Chapter 14. Dynamic Programming

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Assignment

- ► Read §14.2
- ► Problems
 - ► §14.2 1, 3

Chapter 14: Dynamic Programming

- Chapter 14.1: Rod Cutting
- Chapter 14.2: Matrix-Chain Multiplication
- Chapter 14.3: Elements of Dynamic Programming
- Chapter 14.4: Longest Common Subsequence
- ► Chapter 14.5: Optimal Binary Search Trees

What is the Problem?

- ▶ Given a chain of matrices $A_1, A_2, ..., A_n$
- ▶ Goal: Compute the product $A_1A_2...A_n$
- Matrix multiplication is associative, so we can parenthesize it in many ways
- But: Different parenthesizations lead to different computational costs!

Why Does Parenthesization Matter?

- Consider three matrices:
 - $A_1:10\times 100$
 - ► $A_2:100\times 5$
 - $A_3:5\times 50$
- ► Two ways to compute:
 - 1. $((A_1A_2)A_3)$: $10 \cdot 100 \cdot 5 + 10 \cdot 5 \cdot 50 = 7500$
 - 2. $(A_1(A_2A_3))$: $100 \cdot 5 \cdot 50 + 10 \cdot 100 \cdot 50 = 75000$
- ► 10× more efficient!

How Do We Measure Cost?

- **Scalar multiplication:** one operation of the form $a_{ik} \cdot b_{kj}$
- ▶ Standard algorithm for multiplying $p \times q$ by $q \times r$:

$$\mathsf{Cost} = p \cdot q \cdot r$$

 Total cost of parenthesization is the sum of scalar multiplications

What is the Input?

▶ Input is a sequence of dimensions:

$$\langle p_0, p_1, p_2, \ldots, p_n \rangle$$

- ► Matrix A_i has dimensions $p_{i-1} \times p_i$
- ▶ We do **not** multiply matrices we only choose the best parenthesization

Why Use Dynamic Programming?

- Many overlapping subproblems: e.g., A_2A_3 appears in many splits
- Brute-force: exponential number of parenthesizations
- Dynamic Programming:
 - ▶ Use a table to store best cost for each subchain
 - Solve smaller subproblems first
 - Build up to the full problem

What Are We Counting?

- ▶ Given: a sequence of n matrices A_1, A_2, \ldots, A_n
- ► Goal: Count the number of ways to fully parenthesize $A_1A_2...A_n$
- Matrix multiplication is associative → multiple valid parenthesizations
- ▶ But the number of possibilities grows rapidly as *n* increases

Examples of Parenthesization Counts

- ightharpoonup n=1: just one matrix ightarrow 1 way
- ▶ n = 2: $(A_1A_2) \to 1$ way
- n = 3:
 - $((A_1A_2)A_3)$
 - $ightharpoonup (A_1(A_2A_3))$
- ▶ n = 4: 5 ways
- ▶ n = 5: 14 ways

Number of ways increases super-exponentially!

Recursive Formula

$$P(n) = \begin{cases} 1 & \text{if } n = 1\\ \sum_{k=1}^{n-1} P(k) \cdot P(n-k) & \text{if } n \ge 2 \end{cases}$$

- For each split point k, split into:
 - Left subchain: $A_1 \dots A_k$
 - Right subchain: $A_{k+1} \dots A_n$
- Multiply number of ways to parenthesize left and right
- Asymptotically:

$$P(n) = \Omega(2^n)$$

Why Not Brute Force?

- For n = 10: Over 1000 ways to try
- For n = 20: Over a million
- Each possibility requires:
 - Evaluating subchains
 - Tracking multiplication costs
- Exhaustive search is impractical

We need a smarter way \rightarrow Dynamic Programming!

Dynamic Programming Strategy

Four Steps for DP:

- 1. Characterize the structure of an optimal solution
- 2. Recursively define the value of an optimal solution
- 3. Compute the value of an optimal solution (bottom-up)
- 4. Construct the optimal solution from saved data

Step 1: Optimal Substructure

- ▶ To compute $A_iA_{i+1}...A_j$, we must split at some $k \in [i, j-1]$
- ► That is:

$$A_i \ldots A_j = (A_i \ldots A_k) \cdot (A_{k+1} \ldots A_j)$$

So the total cost:

$$cost = left + right + merge$$

Merging cost:

$$p_{i-1} \cdot p_k \cdot p_j$$



Step 2: Recursive Definition

Define m[i][j]: minimum cost to multiply A_i, \dots, A_j

$$m[i][j] = \begin{cases} 0 & \text{if } i = j \\ \min_{i \le k < j} (m[i][k] + m[k+1][j] + p_{i-1} \cdot p_k \cdot p_j) & \text{if } i < j \end{cases}$$

- ▶ Try every split point $k \in [i, j-1]$
- ▶ Recursively compute cost of left and right chains
- ▶ Add cost to multiply the resulting two matrices

Example: Matrix Dimensions

$$p = [10, 100, 5, 50]$$

- $A_1: 10 \times 100$
- ► A₂: 100×5
- ► *A*₃: 5×50

Compare:

- $((A_1A_2)A_3): 10 \cdot 100 \cdot 5 + 10 \cdot 5 \cdot 50 = 7500$
- $(A_1(A_2A_3)): 100 \cdot 5 \cdot 50 + 10 \cdot 100 \cdot 50 = 75000$

$$\Rightarrow m[1][3] = 7500$$

Step 3: Computing the optimal costs

Why Not Recursion?

Recursive solution based on:

$$m[i][j] = \min_{i \le k < j} (m[i][k] + m[k+1][j] + p_{i-1} \cdot p_k \cdot p_j)$$

- ▶ Inefficient: overlaps subproblems → exponential time
- Solution: use bottom-up dynamic programming

The DP Tables

We define:

- ightharpoonup m[i][j]: minimum scalar multiplications for $A_i \dots A_j$
- \triangleright s[i][j]: index k where split yields minimal cost

Base Case:

m[i][i] = 0 (a single matrix requires no multiplications)

Bottom-Up DP: MATRIX-CHAIN-ORDER

- ▶ Loop over chain lengths l = 2 to n
- ▶ For each subchain $A_i ... A_i$ of length I:

$$j = i + l - 1$$

- ▶ Try all split points $k \in [i, j-1]$
- Update:

$$m[i][j] = \min_{i \le k < j} (m[i][k] + m[k+1][j] + p_{i-1} \cdot p_k \cdot p_j)$$

Order of Computation

- ► Fill table by increasing chain length /
- For chain length l = 2: fill m[i][i + 1]
- ► Then I = 3: fill m[i][i + 2], etc.
- ► Ensures all required subproblems m[i][k], m[k+1][j] are filled before use

Visualize diagonals of the DP table being filled from bottom to top

Bottom-Up DP Table

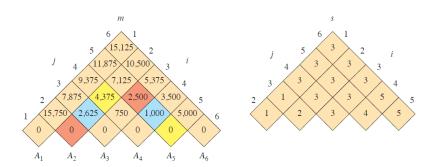


Figure 14.5 The m and s tables computed by MATRIX-CHAIN-ORDER for n=6 and the following matrix dimensions:

matrix	A_1	A_2	A_3	A_4	A_5	A_6
dimension	30×35	35 × 15	15 × 5	5×10	10 × 20	20 × 25

Example: Matrix Dimensions

$$p = [30, 35, 15, 5, 10, 20, 25]$$

- ► *A*₁: 30×35
- ► A₂: 35×15
- ► A_3 : 15×5
- ► *A*₄: 5×10
- ► A₅: 10×20
- ► A₆: 20×25

To compute m[2][5], try:

- k = 2: cost = $0 + 2500 + 35 \cdot 15 \cdot 20 = 13000$
- k = 3: cost = $2625 + 1000 + 35 \cdot 5 \cdot 20 = 7125$
- k = 4: cost = $4375 + 0 + 35 \cdot 10 \cdot 20 = 11375$

$$\Rightarrow m[2][5] = 7125, \quad s[2][5] = 3$$

Bottom-Up DP Algorithm

```
MATRIX-CHAIN-ORDER (p, n)
   let m[1:n, 1:n] and s[1:n-1, 2:n] be new tables
 2 for i = 1 to n
                                    // chain length 1
3 	 m[i,i] = 0
 4 for l=2 to n
                                    # l is the chain length
 5
       for i = 1 to n - l + 1 // chain begins at A_i
           i = i + l - 1
6
                          // chain ends at A_i
           m[i,j] = \infty
           for k = i to j - 1 // try A_{i:k}A_{k+1:j}
8
               q = m[i, k] + m[k + 1, j] + p_{i-1}p_kp_i
               if q < m[i, j]
10
                    m[i, j] = q // remember this cost
11
                   s[i, j] = k // remember this index
12
13
    return m and s
```

Step 4: Constructing an optimal solution

- ▶ DP table m[i][j]: min cost to compute $A_i ... A_j$
- ▶ Split table s[i][j]: best split point k for subchain $A_i ... A_j$
- But: we don't yet know the **full parenthesis structure**Goal: Print optimal parenthesization using s[i][j]

What Does s[i][j] Mean?

- ▶ $s[i][j] = k \Rightarrow$ optimal split is between A_k and A_{k+1}
- ► So:

$$A_i \ldots A_j = (A_i \ldots A_k) \cdot (A_{k+1} \ldots A_j)$$

- ▶ To fully parenthesize $A_i ... A_i$, we:
 - \triangleright Recursively parenthesize $A_i \dots A_k$
 - Recursively parenthesize $A_{k+1} \dots A_j$

Recursive Construction Algorithm

```
PRINT-OPTIMAL-PARENS (s, i, j)

1 if i == j

2 print "A"<sub>i</sub>

3 else print "("

4 PRINT-OPTIMAL-PARENS (s, i, s[i, j])

5 PRINT-OPTIMAL-PARENS (s, s[i, j] + 1, j)

6 print ")"
```

Example Output

Suppose the table gives:

- $s[1][6] = 3 \rightarrow \text{split as } (A_1 A_2 A_3)(A_4 A_5 A_6)$
- $ightharpoonup s[1][3]=1
 ightarrow ext{split} \ ext{as} \ A_1(A_2A_3)$
- ► $s[4][6] = 5 \rightarrow \text{split as } (A_4A_5)A_6$

Then:

Output:
$$((A_1(A_2A_3))((A_4A_5)A_6))$$

Summary of Step 4

- ► Table *s*[*i*][*j*] stores optimal split positions
- Recursively use s[i][j] to reconstruct full parenthesis structure
- ▶ Base case: when i = j, print "A_i"
- Final output is the full multiplication order with minimal cost

Complexity

► Time complexity:

$$O(n^3)$$
 (3 nested loops: I, i, k)

Space complexity:

$$O(n^2)$$
 (tables m and s)

Much more efficient than brute-force exponential time

Complexity of MATRIX-CHAIN-ORDER

Time Complexity:

```
▶ for 1 = 2 to n// chain length \rightarrow O(n)▶ for i = 1 to n - 1 + 1// start index \rightarrow O(n)▶ for k = i to j - 1// split points \rightarrow O(n)
```

$$\Rightarrow$$
 Total time: $O(n) \cdot O(n) \cdot O(n) = O(n^3)$

Space Complexity:

- ► Table m[i][j]: stores optimal costs for A_i...A_j
- ► Table s[i][j]: stores optimal split points

Each table is of size $\Rightarrow O(n^2)$ space



Question?