CS2100

Computer Organization

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Part I

Data Representation

Data is represented as a sequence of bits - 0 or 1.

8 bits form a **byte**, and a fixed multiple of bytes in a computer architecture forms a **word**.

number of bits ← number of values

n bits can represent up to 2^n values.

Conversely, we need at least $\lceil \log_2 m \rceil$ bits to represent m values.

1 Number Systems

Number systems are **weighted-positional** systems, with the **decimal** number system having a **base** (or **radix**) of 10.

number system	base	prefix
binary	2	0b
octal	8	0
decimal	10	_
hexadecimal	16	0×

The digit to the left of the decimal point has a weight of 10^{0} , with the exponent *incrementing* leftward and decrementing rightward.

decimal ⇒ binary

For whole numbers, use repeated division-by-two:

- 1. divide the value by 2, and record the remainder
- 2. prepend the remainder to the binary representation
- 3. repeat until the value is 0

For fractions, use repeated multiplication-by-two:

- 1. multiply the value by 2, and record the carry
- 2. append the carry to the binary representation
- 3. repeat until the value is 1
- 4. append the 1 to the binary representation

binary \implies decimal

Use weighted summation:

- 1. assign the digit to the left of the binary point a weight of 2^0
- 2. increment the weight exponents leftward
- 3. decrement the weight exponents rightward
- 4. multiply each digit by its weight
- 5. sum the products

These conversions generalize to any base!

Converting between 2 bases can be done with base-10 as an intermediary.

binary \iff base-2^k

- 1. partition the binary representation into k-bit chunks outward from the binary point
- 2. convert each chunk to base-10
- 3. convert each base-10 value to base- 2^k

Apply the reverse direction for converting from base- 2^k to binary.

1.1 Negative Numbers

Signed numbers include all positive and negative values, unlike **unsigned numbers** which only include non-negative values.

We will consider *n*-bit values in this section.

sign-and-magnitude

The MSB is the **sign bit** - 0 for positive, 1 for negative.

Negate a value by inverting the sign bit.

- range:
$$-2^{n-1} + 1$$
 to $2^{n-1} - 1$

- **zeros**:
$$-0_{10}$$
 and $+0_{10}$

1s complement

An *n*-bit number *x* has a negated value $-x = 2^n - x - 1$.

Negate a value by inverting all the bits.

- range:
$$-2^{n-1} + 1$$
 to $2^{n-1} - 1$

- **zeros**:
$$-0_{10}$$
 (all 1s) and $+0_{10}$ (all 0s)

The weight of the MSB is $-2^{n-1} + 1$.

2s complement

An *n*-bit number x has a negated value $-x = 2^n - x$.

Negate a value by inverting all the bits to the left of the *rightmost* 1.

- range:
$$-2^{n-1}$$
 to $2^{n-1}-1$

zeros: 0₁₀ (all 0s)

Unlike sign-and-magnitude and 1s complement, 2s complement does not have duplicate zeros.

The weight of the MSB is -2^{n-1} .

The MSB also represents the sign — 0 for positive, 1 for negative.

Negating a fractional number in a complement representation is no different than negating a whole number!

excess representation

Distribute positive and negative values by a simple addition or subtraction by k, which is also known as the **bias**.

k is typically $2^n - 1$ for an n-bit number.

The binary value in excess-k subtracts k from its decimal value.

Conversely, the decimal value in excess-k adds k to its binary value.

1.2 Overflow

Overflow occurs when addition or subtraction goes beyond the fixed range of a signed number.

Subtraction is equivalent to addition of the negated value.

Note that in 1s addition, the carry out of the MSB is added to the result, but this carry out is discarded in 2s addition.

detecting overflow

If the MSB (sign bit) of the result is different from the MSBs of the operands, then overflow has occurred.

Note that overflow can only occur when the operands have the same sign, i.e., adding a negative number to a positive number will *never* result in overflow.

1.3 Real Numbers

Fixed-point representation fixes the number of bits for the whole number and fractional parts, which limits the range of values.

The IEEE 754 **floating-point representation** resolves this by allocating a fixed number of bits to the **sign**, **exponent**, and **mantissa**.

precision	bits	sign	ехр.	mantissa	bias
single	32	1	8	23	127
double	64	1	11	52	1023

The **mantissa** is **normalized** with an implicit leading 1 bit, e.g. 110.1_2 is normalized to $1.101_2 \times 2^2$, and only 101 is stored in the mantissa.

decimal ⇒ IEEE 754 floating-point representation

- 1. convert the decimal value to normalized binary, i.e., $\pm 1.xxx \times 2^y$
- determine the sign bit 0 for positive, and 1 for negative
- 3. add the bias to the exponent y +127 for single precision, and +1023 for double precision
- 4. convert the exponent to binary
- 5. concatenate the sign bit, exponent, and mantissa xxx

Part II

MIPS

An **instruction set architecture** (ISA) is an abstraction on the interface between hardware and low-level software.

MIPS is one such ISA, which runs on a processor.

Processors are connected to **memory** (RAM) via a **bus**, across which code and data is transferred.

2 Registers

Memory access is slow. To avoid frequent memory access, temporary values are stored in the processor in **registers**, which are limited in number.

Registers do not have data types, unlike program variables. Instructions always assume that the data stored in a register is of the correct type.

MIPS has **32 registers**, which are referred to by *number* or *name*:

name	#	usage			
\$zero	0	constant value zero			
\$at	1	reserved for the assembler			
\$v0 - \$v1	2 - 3	values for results and expression evaluation			
\$a0 - \$a3	4 - 7	arguments			
\$t0 - \$t7	8 - 15	temporaries			
\$s0 - \$s7	16 - 23	program variables			
\$t8 - \$t9	24 - 25	temporaries			
\$k0 - \$k1	26 - 27	reserved for the OS			
\$gp	28	global pointer			
\$sp	29	stack pointer			
\$fp	30	frame pointer			
\$ra	31	return address			

3 MIPS Assembly Language

The **general instruction syntax** is as follows:

	op \$s0, \$s1, \$s2					
	description					
ор	operation					
\$s0	destination register					
\$s1	source register 1					
\$s2	source register 2					

Each instruction executes a *single* command. Each line of assembly code contains *at most* one instruction.

Almost all MIPS operations are register-to-register

The # hex synbol is used for comments.

3.1 Arithmetic Instructions

instru	ction		effect		
add	\$s0,	\$s1, \$s2	\$s0 = \$s1 + \$s2		
sub	\$s0,	\$s1, \$s2	\$s0 = \$s1 - \$s2		
addi	\$s0,	\$s0, <k></k>	\$s0 = \$s0 + <k></k>		
move	\$s0,	\$s1	<pre>pseudo-instruction for \$s0 = \$s1, equivalent to add \$s0, \$s1, \$zero</pre>		

The constants <k> in **immediate operations** such as addiange from -2^{15} to $2^{15}-1$, as the 16-bit 2s complement system is used.

However, if 32-bit constants are required, use the lui operation to load the most-significant (leftmost) 16-bits first, followed by an ori operation to set the least-significant 16-bits.

There is no subi operation as its equivalent to addi with a negative constant.

Use the **temporary registers** \$t0 to \$t9 to store intermediate results in complex expressions.

3.2 Logical Instructions

instru	ction			effect
sll	\$t2,	\$s0,	<k></k>	\$t2 = \$s0
srl	\$t2,	\$s0,	<k></k>	\$t2 = \$s0
and	\$t0,	\$t1,	\$t2	bitwise AND, where \$t2 is the bit-mask
or	\$t0,	\$t1,	\$t2	bitwise 0R, to force certain bits to 1
nor	\$t0,	\$t1,	\$t2	bitwise NOR, only 1 if neither bits are 0
xor	\$t0,	\$t1,	\$t2	bitwise X0R, only 1 if both bits are different
andi	\$t0,	\$t1,	<k></k>	bitwise AND with a constant k
ori	\$t0,	\$t1,	<k></k>	bitwise 0R with a constant k
xori	\$t0,	\$t1,	<k></k>	bitwise X0R with a constant k

In bitshift operations (sll and srl), the empty positions are filled with zeros, and the **shift amount** is limited to **5 bits**.

There is no not operation as its equivalent to nor <dest> <src> \$zero.

There is no nori operation as it is rarely used, and not adding it keeps the processor design simple.

3.3 Memory Instructions

Memory can be thought of as a *single-dimensional array* of memory location, with each having an **address**.

Memory addresses allow access to *bytes* of data, or **words** of data, which are usually 2^n bytes — the common unit of transfer between the processor and memory.

Word alignment occurs in memory when words begin at a *byte address* which is a multiple of the word size — 2^n bytes.

In MIPS, each word is 32 bits (4 bytes), and addresses are 32-bits long — such that 2^{30} words are addressable, each of which differing by 4.

instr	uction		effect		
lw	\$dst,	k(\$src)	<pre>loads word at Mem[*src + k] into register \$dst</pre>		
SW	\$src,	k(\$dst)	stores word in register \$src into Mem[*dst + k]		
lb	\$dst,	k(\$src)	loads byte at Mem[*src + k] into register \$dst		
sb	\$src,	k(\$dst)	stores byte in register \$src into Mem[*dst + k]		
ulw	\$dst,	k(\$src)	psuedo-instruction for loading unaligned words		
usw	\$src,	k(\$dst)	psuedo-instruction for storing unaligned words		

Memory operations the only operations which can access data in memory, but there are others which are less frequently used that are not listed here.

Unlike in lw and sw, the displacement constants k for lb and sb do not need to be multiples of 4.

3.4 Control Flow Instructions

instru	ction	effect		
beq	\$r1, \$r2, label	goes to the labelled statement if *r1 == *r2		
bne	\$r1, \$r2, label	goes to the labelled statement if *r1 != *r2		
j	label	jumps to the labelled statement		
slt	\$dst, \$s1, \$s2	*dst = *s1 < *s2 ? 1 : 0		
slti	\$dst, \$src, k	*dst = *src < k ? 1 : 0		

Labels are written as <label>: to the left of a statement.

A j instruction is equivalent to beq \$s0 \$s0, <label>.

The **program counter** (PC) typically stores the address of the *next* address to be executed, and has to be modified by the branching and jump instructions.

4 Instruction Encoding

Every MIPS instruction is **32 bits** in 3 possible formats:

format		destination registers	immediate values	
R	2	1	0	
1	1	1	1	
J	0	0	1	

4.1 R-format

	opcode	rs	rt	rd	shamt	funct
bits	6	5	5	5	5	6

- opcode := 0 for all R-format instructions,
- funct determines the instruction,
- shamt := 0, rd := arith(rs, rt) for non-shift
 (arithmetic) instructions, and,
- rs := 0, rd := shift(rt, shamt) for shift
 instructions.

4.2 I-format

	opcode	rs	rt	immediate
bits	6	5	5	16

- opcode determines the instruction since there is no funct field,
- rt determines the destination register since there is no rd field,
- immediate is a signed integer in 2s complement except for bitwise operations where it is unsigned,
- rt := op(rs, immediate) in general for all non-branching instructions, and,
- PC := (PC + 4) + (immediate * 4) when branching, otherwise PC += 4, which is the next instruction.

For branching instructions, immediate is the offset from the *next* instruction to the label of the *target* instruction.

PC is incremented in multiples of 4 due to word-alignment, which also means that we can now branch $2^{15} \times 4 = 2^{17}$ bytes away from PC.

4.3 J-format

	opcode	target address
bits	6	26

The last 2 bits of every instruction are always 00 due to word-alignment, so we leave them out of the target address.

This leaves with an effective range of 28 bits for the target address, and the remaining 4 bits are derived from the most significant (leftmost) bits of PC + 4.

The destination address is therefore:

	(PC+4)[0:4]	target address	00
bits	4	26	2

This creates a maximum jump range of 256 MB.

4.4 Addressing Modes

Addressing modes are used to calculate the address of an operand.

- register addressing add, xor, etc.: operand is a register
- 2. **immediate addresssing** addi, andi, etc.: operand is a constant within the instruction
- 3. **base/displacement addressing** lw, sw: operand is a memory location at the address the sum of a register and a constant in the instruction
- PC-relative addressing beq, bne: address is the sum of the PC and a constant in the instruction
- psuedo-direct addressing j:
 part of the instruction concantenated with part of the
 PC

5 Aside: Instruction Set Architecture

ISAs have two major design philosophies:

- 1. **CISC** Complex Instruction Set Computer:
 - single instructions for complex operations
 - smaller program sizes
 - complex implementation, little room for hardware optimization
- 2. **RISC** Reduced Instruction Set Computer:
 - smaller and simpler instruction set
 - software combines simpler operations to implement high-level language statements
 - room for compiler optimization

5.1 Data Storage Architecture

There are several common designs:

- stack architecture: operands are implicitly popped from the stack
- accumulator architecture: one operand is implcitly stored in an accumulator
- general-purpose register architecture: operands are stored explicitly in registers, operations are register-memory or register-register
- memory-memory architecture: operands are read from memory

5.2 Memory Architecture

Memory transfer takes place across buses:

- address bus: k-bits, uni-directional from processor to memory
- 2. data bus: n-bits, bi-directional
- 3. control lines: bi-directional, e.g. read/write controls

The address bus feeds addresses from the **memory** address register to the memory.

Data is written to or read from the **memory data register**, depending on the R/W control line.

Endianness is the relative ordering of the *bytes* in a word (*not* the bits in a byte!) in memory:

- big-endian: MSB stored in smallest address
- little-endian: LSB stored in smallest address

6 Datapath

A collection of components that process data, and perform arithmetic, logical, and memory operations.

The instruction execution cycle has 5 stages:

- fetch: get instruction from memory, address in PC
- decode and operand fetch: determine the operation and get the operands needed
- 3. **execute (ALU)**: perform the computations to get a result
- execute (memory access): read from or write to memory if necessary
- 5. **write-back**: store the result of the operation

6.1 Fetch

There are 3 steps in the fetch stage:

- 1. Use PC to fetch the instruction from memory.
- 2. Increment PC by 4 to get the address of the next instruction.
- 3. Feed the output instruction to the decode stage.

The **instruction memory** element is a **sequential circuit** with an internal state which stores the instructions.

When supplied an instruction address m, it outputs the content at address m.

The **adder** element takes in the 32-bit PC and the 32-bit constant 4, and outputs the 32-bit sum PC + 4.

The **clock signal** is a *square wave* with *rising* and *falling* edges, and a period controlled by the CPU.

PC is read in the first half of the **clock period** and updated at the *next rising clock edge*.

6.2 Decode

There are 3 steps in the decode stage:

1. Read the opcode to determine the instruction type and field lengths.

- 2. Read data from all necessary registers.
- 3. Feed the operation and operands to the ALU stage.

The **register file** element is a collection of 32 registers which can be read from or written to.

input	bits	output	bits
read register 1	5	read data 1	32
read register 2	5	read data 2	32
write register	5		
write data	32		

The **RegWrite** control signal determines whether the instruction should read from or write to the registers:

	RegWrite	registers per instruction
read	0	≤ 2
write	1	≤1

6.2.1 R-format Decoding

The binary content (Inst) of R-format instructions map to the inputs as follows:

```
- rs \equiv Inst[25:21] \rightarrow rr1

- rt \equiv Inst[20:16] \rightarrow rr2

- rd \equiv Inst[15:11] \rightarrow wr
```

6.2.2 I-format Decoding

For I-format instructions, 2 problems arise:

- 1. rt, not part of imm, needs to be fed to wr
- 2. imm needs to be fed to the ALU, not rd2

A **multiplexer** chooses the correct Inst slice to feed to wr using the control signal **RegDst**:

	RegDst	input to wr
I-format	0	rt ≡ Inst[20:16]
R-format	1	rd ≡ Inst[15:11]

```
- rs \equiv Inst[25:21] \rightarrow rr1

- rt \equiv Inst[20:16] \rightarrow rr2

- rt \equiv Inst[20:16] \rightarrow wr
```

Another multiplexer chooses the correct 32-bit binary data to feed into the ALU:

	ALUSrc	input to ALU opr2
R-format or beq	0	$rr2 \equiv *rt \equiv *Inst[20:16]$
I-format not beq	1	imm ≡ Inst[15:0], sign extended to 32-bits

6.3 Arithmetic Logic Unit (ALU)

The ALU performs the arithmetic, shifting, logical, memory, and branching operations.

It takes the operation and operands from the decode stage, performs its computation, and feeds the result to the memory stage.

input	bits	output	bits
operand 1	32	is zero?	1
operand 2	32	result	32

The **ALUControl** signal determines the operation to perform:

ALUControl	operation
0000	and
0001	or
0010	add
0110	sub
0111	slt
1100	nor

6.3.1 Branching Instructions

A multiplexer chooses between the next instruction (PC + 4) and the branch target (BT) using the control signal **PCSrc**:

isZero	PCSrc	next instruction
false ≡ 0	0	PC + 4
true ≡ 1	1	$BT \equiv PC + 4 + imm * 4$

Because both register contents need to be compared, the ALUS rc control value is set to 0 for branching instructions.

BT is computed as follows:

- 1. left shift by 2 bits the sign-extended imm from the decode stage (multiplying the offset by 4)
- 2. add it to PC + 4 from the adder in the fetch stage

6.4 Memory

Only lw/lb and sw/sb instructions operate in this stage, the rest remain idle.

The **data memory** element exists in RAM:

input	bits	output	bits
address (addr)	32	read data (rdt)	32
write data (wd)	32		

addr is the effective memory address computed by the ALU, and wd is connected to rd2 from the register file from the decode stage.

The control signals **MemRead** and **MemWrite** control the memory operations:

MemRead	MemWrite	action
0	1	write wd into addr
1	0	read contents of addr into
0	0	do nothing
1	1	undefined, should not occur

6.4.1 Non-memory Instructions

A multiplexer chooses between the result of the ALU and the read data from memory, using the control signal **MemtoReg**:

	MemToReg	output
non-memory instruction	0	ALU output
memory instruction	1	read data

This output is fed to the write-back stage.

6.5 Write-back

Stores, branches, and jumps remain idle in this stage as there is nothing to be written.

The result of the memory stage is fed into write data (wd) of the register file.

7 Control

Control signals are generated by a **control unit** based on the type of instruction.

The control unit is a **combinational circuit** which takes in the 6-bit opcode and the 5-bit function code, and outputs the 8 control signals.

funct is only needed to determine ALUSrc; every other control signal can be derived from opcode alone.

7.1 ALUControl

We start with a simplified 1-bit ALU.

1-bit MIPS ALU

4 control signals are needed:

1. **Ainvert**: 1 to invert A, 0 otherwise

2. **Binvert**: 1 to invert B, 0 otherwise

3. operation (2 bits): select one of the 3 results

5 I/O signals:

1. A: input

2. B: input

3. Cin: carry in4. Cout: carry out

5. **result**: output

These 1-bit ALUs are daisy-chained to form a 32-bit ALU.

The carries from one of the 1-bit ALUs is fed out via Cout and into the next one via Cin.

Ainvert and Binvert control the multiplexers which select between their inputs and their negated values:

Xinvert	output
0	Х
1	NOT(X)

The operation control signal selects one of the 3 results from the AND gate, OR gate, and the adder ADD:

operation	output
00	AND
01	0R
10	ADD
11	SLT

1-bit subtraction

Cin is set to 1 due to 2s complement:

$$A - B \equiv A + (-B) \equiv A + B' + 1$$

ALUControl

In MSB to LSB order, ALUControl comprises of:

- 1. Ainvert
- 2. Binvert
- 3. operation

7.1.1 ALU0p

It is necessary to use the **multi-level decoding approach** to simplify the design process and size of the main controller.

ALUOp is an intermediate 2-bit control signal which is generated from opcode and used with funct to determine ALUControl.

instruction	ALU0p	funct	ALUControl
lw, sw	00	XXXXXX	0010
beq	01	XXXXXX	0110
add	10	100000	0010
sub	10	100010	0110
and	10	100100	0000
or	10	100101	0001
slt	10	101010	0111

In general, ALUOp is 10 for R-format instructions.