## Homework 2: ECON512

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1.

The demands are determined by

$$D_A = D_B = \frac{\exp(1)}{1 + 2\exp(1)}$$

Matlab yields the following results:

D\_A D\_B 0.42232 0.42232

2.

I start off with the initial guess  $p^0 = (1,1)'$ . The criterion was 10e-08. With Broydens method, Matlab yields the following results:

```
iter 1: p(1) = 1.000000, p(2) = 1.000000, norm(f(x)) = 0.59724897
iter 2: p(1) = 0.577681, p(2) = 0.577681, norm(f(x)) = 0.96177748
iter 3: p(1) = 1.691933, p(2) = 1.691933, norm(f(x)) = 0.10363413
iter 4: p(1) = 1.583549, p(2) = 1.583549, norm(f(x)) = 0.01684145
iter 5: p(1) = 1.598700, p(2) = 1.598700, norm(f(x)) = 0.00026551
iter 6: p(1) = 1.598942, p(2) = 1.598942, norm(f(x)) = 0.000000069
iter 7: p(1) = 1.598942, p(2) = 1.598942, norm(f(x)) = 0.000000000
Equilibrium Prices
p_A p_B
1.5989 1.5989
```

0.0062844

Computation Time

3.

When I conduct Gauss-Seidel method to solve the problem, I start with two initial guesses  $p^0 = (2,2)'$  and  $p^{-1} = (0,0)'$ . The criterion was 10e-08. With this method, Matlab yields the following results:

```
iter 1: p(1) = 1.461030, p(2) = 1.567682, norm(f(x)) = 0.12757573
iter 2: p(1) = 1.591911, p(2) = 1.597363, norm(f(x)) = 0.00666873
iter 3: p(1) = 1.598588, p(2) = 1.598862, norm(f(x)) = 0.00033634
```

It took a longer time to solve the problem than the Broyden's method. The underlying logic of this solver comes from the rationalizability in game theory while Broyden's method solves for a price vector in line with the logic of Nash-equilibrium. As it is easier to solve for equilibrium with Nash equilibrium than with rationalizability, it is not that surprising that Broyden's method is faster than this method.

4.

I also start with p = (1,1)'. Under the parametrization v = (2,2)', the proposed updating rule successfully found the root and it was the fastest one among three methods. Matlab yields the following results:

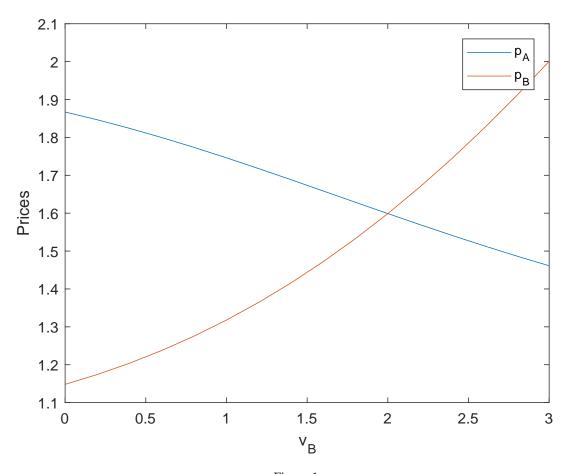
```
iter 1: p(1) = 1.000000, p(2) = 1.000000, norm(f(x)) = 1.03387296
iter 2: p(1) = 1.731059, p(2) = 1.731059, norm(f(x)) = 0.23225003
iter 3: p(1) = 1.566833, p(2) = 1.566833, norm(f(x)) = 0.05628097
iter 4: p(1) = 1.606630, p(2) = 1.606630, norm(f(x)) = 0.01348578
iter 5: p(1) = 1.597094, p(2) = 1.597094, norm(f(x)) = 0.00324129
iter 6: p(1) = 1.599386, p(2) = 1.599386, norm(f(x)) = 0.00077848
iter 7: p(1) = 1.598835, p(2) = 1.598835, norm(f(x)) = 0.00018701
iter 8: p(1) = 1.598967, p(2) = 1.598967, norm(f(x)) = 0.00004492
iter 9: p(1) = 1.598936, p(2) = 1.598936, norm(f(x)) = 0.00001079
iter 10: p(1) = 1.598943, p(2) = 1.598943, norm(f(x)) = 0.00000259
iter 11: p(1) = 1.598942, p(2) = 1.598942, norm(f(x)) = 0.00000062
iter 12: p(1) = 1.598942, p(2) = 1.598942, norm(f(x)) = 0.00000015
iter 13: p(1) = 1.598942, p(2) = 1.598942, norm(f(x)) = 0.00000004
Equilibrium Prices
p_A
            p_B
1.5989
            1.5989
Computation Time
0.005888
```

However, the method is highly sensitive to parametrization. For instance, under v = (2,3)', the method fails to find the fixed point (Even start with p = (1,2)' which is close to the solution).

```
iter 995: p(1) = 1.023864, p(2) = 7.133538, norm(f(x)) = 6.65331409
iter 996: p(1) = 3.612315, p(2) = 1.004386, norm(f(x)) = 6.65331409
iter 997: p(1) = 1.023864, p(2) = 7.133538, norm(f(x)) = 6.65331409
iter 998: p(1) = 3.612315, p(2) = 1.004386, norm(f(x)) = 6.65331409
```

```
iter 999: p(1) = 1.023864, p(2) = 7.133538, norm(f(x)) = 6.65331409 iter 1000: p(1) = 3.612315, p(2) = 1.004386, norm(f(x)) = 6.65331409 Equilibrium Prices p_A p_B 1.0239 7.1335 Computation Time 0.067707
```

## 5. The generated figures are as follow.



```
% Homework #2 ECON 512
                                                  %
% Written by Joonkyo (Jay) Hong, 20 Sept 2018
                                                   %
clear;
%% Question 1
v=[2;2];
p=[1;1];
demand = \exp(v-p)./(1+\sup(\exp(v-p)));
disp('D_A
               D_B')
disp(num2str(demand'));
disp("Question 1 is done. Press any key to continue");
pause
%% Question 2
f = O(p) bertrand(p,v); %make function handle whose argument is a price vector
                     %Bertrand is an outside function that characterize
                     %equilibrium conditions
% START BROYDEN METHODS
maxiter = 100;
tol = 10e-8;
% initial guess
p = [1;1];
init_f = f(p);
invJ = eye(length(p));
tic
for i=1:maxiter
     fnorm = norm(init_f);
     fprintf('iter %d: p(1) = %f, p(2) = %f, norm(f(x)) = %.8f\n', i, p(1), p(2), fnorm);
     if fnorm < tol
        break;
     end
     d = - (invJ*init_f);
```

```
p = p + d;
      new_f = f(p);
      u = invJ*(new_f - init_f);
      invJ = invJ + ((d - u) * (d'*invJ))/(d'*u);
      init_f = new_f;
 end
t=toc;
disp("Equilibrium Prices")
disp('p_A
                  p_B')
disp(num2str(p'));
disp("Computation Time")
disp(num2str(t));
disp("Question 2 is done. Press any key to continue");
pause
%% Question 3
pa = 1; pb=1;
f = O(p) bertrand(p,v); % Again, make function handle
fval = f([pa;pb]);
pa_old = 0;
pb_old = 0;
bigloop_iter = 1000;
tic
for i=1:bigloop_iter % Big loop
    if norm(fval) < 10e-8
        break
    end
% Sub loop for good A
\% In order to perform secent method, fix two initial conditions
      fa = @(pa) bertrand1(pa,pb,v);  % FOC only for good A
      faold = fa(pa_old);
      maxiter = 100;
      tol = 10e-8;
```

```
for j=1:maxiter
          faval = fa(pa);
          if norm(faval) < tol</pre>
             break
          else
             pa_new = pa - ( (pa - pa_old)/(faval-faold) )*faval;
             pa_old = pa;
             pa = pa_new;
             faold = faval;
          end
      \quad \text{end} \quad
% Sub loop for good B
       fb = @(pb) bertrand2(pa,pb,v);
       fbold = fb(pb_old);
     for j=1:maxiter
          fbval = fb(pb);
         if norm(fbval) < tol</pre>
            break
         else
             pb_new = pb - ( (pb - pb_old)/(fbval-fbold) )*fbval;
            pb_old = pb;
            pb = pb_new;
            fbold = fbval;
         end
     end
     fval=f([pa;pb]);
                           % Updating fval for the next loop
     fprintf('iter %d: p(1) = %f, p(2) = %f, norm(f(x)) = %.8f\n',i, pa, pb, norm(fval));
end
t=toc;
disp("Equilibrium Prices")
disp('p_A
                   p_B')
disp(num2str([pa pb]));
disp("Computation Time")
disp(num2str(t));
disp("Question 3 is done. Press any key to continue");
pause
%% Question 4
```

```
% Updating Rule
g = O(p) 1./(1 - exp(v-p)./(1+sum(exp(v-p))));
p = [1;1];
maxit = 1000;
tic
for i=1:maxit
     nextp = g(p);
     diff = norm(nextp-p);
     fprintf('iter \%d: p(1) = \%f, p(2) = \%f, norm(f(x)) = \%.8f\n',i, p(1), p(2), diff);
      if diff < 10e-8
          break;
      end
      p = nextp;
 end
t=toc;
% What if v2=3?
v = [2;3];
g = @(p) 1./(1 - exp(v-p)./(1+sum(exp(v-p))));
p2 = [1;2];
maxit = 1000;
tic
for i=1:maxit
     nextp2 = g(p2);
     diff = norm(nextp2-p2);
     fprintf('iter %d: p(1) = %f, p(2) = %f, norm(f(x)) = %.8f\n',i, p2(1), p2(2), diff);
      if diff < 10e-8
          break;
      end
      p2 = nextp2;
end
t2=toc;
disp("CASE 1: v1=v2=2")
```

```
disp("Equilibrium Prices")
disp('p_A
                   p_B')
disp(num2str(p'));
disp("Computation Time")
disp(num2str(t));
disp("Question 4 is done. Press any key to continue");
disp(" ")
disp("CASE 2: v1=2, v2=3")
disp("Equilibrium Prices")
                   p_B')
disp('p_A
disp(num2str(p2'));
disp("Computation Time")
disp(num2str(t2));
disp("Question 4 is done. Press any key to continue");
pause
%% Question 5
vb_vec = 0:0.2:3;
                                           % vector of values
p_eqmvec = zeros(length(vb_vec),2);
                                           \% vector that will contain the equilibrium prices
                                           % Initial guess of solution
p = [1;1];
for iter=1:length(vb_vec)
    vb = vb_vec(iter);
    v = [2; vb];
    f = @(p) bertrand(p,v);
          \mbox{\ensuremath{\mbox{\%}}} Perform Broyden Method to solve the equilibrium
          init_f = f(p);
          invJ = eye(length(p));
          maxiter = 1000;
          tol = 10e-8;
             for i=1:maxiter
                  fnorm = norm(init_f);
                  if fnorm < tol
                      break;
```

```
end
                 d = - (invJ*init_f);
                p = p + d;
                new_f = f(p);
                u = invJ*(new_f - init_f);
                invJ = invJ + ( (d - u) * (d'*invJ) )/ (d'*u);
                 init_f = new_f;
             end
       p_eqmvec(iter,:) = p';
end
figure(1)
plot(vb_vec,p_eqmvec);
xlabel('v_{B}');
ylabel('Prices');
legend('p_{A}', 'p_{B}');
disp("Question 5 is done. See the figure that poped up");
```