

# < Part 2 > 엔지니어링 리눅스

[ Ch 02. ] Jacobian Matrix  
& Backpropagation

[ CH 02. ] 06, 07, 08

Lecture.2

Basic Differentiation

YHJ

# CH02 - 06. Constant, Multiple and - Sum - Rules

## < Differentiation Rules >

• Constant Multiple Rule

$$\underline{\frac{d}{dx} [c \cdot f(x)] = c \cdot \frac{d}{dx} [f(x)]}$$

ex1)  $f(x) = 2x$      $g(x) = x, g'(x) = 1$

①  $f'(x) = 2 \cdot 1 \cdot \cancel{x^1} = 2$

②  $f'(x) = 2 \cdot g'(x) = 2$

ex2)  $f(x) = -3 \cdot e^x$      $g(x) = e^x, g'(x) = e^x$

$$f'(x) = -3 \cdot e^x$$

• Sum Rule

$$\underline{\frac{d}{dx} [f(x) + g(x)] = \frac{df}{dx} + \frac{dg}{dx}}$$

ex1)  $f(x) = 2x^2 - x + 1$

$$\rightarrow f'(x) = 4x - 1$$

ex2)  $f(x) = \sin(x) - \frac{1}{\sqrt{x}}$

$$= \sin(x) - x^{-\frac{1}{2}}$$

$$f'(x) = \cos x + \frac{1}{2} \cdot x^{-\frac{3}{2}}$$

$$= \cos x + \frac{1}{2\sqrt{x}x}$$

ex3)  $f(x) = \sinh(x)$

$$= \frac{e^x - e^{-x}}{2}$$

$$= \frac{1}{2}e^x - \frac{1}{2}e^{-x}$$

$$y = f(g(x))$$

$$y' = f'(g(x)) \cdot g'(x)$$

$$f'(x) = \frac{1}{2}e^x + \frac{1}{2}e^x$$

ex4)

$$f(x) = \cosh(x) = \frac{e^x + e^{-x}}{2}$$

$$f(x) = \frac{e^x - e^{-x}}{2}$$

$$\frac{d}{dx}$$

# CH02-07. LTI\_System\_and\_Differentiation

- Linearity of D(f).

$$\mathcal{L}\{ \alpha \cdot f(t) \} = \alpha \mathcal{L}\{ f(t) \} \rightarrow \text{Homogeneity}$$

$$\frac{d}{dx} [\alpha f(x)] = \alpha \cdot \frac{d}{dx} [f(x)]$$

= 위와 Homogeneity를 갖는다.

$$\mathcal{L}\{ f(t) + g(t) \} = \mathcal{L}\{ f(t) \} + \mathcal{L}\{ g(t) \} \rightarrow \text{Additivity}$$

$$\frac{d}{dx} [f(x) + g(x)] = \frac{d}{dx} [f(x)] + \frac{d}{dx} [g(x)]$$

= 위와 Additivity를 갖는다.

Additivity + Homogeneity  $\Rightarrow$  Linearity를 갖는다.

$$\mathcal{L}\{ \alpha \cdot f(t) + \beta \cdot g(t) \} = \alpha \mathcal{L}\{ f(t) \} + \beta \mathcal{L}\{ g(t) \}$$

$$\frac{d}{dx} [\alpha f(x) + \beta g(x)] = \alpha \cdot \frac{d}{dx} [f(x)] + \beta \cdot \frac{d}{dx} [g(x)]$$

= 위와 Linearity를 갖는다.

• Time-invariance of diff

$$\text{sys} \{ f(t) \} = f(t) \Rightarrow \text{sys} \{ f(t-\tau) \} = f(t-\tau)$$

$$\frac{d f(t)}{dt} = f'(t) \Rightarrow \frac{d f(t-\tau)}{dt} = f'(t-\tau)$$

• LTI (Linearity ~~prz~~ + Time-invariance ~~prz~~)  
systems and diff.

$$\frac{d}{dx} [\alpha \cdot f(t-\tau) + \beta \cdot g(t-\tau)] = \alpha \cdot f'(t-\tau) + \beta$$

: ~~prz~~ LTI ~~prz~~ ~~prz~~.

# CH02 - 08. Product- and Quotient-Rules

## • product Rule

$$\begin{aligned}\frac{d}{dx} [f(x) \cdot g(x)] &= \frac{d}{dx} [f(x)] \cdot g(x) + f(x) \cdot \frac{d}{dx} [g(x)] \\ &= f'(x)g(x) + f(x)g'(x)\end{aligned}$$

ex1)  $f(x) = x^3$

$$f'(x) = 3x^2$$

$$f(x) = x \cdot x^2 = x^2 \cdot x = 1 \cdot x^3$$

ex2)  $f(x) = e^x \cdot \ln x$

$$\begin{aligned}f'(x) &= e^x \cdot \ln x + e^x \cdot \frac{1}{x} \\ &= e^x \left[ \ln x + \frac{1}{x} \right]\end{aligned}$$

## • Quotient Rule

$$\frac{d}{dx} \left[ \frac{f(x)}{g(x)} \right] = \frac{\frac{d}{dx} [f(x)] \cdot g(x) - f(x) \cdot \frac{d}{dx} [g(x)]}{(g(x))^2}$$

ex)  $f(x) = \tanh(x) = \frac{\sinh(x)}{\cosh(x)}$  \*  $\frac{d}{dx} [\sinh(x)] = \cosh(x)$   
 $\frac{d}{dx} [\cosh(x)] = \sinh(x)$

$$\begin{aligned}f'(x) &= \frac{\cosh^2(x) - \sinh^2(x)}{\cosh^2(x)} = 1 - \frac{\sinh(x)}{\cosh(x)} \\ &= 1 - (\tanh(x))^2 = (1 + \tanh(x))(1 - \tanh(x))\end{aligned}$$