## EVALUATION ONLINE LEARNING LINKS WITH OPTIMIZATION AND GAMES

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## VARIANTS OF ADAGRAD-NORM AND APPLICATION TO GAMES

Let  $d\geqslant 1$ ,  $\mathscr{X}\subset\mathbb{R}^d$  a nonempty closed convex set,  $\gamma$ ,  $\eta$ , L>0,  $x_1\in\mathscr{X}$ , and  $(u_t)_{t\geqslant 1}$  a sequence in  $\mathbb{R}^d$ . We consider

• AdaGrad-Norm, defined as

$$x_{t+1} = \Pi_{\mathscr{X}}\left(x_t + rac{\gamma}{\sqrt{\sum_{s=1}^t \left\|u_s
ight\|_2^2}}u_t
ight), \quad t\geqslant 1,$$

with convention 0/0 = 0;

• AdaGrad-DA-Norm, defined as

$$x_{t+1}^{(\mathrm{DA})} = \Pi_{\mathcal{X}}\left(\frac{\eta}{\sqrt{L^2 + \sum_{s=1}^{t} \left\|u_s\right\|_2^2}} \sum_{s=1}^{t} u_t\right), \quad t \geqslant 1;$$

• AdaGrad-Hybrid-Norm, defined as

$$x_{t+1}^{( ext{hyb})} = \Pi_{\mathscr{X}}\left(\eta_{t+1}\left(rac{x_t^{( ext{hyb})}}{\eta_t} + u_t
ight)
ight), \quad t\geqslant 1,$$

where 
$$\eta_t = \eta / \sqrt{L^2 + \sum_{s=1}^{t-1} \|u_s\|_2^2}$$
.

1) Assume that for all  $t \ge 1$ ,  $\|u_t\|_2 \le L$ . For  $T \ge 1$  and  $x \in \mathcal{X}$ , establish an upper bound on the regret

$$\sum_{t=1}^{T} \left\langle u_t, x - x_t^{(\mathrm{DA})} \right\rangle \qquad \left( \mathrm{resp.} \quad \sum_{t=1}^{T} \left\langle u_t, x - x_t^{(\mathrm{hyb})} \right\rangle \right).$$

*Hint.* — For  $t \ge 1$ , consider mirror map

$$H_t(x) = rac{\sqrt{L^2 + \sum_{s=1}^{t-1} \|u_s\|_2^2}}{2\eta} \|x\|_2^2, \quad x \in \mathbb{R}^d,$$

and associated regularizer  $h_t = H_t + I_{\mathcal{X}}$ .

- 2) Let  $m, n \ge 1$  be integers, and  $A \in \mathbb{R}^{m \times n}$ . Apply each of the above algorithms for solving the two-player zero-sum game associated with A and derive corresponding guarantees.
- 3) Perform numerical experiments in the context of solving two-player zerosum games and compare the performance of the three above algorithms with RM, RM+, the exponential weights algorithm, as well as *optimistic* counterparts of all previous algorithms. Use the following function to compute the Euclidean projection onto the simplex.

```
def projection_simplex(y):
    n_features = y.shape[0]
    z = np.sort(y)[::-1]
    cssv = np.cumsum(z) - 1
    ind = np.arange(n_features) + 1
    cond = z - cssv / ind > 0
    rho = ind[cond][-1]
    theta = cssv[cond][-1] / float(rho)
    w = np.maximum(y - theta, 0)
    return w
```

4) Bonus. — Also study the diagonal variants of each above algorithm and include them in the numerical experiments.

5) Bonus. — Also perform numerical experiments for extensive-form games using the counterfactual regret minimization approach.

