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## Linear Programming (poggers)

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Very shortly put, it is simply optimizing a linear function w.r.t. linear constraints.

The matrix form of a maximization problem would be:

$$\text{Maximize } c^T x \quad (1)$$

$$\text{Subject to } Ax \leq b \quad (2)$$

Or, they could be split into many constraints instead, with both  $\leq$ ,  $\geq$ , and  $=$  between them.

The decision variables are  $x$ . An assignment to them is a solution. A solution satisfying the constraints is feasible. A feasible solution that actually minimizes/maximizes is optimal (sometimes denoted by an asterisk, i.e.  $P^*$ ).

The set of feasible solutions, called  $F$ , is a convex polyhedron. That means it has  $n$  sides and has no two points such that a line may be drawn between them that crosses outside of the polyhedron. Usually, you need to traverse to a corner of the polyhedron to attain an optimal solution.

Two stinky cases: unbounded solutions, where an arbitrarily good solution may be found, and infeasible LP's, where the set of feasible solutions is empty.

I know what you're thinking at this point: "That's really cool, Jonathan, but what is the standard form of a linear program?" Well, here it is!

$$\text{Maximize } c_1x_1 + c_2x_2 + \dots + c_nx_n \quad (3)$$

$$\text{Subject to} \quad (4)$$

$$a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n \leq b_1 \quad (5)$$

$$a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n \leq b_2 \quad (6)$$

$$\dots \quad (7)$$

$$a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n \leq b_m \quad (8)$$

Hello.