EVALUATION ONLINE LEARNING LINKS WITH OPTIMIZATION AND GAMES

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APPROACHABILITY-BASED OPTIMIZATION

We first reduce online linear optimization on a convex compact set to an approachability problem and consider Blackwell and greedy Blackwell algorithms in this context. Those algorithms are then converted into optimization algorithms.

Let $\mathcal{A} \subset \mathbb{R}^d$ be a nonempty convex compact set. We consider online linear optimization on \mathcal{A} : for sequences $(a_t)_{t\geqslant 0}$ and $(u_t)_{t\geqslant 0}$ in \mathcal{A} and \mathbb{R}^d respectively, the quantity of interest is the following regret:

$$\max_{a \in \mathcal{A}} \sum_{t=0}^{T} \langle u_t, a - a_t \rangle, \quad T \geqslant 0.$$
 (1)

Consider the auxiliary approachability problem where \mathcal{A} and $\mathcal{B}=\mathbb{R}^d$ are the actions sets, and where outcome function $g:\mathcal{A}\times\mathcal{B}\to\mathbb{R}^{d+1}$ is defined as

$$g(a, u) = (u, \langle u, x \rangle), \quad a \in \mathcal{A}, u \in \mathbb{R}^d.$$

Consider $\mathscr{X}_0 = \mathscr{A} \times \{-1\}$ and $\mathscr{C} = \mathscr{X}_0^{\circ}$.

1) Prove that $\mathscr C$ satisfies Blackwell's condition and give an associated oracle.

- 2) Relate the regret (1) with the above approachability problem.
- 3) In the approachability problem, consider Blackwell and greedy Blackwell algorithms and write corresponding guarantees. Deduce guarantees on the regret (1).
- 4) Convert the regret minimization algorithms thus obtained into constrained convex optimization algorithms on A and derive guarantees.
- 5) Conduct numerical experiments and compare the above algorithms to classical algorithms. A possible setting is e.g. an SVM constrained on a closed Euclidean ball on a small (but not tiny) dataset—this is only a suggestion. Ideally, consider two or three different settings.
- 6) Bonus. Also apply to stochastic optimization.

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