

# Business Cycles in Space

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<sup>1</sup>The views expressed are those of the authors and should not be interpreted as reflecting the views of the Bank of Canada, the Deutsche Bundesbank, the Eurosystem, or their staffs.

# Motivation

Macro literature usually focuses on country-level outcomes.

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New economic geography (NEG) literature has looked at regional outcomes, but chiefly in static models.

- ▶ Does not look at business cycles; usually no shocks in the model.
- ▶ NEG models are usually not forward looking.
- ▶ Dynamic NEG models usually contain just a few regions.
  - ▶ Difficult to track spatial dynamics.
  - ▶ Non-atomistic regions make optimal policy very difficult.
- ▶ Those in continuous space usually have very restrictive assumptions.

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▶ NEG Literature

We attempt to bring two literatures together:

- ▶ Propose new approach to building macro models with spatial heterogeneity.
- ▶ Study spatial effects of business cycles.

## Spatially correlated shocks

Starting point: spatial heterogeneity driven by spatially correlated shocks.

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- ▶ Firms physically closer to frontier firms catch up quicker (Griffith, Redding & Simpson 2009, Comin, Dmitriev & Rossi-Hansberg 2012, Cardamone 2017).
- ▶ Physical distance more important than economic distance in cross-country spillover of TFP growth (Glass, Kenjegalieva & Paez-Farrell 2013).

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Fortunately, spatial correlation enhances tractability of heterogeneous agent models.

## Consequences of spatial correlation

Individual shocks generate aggregate volatility:

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- ▶ Role for redistribution across space.
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Many interesting questions, for example:

- ▶ How do regional asymmetries effect transmission of monetary policy?
- ▶ How do local shocks affect internal migration / housing markets / labour markets across physical space?
- ▶ Who are the regional winners/losers to policy programmes or other macro/local shocks?

▶ Example [another paper]

# Contributions

1. We propose a new approach to building macro models featuring spatial heterogeneity.
  - ▶ Our approach is quite general:
    - ▶ Space need not be physical space.  
E.g. it could be the space of product-categories or labour skill levels.
    - ▶ The geometry of space is flexible.  
E.g. it could be a plane, torus, sphere or network.
  - ▶ Correlated shocks actually help computation:
    - ▶ Continuity means relatively few grid points are needed.
  - ▶ We provide general conditions for the existence of spatially correlated shock processes.

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    - ▶ Continuity means relatively few grid points are needed.
  - ▶ We provide general conditions for the existence of spatially correlated shock processes.
2. We develop a spatial DSGE model with the key ingredients from the NEG literature.
  - ▶ Strong agglomeration forces will lead to persistent movements in population and capital.

## An example spatially correlated shock process

Suppose space is 1-dimensional over the interval  $[0, 1]$ .

One shock process over this space is the Orstein-Uhlenbeck process:

- ▶ Continuous time (space) analogue to Gaussian AR(1) process.
- ▶ Characterised by covariance structure:

$$\text{cov}(\varepsilon_x, \varepsilon_{\tilde{x}}) = \exp(-\zeta|x - \tilde{x}|)$$

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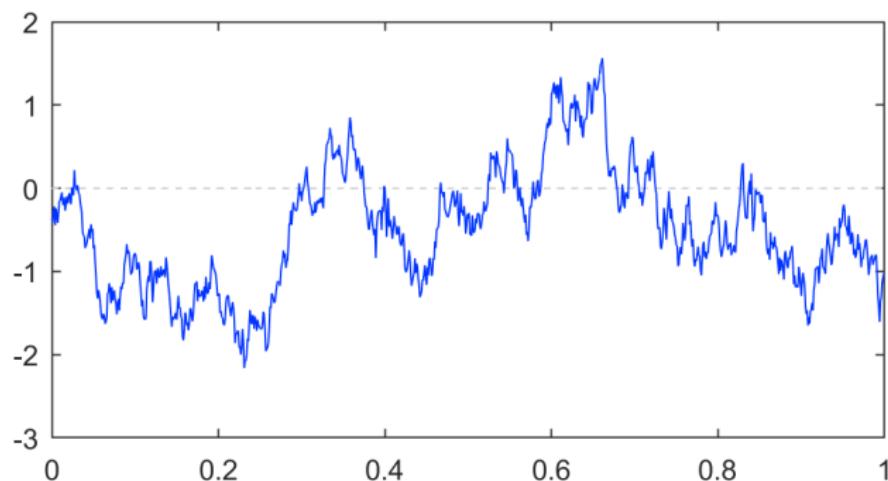
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E.g.  $\zeta = 8$ :



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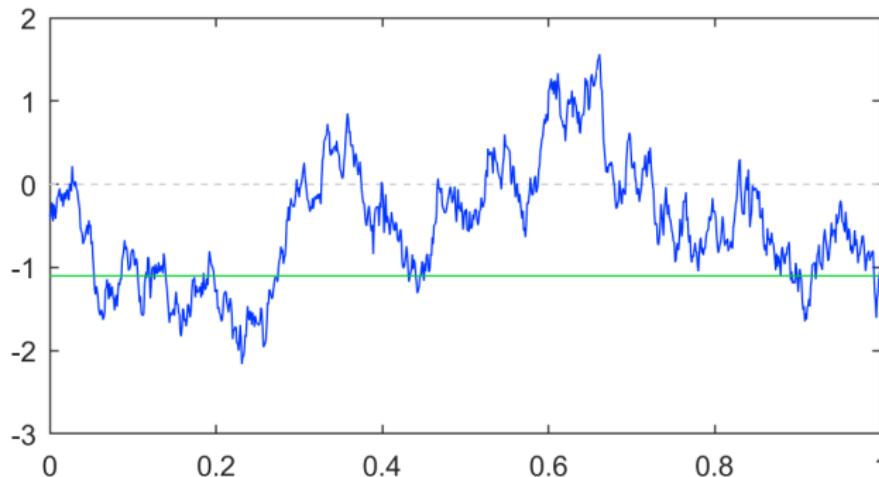
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E.g.  $\zeta = 8$  and  $\zeta = 0$ :



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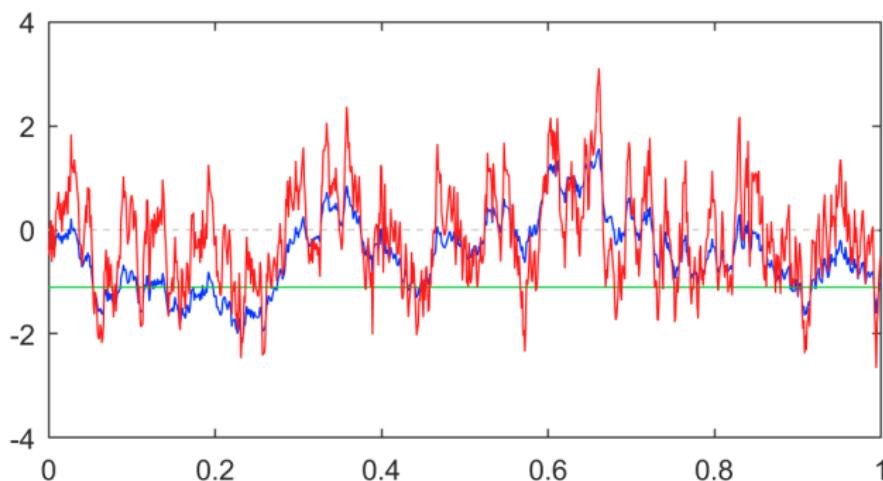
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$$\text{cov}(\varepsilon_x, \varepsilon_{\tilde{x}}) = \exp(-\zeta|x - \tilde{x}|)$$

E.g.  $\zeta = 8$ ,  $\zeta = 0$  and  $\zeta = 100$ :



## General modelling approach I

1. Define the geometry of the relevant space: plane, circle, torus, network, etc.
  - ▶ E.g., suppose space is a circle, indexed by  $x \in X$ .

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2. Define the model: objectives, markets, frictions and spatial shock.
  - ▶ There will be conditions at each location  $x$  giving decisions and state evolution.
  - ▶ There will be some aggregate / market conditions.
  - ▶ Example spatial stochastic process:

$$a_{x,t} = \rho a_{x,t-1} + \sigma \varepsilon_{x,t}$$
$$\text{cov}(\varepsilon_{x,t}, \varepsilon_{\tilde{x},t}) = s(\zeta, d(x, \tilde{x}))$$

- ▶  $\zeta$  will control spatial correlation.
- ▶  $s$  and  $d$  must fulfil certain conditions to produce a valid process. See paper.
- ▶ Often  $s(\zeta, d) = \exp(-\zeta d)$ .
- ▶ Note, with  $a_t \equiv \int_0^1 a_{x,t} dx$  and  $\varepsilon_t \equiv \int_0^1 \varepsilon_{x,t} dx$ , we have:

$$a_t = \rho a_{t-1} + \sigma \varepsilon_t$$

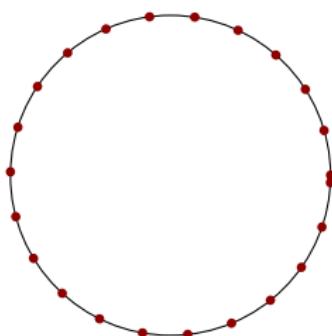
## General modelling approach II

3. Choose grid geometry, e.g.  $N = 100$  evenly spaced points.

- ▶ Note on accuracy:

- ▶ Bounded variation of shock implies error from using the trapezium rule decays at  $1/N^2$  at the slowest.
- ▶ For sufficiently smooth functions the rate is  $k^{-N}$  for some  $k > 1$  (thanks to periodicity).
- ▶ Compare with  $1/\sqrt{N}$ , with Monte Carlo used in e.g. Krusell-Smith.

- ▶ Approximate outcomes at locations between nodes via linear interpolation.
- ▶ Approximate integrals over space via the trapezium rule.
- ▶ E.g. market clearing conditions of the form:  
 $0 = \int_0^1 B_{x,t} dx$  become  $0 = \sum_{n=1}^N B_{x_n, t}$ .



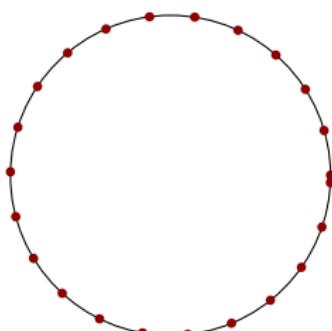
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4. Solve via perturbation. e.g., with Dynare.

- ▶ We provide a toolkit to help define spatially correlated shocks:  
<https://github.com/tholden/DynareTransformationEngine>

# Model Overview

- ▶ RBC model + standard new economic geography features (following Krugman 1991).
- ▶ Key features:
  - ▶ Population movement.
  - ▶ Competing land usage: farming and residential.
  - ▶ Non-tradeable raw goods (production services).
  - ▶ Two types of final good: agricultural products and manufactured products.
  - ▶ Differentiated intermediate manufactured goods subject to iceberg trade costs.
  - ▶ Firm entry à la Bilbiie, Gheroni & Melitz (2012).

# Agglomeration mechanism

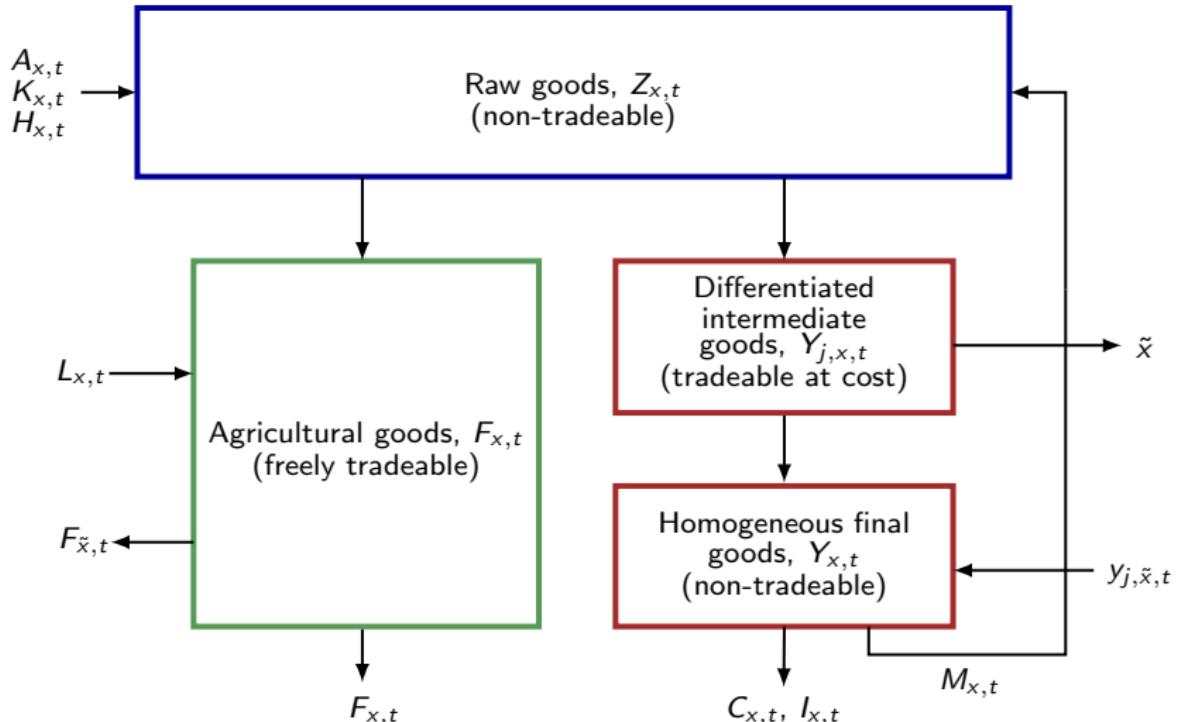
The key mechanism works as follows:

- ▶ Productivity shock at  $x$  increases wages there.
- ▶ People move to  $x$  for higher wages.
- ▶ The increased demand leads to firm entry.
- ▶ More products on sale implies increased productivity due to the taste for variety.
- ▶ This feeds back to higher wages, more migration, more firm entry etc.
- ▶ Nearby locations also benefit as iceberg transport costs mean the increased demand from  $x$  is concentrated in its neighbourhood.

## Households and firms over space

- ▶ Set of points in space  $x \in X$ , normalised so  $\int_X dx = 1$ .
- ▶ Distance between any  $x, \tilde{x} \in X$  given by  $d(x, \tilde{x})$ .
- ▶ Firms, capital and population have a density over space.
- ▶ Land is uniform over space.
- ▶ Representative household at each location, each household is part of a representative family.
- ▶ Representative family maximises a utilitarian social welfare function.
  - ▶ Equivalent to complete markets.

# Productive sectors at $x \in X$



## Production at $x \in X$

▶ Skip details

- ▶ Raw good:  $Z_{x,t} = \left[ K_{x,t-1}^\alpha (A_{x,t} H_{x,t})^{1-\alpha} \right]^{1-\kappa} M_{x,t}^\kappa$ 
  - ▶ Non-tradeable.
  - ▶ Sold at  $\mathcal{P}_{x,t}$ .

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- ▶ Agriculture:  $F_{x,t} = L_{x,t}^\gamma Z_{F,x,t}^{1-\gamma}$ 
  - ▶ Freely tradeable.
  - ▶ Numeraire.

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- ▶ Manufactured good:  $Y_{j,x,t} = Z_{j,x,t}$ .
  - ▶ Firm entry cost  $\phi_t$  units of raw good, exit rate  $\delta_t$ .
  - ▶ Tradeable subject to iceberg costs (increasing in distance,  $\tau_t$  controls rate).
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▶ Price  $P_{x,t} = (1 + \lambda) \left[ \int_X J_{\tilde{x},t} \left( \mathcal{P}_{\tilde{x},t} \exp [\tau_t d(x, \tilde{x})] \right)^{-\frac{1}{\lambda}} d\tilde{x} \right]^{-\lambda}$ .

## Capital holding companies at $x \in X$

- ▶ Capital law of motion:

$$K_{x,t} = (1 - \delta_K) K_{x,t-1} + \left[ 1 - \Phi \left( \frac{I_{x,t}}{I_{x,t-1}} \right) I_{x,t} \right]$$

- ▶ Capital rented out at  $\mathcal{R}_{K,x,t}$  per unit to firms at  $x$ .
- ▶ Standard CEE assumptions about investment adjustment costs,  $\Phi(\cdot)$ .
- ▶ Location specific capital stocks and adjustment costs make it particularly hard to move capital between locations.

# Households and the representative family

Family head maximizes:

▶ FOCs

$$\mathbb{E}_t \sum_{s=0}^{\infty} \left[ \prod_{k=1}^s \beta_{t+k-1} \right] \int_X N_{x,t+s-1} \frac{U_{x,t+s}^{1-\varsigma}}{1-\varsigma} dx,$$

s.t.

$$\int (P_{x,t} C_{x,t} + E_{x,t}) dx + B_t = \int (\mathcal{R}_{L,x,t} L_{x,t} + W_{x,t} H_{x,t}) dx + R_{t-1} B_{t-1} + T_t$$

where:

$$U_{x,t} = \left( \frac{C_{x,t}}{N_{x,t-1}} \right)^{\theta_C} \left( \frac{E_{x,t}}{N_{x,t-1}} \right)^{\theta_F} \left( \frac{1 - L_{x,t}}{N_{x,t-1}} \right)^{\theta_L} \dots$$

$$N_{t-1} \equiv \int_X N_{\tilde{x},t-1} d\tilde{x}, \quad \mathcal{D}_{x,t} \equiv \int_X d(x, \tilde{x}) N_{x,\tilde{x},t} d\tilde{x},$$

$$\begin{aligned} \mathcal{N}_{x,t} &\equiv \int_X \mathcal{N}_{x,\tilde{x},t} d\tilde{x}, & N_{x,t} &= G_{N,t} N_{x,t-1} - \int_X \mathcal{N}_{x,\tilde{x},t} d\tilde{x} + \int_X \mathcal{N}_{\tilde{x},x,t} d\tilde{x} \\ & & 1 &= \theta_C + \theta_F + \theta_L + \theta_H + \theta_N + \psi_1 + \psi_2 + \psi_3. \end{aligned}$$

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where:

$$U_{x,t} = \dots \left( \frac{\Gamma^{1+\nu}}{1+\nu} - \frac{1}{1+\nu} \left( \frac{H_{x,t}}{N_{x,t-1}} \right)^{1+\nu} \right)^{\theta_H} \left( \frac{1}{2} \Omega^2 - \frac{1}{2} \left( \log \left( \frac{N_{x,t-1}}{N_{t-1}} \right) \right)^2 \right)^{\theta_N} \dots$$

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$$U_{x,t} = \cdots \left( 1 - \frac{N_{x,t}}{N_{x,t-1}} \right)^{\psi_1} \left( \bar{d} - \frac{\mathcal{D}_{x,t}}{N_{x,t}} \right)^{\psi_2} \exp \left[ \psi_3 \int_X \frac{N_{\tilde{x},t-1}}{N_{t-1}} \log \left( \frac{N_{x,\tilde{x},t}}{N_{x,t-1}} \right) d\tilde{x} \right]$$

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$$1 = \theta_C + \theta_F + \theta_L + \theta_H + \theta_N + \psi_1 + \psi_2 + \psi_3.$$

## Market clearing

$$B_t = 0$$

$$Y_{x,t} = C_{x,t} + I_{x,t} + M_{x,t}$$

$$Z_{x,t} = Z_{F,x,t} + \phi_t [J_{x,t} - (1 - \delta_J) J_{x,t-1}] + \int_0^{J_{x,t}} Z_{j,x,t} \, dj$$
$$\int E_{x,t} \, dx = \int F_{x,t} \, dx$$

# Stochastic processes

Technology:

$$A_{x,t} = A_t^P A_{x,t}^T$$

$$A_t^P = G_{A,t} A_{t-1}^P$$

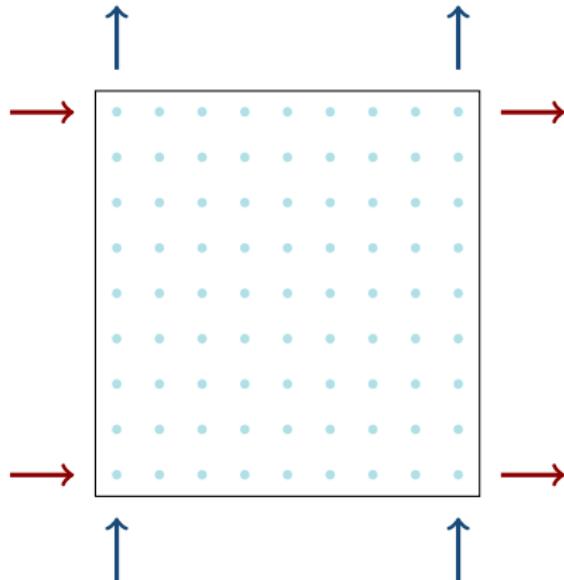
$$\log G_{A,t} = (1 - \rho_{G_A}) \log G_A + \rho_{G_A} \log G_{A,t-1} + \sigma_{G_A} \varepsilon_{G_A,t}$$

$$\log A_{x,t}^T = \rho_A \log A_{x,t-1}^T + \sigma_A \varepsilon_{A,x,t}$$

Similar AR(1) processes for  $G_{N,t}$ ,  $\tau_t$ ,  $\phi_t$  and  $\beta_t$ .

## Choice of space

- We choose a torus since this has a uniform steady state:



- Distance metric and continuous stochastic process:

$$d([x_1, x_2], [\tilde{x}_1, \tilde{x}_2]) = \sqrt{\left(\min\{|x_1 - \tilde{x}_1|, 1 - |x_1 - \tilde{x}_1|\}\right)^2 + \left(\min\{|x_2 - \tilde{x}_2|, 1 - |x_2 - \tilde{x}_2|\}\right)^2}$$
$$\text{cov}(\varepsilon_{A,x,t}, \varepsilon_{A,\tilde{x},t}) = s(\zeta, d(x, \tilde{x}))$$

► ACF

## Shock calibration

- ▶ To calibrate the spatial persistence of the shock, we use a dynamic factor approach using county-level quarterly average weekly wage growth as a proxy for productivity.

1. Compute first principle component then regress:

$$\Delta w_{i,t} = \beta_0 + \beta_1 \Delta w_{i,t-1} + \beta_2 \gamma_i F_t + \beta_3 \gamma_i F_{t-1} + e_{i,t} \quad (1)$$

2. Standardize residuals, compute the correlation matrix,  $\Sigma$ , across locations, and estimate  $\Sigma_{i,j} = \exp[-\zeta d_{i,j}]$ 
  - ▶ distance  $d_{i,j}$  is the geodesic distance between county centroids (i.e., as-the-crow flies between county centres), normalized so that the maximum distance is  $\sqrt{2}$ .

## Shock calibration

- ▶ To calibrate the spatial persistence of the shock, we use a dynamic factor approach using county-level quarterly average weekly wage growth as a proxy for productivity.
  1. Compute first principle component then regress:

$$\Delta w_{i,t} = \beta_0 + \beta_1 \Delta w_{i,t-1} + \beta_2 \gamma_i F_t + \beta_3 \gamma_i F_{t-1} + e_{i,t} \quad (1)$$

2. Standardize residuals, compute the correlation matrix,  $\Sigma$ , across locations, and estimate  $\Sigma_{i,j} = \exp[-\zeta d_{i,j}]$ 
    - ▶ distance  $d_{i,j}$  is the geodesic distance between county centroids (i.e., as-the-crow flies between county centres), normalized so that the maximum distance is  $\sqrt{2}$ .
- ▶ We estimate  $\zeta \approx 8$ .
  - ▶ Found estimate robust having experimented with various specifications including:
    - ▶ both state level and county level wages,
    - ▶ both fixed effect and state space approaches to removing common variation over time,
    - ▶ both in differences and filtered.

## Selected calibration

- ▶ U.S. evidence suggests that the average home buyer stays in their house for around 13 years (NAHB/DHUD).
  - ▶ Calibrate  $\psi_3$  to hit a proportion of  $\frac{1}{12.5 \times 4} = \frac{1}{50}$  household members moving each quarter.
- ▶ About 75% U.S. land is in broadly agricultural usage (USDA).
  - ▶ Set  $\theta_L = \frac{1-0.75}{0.75} \gamma \theta_F$ .
- ▶ Spending on food in U.S. is around 20% of personal consumption expenditure excluding housing (BEA).
  - ▶ Set  $\theta_F = \frac{1}{4} \theta_C$ .
- ▶ U.S. population density is  $41.5/\text{km}^2$ , but ranges between  $2.33/\text{km}^2$  for Wyoming and  $470/\text{km}^2$  for New Jersey.
  - ▶ Correspond to absolute log ratios to the whole U.S. of 2.88 and 2.43 respectively.
  - ▶ Set  $\Omega = 3$  to allow for such dispersion.

## Remaining parameters

- ▶ Set  $\theta_H = \theta_C$ , and  $\psi_1 = \psi_2 = \frac{\theta_F}{2}$ , so one remaining degree of freedom in preference share parameters.
- ▶ We set  $\theta_N$  to generate a high degree of persistence in population movements, while ensuring stability of the symmetric steady-state.
  - ▶ A more careful calibration will be in future versions.
- ▶ All parameters:

$$\alpha = 0.3, \gamma = 0.5, \kappa = 0.5, \nu = 2, \varsigma = 1.5, \zeta = 8, \lambda = 0.1, \delta_j = 0.01, \delta_k = 0.03,$$

$$\Gamma = 1, \Omega = 3, \Phi''(1) = 4,$$

$$\theta_C = \theta_H = 0.2618, \theta_F = \frac{\theta_C}{4}, \theta_L = 0.0109, \theta_N = 0.3338,$$

$$\psi_1 = \psi_2 = \frac{\theta_F}{2}, \psi_3 = 0.007,$$

$$G_A = 1.005, G_N = 1.0025, \tau = 1, \phi = 1, \beta = 0.99,$$

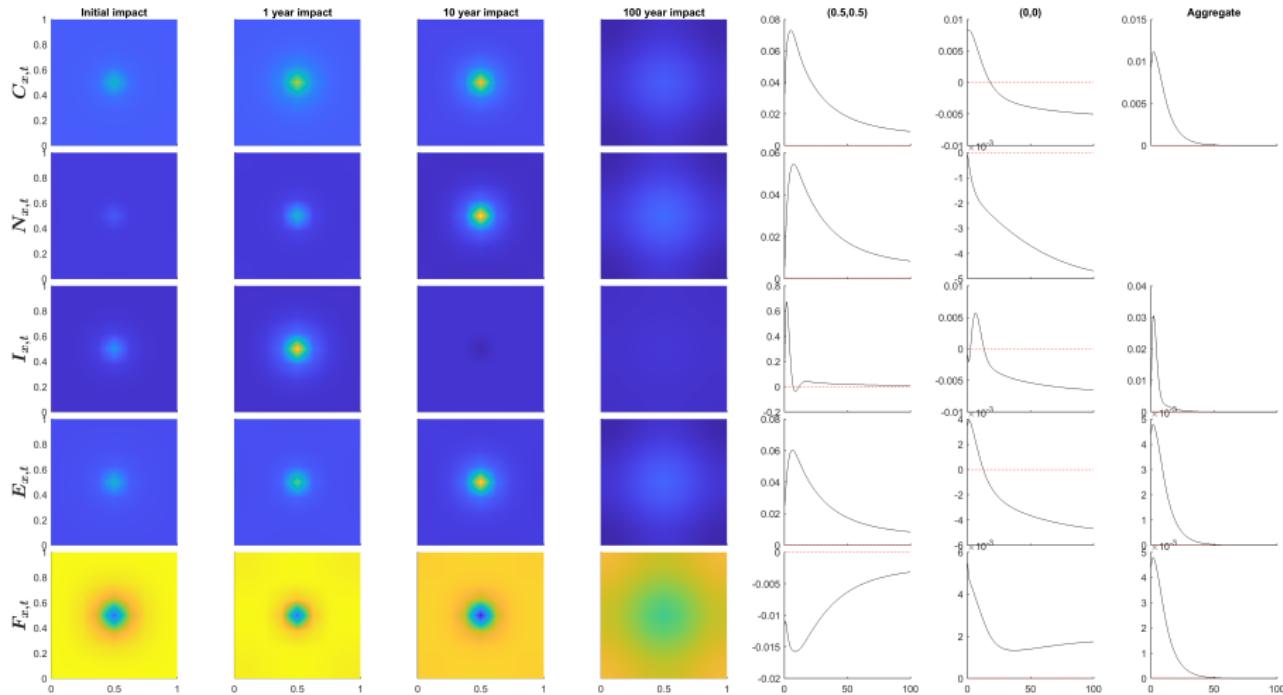
$$\rho_A = 0.9, \rho_{G_A} = 0.8, \rho_{G_N} = 0.5, \rho_\tau = 0.95, \rho_\phi = 0.95, \rho_\beta = 0.95,$$

$$\sigma_A = \sigma_{G_A} = \sigma_{G_N} = \sigma_\tau = \sigma_\phi = \sigma_\beta = 0.001.$$

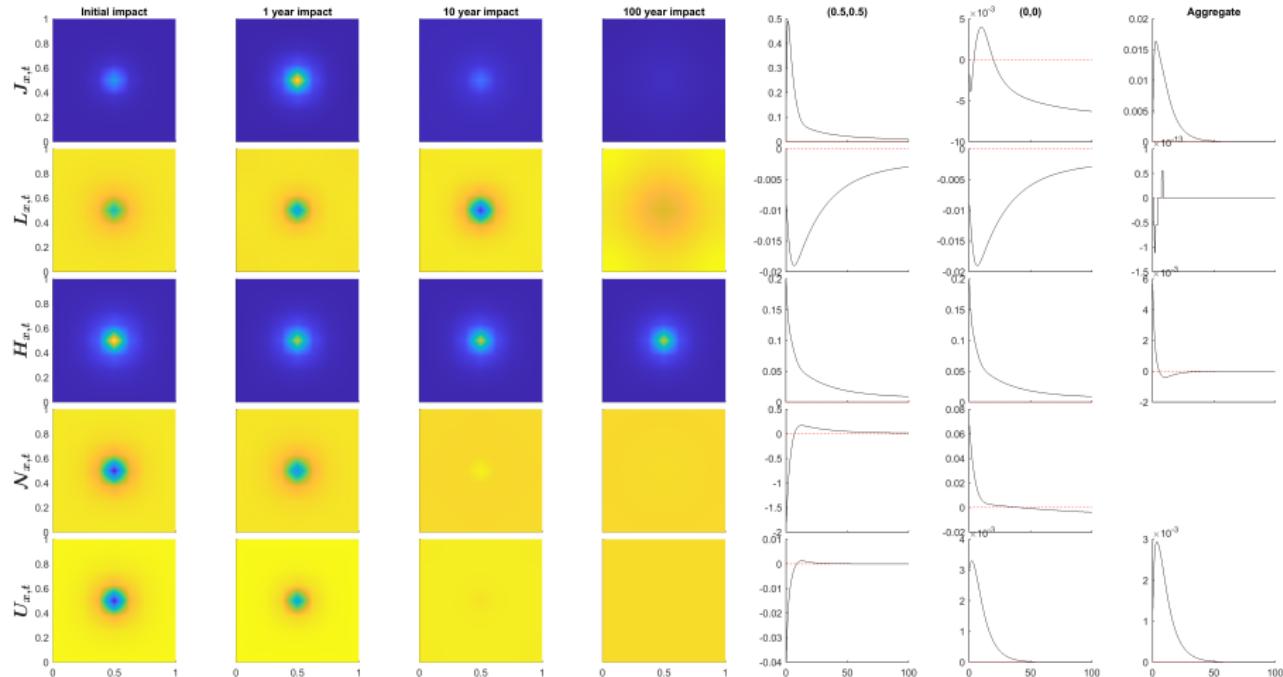
## Numerical Simulations

- ▶ Use a  $9 \times 9$  square grid.
- ▶ IRF simulations:
  - ▶ 1% spatial productivity shock.
  - ▶ Focus on shock centred on the point  $(\frac{1}{2}, \frac{1}{2})$ .
- ▶ 10,000 year stochastic simulation (video).

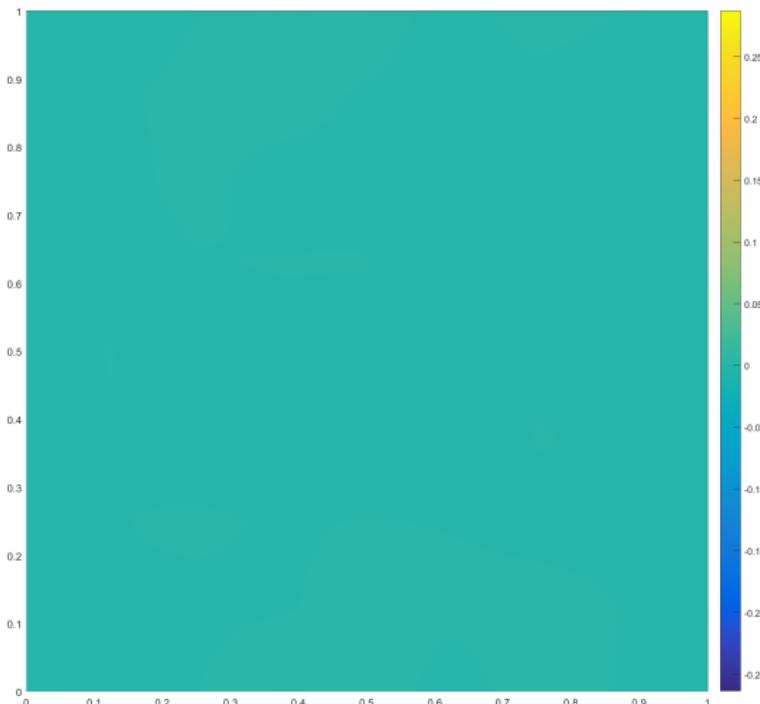
# IRF to spatial productivity shock I



# IRF to spatial productivity shock II



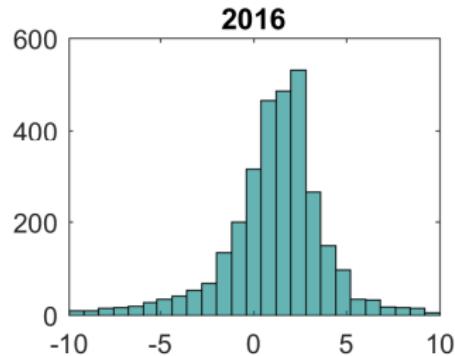
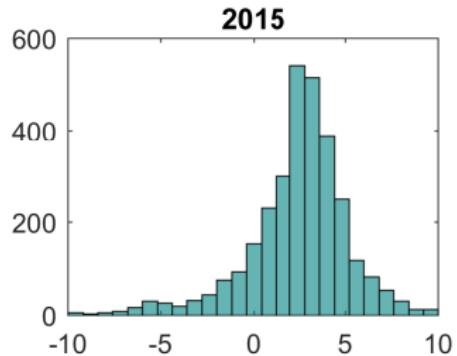
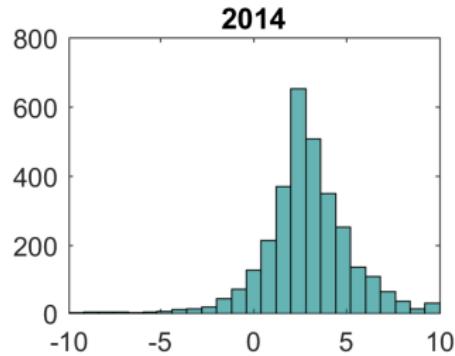
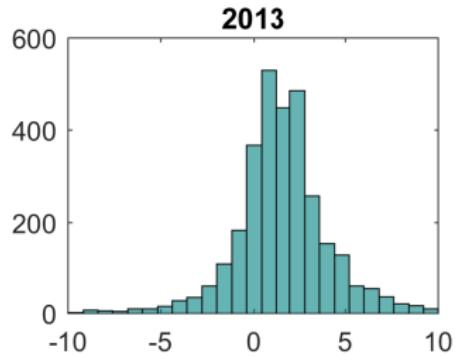
# 1000 years of population movements (Alternative link)



# Conclusions

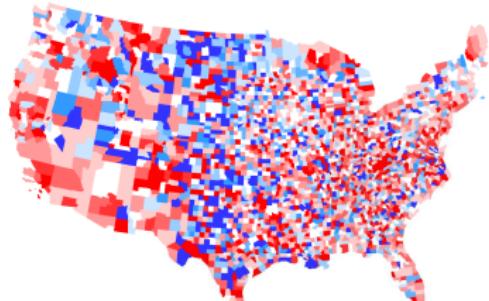
- ▶ We present a new approach to building heterogeneous agent models in which heterogeneity is across space.
  - ▶ Wide range of possible applications (not just physical space).
- ▶ Presented a DSGE model featuring key components of the new economic geography literature.
  - ▶ Including firm entry and strong agglomeration forces.
  - ▶ Model generates very persistent movements in population.
  - ▶ Leads to the birth and death of cities, and the rise and decline of regions
- ▶ Lots of plans for future work and extensions.
  - ▶ Comments appreciated!

# US county-level average weekly wage oty % change (BLS)

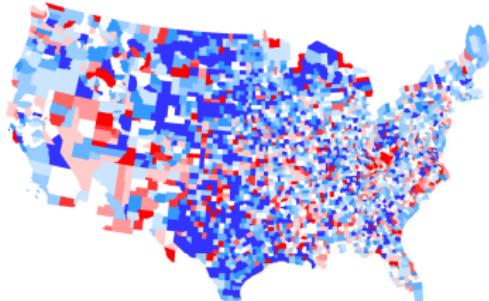


# US county-level average weekly wage growth % change (BLS)

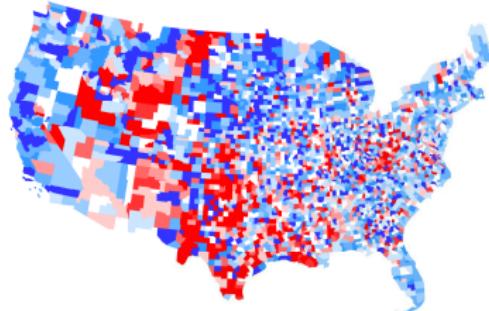
2013



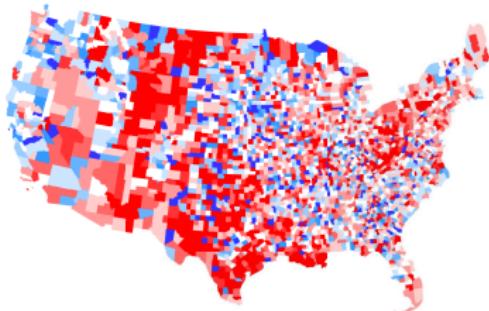
2014



2015



2016



► Return

# New economic geography

Starts with Krugman (1991). See Krugman (1998) and Redding (2013) for reviews.

Branches of the existing literature:

- ▶ Stochastic, forward-looking, but few locations, e.g., two-bloc model:
  - ▶ E.g., Caselli & Coleman II (2001).
- ▶ Stationary equilibria, or purely backward looking decisions, with discrete space:
  - ▶ E.g., Michaels, Rauch & Redding (2012), Nagy (2016) and Eckert & Peters (2017).
- ▶ Continuous space, dynamic but backward-looking:
  - ▶ E.g., Desmet & Rossi-Hansberg (2014) and Desmet, Nagy & Rossi-Hansberg (2015).
- ▶ Some dynamic stochastic models in continuous space but with restrictive assumptions:
  - ▶ E.g., Quah (2002), Brito (2004), Duranton (2007), Rossi-Hansberg & Wright (2007) and Boucekkine, Camacho & Zou (2009).

## Auto-covariance function

We recommend (and use) the following auto-covariance function on a circle (identified with  $[0, 1]$ ) or torus (identified with  $[0, 1] \times [0, 1]$ ):

$$\text{cov}(\varepsilon_x, \varepsilon_{\tilde{x}}) = s(\zeta, d(x, \tilde{x}))$$

where:

$$s(\zeta, d) = \frac{\exp(-\zeta d + \zeta \bar{d}) + \exp(\zeta d - \zeta \bar{d})}{\exp(\zeta \bar{d}) + \exp(-\zeta \bar{d})}$$

and:

$$\bar{d} \equiv \sup_{x, \tilde{x} \in X} d(x, \tilde{x})$$

is the maximum distance between points.

The reasons for this choice are made clear in the paper.

## For example... [To be examined fully in another paper]

The shale oil and gas "revolution" in the US provides a natural experiment to look at the effects of regional shocks on broader outcomes.

- ▶ Even with assorted controls, "high oil (gas) growth" (ERS-USDA) counties experienced 43.3ppts (25.4ppts) higher wage growth than other counties between 2000 and 2011.
- ▶ Over the period, population growth was significantly above average in such counties.
- ▶ Looking at the Bakken Shale Play area in North Dakota, up to 2012 we see sharp increases in population and wage growth not just in the shale counties, but also in neighbouring ones.
- ▶ After 2012, there is a corresponding decline.

# Household first order conditions I

- ▶ Euler equation:

$$1 = \mathbb{E}_t [\Xi_{t,t+1} R_t]$$

- ▶ where:

$$\Xi_{t,t+1} \equiv \beta_t \frac{N_{x,t} E_{x,t} U_{x,t+1}^{1-\varsigma}}{N_{x,t-1} E_{x,t+1} U_{x,t}^{1-\varsigma}}$$

- ▶ and:

$$\frac{E_{x,t}}{N_{x,t-1} U_{x,t}^{1-\varsigma}} = \frac{E_{\tilde{x},t}}{N_{\tilde{x},t-1} U_{\tilde{x},t}^{1-\varsigma}}$$

## Household first order conditions II

- ▶ Consumption:

$$\theta_C E_{x,t} = \theta_F P_{x,t} C_{x,t}$$

- ▶ Land:

$$\theta_L E_{x,t} = \theta_F \mathcal{R}_{L,x,t} (1 - L_{x,t})$$

- ▶ Labour:

$$\theta_H \left( \frac{H_{x,t}}{N_{x,t-1}} \right)^\nu = \theta_F \frac{N_{x,t-1}}{E_{x,t}} W_{x,t} \left( \frac{1}{1+\nu} \Gamma^{1+\nu} - \frac{1}{1+\nu} \left( \frac{H_{x,t}}{N_{x,t-1}} \right)^{1+\nu} \right)$$

# Household first order conditions III

## ► Population:

$$\mu_{N,x,t} = \beta_t \mathbb{E}_t \left[ \begin{array}{l} \mu_{N,x,t+1} G_{N,t+1} + u_{x,t+1}^{1-\varsigma} \\ + (1-\varsigma) u_{x,t+1}^{1-\varsigma} \left[ \theta_H \frac{\left( \frac{H_{x,t+1}}{N_{x,t}} \right)^{1+\nu}}{\frac{1}{1+\nu} \Gamma^{1+\nu} - \frac{1}{1+\nu} \left( \frac{H_{x,t+1}}{N_{x,t}} \right)^{1+\nu}} - \theta_N \frac{\log \left( \frac{N_{x,t}}{N_t} \right)}{\frac{1}{2} \Omega^2 - \frac{1}{2} \left( \log \left( \frac{N_{x,t}}{N_t} \right) \right)^2} \right. \\ \left. + \psi_1 \frac{\mathcal{N}_{x,t+1}}{N_{x,t} - \mathcal{N}_{x,t+1}} - (\theta_C + \theta_F + \theta_L + \psi_3) \right] \end{array} \right]$$

## ► Migration:

$$\mu_{N,x,t} = \mu_{N,\tilde{x},t} + (1-\varsigma) N_{x,t-1} u_{x,t}^{1-\varsigma} \left[ \psi_3 \frac{N_{\tilde{x},t-1}}{N_{t-1} \mathcal{N}_{x,\tilde{x},t}} - \psi_1 \frac{1}{N_{x,t-1} - \mathcal{N}_{x,t}} - \psi_2 \frac{d(x, \tilde{x}) \mathcal{N}_{x,t} - \mathcal{D}_{x,t}}{\bar{d} \mathcal{N}_{x,t}^2 - \mathcal{N}_{x,t} \mathcal{D}_{x,t}} \right]$$

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