Input image



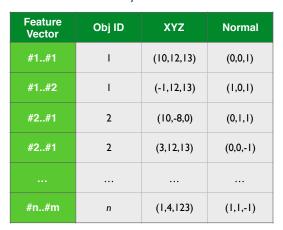
Feature matching

Specialized for PnP



Detected features

Feature DB with object ID and annotations



Pose estimation Solve PnP





Estimated pose for each object