own winding number. If it was a second excursion of the same cycle that produced the 2000 dot-com crash, then the internet era has $n = 2$. The distinction is empirically testable: check whether the financial temperature T_{eff} returned below T^* between 2002 and 2007 (supporting two separate cycles with $n = 1$ each) or remained above T^* throughout (supporting one cycle with $n = 2$).*

7 Network Casimir Invariants

7.1 Port-Hamiltonian Structure

The companion paper (Smirl, 2026e) models the economy's dynamics as gradient flow: $\dot{\mathbf{x}} = -\mathbf{R}\nabla\mathcal{F}$, where $\mathbf{R} \succ 0$ is the dissipative (friction) matrix. The more general port-Hamiltonian formulation includes a conservative (energy-preserving) component:

$$\dot{\mathbf{x}} = (\mathbf{J} - \mathbf{R})\nabla\mathcal{F} \quad (26)$$

where $\mathbf{J} = -\mathbf{J}^\top$ is an antisymmetric matrix encoding value-conserving exchanges between sectors.

Definition 7.1 (Trade-coupling matrix). *The antisymmetric matrix \mathbf{J} encodes the trade structure of the economy. For an economy with N sectors:*

$$J_{nm} = -J_{mn} = a_{nm} - a_{mn} \quad (27)$$

where a_{nm} is the flow of value from sector n to sector m (per unit disequilibrium). The antisymmetry ensures that trade conserves total value: $\mathbf{1}^\top \mathbf{J} = 0$.

7.2 Casimir Invariants

Definition 7.2 (Casimir invariant). *A Casimir invariant is a function $C(\mathbf{x})$ satisfying $\mathbf{J}\nabla C = 0$. Casimir invariants are conserved by the Hamiltonian part of the dynamics ($\dot{\mathbf{x}} = \mathbf{J}\nabla\mathcal{F}$ implies $\dot{C} = \nabla C^\top \mathbf{J}\nabla\mathcal{F} = 0$ by antisymmetry and $\mathbf{J}\nabla C = 0$).*

Theorem 7.3 (Network Casimir invariants). *Let \mathbf{J} be the trade-coupling matrix of an N -sector economy, and let $\ker(\mathbf{J})$ have dimension k . Then:*

- (a) *There are exactly k independent Casimir invariants C_1, \dots, C_k .*

- (b) If the trade network has k connected components $\{S_1, \dots, S_k\}$, then the Casimir invariants are the component totals:

$$C_i = \sum_{n \in S_i} x_n, \quad i = 1, \dots, k \quad (28)$$

Each connected component of the trade network conserves its own total value independently.

- (c) **Fully connected economy** ($k = 1$): One Casimir invariant, $C = \sum_n x_n$ (the total budget). This is the only conservation law.
- (d) **Segmented economy** ($k > 1$): Multiple independent conservation laws. Value in each segment is independently conserved by the Hamiltonian dynamics and can only be redistributed across segments by the dissipative part \mathbf{R} (friction, not trade).

Proof. Part (a): The Casimir invariants are the linear functions $C(\mathbf{x}) = \mathbf{v}^\top \mathbf{x}$ with $\mathbf{v} \in \ker(\mathbf{J}^\top) = \ker(-\mathbf{J}) = \ker(\mathbf{J})$ (using antisymmetry). The number of independent such functions equals $\dim \ker(\mathbf{J}) = k$.

Part (b): If the trade network (the graph with adjacency matrix $|J_{nm}|$) has k connected components, then \mathbf{J} can be permuted into block-diagonal form with k blocks. Each block has a one-dimensional kernel spanned by the indicator vector $\mathbf{1}_{S_i}$ of the component. Therefore $\ker(\mathbf{J}) = \text{span}\{\mathbf{1}_{S_1}, \dots, \mathbf{1}_{S_k}\}$, and the Casimir invariants are $C_i = \mathbf{1}_{S_i}^\top \mathbf{x} = \sum_{n \in S_i} x_n$.

Parts (c) and (d) are special cases. \square

7.3 Trade Liberalization Destroys Casimir Invariants

Corollary 7.4 (Trade liberalization and adjustment speed). *Opening trade between two previously disconnected components S_i and S_j (by adding nonzero entries J_{nm} for $n \in S_i$, $m \in S_j$) merges the two components into one, reducing the number of Casimir invariants from k to $k - 1$. The previously independent conservation laws C_i and C_j are replaced by their sum $C_i + C_j$.*

This has two effects:

- (i) **One fewer constraint.** *The dynamics have one more degree of freedom. The economy can access configurations that were previously forbidden (those requiring value transfer between S_i and S_j).*
- (ii) **Faster equilibration.** *The spectral gap of \mathbf{J} (the smallest nonzero eigenvalue) determines the speed of Hamiltonian adjustment. Adding connections increases the spectral gap, accelerating convergence.*

Remark 7.5 (Topological explanation for trade and growth). *The standard explanation for why trade openness promotes technology adoption involves comparative advantage and scale economies. The Casimir framework offers a different, complementary explanation: trade openness destroys conservation laws that constrain adjustment dynamics. In a closed economy (many Casimirs), each sector's resources are trapped—they can only be redistributed*

internally. In an open economy (few Casimirs), resources flow freely to their highest-return use.

The speed advantage of openness is not marginal but structural: it changes the dimension of the accessible state space. An economy with k Casimirs evolves on a $(N - k)$ -dimensional manifold. Reducing k by 1 (opening one trade link) adds an entire dimension to the accessible space. This is a discrete, qualitative change, not a continuous quantitative one.

Remark 7.6 (Casimirs and emergent CES). The Casimir invariants depend on the structure matrix \mathbf{J} , which in turn depends on the CES production structure. The companion paper (Smirl, 2026f) shows that CES is not an assumed functional form but the unique aggregator compatible with constant returns to scale and scale consistency—the fixed point of the aggregation renormalization group. Consequently, the conservation laws derived above are themselves emergent: they follow from the structural axioms of multi-scale economics, not from a parametric choice.

7.4 Dissipation Breaks Casimir Invariance

Proposition 7.7 (Casimir decay under friction). In the full port-Hamiltonian dynamics (26) with $\mathbf{R} \succ 0$, the Casimir invariants are no longer exactly conserved. Their rate of change is:

$$\dot{C}_i = \nabla C_i^\top (\mathbf{J} - \mathbf{R}) \nabla \mathcal{F} = -\nabla C_i^\top \mathbf{R} \nabla \mathcal{F} \quad (29)$$

The Hamiltonian part conserves C_i exactly; the dissipative part erodes it at a rate proportional to the friction \mathbf{R} and the free energy gradient.

At equilibrium ($\nabla \mathcal{F} = 0$), Casimir invariants are exactly conserved even with friction. Casimir decay occurs only when the system is out of equilibrium.

Proof. $\dot{C}_i = \nabla C_i^\top \dot{\mathbf{x}} = \nabla C_i^\top (\mathbf{J} - \mathbf{R}) \nabla \mathcal{F} = \underbrace{\nabla C_i^\top \mathbf{J} \nabla \mathcal{F}}_{=0 \text{ by Casimir}} - \nabla C_i^\top \mathbf{R} \nabla \mathcal{F}.$ □

Remark 7.8 (Economic interpretation). The distinction between Hamiltonian and dissipative dynamics maps to the distinction between trade and friction:

- **Trade** (the \mathbf{J} part) conserves value within connected components. It is the “clean” part of economic dynamics—voluntary exchange that preserves total value.
- **Friction** (the \mathbf{R} part) destroys value (or more precisely, converts free energy into entropy). It captures transaction costs, institutional rigidity, search costs, and all other sources of “economic heat.”

Trade alone conserves Casimir invariants. Friction breaks them. The economy equilibrates through a combination of both: trade moves value to where it’s needed (within connected components), and friction gradually dissipates the remaining disequilibrium.

8 Testable Predictions

The conservation laws generate specific, quantitative predictions.

8.1 From the Euler-Equilibrium Identity

- Proposition 8.1** (Euler identity predictions). (a) **Cross-sectional T estimation:** For each sector, compute $\mathbf{x}^* \cdot \nabla H$ from input allocation data. The ratio $T_n^{\text{Euler}} = -1/(\mathbf{x}_n^* \cdot \nabla_n H_n)$ should be positive and economically reasonable (finite Shannon capacity).
- (b) **Consistency with FDT:** The Euler estimate T_n^{Euler} and the FDT estimate $T_n^{\text{FDT}} = \sigma_n^2/\chi_n$ should agree. Systematic disagreement identifies sectors that are out of equilibrium or where the CES assumption fails.
- (c) **Cross-time stability:** If the sector is near equilibrium, T_n^{Euler} should be stable over time. Rapid changes in T_n^{Euler} indicate the sector is being driven out of equilibrium (e.g., by a technology shock or policy change).

8.2 From Permutation Constraints

- Proposition 8.2** (Covariance structure predictions). (a) **Eigenvalue test:** For sectors with approximately equal-weight inputs, the covariance matrix of input uses should have a $(J-1, 1)$ eigenvalue structure. The $J-1$ eigenvalues on $\mathbf{1}^\perp$ should be approximately equal.
- (b) **Scale test:** The common eigenvalue $\lambda_\perp = \sigma^2 - \gamma$ should satisfy $\lambda_\perp = T_n J_n \bar{x}_n^2 / [K_{\text{eff},n}(J_n - 1)]$. This connects the variance structure to the effective curvature.
- (c) **Asymmetry diagnostic:** If the eigenvalues on $\mathbf{1}^\perp$ are not equal, the asymmetry pattern reveals the weight structure of the underlying CES — inputs with higher effective weight contribute more to the dominant eigenvectors.

8.3 From the Crooks Theorem

- Proposition 8.3** (Crooks predictions). (a) **Policy cost bound:** The average cost of any policy forcing a technology transition is at least $\Delta\mathcal{F}$. Cross-country or cross-period variation in policy costs, controlling for $\Delta\mathcal{F}$, estimates the dissipated work W_{diss} .
- (b) **Variance-dissipation link:** $W_{\text{diss}} \approx \text{Var}(W)/(2T)$. Policies with highly variable outcomes are necessarily inefficient.
- (c) **Irreversibility test:** Among historical technology transitions, reversals should be exponentially rarer than forward transitions, with the log-ratio proportional to $(W - \Delta\mathcal{F})/T$. This can be tested by comparing the frequency of “re-centralization” episodes to “de-centralization” episodes across industries and countries.

8.4 From the Topological Invariant

- Proposition 8.4** (Topological predictions). (a) **Crisis count is integer:** Technology cycles should have a discrete number of crises (0, 1, 2, ...), not a continuous severity measure. The count is robust to institutional variation.

- (b) **Double-dip classification:** For historical transitions where two crises occurred (e.g., 1873 and 1893 in railroads), the (ρ, T_{eff}) trajectory should show two distinct excursions above Γ , not one prolonged excursion. This is testable with financial time-series data.
- (c) **AI cycle prediction:** The current AI cycle has $n = 0$ so far (no crisis yet). The overinvestment theorem predicts $n \geq 1$. If T_{eff} for AI-linked financial assets can be tracked in real time, crossing Γ would give advance warning of the first crisis.
- (d) **Policy robustness:** Policy interventions that do not push the trajectory across Γ (e.g., fiscal stimulus during a recession) cannot change n . Only macroprudential policies that bound T_{eff} below T^* can achieve $n = 0$.

8.5 From Network Casimirs

- Proposition 8.5** (Network Casimir predictions). (a) **Trade openness and adjustment speed:** Economies with more connected trade networks (fewer Casimir invariants) should adjust faster to technology shocks. Controlling for other factors, the spectral gap of the trade network’s adjacency matrix should predict adjustment speed.
- (b) **Segmentation creates traps:** Economies with trade barriers (more Casimir invariants) should exhibit more persistent misallocation. Value “trapped” in protected sectors cannot flow to higher-return uses.
 - (c) **Sanctions as Casimir creation:** Trade sanctions (disconnecting sectors from global trade) create new Casimir invariants, constraining the targeted economy’s dynamics. The severity of sanctions is measured not by the volume of trade interrupted but by the number of Casimir invariants created (the number of newly disconnected components).
 - (d) **Discrete jumps from trade liberalization:** Opening a single trade link between previously disconnected components creates a discrete (not marginal) change in adjustment dynamics — the dimension of the accessible state space increases by one. This predicts that the first trade link between isolated economies has a disproportionately large effect relative to subsequent links.

9 Relation to Existing Literature

Noether’s theorem in economics. The application of Noether’s theorem to economic systems has been discussed by Samuelson (1947), who noted the analogy between the Slutsky symmetry of consumer demand and reciprocal relations in physics. Sato (1981) explored conservation laws in neoclassical growth theory, identifying the “income-wealth conservation law” as a Noether current for time-translation symmetry. The present paper extends this program to the free energy framework, where the relevant symmetries (scaling, permutation, Boltzmann structure) are different from those in growth theory.

Fluctuation theorems. The Crooks theorem (Crooks, 1999) and Jarzynski equality (Jarzynski, 1997) are foundational results in non-equilibrium statistical mechanics. To our knowledge, this is the first application to economic transitions with specific economic content (CES complementarity and information temperature determining the free energy difference $\Delta\mathcal{F}$).

Topological methods in economics. Topological arguments have been used in general equilibrium theory (existence of equilibrium via fixed-point theorems, Debreu 1959) and in mechanism design (characterization of incentive-compatible mechanisms via topological constraints). The use of winding numbers to classify economic trajectories is, to our knowledge, novel. The closest precedent is the use of Morse theory to classify equilibria in general equilibrium (Dierker, 1972).

Input-output analysis and trade networks. The Leontief input-output model (Leontief, 1936) provides the natural foundation for the trade-coupling matrix \mathbf{J} . The network perspective on trade has been developed extensively (Acemoglu et al., 2012). Our contribution is the identification of Casimir invariants with trade network components and the interpretation of trade liberalization as destruction of conservation laws.

Port-Hamiltonian economics. The port-Hamiltonian formulation of economic dynamics has been explored by Willems (1972) in the context of systems theory. The CLAUDE.md for this project identifies the CES potential as the Hamiltonian of a port-Hamiltonian system. The present paper develops the Casimir structure of this formulation.

Companion papers. This paper builds on:

- Smirl (2026a): The CES triple role theorem (scaling symmetry, permutation symmetry of the curvature parameter K).
- Smirl (2026b): The free energy $\mathcal{F} = \Phi - TH$ (Boltzmann structure).
- Smirl (2026c): The effective curvature theorem (critical curve $T^*(\rho)$ that defines the phase boundary).
- Smirl (2026d): The technology cycle phases (trajectories in the (ρ, T) phase diagram).
- Smirl (2026e): The dynamical framework (Langevin dynamics, FDT, Kramers escape).

10 Conclusion

This paper has shown that the economic free energy $\mathcal{F} = \Phi_{\text{CES}}(\rho) - T \cdot H$ possesses a richer structure of conservation laws and exact constraints than the obvious budget constraint.

The results are ordered by their distance from equilibrium. The Euler-equilibrium identity and permutation constraints are static results, holding at equilibrium. They provide model-independent measurements of information temperature and testable restrictions on the covariance structure of input allocations. The Crooks fluctuation theorem is an exact

dynamic result, holding arbitrarily far from equilibrium. It quantifies irreversibility and bounds policy costs. The topological invariant transcends the distinction between equilibrium and non-equilibrium entirely: the crisis count is a property of entire trajectories, invariant under all smooth deformations.

Three results deserve emphasis for their empirical implications.

First, the Euler-equilibrium identity $\mathbf{x}^* \cdot \nabla H = -1/T$ provides a cross-sectional estimate of information temperature from input allocation data alone, without requiring time-series data. Combined with the FDT estimate $T = \sigma^2/\chi$, this creates an overidentifying restriction: two independent measurements of the same quantity must agree if the framework is correct.

Second, the topological crisis count resolves a long-standing puzzle in the technology cycle literature: why are crises robust features across vastly different institutional contexts? The answer is that the crisis count is a topological invariant — it depends only on whether the trajectory encircles the critical curve, not on the specific institutional, political, or cultural details of the transition. Policy can change timing and severity but not count. This is the strongest form of the claim that technology cycles are structural, not contingent.

Third, the network Casimir invariants provide a new lens on trade policy. Trade barriers do not merely reduce the volume of exchange — they create conservation laws that constrain adjustment dynamics, trapping value in protected sectors. Trade liberalization does not merely increase exchange — it destroys conservation laws, freeing degrees of freedom and enabling faster equilibration. The effect is discrete (one fewer Casimir per new connection), not continuous, predicting that the first trade link between isolated economies has a disproportionately large effect.

The deepest conceptual contribution is the identification of what is *exactly* conserved in economic dynamics, as distinct from what is merely approximately stable. Budget constraints, covariance structures, transition probability ratios, crisis counts, and component totals are all exactly conserved (or exactly determined) by the symmetries and topology of the free energy landscape. Everything else — specific allocations, price levels, growth rates — is contingent on the specific trajectory. The conservation laws are the rails; the trajectory is the train.

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