CSU22012: Data Structures and Algorithms II

Graphs

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Outline

- Undirected graphs
  - Depth-first search (DFS) – path finding
  - Breadth-first search (BFS) – shortest path
- Directed graphs – DFS, BFS
- Directed acyclic graphs
  - Topological sort
- Shortest path finding
  - Dijkstra's algorithm

Outline

- Minimum spanning trees
  - Prim's and Kruskal's algorithms – greedy algorithms
- Shortest paths
  - Single source shortest path
    - Topological sort – acyclic graphs
    - Dijkstra – non negative weights
    - Bellman-Ford – non-negative cycles
  - Single-pair shortest path
    - A* search algorithm
  - All pairs shortest path
    - Floyd-Warshall

Outline

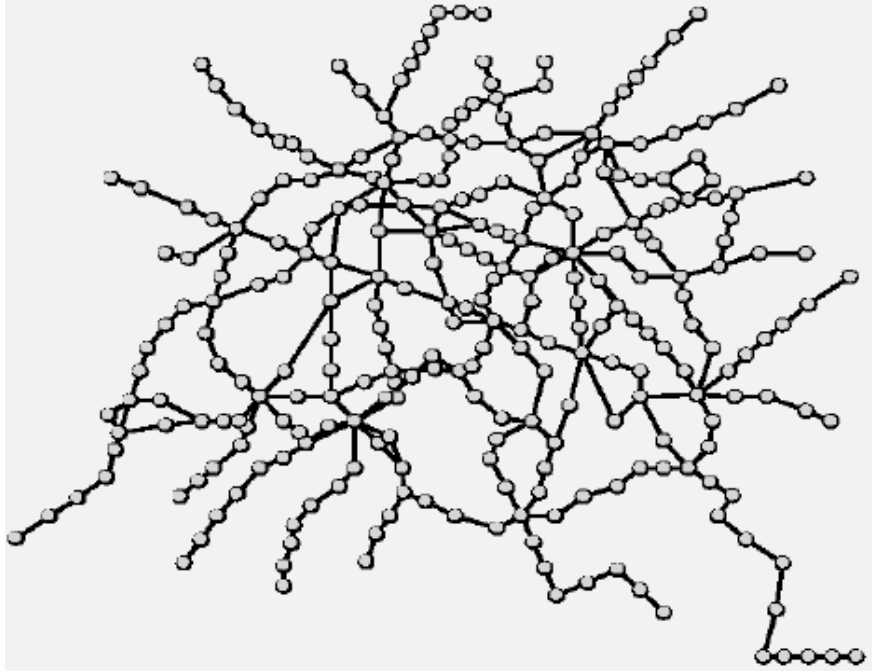
- Dynamic programming examples
  - Bellman-Ford and Floyd-Warshall
- Network flow
  - Positive edge (capacity) directed graph with a source and sink
  - Maxflow problem – flow of maximum capacity
  - Ford-Fulkerson algorithm

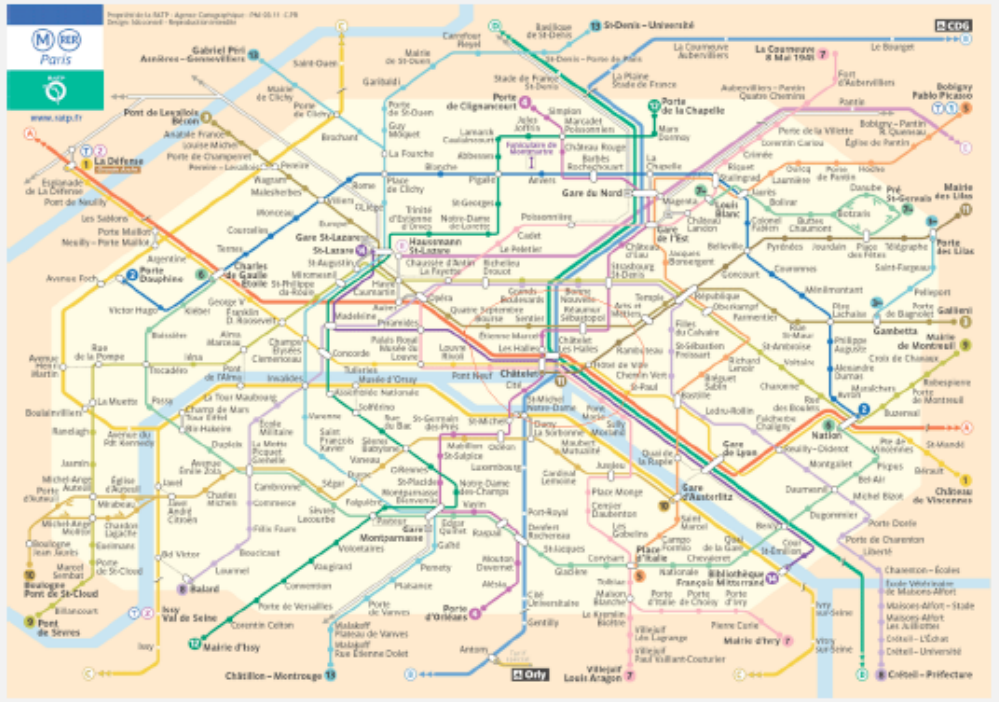
Background and applications

- Graph = a set of vertices connected pairwise by edges
- Thousands of practical applications.
- Hundreds of graph algorithms known.
- Interesting and broadly useful abstraction.
- Challenging branch of computer science and discrete math

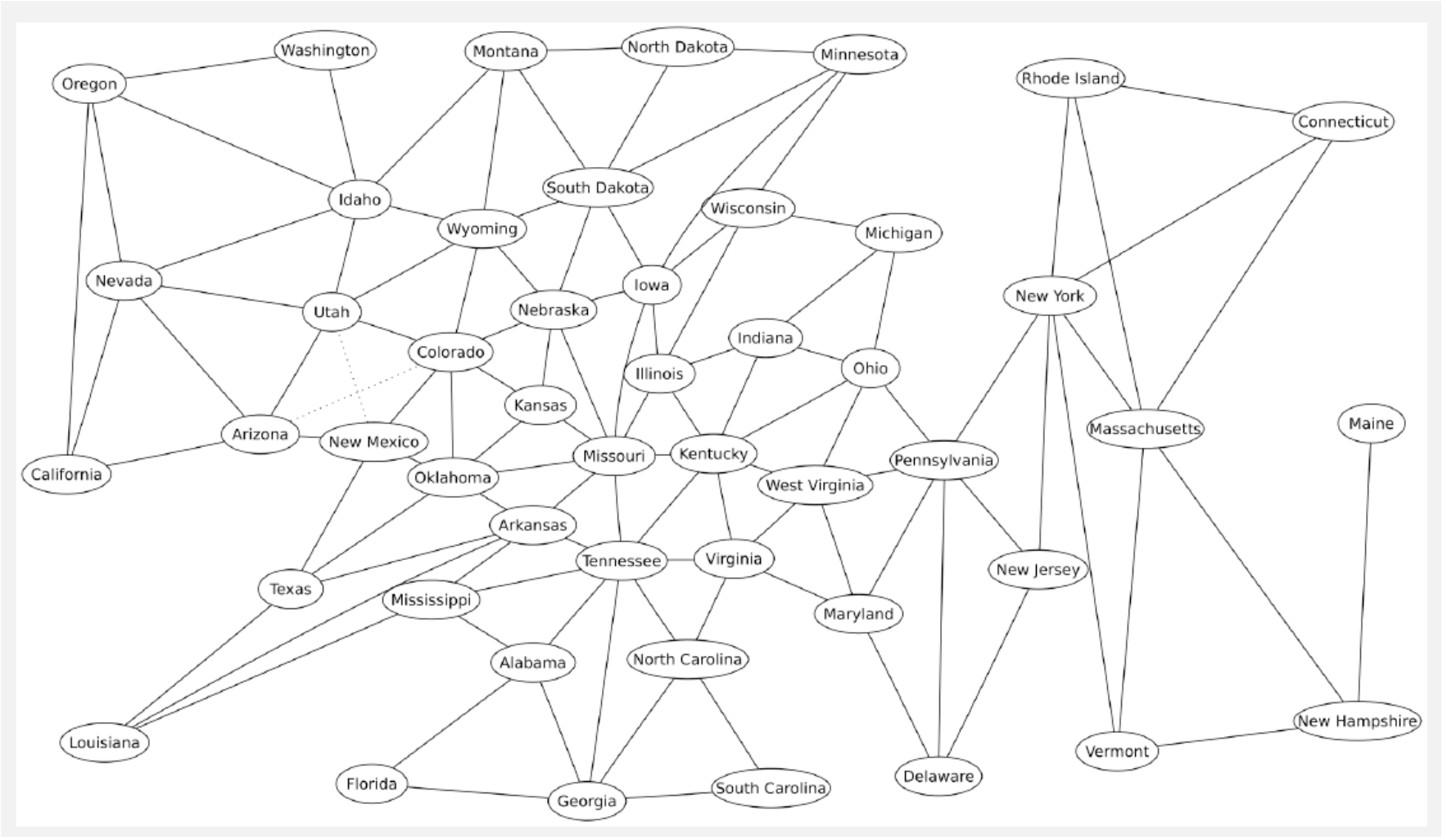
graph	vertex	edge
communication	telephone, computer	fiber optic cable
circuit	gate, register, processor	wire
mechanical	joint	rod, beam, spring
financial	stock, currency	transactions
transportation	intersection	street
internet	class C network	connection
game	board position	legal move
social relationship	person	friendship
neural network	neuron	synapse
protein network	protein	protein-protein interaction
molecule	atom	bond

Transport networks

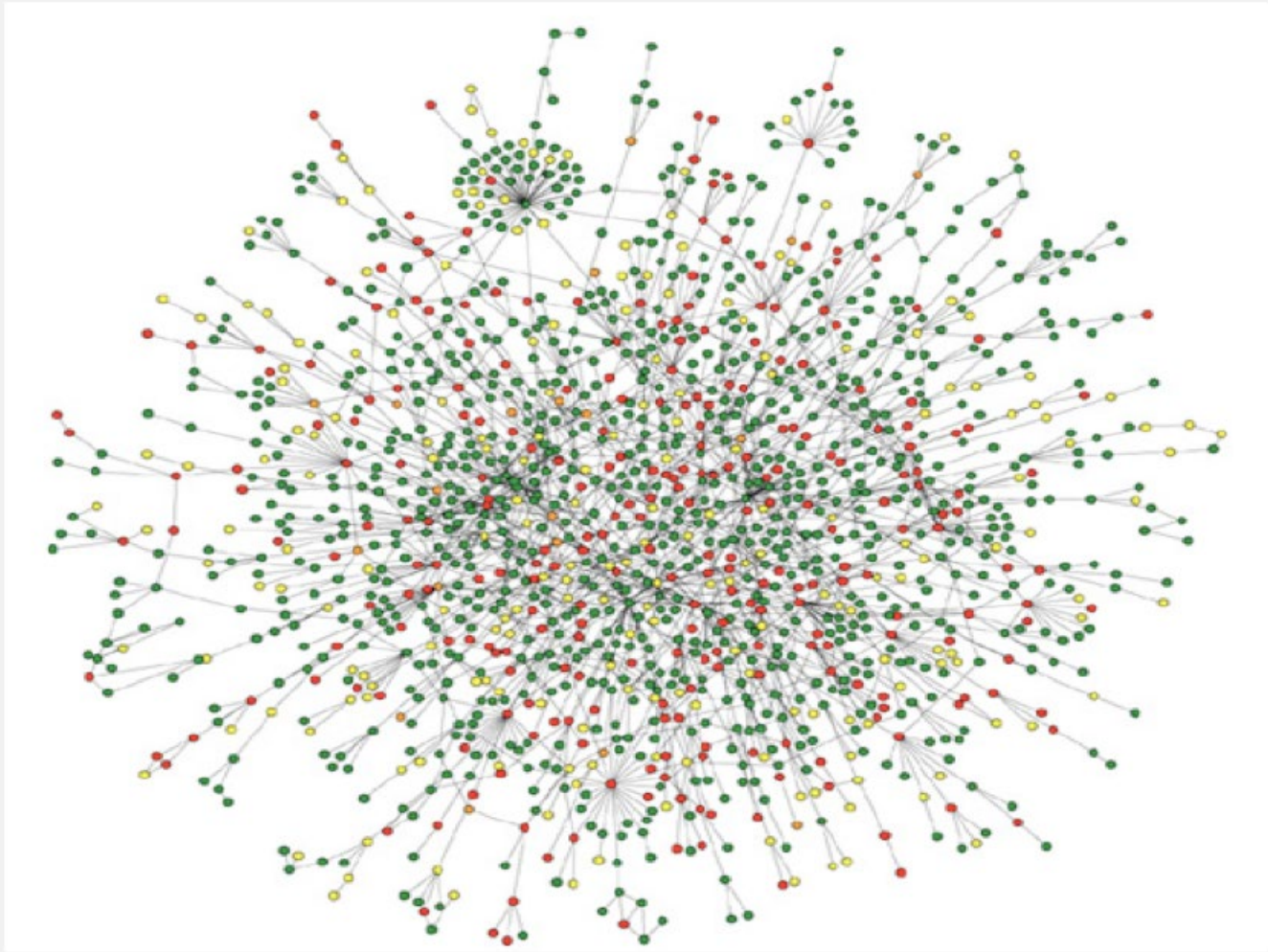




Borders graph – American states

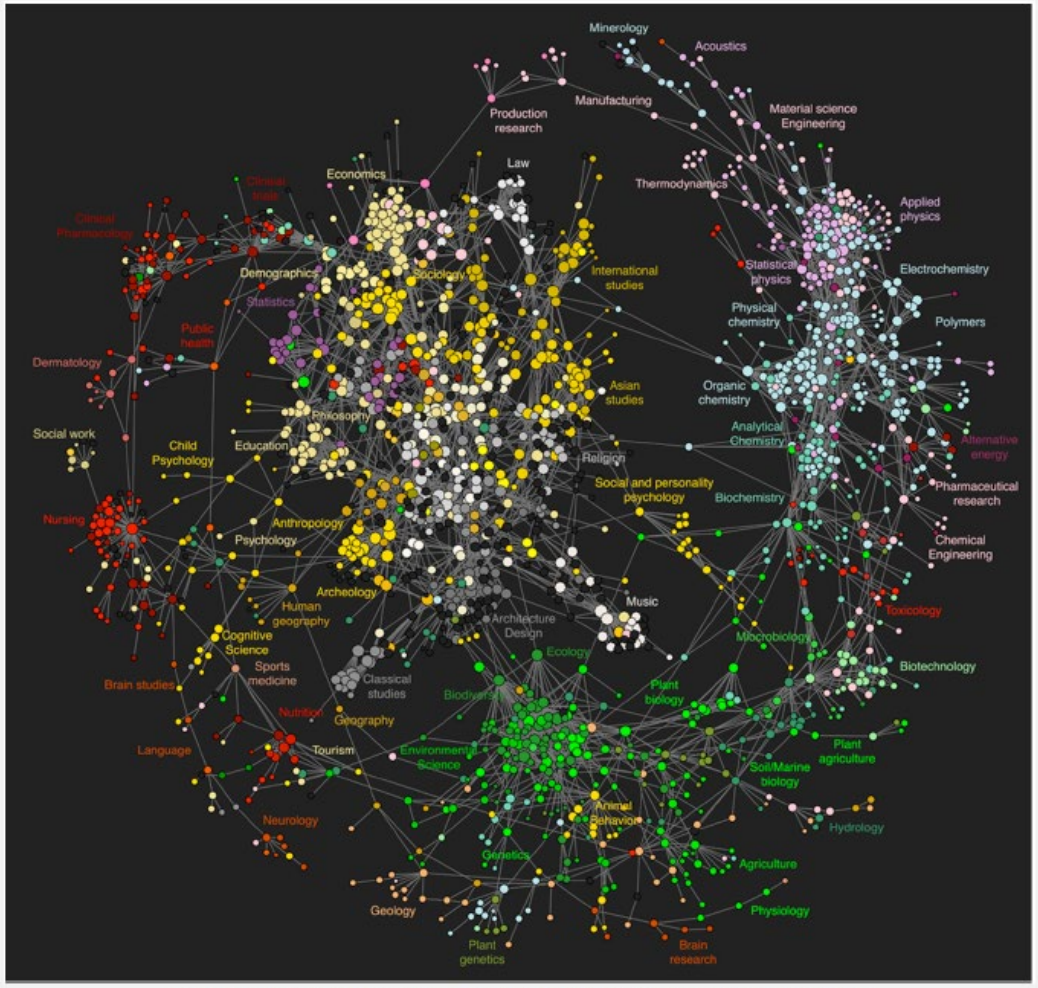


Protein interaction network



Reference: Jeong et al, Nature Review | Genetics

Science clickstreams – citation networks



http://www.plosone.org/article/info:doi/10.1371/journal.pone.0004803

Facebook connections

"Visualizing Friendships" by Paul Butler

Health studies

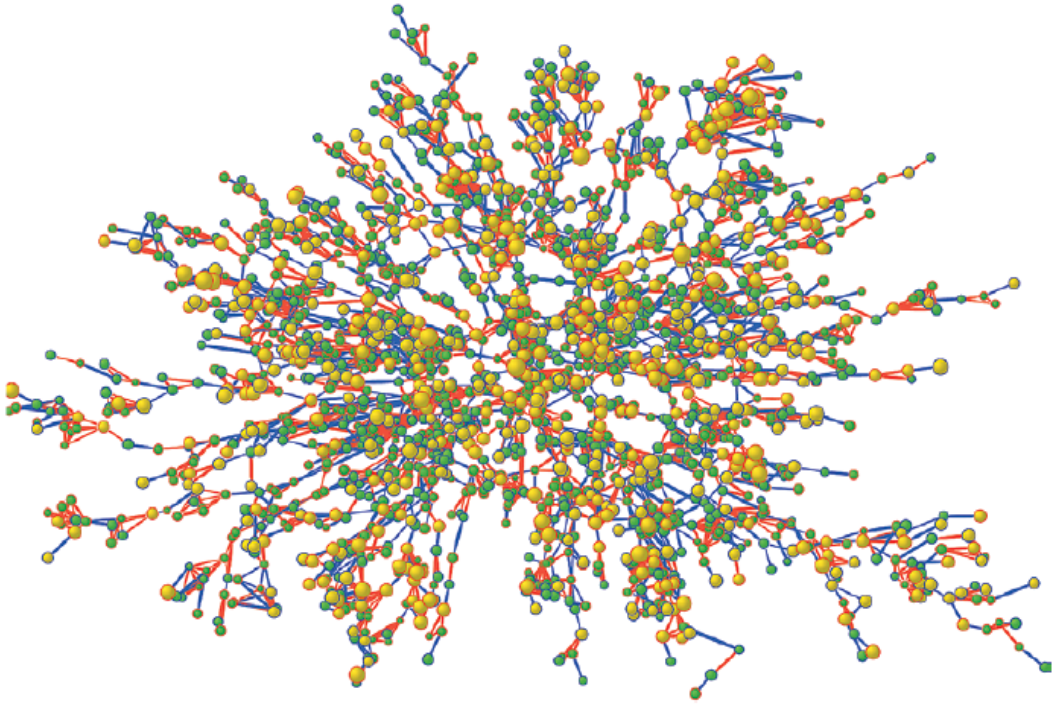
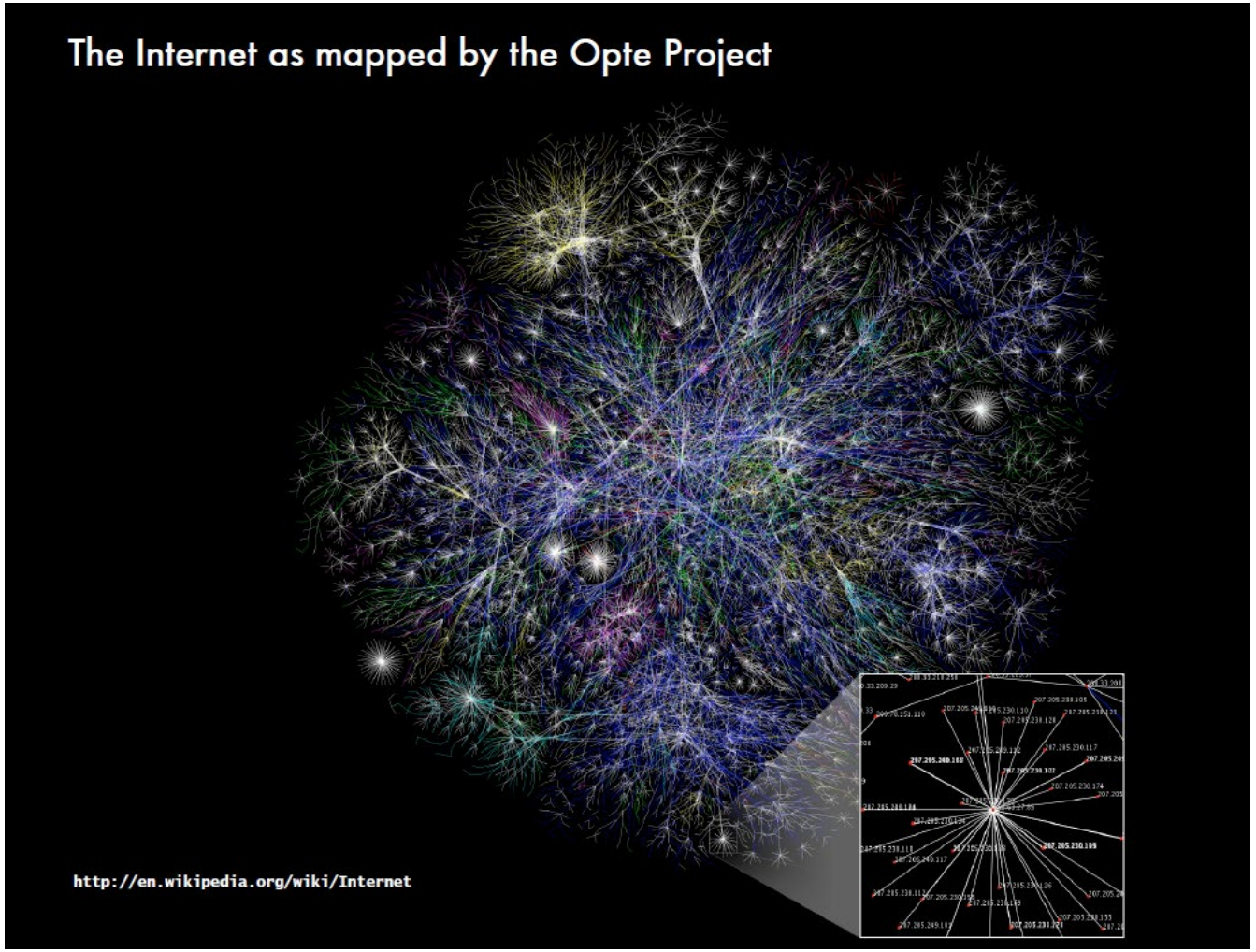


Figure 1. Largest Connected Subcomponent of the Social Network in the Framingham Heart Study in the Year 2000.
Each circle (node) represents one person in the data set. There are 2200 persons in this subcomponent of the social network. Circles with red borders denote women, and circles with blue borders denote men. The size of each circle is proportional to the person's body-mass index. The interior color of the circles indicates the person's obesity status: yellow denotes an obese person (body-mass index, ≥30) and green denotes a nonobese person. The colors of the ties between the nodes indicate the relationship between them: purple denotes a friendship or marital tie and orange denotes a familial tie.

"The Spread of Obesity in a Large Social Network over 32 Years" by Christakis and Fowler in New England Journal of Medicine, 2007

Internet links

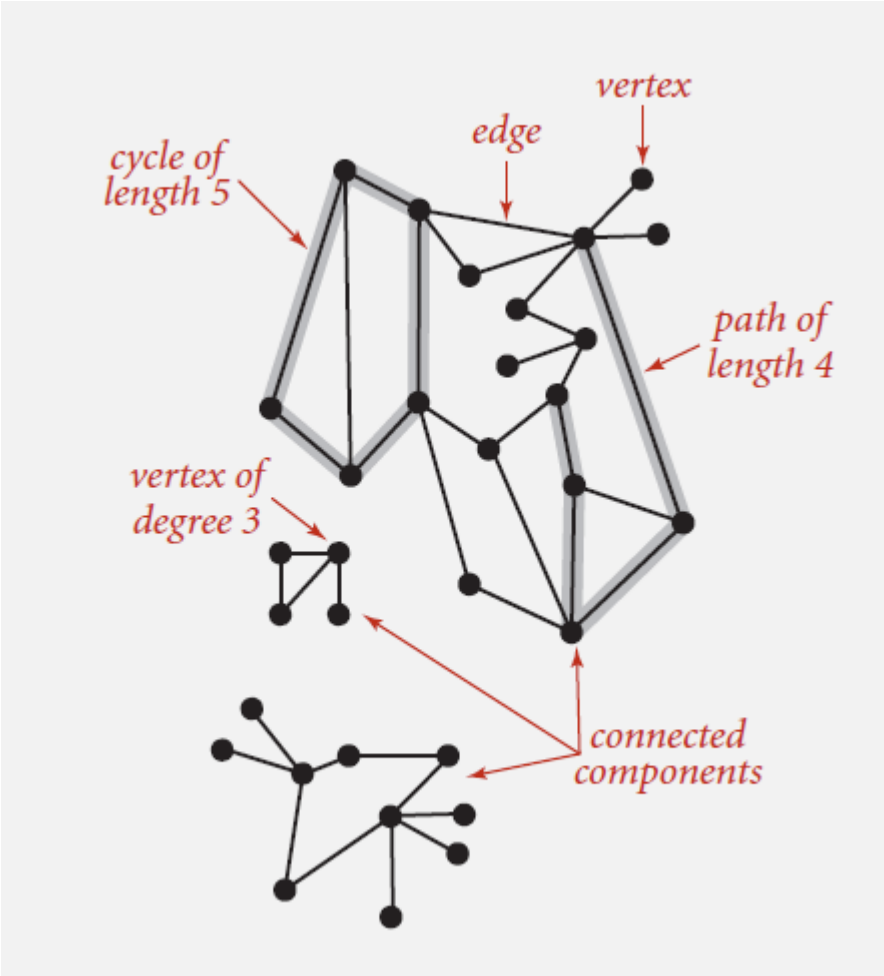


How connected are we?

- Small-world experiment by Milgram
- 6 degrees of separation
  - 3.57 on facebook
- 6 degrees of Kevin Bacon
- Erdos number

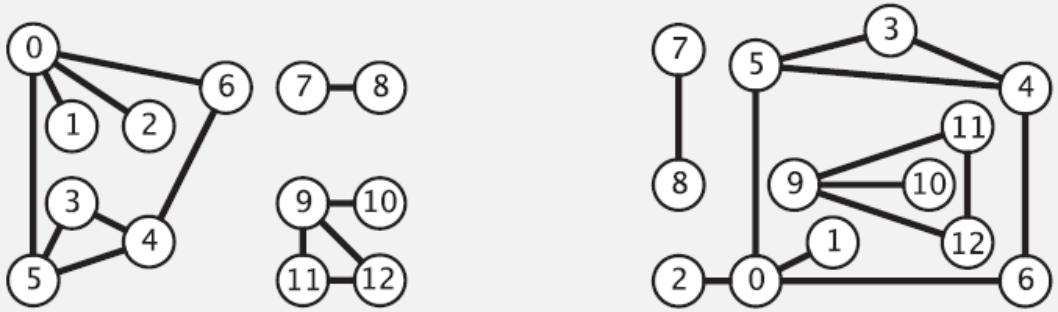
Graph terminology

- Path - Sequence of vertices connected by edges.
- Cycle - Path whose first and last vertices are the same.
- Two vertices are connected if there is a path between them



Graph representation

Graph drawing. Provides intuition about the structure of the graph.



two drawings of the same graph

Caveat. Intuition can be misleading.

Graph API

public class Graph	
Graph(int V)	*create an empty graph with V vertices*
Graph(In in)	*create a graph from input stream*
void addEdge(int v, int w)	*add an edge v-w*
Iterable<Integer> adj(int v)	*vertices adjacent to v*
int V()	*number of vertices*
int E()	*number of edges*

```
In in = new In(args[0]);
Graph G = new Graph(in);

for (int v = 0; v < G.V(); v++)
   for (int w : G.adj(v))
      StdOut.println(v + "-" + w);
```

read graph from input stream

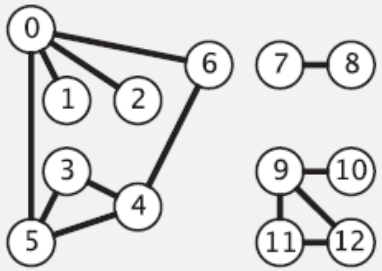
print out each edge (twice)

Graph API: sample client

Graph input format.

tinyG.txt

```
V → 13
    13 ← E
    0 5
    4 3
    0 1
    9 12
    6 4
    5 4
    0 2
    11 12
    9 10
    0 6
    7 8
    9 11
    5 3
```




```
% java Test tinyG.txt
0-6
0-2
0-1
0-5
1-0
2-0
3-5
3-4
⋮
12-11
12-9
```

```
In in = new In(args[0]);
Graph G = new Graph(in);

for (int v = 0; v < G.V(); v++)
   for (int w : G.adj(v))
      StdOut.println(v + "-" + w);
```

read graph from input stream

print out each edge (twice)

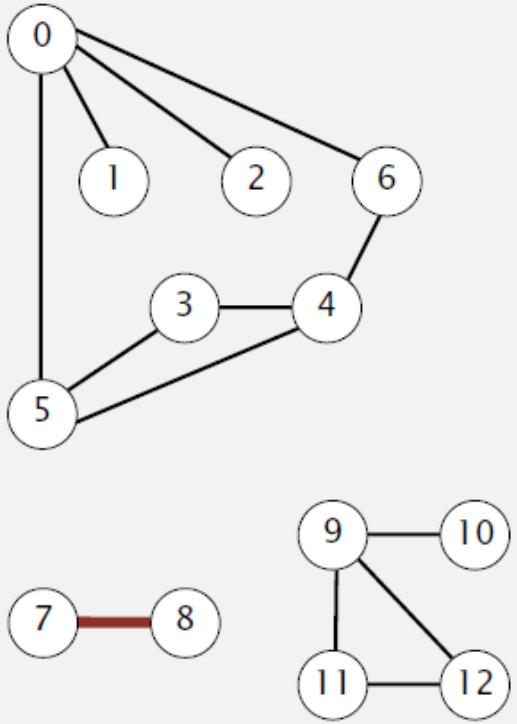
Typical graph-processing code

public class Graph		
	Graph(int V)	*create an empty graph with V vertices*
	Graph(In in)	*create a graph from input stream*
void	addEdge(int v, int w)	*add an edge v-w*
Iterable<Integer>	adj(int v)	*vertices adjacent to v*
int	V()	*number of vertices*
int	E()	*number of edges*

```
// degree of vertex v in graph G
public static int degree(Graph G, int v)
{
    int degree = 0;
    for (int w : G.adj(v))
       degree++;
    return degree;
}
```

Set-of-edges graph representation

Maintain a list of the edges (linked list or array).



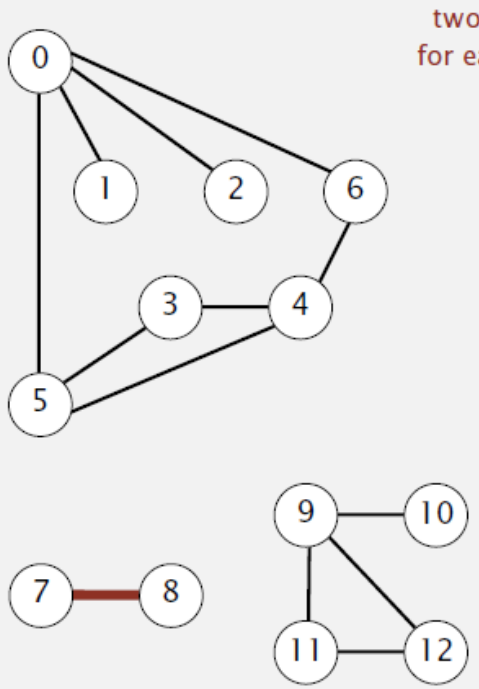
0	1
0	2
0	5
0	6
3	4
3	5
4	5
4	6
7	8
9	10
9	11
9	12
11	12

Q. How long to iterate over vertices adjacent to v ?

Adjacency-matrix graph representation

Maintain a two-dimensional V-by-V boolean array;

for each edge v–w in graph: `adj[v][w] = adj[w][v] = true`.



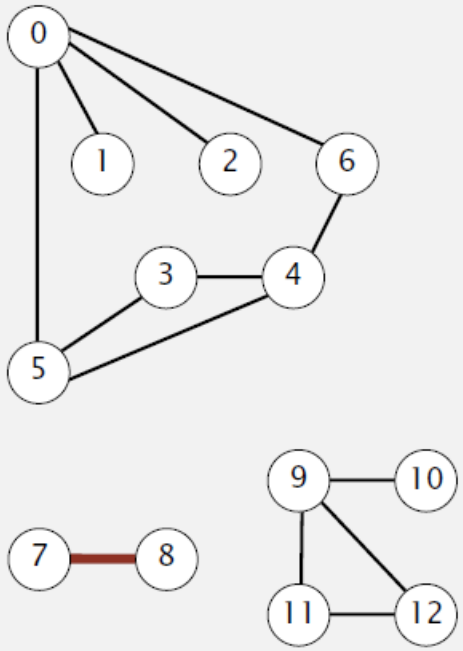
two entries for each edge

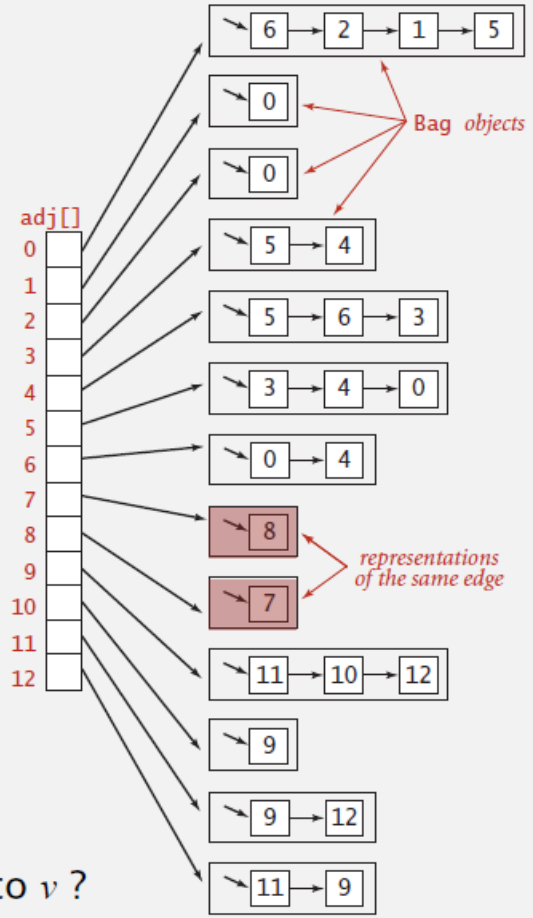
	0	1	2	3	4	5	6	7	8	9	10	11	12
0	0	1	1	0	0	1	1	0	0	0	0	0	0
1	1	0	0	0	0	0	0	0	0	0	0	0	0
2	1	0	0	0	0	0	0	0	0	0	0	0	0
3	0	0	0	0	1	1	0	0	0	0	0	0	0
4	0	0	0	1	0	1	1	0	0	0	0	0	0
5	1	0	0	1	1	0	0	0	0	0	0	0	0
6	1	0	0	0	1	0	0	0	0	0	0	0	0
7	0	0	0	0	0	0	0	0	1	0	0	0	0
8	0	0	0	0	0	0	0	1	0	0	0	0	0
9	0	0	0	0	0	0	0	0	0	0	1	1	1
10	0	0	0	0	0	0	0	0	0	1	0	0	0
11	0	0	0	0	0	0	0	0	0	1	0	0	1
12	0	0	0	0	0	0	0	0	0	1	0	1	0

Q. How long to iterate over vertices adjacent to v ?

Adjacency-list graph representation

Maintain vertex-indexed array of lists.





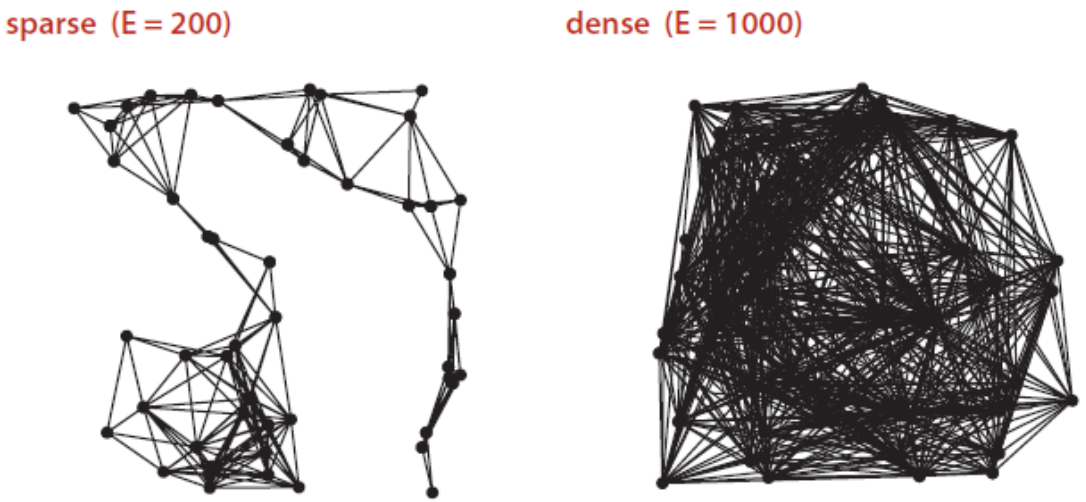
Q. How long to iterate over vertices adjacent to v ?

Graph representations

In practice. Use adjacency-lists representation.

- Algorithms based on iterating over vertices adjacent to v.
- Real-world graphs tend to be sparse.

huge number of vertices,
small average vertex degree

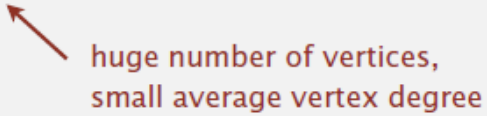


Two graphs (V = 50)

Graph representations

In practice. Use adjacency-lists representation.

- Algorithms based on iterating over vertices adjacent to v.
- Real-world graphs tend to be sparse.



representation	space	add edge	edge between v and w?	iterate over vertices adjacent to v?
list of edges	E	1	E	E
adjacency matrix	V^2	1 *	1	V
adjacency lists	$E + V$	1	$degree(v)$	$degree(v)$

* disallows parallel edges

Adjacency-list graph representation: Java implementation

```
public class Graph
{
   private final int V;
   private Bag<Integer>[] adj;

   public Graph(int V)
   {
      this.V = V;
      adj = (Bag<Integer>[]) new Bag[V];
      for (int v = 0; v < V; v++)
         adj[v] = new Bag<Integer>();
   }

   public void addEdge(int v, int w)
   {
      adj[v].add(w);
      adj[w].add(v);
   }

   public Iterable<Integer> adj(int v)
   {  return adj[v];  }
}
```

adjacency lists
(using Bag data type)

create empty graph
with V vertices

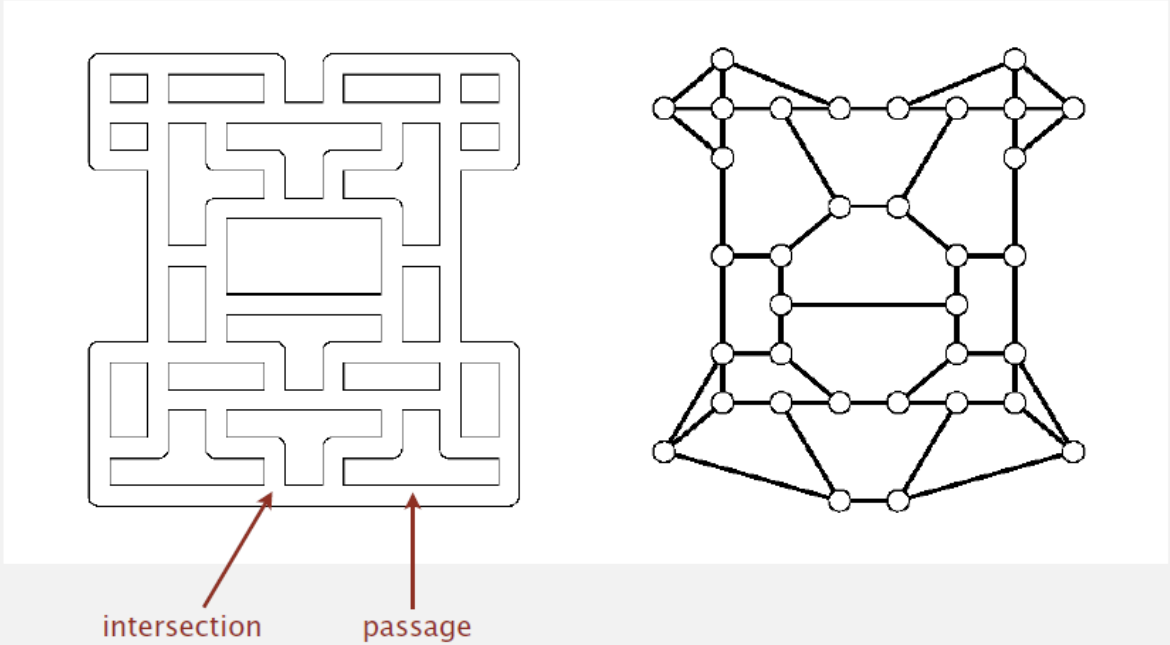
add edge v-w
(parallel edges and
self-loops allowed)

iterator for vertices adjacent to v

Depth First Search (DFS)

Maze graph.

- Vertex = intersection.
- Edge = passage.

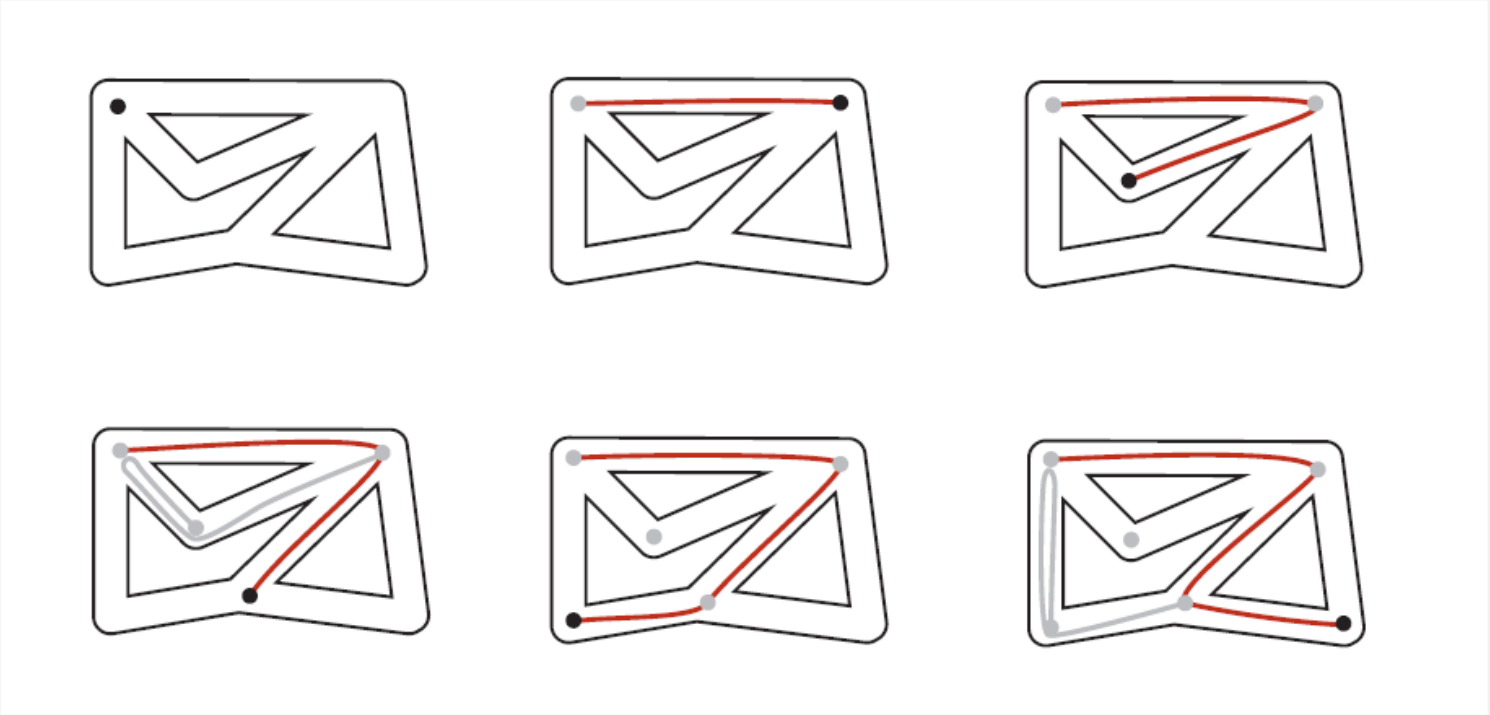


Goal. Explore every intersection in the maze.

Trémaux maze exploration

Algorithm.

- Unroll a ball of string behind you.
- Mark each visited intersection and each visited passage.
- Retrace steps when no unvisited options.



Depth-first search (DFS)

- Undirected or directed graphs
  - Undirected for now
- Find all vertices connected to a given source vertex
- Find a path between 2 vertices

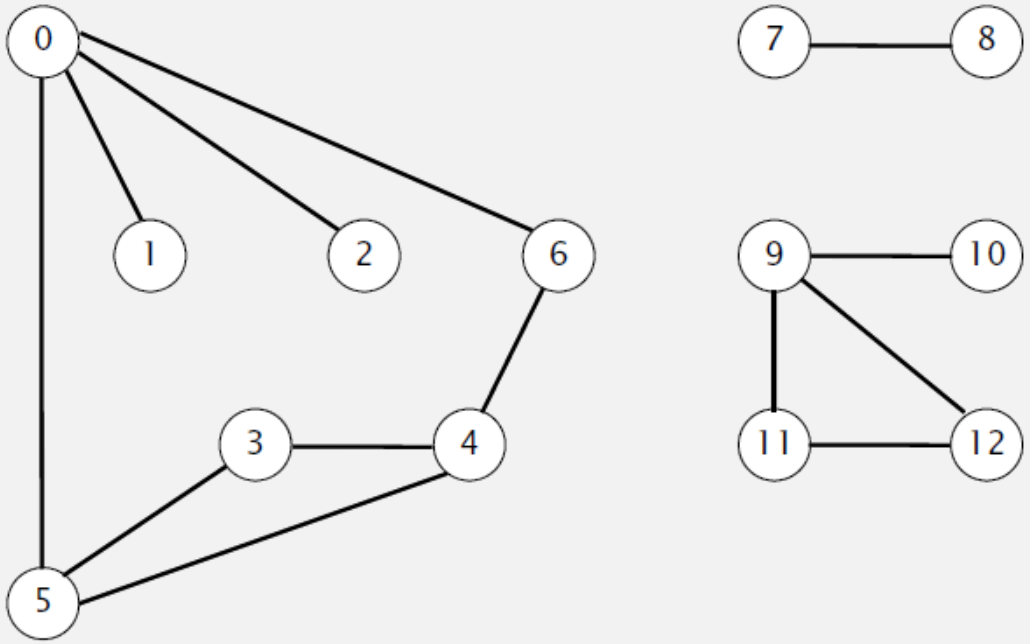
- Mark vertex v as visited
- Recursively visit all unmarked vertices adjacent to v (or pointing from v, in directed graphs)

- boolean marked [] – list visited vertices
- Integer edgeTo[] – edgeTo[w]=v, means edge v-w taken to visit W (for the first time)

Depth-first search demo

To visit a vertex v :

- Mark vertex v as visited.
- Recursively visit all unmarked vertices adjacent to v.



graph G

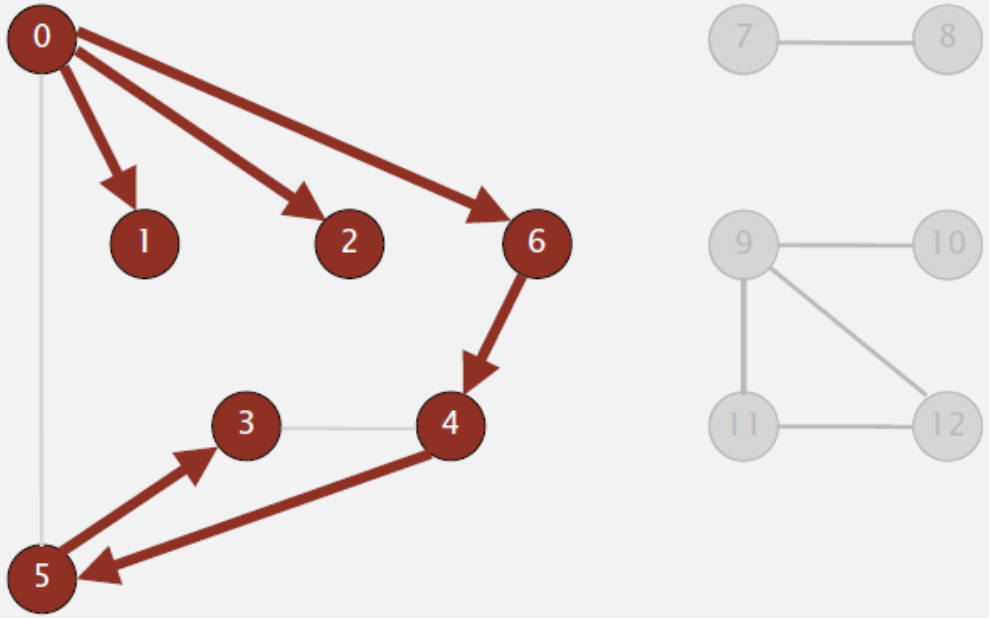
tinyG.txt

```
V → 13
    13   ← E
0  5
4  3
0  1
9  12
6  4
5  4
0  2
11  12
9  10
0  6
7  8
9  11
5  3
```

Depth-first search demo

To visit a vertex v :

- Mark vertex v as visited.
- Recursively visit all unmarked vertices adjacent to v.

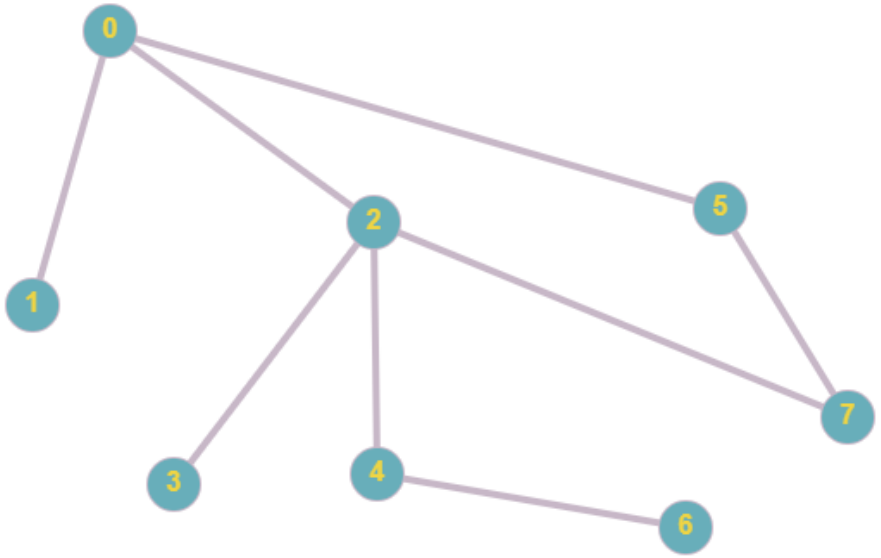


v	marked[]	edgeTo[]
0	T	–
1	T	0
2	T	0
3	T	5
4	T	6
5	T	4
6	T	0
7	F	–
8	F	–
9	F	–
10	F	–
11	F	–
12	F	–

vertices reachable from 0

DFS exercise

v	marked[]	edgeTo[]
0		
1		
2		
3		
4		
5		
6		
7		



Source vertex: 0
Provide the trace in which vertices were visited

http://graphonline.ru/en/ - draw your own graphs and run algorithms

Design pattern for graph processing

Design pattern. Decouple graph data type from graph processing.

- Create a `Graph` object.
- Pass the `Graph` to a graph-processing routine.
- Query the graph-processing routine for information.

public class Paths		
	`Paths(Graph G, int s)`	*find paths in G from source s*
`boolean`	`hasPathTo(int v)`	*is there a path from s to v?*
`Iterable<Integer>`	`pathTo(int v)`	*path from s to v; null if no such path*

```
Paths paths = new Paths(G, s);
for (int v = 0; v < G.V(); v++)
   if (paths.hasPathTo(v))
      StdOut.println(v);
```

print all vertices connected to s

Depth-first search: data structures

To visit a vertex v :

- Mark vertex v as visited.
- Recursively visit all unmarked vertices adjacent to v.

Data structures.

- Boolean array `marked[]` to mark visited vertices.
- Integer array `edgeTo[]` to keep track of paths.

  `(edgeTo[w] == v)` means that edge `v-w` taken to visit `w` for first time
- Function-call stack for recursion.

Depth-first search: Java implementation

```
public class DepthFirstPaths
{
   private boolean[] marked;
   private int[] edgeTo;
   private int s;

   public DepthFirstPaths(Graph G, int s)
   {
      ...
      dfs(G, s);
   }

   private void dfs(Graph G, int v)
   {
      marked[v] = true;
      for (int w : G.adj(v))
         if (!marked[w])
         {
            dfs(G, w);
            edgeTo[w] = v;
         }
   }
}
```

marked[v] = true if v connected to s

edgeTo[v] = previous vertex on path from s to v

initialize data structures

find vertices connected to s

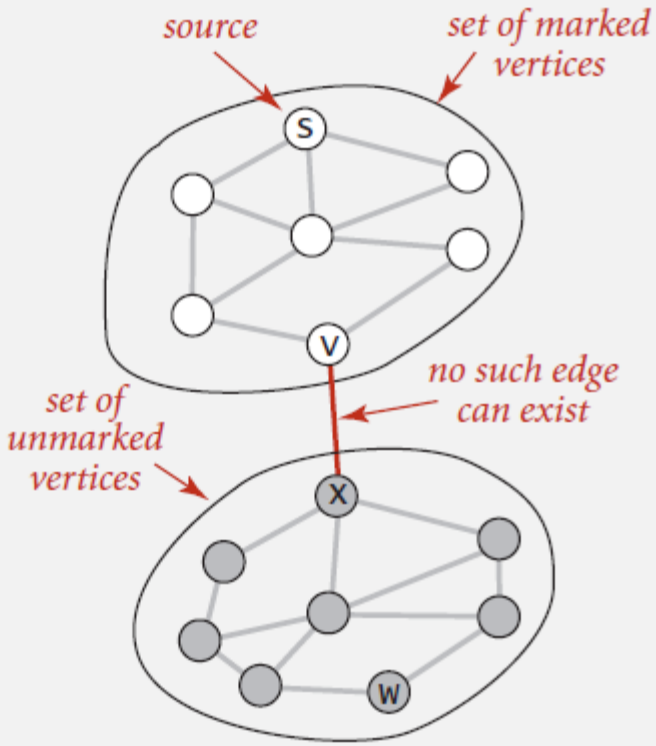
recursive DFS does the work

Depth-first search: properties

Proposition. DFS marks all vertices connected to s in time proportional to the sum of their degrees (plus time to initialize the `marked[]` array).

Pf. [correctness]

- If w marked, then w connected to s (why?)
- If w connected to s, then w marked.
  (if w unmarked, then consider last edge on a path from s to w that goes from a marked vertex to an unmarked one).



Pf. [running time]

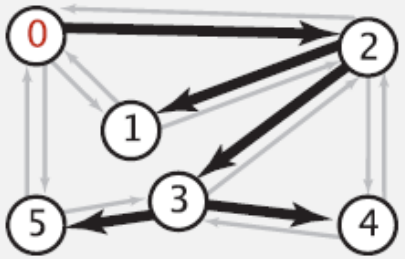
Each vertex connected to s is visited once.

Depth-first search: properties

Proposition. After DFS, can check if vertex v is connected to s in constant time and can find v–s path (if one exists) in time proportional to its length.

Pf. `edgeTo[]` is parent-link representation of a tree rooted at vertex `s`.

```
public boolean hasPathTo(int v)
{  return marked[v];  }

public Iterable<Integer> pathTo(int v)
{
   if (!hasPathTo(v)) return null;
   Stack<Integer> path = new Stack<Integer>();
   for (int x = v; x != s; x = edgeTo[x])
      path.push(x);
   path.push(s);
   return path;
}
```



edgeTo[]

0	
1	2
2	0
3	2
4	3
5	3

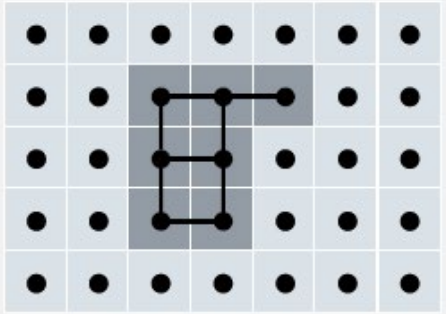
Depth-first search application: flood fill

Challenge. Flood fill (Photoshop magic wand).

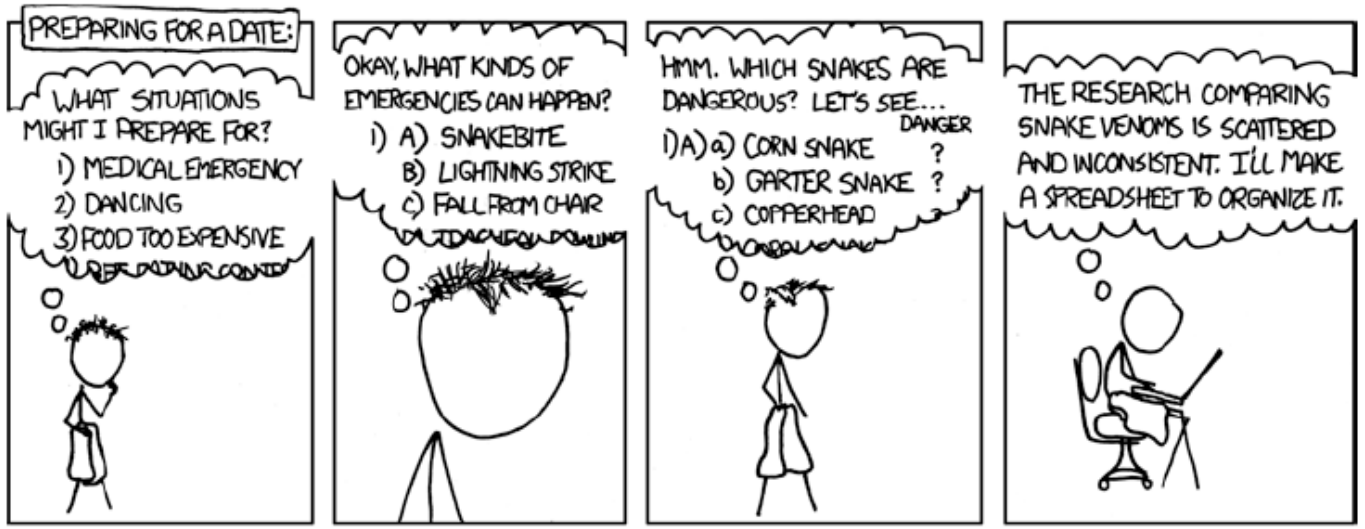
Assumptions. Picture has millions to billions of pixels.

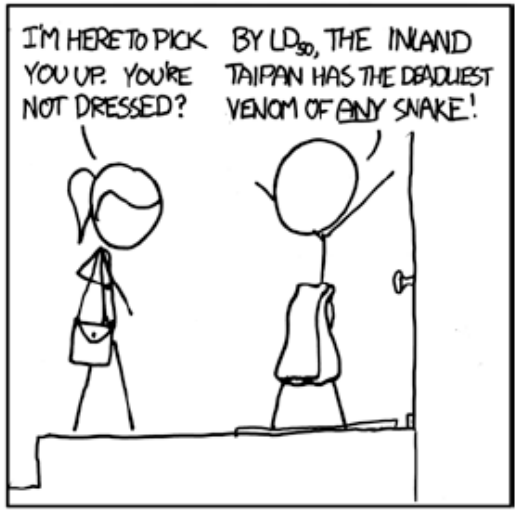
Solution. Build a grid graph (implicitly).

- Vertex: pixel.
- Edge: between two adjacent gray pixels.
- Blob: all pixels connected to given pixel.



Depth-first search application: preparing for a date





xkcd

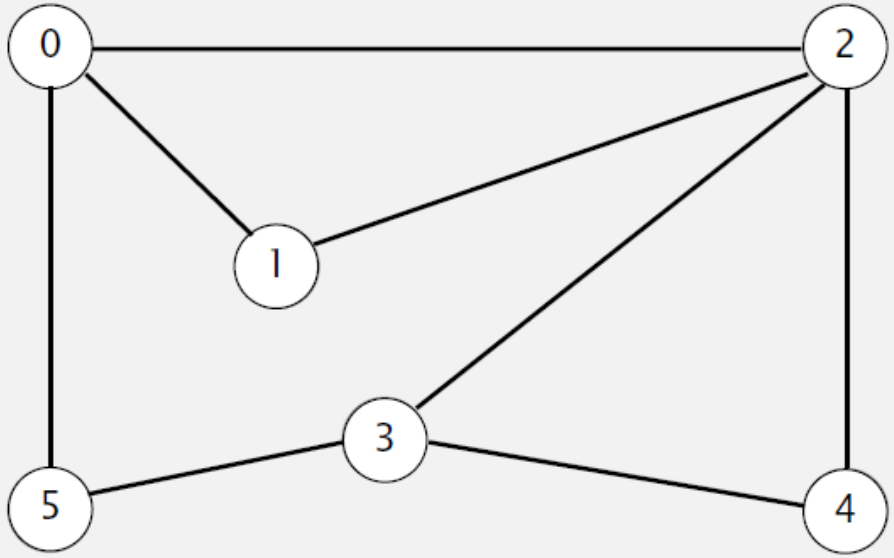
http://xkcd.com/761/

Breadth First Search (BFS)

Breadth-first search demo

Repeat until queue is empty:

- Remove vertex v from queue.
- Add to queue all unmarked vertices adjacent to v and mark them.



tinyCG.txt

V

6

E

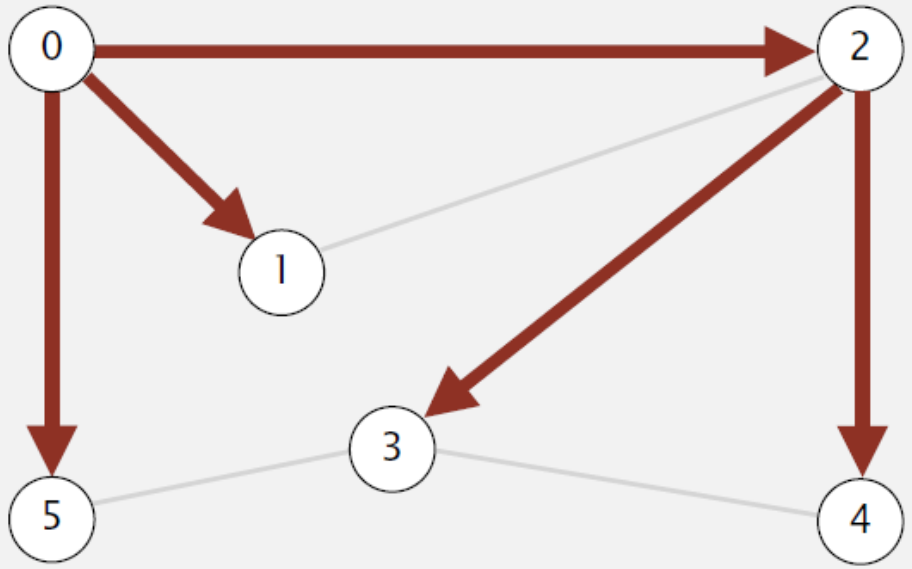
8

0 5
2 4
2 3
1 2
0 1
3 4
3 5
0 2

Breadth-first search demo

Repeat until queue is empty:

- Remove vertex v from queue.
- Add to queue all unmarked vertices adjacent to v and mark them.



v	edgeTo[]	distTo[]
0	–	0
1	0	1
2	0	1
3	2	2
4	2	2
5	0	1

Breadth-first search

Repeat until queue is empty:

- Remove vertex v from queue.
- Add to queue all unmarked vertices adjacent to v and mark them.

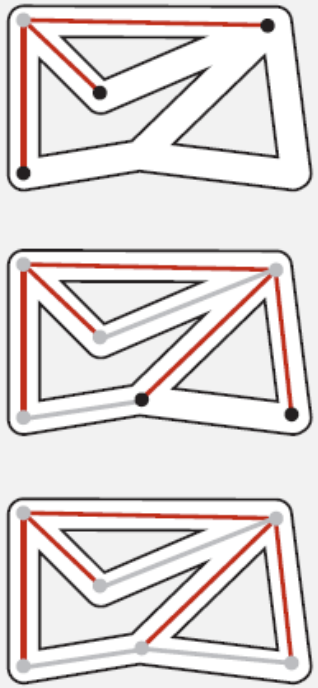
BFS (from source vertex s)

Put s onto a FIFO queue, and mark s as visited.

Repeat until the queue is empty:

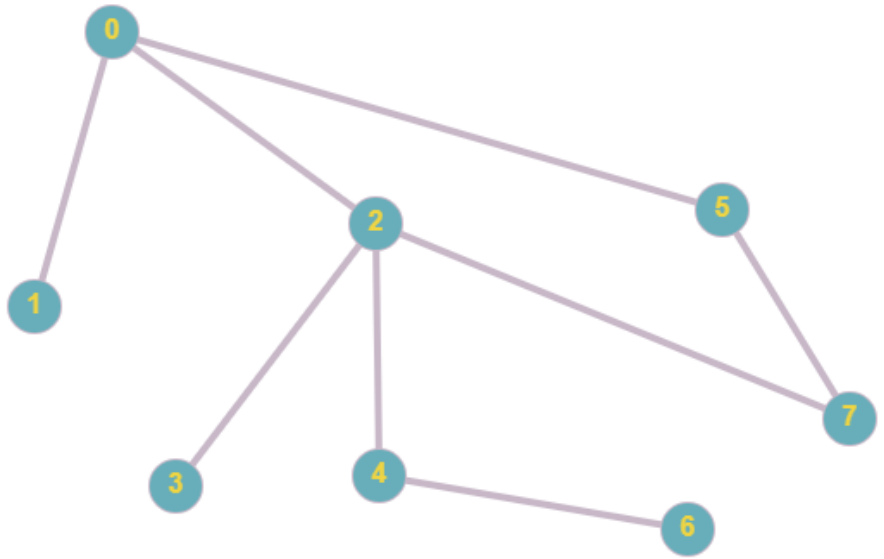
- remove the least recently added vertex v

- add each of v's unvisited neighbors to the queue, and mark them as visited.



BFS Exercise

v	marked[]	edgeTo[]	distanceTo[]
0			
1			
2			
3			
4			
5			
6			
7			



Source vertex: 0

Fill in the table and provide trace of the queue content – order in which vertices were visited

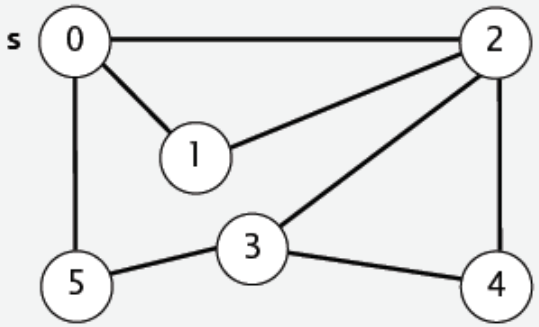
Breadth-first search properties

Q. In which order does BFS examine vertices?

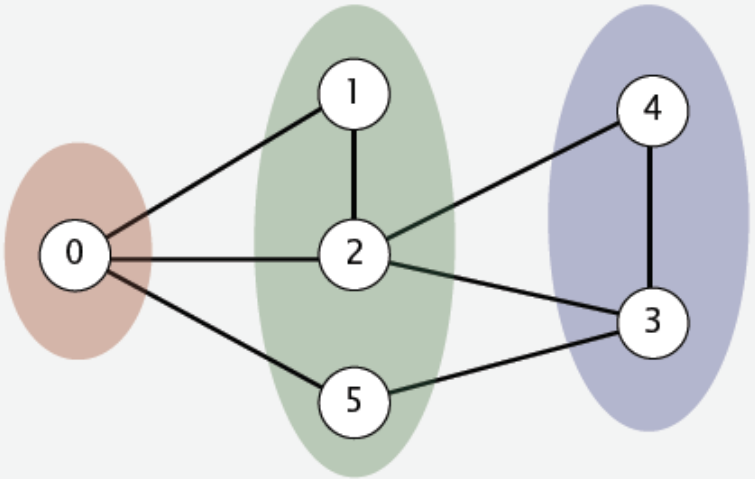
A. Increasing distance (number of edges) from s.

queue always consists of ≥ 0 vertices of distance k from s,
followed by ≥ 0 vertices of distance k+1

Proposition. In any connected graph G, BFS computes shortest paths from s to all other vertices in time proportional to $E + V$.



graph G



dist = 0 dist = 1 dist = 2

How to answer?

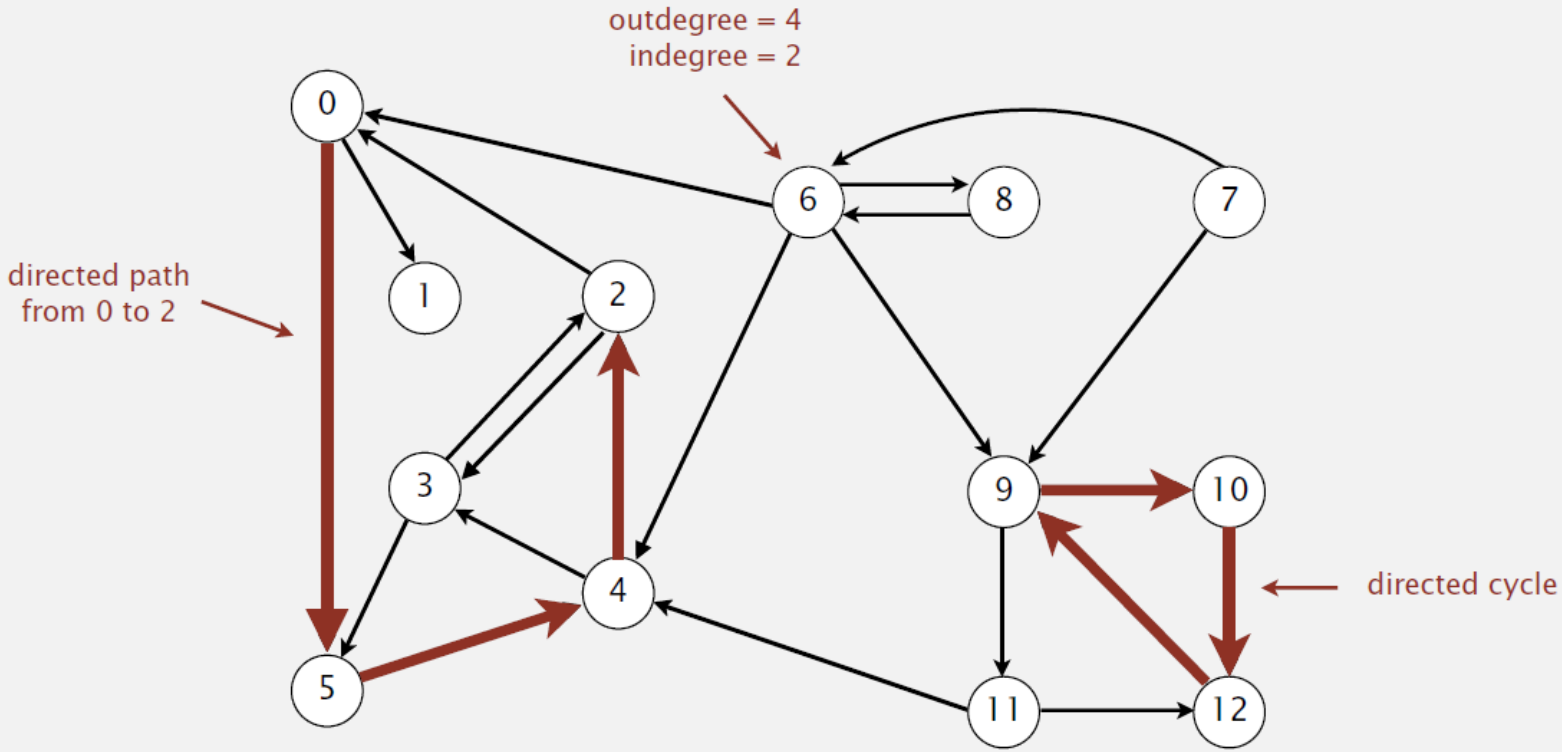
- Does a path from A to B exist?
- Find a shortest path from A to B?
- Is A connected to all other nodes in the system?

- Both DFS and BFS are brute-force/exhaustive-search algorithms
- Other algorithms to follow

Directed Graphs

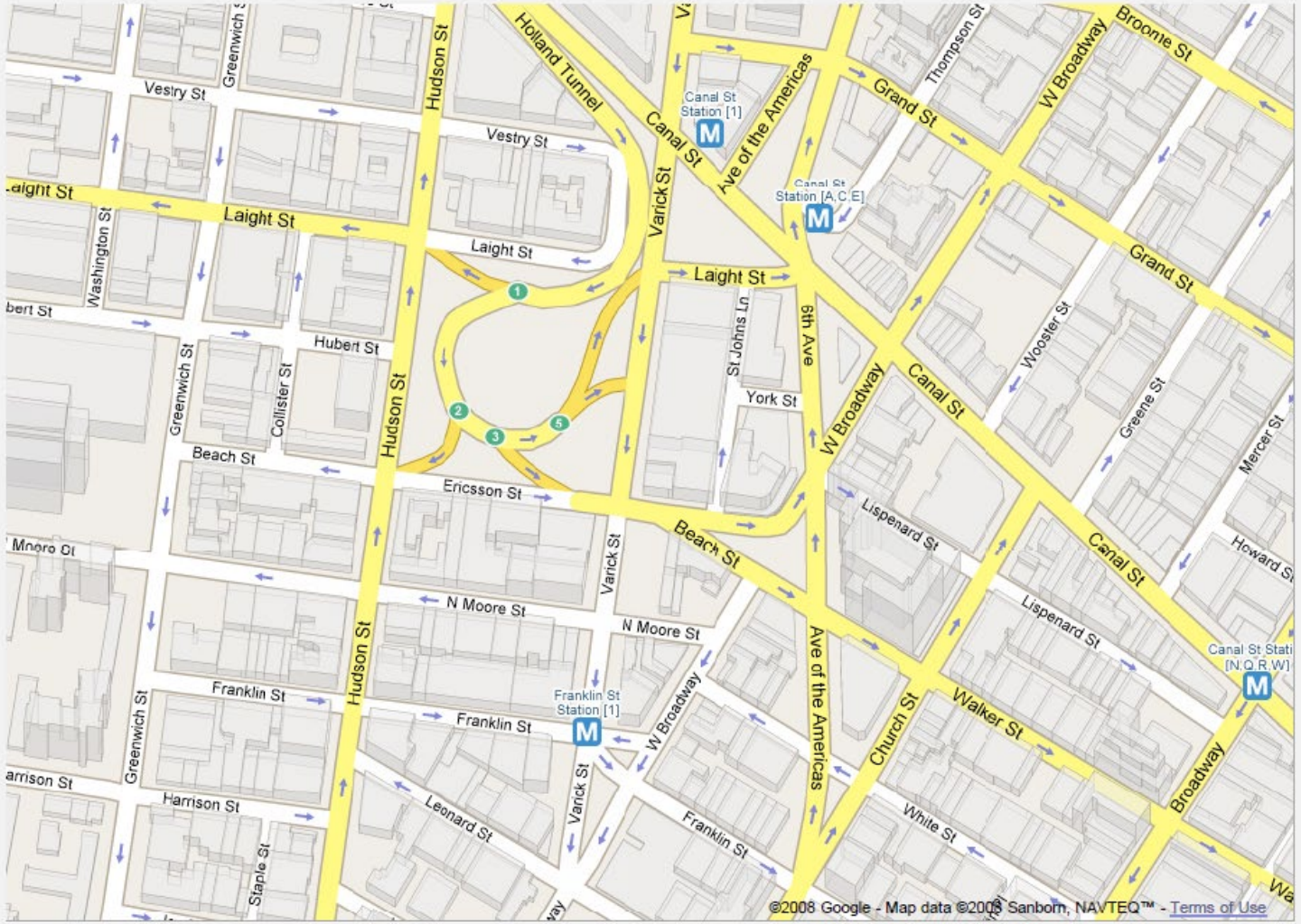
Directed graphs

Digraph. Set of vertices connected pairwise by directed edges.



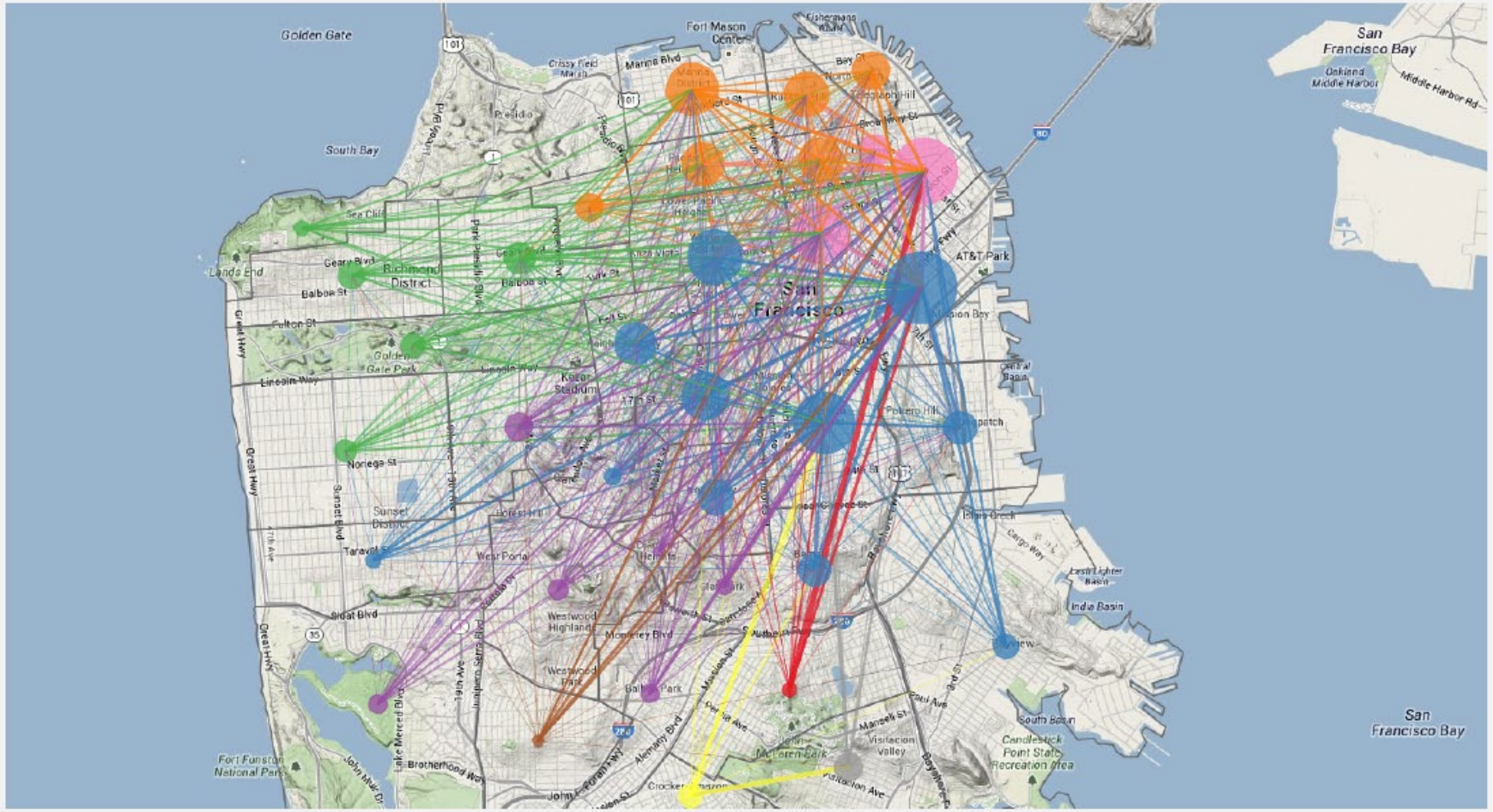
Road network

Vertex = intersection; edge = one-way street.



Uber taxi graph

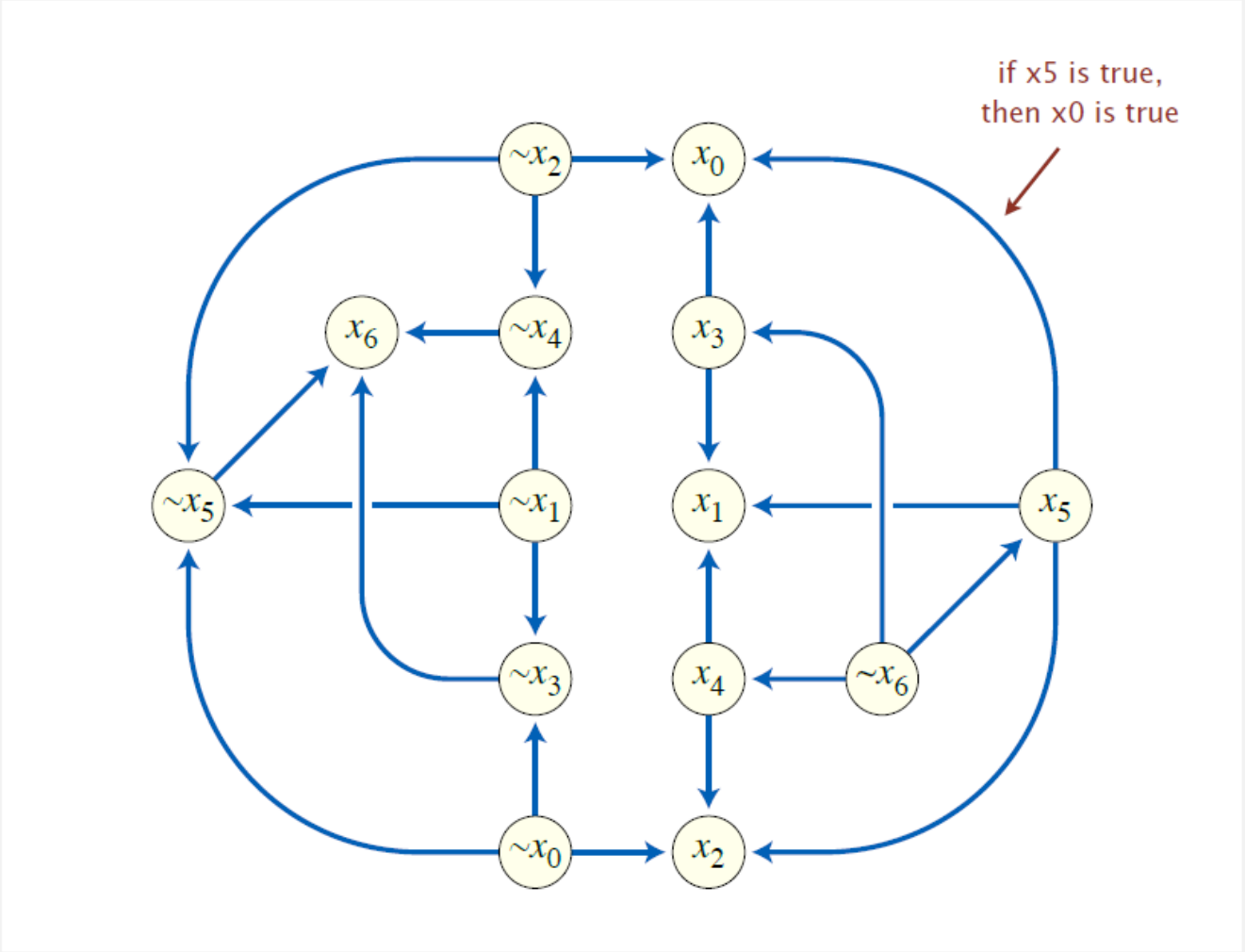
Vertex = taxi pickup; edge = taxi ride.



http://blog.uber.com/2012/01/09/uberdata-san-franciscomics/

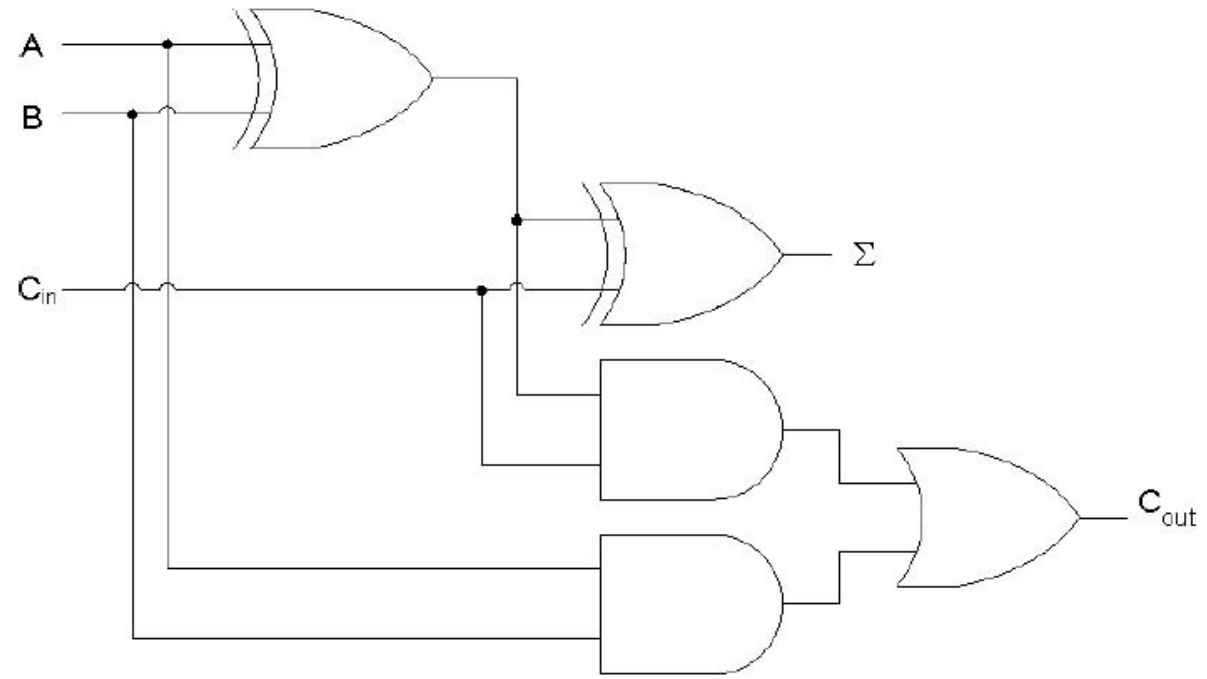
Implication graph

Vertex = variable; edge = logical implication.



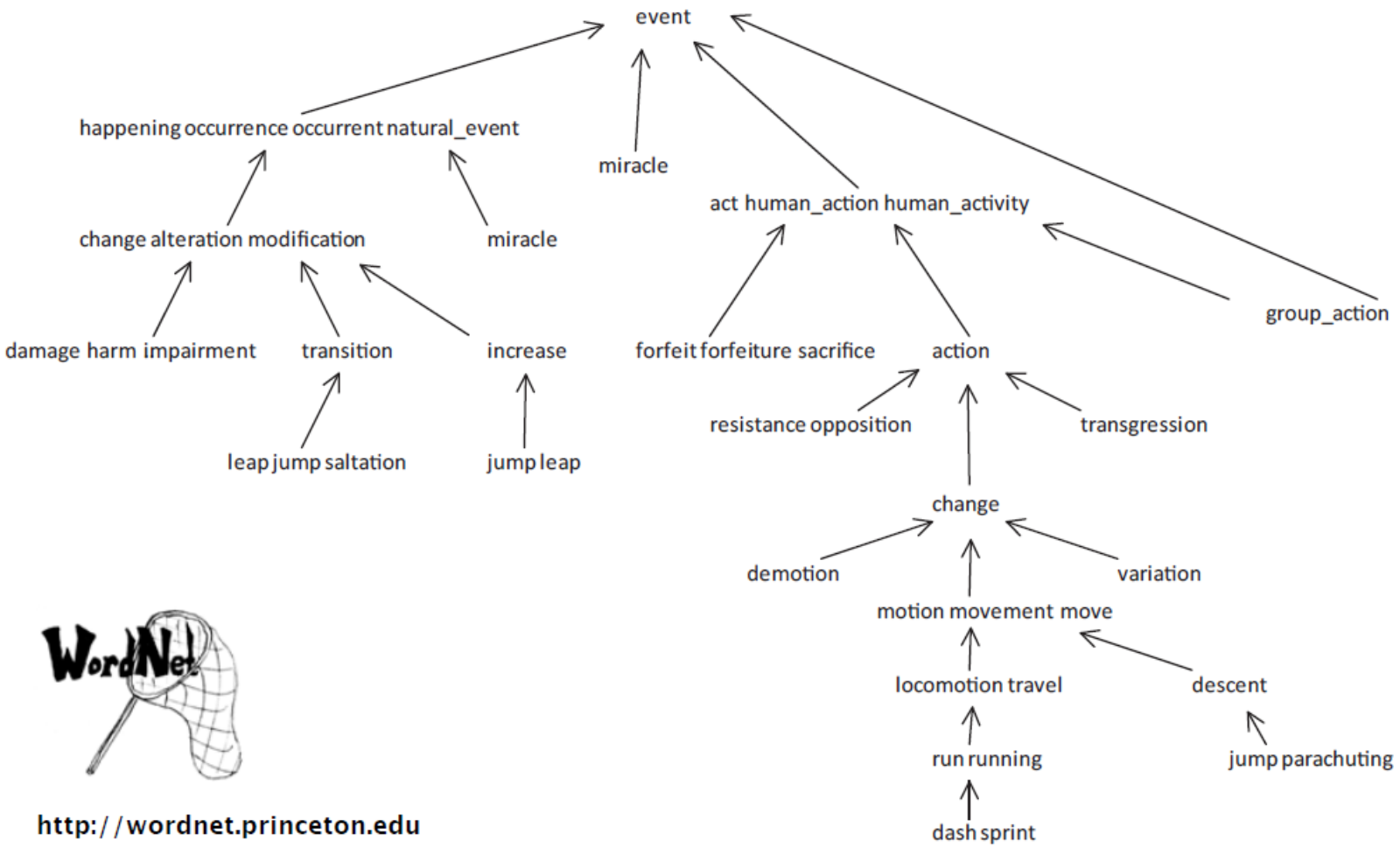
Combinational circuit

Vertex = logical gate; edge = wire.



WordNet graph

Vertex = synset; edge = hypernym relationship.



http://wordnet.princeton.edu

Digraph applications

digraph	vertex	directed edge
transportation	street intersection	one-way street
web	web page	hyperlink
food web	species	predator-prey relationship
WordNet	synset	hypernym
scheduling	task	precedence constraint
financial	bank	transaction
cell phone	person	placed call
infectious disease	person	infection
game	board position	legal move
citation	journal article	citation
object graph	object	pointer
inheritance hierarchy	class	inherits from
control flow	code block	jump

Digraph API

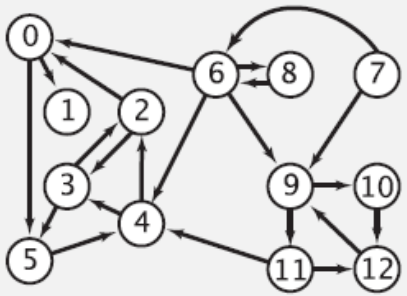
Almost identical to `Graph` API.

public class Digraph		
	`Digraph(int V)`	*create an empty digraph with V vertices*
	`Digraph(In in)`	*create a digraph from input stream*
`void`	`addEdge(int v, int w)`	*add a directed edge v→w*
`Iterable<Integer>`	`adj(int v)`	*vertices pointing from v*
`int`	`V()`	*number of vertices*
`int`	`E()`	*number of edges*
`Digraph`	`reverse()`	*reverse of this digraph*
`String`	`toString()`	*string representation*

Digraph API

tinyDG.txt

```
V
13
22
 4  2
 2  3
 3  2
 6  0
 0  1
 2  0
11 12
12  9
 9 10
 9 11
 7  9
10 12
11  4
 4  3
 3  5
 6  8
 8  6
⋮
```




```
% java Digraph tinyDG.txt
0->5
0->1
2->0
2->3
3->5
3->2
4->3
4->2
5->4
⋮
11->4
11->12
12->9
```

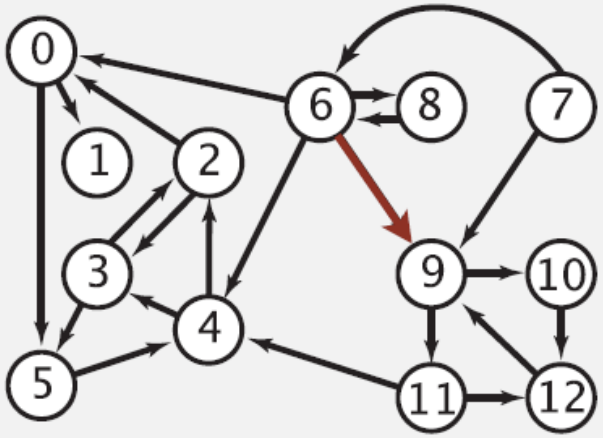
```
In in = new In(args[0]);
Digraph G = new Digraph(in);

for (int v = 0; v < G.V(); v++)
   for (int w : G.adj(v))
      StdOut.println(v + "->" + w);
```

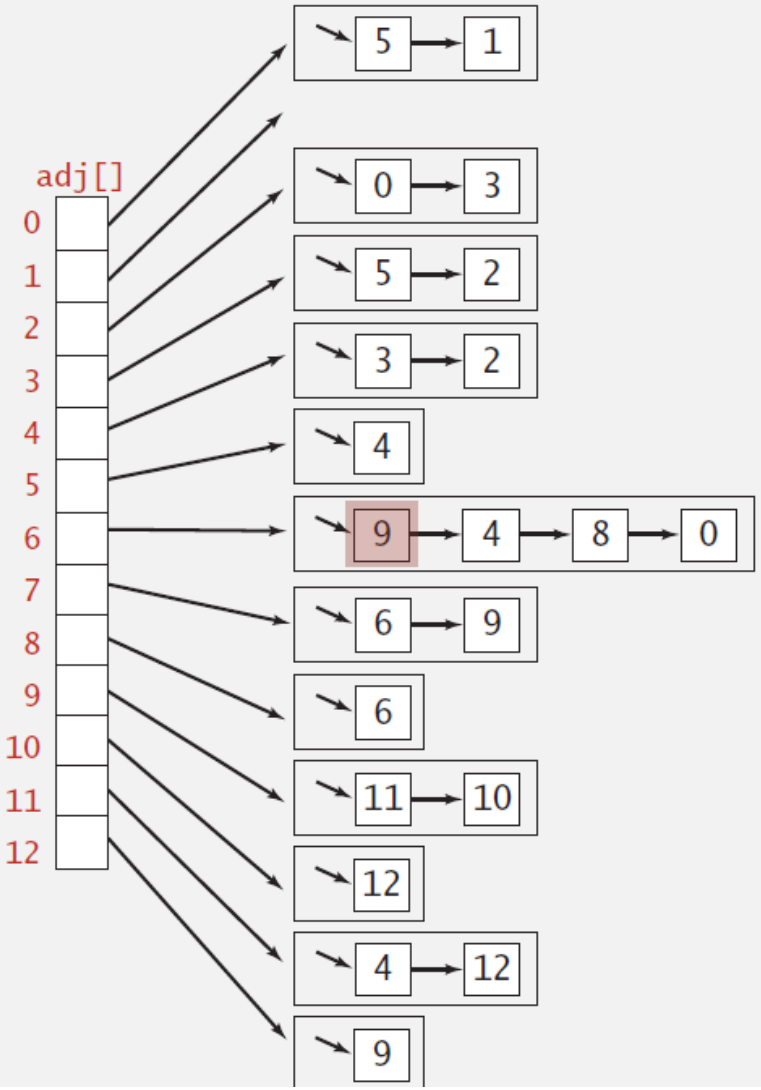
read digraph from input stream

print out each edge (once)

Digraph representation: adjacency lists

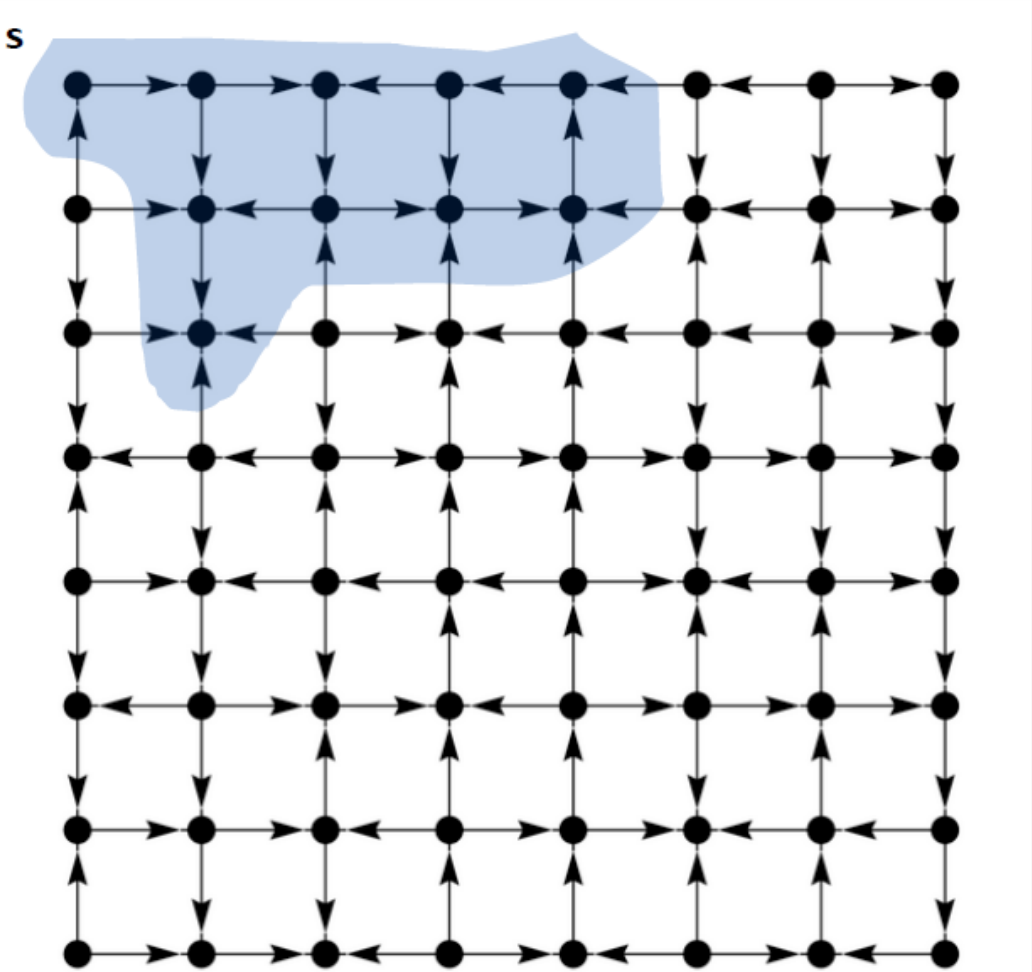
Maintain vertex-indexed array of lists.





Reachability

Problem. Find all vertices reachable from s along a directed path.



Search in digraphs

› BFS and DFS work

DFS in diagraphs

DFS enables direct solution of simple digraph problems.

- ✓ Reachability.
- Path finding.
- Topological sort.
- Directed cycle detection.

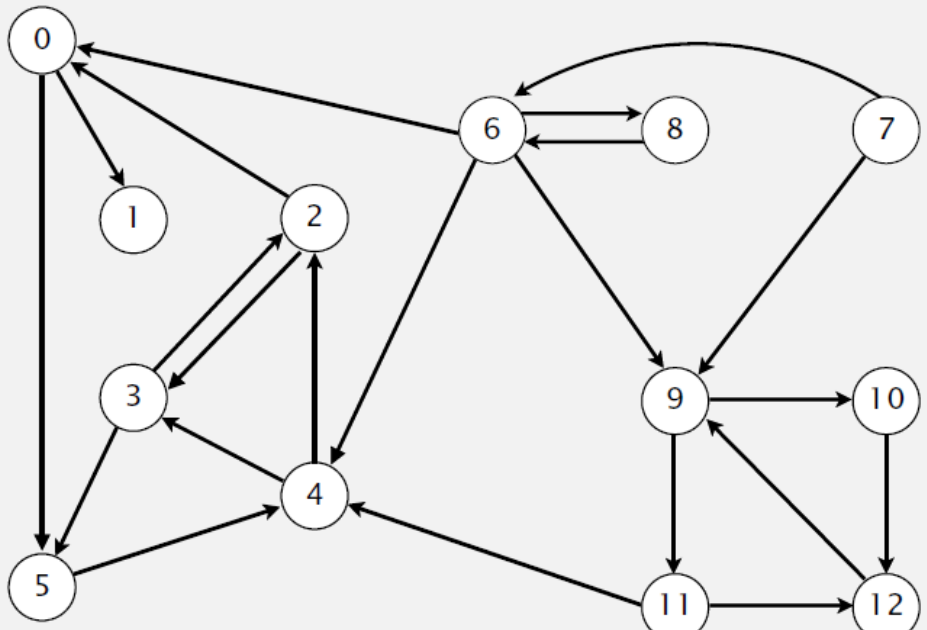
Basis for solving difficult digraph problems.

- 2-satisfiability.
- Directed Euler path.
- Strongly-connected components.

DFS demo

To visit a vertex v :

- Mark vertex v as visited.
- Recursively visit all unmarked vertices pointing from v.

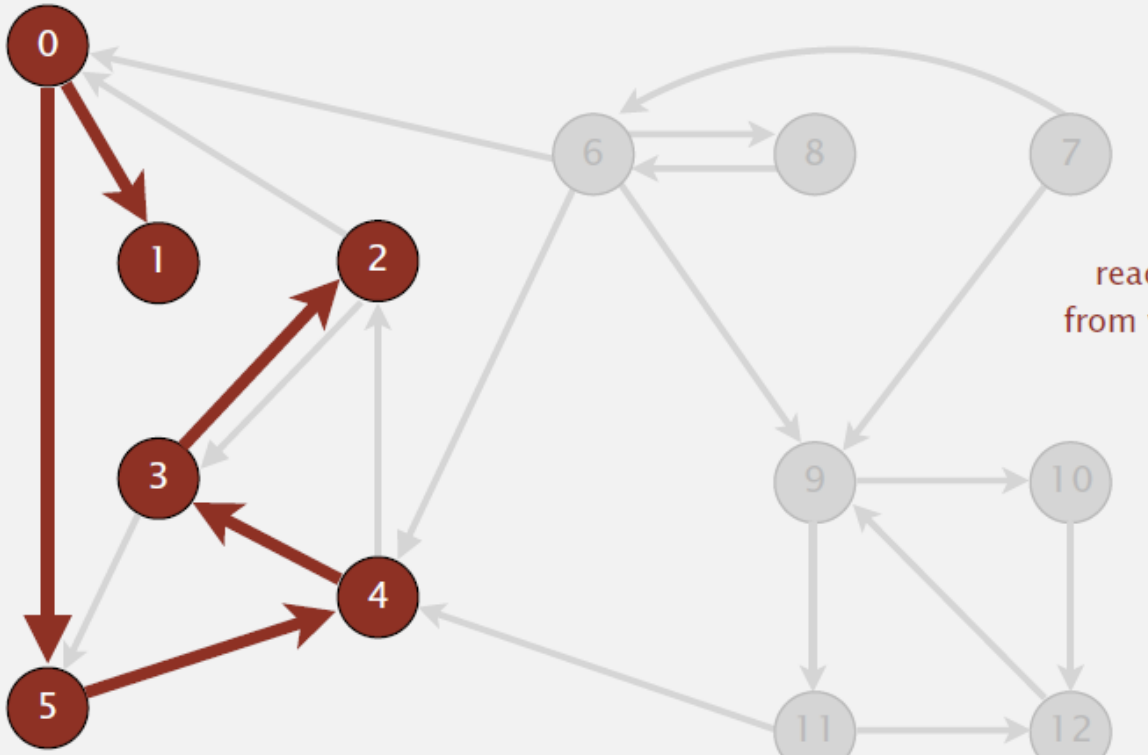


a directed graph

4→2
2→3
3→2
6→0
0→1
2→0
11→12
12→9
9→10
9→11
8→9
10→12
11→4
4→3
3→5
6→8
8→6
5→4
0→5
6→4
6→9
7→6

To visit a vertex v :

- Mark vertex v as visited.
- Recursively visit all unmarked vertices pointing from v.



reachable from vertex 0

v	marked[]	edgeTo[]
0	T	–
1	T	0
2	T	3
3	T	4
4	T	5
5	T	0
6	F	–
7	F	–
8	F	–
9	F	–
10	F	–
11	F	–
12	F	–

reachable from 0

Breadth-first search in digraphs

Same method as for undirected graphs.

- Every undirected graph is a digraph (with edges in both directions).
- BFS is a digraph algorithm.

BFS (from source vertex s)

Put s onto a FIFO queue, and mark s as visited.

Repeat until the queue is empty:

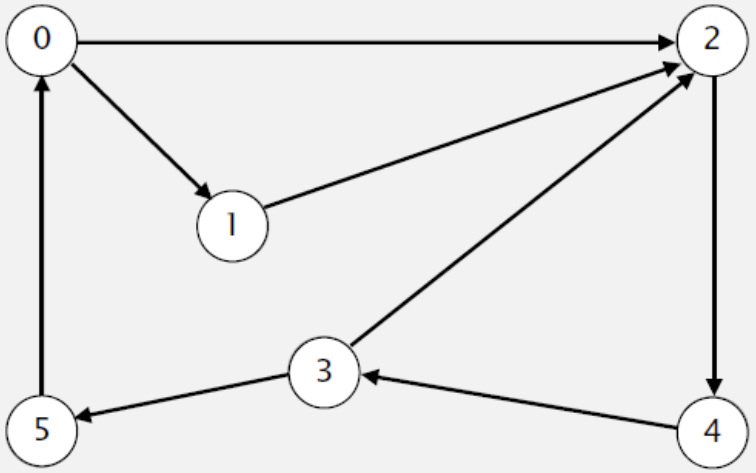
- **remove the least recently added vertex v**
- **for each unmarked vertex pointing from v: add to queue and mark as visited.**

Proposition. BFS computes shortest paths (fewest number of edges) from s to all other vertices in a digraph in time proportional to $E + V$.

Directed breadth-first search demo

Repeat until queue is empty:

- Remove vertex v from queue.
- Add to queue all unmarked vertices pointing from v and mark them.



graph G

tinyDG2.txt

V → 6

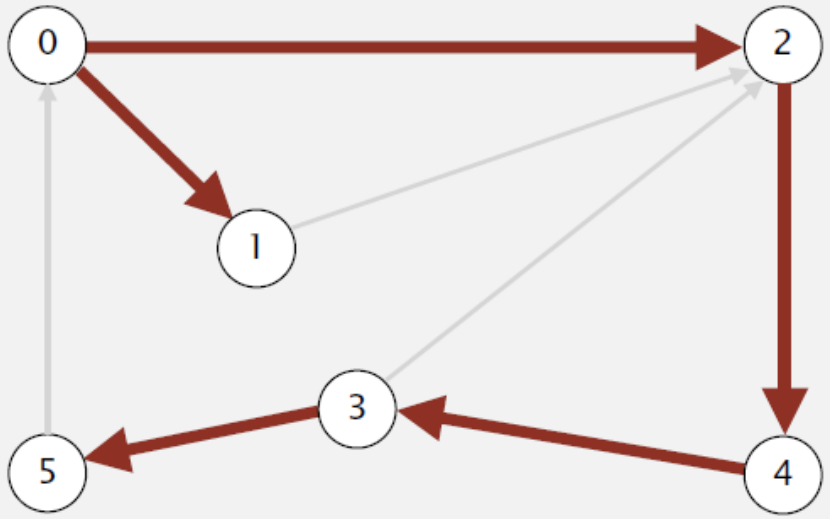
E → 8

5 0
2 4
3 2
1 2
0 1
4 3
3 5
0 2

Directed breadth-first search demo

Repeat until queue is empty:

- Remove vertex v from queue.
- Add to queue all unmarked vertices pointing from v and mark them.



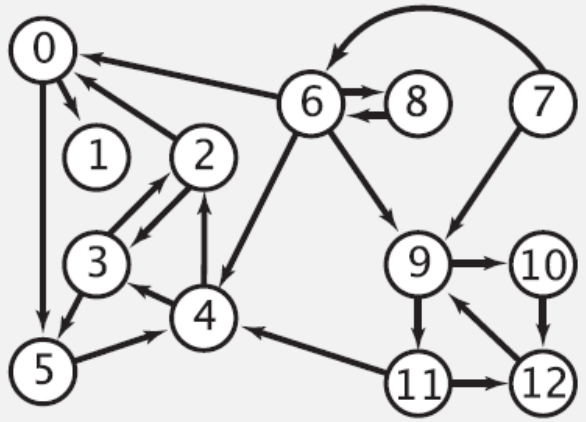
v	edgeTo[]	distTo[]
0	–	0
1	0	1
2	0	1
3	4	3
4	2	2
5	3	4

Multiple-source shortest paths

Multiple-source shortest paths. Given a digraph and a set of source vertices, find shortest path from any vertex in the set to each other vertex.

Ex. $S = \{ 1, 7, 10 \}$.

- Shortest path to 4 is 7→6→4.
- Shortest path to 5 is 7→6→0→5.
- Shortest path to 12 is 10→12.
- ...



Q. How to implement multi-source shortest paths algorithm?

A. Use BFS, but initialize by enqueuing all source vertices.

Applications

- AI – search, constraint programming, NLP ….
- Topological sort
- Directed cycle detection
- Strongly-connected components

Topological sort

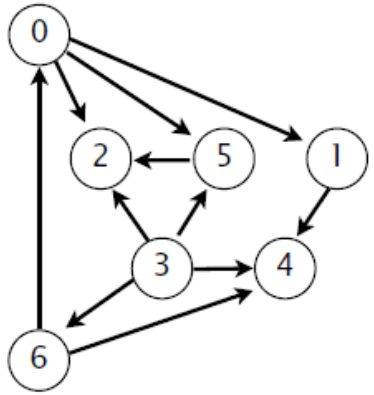
Precedence scheduling

Goal. Given a set of tasks to be completed with precedence constraints, in which order should we schedule the tasks?

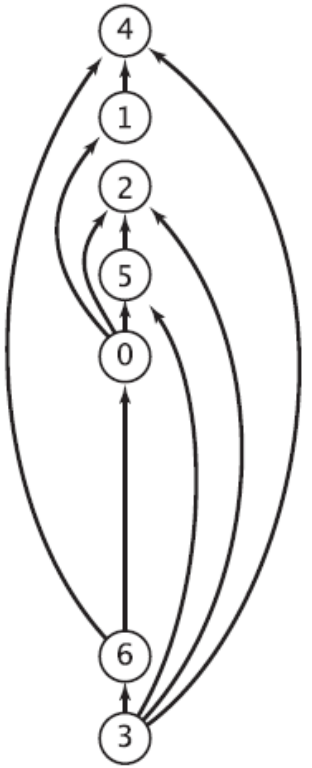
Digraph model. vertex = task; edge = precedence constraint.

0. Algorithms
1. Complexity Theory
2. Artificial Intelligence
3. Intro to CS
4. Cryptography
5. Scientific Computing
6. Advanced Programming

tasks



precedence constraint graph



feasible schedule

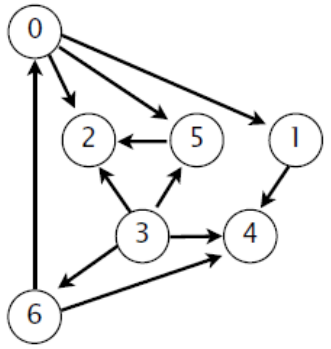
Topological sort

DAG. Directed acyclic graph.

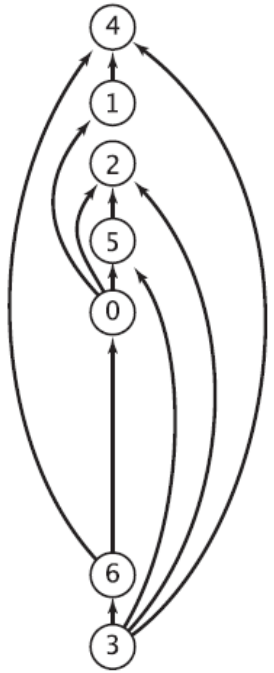
Topological sort. Redraw DAG so all edges point upwards.

0→5	0→2
0→1	3→6
3→5	3→4
5→2	6→4
6→0	3→2
1→4	

directed edges



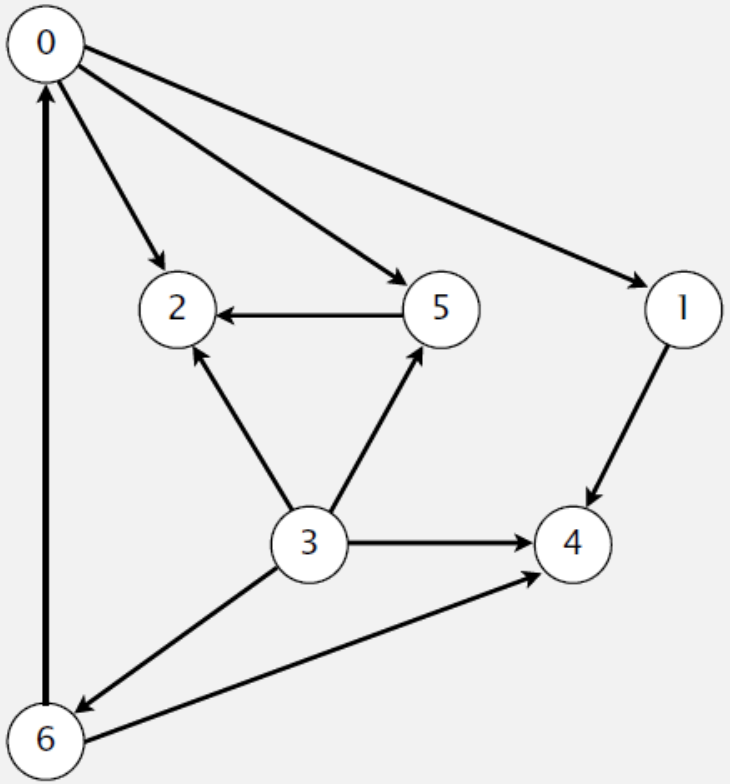
DAG



topological order

Solution. DFS. What else?

- Run depth-first search.
- Return vertices in reverse postorder.



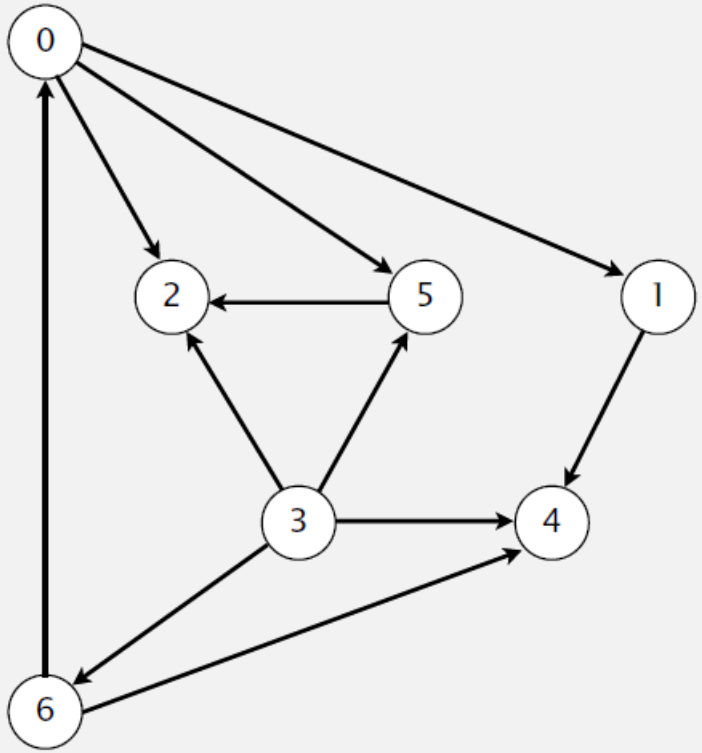
a directed acyclic graph

tinyDAG7.txt

```
7
11
 0  5
 0  2
 0  1
 3  6
 3  5
 3  4
 5  2
 6  4
 6  0
 3  2
```

Topological sort demo

- Run depth-first search.
- Return vertices in reverse postorder.



postorder

4 1 2 5 0 6 3

topological order

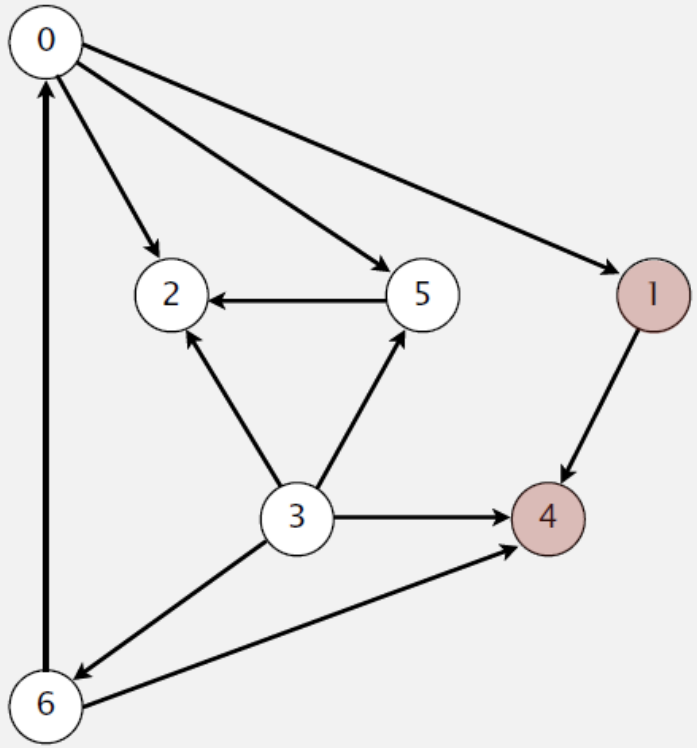
3 6 0 5 2 1 4

done

Topological sort in a DAG: intuition

Why does topological sort algorithm work?

- First vertex in postorder has outdegree 0.
- Second-to-last vertex in postorder can only point to last vertex.
- ...



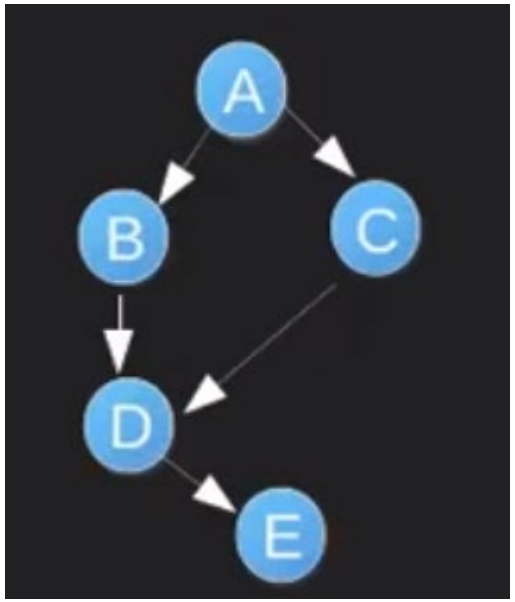
postorder

4 1 2 5 0 6 3

topological order

3 6 0 5 2 1 4

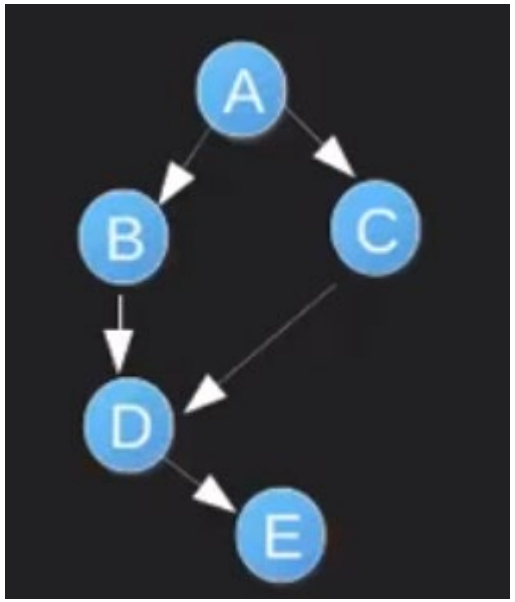
Topological sort



Topological sort

- Not unique ordering
- A B C D E
- A C B D E

- Complexity
  - DFS with an extra stack
  - Same as DFS which is O(V+E)



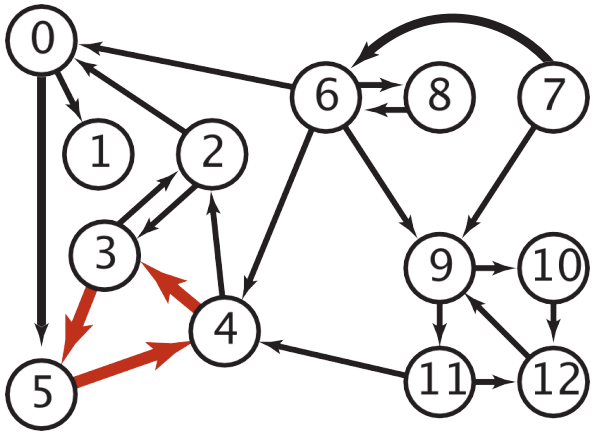
Directed Cycle Detection

Directed cycle detection

Proposition. A digraph has a topological order iff no directed cycle.

Pf.

- If directed cycle, topological order impossible.
- If no directed cycle, DFS-based algorithm finds a topological order.



a digraph with a directed cycle

Goal. Given a digraph, find a directed cycle.

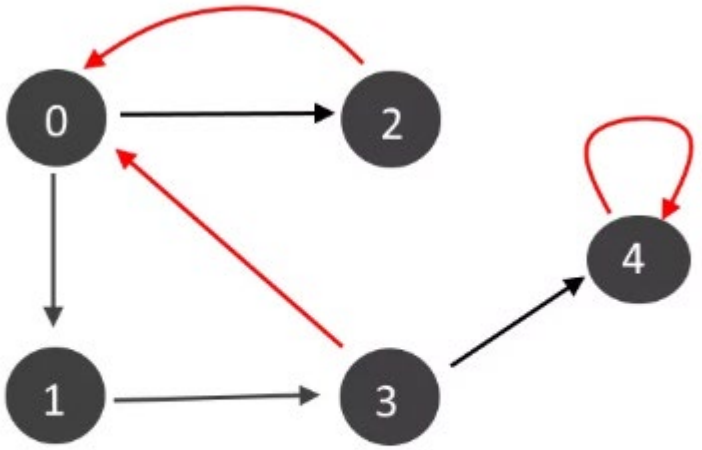
Directed cycle detection

Graph contains cycle if there are any back edges.

1.Edge from a vertex to itself. Self loop.
2.Edge from any descendent back to vertex.

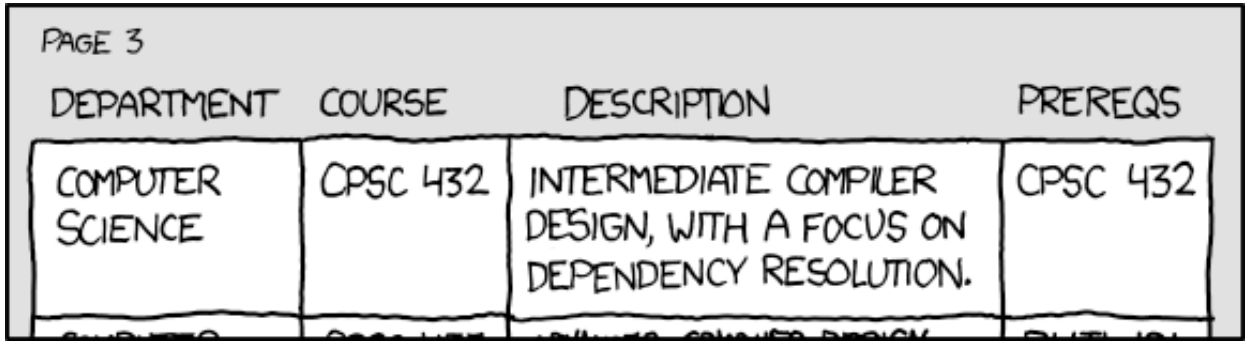
- Do the **DFS** from each vertex

- For DFS from each vertex, keep track of visiting vertices in a recursion stack (array).
- If you encounter a vertex which already present in recursion stack then we have found a cycle.
- Use visited[] for DFS to keep track of already visited vertices.



Directed cycle detection application: precedence scheduling

Scheduling. Given a set of tasks to be completed with precedence constraints, in what order should we schedule the tasks?



http://xkcd.com/754

Remark. A directed cycle implies scheduling problem is infeasible.

Directed cycle detection application: cyclic inheritance

The Java compiler does cycle detection.

```
public class A extends B
{
   ...
}
```

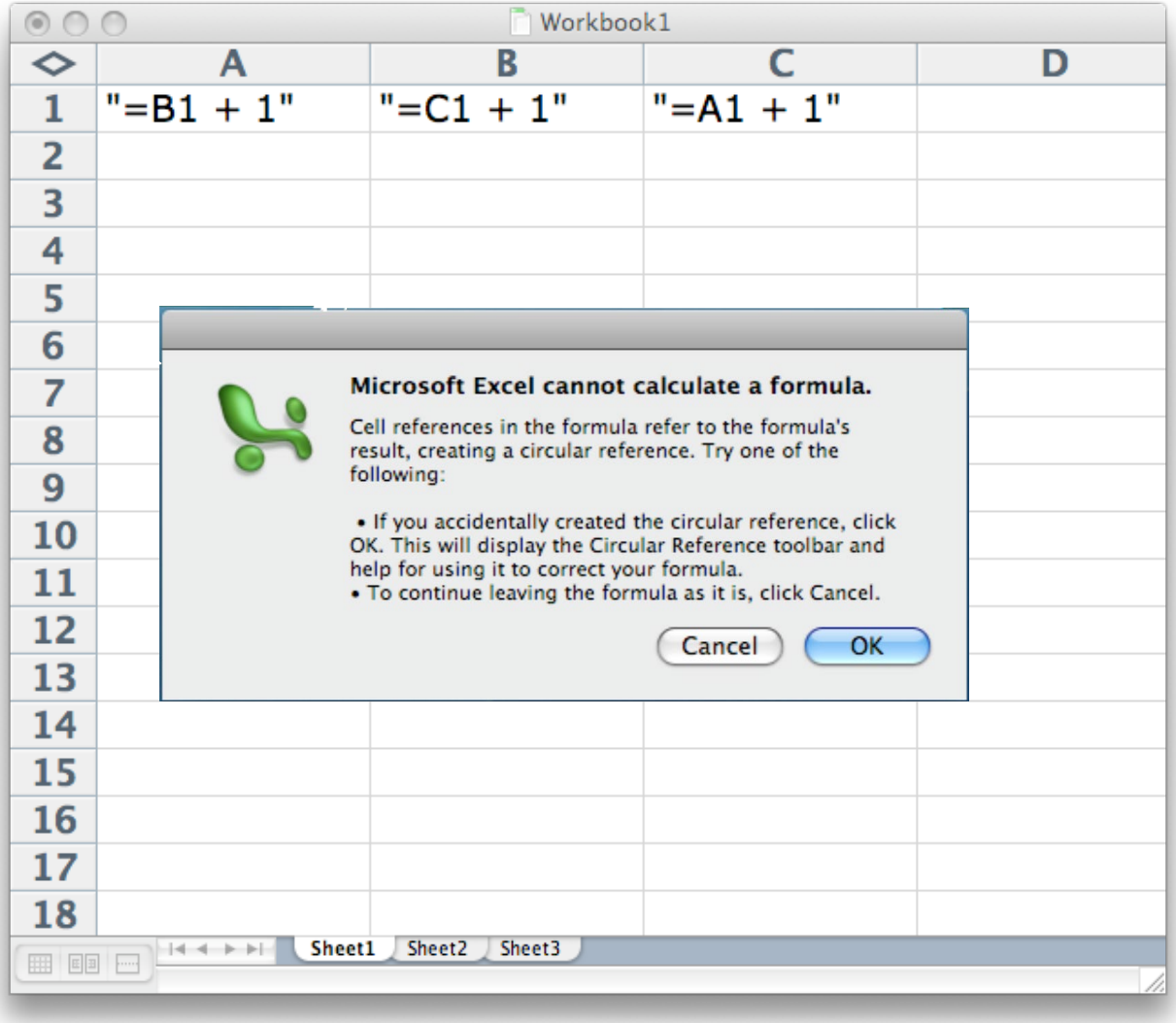
```
public class B extends C
{
   ...
}
```

```
public class C extends A
{
   ...
}
```

```
% javac A.java
A.java:1: cyclic inheritance
involving A
public class A extends B { }
       ^
1 error
```

Directed cycle detection application: spreadsheet recalculation

Microsoft Excel does cycle detection (and has a circular reference toolbar!)



Depth-first search orders

Observation. DFS visits each vertex exactly once. The order in which it does so can be important.

Orderings.

- Preorder: order in which `dfs()` is called.
- Postorder: order in which `dfs()` returns.
- Reverse postorder: reverse order in which `dfs()` returns.

```
private void dfs(Graph G, int v)
{
   marked[v] = true;
   preorder.enqueue(v);
   for (int w : G.adj(v))
      if (!marked[w]) dfs(G, w);
   postorder.enqueue(v);
   reversePostorder.push(v);
}
```

Topological sort exercise

- Show the nodes in the graph in topological order
- Keep track of the stack of nodes as they are added and removed
- Is the ordering unique? If not, show another valid topological ordering