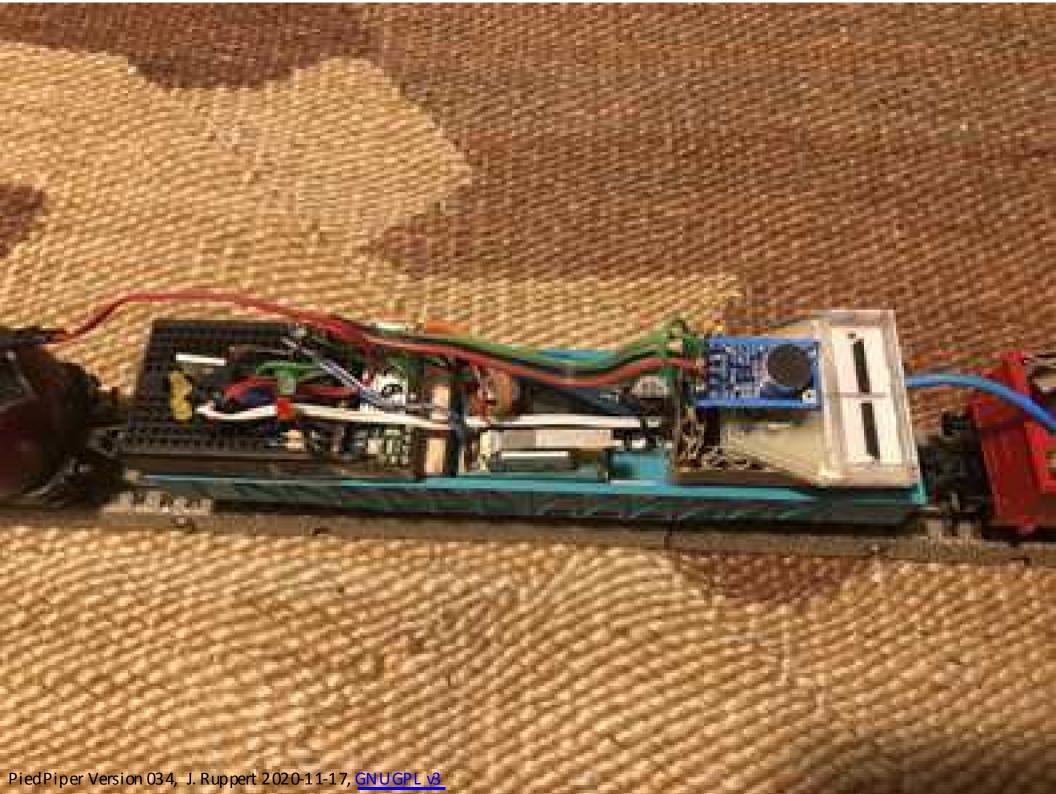


- Electret microphone, nano size micro controller, C++ Arduino software for FFT tone analysis
- No proprietary elements, construction time 2-4 weekends, material cost ca. 60 €
  PiedPiper Version 056, J. Ruppert 2021-03-20, GNUGPL v8 GitHub: https://github.com/jorail/PiedPiper



## Material demand

### for 1 train with whistle control

### **Electronics**

- Nano size microcontroller,
   e.g. Teensy 4.0, but similar solutions are possible with other microcontrollers like Teensy 3.2, ESP32, etc.
  - 1 analogue in for microphone output
  - 2 PW M outputs for motor control
  - 2 digital outputs for LED indicators
  - 1 digital input for option 1 switch
- Compatible electret microphone module, 3.3 V, e.g. MAX9814, Amplifier with Auto Gain Control
- Step-up DC/DC converter module, 5 V to 12V ... 16 V
- H-Bridge DC motor control IC, e.g. TLE5206-2S
- Small size USB power bank as 5 V DC power supply it is good to have two, 2<sup>nd</sup> for replacement when 1<sup>st</sup> empty
- Small size breadboard, e.g. 170 contacts
- Solder IC pin contacts, single row, separable, total of ca. 50 contacts
- Shrink tube with diameter for holding two IC pin contacts
- Thin USB cable, old and used, but reliable for power connection
- LEDs: 1 green, 1 red, 2 yellow, 3 mm diameter
- 2 x 180 Ω resistors
- 1 kΩ resistor
- 2 pole cable, thin and flexible, ca. 40 cm, for connection to motor
- 3 pole isolated wire for microphone module, 10 cm
- 1 pole wires for breadboard and step up converter connections, ca. 60 cm in total

### Other material

- Model train locomotive with 12V ... 16 V DC motor
- Flat wagon for electronics equipment
- Eaos high board open wagon for USB power bank
- Some paper cardboard
- Single and double sided adhesive tape

### Tools

- Single tone sound source: Whistle or flute, e.g. recorder
- Fine tip solder iron with equipment
- Cutter, fine pincers
- Multi-meter tool

### Option 1 addition

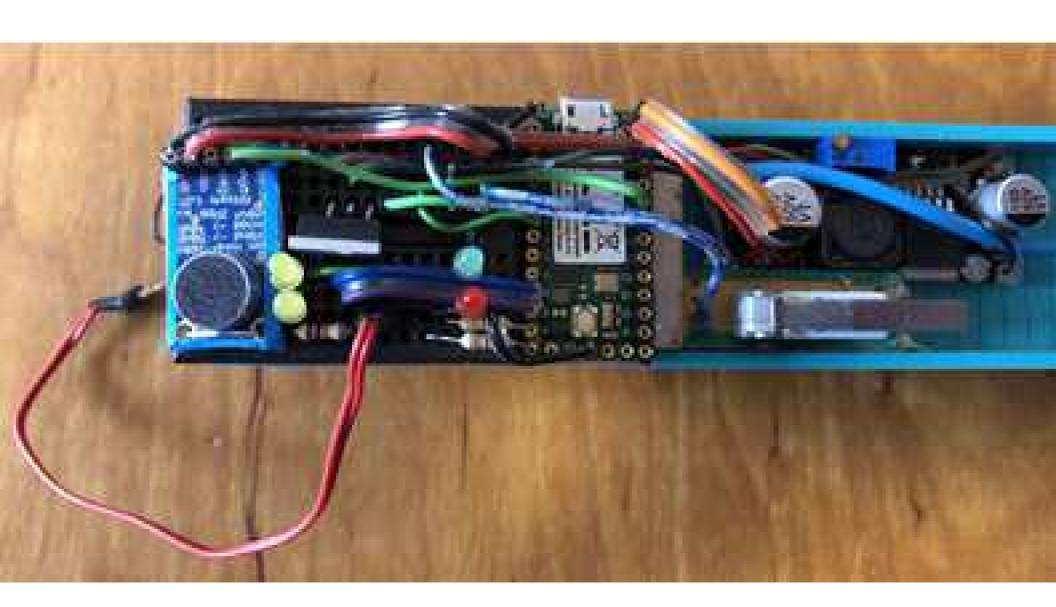
- Micro switch for testing and manual commands
- 10 kΩ resistor
- 1 pole wire, ca. 15 cm

### Option 2 addition

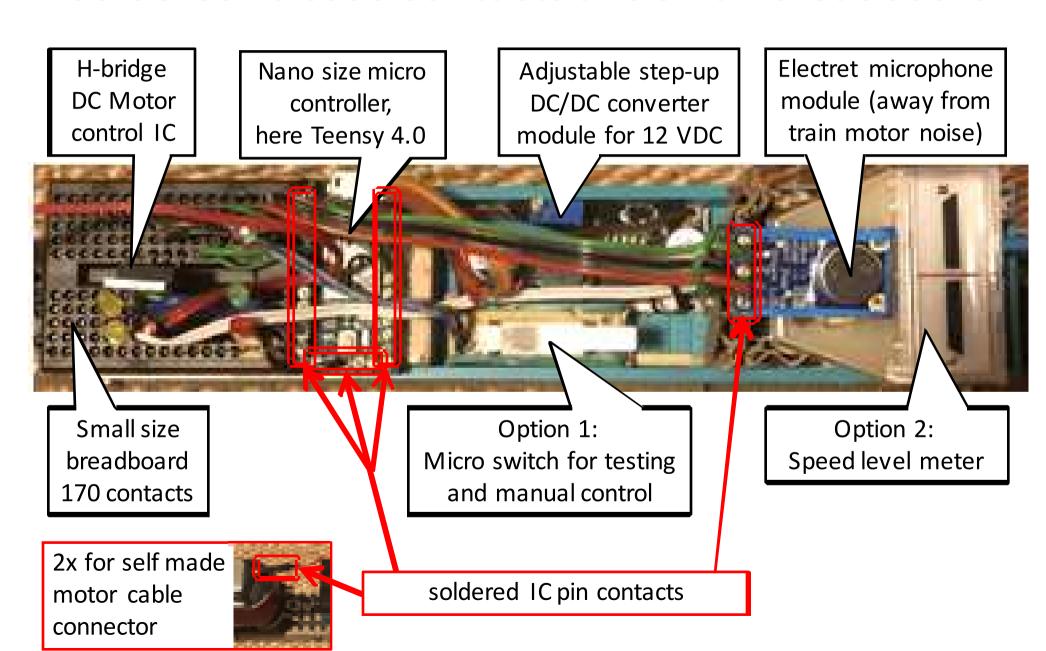
- Small left/right sound balance meter from old equipment, e.g. 270  $\Omega$
- Suitable set of resistors, e.g.  $10 \text{ k}\Omega$  + several 1 to 5 k $\Omega$  resistors
- 2 pole cable, thin and flexible, ca. 10 cm

Estimated material cost ca. 60 € excl. other material, tools and additions

# Nano size micro controller and electronics stored on first wagon and connected with wires

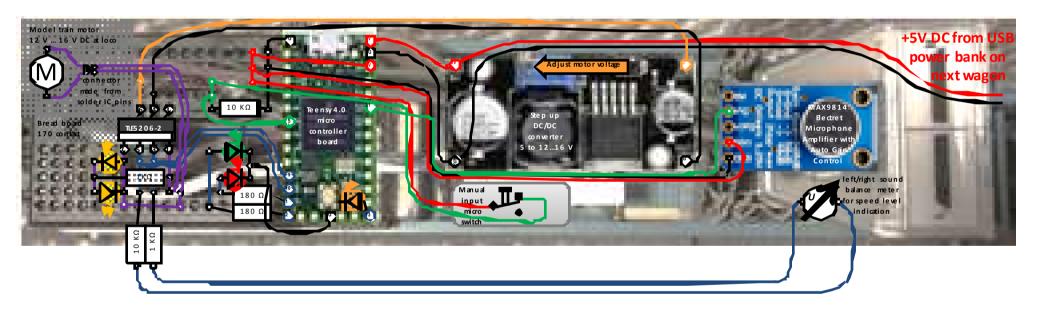


### Soldered IC base contacts and small breadboard



PiedPiper Version 034, J. Ruppert 2020-11-17, GNUGPL v3

## Circuit, parts and connections



## PiedPiper whistle tone commands

Morse code	Command for speed level	Meaning
•		decrease speed
• •		slow down
•••		break to halt
•••	0	fast brake and stop
••••	00<	fast stop, reverse
		direction
• —	++	increase s peed
• — —	++++++	speed up
• — — —	++++++++++++	gofast
_	0	fast brake and stop
	00	fast brake and stop
	00	fast brake and stop
	?	info?
?	?	info?

## PiedPiper LED indicators

LEDs	<b>A A A A A</b>
<ul> <li>Motor speed according to pulse width, resulting voltage and polarity</li> <li>forward, voltage + 12 V to +4 V</li> <li>backward, voltage - 4 V to - 12 V</li> <li>Information on motor direction and speedlevel:</li> </ul>	
<ul> <li>forward = 1 = green LED + 0 to 32 short LED flashes</li> <li>backward = 0 = red LED + 0 to 32 short LED flashes</li> </ul>	
<ul> <li>Adjustment of motor speed:</li> <li>2 green LED flash = speed level + 2;</li> <li>2 red LED flash = speed level - 2;</li> <li>green &amp; red LEDs long flash = fast brake, speed level = 0</li> </ul>	•••
<ul> <li>Change of motor direction:</li> <li>green/red/green + green LED flash = forward = 1</li> <li>red/green/red + red LED flash = backward = 0</li> </ul>	:
<ul> <li>Tone signal detected:</li> <li>Single FFT analysis, frequency window&gt;THRESHOLD1: red LED</li> <li>Averaged FFTs, frequency windows&gt;THRESHOLD2: green LED = tone signal active</li> </ul>	
<ul> <li>Program running and main loop frequency:</li> <li>orange flash after 5,000,000 main loop cycles and 500,000 times monitoring for input activity</li> </ul>	• •

# Tone frequency table

Tone Hertz	Tone Hertz	Tone Hertz	Tone Hertz	Tone Hertz
''A 27,50	C 65,41	c' 261,63	c''' 1.046,50	c'''' 4.186,01
''B 29,14	Des 69,30	des' 277,18	des''' 1.108,73	
''H 30,87	D 73,42	d' 293,66	d''' 1.174,66	
'C 32,70	Es 77,78	es' 311,13	es''' 1.244,51	
'Des 34,65	E 82,41	e' 329,63	e''' 1.318,51	
'D 36,71	F 87,31	f' 349,23	f''' 1.396,91	
'Es 38,89	Ges 92,50	ges' 369,99	ges''' 1.479,98	
'E 41,20	G 98,00	g' 392,00	g''' 1.567,98	
'F 43,65	As 103,83	as' 415,30	as''' 1.661,22	
'Ges 46,25	A 110,00	a' 440,00	a''' 1.760,00	
'G 49,00	B 116,54	b' 466,16	b''' 1.864,66	
'As 51,91	H 123,47	h' 493,88	h''' 1.975,53	
'A 55,00	c 130,81	c'' 523,25	c'''' 2.093,00	
'B 58,27	des 138,59	des'' 554,37	des'''' 2.217,46	
'H 61,74	d 146,83	d'' 587,33	d'''' 2.349,32	
	es 155,56	es'' 622,25	es''' 2.489,02	
	e 164,81	e'' 659,26	e'''' 2.637,02	
	f 174,61	f'' 698,46	f'''' 2.793,83	
	ges 185,00	ges'' 739,99	ges'''' 2.959,96	
	g 196,00	g'' 783,99	g'''' 3.135,96	
	as 207,65	as'' 830,61	as'''' 3.322,44	
	a 220,00	a'' 880,00	a'''' 3.520,00	
	b 233,08	b'' 93 2,33	b''' 3.729,31	
	h 246,94	h'' 987,77 =de fault	h'''' 3.951,07	



