## EVALUATION ONLINE LEARNING LINKS WITH OPTIMIZATION AND GAMES

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## ONLINE NEWTON STEP

Let  $d \ge 1$  and  $\mathscr{X} \subset \mathbb{R}^d$  a nonempty closed convex set. We consider an online convex optimization problem where the loss functions admit quadratic lower bounds as follows. At step  $t \ge 0$ ,

- the Decision Maker chooses  $x_t \in \mathcal{X}$
- Nature chooses a loss function  $\ell_t$  such that there exists  $g_t \in \partial \ell_t(x_t)$  and  $M_t$  a positive semi-definite matrix of size  $d \times d$  such that:

$$\forall x \in \mathcal{X}, \quad \ell_t(x) - \ell_t(x_t) \geqslant \langle g_t, x - x_t \rangle + \frac{1}{2} \langle x - x_t, M_t(x - x_t) \rangle.$$

 $\ell_t$ ,  $g_t$  and  $M_t$  are revealed.

Let 
$$\lambda > 0$$
. For all  $t \geqslant 0$ , denote  $A_t = \frac{1}{2} \left( \lambda I + \sum_{s=0}^{t-1} M_s \right)$ .

1) For each of the three iterations defined below, establish an upper bound on the regret

$$\sum_{t=0}^{\mathrm{T}} \left( \ell_t(x_t) - \ell_t(x) \right), \quad x \in \mathcal{X}, \; \mathrm{T} \geqslant 0.$$

Hint. — Use the lemma from the course involved in the analysis of the Vovk–Azoury–Warmuth algorithm.

(i) Let  $x_0 \in \mathcal{X}$  and

$$x_{t+1} = \mathop{\arg\min}_{\mathbf{x} \in \mathcal{K}} \left\| (x_t - \mathbf{A}_t^{-1} \mathbf{g}_t) - \mathbf{x} \right\|_{\mathbf{A}_t}, \quad t \geqslant 0.$$

(ii) Let  $x_0 \in \mathcal{X}$  and

$$x_{t+1} = \operatorname*{arg\,min}_{x \in \mathcal{X}} \left\{ \langle -\mathbf{A}_t x_t + g_t, x \rangle - \frac{1}{2} x^\top \mathbf{A}_{t+1} x \right\}, \quad t \geqslant 0.$$

(iii) Let  $y_0 \in \mathbb{R}^d$  and

$$x_{t} = \operatorname*{arg\,min}_{x \in \mathscr{X}} \left\{ \left\langle -y_{0} + \sum_{s=0}^{t-1} g_{s}, x \right\rangle + \frac{1}{2} \left\langle x, A_{t} x \right\rangle \right\}, \quad t \geqslant 0.$$

2) Bonus. — Derive the corresponding regret bounds in the special case of online portfolio optimization where  $\mathscr{X}=\Delta_d$  and where the loss functions are of the form  $\ell_t(x)=-\log \langle r_t, x \rangle$  for some  $r_t \in (\mathbb{R}_+^*)^d$ .

