

# CS2040S

## Data Structures and Algorithms

All about minimum spanning trees...

### Riddle of the Week: The Travelling SalesPeople

Three travelers show up at a hotel where a room costs \$300. They each pay \$100 and go to their room.

The manager realizes there is a special sale and the room only costs \$250. He gives his assistant \$50 to return to the travelers. The assistant only has tens for change, and so gives each traveler \$10 in change, keeping \$20 for himself.

So each traveler paid \$90, and the assistant kept \$20, leading to a total of  $3 \times 90 + 20 = 290$  dollars. What happened to the remaining 10 dollars?

# Roadmap

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## Minimum Spanning Trees

- Background
- Prim's Algorithm
- Kruskal's Algorithm
- (Boruvka's Algorithm)

## Variations:

- Constant weight edges
- Bounded integer edge weights
- Directed graphs
- Maximum Spanning Tree

# Roadmap

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## Minimum Spanning Trees

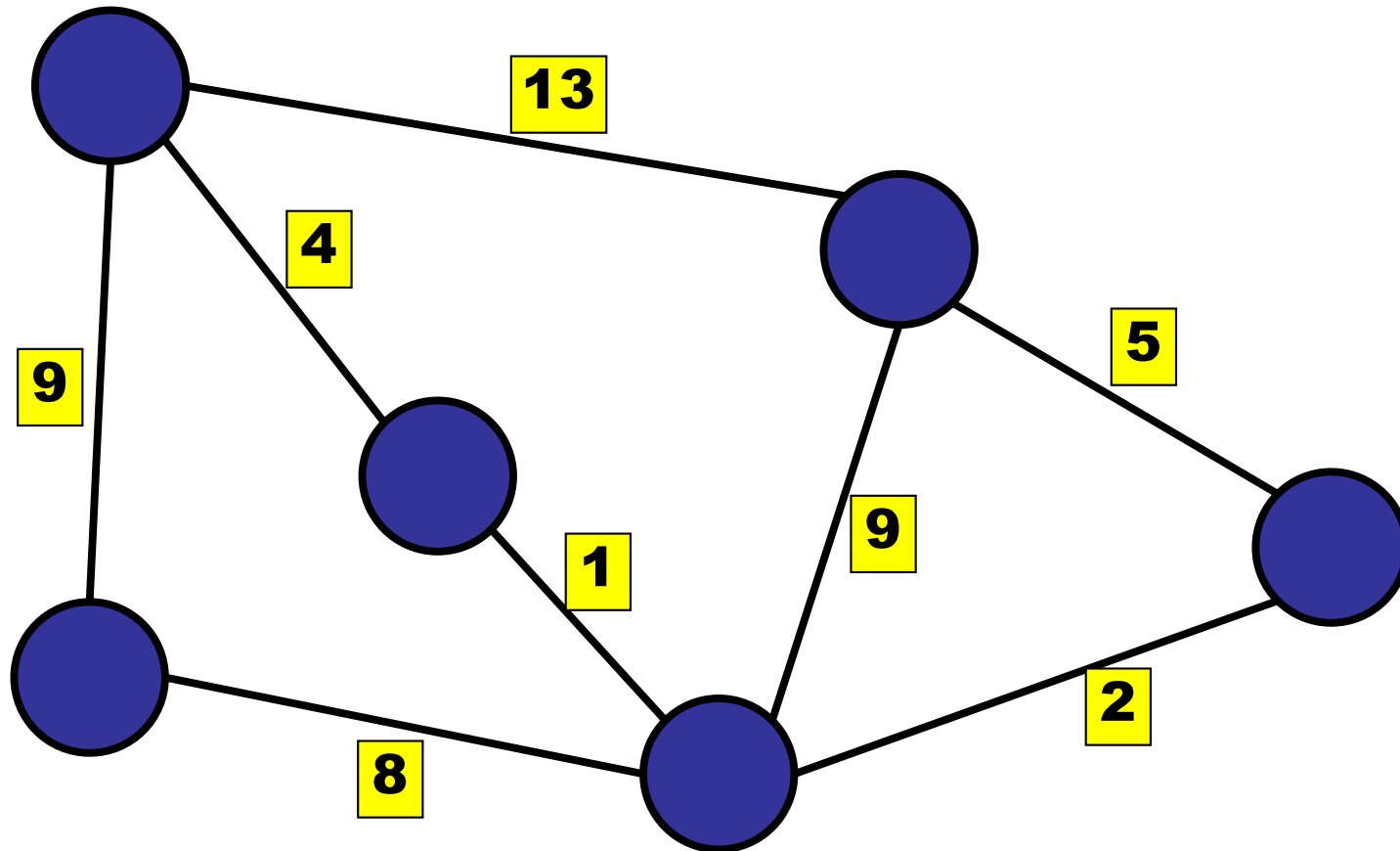
- **The MST Problem**
- Basic Properties of an MST
- Generic MST Algorithm
- Prim's Algorithm
- Kruskal's Algorithm
- Variations
- (Boruvka's Algorithm)

# Spanning Tree

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Weighted, undirected graph:

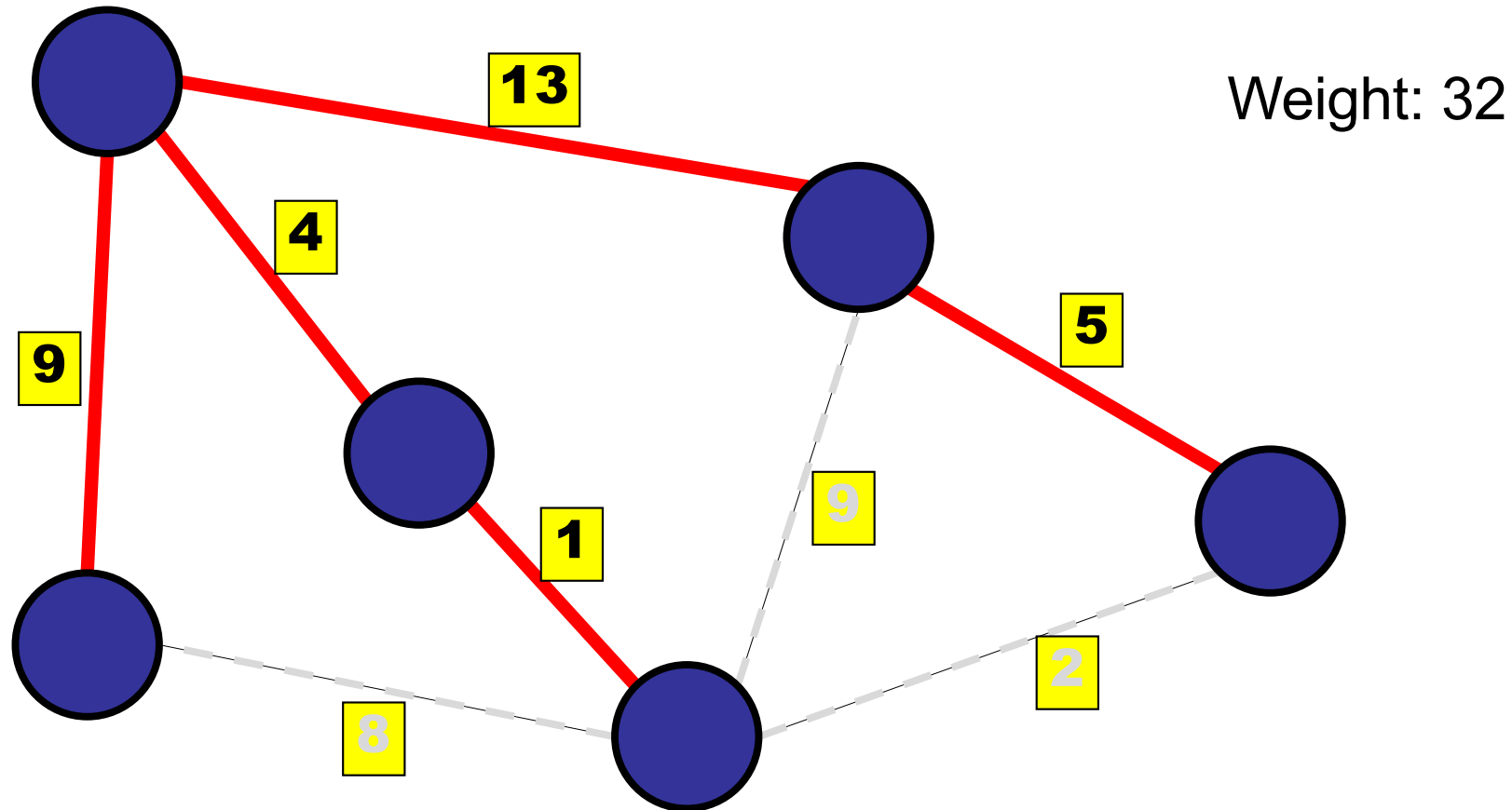
To think about:  
Why is this more  
complicated with  
directed graphs?



# Spanning Tree

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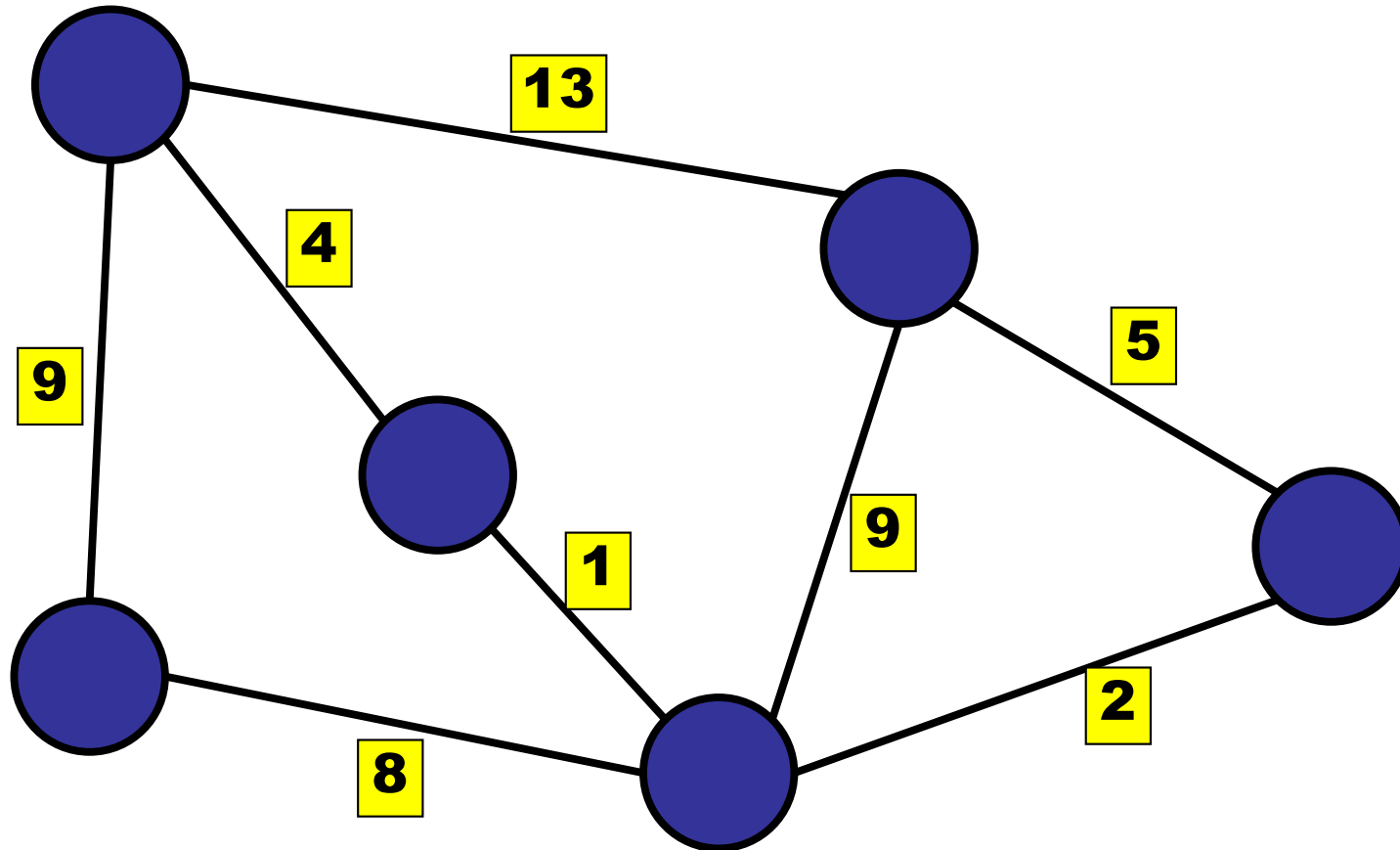
Definition: a spanning tree is an acyclic subset of the edges that connects all nodes



# Minimum Spanning Tree

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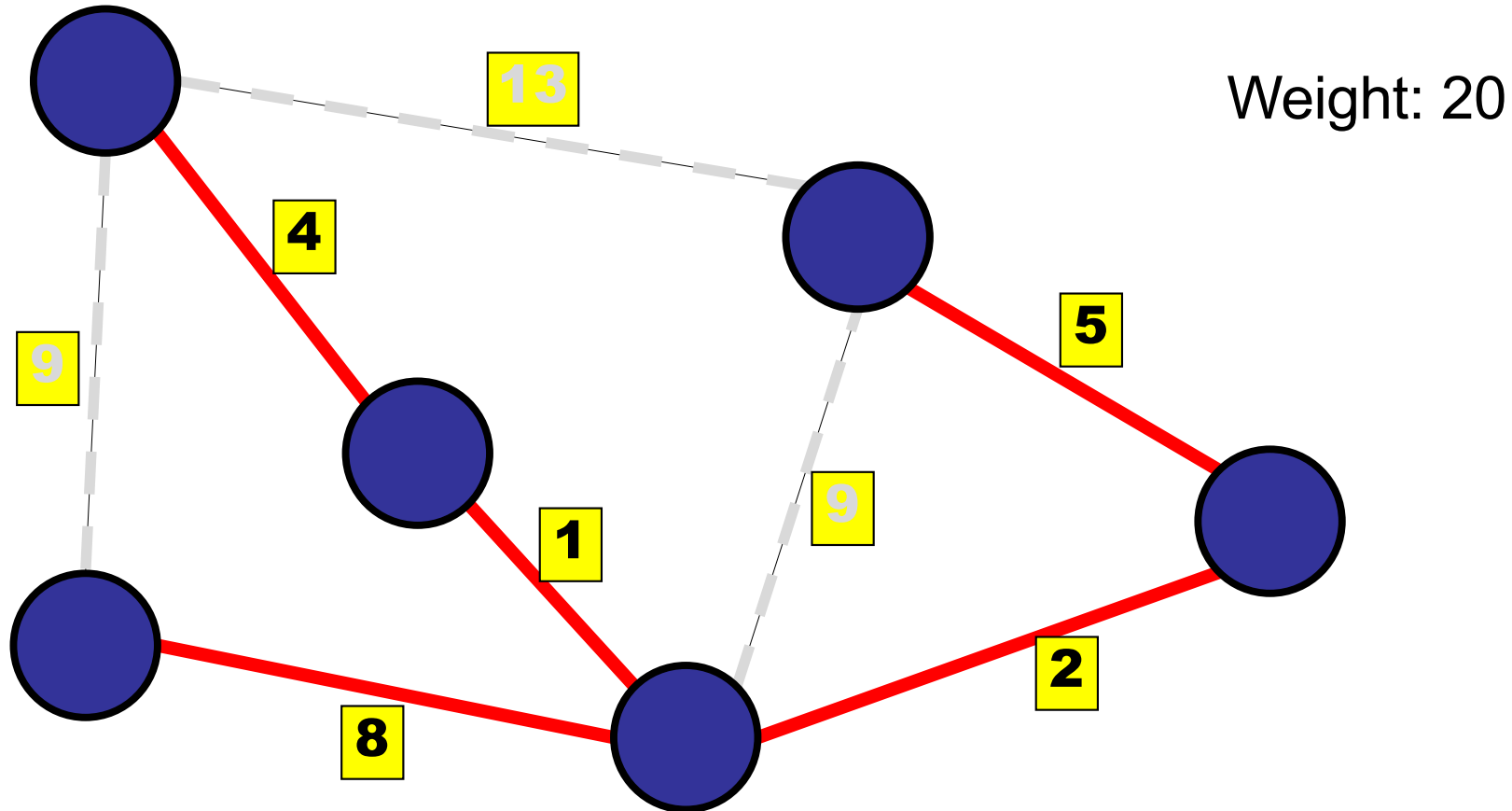
Definition: a spanning tree with minimum weight



# Minimum Spanning Tree

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Definition: a spanning tree with minimum weight

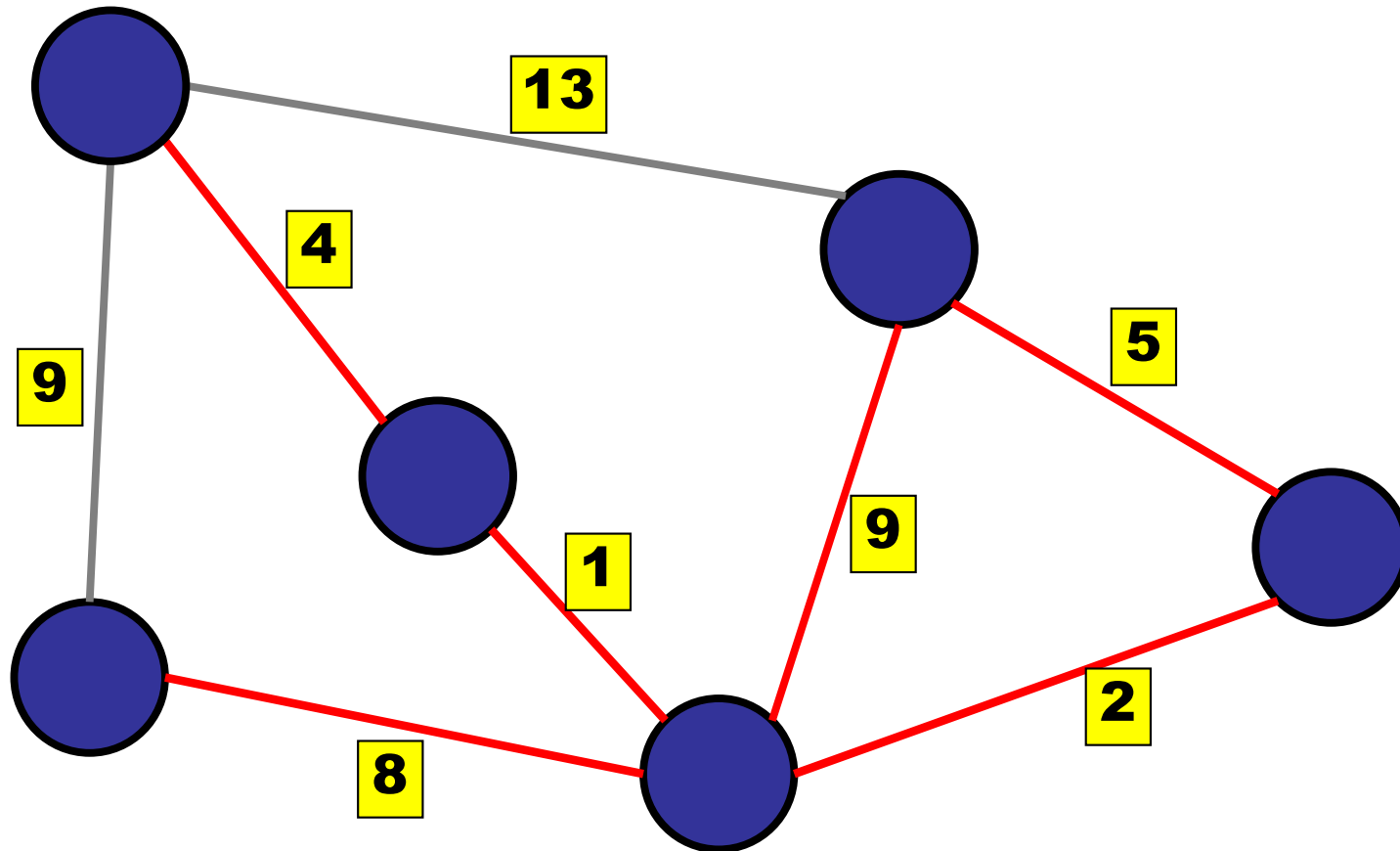


# Minimum Spanning Tree

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Note: no cycles

Why? If there were cycles, we could remove one edge and reduce the weight!





# Can we use MST to find shortest paths?

1. Yes
2. Only on connected graphs.
3. Only on dense graphs.
- ✓ 4. No.
5. I need to see a picture.

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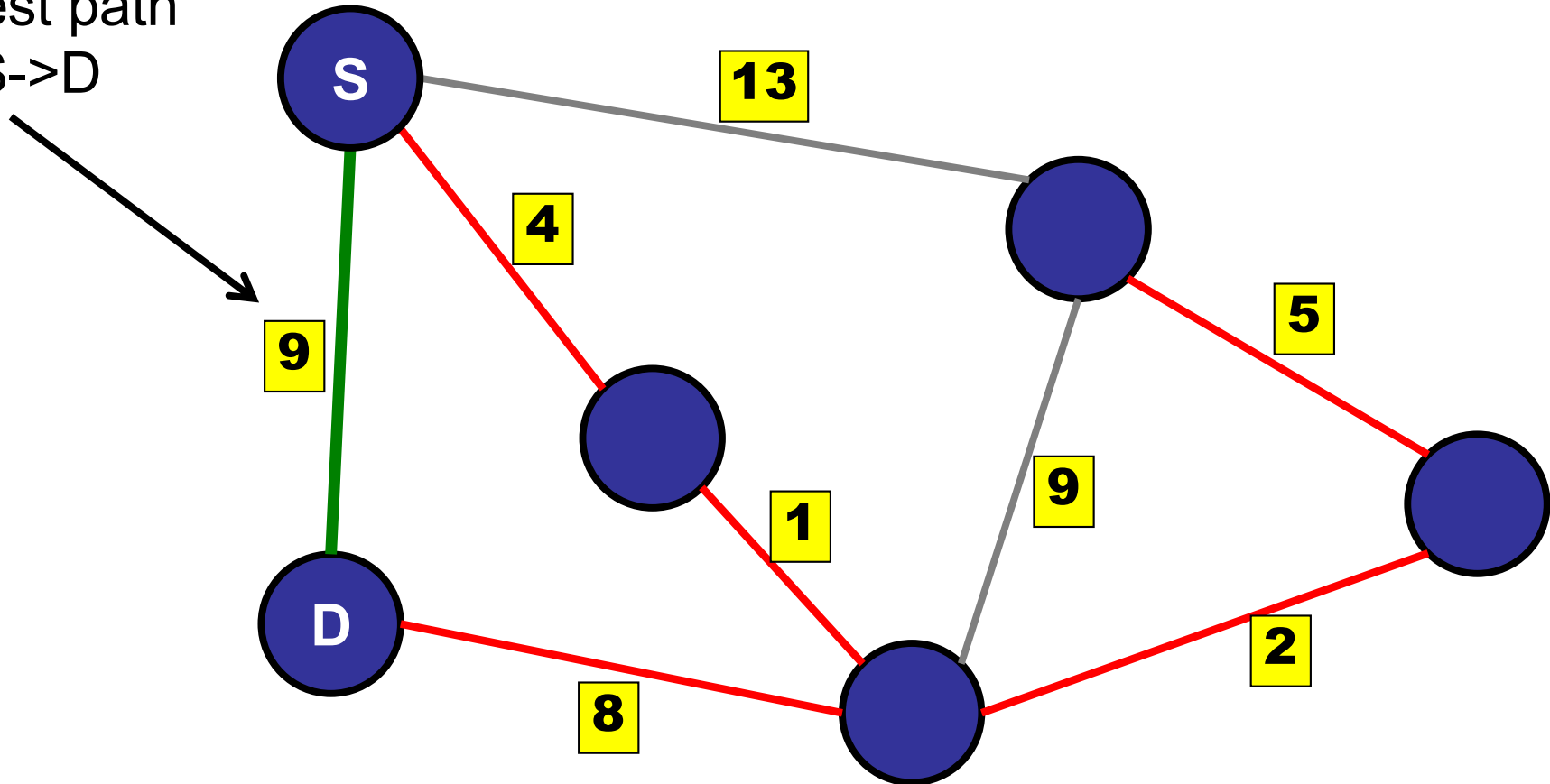
is open

# Minimum Spanning Tree

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Not the same a shortest paths:

Shortest path  
from S->D



# Applications of MST

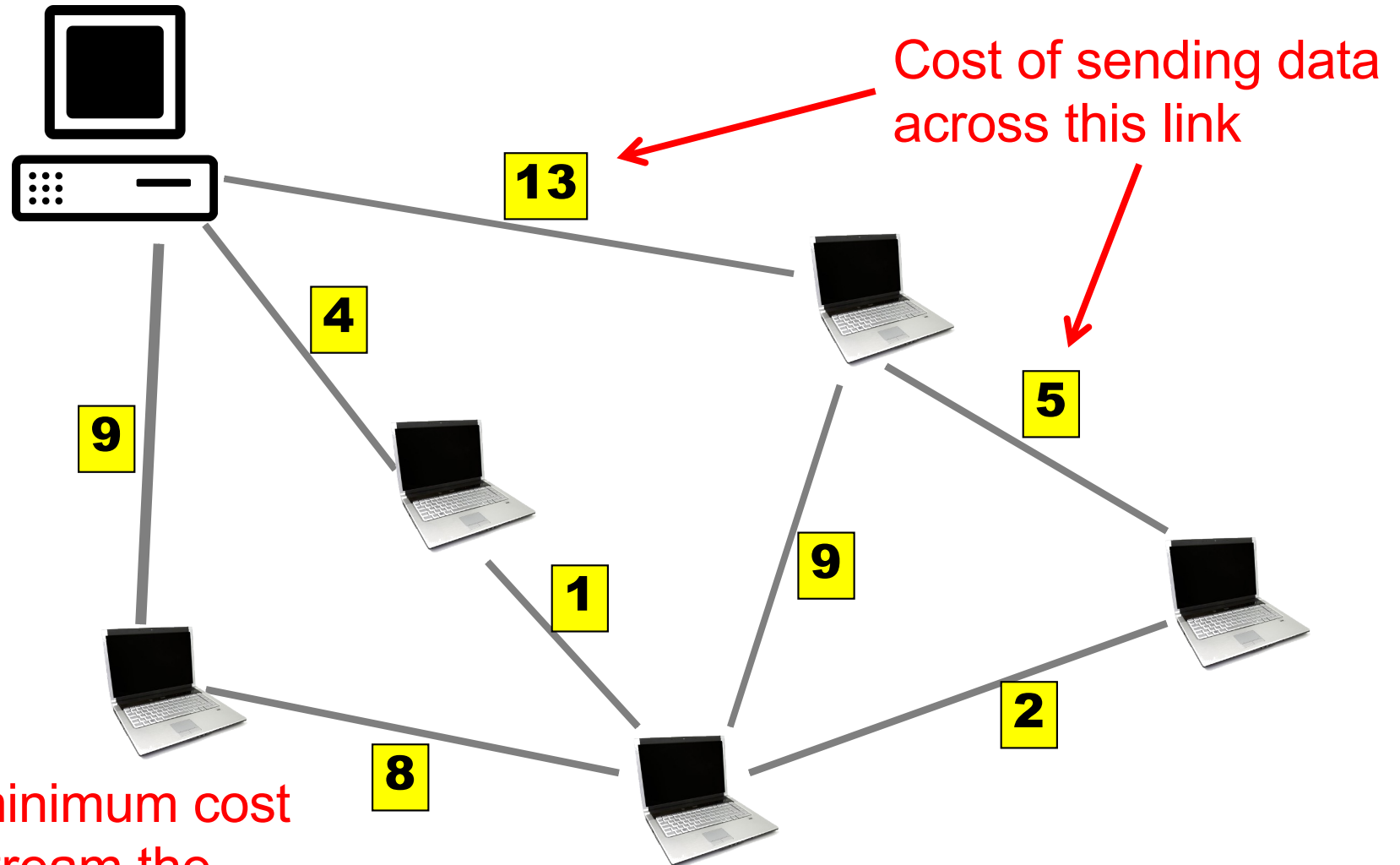
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## Network design problems:

- Telephone networks
- Electrical networks
- Computer networks
- Ethernet autoconfig
- Road networks
- Bottleneck paths

# Data distribution

Stream a movie over the internet:



What is the minimum cost **network** to stream the movie to all the users?

# Applications of MST

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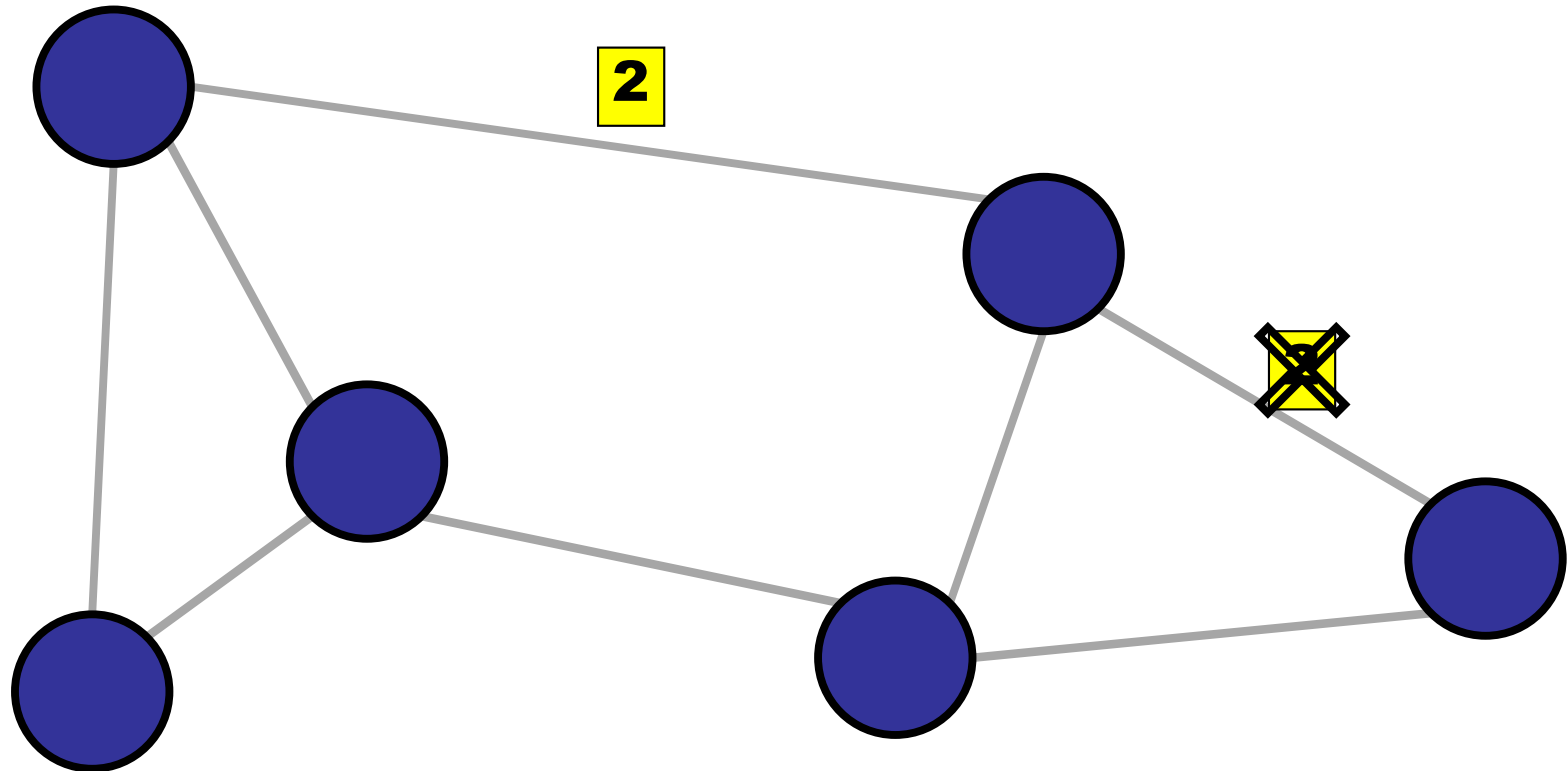
Less obvious applications:

- Error correcting codes
- Face verification
- Cluster analysis
- Image registration

# Assumption

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All edge weights are distinct. (Simplification...)



# Roadmap

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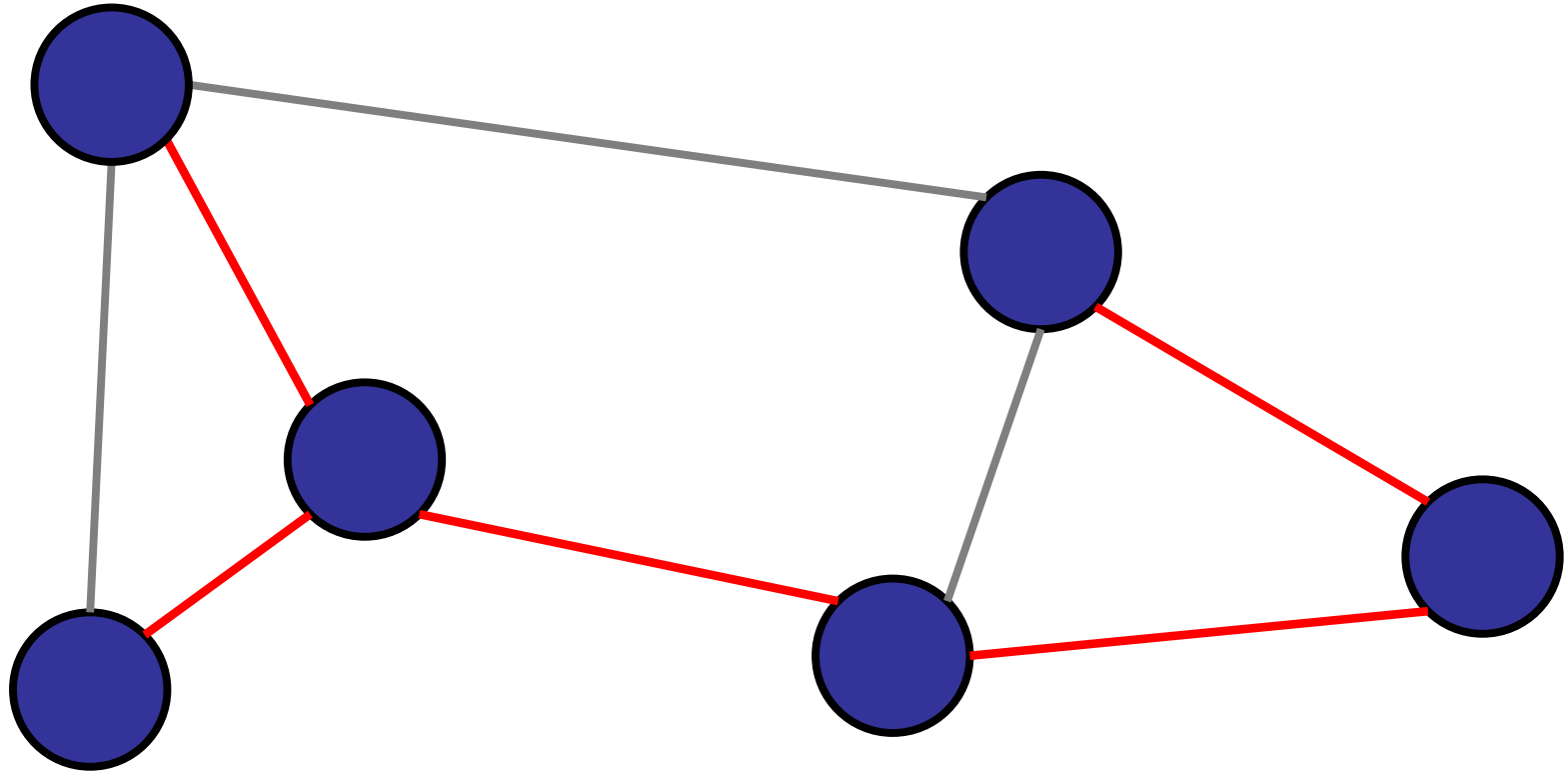
## Minimum Spanning Trees

- The MST Problem
- **Basic Properties of an MST**
- Generic MST Algorithm
- Prim's Algorithm
- Kruskal's Algorithm
- Boruvka's Algorithm
- Variations

# Properties of MST

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Property 1: No cycles

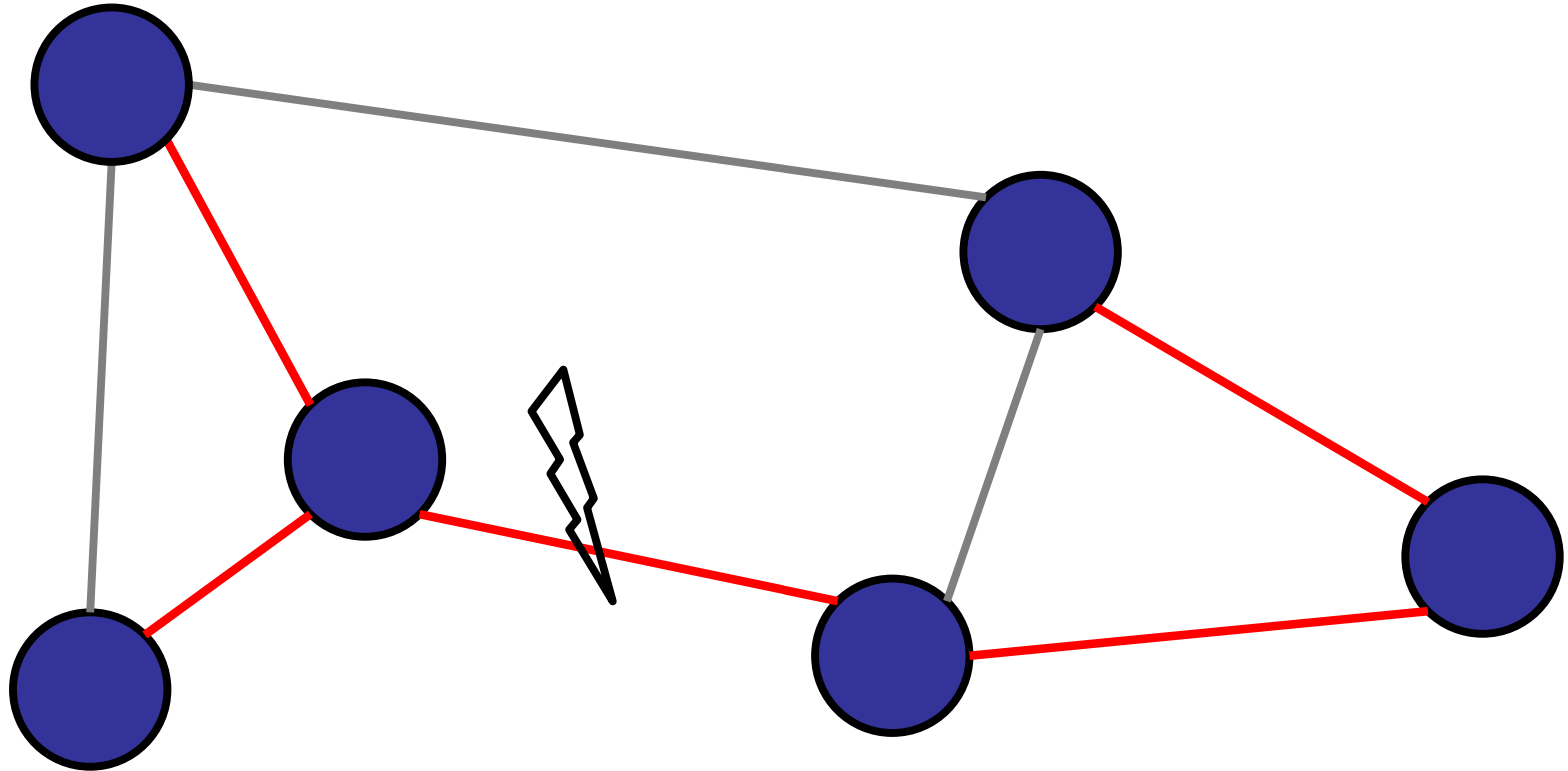




# Properties of MST

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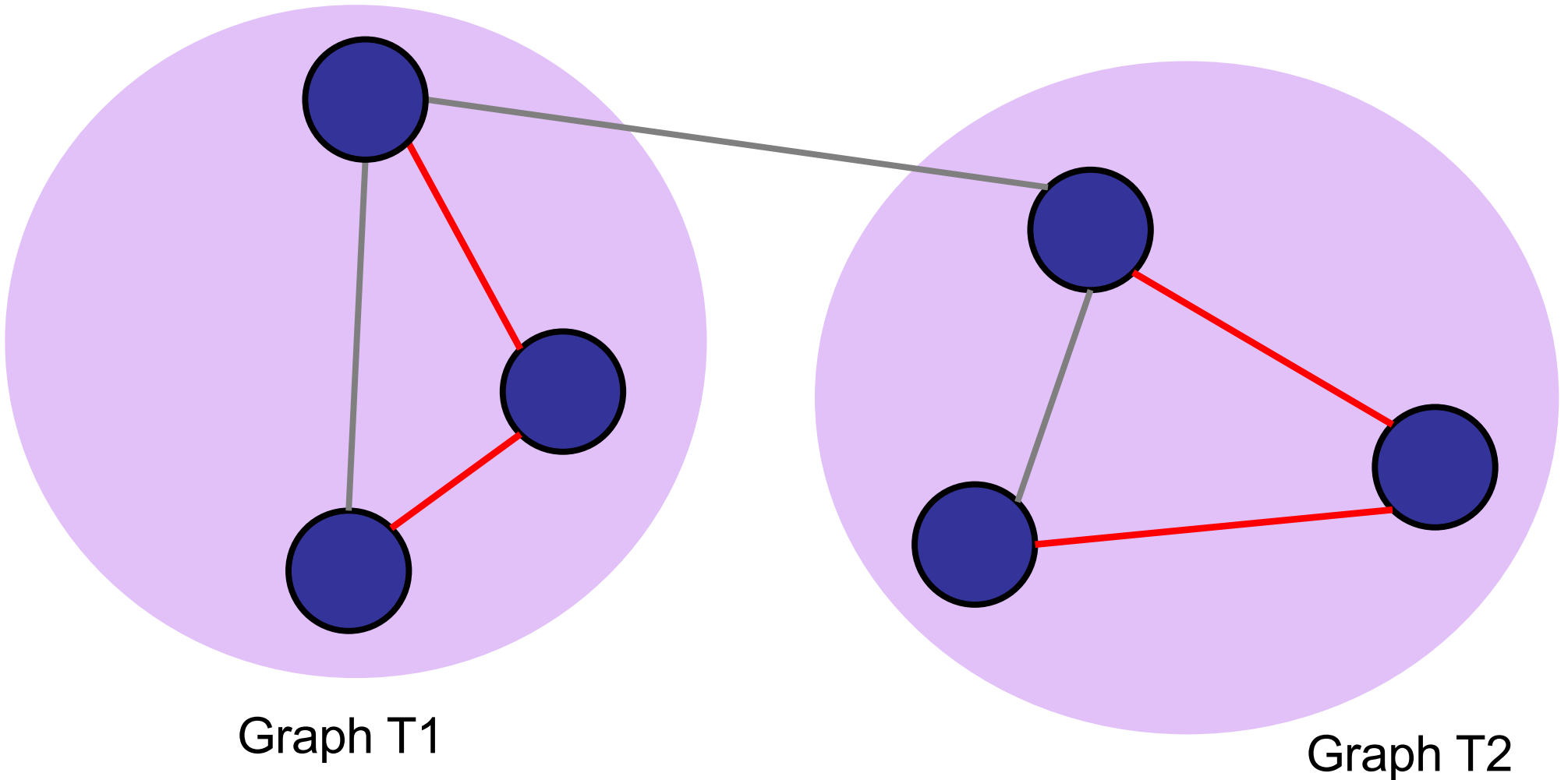
What happens if you cut an MST?



# Properties of MST

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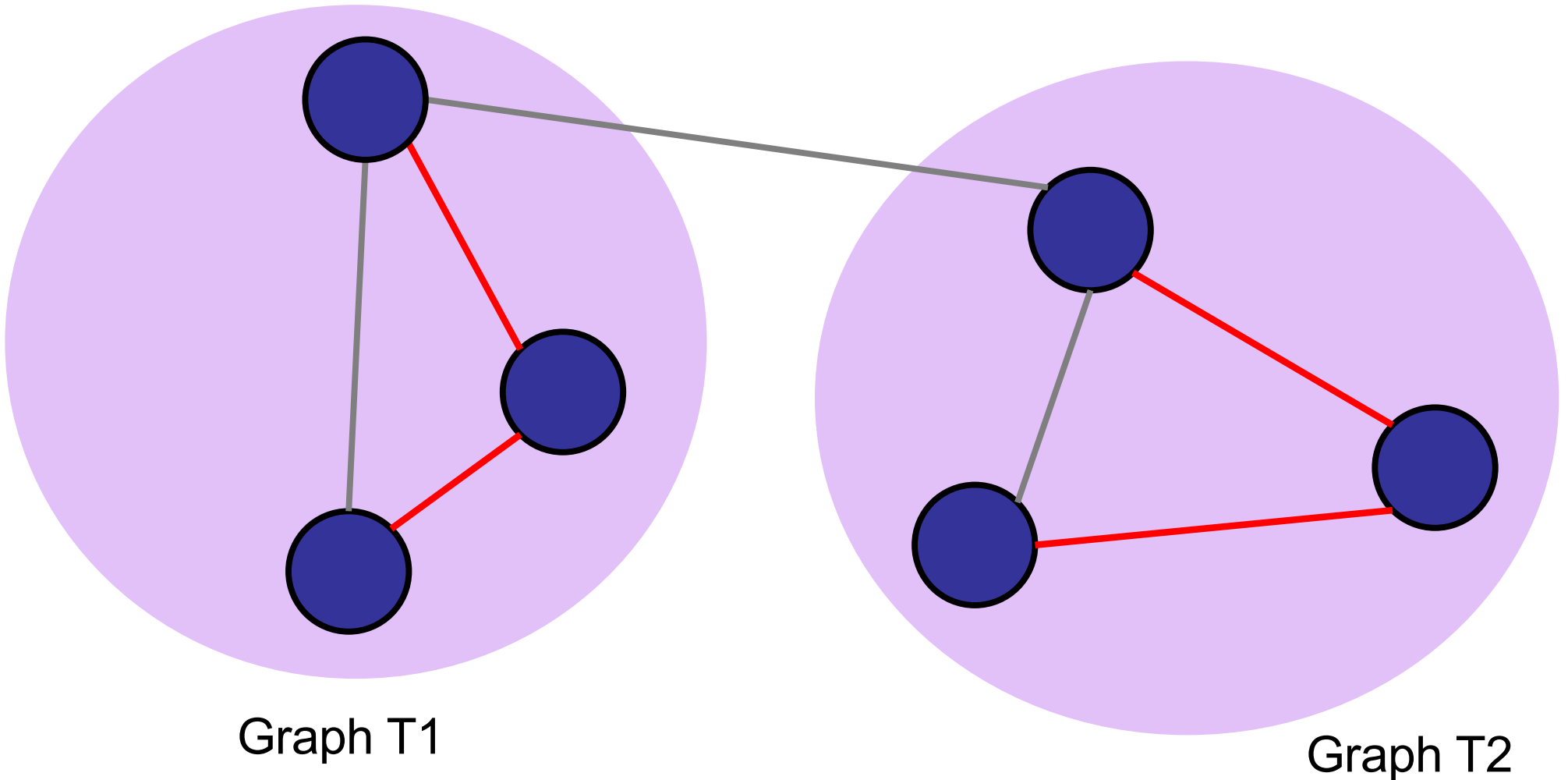
What happens if you cut an MST?



# Properties of MST

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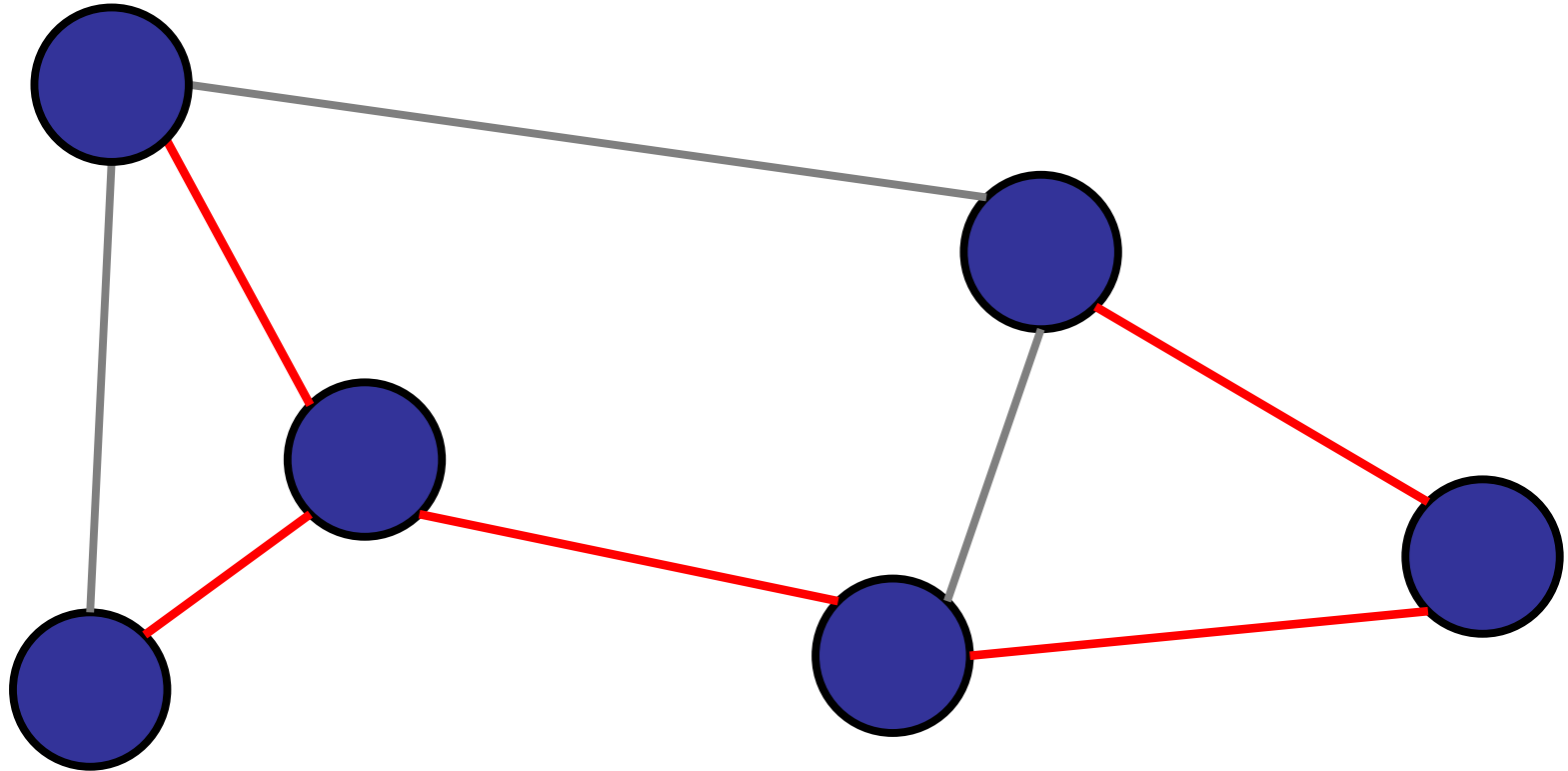
Theorem: T1 is an MST and T2 is an MST.



# Properties of MST

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Property 2: If you cut an MST, the two pieces are both MSTs.

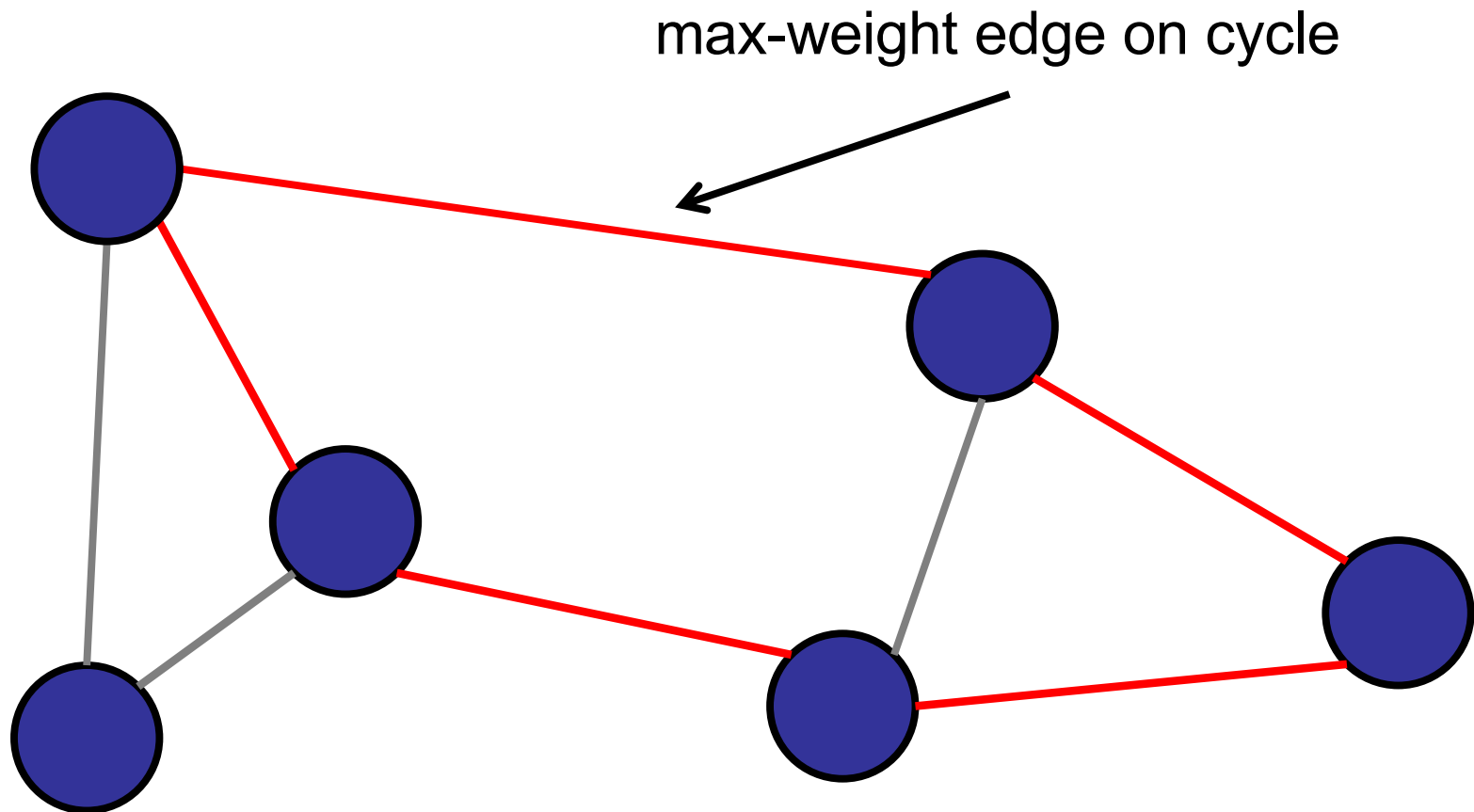


*Overlapping sub-problems! Dynamic programming? Yes, but better...*

# Properties of MST

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## Property 3: Cycle property

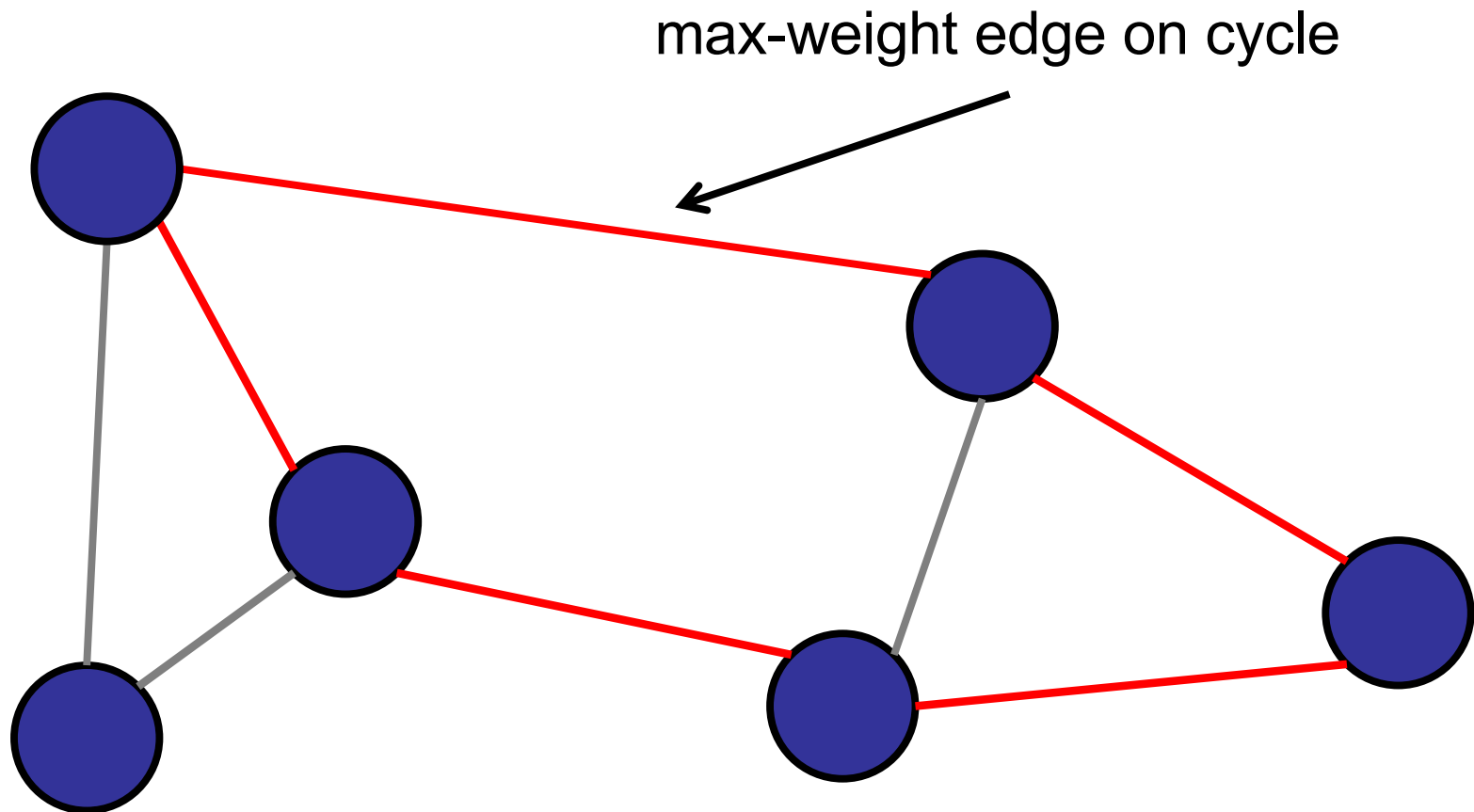


# Properties of MST

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## Property 3: Cycle property

For every cycle, the maximum weight edge is **not** in the MST.

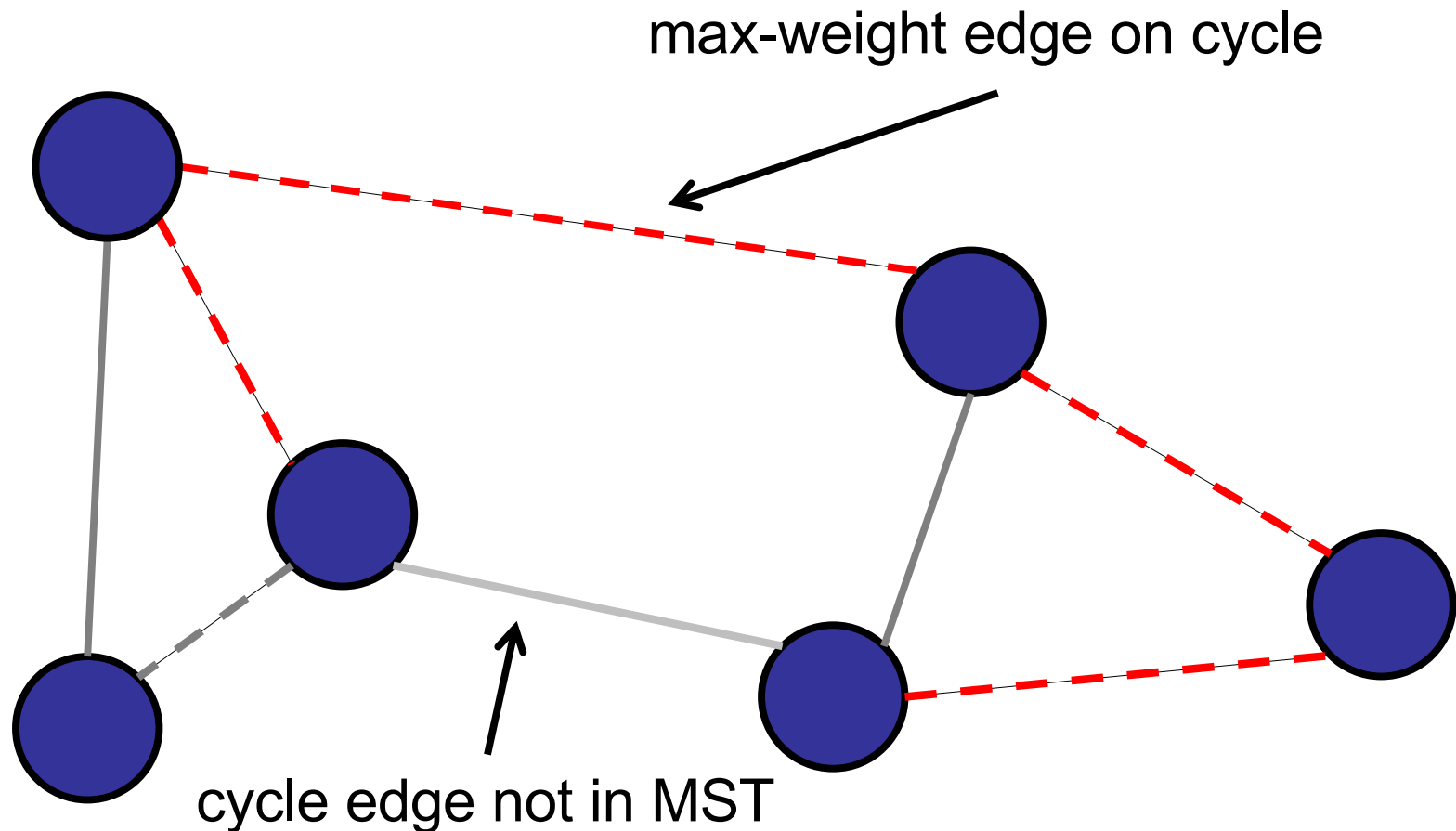


# Properties of MST

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Proof: Cut-and-paste

Assume heavy edge is in the MST.



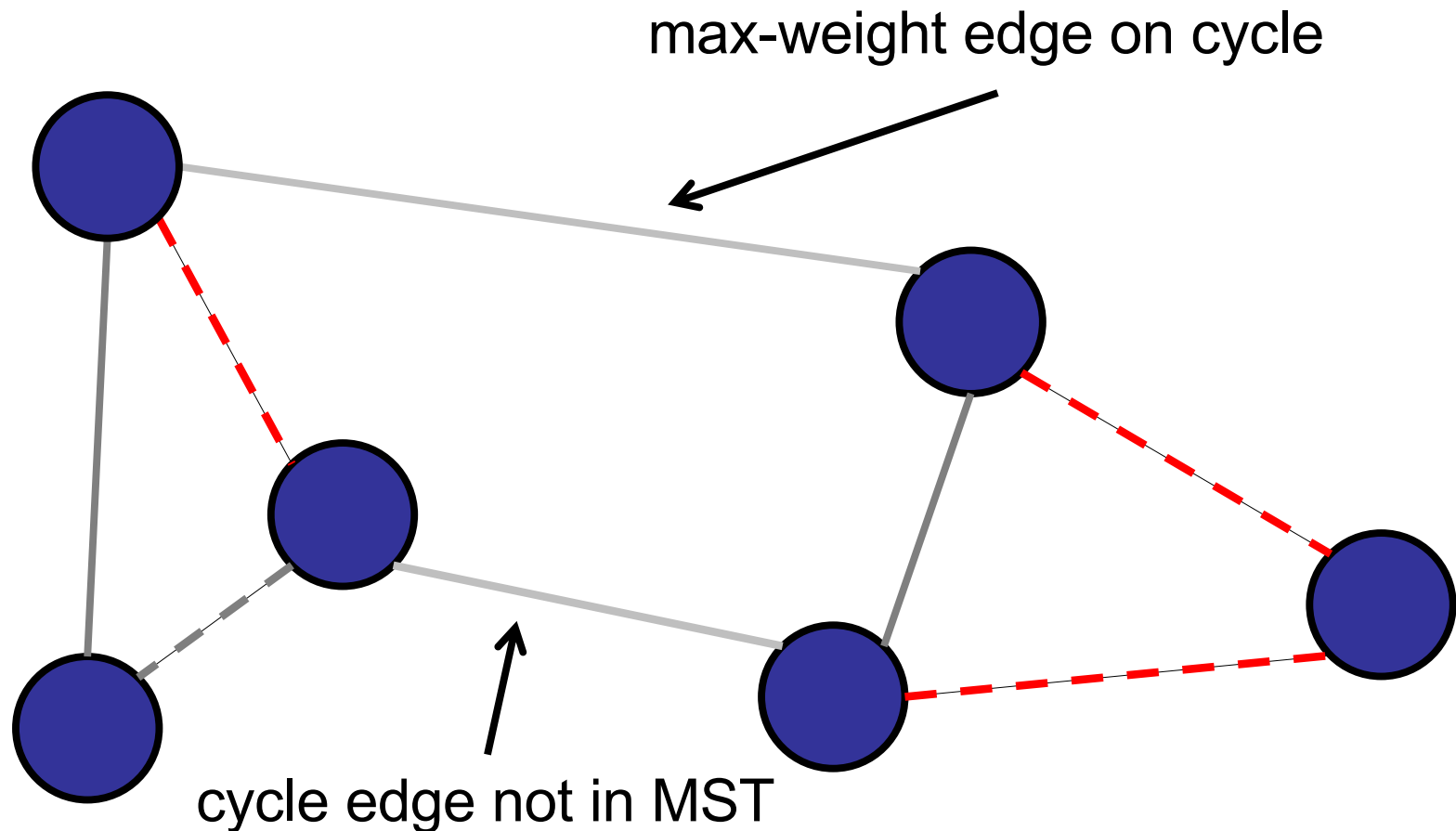
# Properties of MST

---

Proof: Cut-and-paste

Assume heavy edge is in the MST.

Remove max-weight edge; cuts graph.



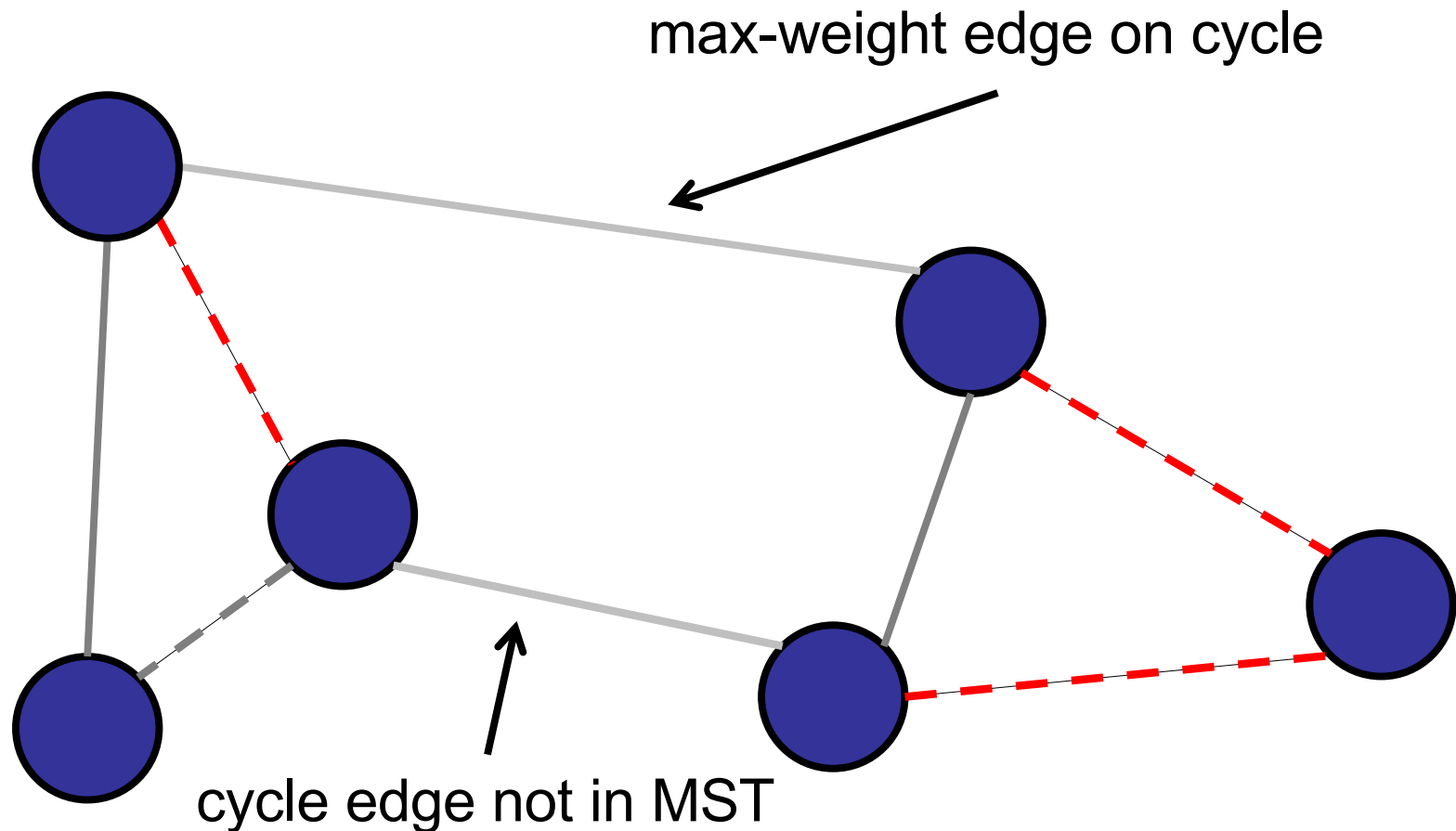


# Properties of MST

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## Proof: Cut-and-paste

There exists another cycle edge that crosses the cut. (Even # of cycle edges across cut.)



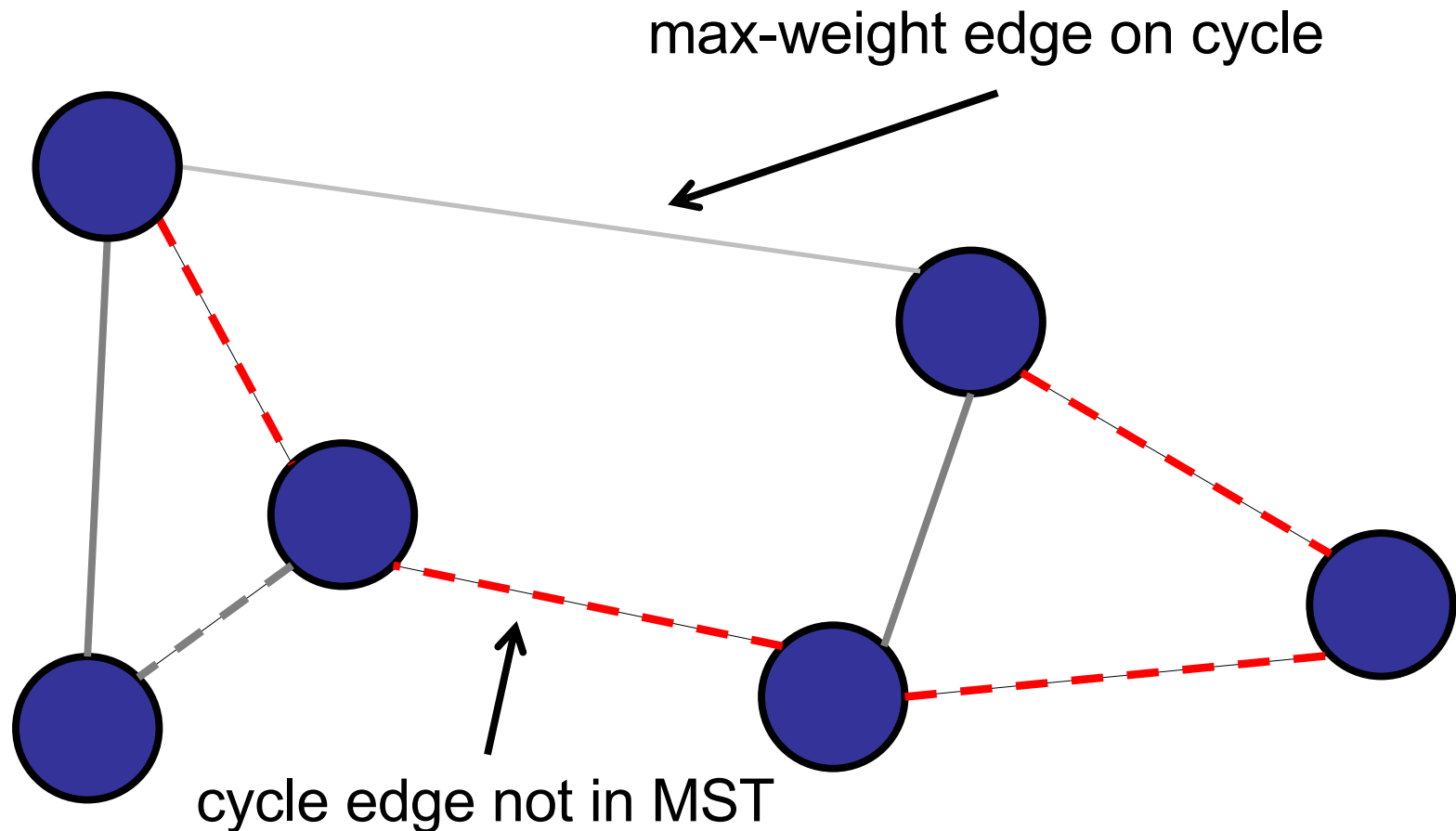
# Properties of MST

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Proof: Cut-and-paste

Replace heavy edge with lighter edge.

Still a spanning tree: Property 2.

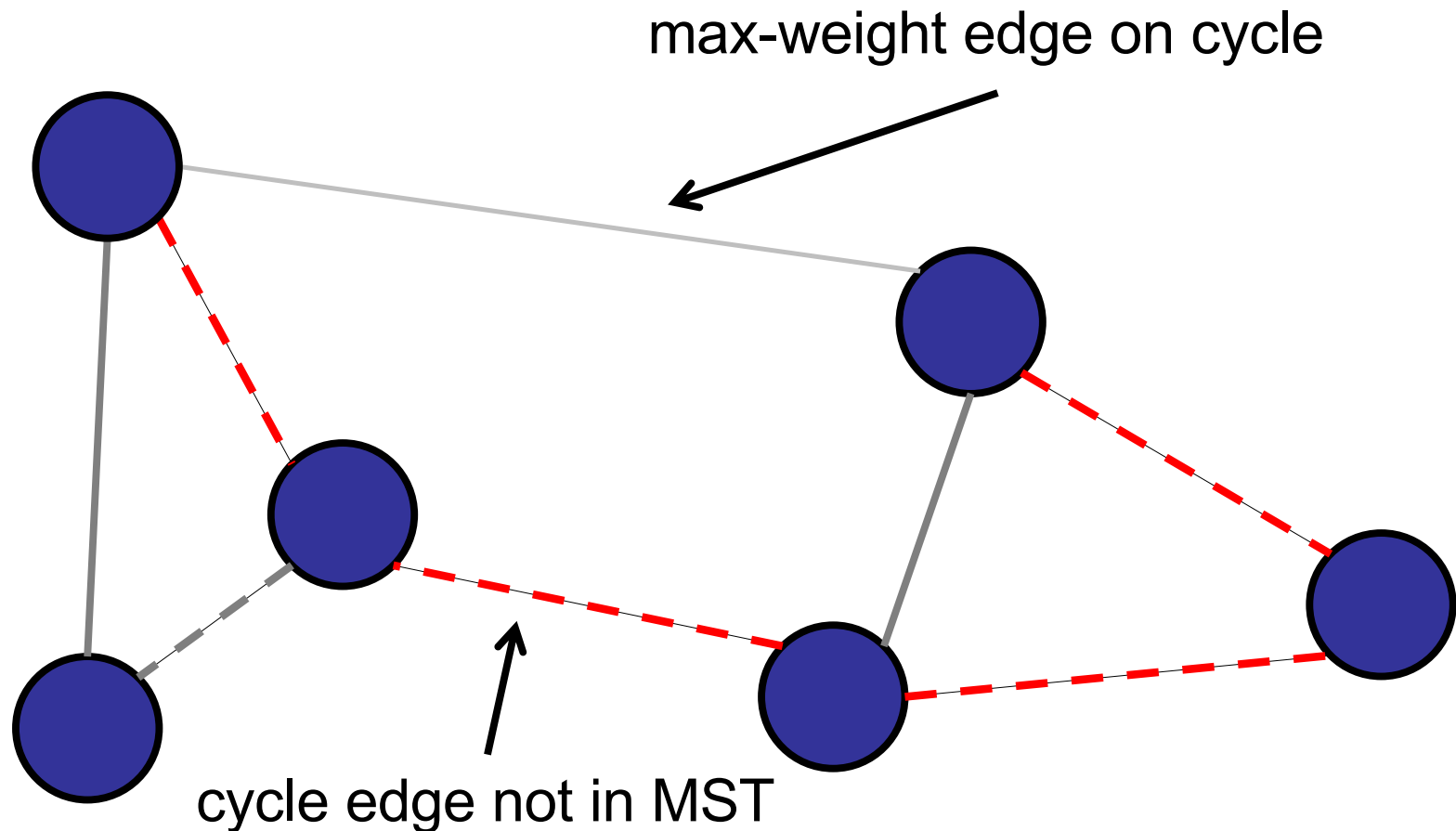


# Properties of MST

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Proof: Cut-and-paste

Replace heavy edge with lighter edge.  
Less weight! Contradiction...

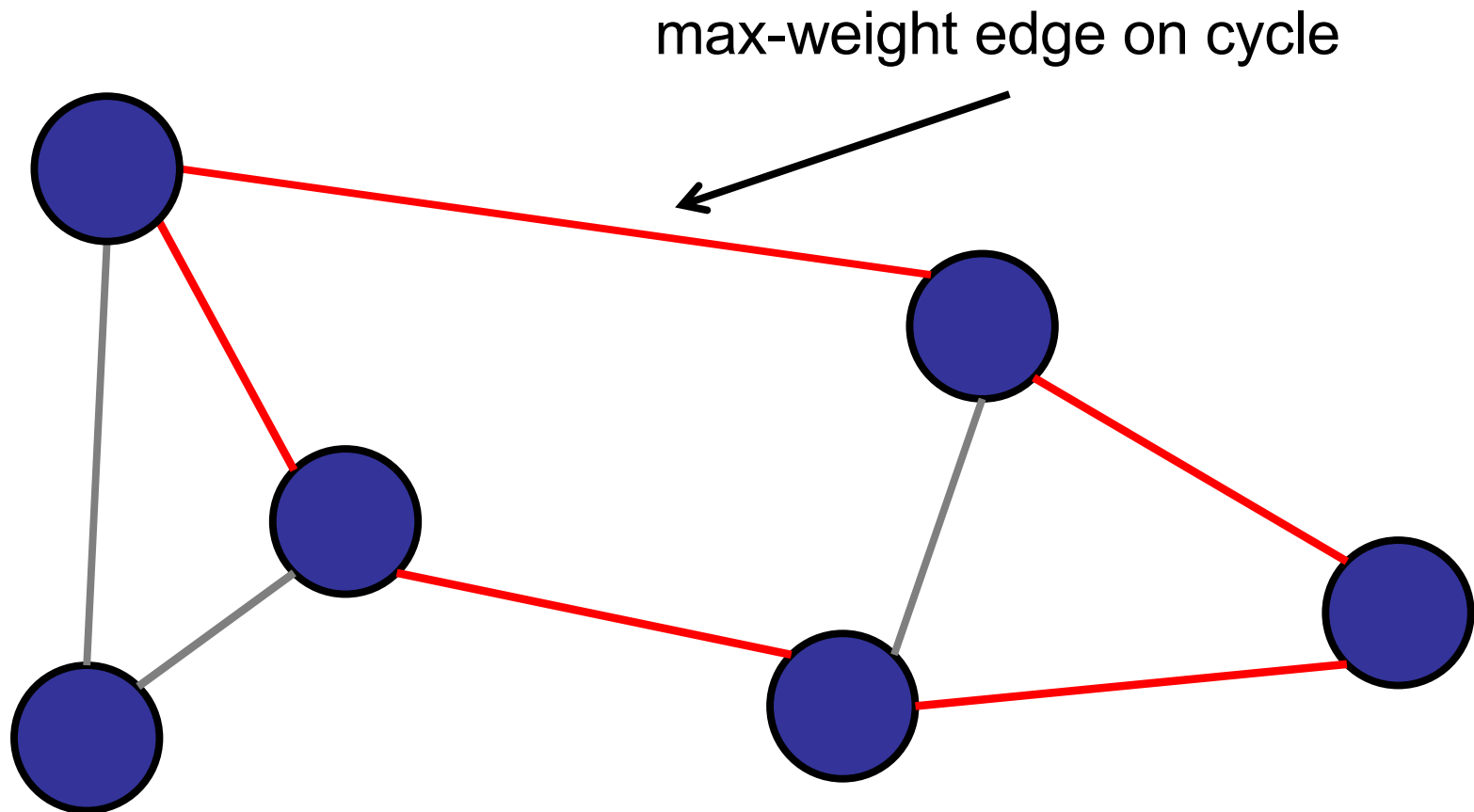


# Properties of MST

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## Property 3: Cycle property

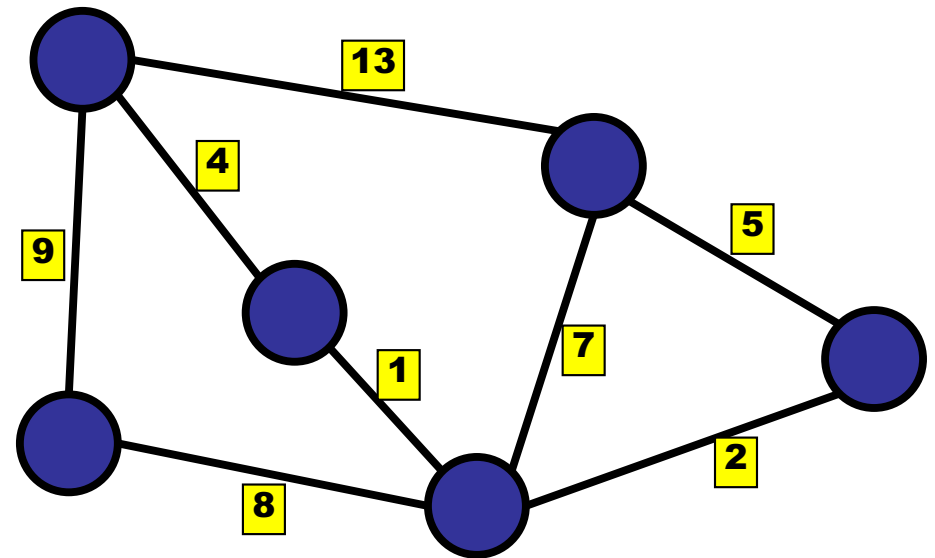
For every cycle, the maximum weight edge is **not** in the MST.



True or False:

For every cycle, the minimum weight edge is always in the MST.

1. True
- ✓ 2. False
3. I don't know.



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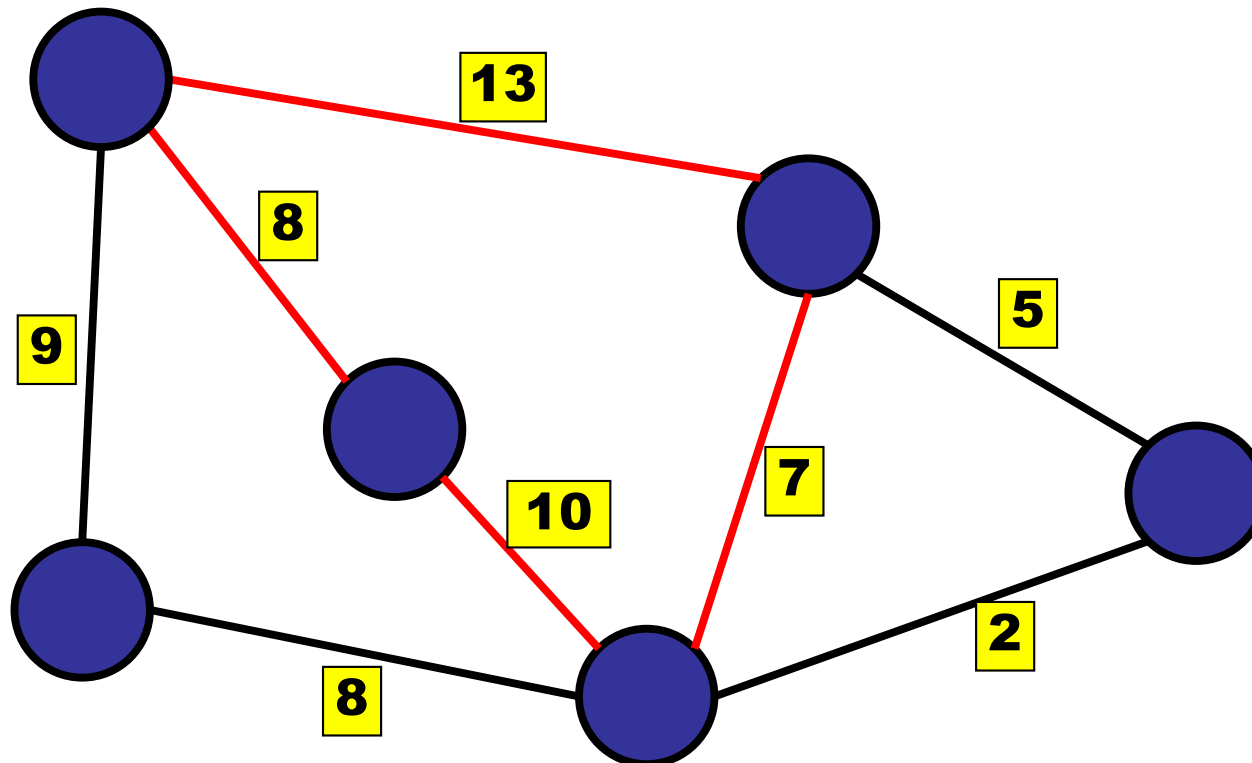
is open

# Properties of MST

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## Property 3: False Cycle property

For every cycle, the minimum weight edge may or may *not* be in the MST.

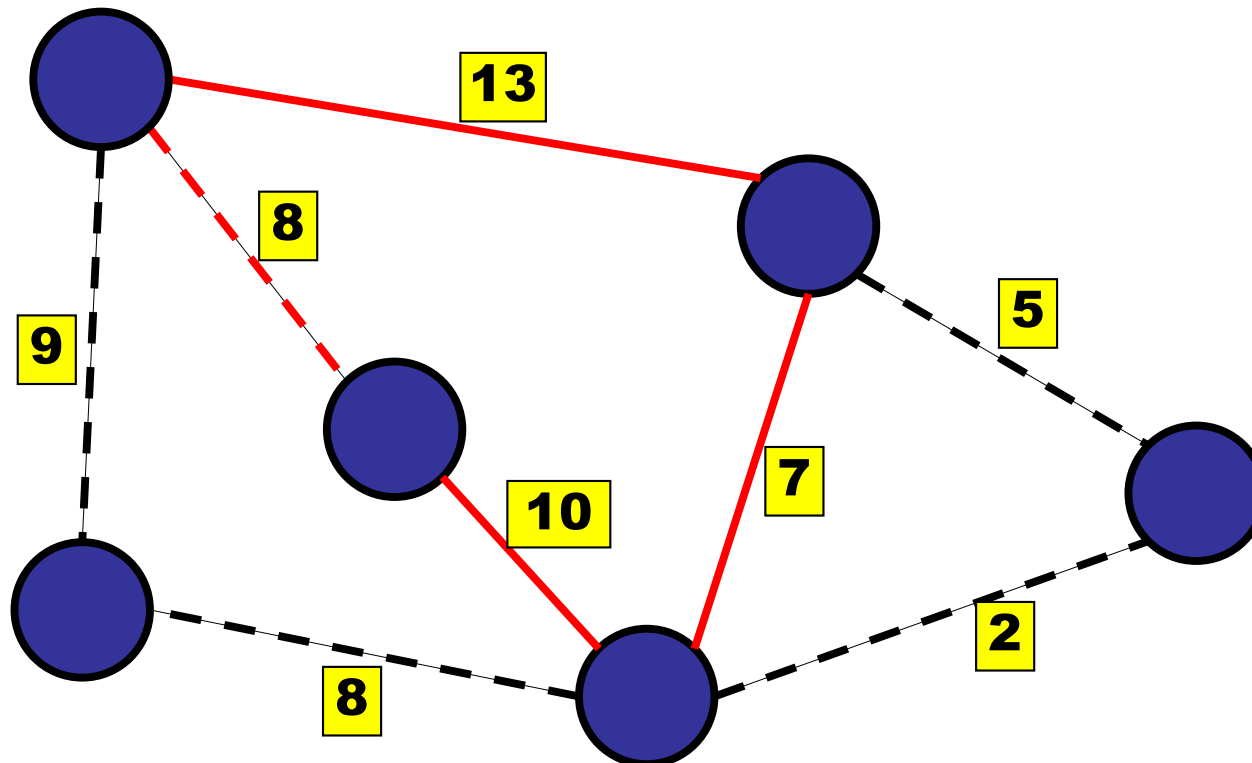


# Properties of MST

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## Property 3: False Cycle property

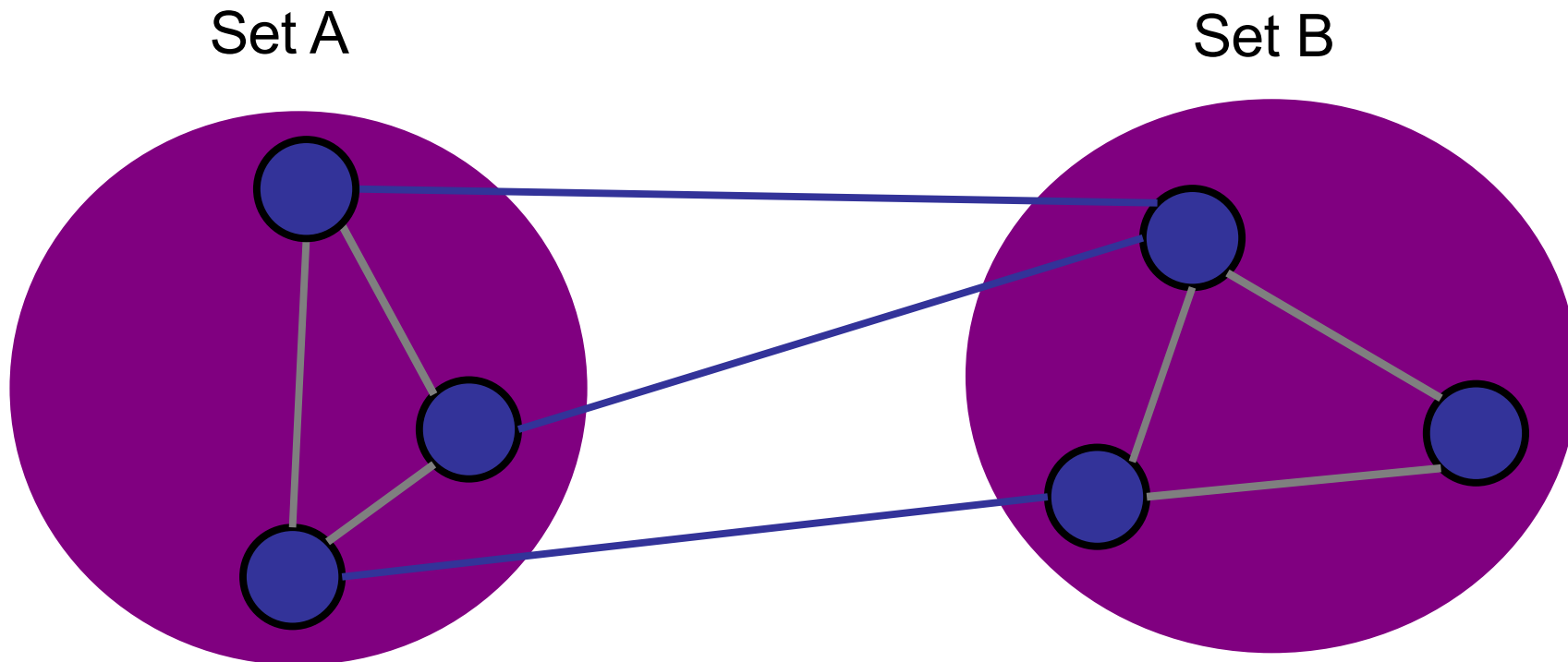
For every cycle, the minimum weight edge may or may *not* be in the MST.



# Properties of MST

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Definition: A *cut* of a graph  $G=(V,E)$  is a partition of the vertices  $V$  into two disjoint subsets.

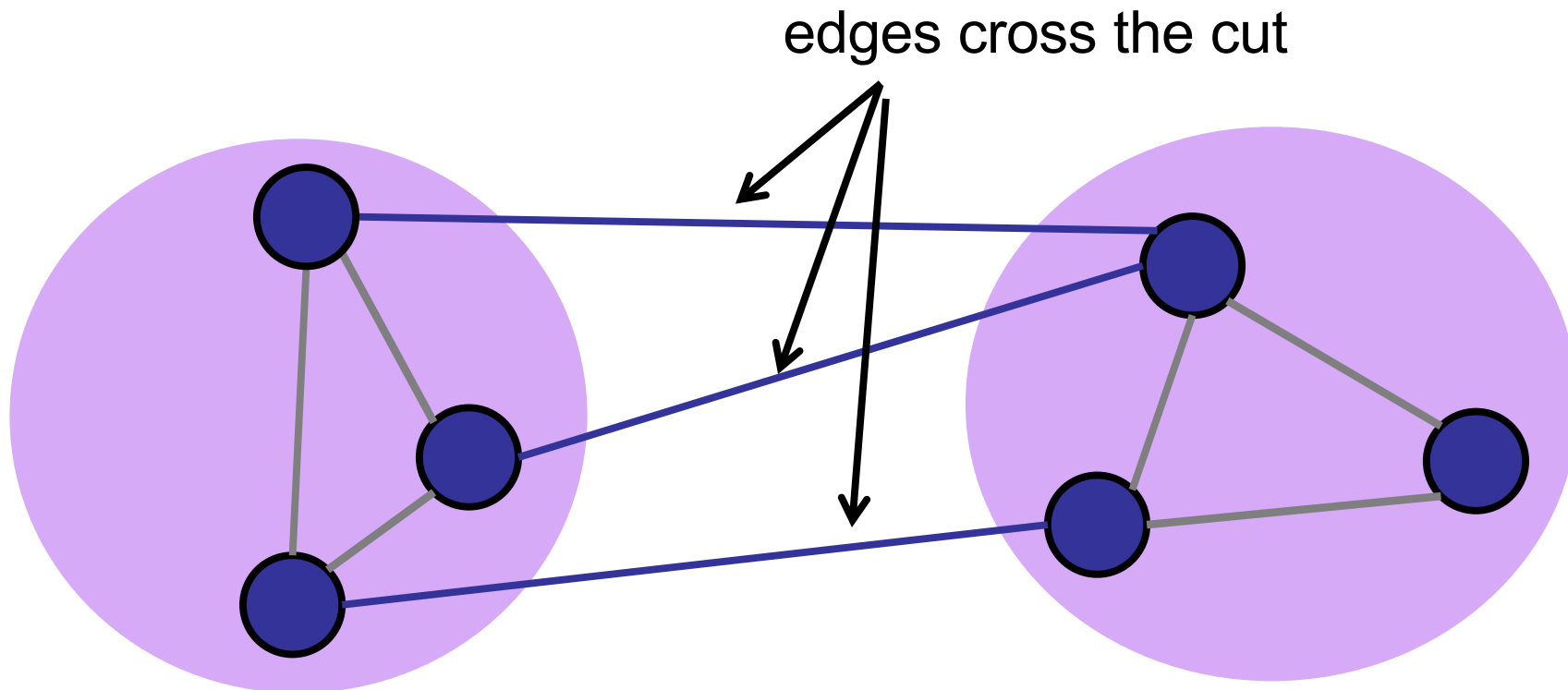




# Properties of MST

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Definition: An edge *crosses a cut* if it has one vertex in each of the two sets.

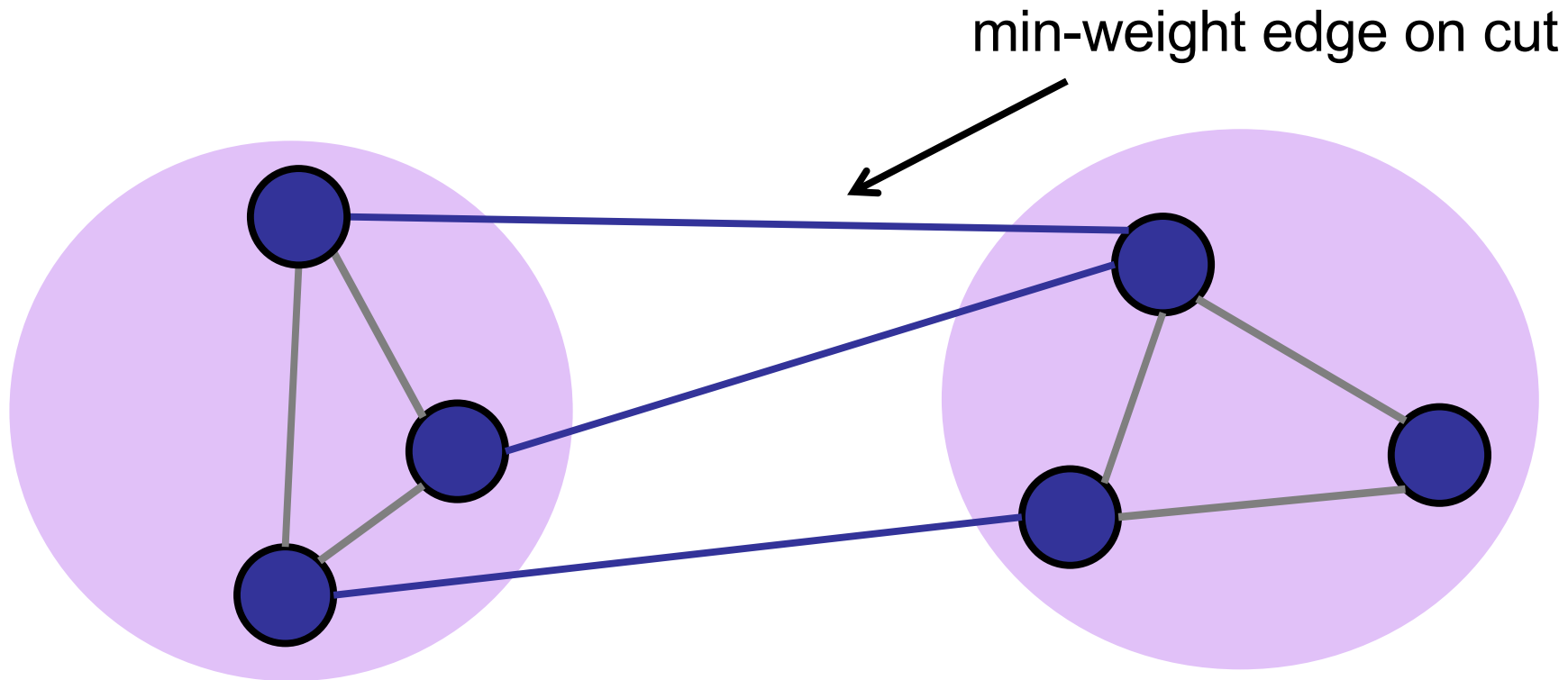


# Properties of MST

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## Property 4: Cut property

For every partition of the nodes, the minimum weight edge across the cut *is* in the MST.

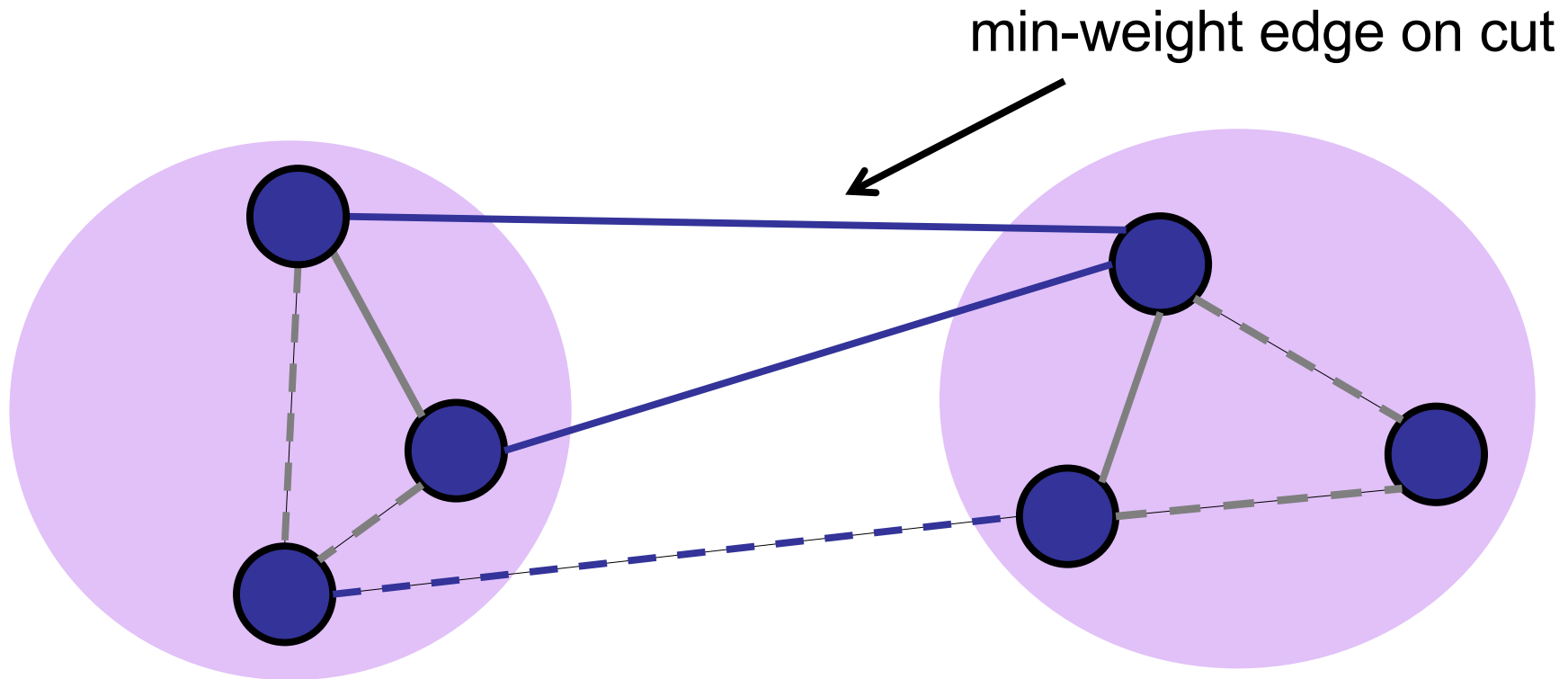


# Properties of MST

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Proof: Cut-and-paste

Assume not.



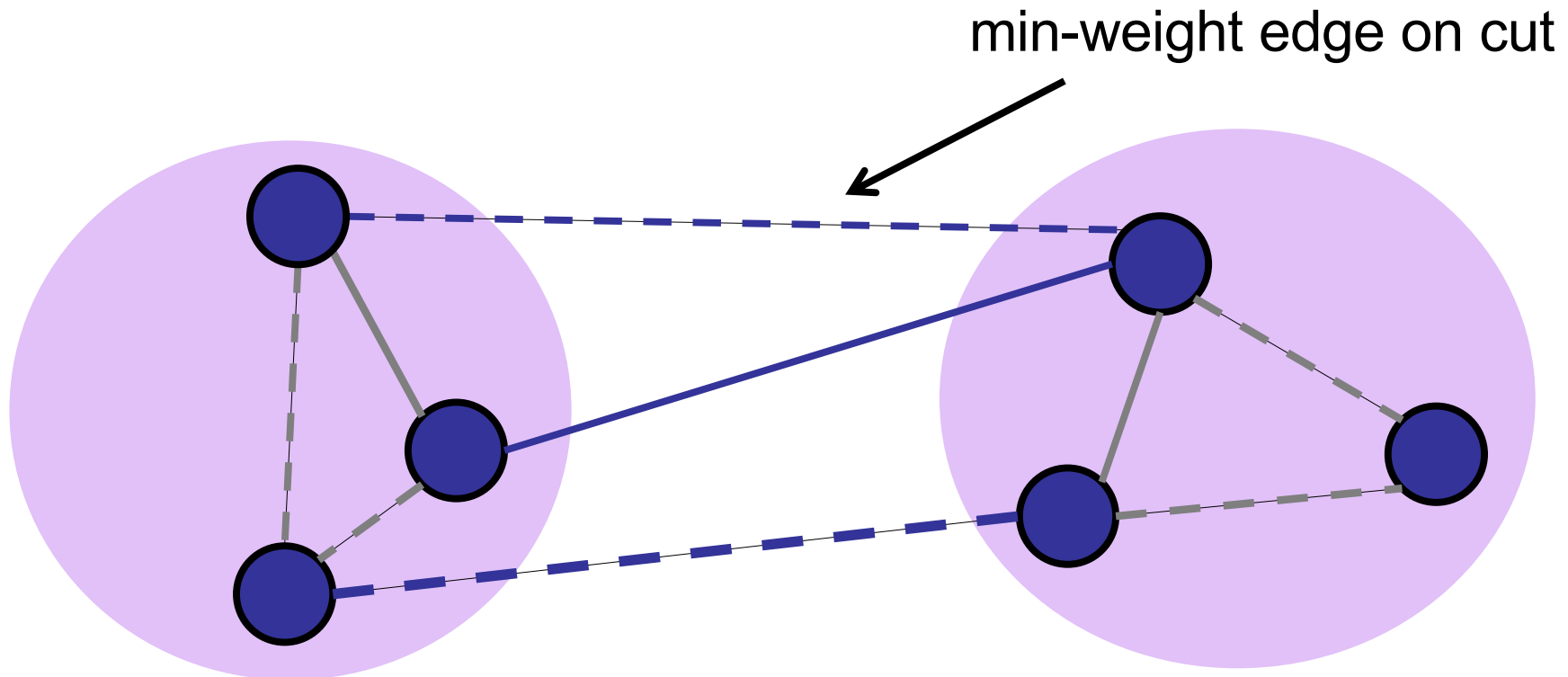
# Properties of MST

---

Proof: Cut-and-paste

Assume not.

Add min-weight edge on cut.



# Properties of MST

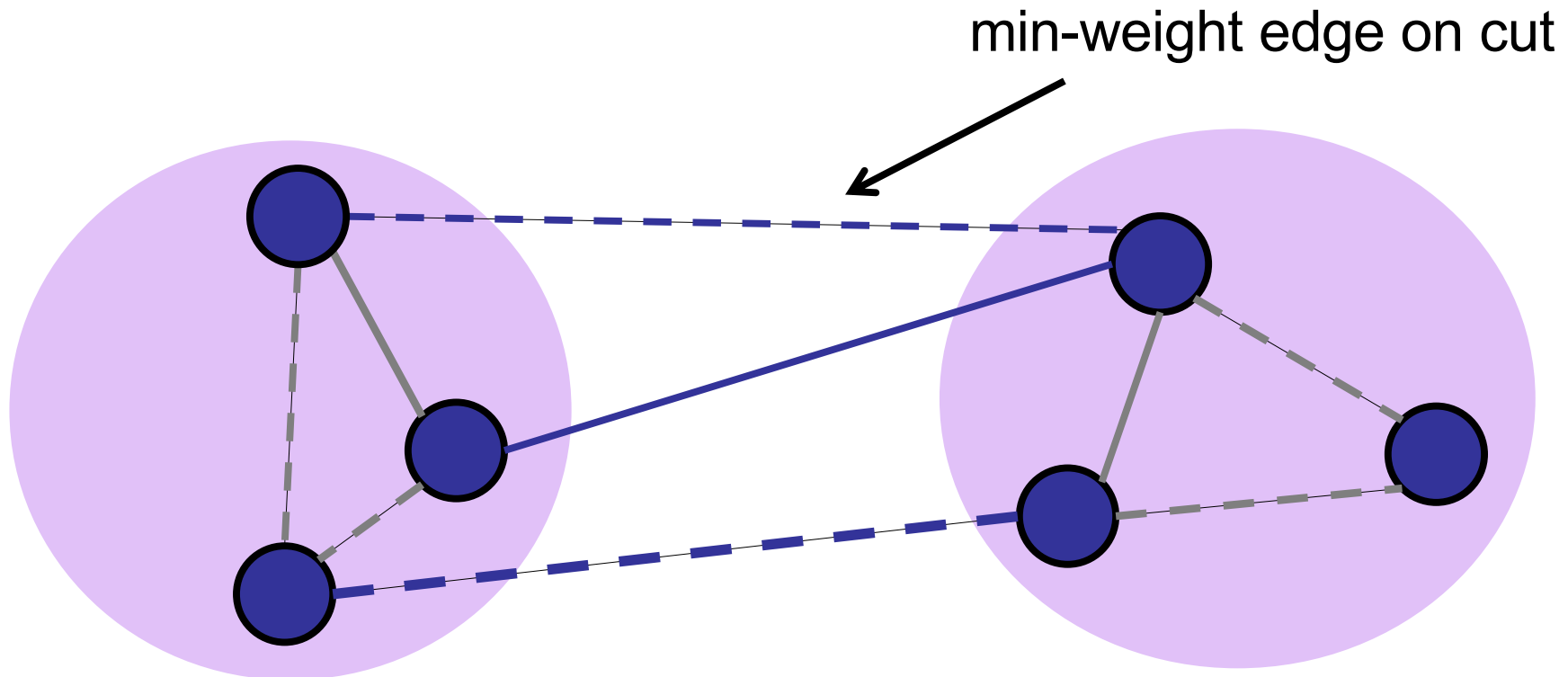
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Proof: Cut-and-paste

Assume not.

Add min-weight edge on cut.

Oops, creates a cycle!



# Properties of MST

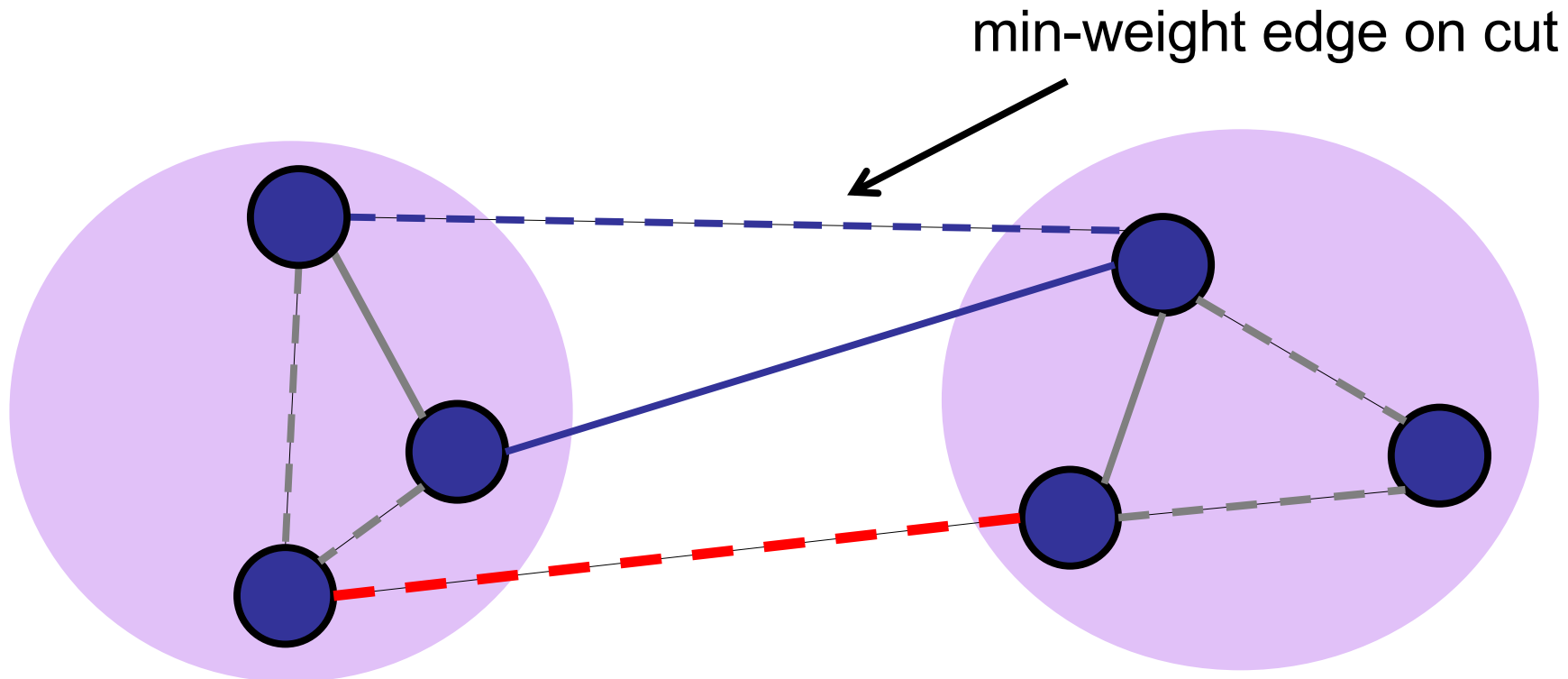
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Proof: Cut-and-paste

Assume not.

Add min-weight edge on cut.

Remove heaviest edge on cycle.



# Properties of MST

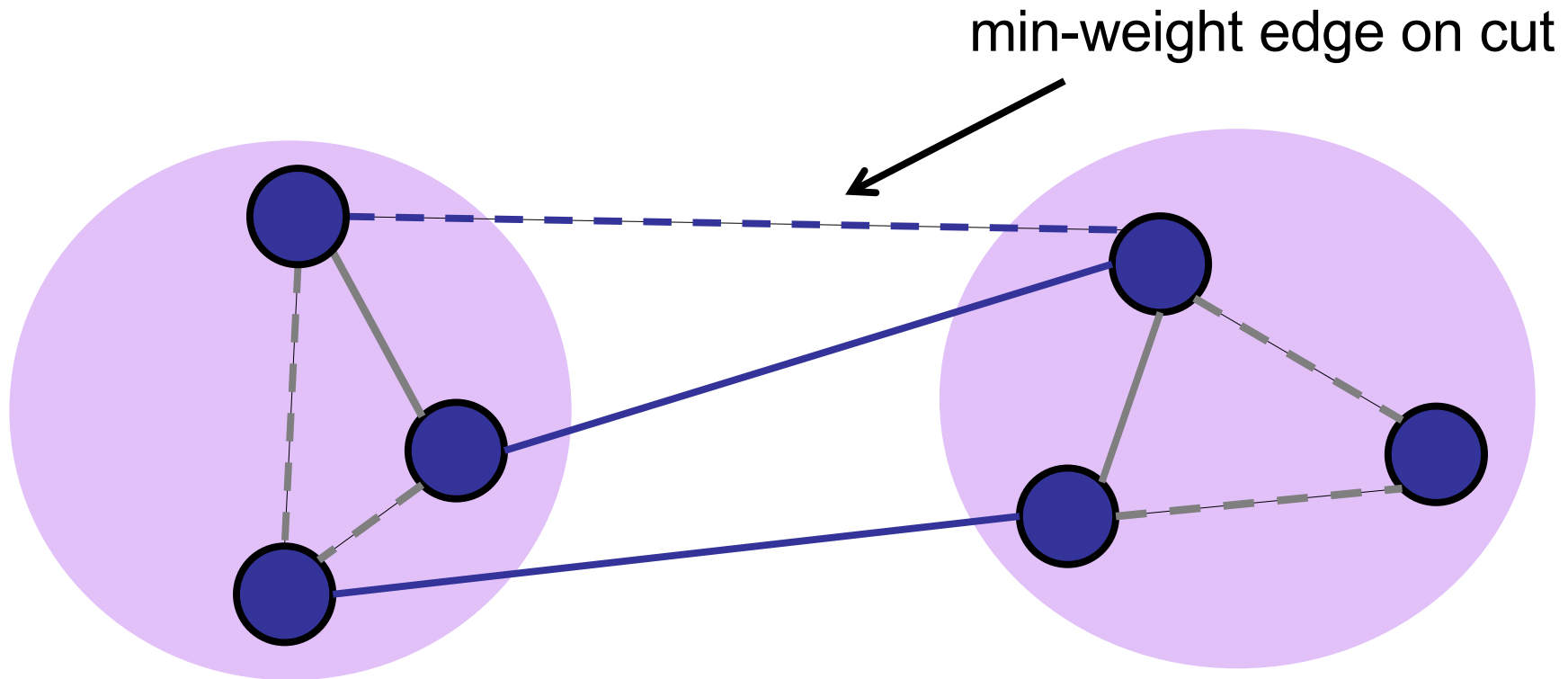
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Proof: Cut-and-paste

Assume not.

Add min-weight edge on cut.

Remove heaviest edge on cycle.

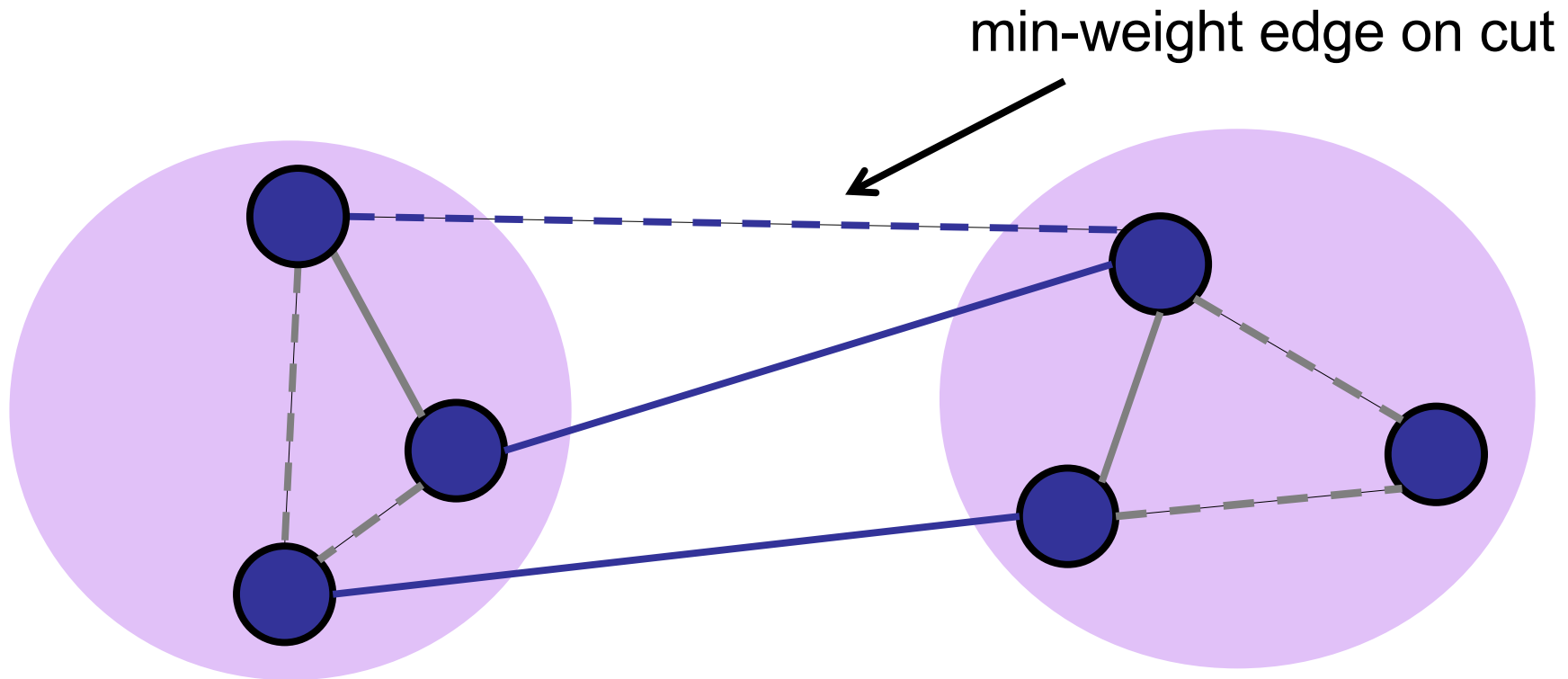


# Properties of MST

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Proof: Cut-and-paste

Result: a new spanning tree.



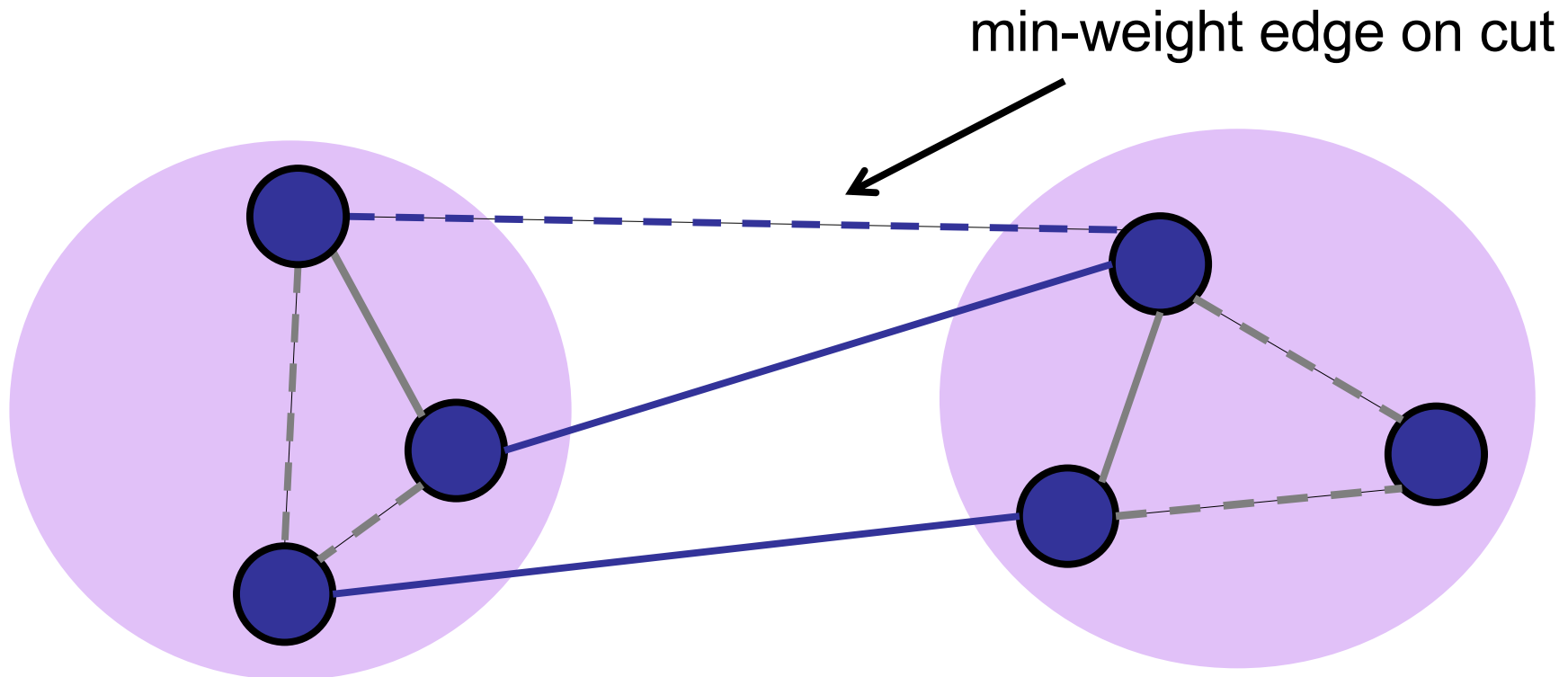


# Properties of MST

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Proof: Cut-and-paste

Less weight: replaced heavier edge with lighter edge.

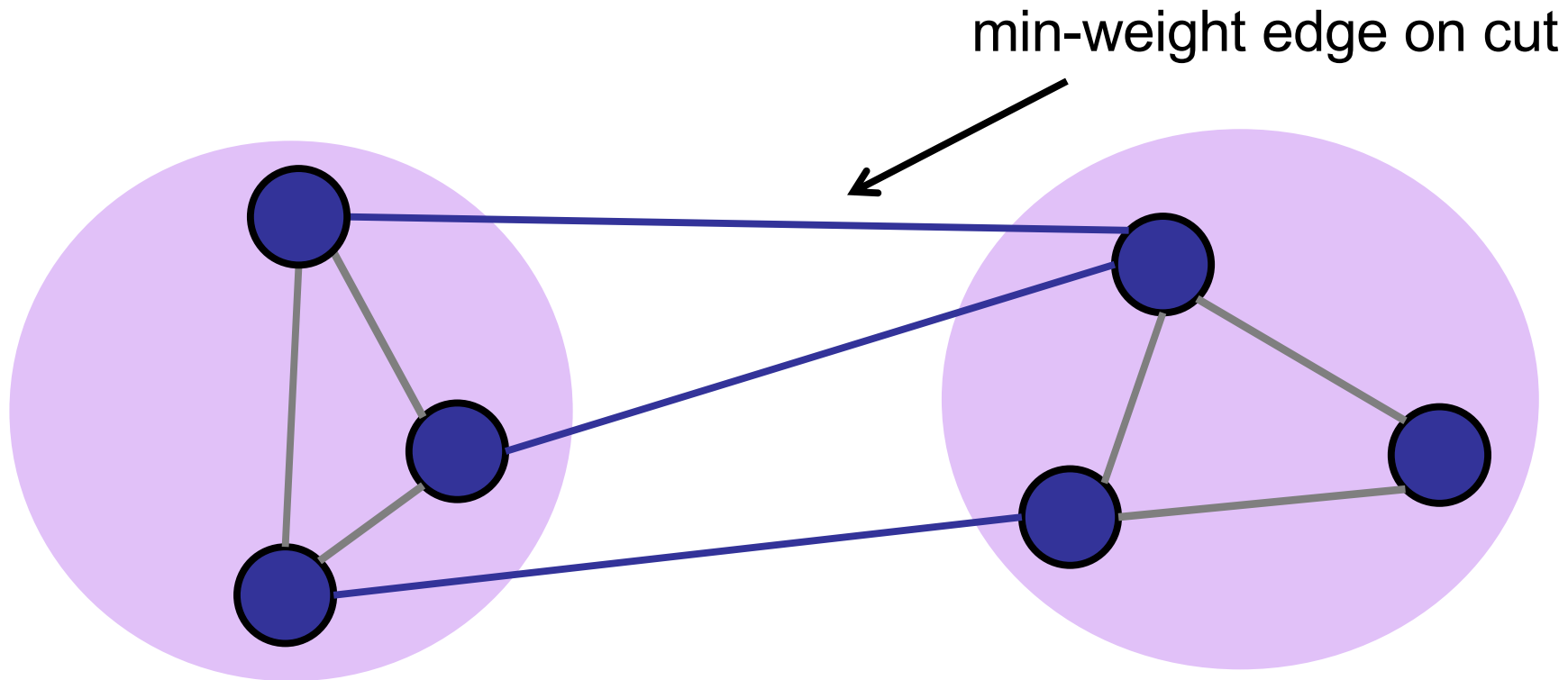


# Properties of MST

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## Property 4: Cut property

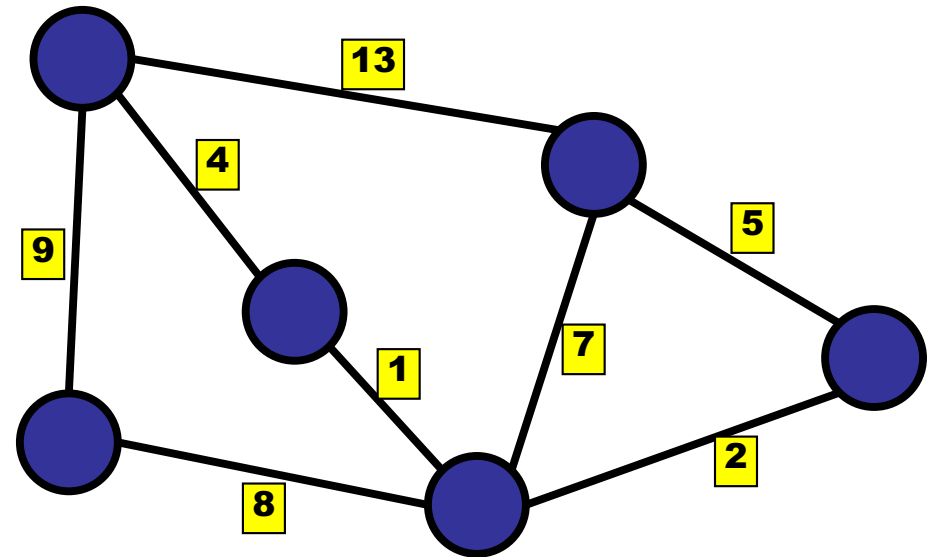
For every partition of the nodes, the minimum weight edge across the cut *is* in the MST.



True or False:

For every vertex, the minimum outgoing edge is always part of the MST.

- ✓ 1. True
- 2. False
- 3. I don't know.



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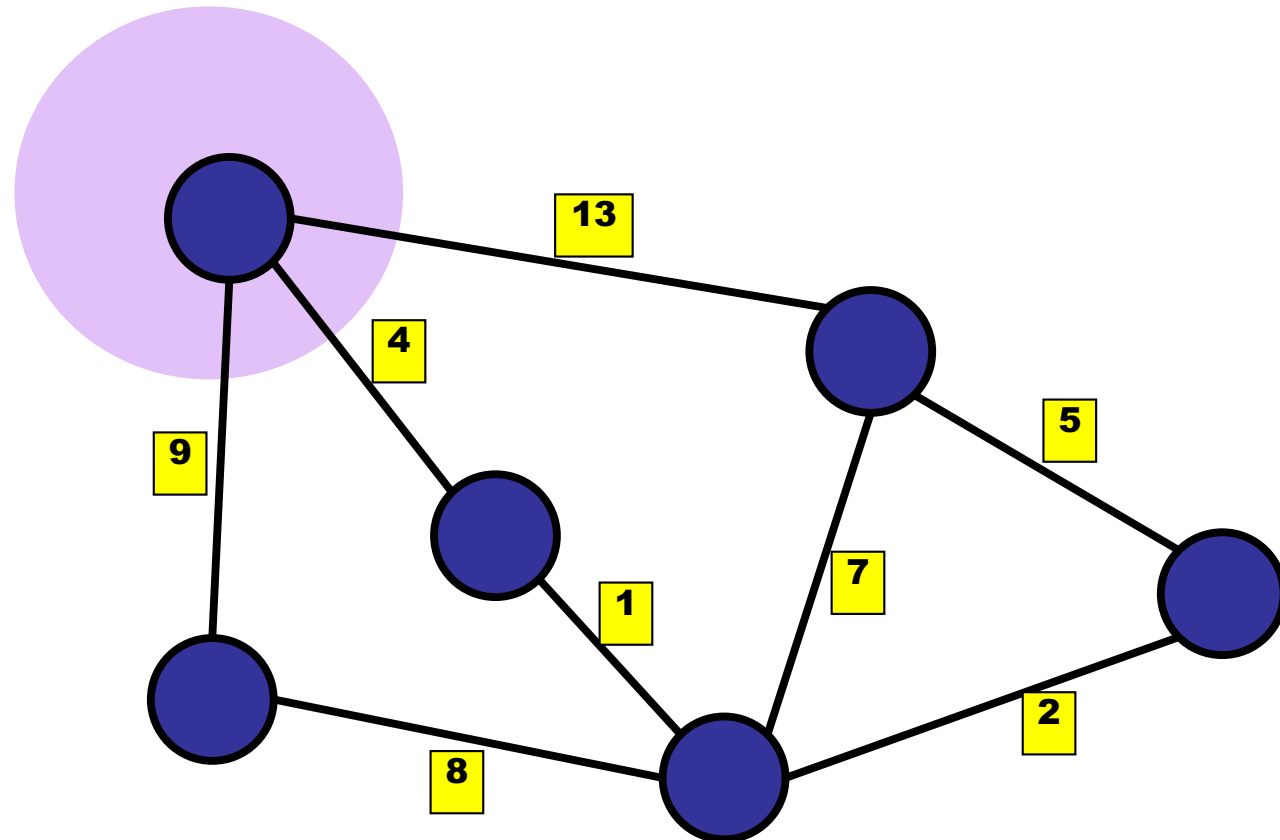
is open

# Properties of MST

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## Property 4: Cut property

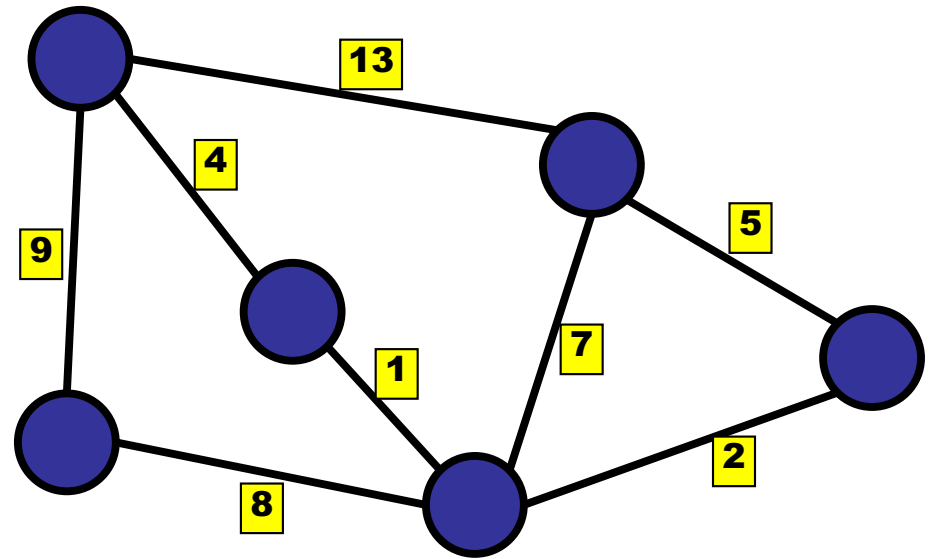
For every partition of the nodes, the minimum weight edge across the cut *is* in the MST.



True or False:

For every vertex, the maximum outgoing edge is never part of the MST.

1. True
- ✓ 2. False
3. I don't know.

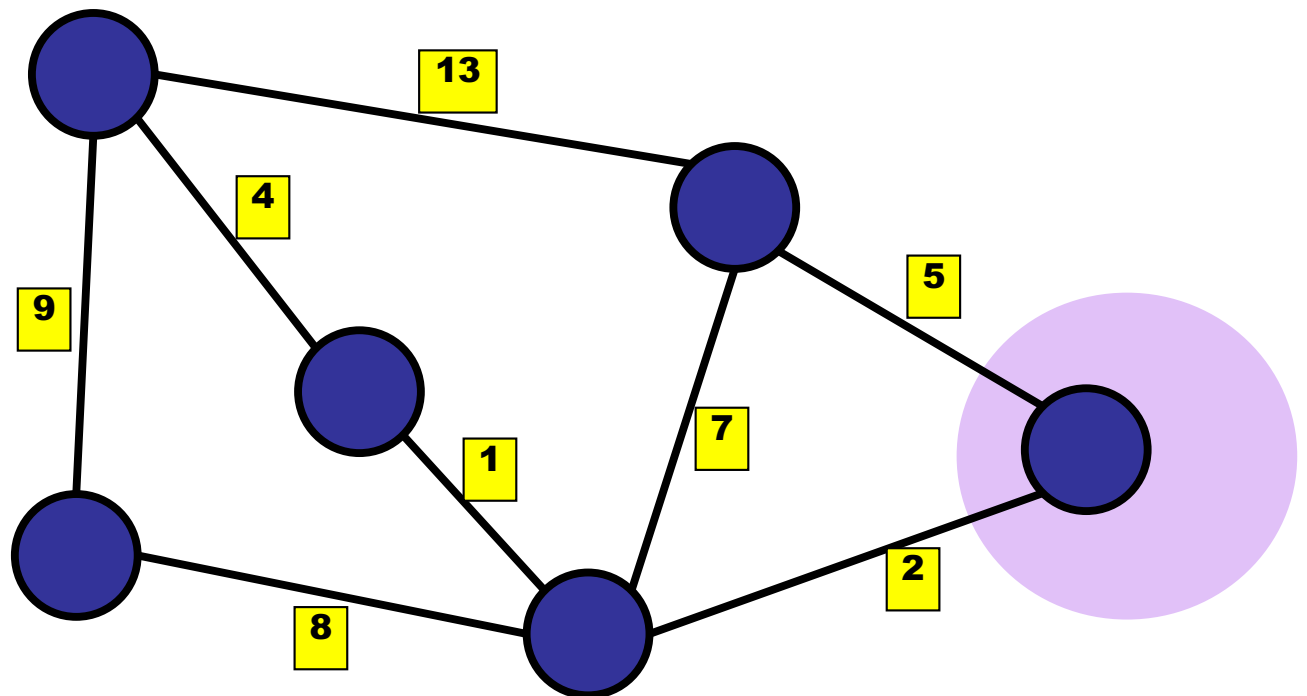


# Properties of MST

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## Property 4: Cut property

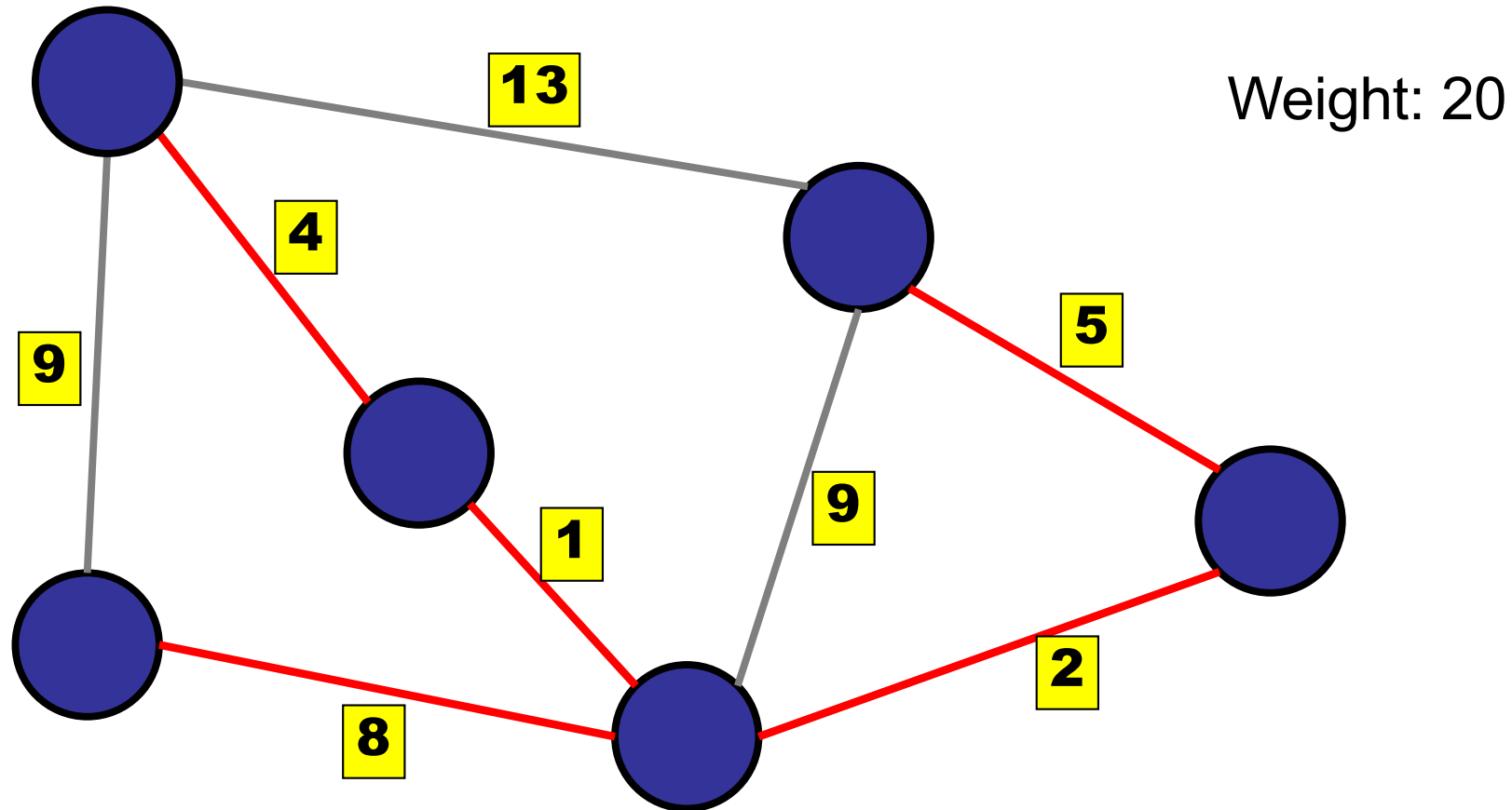
For every partition of the nodes, the minimum weight edge across the cut *is* in the MST.



# Minimum Spanning Tree

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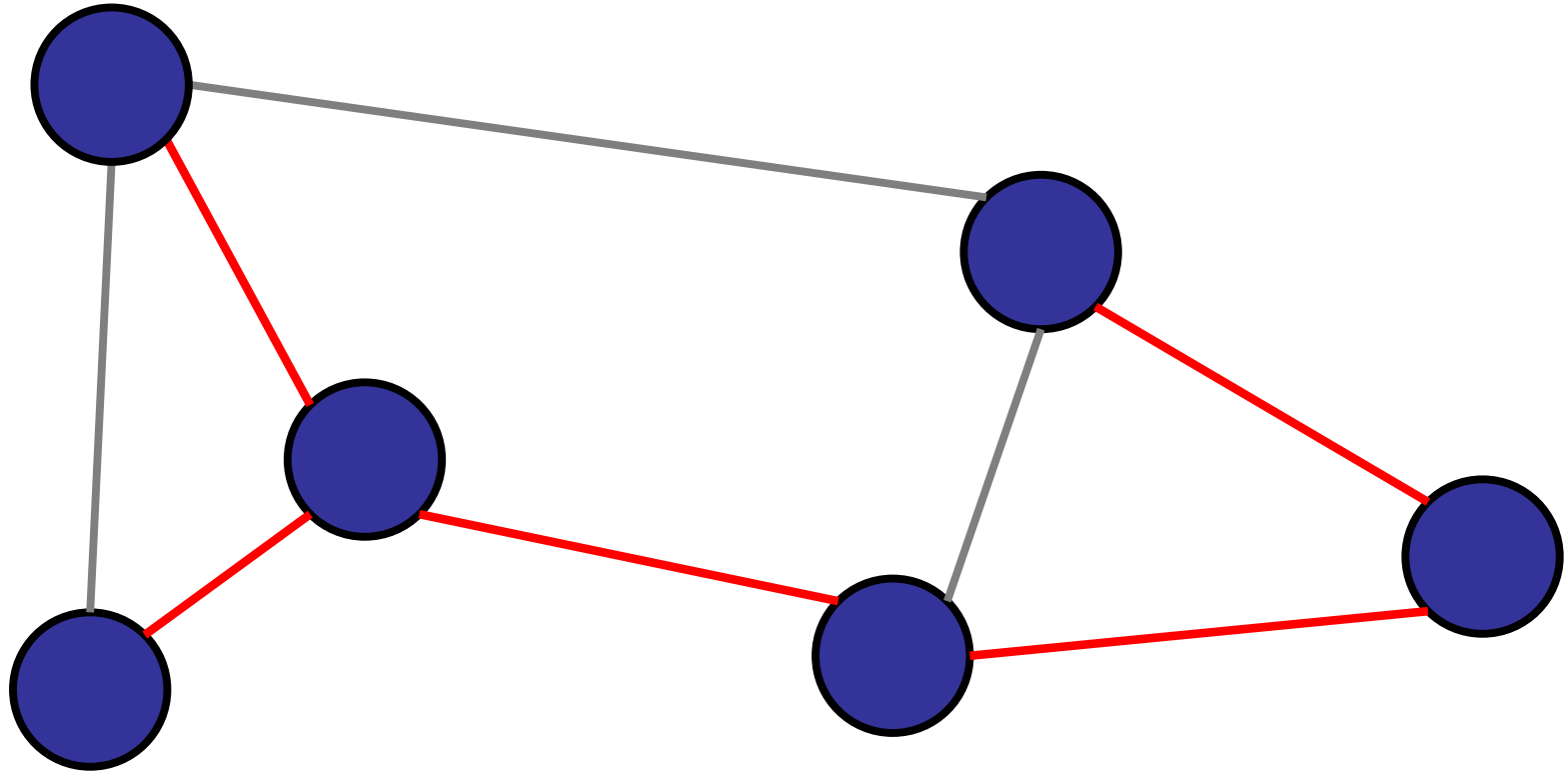
Definition: a spanning tree with minimum weight



# Properties of MST

---

Property 1: No cycles

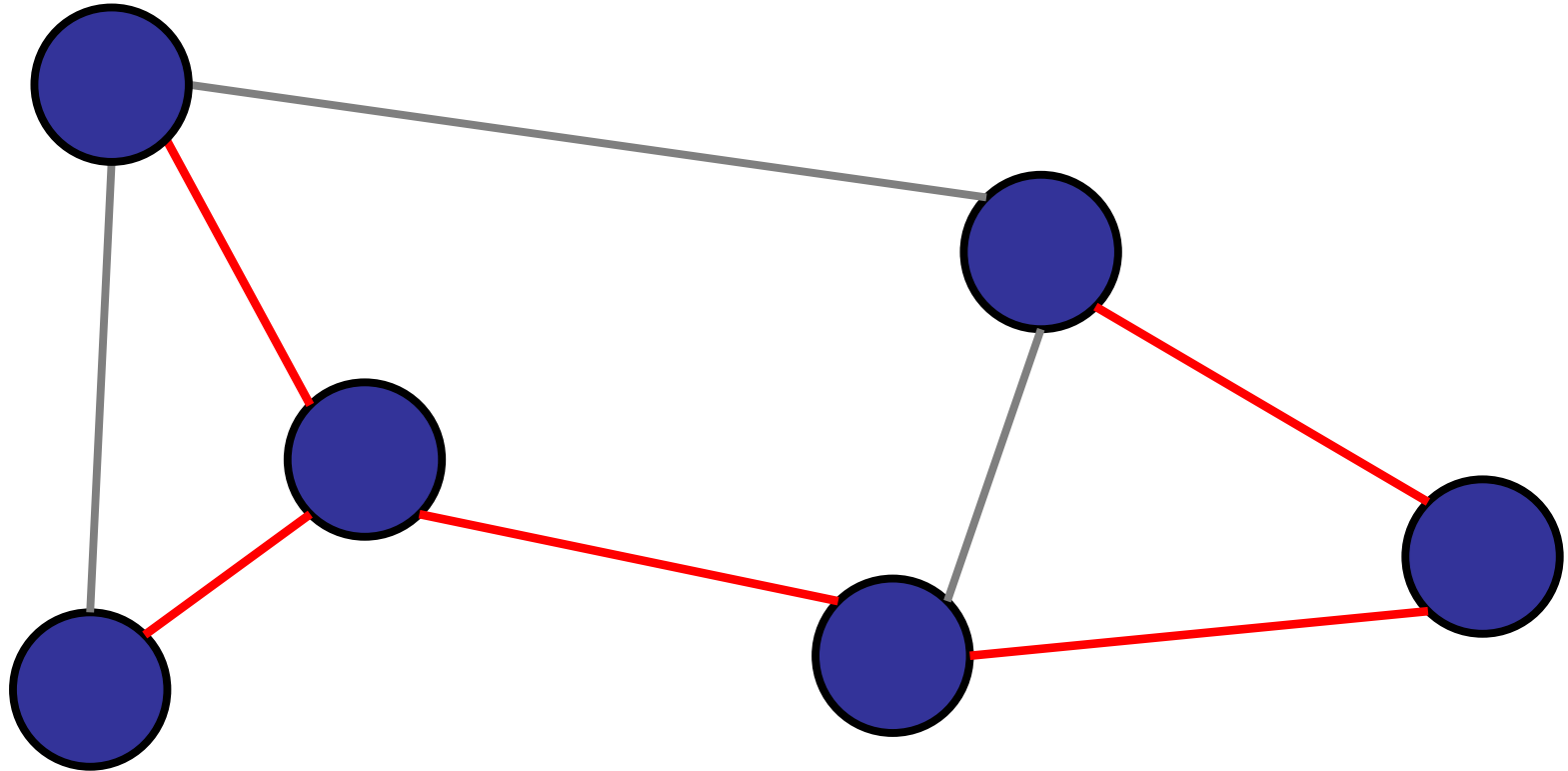




# Properties of MST

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Property 2: If you cut an MST, the two pieces are both MSTs.

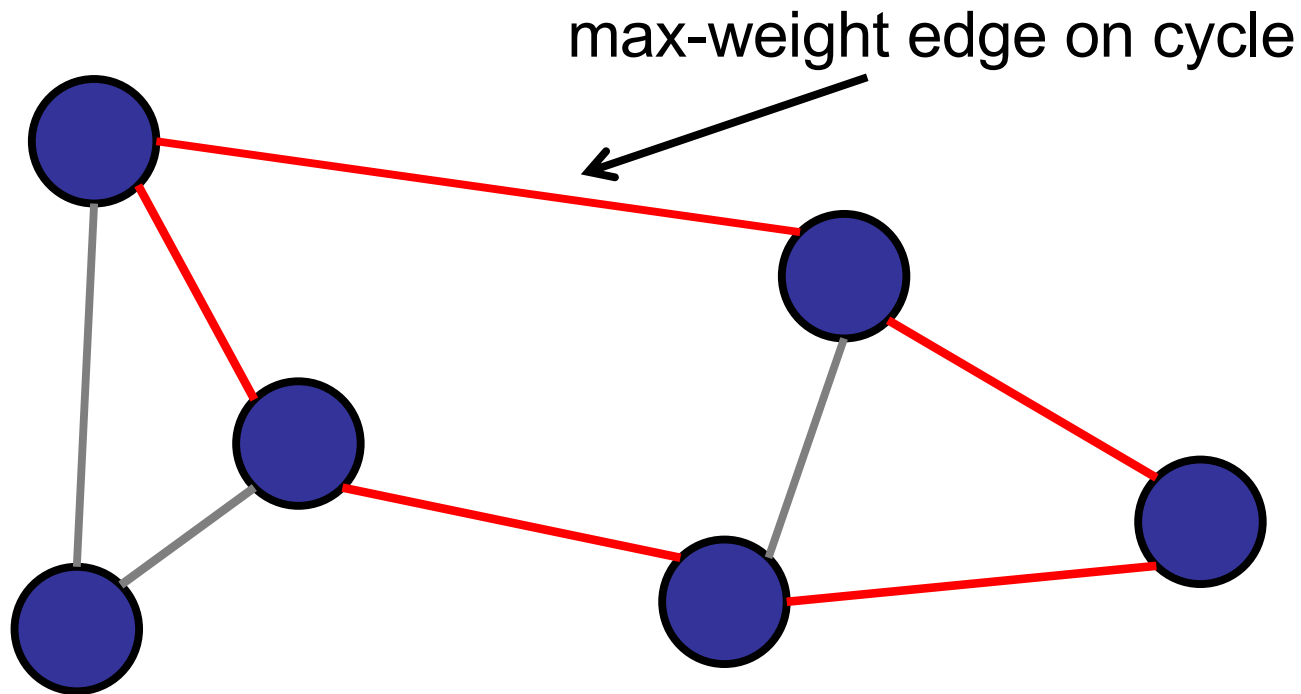


# Properties of MST

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## Property 3: Cycle property

For every cycle, the maximum weight edge is *not* in the MST.

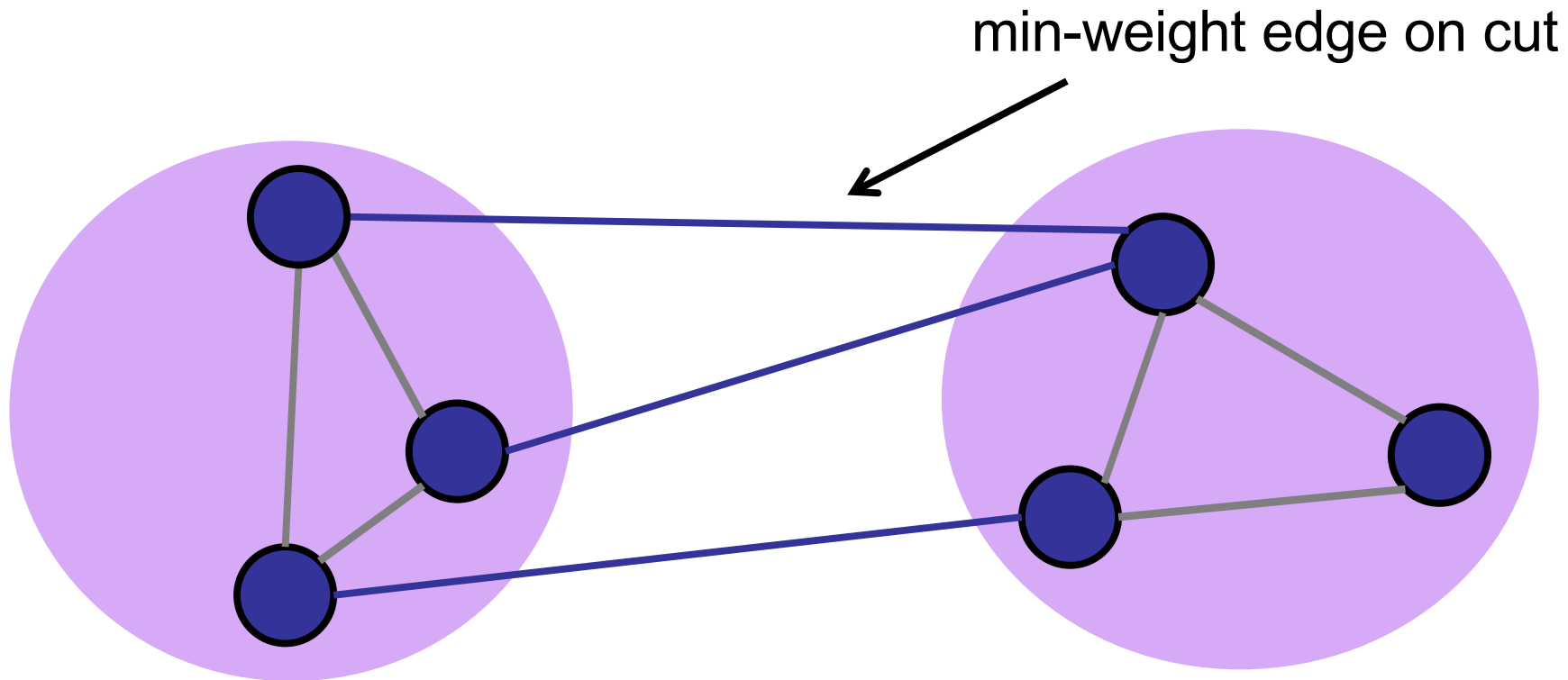


# Properties of MST

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## Property 4: Cut property

For every cut  $D$ , the minimum weight edge that crosses the cut *is* in the MST.



# Property of MST

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- No cycles
- If you cut an MST, the two pieces are both MSTs.
- Cycle property
  - For every cycle, the maximum weight edge is not in the MST.
- Cut property
  - For every cut  $D$ , the minimum weight edge that crosses the cut is in the MST.

# Roadmap

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## Minimum Spanning Trees

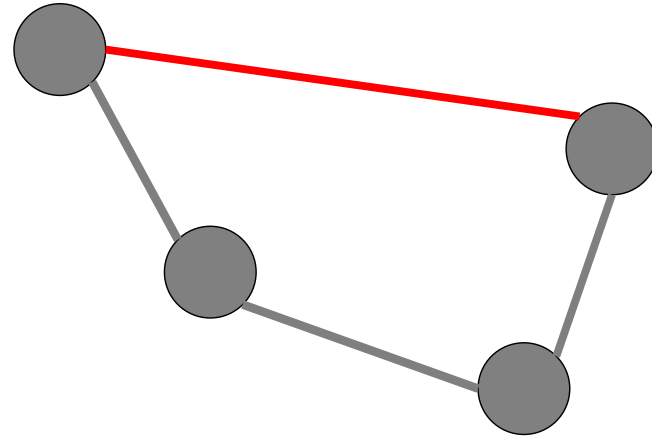
- The MST Problem
- Basic Properties of an MST
- **Generic MST Algorithm**
- Prim's Algorithm
- Kruskal's Algorithm
- Boruvka's Algorithm
- Variations

# Generic MST Algorithm

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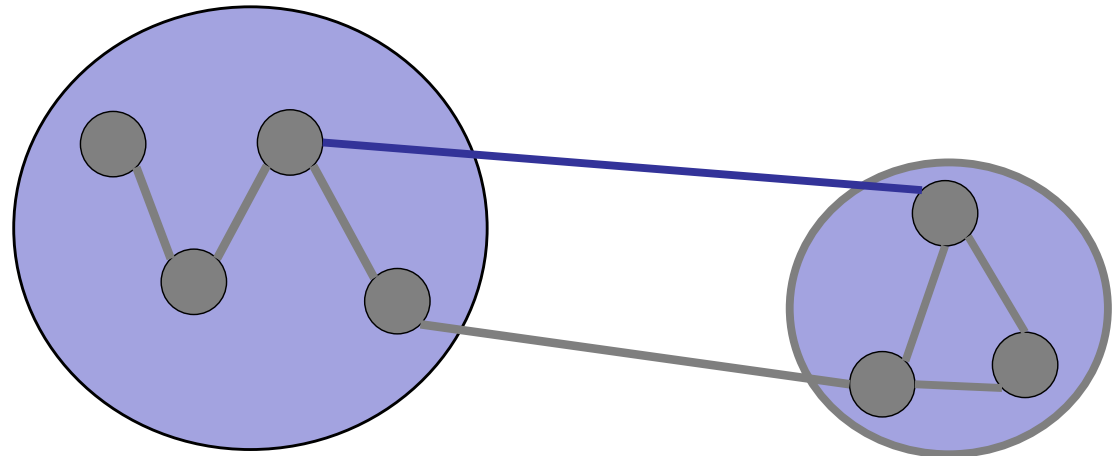
## Red rule:

If  $C$  is a cycle with no red arcs, then color the max-weight edge in  $C$  red.



## Blue rule:

If  $D$  is a cut with no blue arcs, then color the min-weight edge in  $D$  blue.



# Generic MST Algorithm

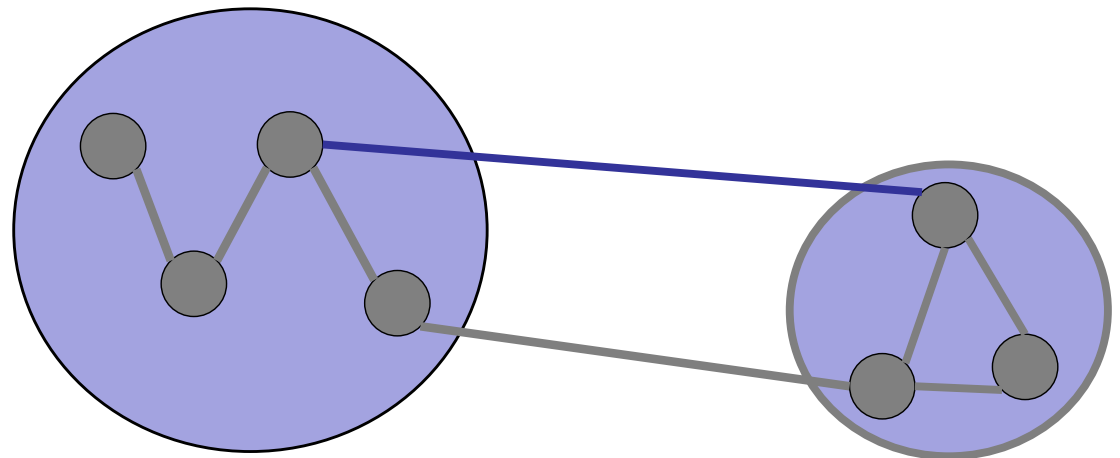
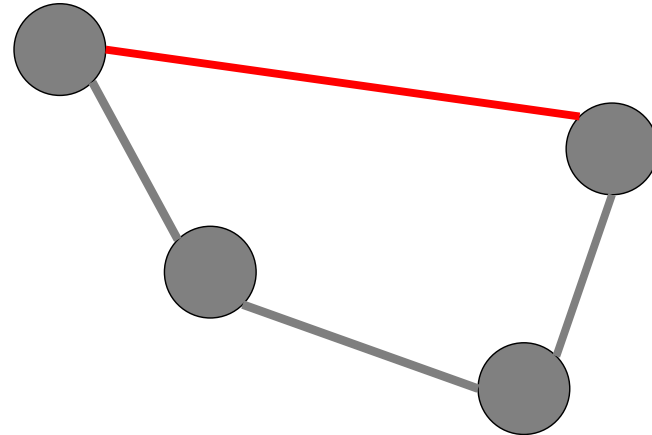
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## Greedy Algorithm:

Repeat:

**Apply red rule or  
blue rule to an  
arbitrary edge.**

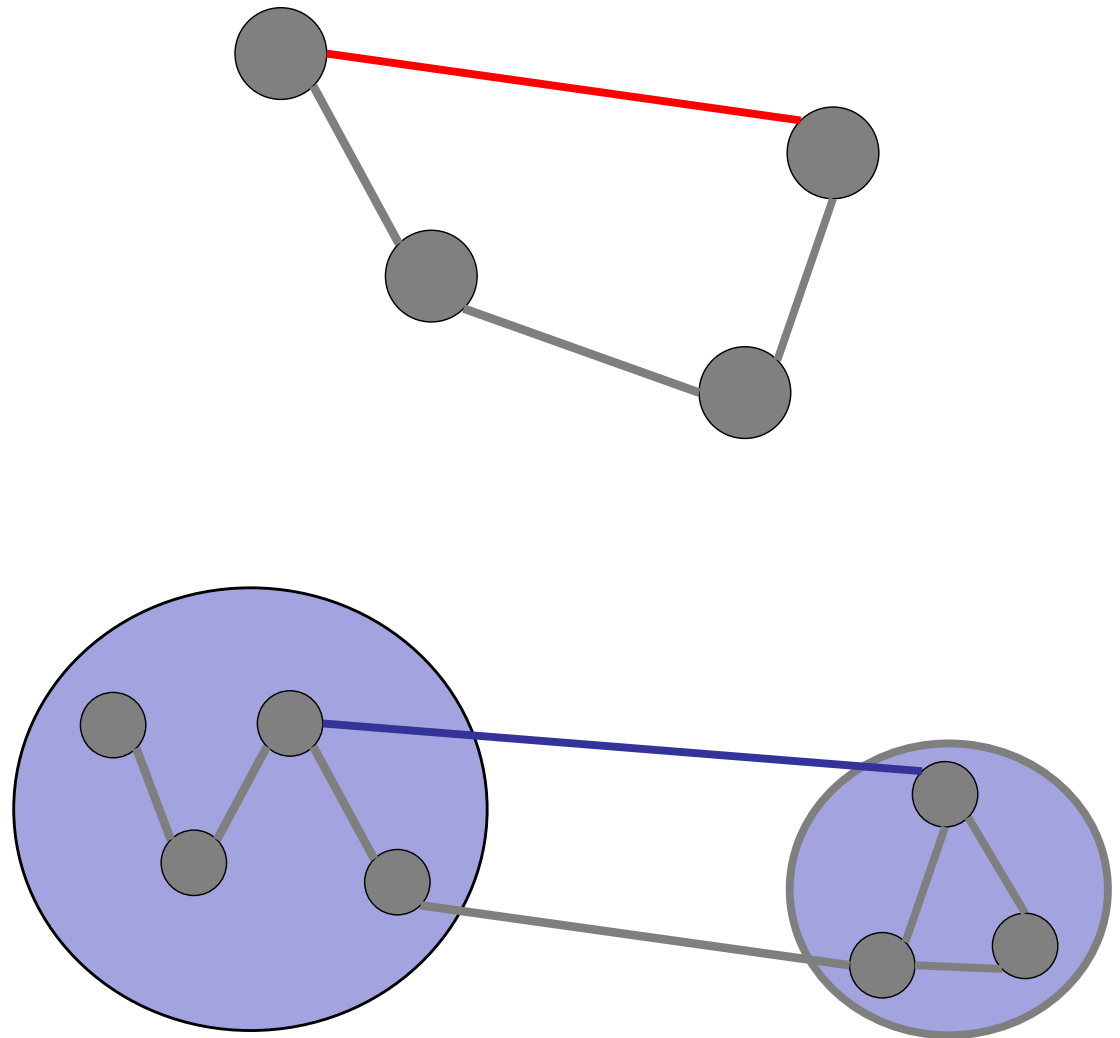
until no more edges  
can be colored.



# Generic MST Algorithm

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**Claim:** On termination, the blue edges are an MST.





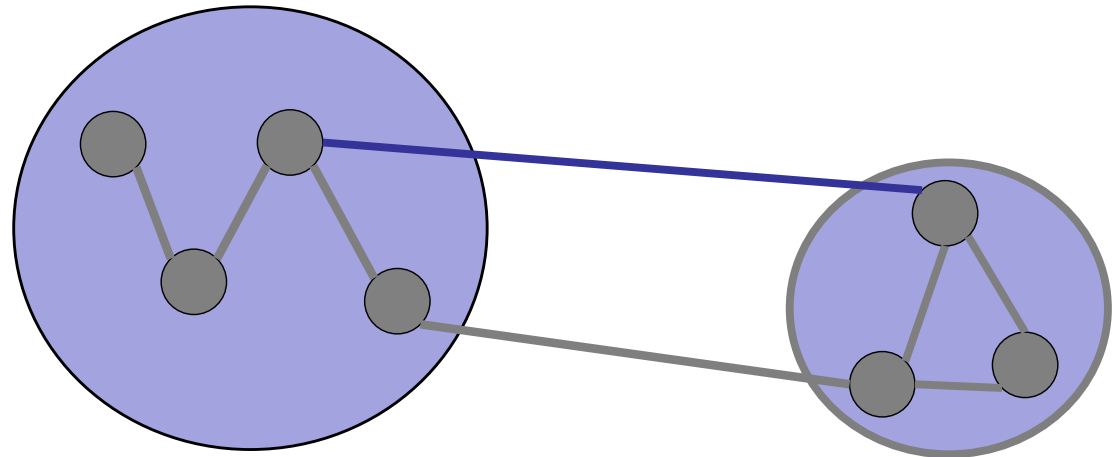
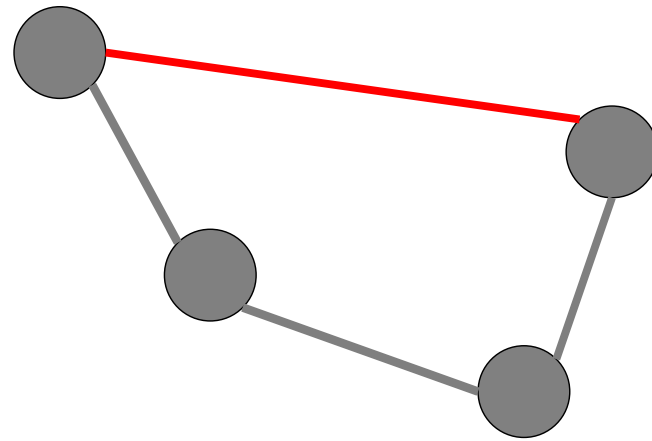
# Generic MST Algorithm

---

**Claim:** On termination, the blue edges are an MST.

On termination:

1. Every cycle has a **red** edge.  
No **blue** cycles  $\rightarrow$  forest.



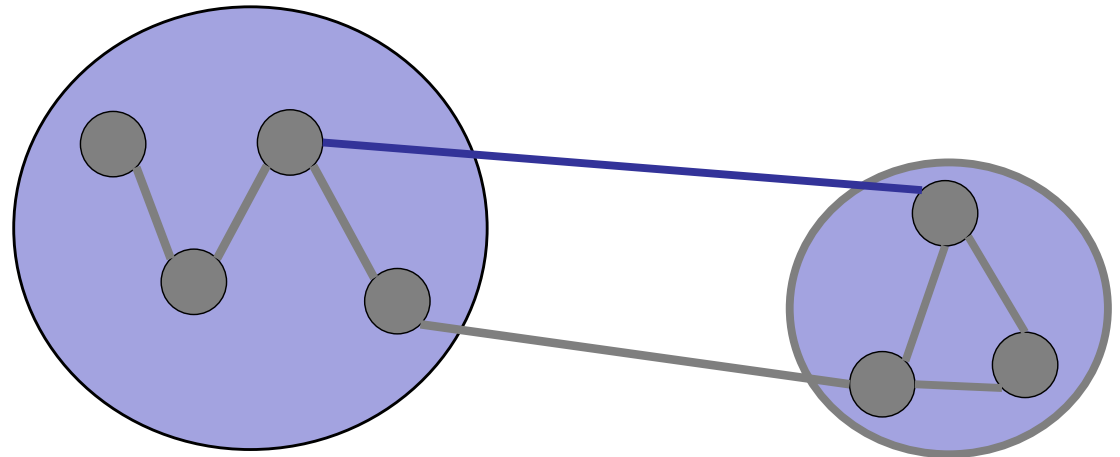
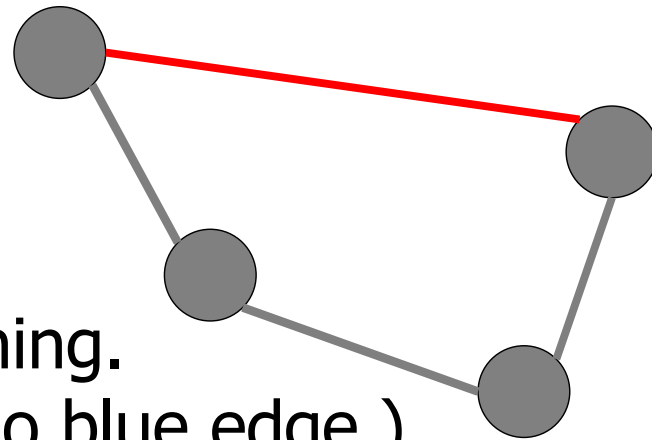
# Generic MST Algorithm

---

**Claim:** On termination, the blue edges are an MST.

On termination:

1. Every cycle has a **red** edge.  
No **blue** cycles  $\rightarrow$  forest.
2. **Blue** edges form a tree  $\rightarrow$  spanning.  
(Otherwise, there is a cut with no blue edge.)



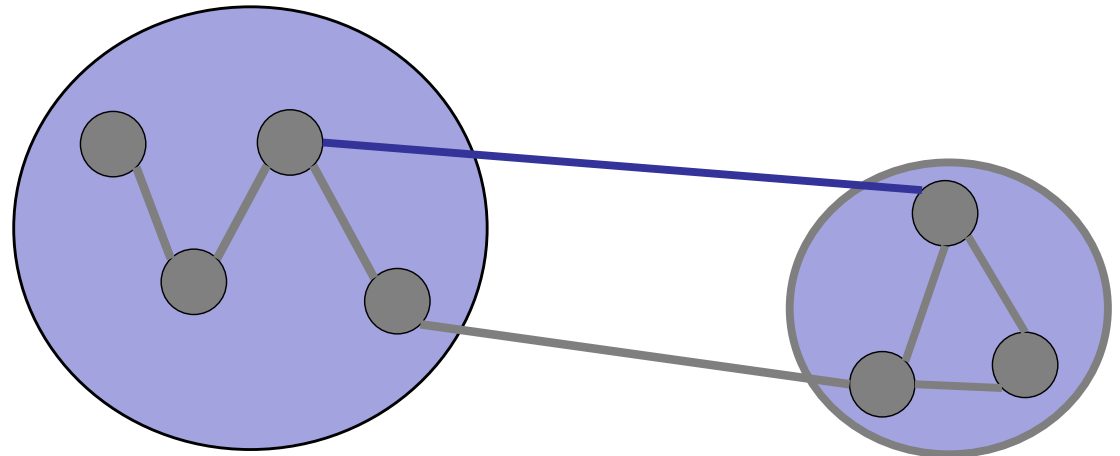
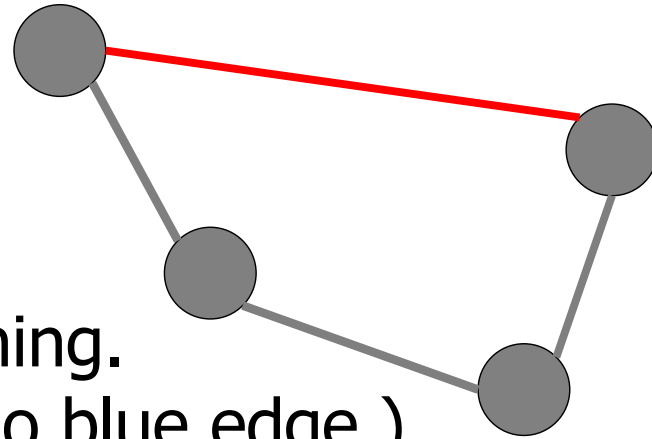
# Generic MST Algorithm

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**Claim:** On termination, the blue edges are an MST.

On termination:

1. Every cycle has a **red** edge.  
No **blue** cycles  $\rightarrow$  forest.
2. **Blue** edges form a tree  $\rightarrow$  spanning.  
(Otherwise, there is a cut with no blue edge.)
3. Every edge is colored.



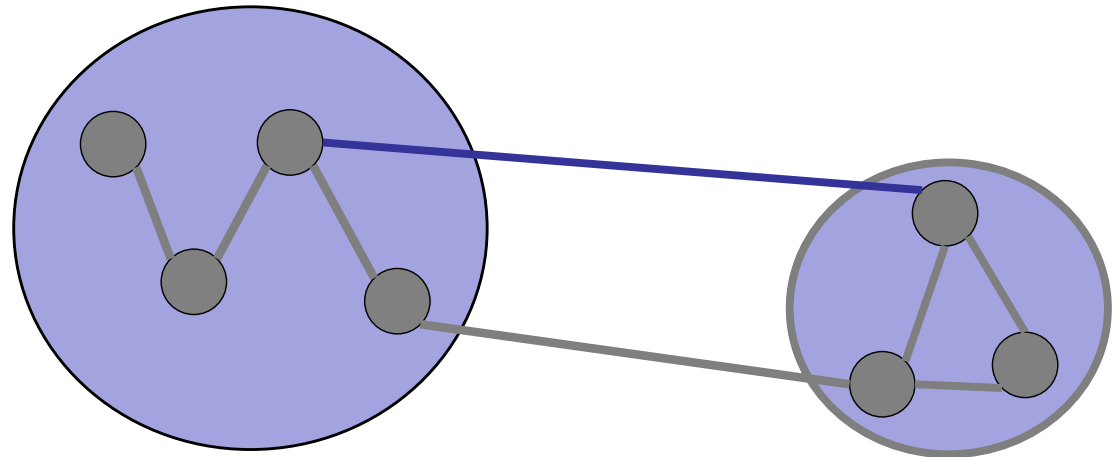
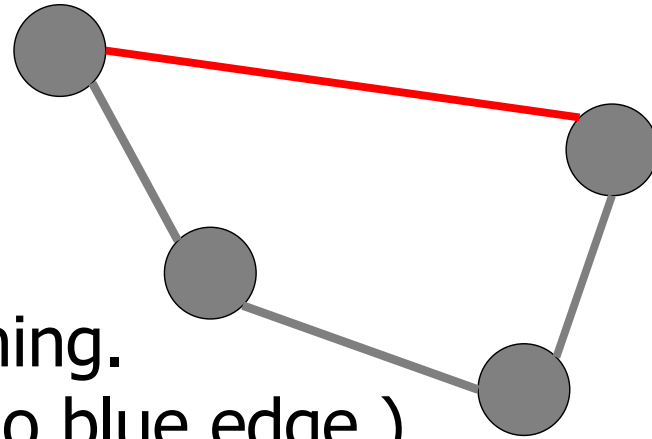
# Generic MST Algorithm

---

**Claim:** On termination, the blue edges are an MST.

On termination:

1. Every cycle has a **red** edge.  
No **blue** cycles  $\rightarrow$  forest.
2. **Blue** edges form a tree  $\rightarrow$  spanning.  
(Otherwise, there is a cut with no blue edge.)
3. Every edge is colored.
4. Every **blue edge** is in the MST (Property 4).



# Generic MST Algorithm

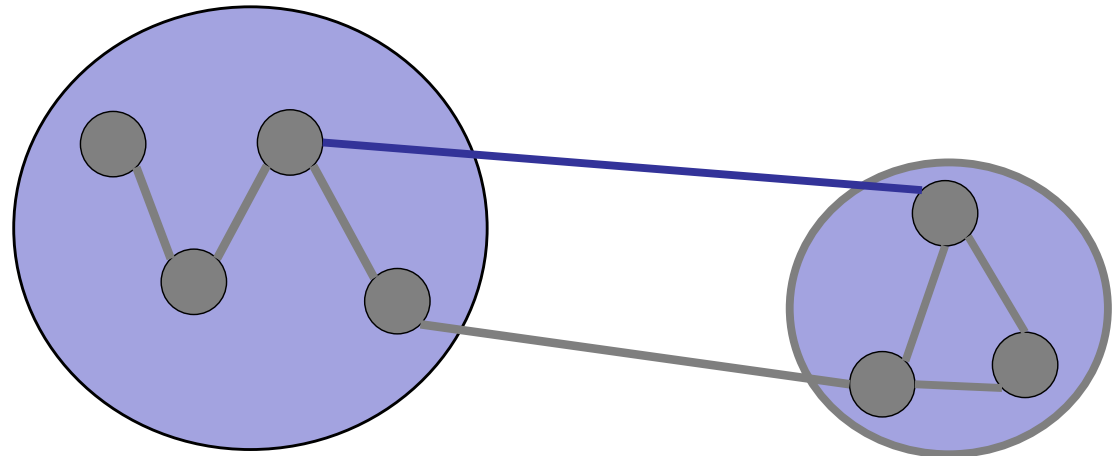
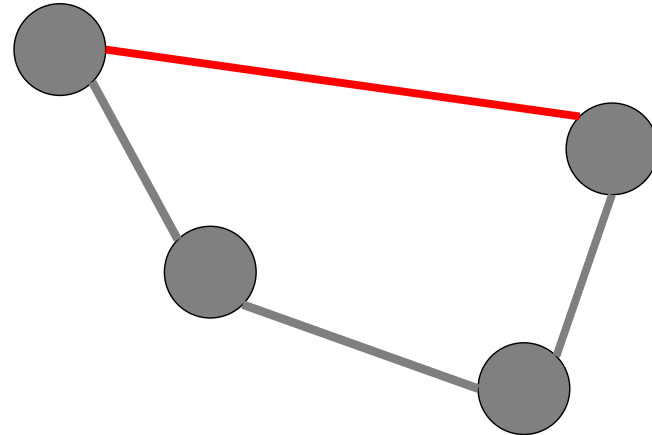
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## Greedy Algorithm:

Repeat:

**Apply red rule or  
blue rule to an  
arbitrary edge.**

until no more edges  
can be colored.



# Candidate MST Algorithm

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## Divide-and-Conquer:

1. If the number of vertices is 1, then return.
2. Divide the nodes into two sets.
3. Recursively calculate the MST of each set.
4. Find the lightest edge the connects the two sets and add it to the MST.
5. Return.

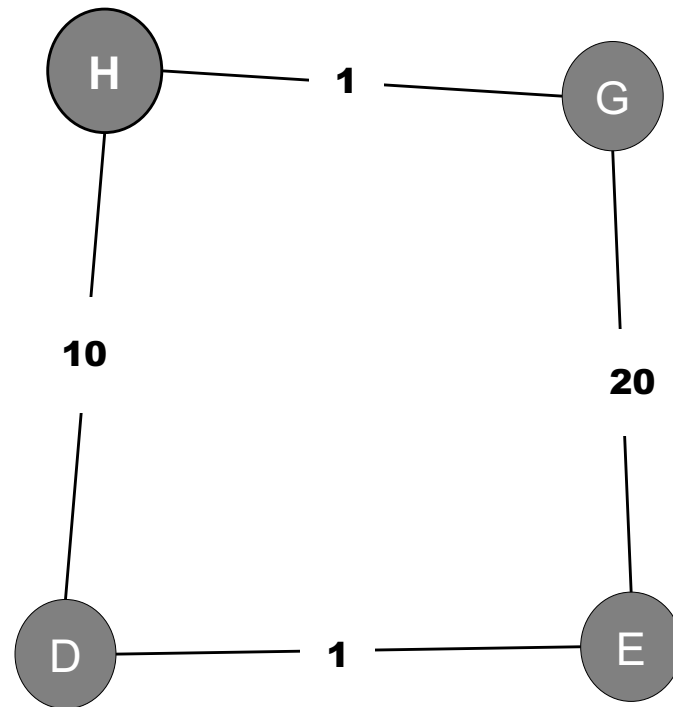
The problem with this algorithm is?

1. Nothing. It efficiently implements the red-blue strategy.
2. It is too expensive to implement because finding the lightest edge is hard.
3. It is too expensive to implement because partitioning the nodes is expensive.
- ✓ 4. It returns the wrong answer.

# Candidate MST Algorithm

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Example:

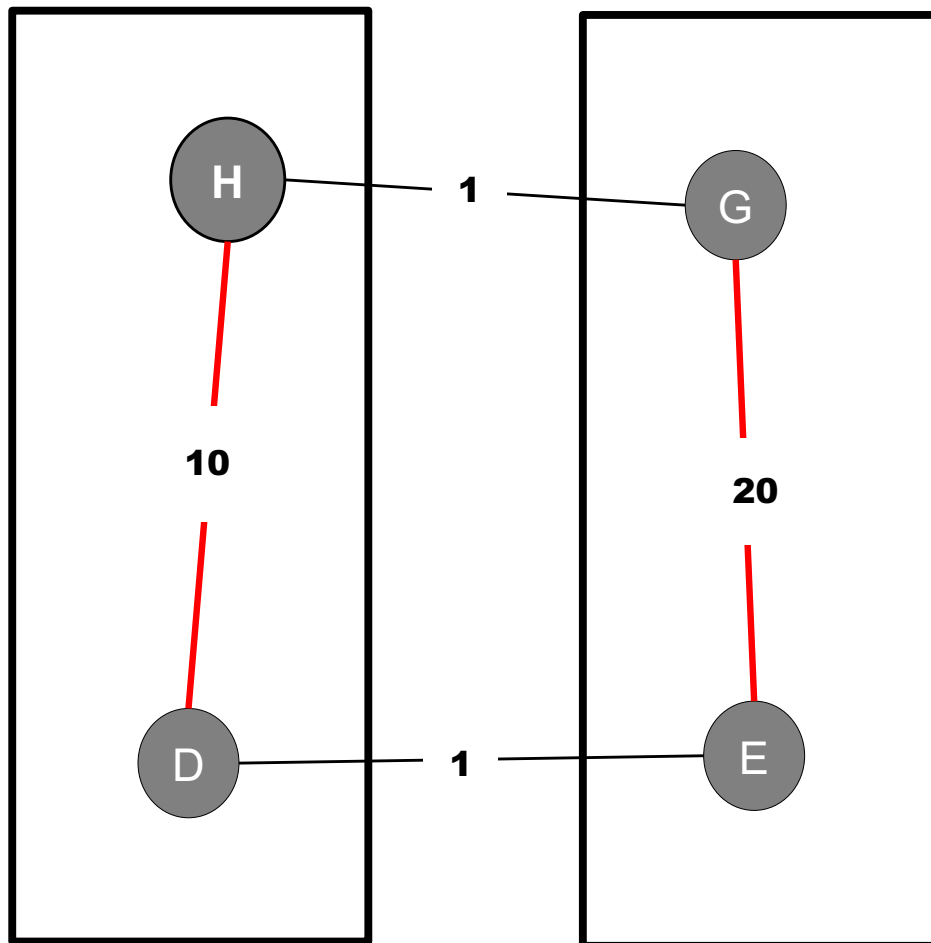




# Candidate MST Algorithm

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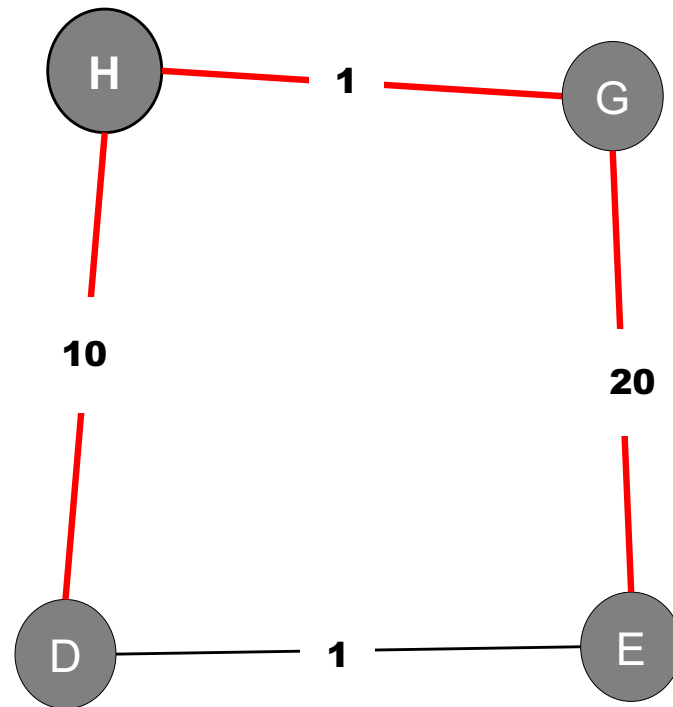
Example: Divide-and-Conquer



# Candidate MST Algorithm

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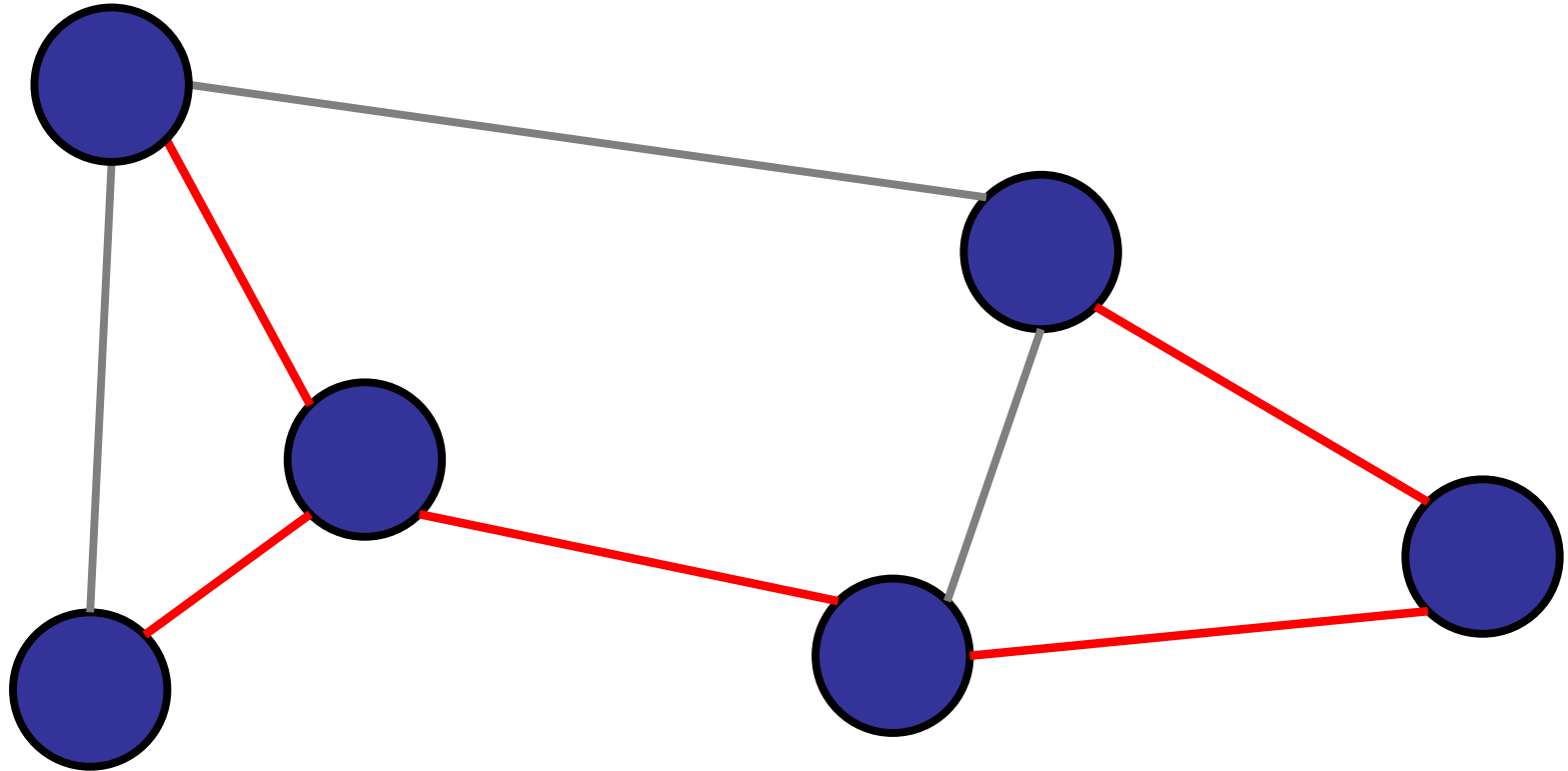
Example: Divide-and-Conquer



# Properties of MST

---

Property 2: If you cut an MST, the two pieces are both MSTs.



# BAD MST Algorithm

---

## Divide-and-Conquer:

1. If the number of vertices is 1, then return.
2. Divide the nodes into two sets.
3. Recursively calculate the MST of each set.
4. Find the lightest edge the connects the two sets and add it to the MST.
5. Return.

# Generic MST Algorithm

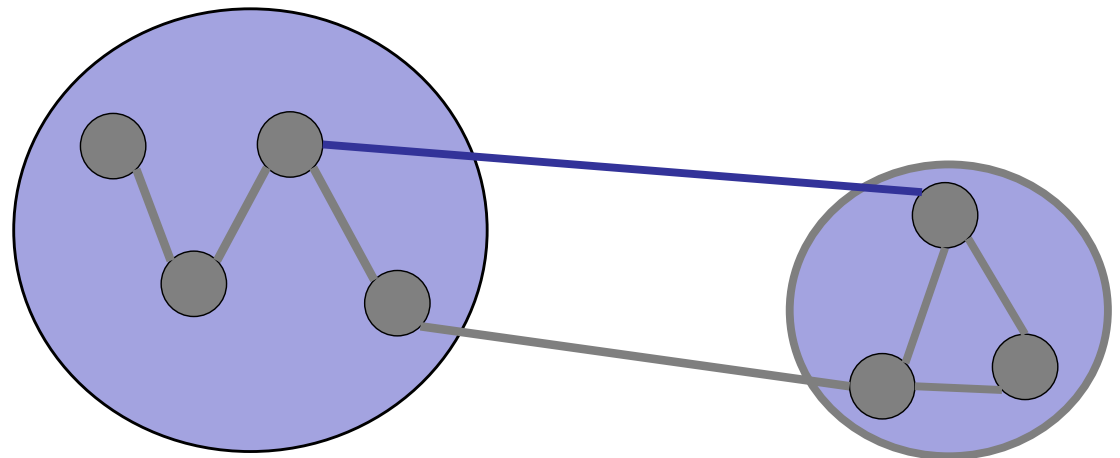
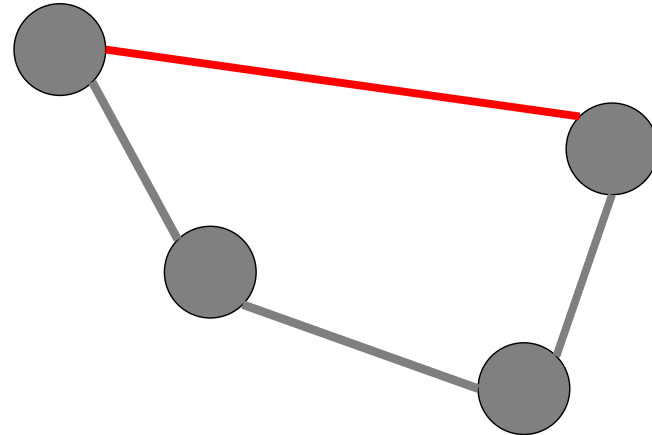
---

## Greedy Algorithm:

Repeat:

**Apply red rule or  
blue rule to an  
arbitrary edge.**

until no more edges  
can be colored.



# Roadmap

---

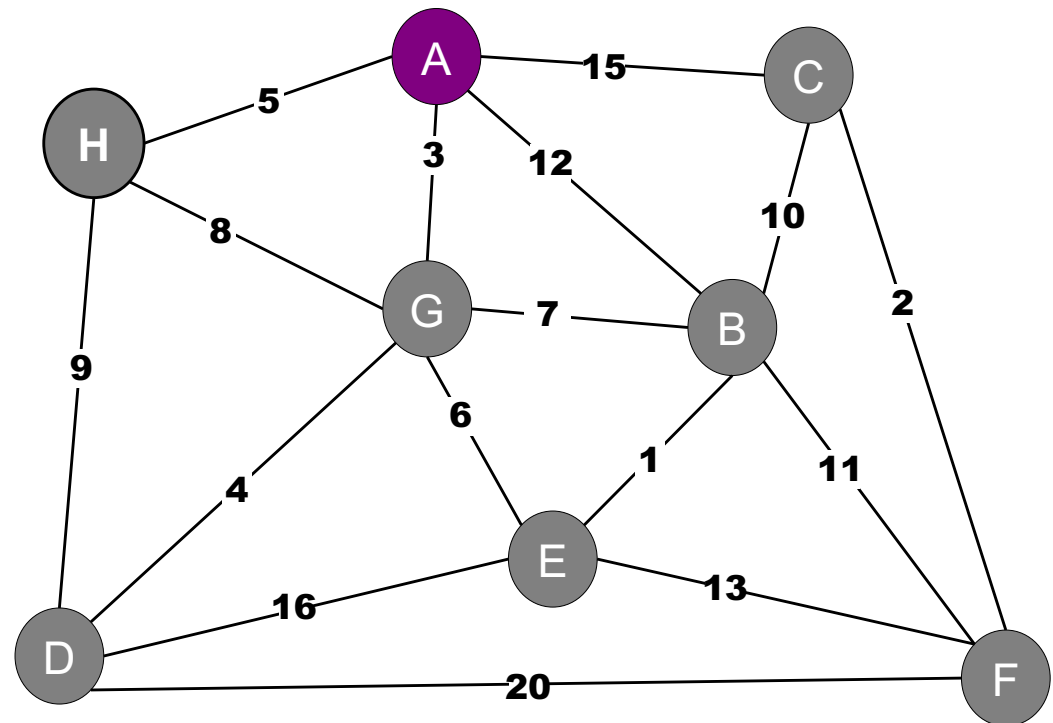
## Minimum Spanning Trees

- The MST Problem
- Basic Properties of an MST
- Generic MST Algorithm
- **Prim's Algorithm**
- Kruskal's Algorithm
- Boruvka's Algorithm
- Variations

# Prim's Algorithm

---

Prim's Algorithm. (Jarnik 1930, Dijkstra 1957, Prim 1959)



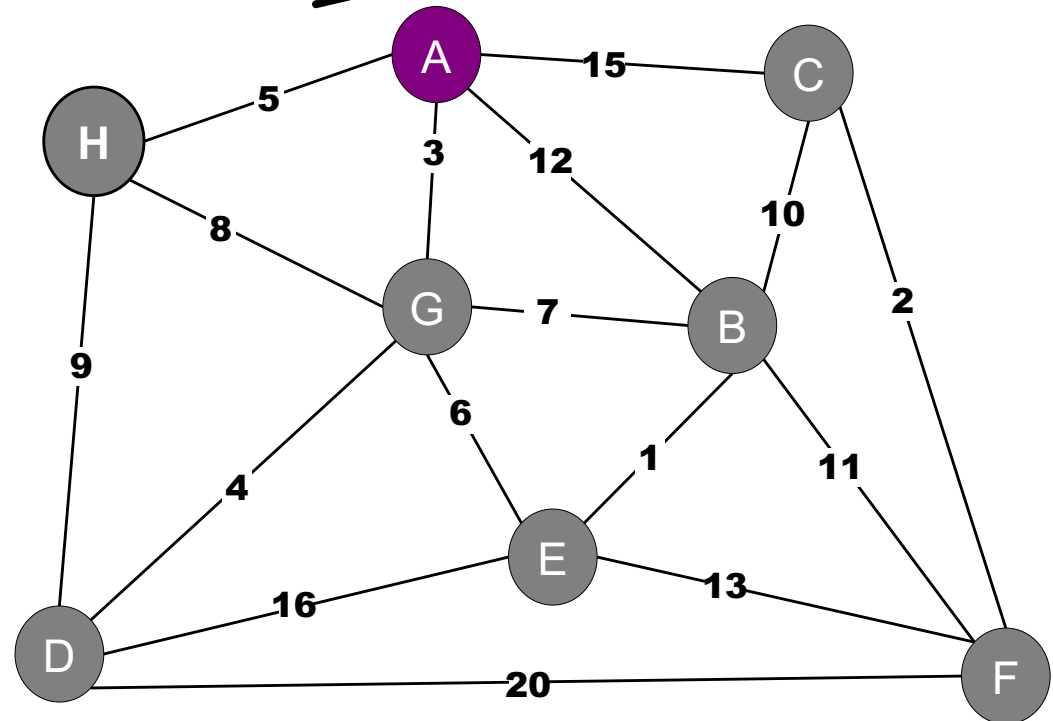
# Prim's Algorithm

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**Prim's Algorithm.** (Jarnik 1930, Dijkstra 1957, Prim 1959)

Basic idea:

- $S$  : set of nodes connected by blue edges.
- Initially:  $S = \{A\}$





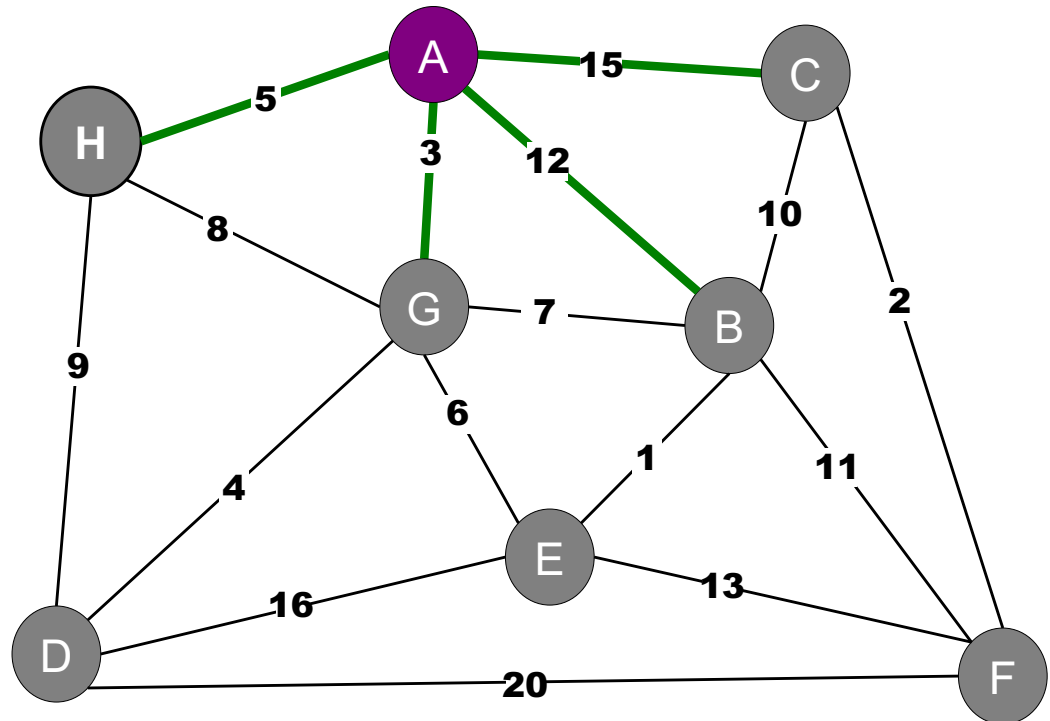
# Prim's Algorithm

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**Prim's Algorithm.** (Jarnik 1930, Dijkstra 1957, Prim 1959)

Basic idea:

- $S$  : set of nodes connected by blue edges.
- Initially:  $S = \{A\}$
- Identify cut:  $\{S, V-S\}$



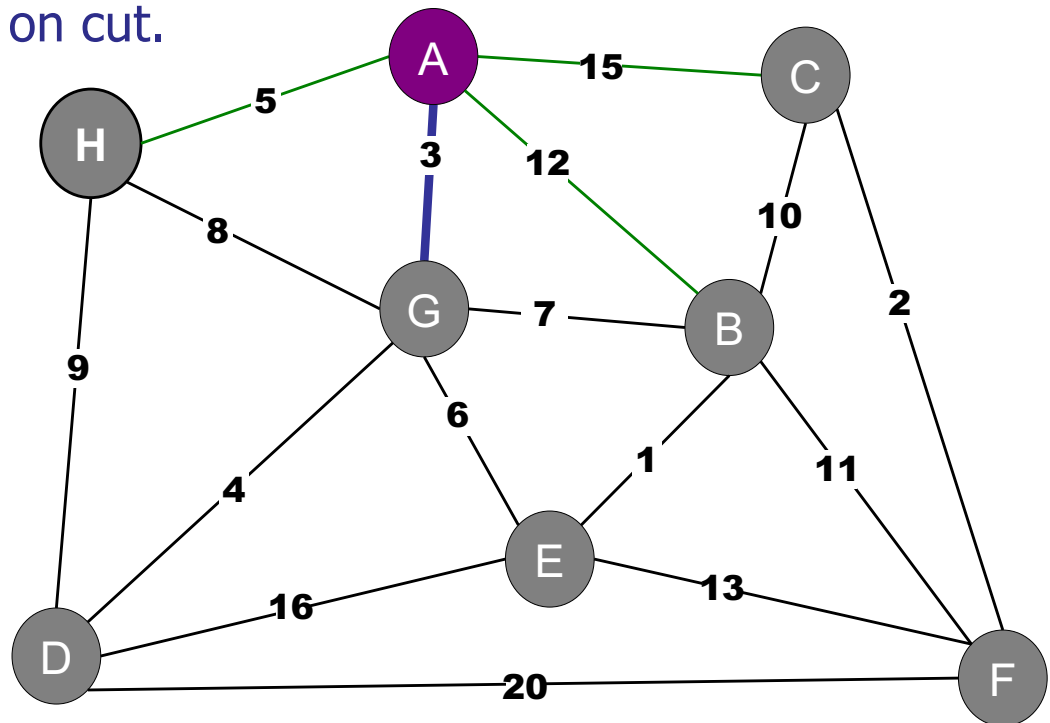
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- Find minimum weight edge on cut.



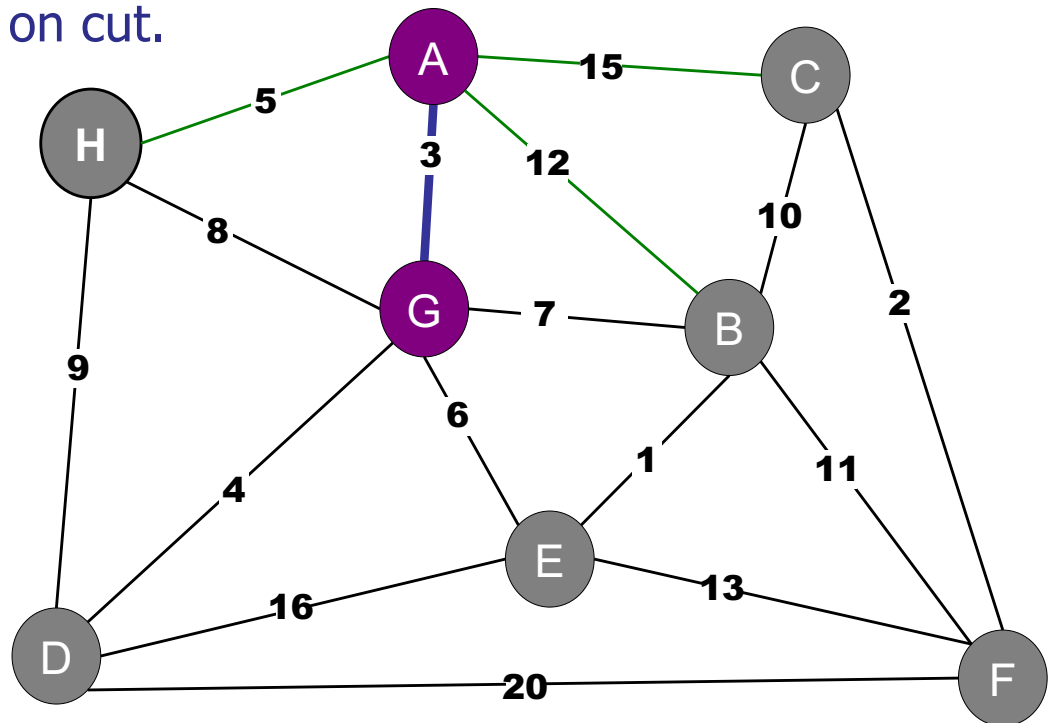
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- Identify cut:  $\{S, V-S\}$
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- Add new node to  $S$ .

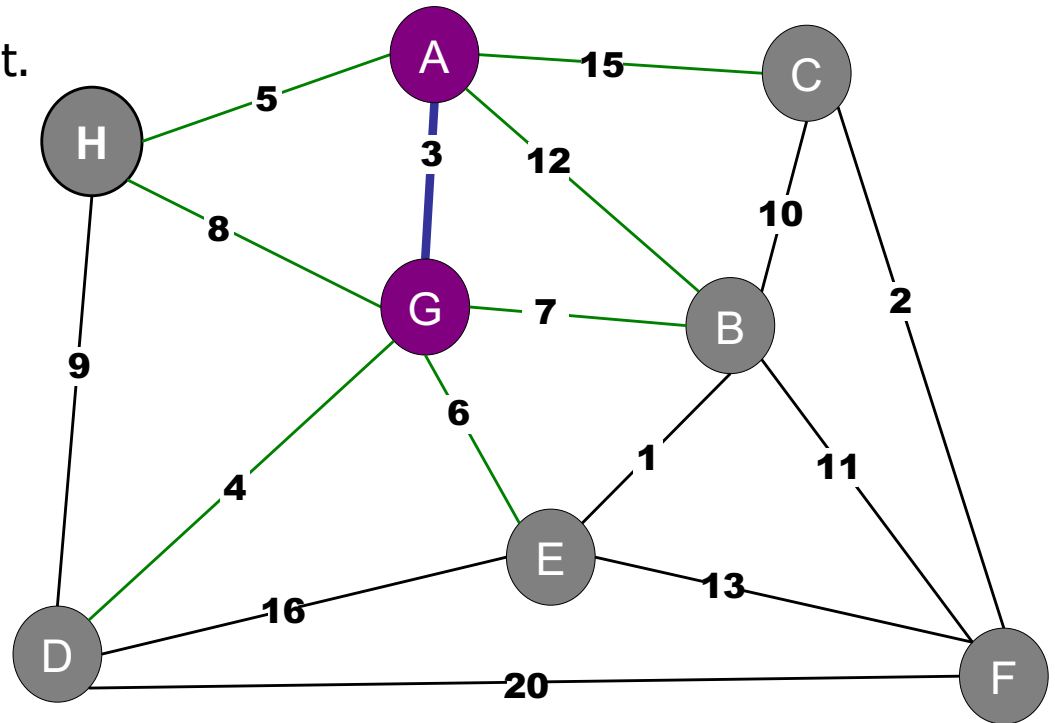


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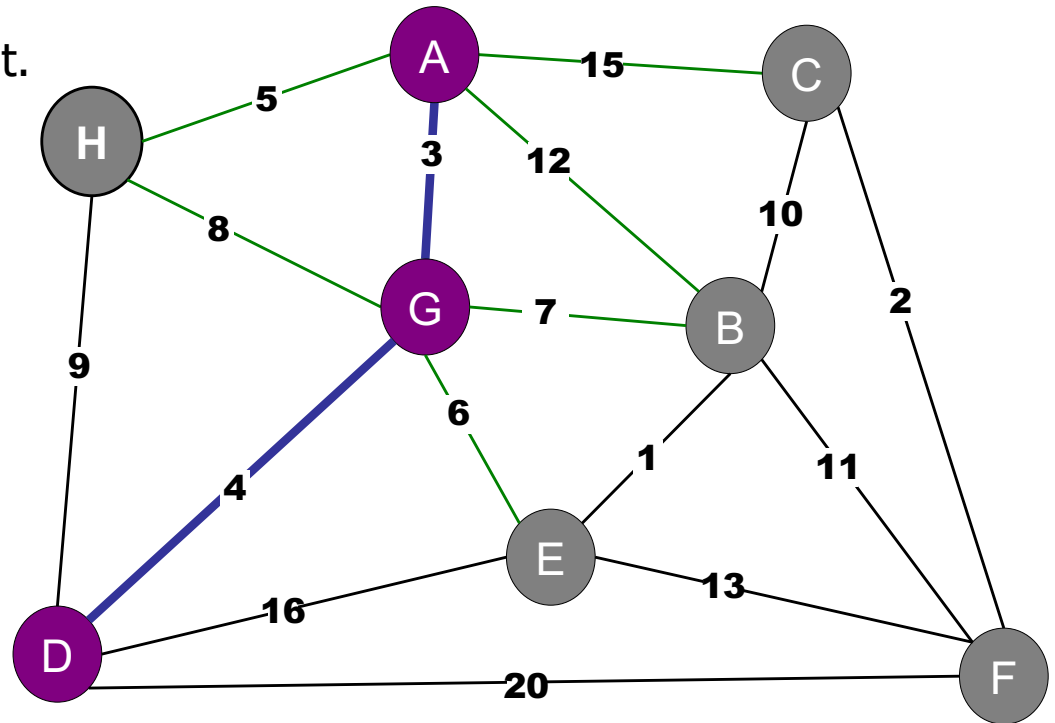
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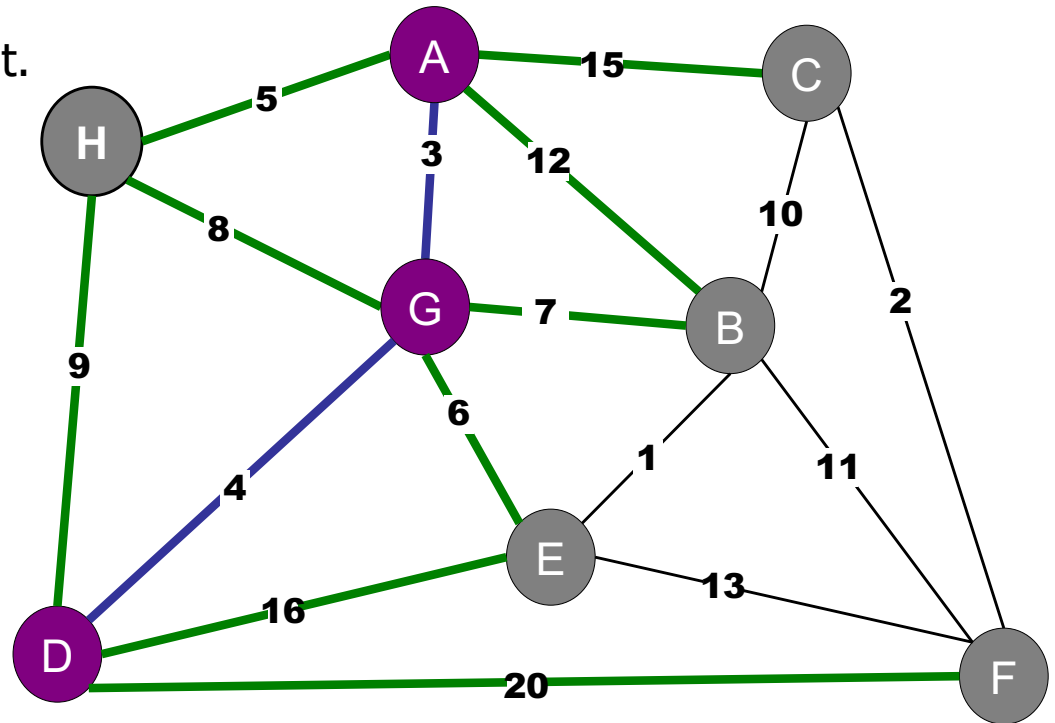


# Prim's Algorithm

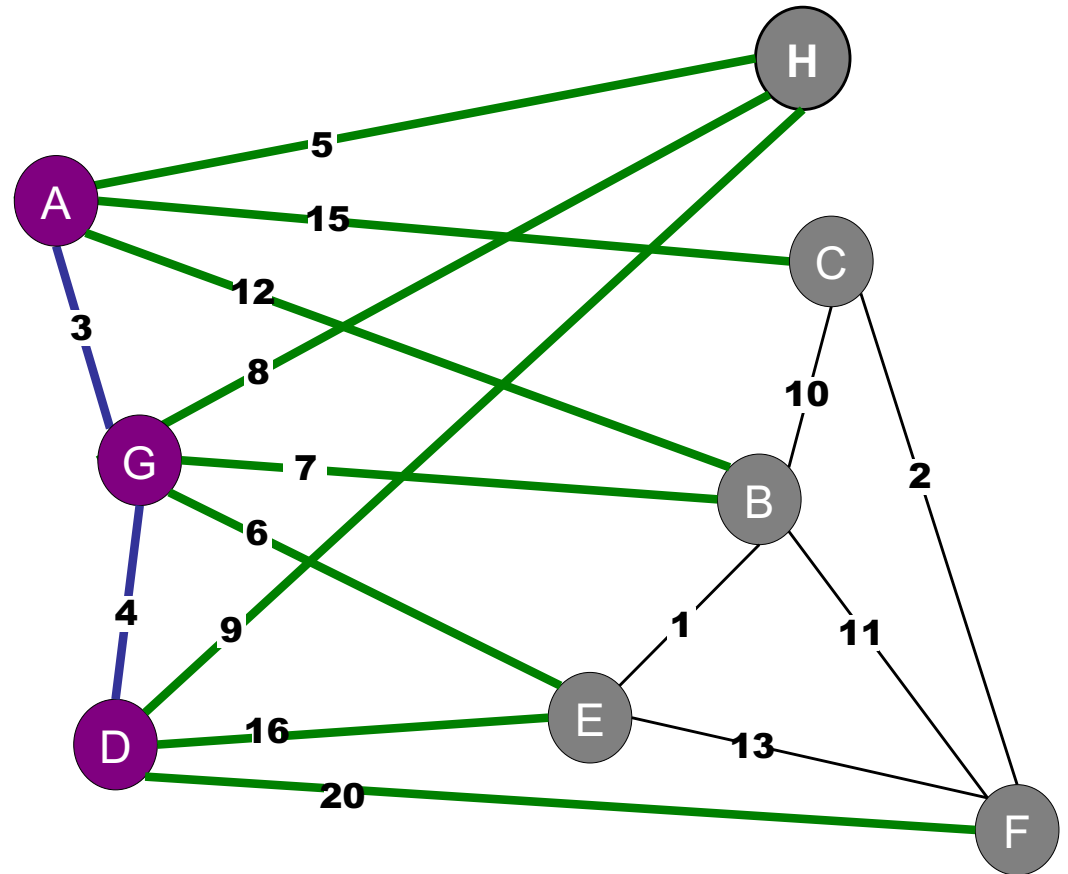
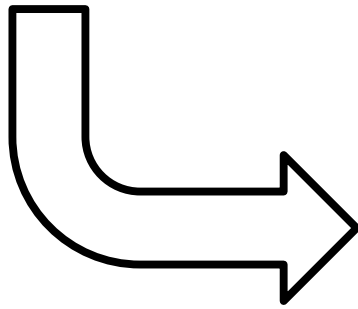
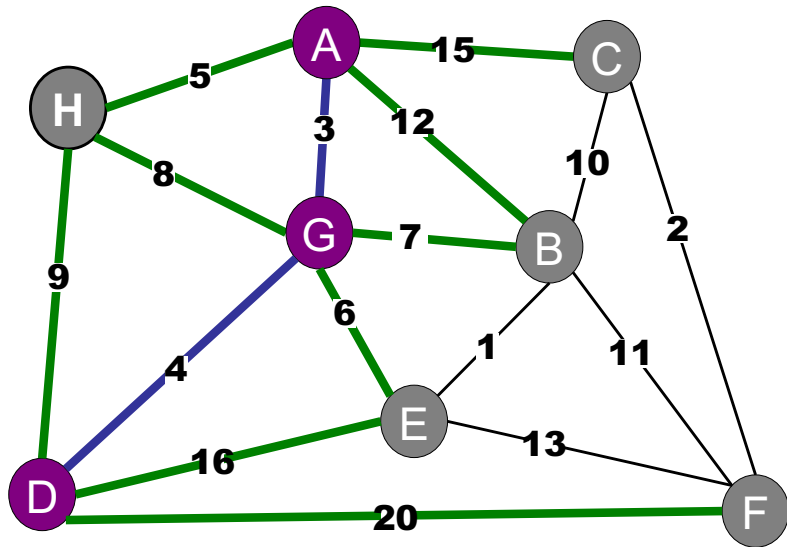
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- Initially:  $S = \{A\}$
- Repeat:
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  - Find minimum weight edge on cut.
  - Add new node to  $S$ .



# Prim's Algorithm



# How do we find the lightest edge on a cut?

- ✓ 1. Priority Queue
- 2. Union-Find
- 3. Max-flow / Min-cut
- 4. BFS
- 5. DFS

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is open



# Prim's Algorithm: Initialization

---

// Initialize priority queue

```
PriorityQueue pq = new PriorityQueue();  
for (Node v : G.V()) {  
    pq.insert(v, INFTY);  
}  
pq.decreaseKey(start, 0);
```

// Initialize set S

```
HashSet<Node> S = new HashSet<Node>();  
S.put(start);
```

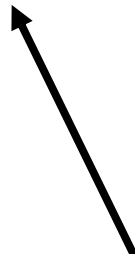
// Initialize parent hash table

```
HashMap<Node, Node> parent = new HashMap<Node, Node>();  
parent.put(start, null);
```

# Prim's Algorithm

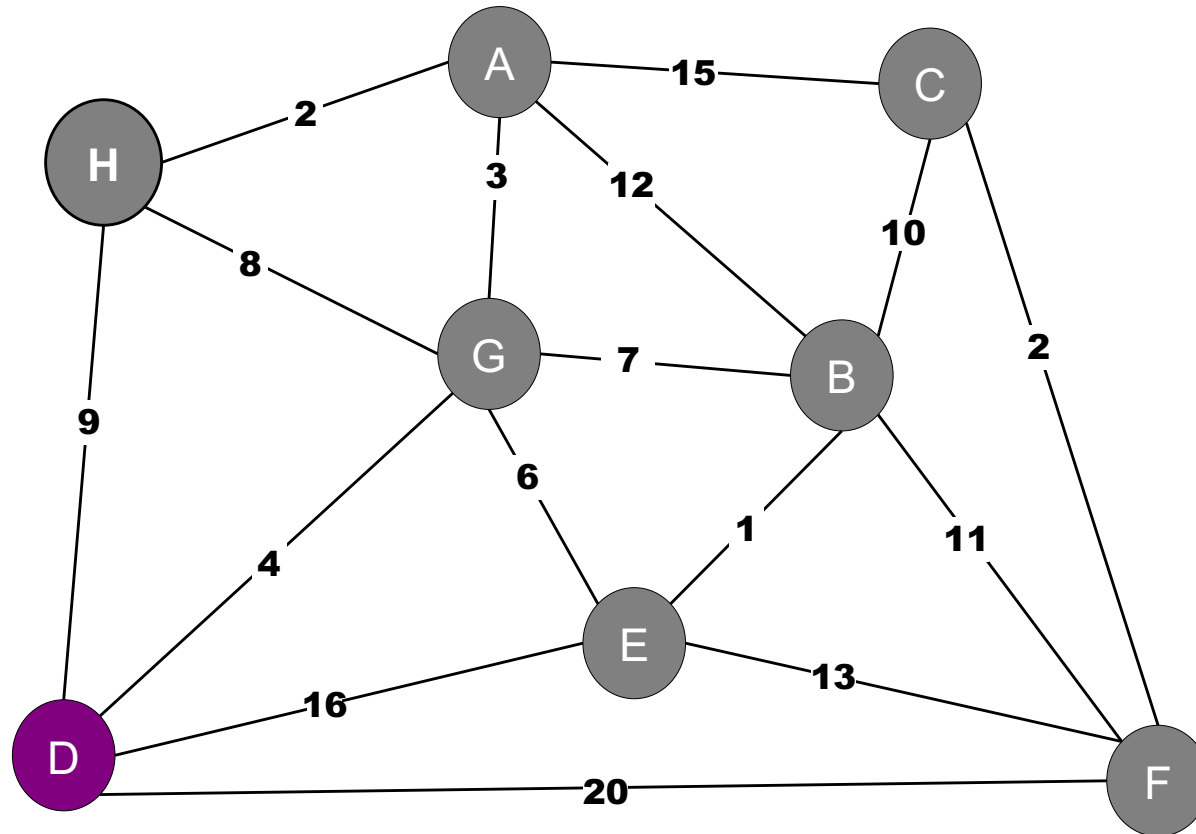
---

```
while (!pq.isEmpty()) {  
    Node v = pq.deleteMin();  
    S.put(v);  
    for each (Edge e : v.edgeList()) {  
        Node w = e.otherNode(v);  
        if (!S.get(w)) {  
            pq.decreaseKey(w, e.getWeight());  
            parent.put(w, v);  
        }  
    }  
}
```



Assume:  
decreaseKey does nothing  
if new weight is larger than  
old weight

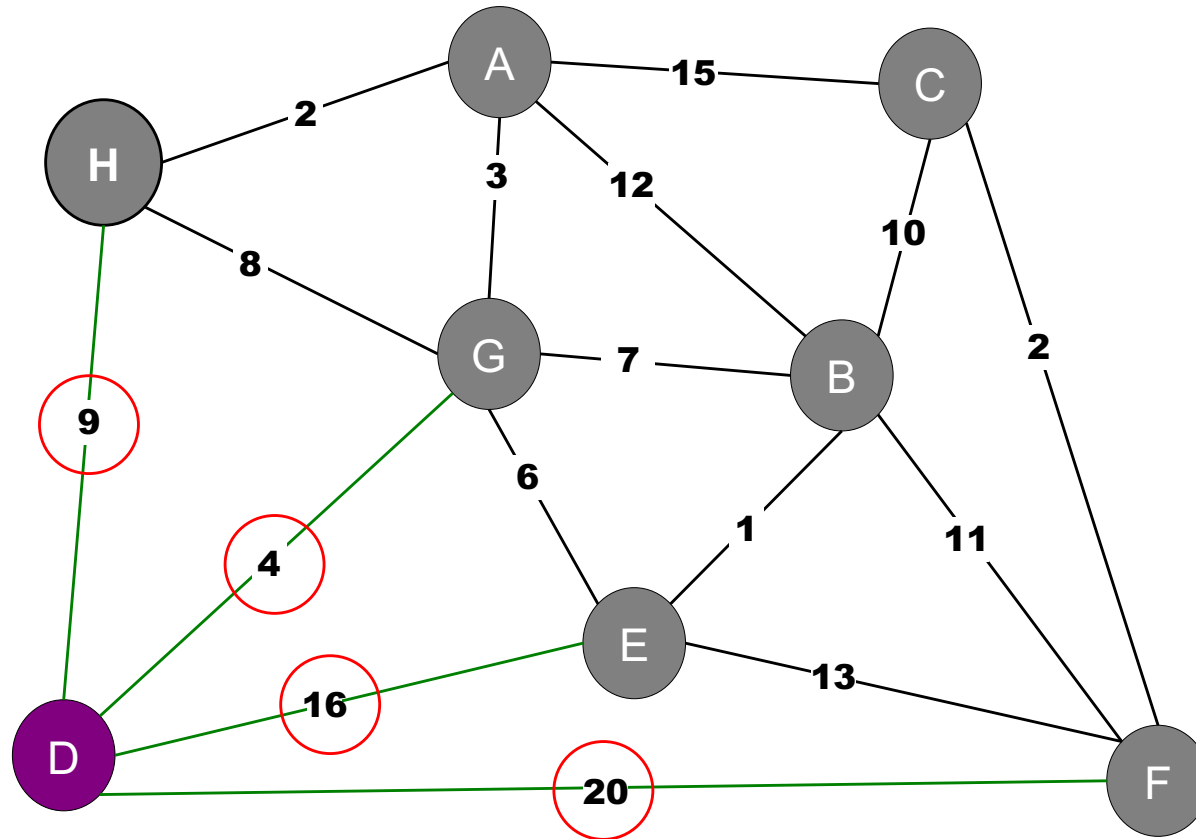
# Prim's Example



Vertex	Weight
D	0

Not drawing  
infinite weight  
nodes in PQ.

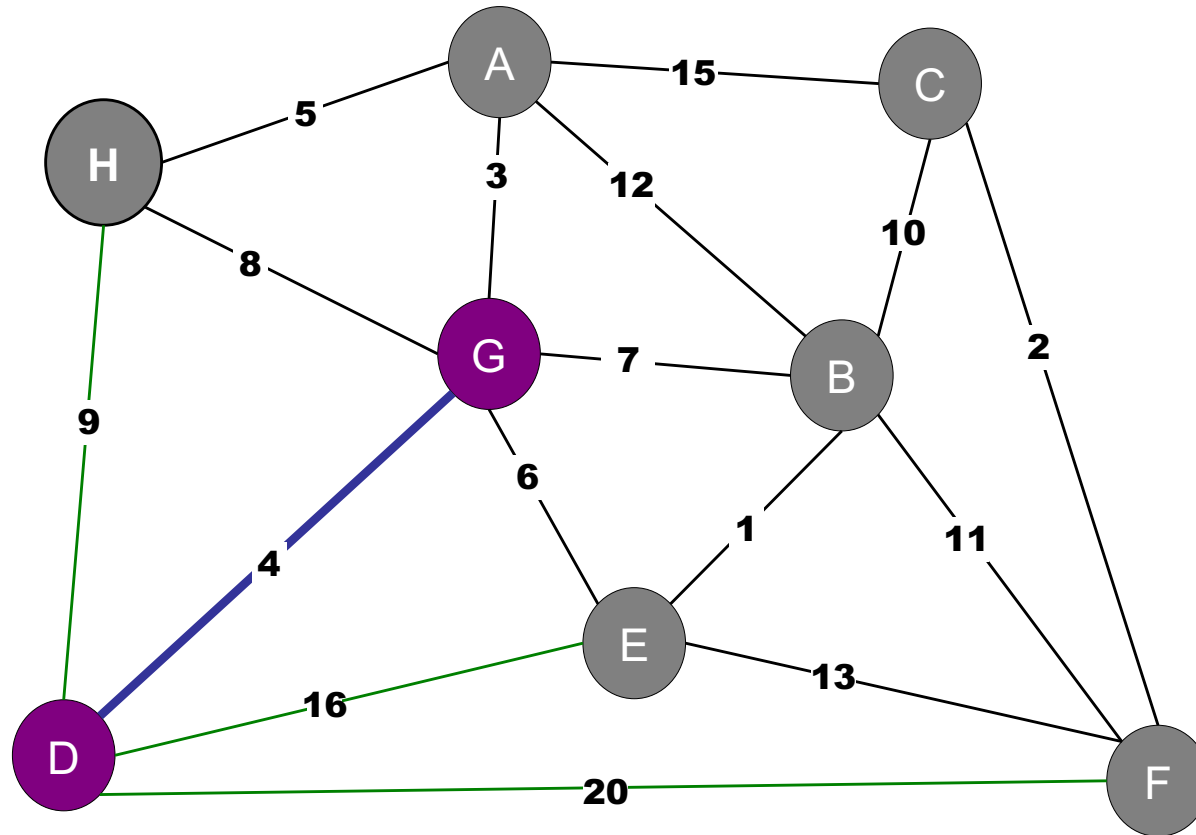
# Prim's Example



Vertex	Weight
G	4
H	9
E	16
F	20

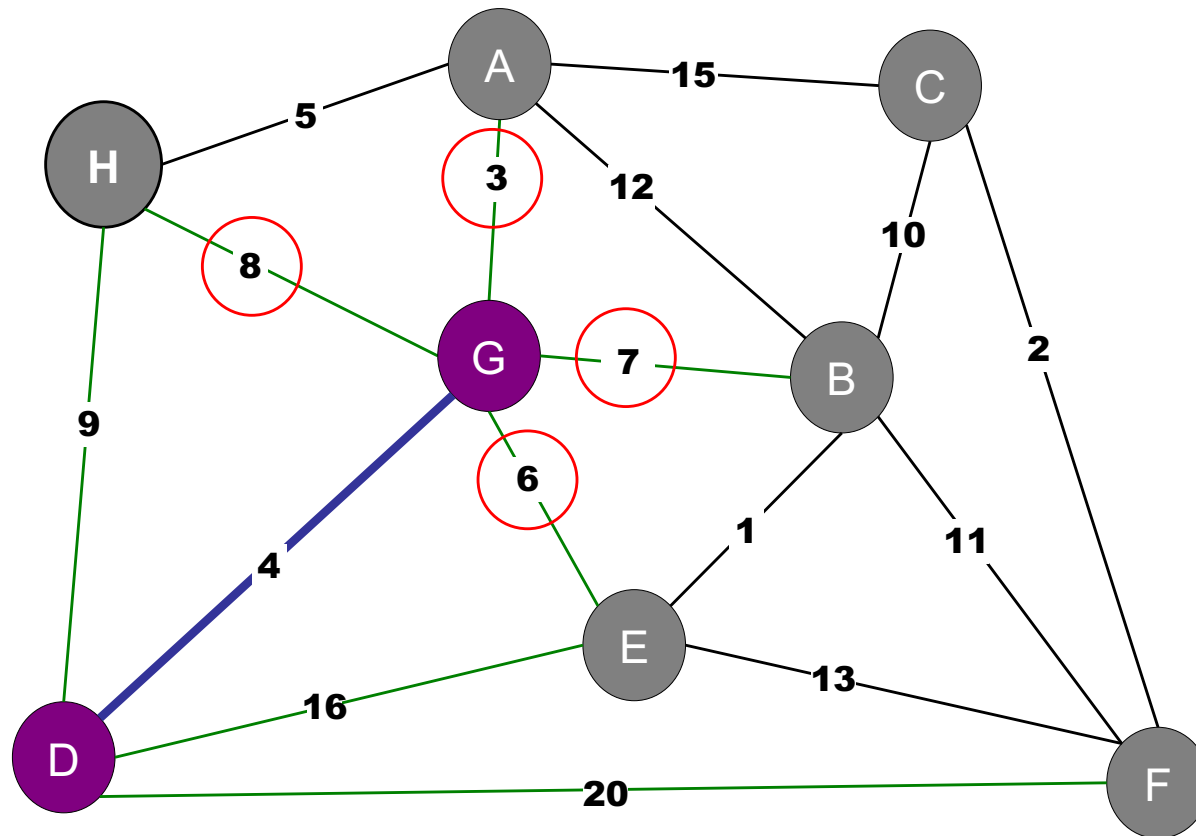
# Prim's Example

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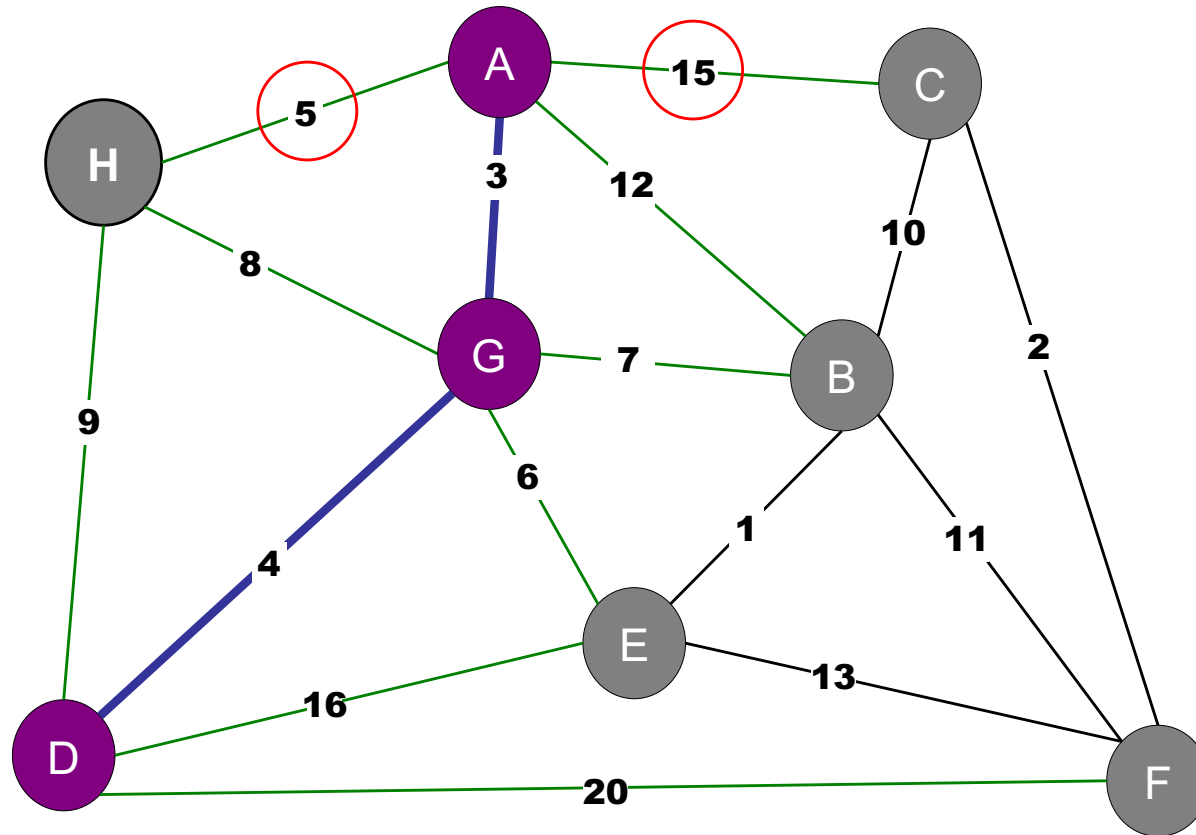
Vertex	Weight
H	9
E	16
F	20

# Prim's Example



Vertex	Weight
A	3
E	16->6
B	7
H	9->8
F	20

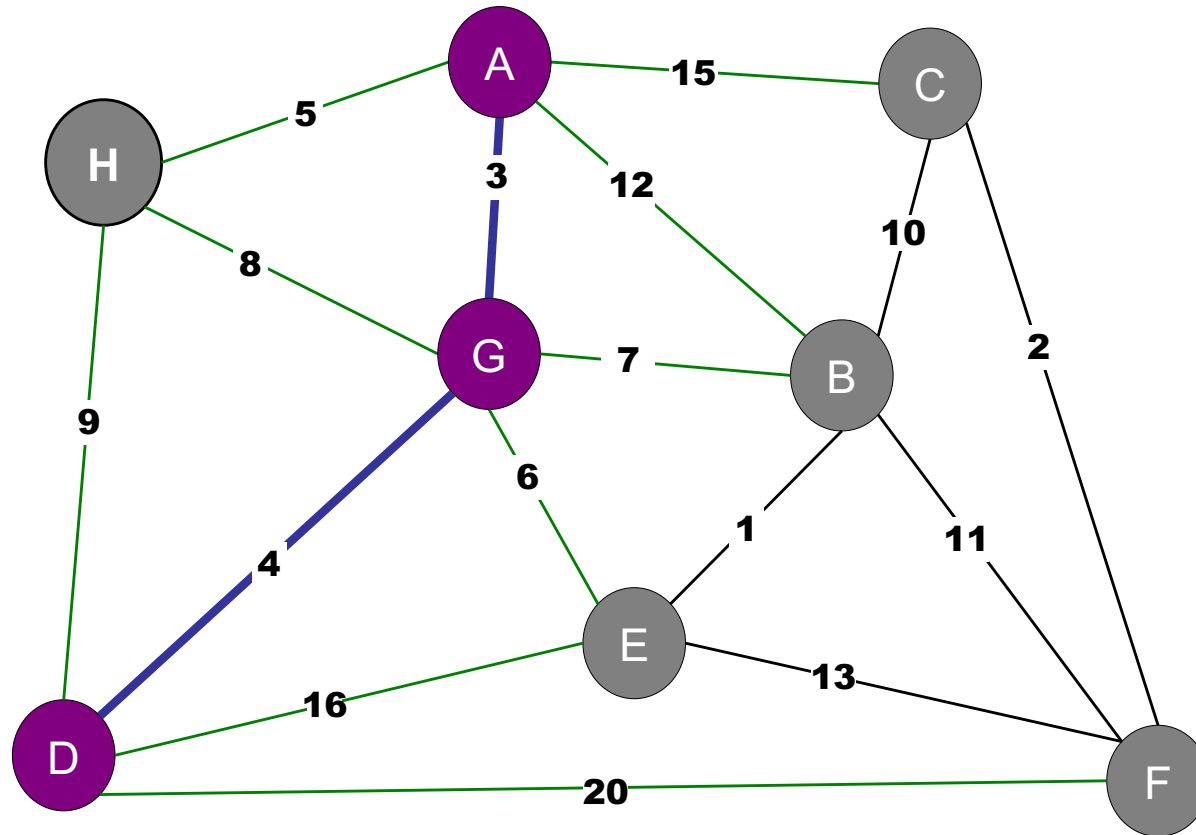
# Prim's Example



Vertex	Weight
H	8->5
E	6
B	7
C	15
F	20

# Prim's Example

---

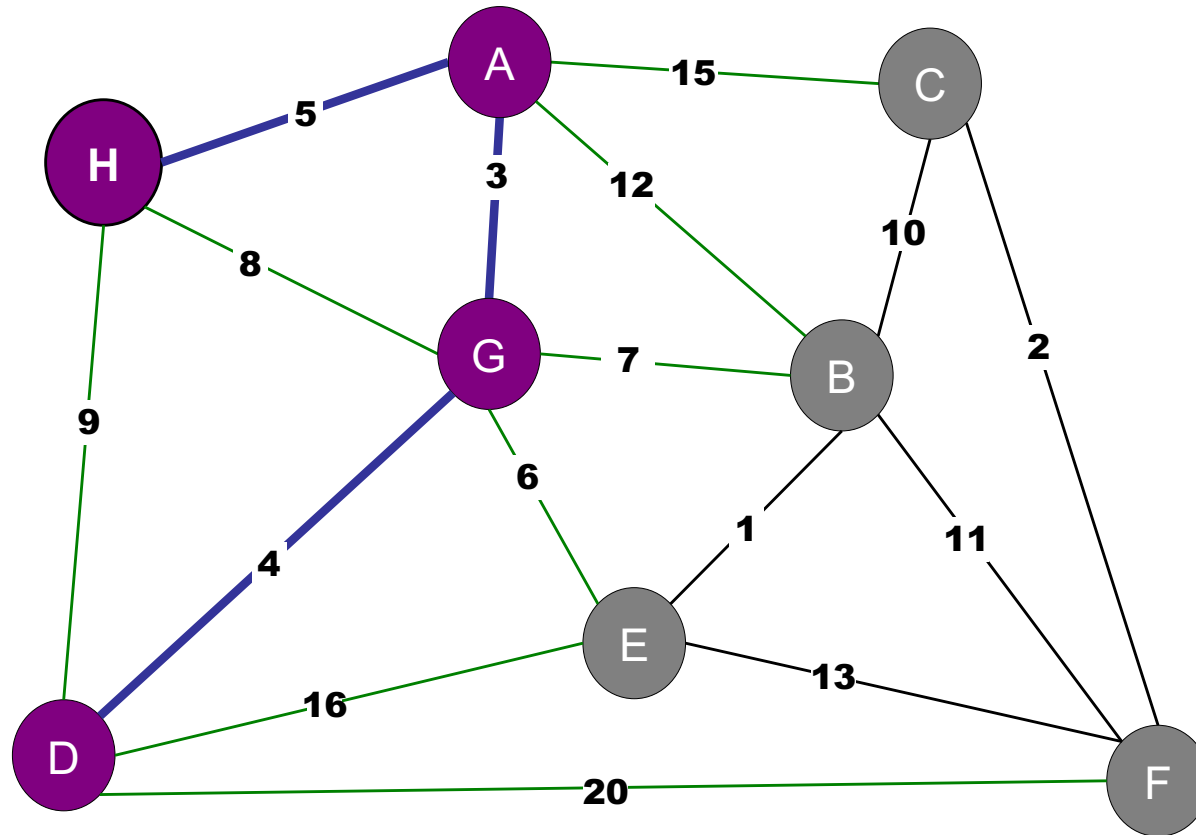


Vertex	Weight
H	5
E	6
B	7
C	15
F	20



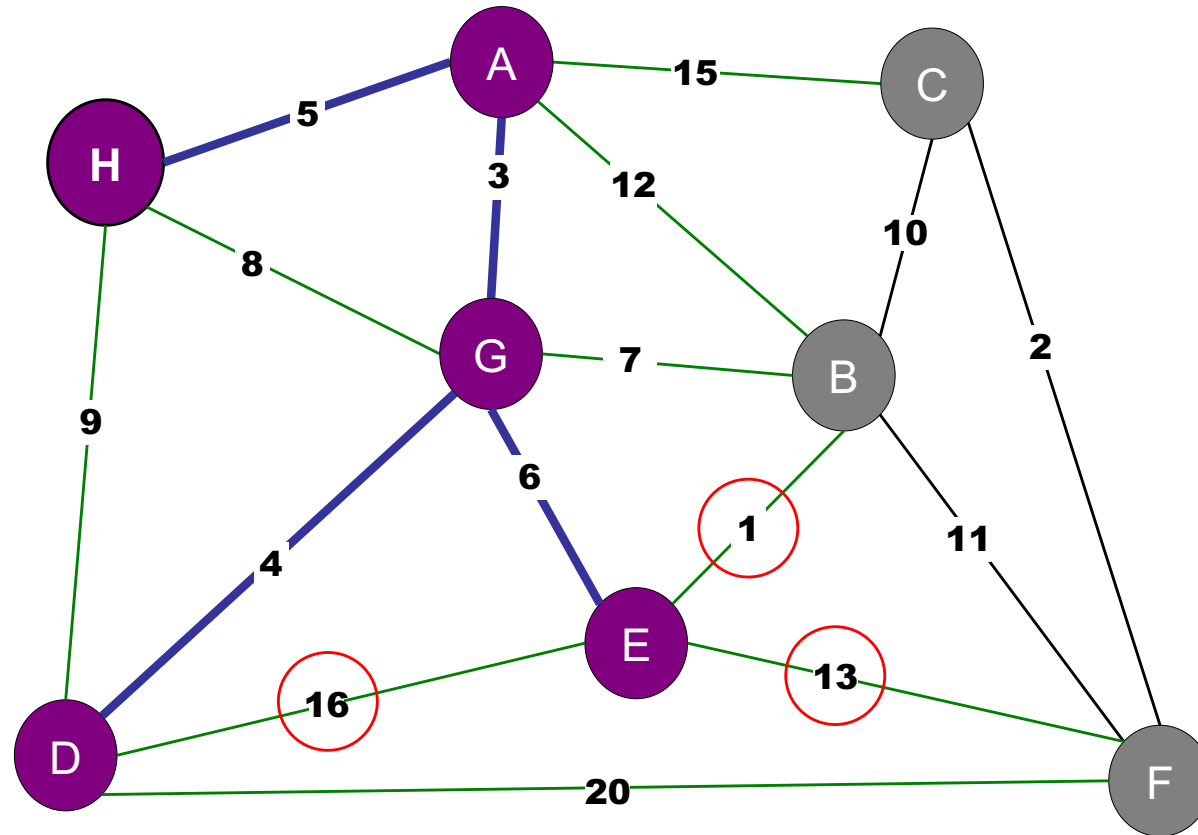
# Prim's Example

---



Vertex	Weight
E	6
B	7
C	15
F	20

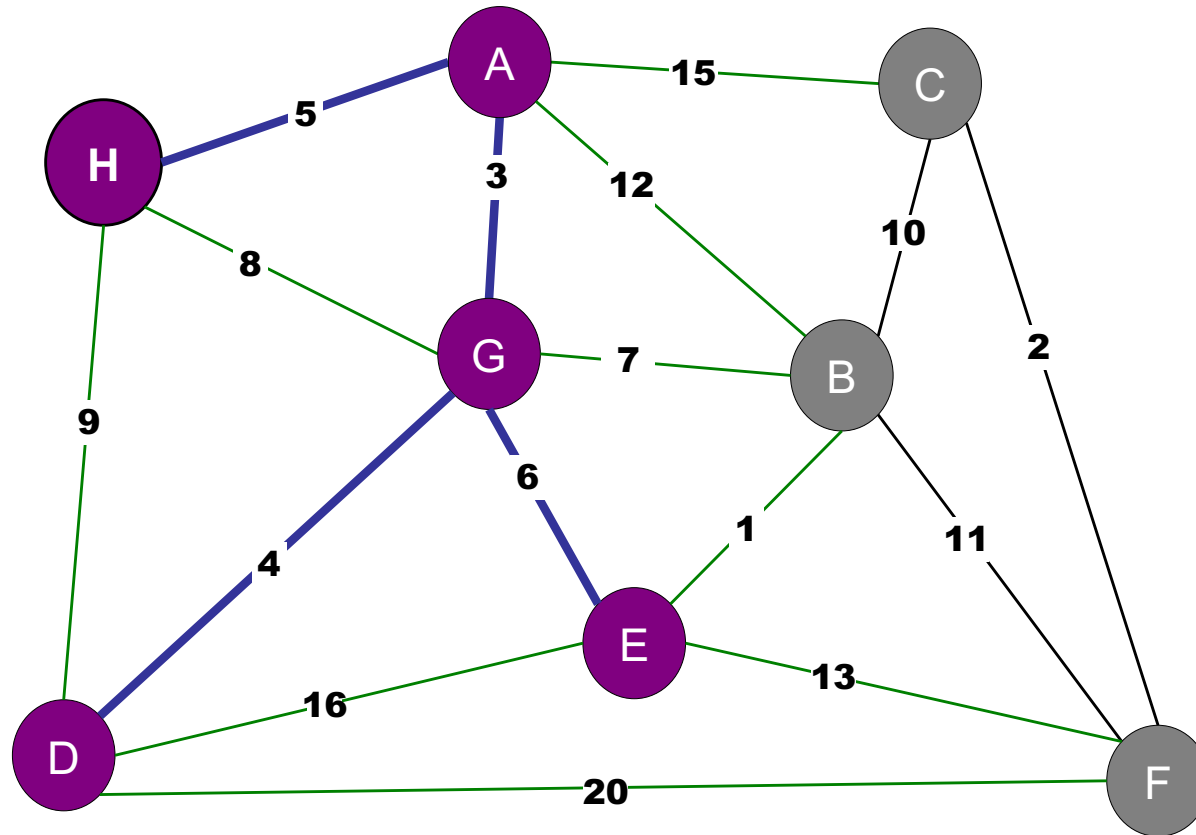
# Prim's Example



Vertex	Weight
<b>B</b>	<b>7-&gt;1</b>
C	15
<b>F</b>	<b>20-&gt;13</b>

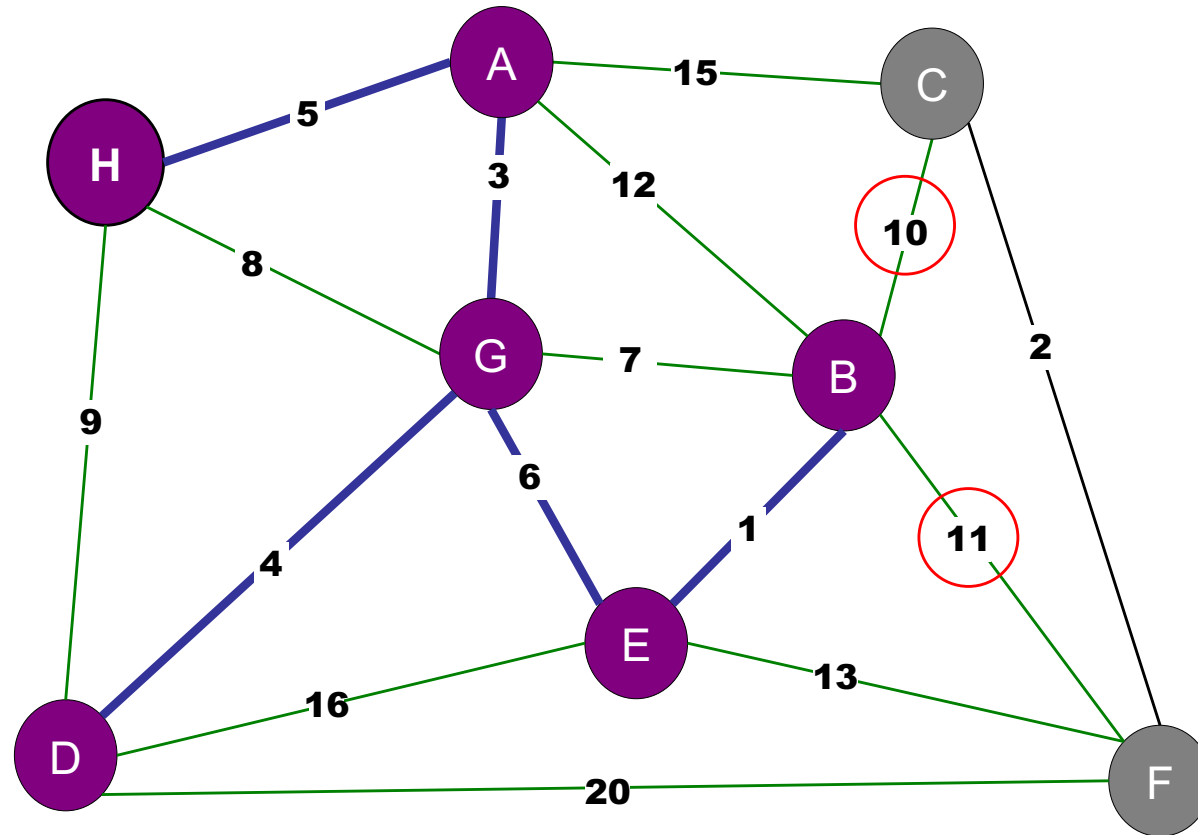
# Prim's Example

---



Vertex	Weight
B	1
C	15
F	13

# Prim's Example

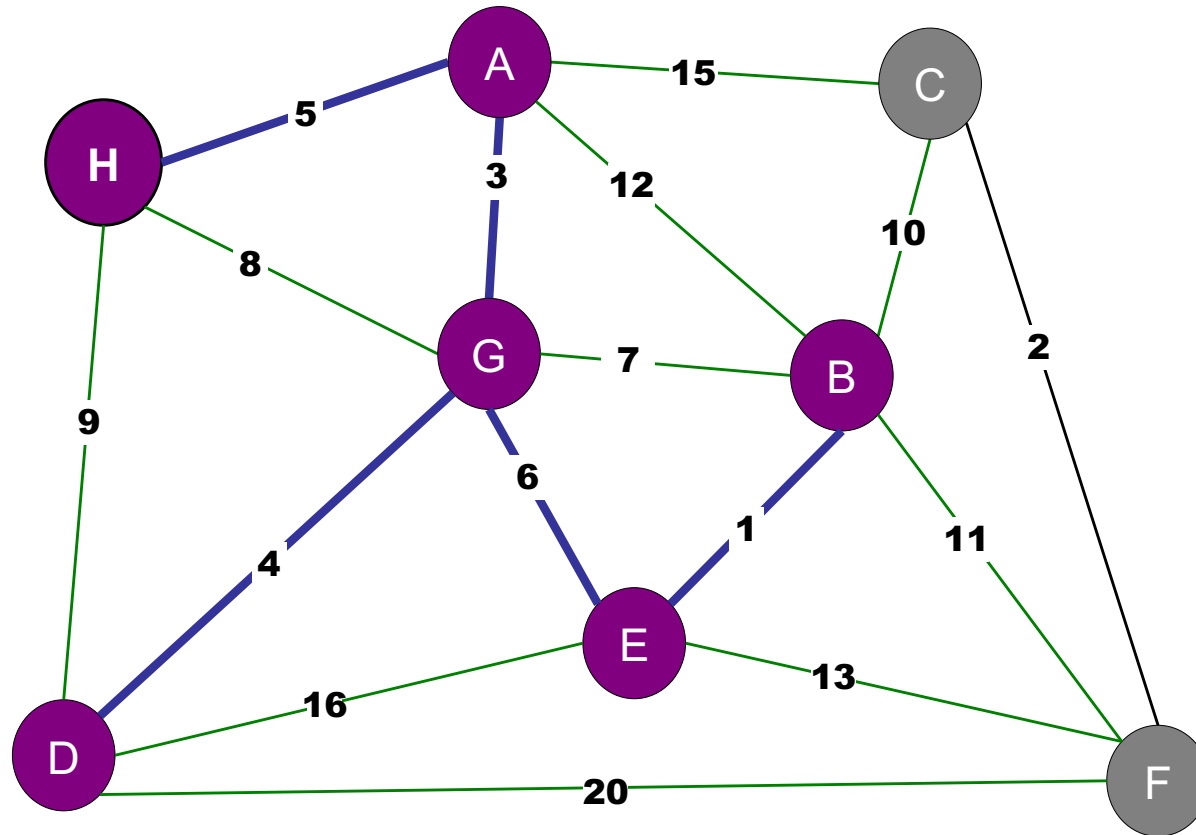


Vertex	Weight
C	<b>15-&gt;10</b>
F	<b>13-&gt;11</b>

# Prim's Example

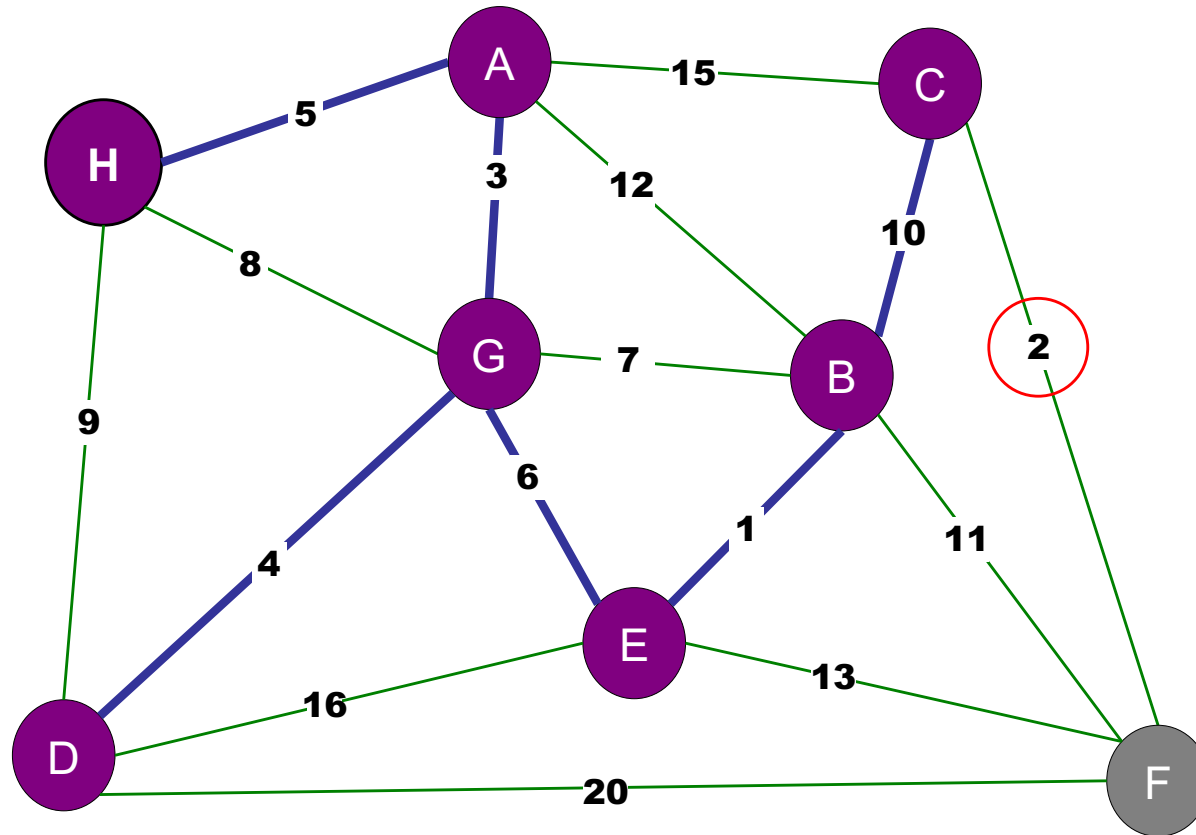
---

Vertex	Weight
C	10
F	11



# Prim's Example

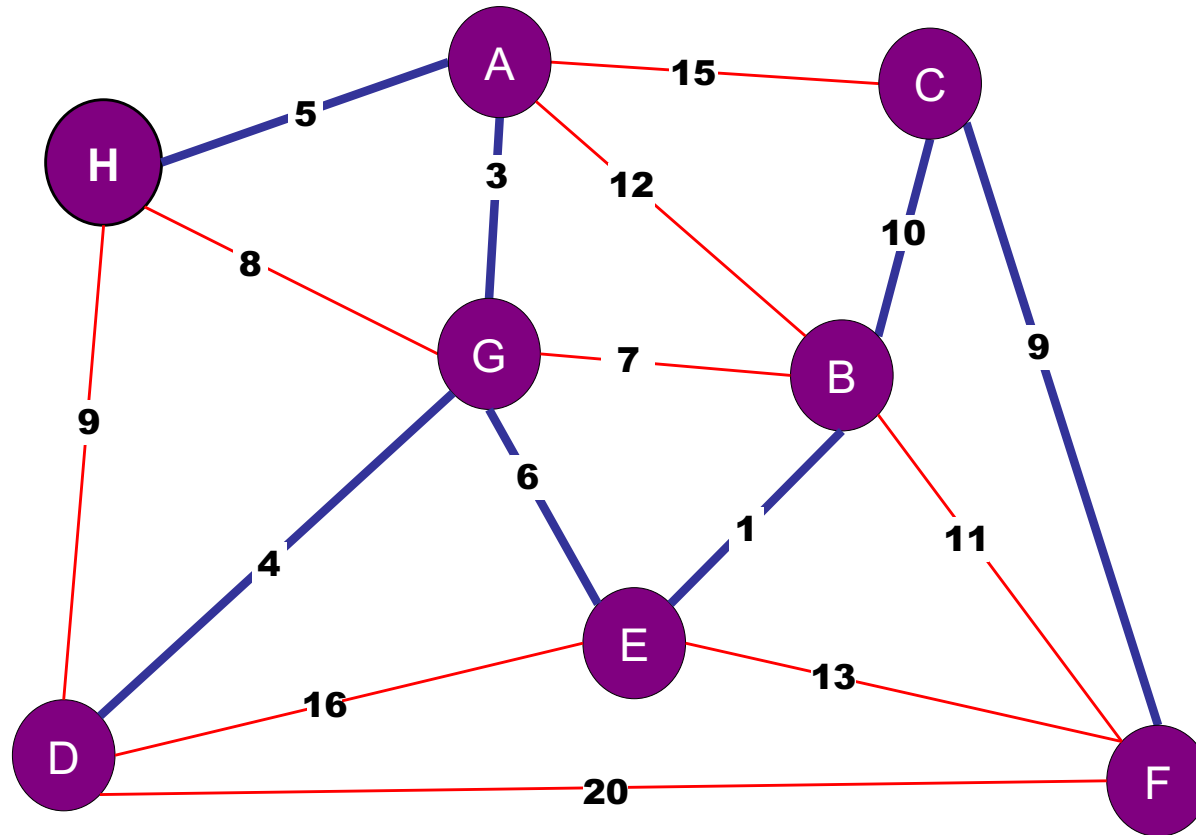
Vertex	Weight
F	11->2



# Prim's Example

---

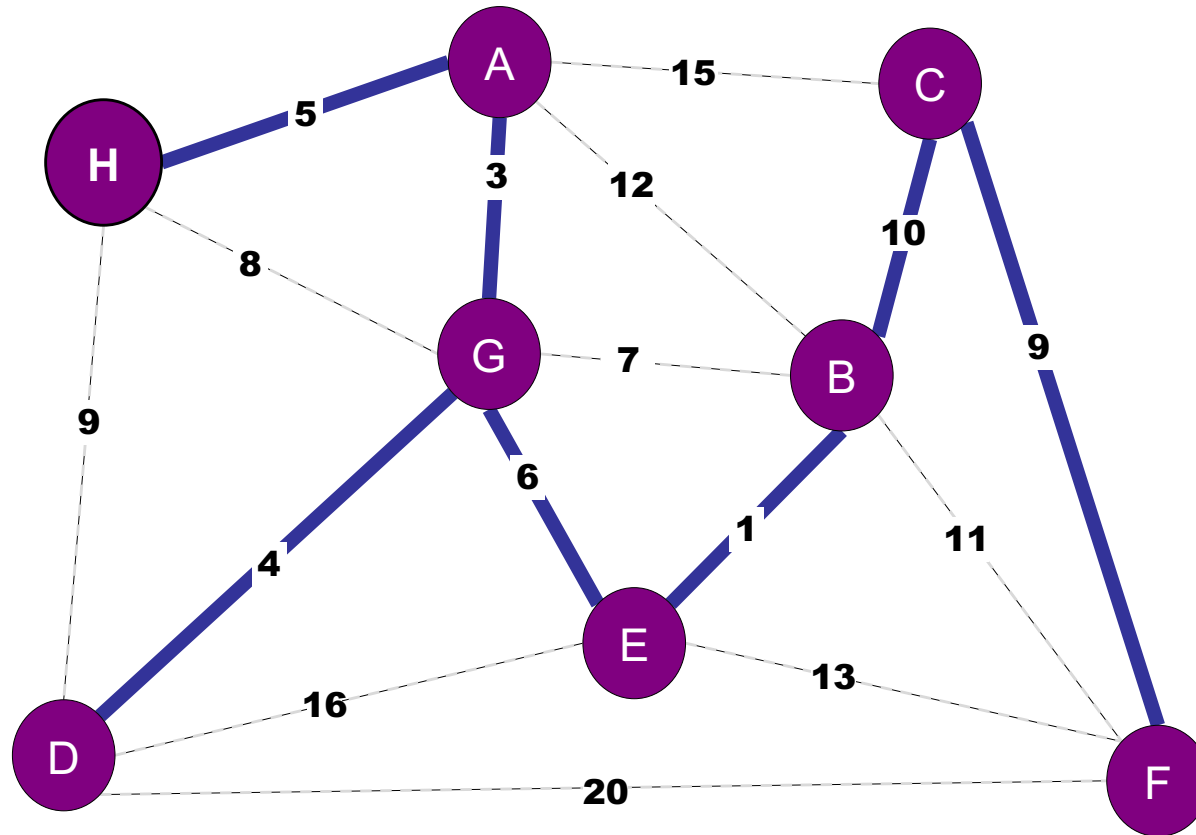
Vertex	Weight



# Prim's Example

---

Vertex	Weight





# Prim's Algorithm

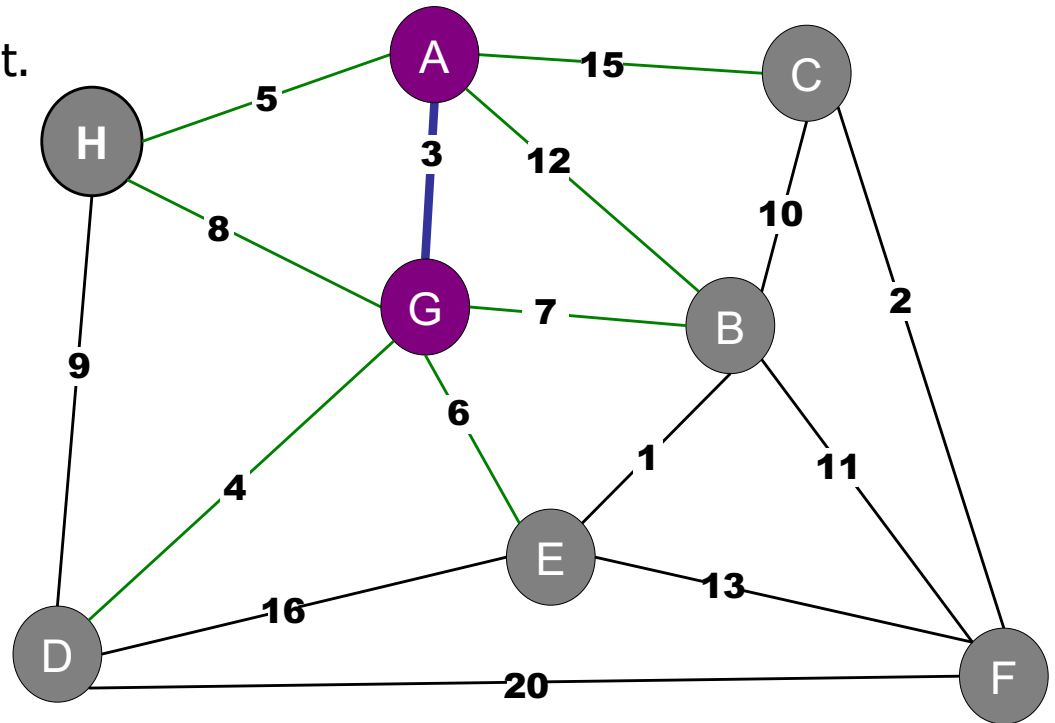
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- Repeat:
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  - Find minimum weight edge on cut.
  - Add new node to  $S$ .

Proof:

- Each added edge is the lightest on some cut.
- Hence each edge is in the MST.



What is the running time of Prim's Algorithm, using an AVL tree for PQ?

1.  $O(V)$
2.  $O(E)$
- ✓ 3.  $O(E \log V)$
4.  $O(V \log E)$
5.  $O(EV)$

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# Prim's Algorithm

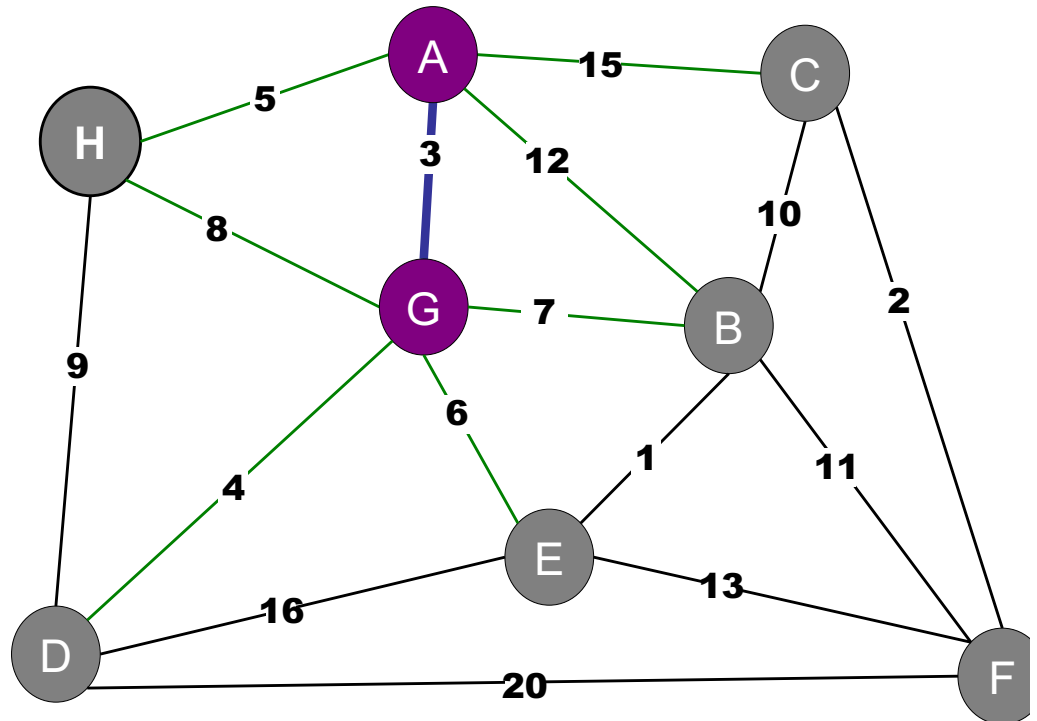
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Analysis:

- Each vertex added/removed once from the priority queue:  $O(V \log V)$
- Each edge  $\Rightarrow$  one decreaseKey:  $O(E \log V)$ .



# Two Algorithms

---

## Prim's Algorithm.

Basic idea:

- Maintain a set of visited nodes.
- Greedily grow the set by adding node connected via the lightest edge.
- Use Priority Queue to order nodes by edge weight.

## Dijkstra's Algorithm.

Basic idea:

- Maintain a set of visited nodes.
- Greedily grow the set by adding neighboring node that is closest to the source.
- Use Priority Queue to order nodes by distance.

# Roadmap

---

## Minimum Spanning Trees

- The MST Problem
- Basic Properties of an MST
- Generic MST Algorithm
- Prim's Algorithm
- **Kruskal's Algorithm**
- Boruvka's Algorithm
- Variations

# Generic MST Algorithm

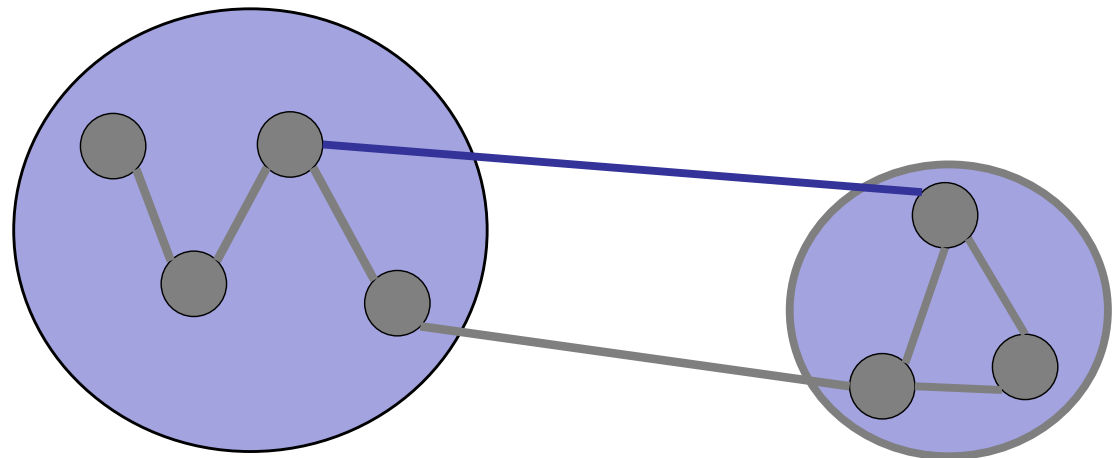
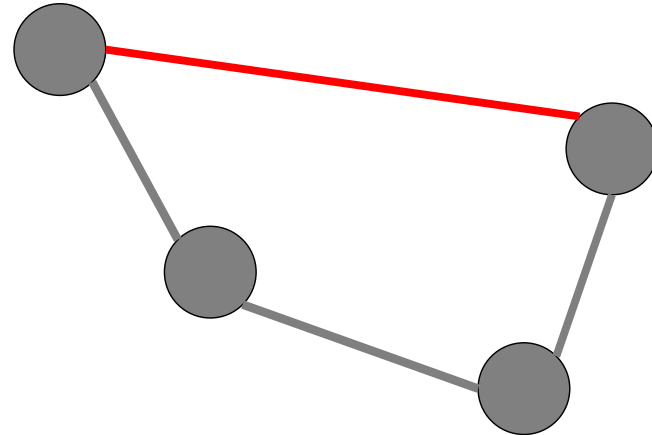
---

## Greedy Algorithm:

Repeat:

**Apply red rule or  
blue rule to an  
arbitrary edge.**

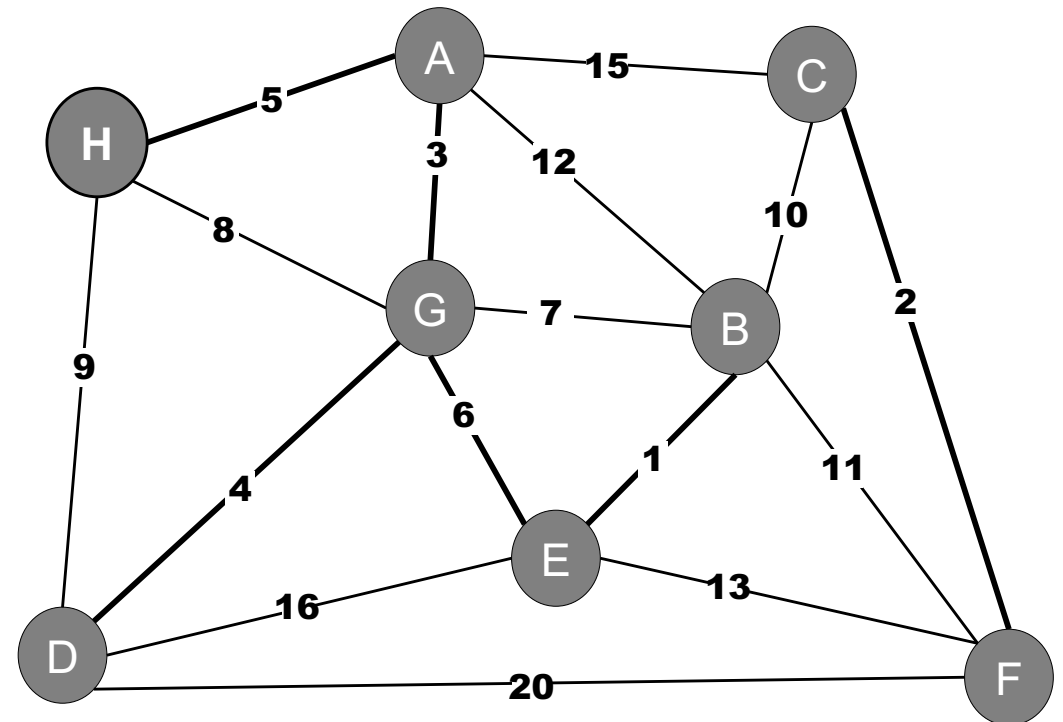
until no more edges  
can be colored.



# Kruskal's Algorithm

---

Kruskal's Algorithm. (Kruskal 1956)



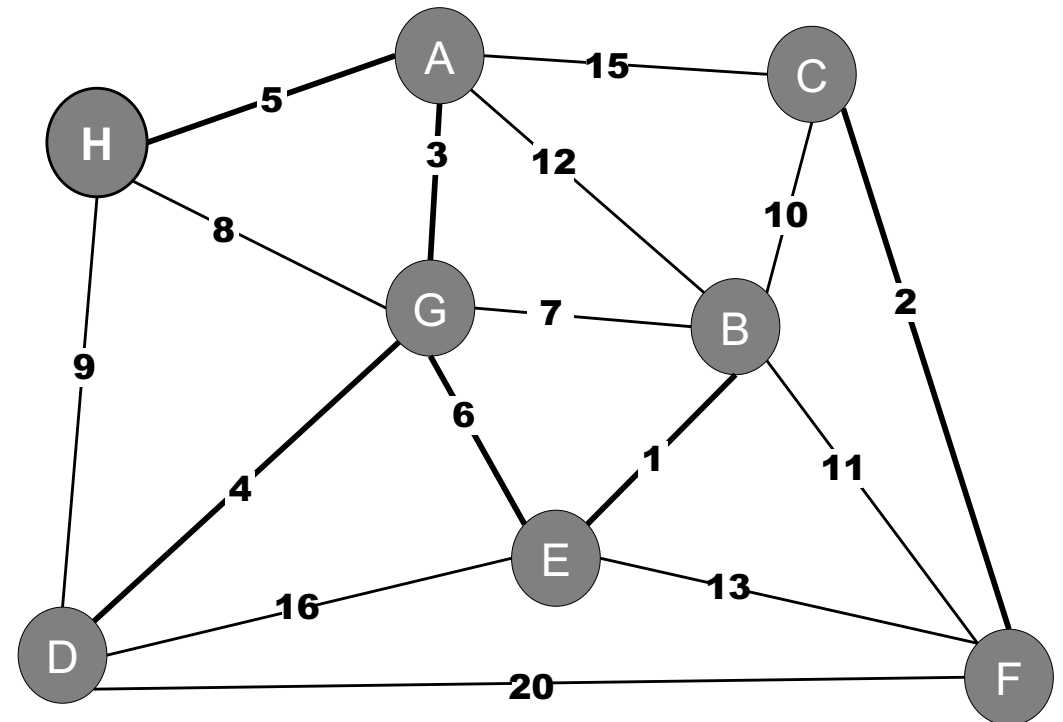
# Kruskal's Algorithm

---

## Kruskal's Algorithm. (Kruskal 1956)

Basic idea:

- Sort edges by weight from smallest to biggest.
- Consider edges in ascending order:
  - If both endpoints are in the **same** blue tree, then color the edge red.
  - Otherwise, color the edge blue.





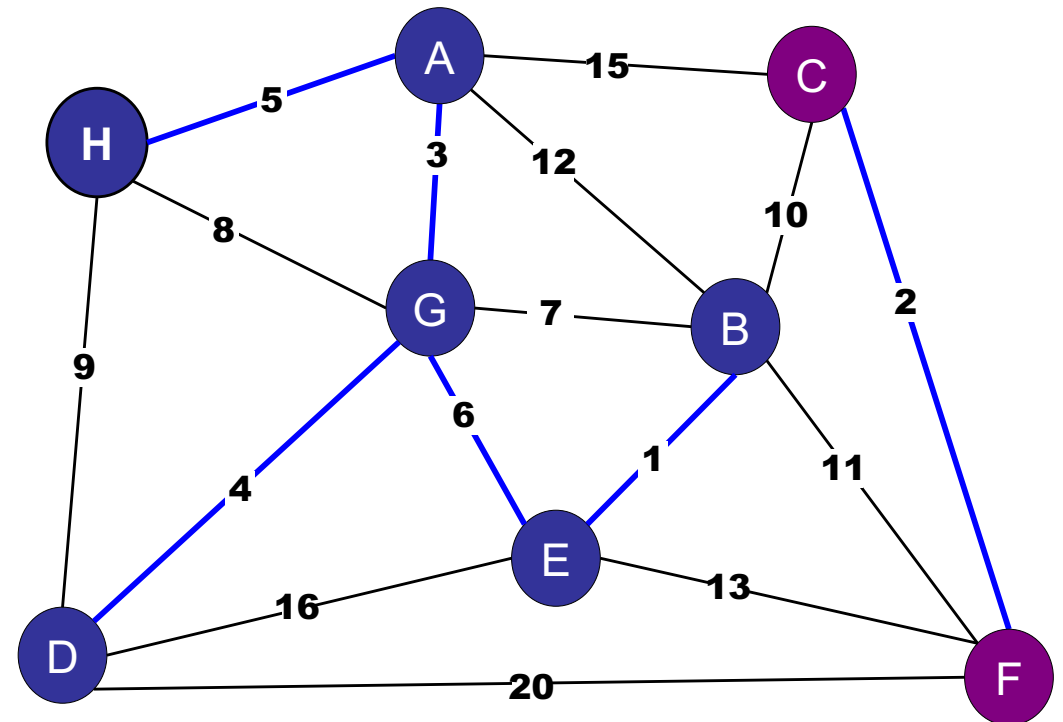
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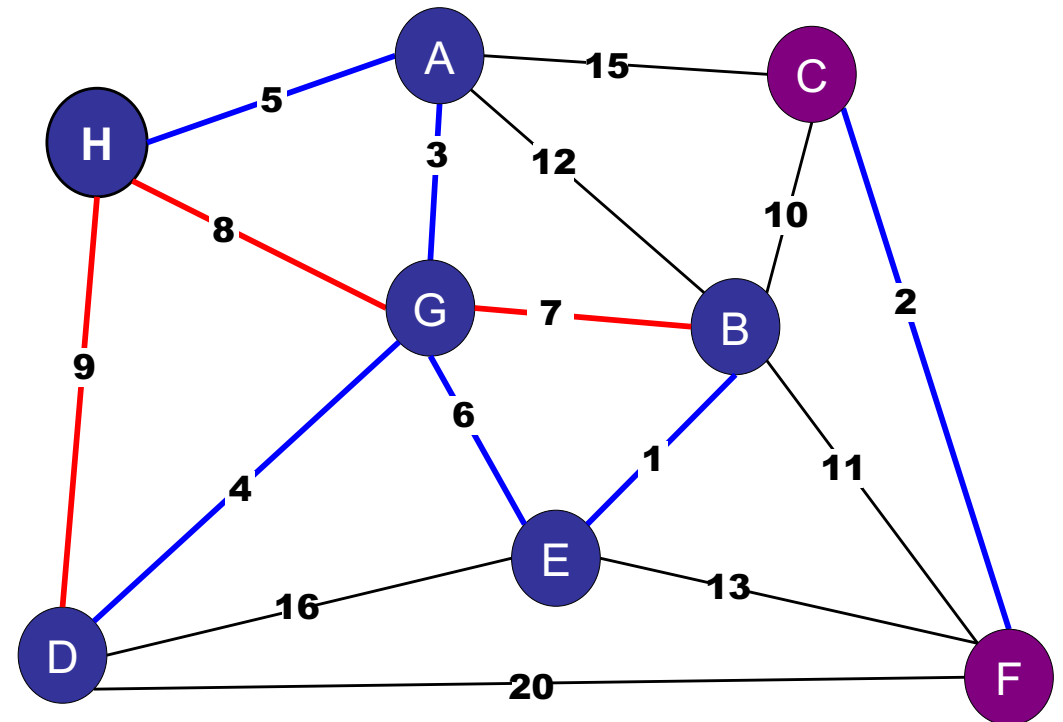
Must be the heaviest edge on the cycle!



## Kruskal's Algorithm. (Kruskal 1956)

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# Kruskal's Algorithm

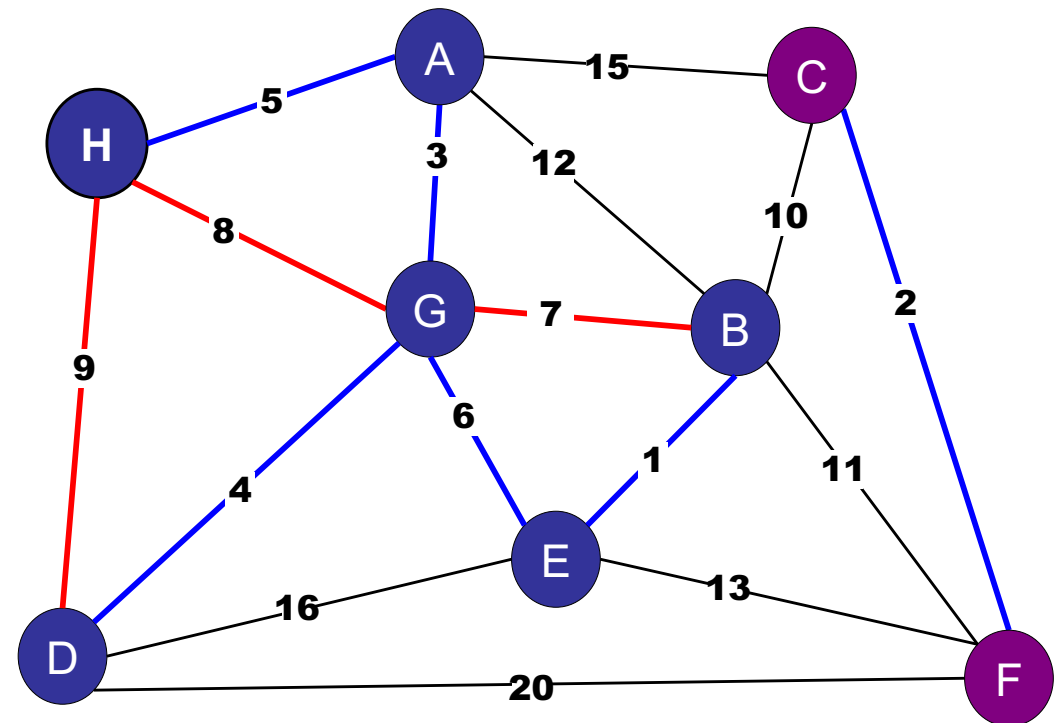
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Data structure:

- Union-Find
- Connect two nodes if they are in the same blue tree.



# Kruskal's Algorithm

---

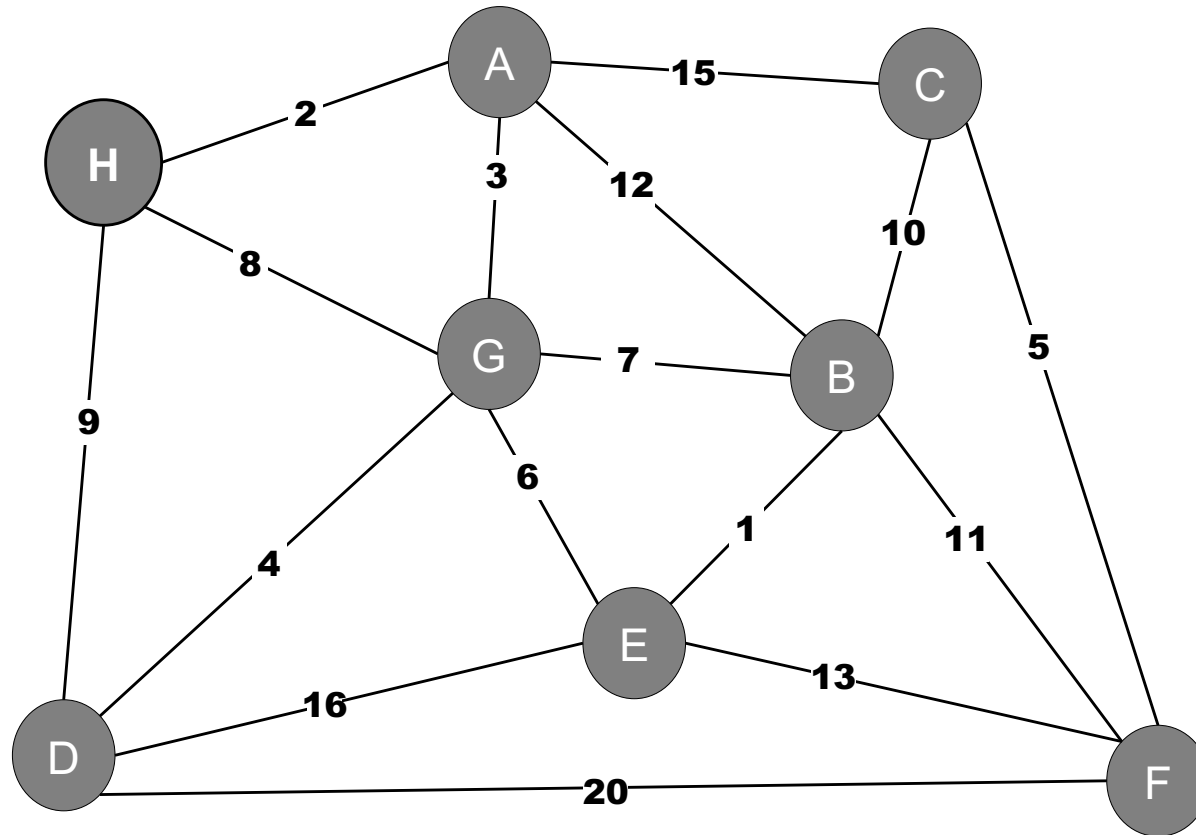
```
// Sort edges and initialize
Edge[] sortedEdges = sort(G.E());
ArrayList<Edge> mstEdges = new ArrayList<Edge>();
UnionFind uf = new UnionFind(G.V());

// Iterate through all the edges, in order
for (int i=0; i<sortedEdges.length; i++) {
    Edge e = sortedEdges[i]; // get edge
    Node v = e.one(); // get node endpoints
    Node w = e.two();

    if (!uf.find(v,w)) { // in the same tree?
        mstEdges.add(e); // save edge
        uf.union(v,w); // combine trees
    }
}
```

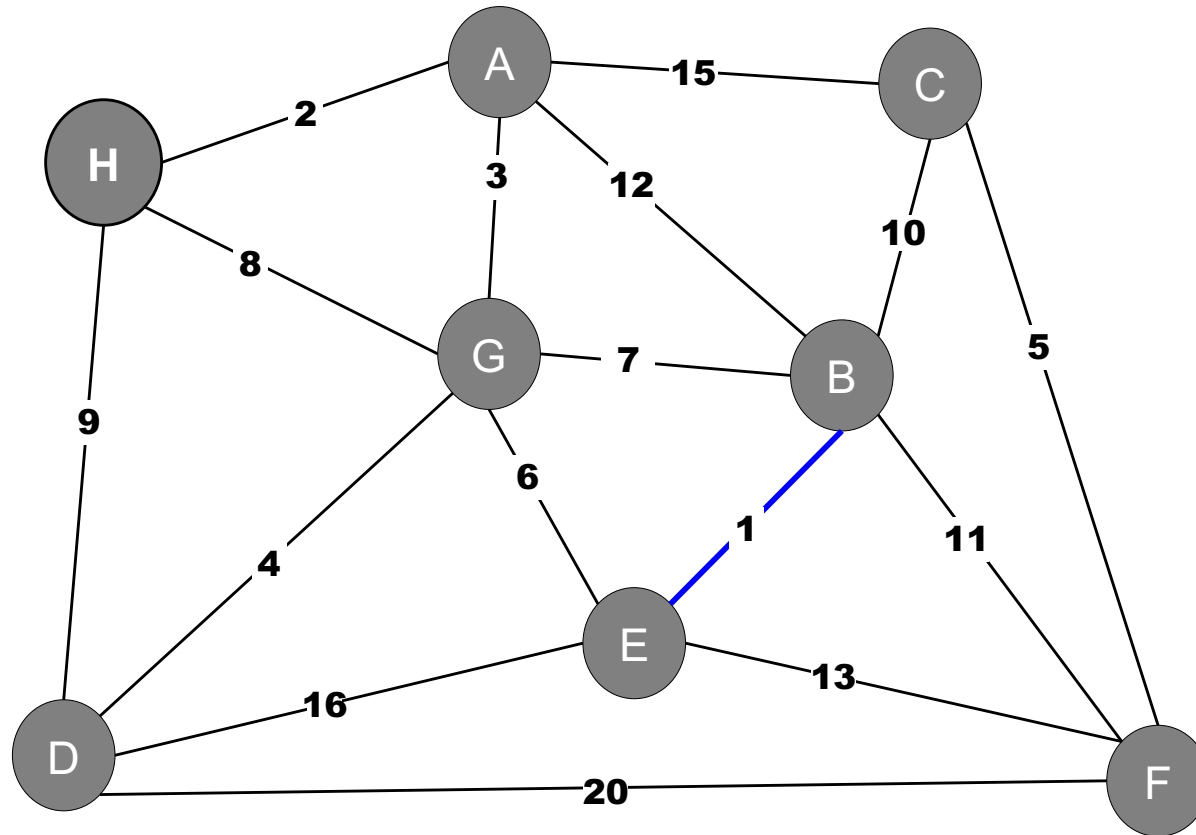
# Kruskal's Example

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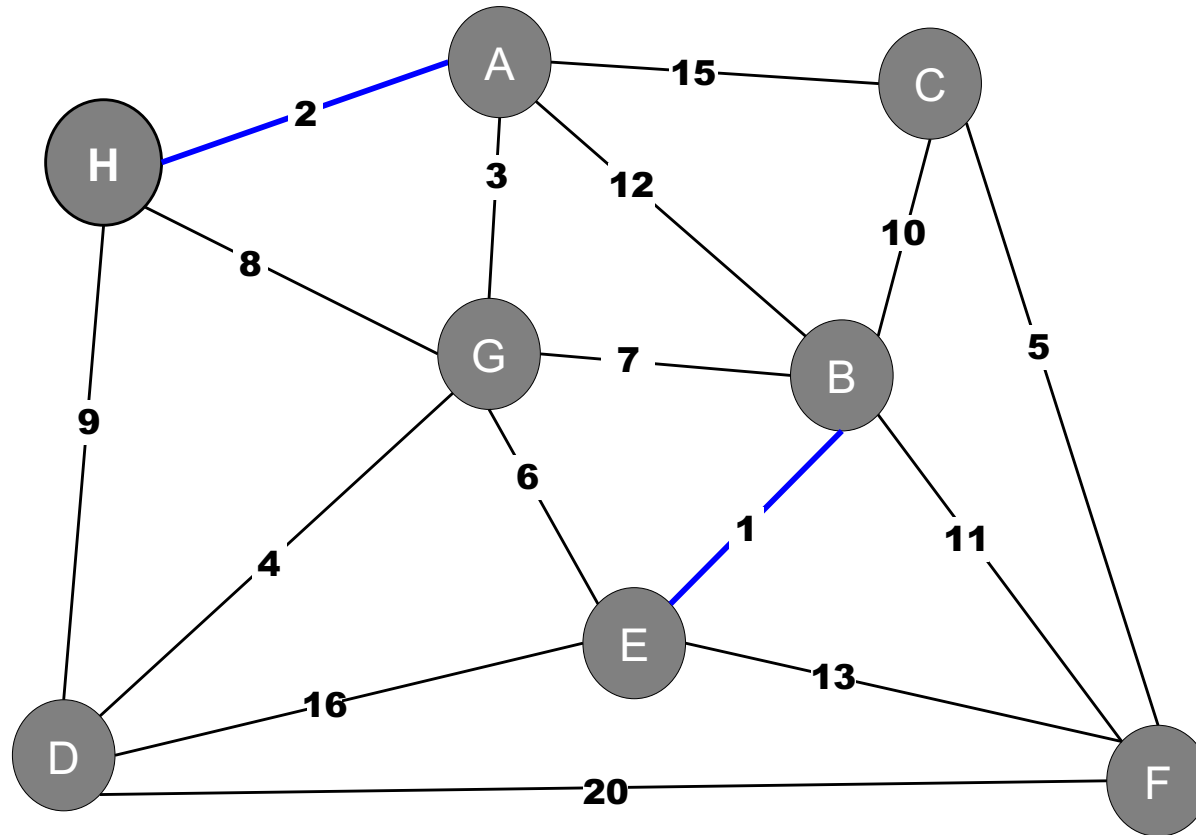
Weight	Edge
1	(E,B)
2	(C,F)
3	(A,G)
4	(D,G)
5	(C,F)
6	(E,G)
7	(B,G)
8	(G,H)
9	(D,G)
10	(B,C)
11	(B,F)
12	(A,B)
13	(E,F)
15	(A,C)
16	(D,E)
20	(D,F)

# Kruskal's Example



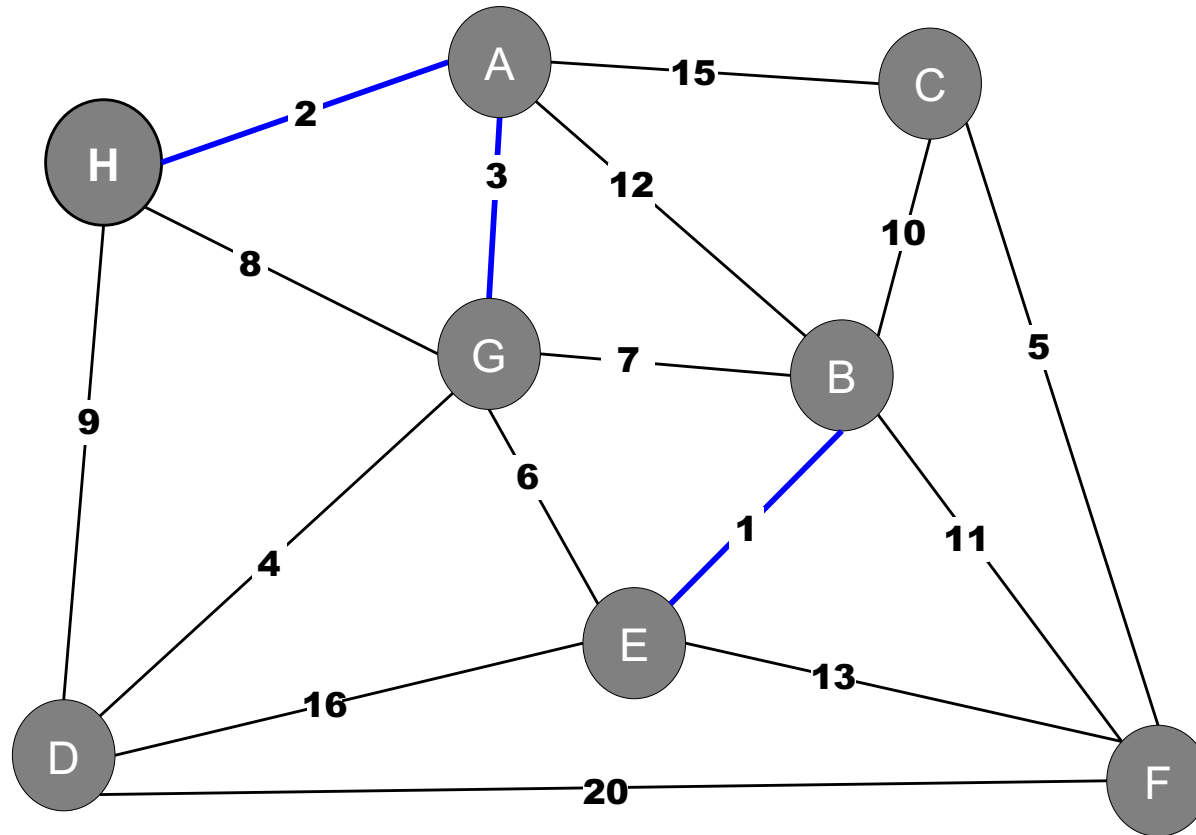
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# Kruskal's Example



Weight	Edge
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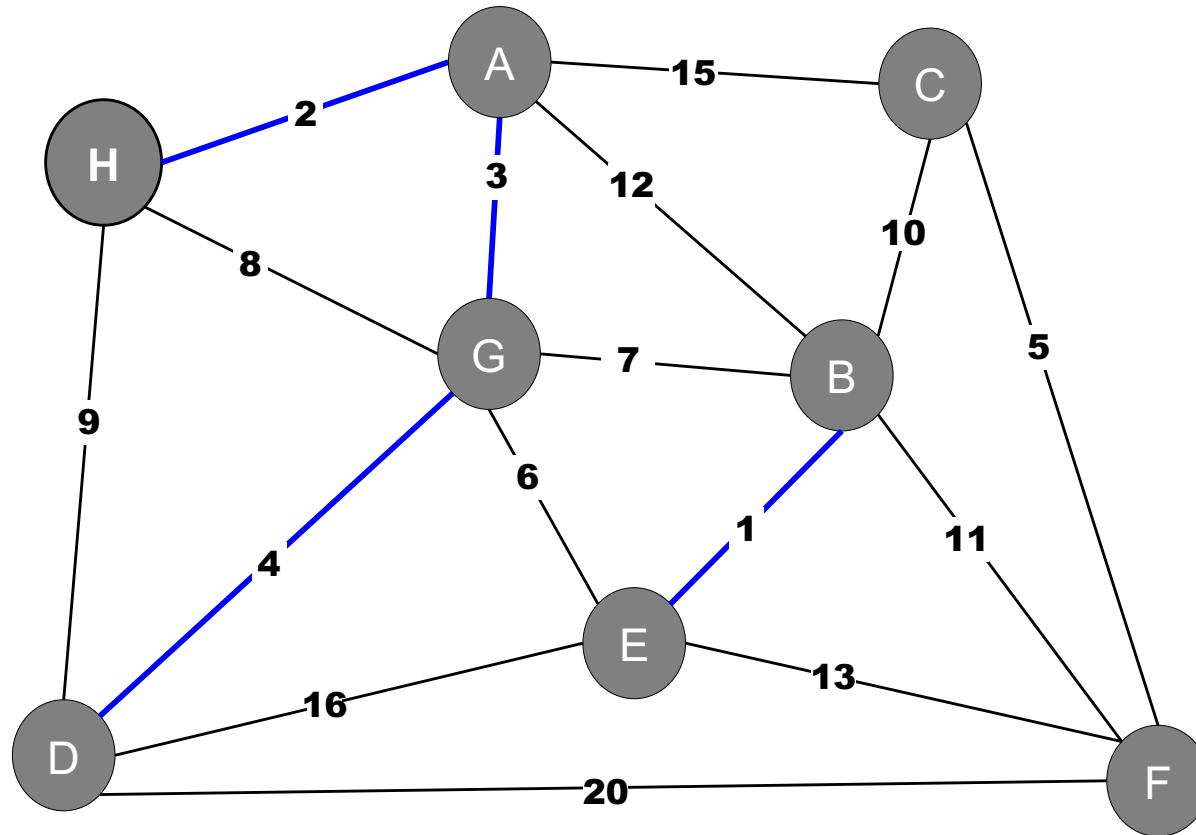
# Kruskal's Example



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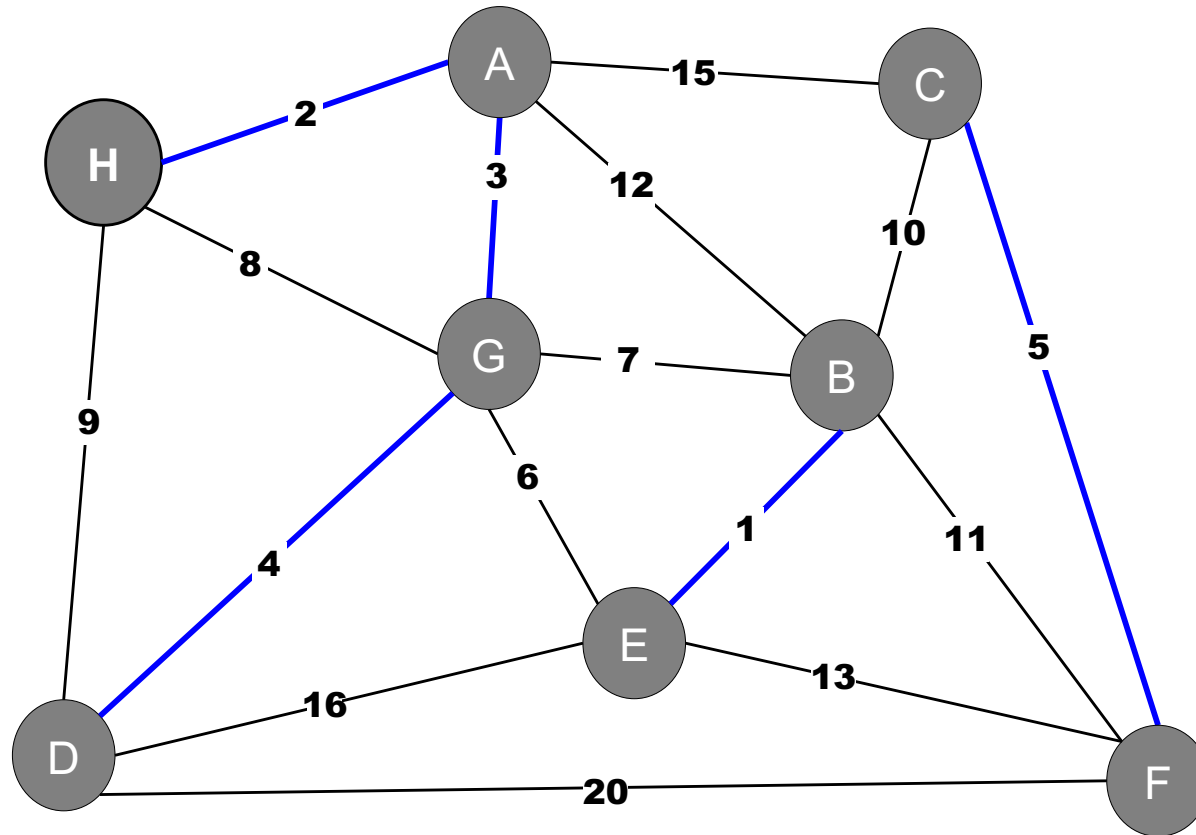


# Kruskal's Example



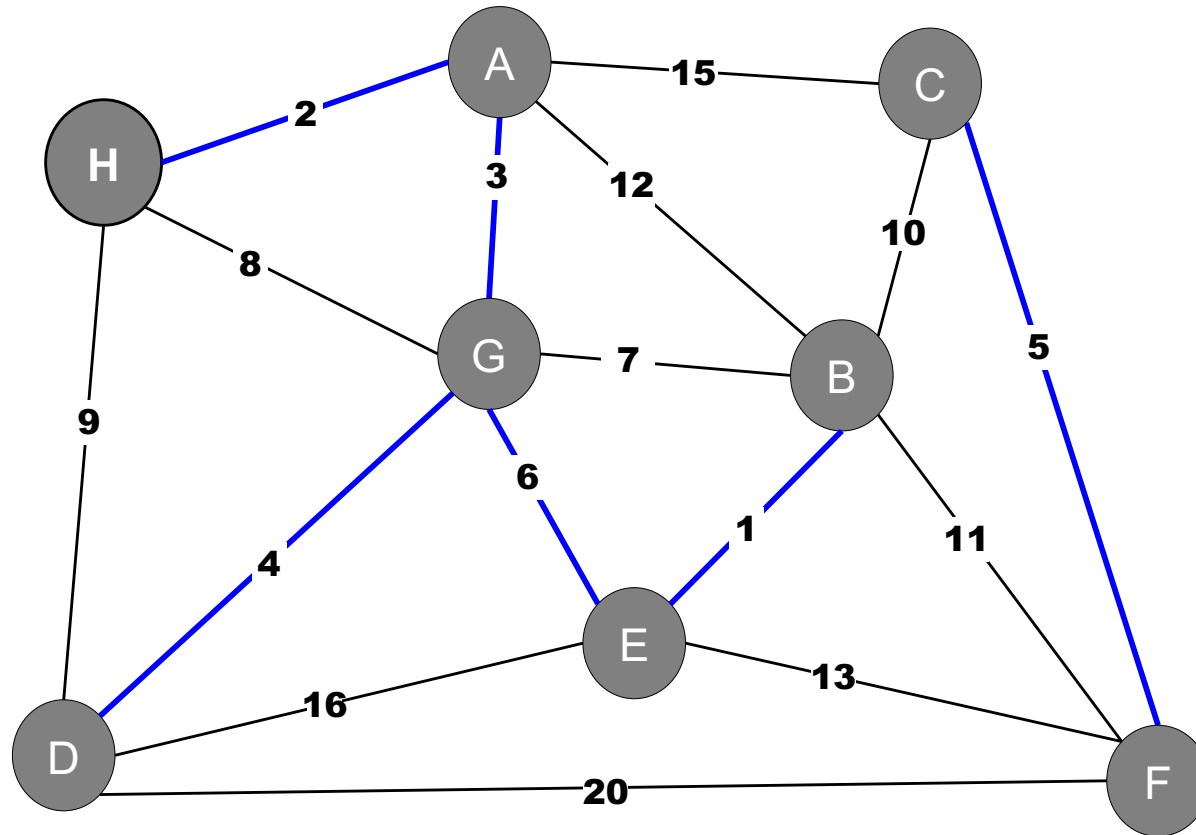
Weight	Edge
1	(E,B)
2	(C,F)
3	(A,G)
<b>4</b>	<b>(D,G)</b>
5	(C,F)
6	(E,G)
7	(B,G)
8	(G,H)
9	(D,G)
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# Kruskal's Example



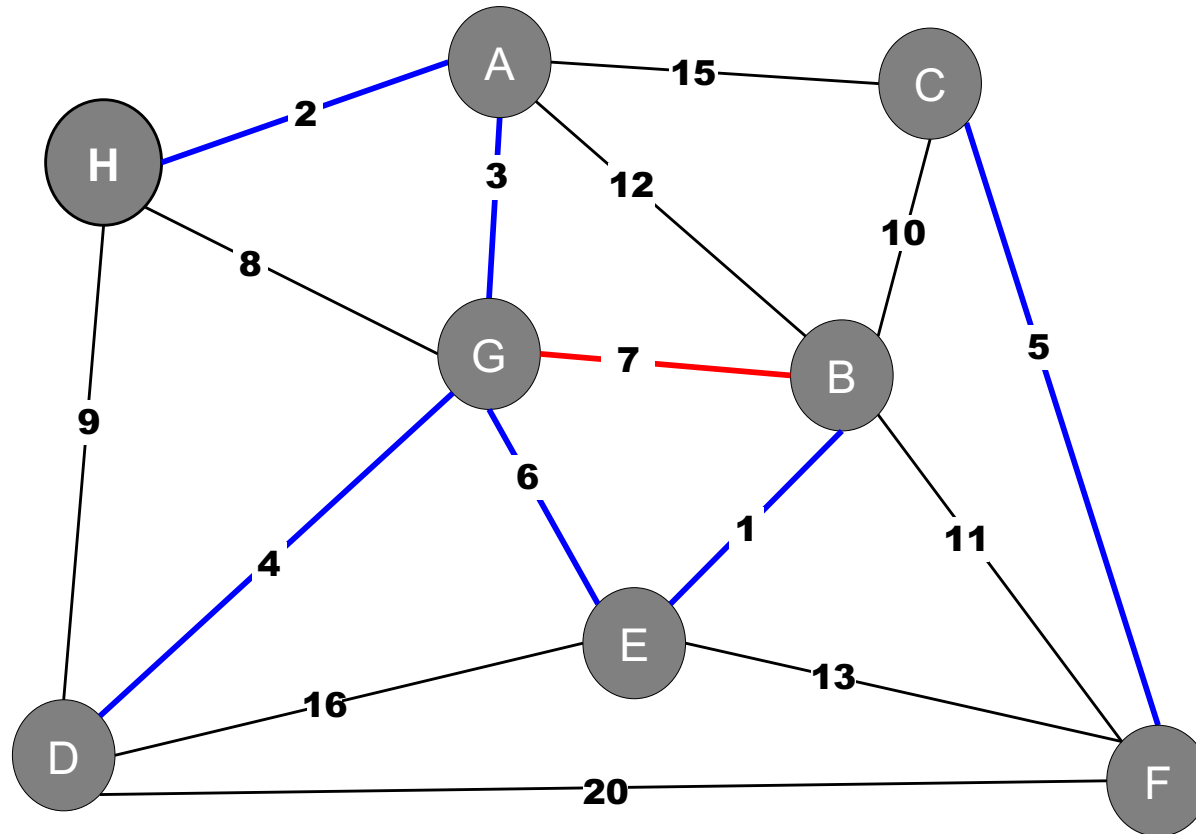
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# Kruskal's Example



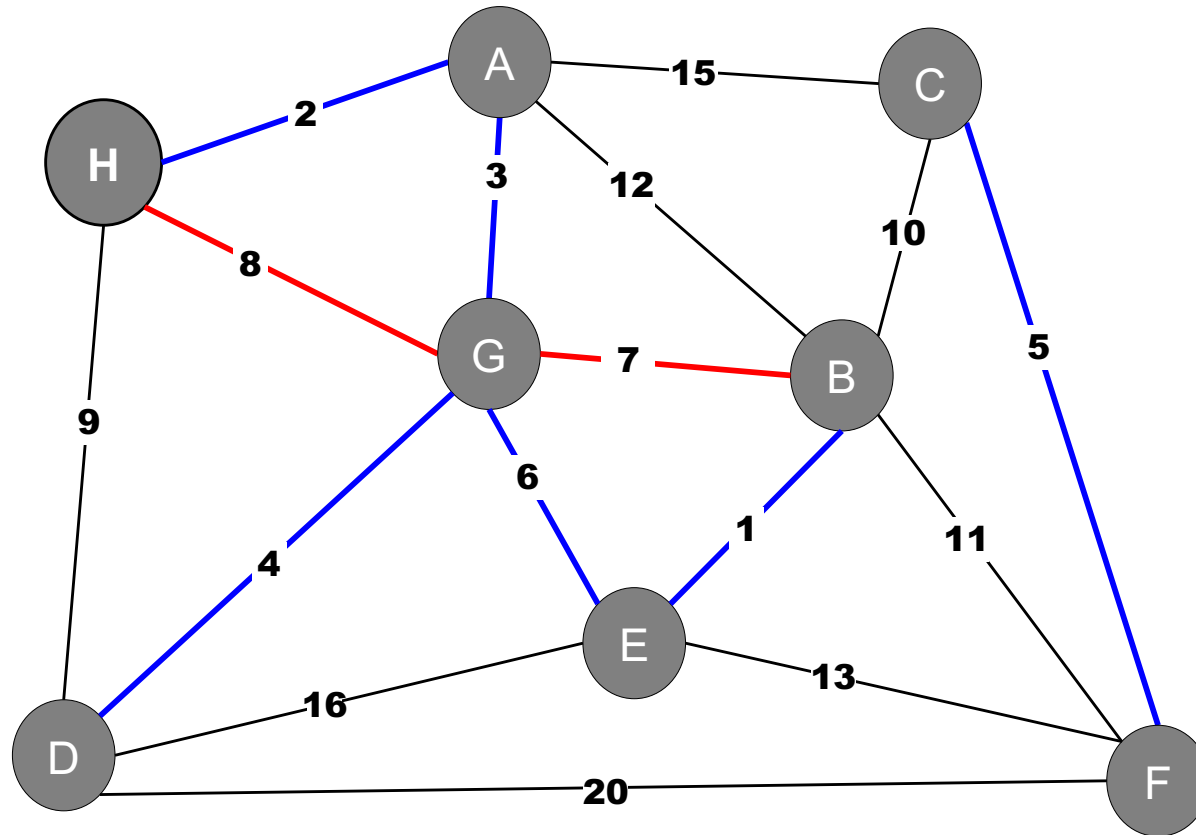
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13	(E,F)
15	(A,C)
16	(D,E)
20	(D,F)

# Kruskal's Example



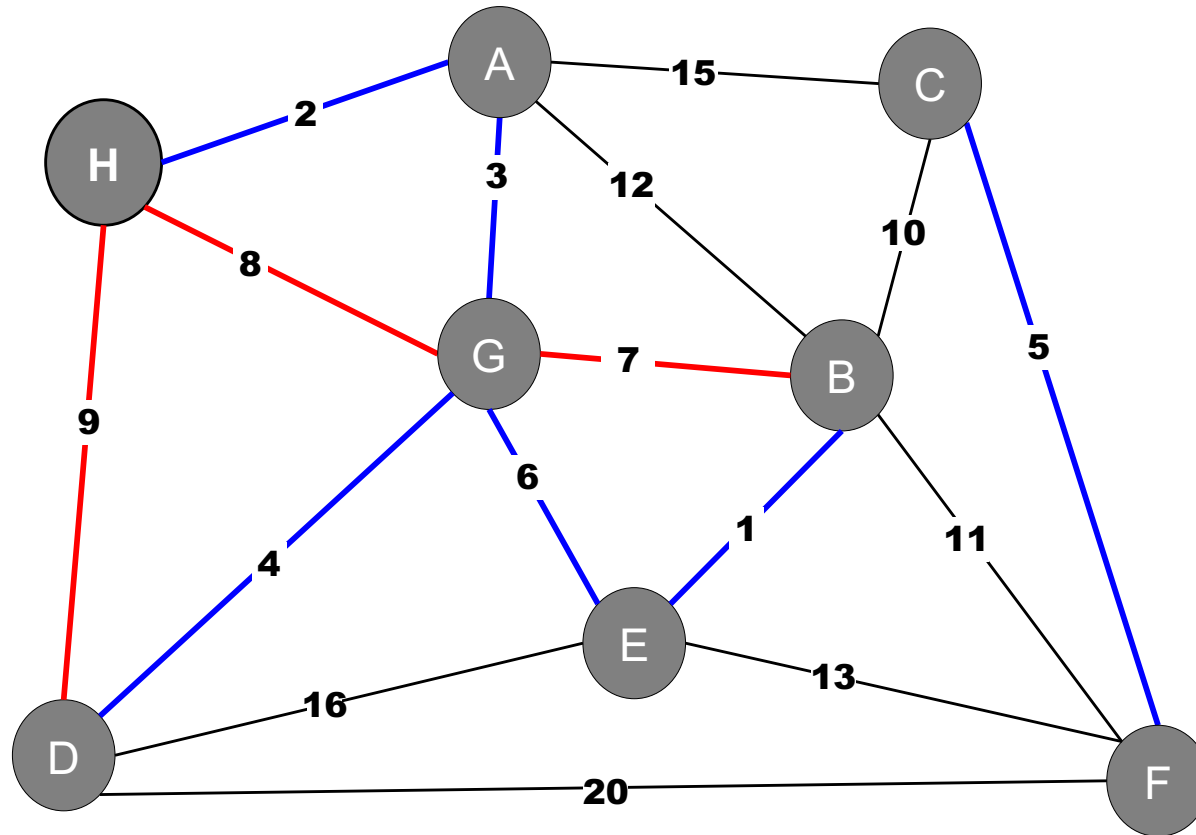
Weight	Edge
1	(E,B)
2	(C,F)
3	(A,G)
4	(D,G)
5	(C,F)
6	(E,G)
7	(B,G)
8	(G,H)
9	(D,G)
10	(B,C)
11	(B,F)
12	(A,B)
13	(E,F)
15	(A,C)
16	(D,E)
20	(D,F)

# Kruskal's Example



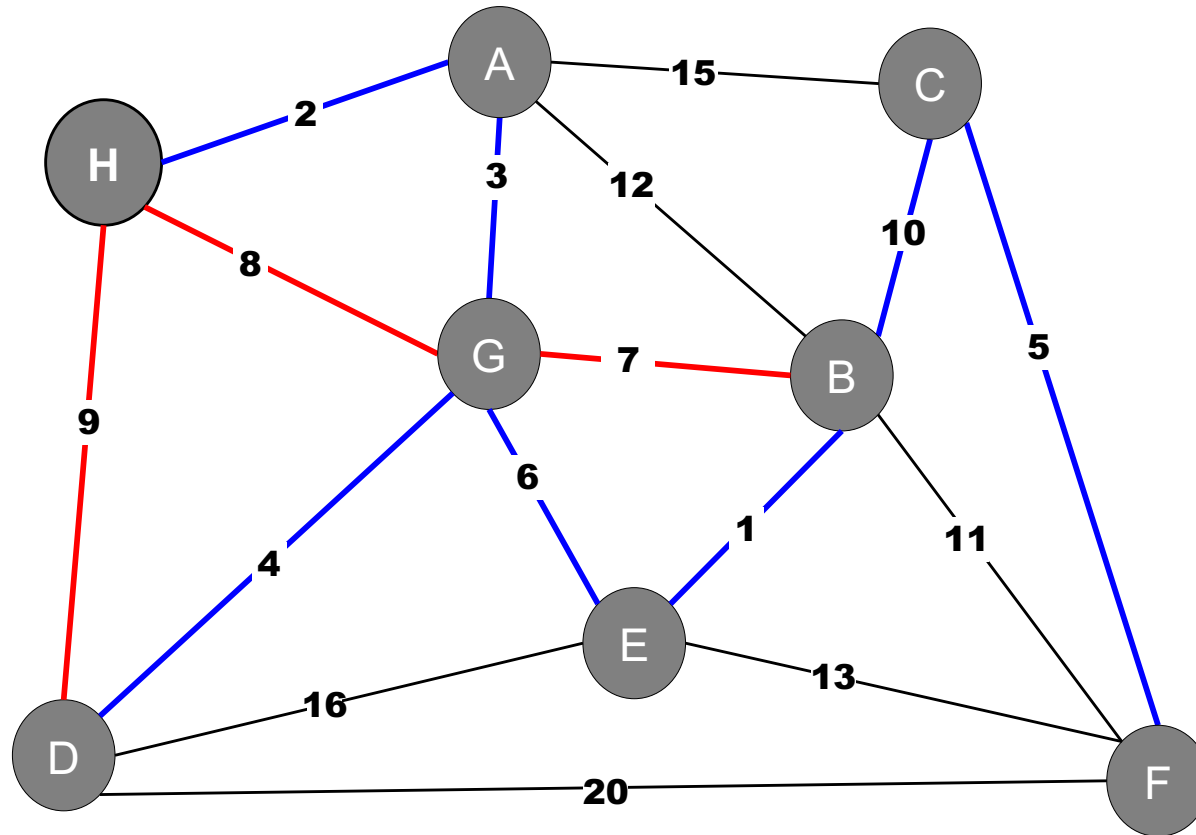
Weight	Edge
1	(E,B)
2	(C,F)
3	(A,G)
4	(D,G)
5	(C,F)
6	(E,G)
7	(B,G)
8	(G,H)
9	(D,G)
10	(B,C)
11	(B,F)
12	(A,B)
13	(E,F)
15	(A,C)
16	(D,E)
20	(D,F)

# Kruskal's Example



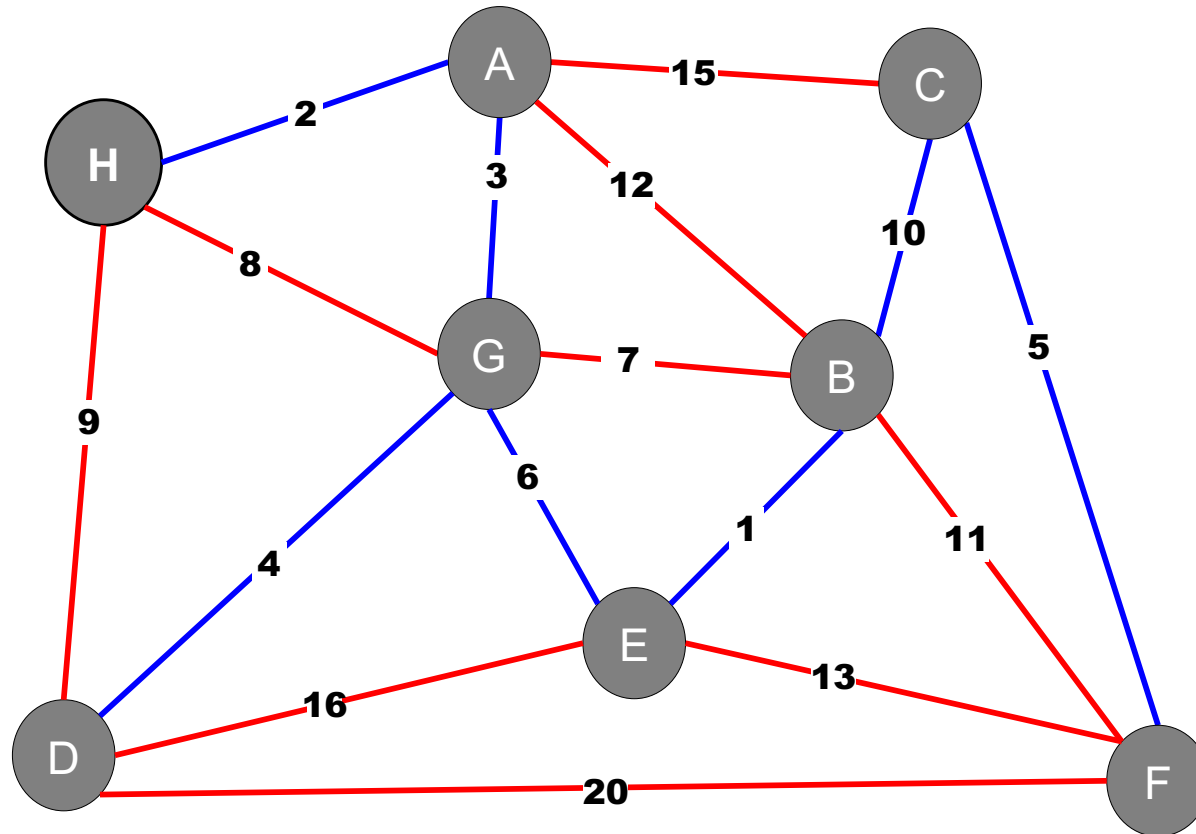
Weight	Edge
1	(E,B)
2	(C,F)
3	(A,G)
4	(D,G)
5	(C,F)
6	(E,G)
7	(B,G)
8	(G,H)
9	(D,G)
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11	(B,F)
12	(A,B)
13	(E,F)
15	(A,C)
16	(D,E)
20	(D,F)

# Kruskal's Example



Weight	Edge
1	(E,B)
2	(C,F)
3	(A,G)
4	(D,G)
5	(C,F)
6	(E,G)
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# Kruskal's Example



Weight	Edge
1	(E,B)
2	(C,F)
3	(A,G)
4	(D,G)
5	(C,F)
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10	(B,C)
11	(B,F)
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13	(E,F)
15	(A,C)
16	(D,E)
20	(D,F)



# Kruskal's Algorithm

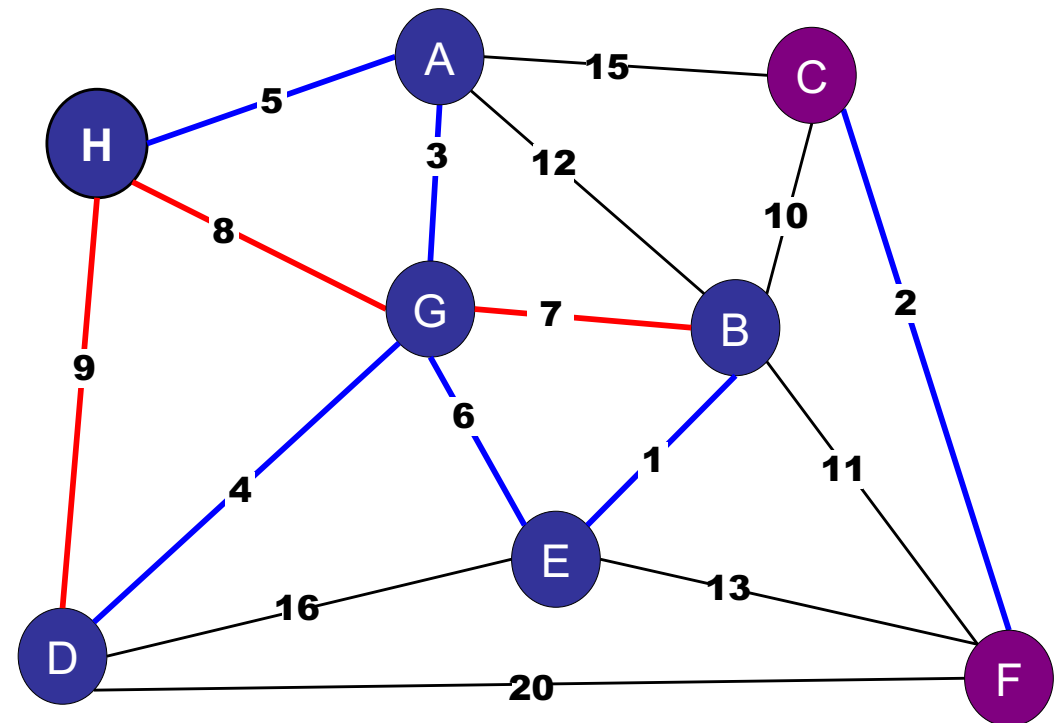
## Kruskal's Algorithm. (Kruskal 1956)

Basic idea:

- Sort edges by weight.
- Consider edges in ascending order:
  - If both endpoints are in the **same** blue tree, then color the edge red.
  - Otherwise, color the edge blue.

Proof:

- Each added edge crosses a cut.
- Each edge is the lightest edge across the cut: all other lighter edges across the cut have already been considered.



# Generic MST Algorithm

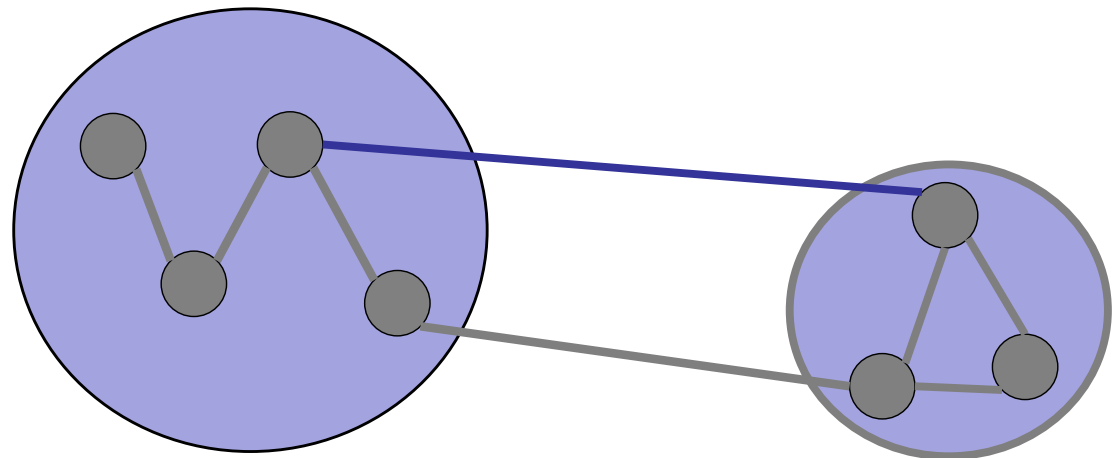
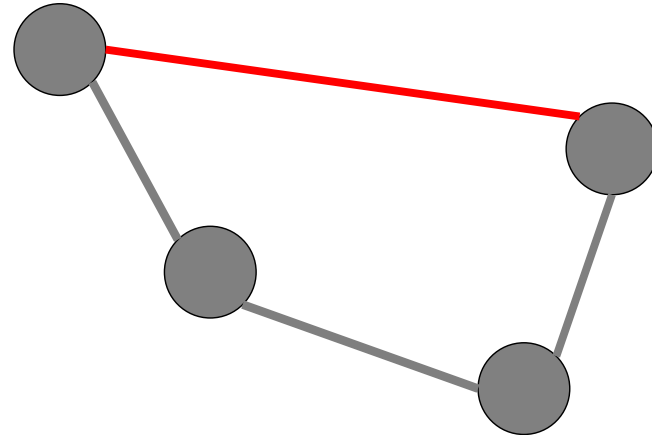
---

## Greedy Algorithm:

Repeat:

**Apply red rule or  
blue rule to an  
arbitrary edge.**

until no more edges  
can be colored.



What is the running time of Kruskal's Algorithm on a connected graph?

1.  $O(V)$
2.  $O(E)$
3.  $O(E \alpha)$
4.  $O(V \alpha)$
- ✓ 5.  $O(E \log V)$
6.  $O(V \log E)$

# Kruskal's Algorithm

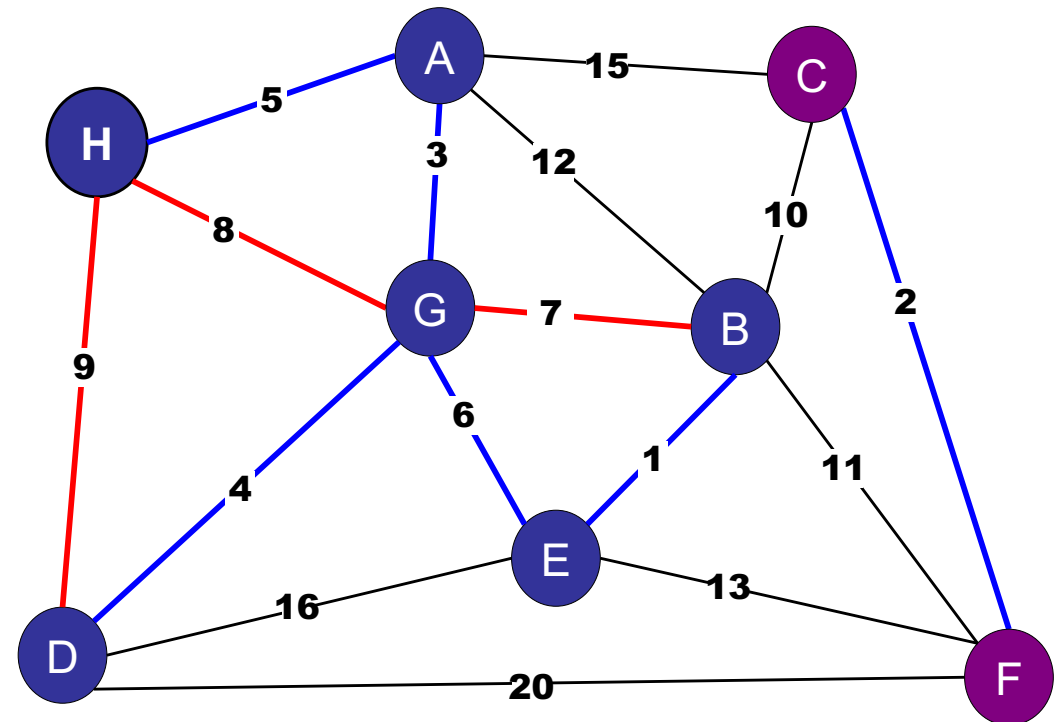
## Kruskal's Algorithm. (Kruskal 1956)

Basic idea:

- Sort edges by weight.
- Consider edges in ascending order:
  - If both endpoints are in the **same** blue tree, then color the edge red.
  - Otherwise, color the edge blue.

Performance:

- Sorting:  $O(E \log E) = O(E \log V)$
- For  $E$  edges:
  - Find:  $O(\alpha(n))$  or  $O(\log V)$
  - Union:  $O(\alpha(n))$  or  $O(\log V)$



# Roadmap

---

## Minimum Spanning Trees

- Prim's Algorithm
- Kruskal's Algorithm
- (Boruvka's Algorithm)

## Variations

- Constant weight edges
- Bounded integer edge weights
- Directed graphs
- Maximum Spanning Tree

# MST Variants

---

What if all the edges have the same weight?

# How fast can you find an MST?

1.  $O(V)$
- ✓ 2.  $O(E)$
3.  $O(E \log V)$
4.  $O(V \log E)$
5.  $O(VE)$

ARCHIPELAGO

is open

# MST Variants

---

What if all the edges have the same weight?

Depth-First-Search or Breadth-First-Search



If all edge-weights are 2, what is the **cost** of a MST?

1.  $V-1$
2.  $V$
- ✓ 3.  $2(V-1)$
4.  $2V$
5.  $E-V$
6.  $E$

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is open

# MST Variants

---

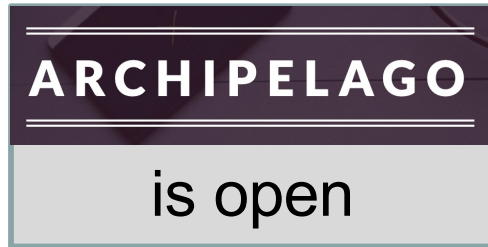
What if all the edges have the same weight?

- Depth-First-Search or Breadth-First-Search
- An MST contains exactly  $(V-1)$  edges.
- Every spanning tree contains  $(V-1)$  edges!
- Thus, any spanning tree you find with DFS/BFS is a minimum spanning tree.

# Kruskal's Variants

---

What if all the edges have weights from  $\{1..10\}$ ?

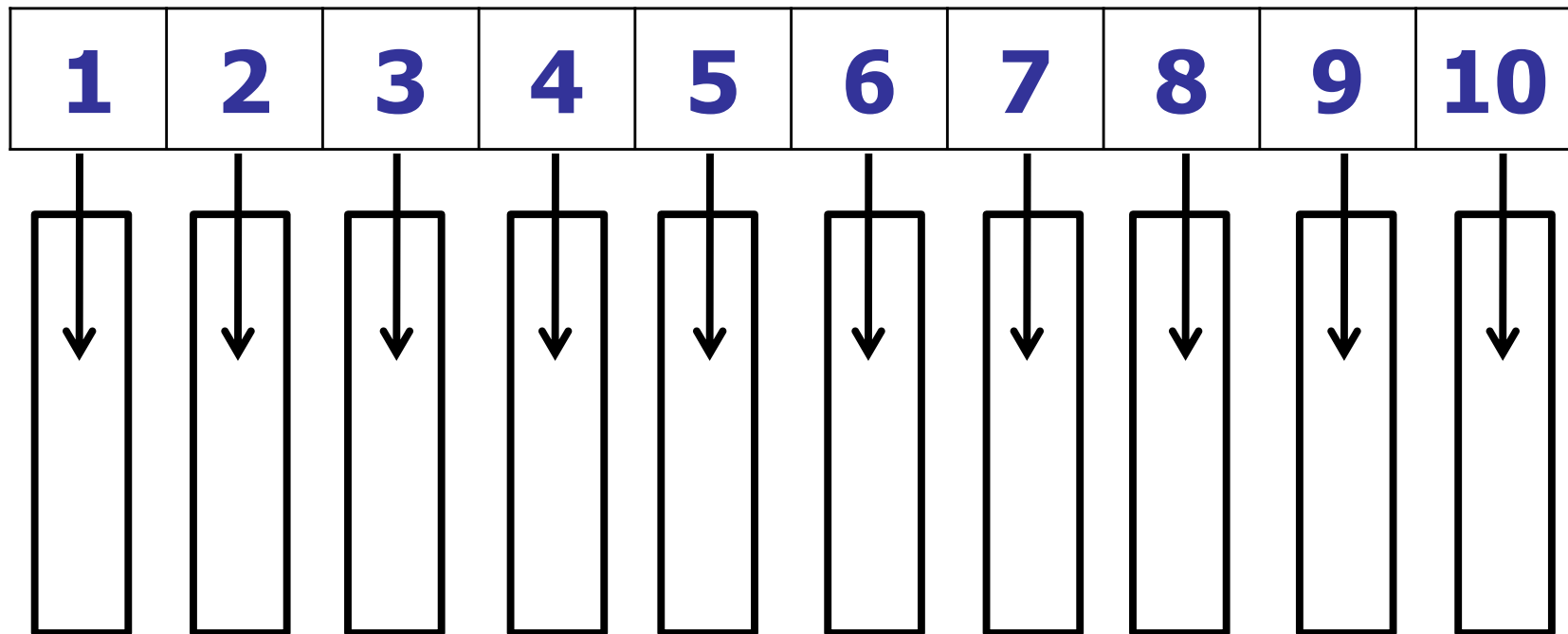


# Kruskal's Variants

---

What if all the edges have weights from  $\{1..10\}$ ?

Idea: Use an array of size 10 to sort



slot  $A[j]$  holds a linked list of edges of weight  $j$

# Kruskal's Variants

---

What if all the edges have weights from  $\{1..10\}$ ?

Idea: Use an array of size 10

- Putting edges in array of linked lists:  $O(E)$
- Iterating over all edges in ascending order:  $O(E)$
- For each edge:
  - Checking whether to add an edge:  $O(\alpha)$
  - Union two components:  $O(\alpha)$

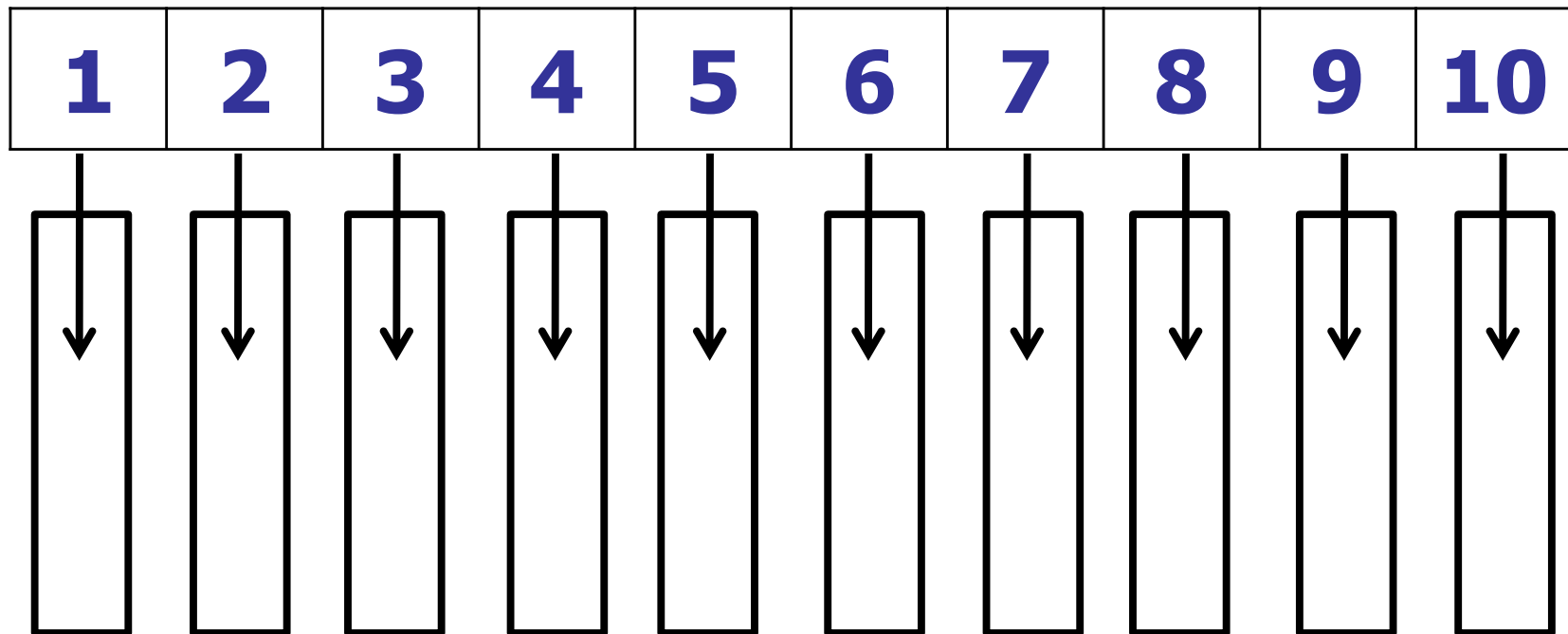
Total:  $O(\alpha E)$

# Prim's Variants

---

What if all the edges have weights from  $\{1..10\}$ ?

Idea: Use an array of size 10 as a Priority Queue



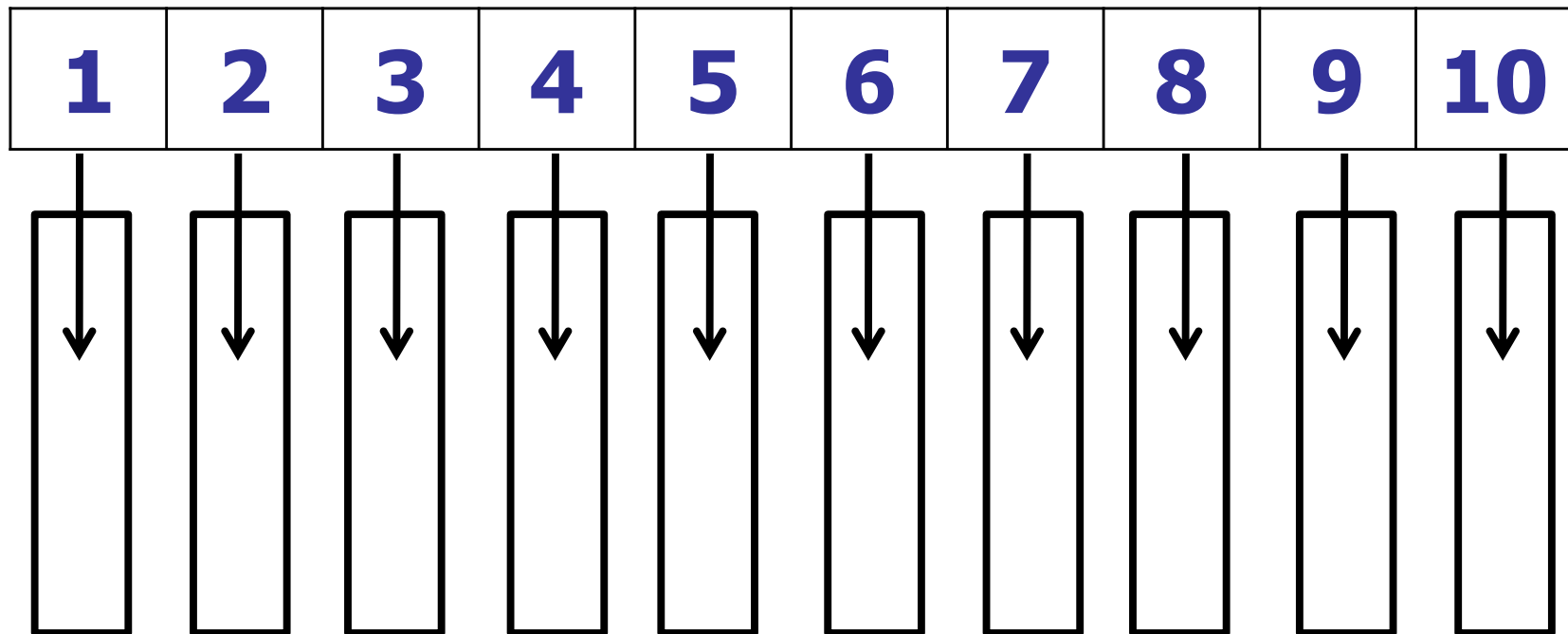
slot  $A[j]$  holds a linked list of **nodes** of weight  $j$

# Prim's Variants

---

What if all the edges have weights from  $\{1..10\}$ ?

Idea: Use an array of size 10 as a Priority Queue



decreaseKey: move node to new linked list

What is the running time of (modified)  
Prim's if all the edge weights are in  $\{1..10\}$ ?

1.  $O(V)$
- ✓ 2.  $O(E)$
3.  $O(E \log V)$
4.  $O(V \log E)$
5.  $O(EV)$

**ARCHIPELAGO**

is open



# Prim's Variants

---

What if all the edges have weights from  $\{1..10\}$ ?

Implement Priority Queue:

- Use an array of size 10 to implement
- Insert: put node in correct list
- Remove: lookup node (e.g., in hash table) and remove from liked list.
- ExtractMin: Remove from the minimum bucket.
- DecreaseKey: lookup node (e.g., in hash table) and move to correct liked list.

# Prim's Variants

---

What if all the edges have weights from  $\{1..10\}$ ?

Idea: Use an array of size 10

- Inserting/Removing nodes from PQ:  $O(V)$
- decreaseKey:  $O(E)$

Total:  $O(V + E) = O(E)$

# Prim's Variants

---

What if all the edges have weights from  $\{1..10\}$ ?

Implement Priority Queue....

Why does this fail for Dijkstra's Algorithm?

# Roadmap

---

## Minimum Spanning Trees

- Prim's Algorithm
- Kruskal's Algorithm
- (Boruvka's Algorithm)

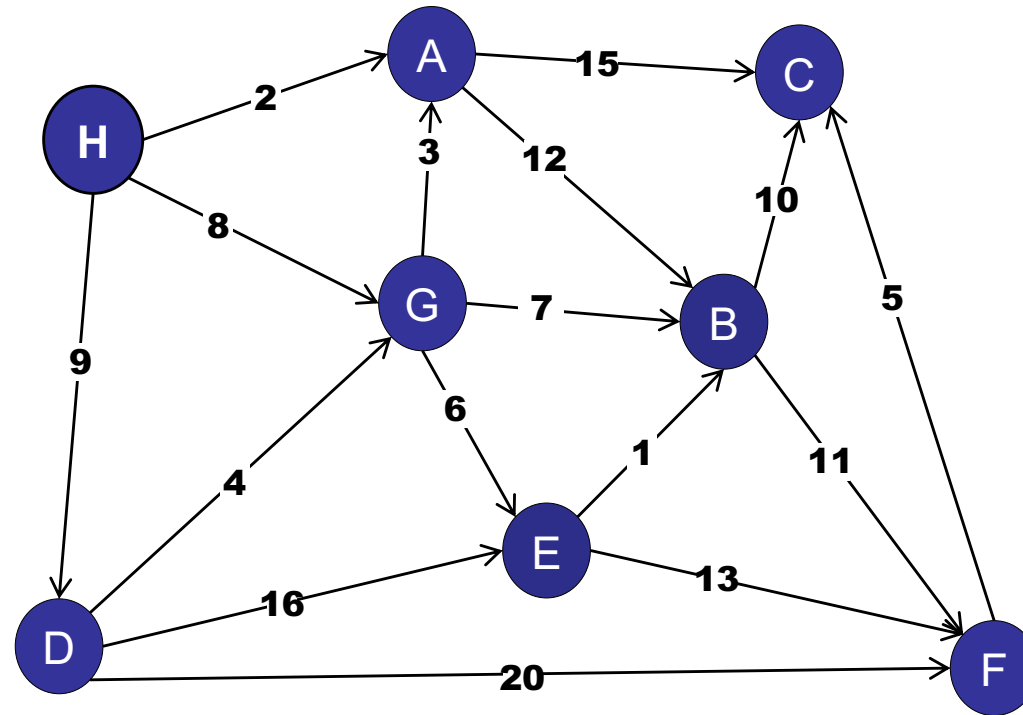
## Variations:

- Constant weight edges
- Bounded integer edge weights
- Directed graphs
- Maximum Spanning Tree

# Directed Minimum Spanning Tree

---

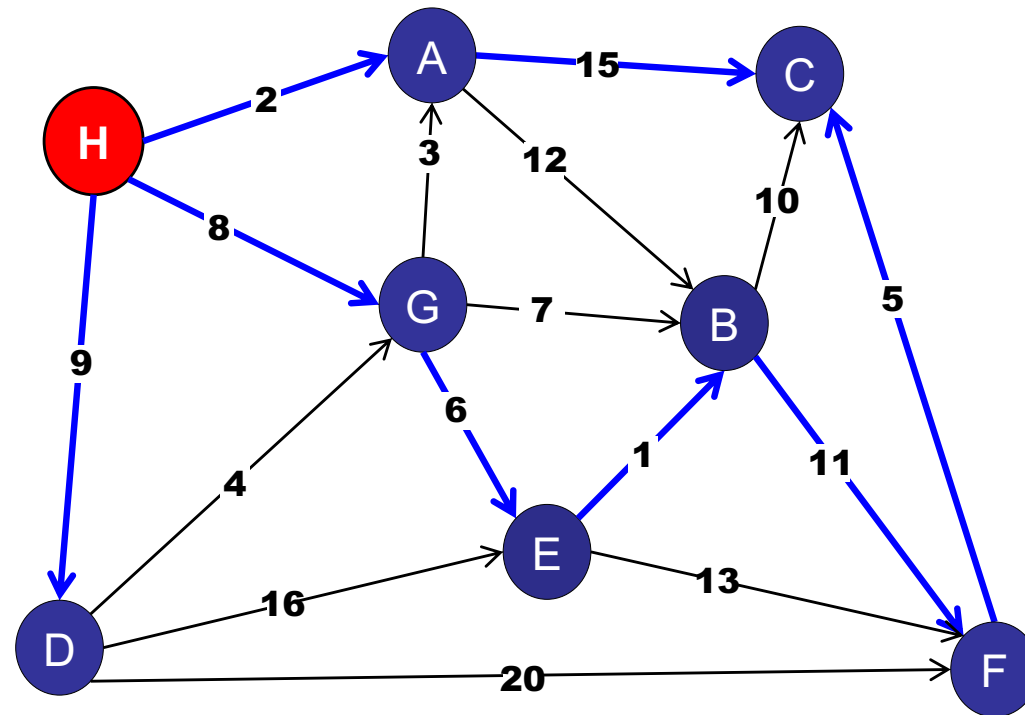
What if the edges are directed?



# Directed Minimum Spanning Tree

---

A rooted spanning tree:



Every node is reachable on a path from the root.

No cycles.

# Directed Minimum Spanning Tree

---

## Harder problem:

- Cut property does not hold.
- Cycle property does not hold.
- Generic MST algorithm does not work.

Prim's, Kruskal's, Boruvka's do not work.

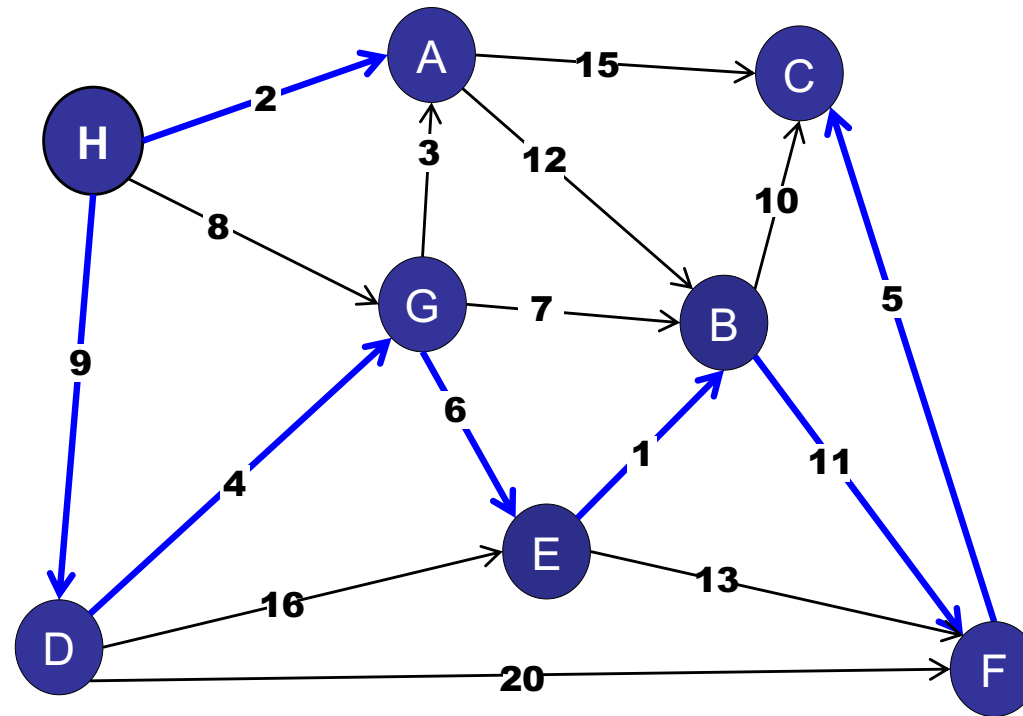
See CS3230 / CS4234 for more details...

**Exercise:** Draw a directed graph where the cut property or cycle property is violated.

# Directed Minimum Spanning Tree

---

Special case: a directed acyclic graph with one "root":



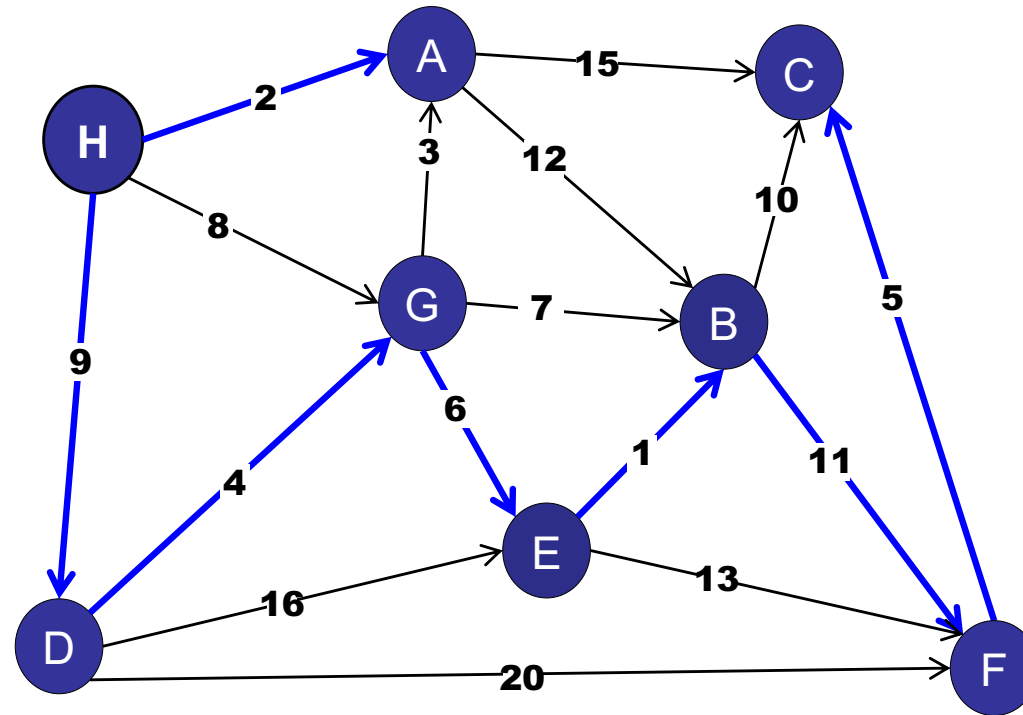


# Directed Minimum Spanning Tree

---

For a directed acyclic graph with one “root”:

For every node except the root: add minimum weight incoming edge.



# Directed Minimum Spanning Tree

---

For a directed acyclic graph with one “root”:

For every node except the root: add minimum weight incoming edge.

## Observations:

- No cycles (since acyclic graph).
- Each edge is chosen only once.

Tree:

$V$  nodes  
 $V - 1$  edges  
No cycles



# Directed Minimum Spanning Tree

---

For a directed acyclic graph with one “root”:

For every node except the root: add minimum weight incoming edge.

## Observations:

- No cycles (since acyclic graph).
- Each edge is chosen only once.
- Every node has to have at least one incoming edge in the MST, so this is the minimum spanning tree.

Tree:

$V$  nodes  
 $V - 1$  edges  
No cycles



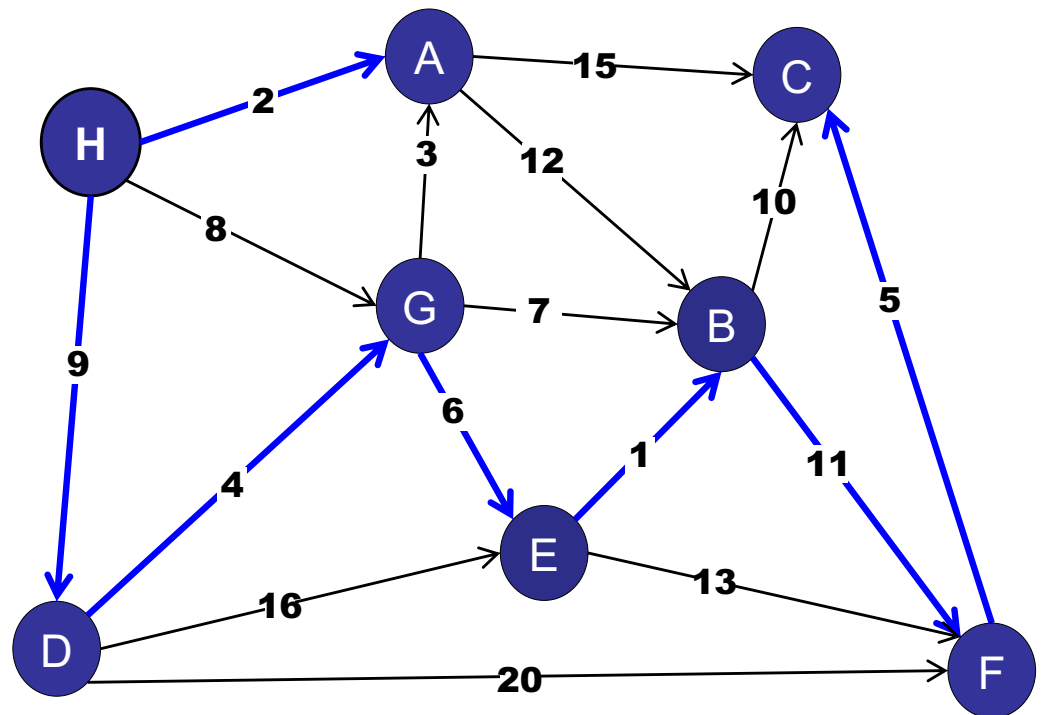
# Directed Minimum Spanning Tree

For a directed acyclic graph with one “root”:

For every node except the root: add minimum weight incoming edge.

Conclusion: Minimum Spanning Tree

$O(E)$  time



# Maximum Spanning Tree

---

A MaxST is a spanning tree of maximum weight.

How do you find a MaxST?

# Maximum Spanning Tree

---

Reweighting a spanning tree:

- What happens if you add a constant  $k$  to the weight of every edge?



# Kruskal's Algorithm

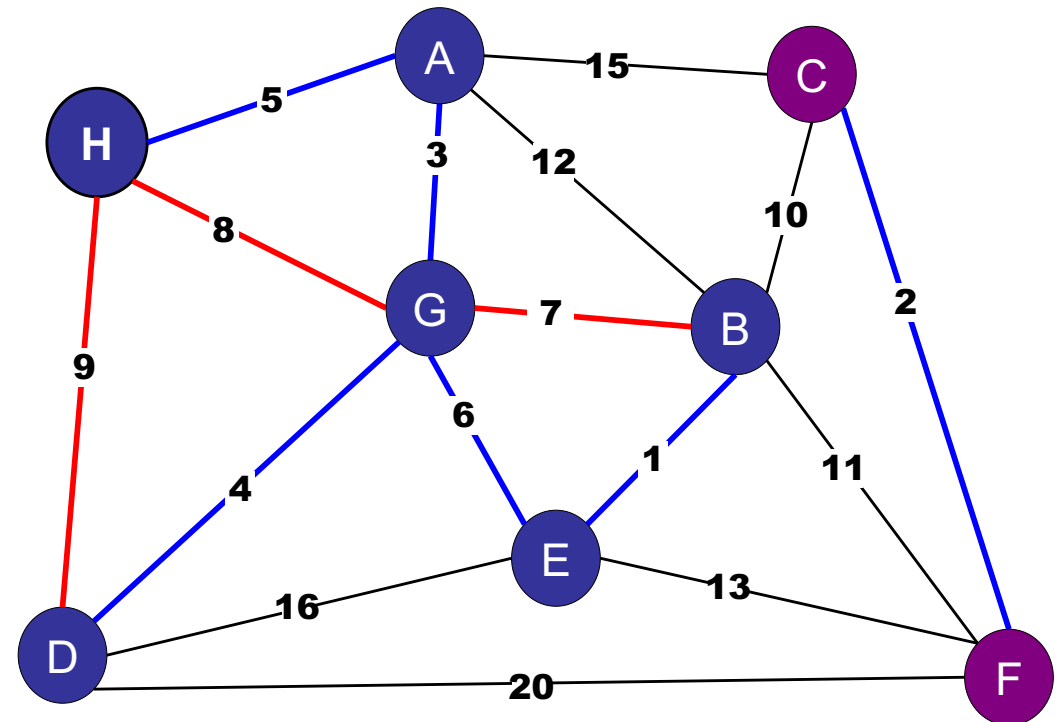
## Kruskal's Algorithm. (Kruskal 1956)

Basic idea:

- Sort edges by weight.
- Consider edges in ascending order:
  - If both endpoints are in the **same** blue tree, then color the edge red.
  - Otherwise, color the edge blue.

What matters?

- Relative edge weights.
- Absolute edge weights have no impact.

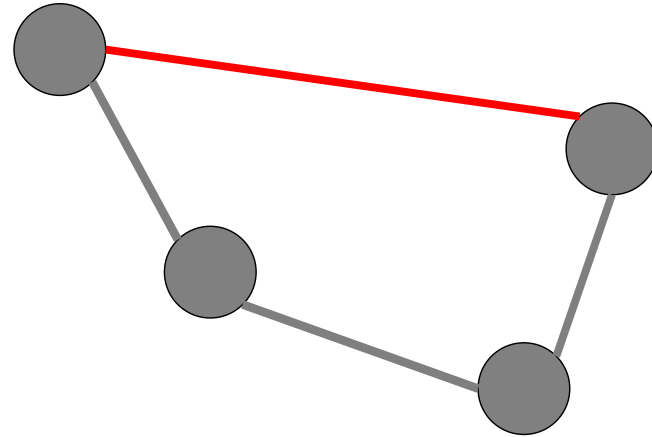


# Generic MST Algorithm

---

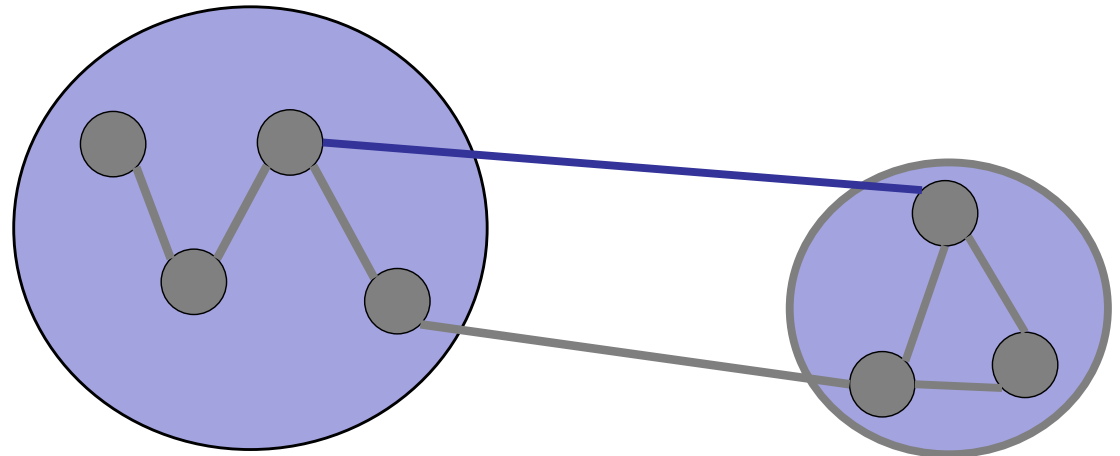
## **Red** rule:

If  $C$  is a cycle with no red arcs, then color the max-weight edge in  $C$  red.



## **Blue** rule:

If  $D$  is a cut with no blue arcs, then color the min-weight edge in  $D$  blue.





# Maximum Spanning Tree

---

Reweighting a spanning tree:

- What happens if you add a constant  $k$  to the weight of every edge?

No change!

We can add or subtract weights without effecting the MST.

(Very *different* from shortest paths...)

# Maximum Spanning Tree

---

MST with negative weights?

# Maximum Spanning Tree

---

MST with negative weights?

No problem!

1. Reweight MST by adding a big enough value to each edge so that it is positive.
2. Actually, no need to reweight. Only relative edge weights matter, so negative weights have no bad impact.

# Maximum Spanning Tree

---

A MaxST is a spanning tree of maximum weight.

How do you find a MaxST?

Easy!

1. Multiply each edge weight by -1.
2. Run MST algorithm.
3. MST that is “most negative” is the maximum.

# Maximum Spanning Tree

---

A MaxST is a spanning tree of maximum weight.

How do you find a MaxST?

Or... run Kruskal's in reverse.

# Roadmap

---

## Minimum Spanning Trees

- The MST Problem
- Basic Properties of an MST
- Generic MST Algorithm
- Prim's Algorithm
- Kruskal's Algorithm
- Variations
- **Boruvka's Algorithm**

# MST Algorithms

---

## Classic:

- Prim's Algorithm
- Kruskal's Algorithm

## Modern requirements:

- Parallelizable
- Faster in “good” graphs (e.g., planar graphs)
- Flexible

# Boruvka's Algorithm

---

Origin: 1926

- Otakar Boruvka
- Improve the electrical network of Moravia

Based on generic algorithm:

- Repeat: add all “obvious” blue edges.
- Very simple, very flexible.



# Generic MST Algorithm

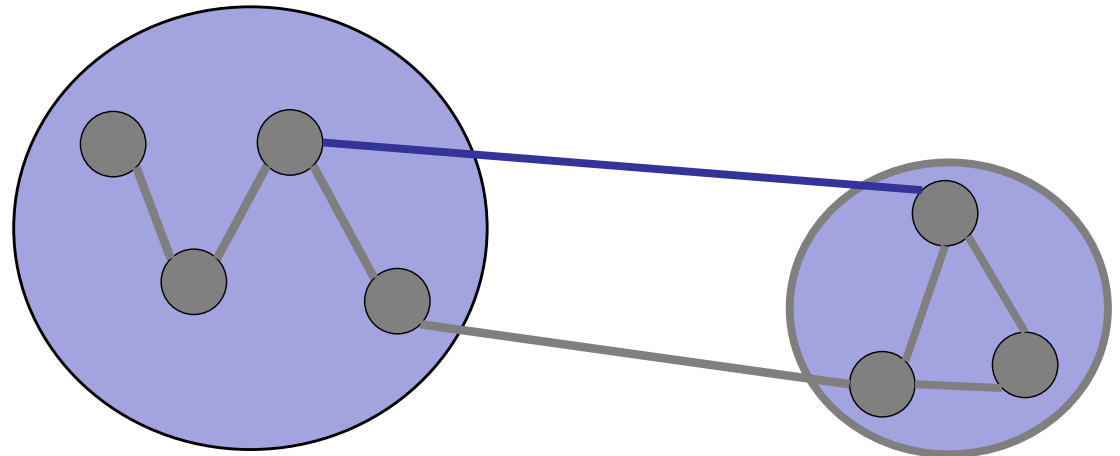
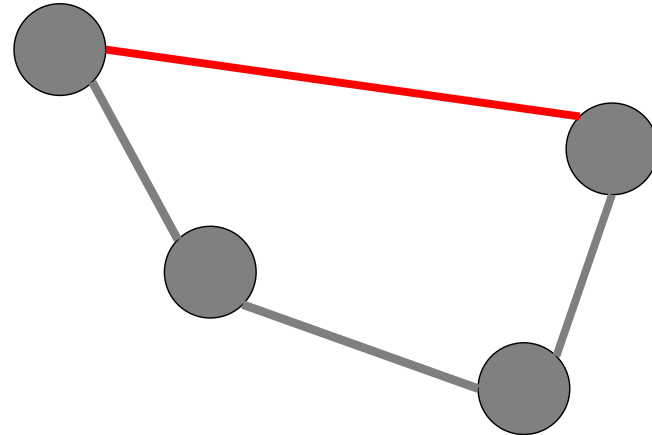
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## Greedy Algorithm:

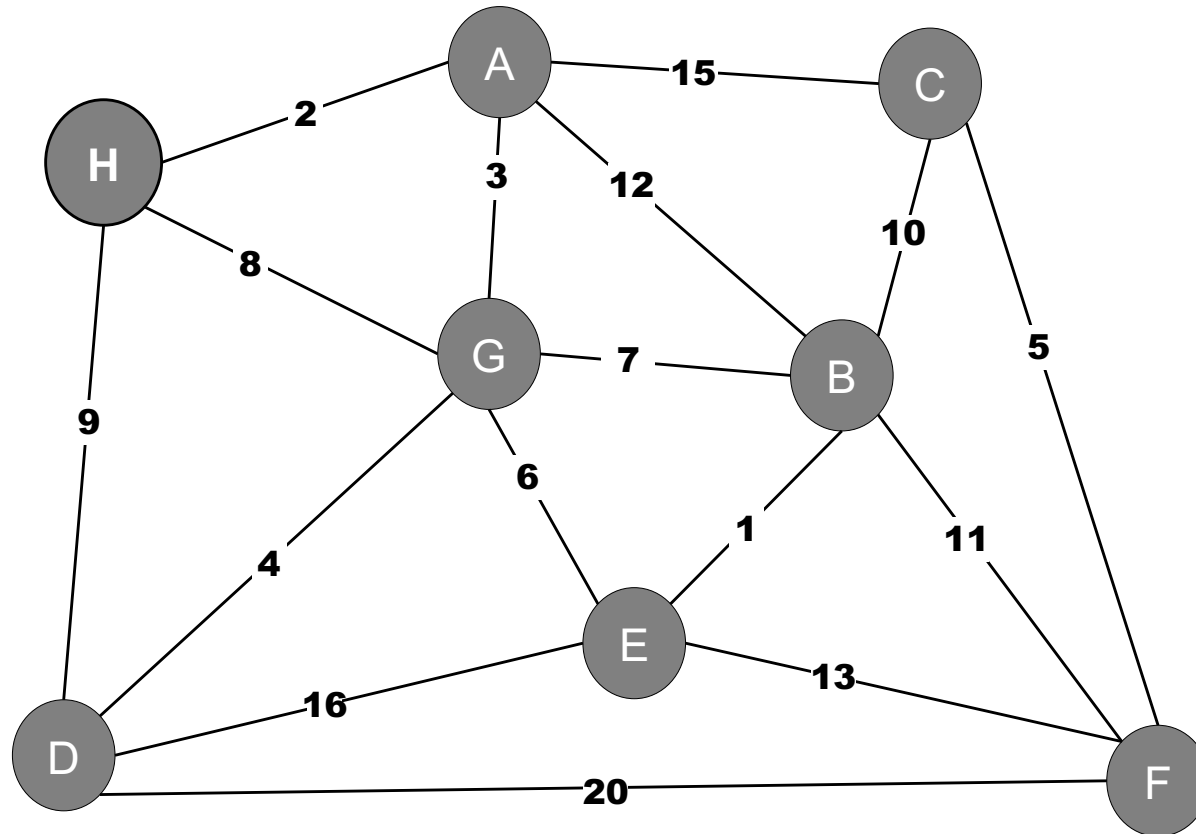
Repeat:

**Apply red rule or  
blue rule to an  
arbitrary edge.**

until no more edges  
can be colored.



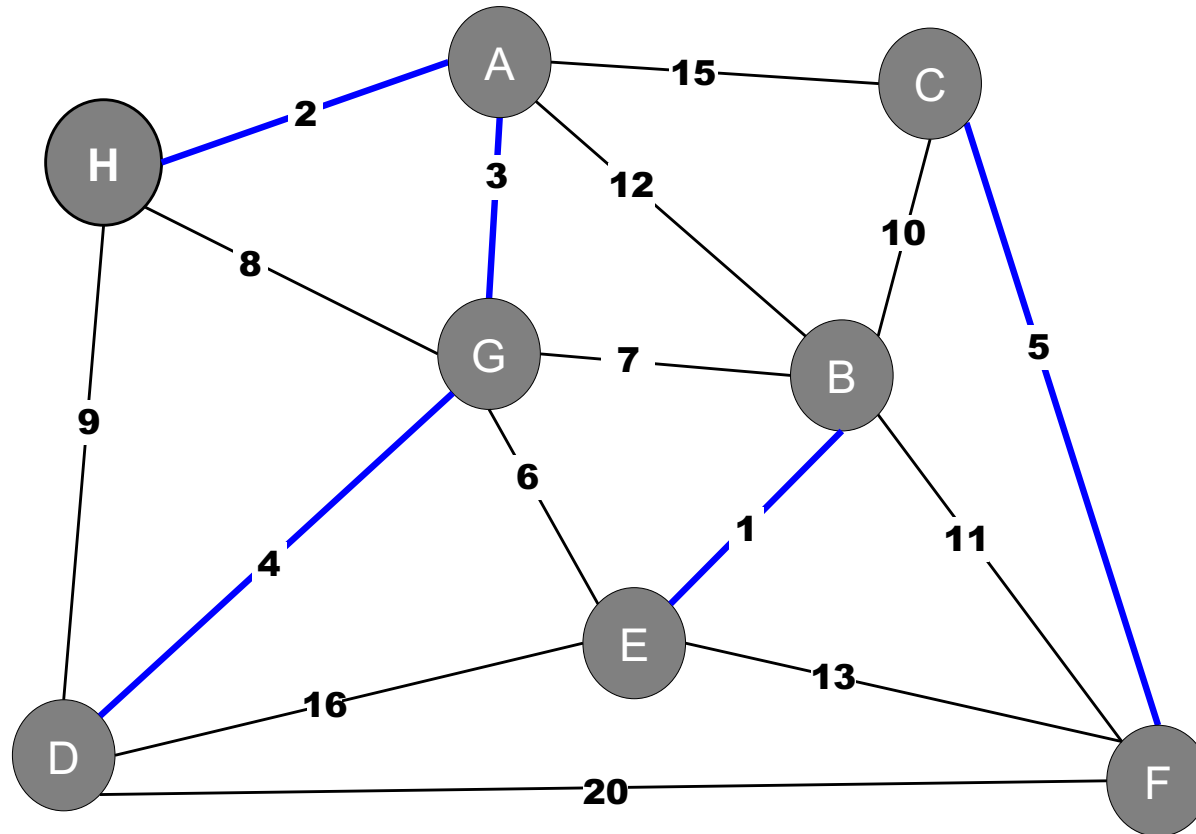
# Boruvka's Example



Weight	Edge
1	(E,B)
2	(C,F)
3	(A,G)
4	(D,G)
5	(C,F)
6	(E,G)
7	(B,G)
8	(G,H)
9	(D,G)
10	(B,C)
11	(B,F)
12	(A,B)
13	(E,F)
15	(A,C)
16	(D,E)
20	(D,F)

Which edges are “obviously” in the MST?

# Boruvka's Example

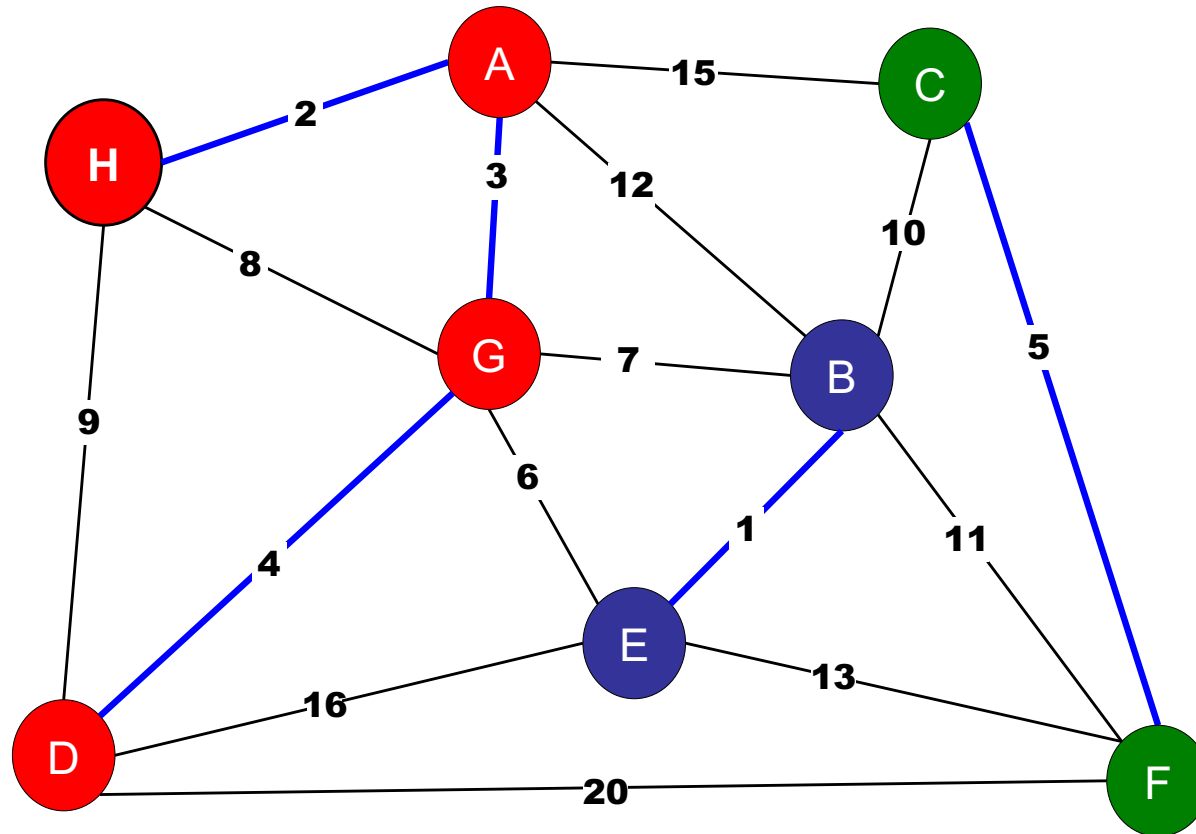


For every node: add minimum adjacent edge.

Add at least  $n/2$  edges.

Weight	Edge
1	(E,B)
2	(C,F)
3	(A,G)
4	(D,G)
5	(C,F)
6	(E,G)
7	(B,G)
8	(G,H)
9	(D,G)
10	(B,C)
11	(B,F)
12	(A,B)
13	(E,F)
15	(A,C)
16	(D,E)
20	(D,F)

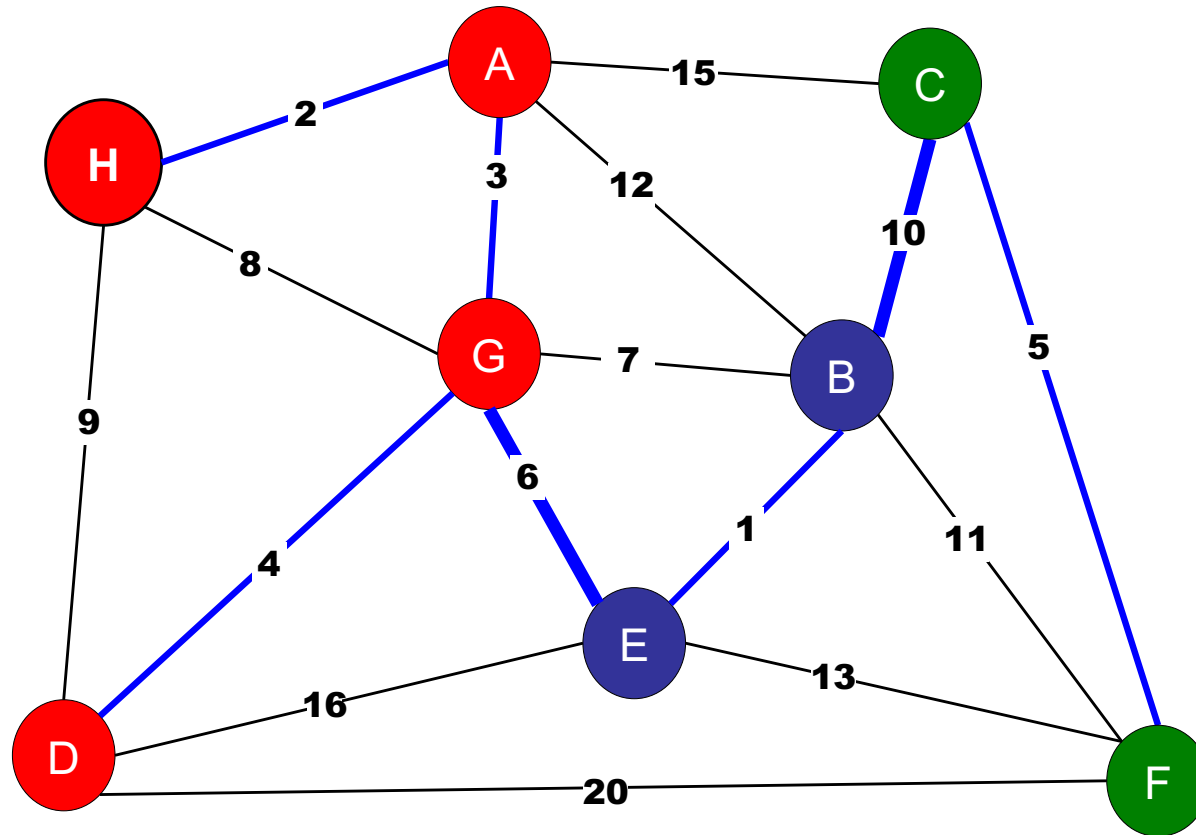
# Boruvka's Example



Look at connected components...

At most  $n/2$  connected components.

Weight	Edge
1	(E,B)
2	(C,F)
3	(A,G)
4	(D,G)
5	(C,F)
6	(E,G)
7	(B,G)
8	(G,H)
9	(D,G)
10	(B,C)
11	(B,F)
12	(A,B)
13	(E,F)
15	(A,C)
16	(D,E)
20	(D,F)



Repeat: for every connected components, add minimum outgoing edge.

Weight	Edge
1	(E,B)
2	(C,F)
3	(A,G)
4	(D,G)
5	(C,F)
6	(E,G)
7	(B,G)
8	(G,H)
9	(D,G)
10	(B,C)
11	(B,F)
12	(A,B)
13	(E,F)
15	(A,C)
16	(D,E)
20	(D,F)

# Boruvka's Algorithm

---

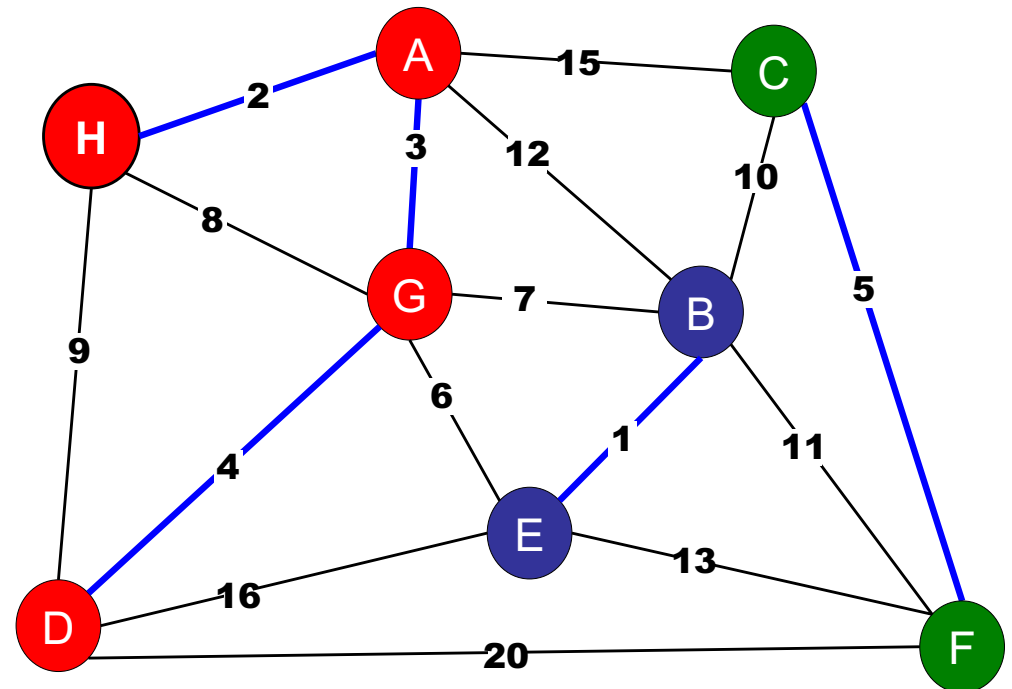
## Boruvka's Algorithm

Initially:

- Create **n** connected components, one for each node in the graph.

One “Boruvka” Step:

- For each connected component, search for the minimum weight outgoing edge.
- Add selected edges.
- Merge connected components.



# Boruvka's Algorithm

---

## Boruvka's Algorithm

Initially:

- Create  $n$  connected components, one for each node in the graph.

For each node: store a component identifier.



One "Boruvka" Step:

- For each connected component, search for the minimum weight outgoing edge.
- Add selected edges.
- Merge connected components.

# Boruvka's Algorithm

## Boruvka's Algorithm

Initially:

- Create **n** connected components, one for each node in the graph.

One "Boruvka" Step:

- For each connected component, search for the minimum weight outgoing edge.
- Add selected edges.
- Merge connected components.

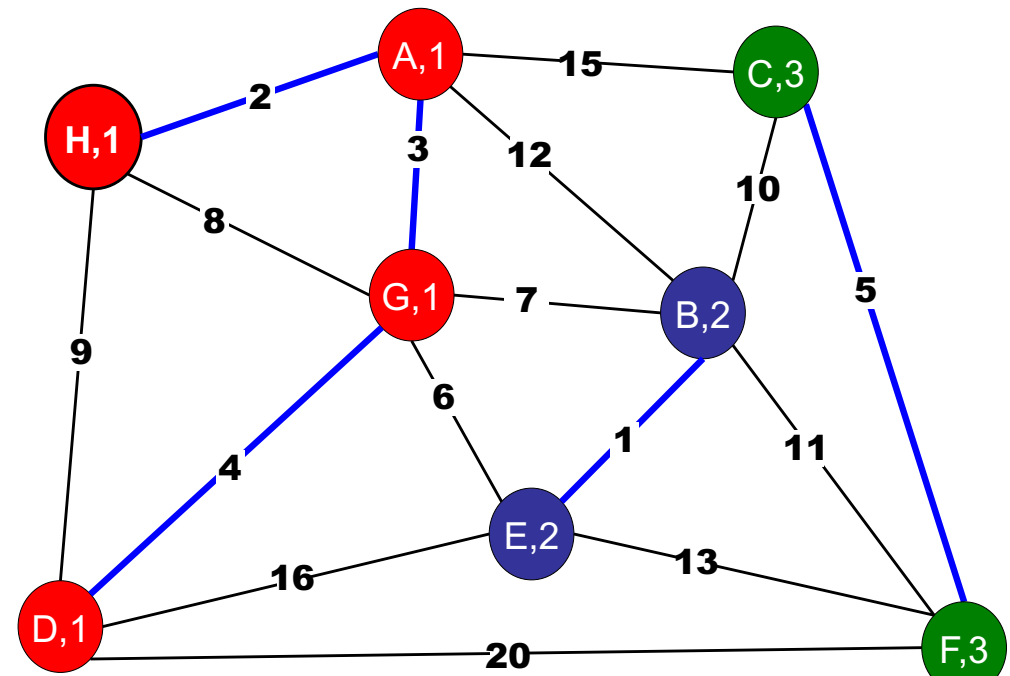
For each node: store a component identifier.

DFS or BFS:

Check if edge connects two components.

Remember minimum cost edge connected to each component.

Component	1	2	3
Min cost edge	(G,E), 6	(G,E), 6	(B,C), 10
To be merged	1 and 2	1 and 2	2 and 3





# Boruvka's Algorithm

## Boruvka's Algorithm

Initially:

- Create **n** connected components, one for each node in the graph.

One “Boruvka” Step:

- For each connected component, search for the minimum weight outgoing edge.
- Add selected edges.
- Merge connected components.

**For each node:** store a component identifier.

**DFS or BFS:**

Check if edge connects two components.

Remember minimum cost edge connected to each component.

**Scan every node:**

Computer new component ids.

Update component ids.

Mark added edges.

Component	1	2	3
Min cost edge	(G,E), 6	(G,E), 6	(B,C), 10
To be merged	1 and 2	1 and 2	2 and 3
New ID:	1	1	1

# Boruvka's Algorithm

---

## Boruvka's Algorithm

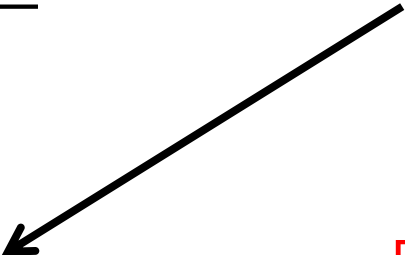
Initially:

- Create  $n$  connected components, one for each node in the graph.

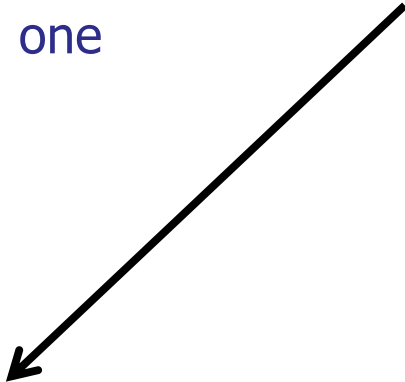
One “Boruvka” Step:  $O(V+E)$

- For each connected component, search for the minimum weight outgoing edge.
- Add selected edges.
- Merge connected components.

For each node:  $O(V)$   
store a component identifier.



DFS or BFS:  $O(V + E)$   
Check if edge connects two components.



Remember minimum cost edge connected to each component.

Scan every node:  $O(V)$

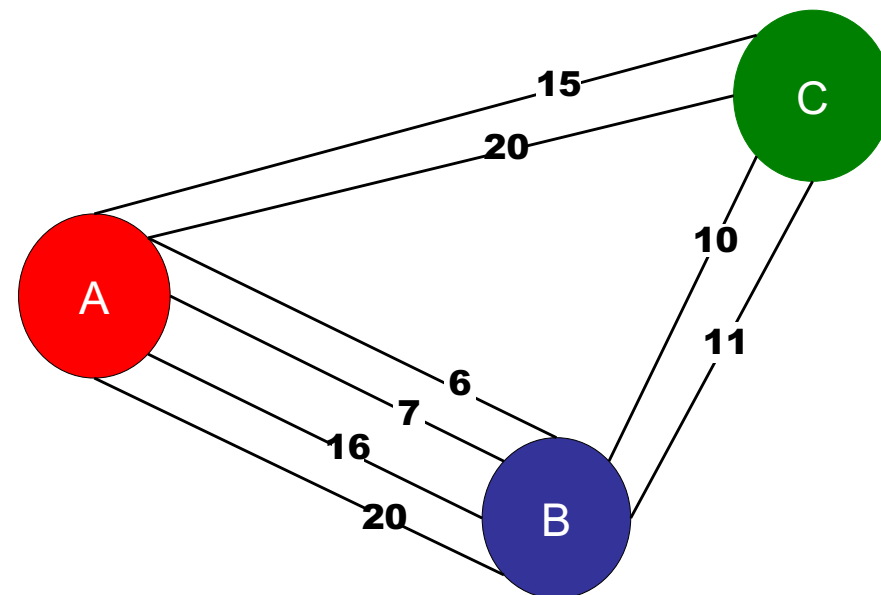
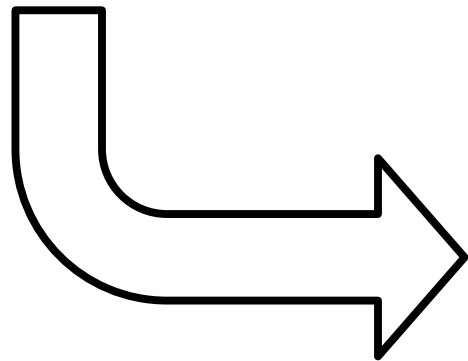
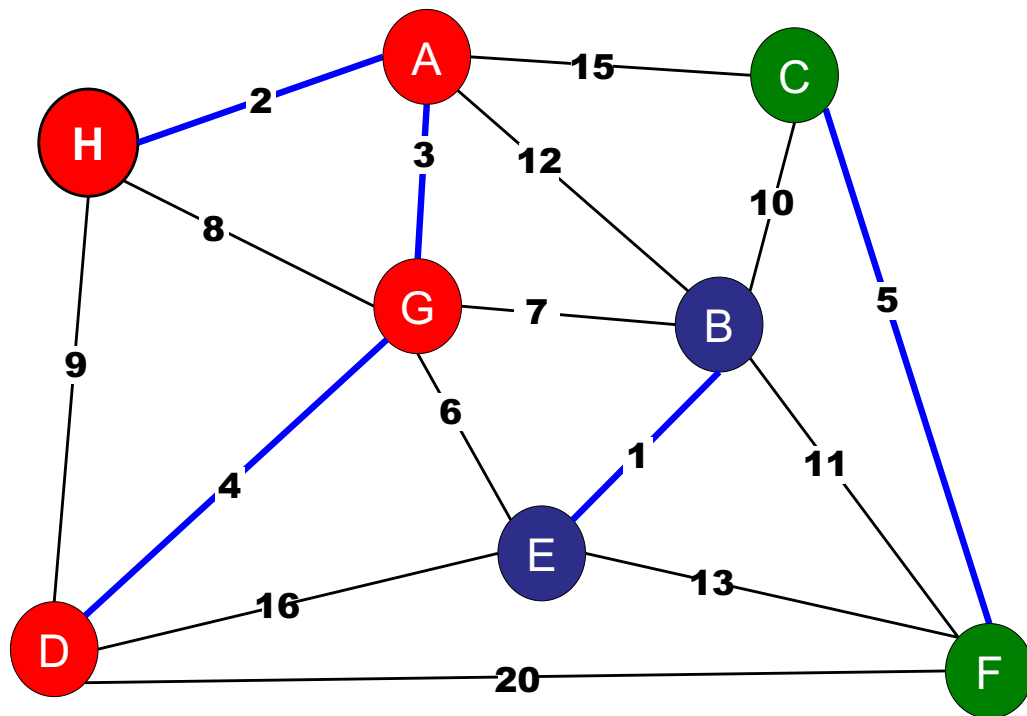


Computer new component ids.

Update component ids.

Mark added edges.

# Boruvka's Example: Contraction



# Boruvka's Algorithm

---

## Boruvka's Algorithm

Initially:

- Create  $n$  connected components, one for each node in the graph.

In each “Boruvka” Step:  $O(V+E)$

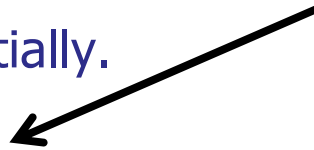
- Assume  $k$  components, initially.
- At least  $k/2$  edges added.

Count edges:

Each component adds one edge.

Some choose same edge.

Each edge is chosen by at most two different components.



# Boruvka's Algorithm

---

## Boruvka's Algorithm

Initially:

- Create  $n$  connected components, one for each node in the graph.

In each “Boruvka” Step:  $O(V+E)$

- Assume  $k$  components, initially.
- At least  $k/2$  edges added.
- At least  $k/2$  components merge.

Merging:

Each edge merges two components

# Boruvka's Algorithm

---

## Boruvka's Algorithm

Initially:

- Create  $n$  connected components, one for each node in the graph.

In each “Boruvka” Step:  $O(V+E)$

- Assume  $k$  components, initially.
- At least  $k/2$  edges added.
- At least  $k/2$  components merge.
- At end, at most  $k/2$  components remain.

# Boruvka's Algorithm

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## Boruvka's Algorithm

**Initially:**

n components

**At each step:**

k components  $\rightarrow$   $k/2$  components.

**Termination:**

1 component

**Conclusion:**

At most  $O(\log V)$  Boruvka steps.

# Boruvka's Algorithm

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## Boruvka's Algorithm

**Initially:**

n components

**At each step:**

k components  $\rightarrow$   $k/2$  components.

**Termination:**

1 component

**Conclusion:**

At most  $O(\log V)$  Boruvka steps.

**Total time:**

$O((E+V)\log V) = O(E \log V)$



# Boruvka's Algorithm

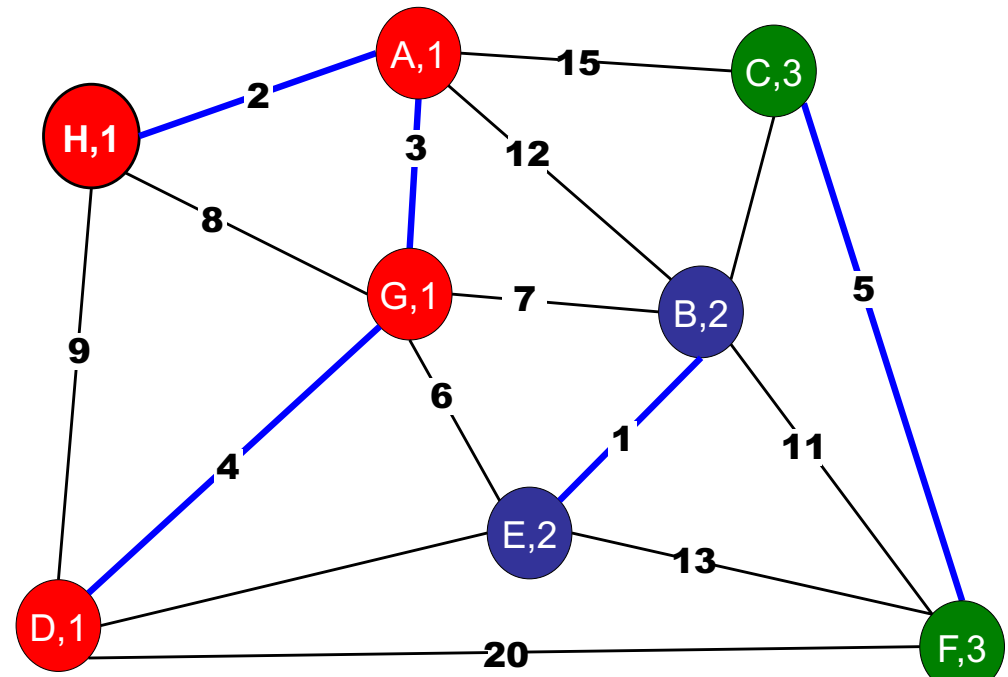
## Boruvka's Algorithm

Initially:

- Create  $n$  connected components, one for each node in the graph.

One “Boruvka” Step:  $O(V+E)$

- For each connected component, search for the minimum weight outgoing edge.
- Add selected edges.
- Merge connected components.



# Roadmap

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So far:

## Minimum Spanning Trees

- Prim's Algorithm
- Kruskal's Algorithm
- Boruvka's Algorithm

# Minimum Spanning Tree Summary

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Classic greedy algorithms:  $O(E \log V)$

- Prim's (Priority Queue)
- Kruskal's (Union-Find)
- Boruvka's

Best known:  $O(m \alpha(m, n))$

- Chazelle (2000)

Holy grail and major open problem:  $O(m)$

# Minimum Spanning Tree Summary

---

Classic greedy algorithms:  $O(E \log V)$

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Best known:  $O(m \alpha(m, n))$

- Chazelle (2000)

Holy grail and major open problem:  $O(m)$

- Randomized: Karger-Klein-Tarjan (1995)
- Verification: Dixon-Rauch-Tarjan (1992)

CS2040S

# Data Structures and Algorithms

All about minimum spanning trees...