LBA, Space complexity, PSPACE, L, and NL

Textbook: Chapter 5.1, 8

Finite TMs (LBA)

- ► TMs are definitionally *infinite*
- ► Reality is definitionally *finite*
- Corollary: TMs are impossible in real life!
- ► We have to use a finite-sized tape
 - Or a computer that can manufacture new RAM, but imagine a memory leak!

Formal definition of LBA

Def: A **linear bounded automaton** (LBA) is a restricted type of TM which has no memory outside of its input. Equivalently, it has some fixed constant amount of memory.

- An LBA configuration looks like $w_1w_2...w_iq_jw_{i+1}...w_k$, where k is constant a given input
- Since a configuration is of constant length, we can check if it has occurred before in the computation history!
- Therefore, the acceptance and halting problems for LBA are decidable!
- ▶ However, there are still infinitely many inputs: Therefore, E_{LBA} is still undecidable

Space complexity

- We measured time complexity to be the number of steps before halting
- ► In real computation, time is not the only important factor! Memory is often just as, if not more, expensive
- ▶ We can measure memory/space complexity in the same way

Def: Let M be a DTM that always halts. The **space complexity** of M on input of length n is the function $f: \mathcal{N} \to \mathcal{N}$, where f(n) is the maximal number of tape cells that M scans. If the space complexity of M is f(n), we say M runs in space f(n).

If M is a **NTM**, the space complexity is the maximal number of tape cells scanned on **any single branch** of the nondeterminism.

Space complexity classes

- ▶ We usually use asymptotic notation
- ▶ Just like we had TIME and NTIME, we can define SPACE and NSPACE

Def: Space complexity class operators.

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SPACE(f(n)) = \{L : L \text{ is decided by an } O(f(n)) \text{ space DTM}\}

NSPACE(f(n)) = \{L : L \text{ is decided by an } O(f(n)) \text{ space NTM}\}
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Savitch's theorem

- \triangleright We don't think P = NP, but does the space equivalent hold?
- As it turns out, yes! DTMs can simulate NTMs in polynomial space

Def: Savitch's theorem. For any function $f: \mathcal{N} \to \mathcal{R}^+$ where $f(n) \geq log(n)$,

$$NSPACE(f(n)) \subseteq SPACE((f(n))^2)$$

Pf. excluded.

PSPACE

▶ Just like we have *P* for the set of all languages decidable in polynomial time, we can define *PSPACE* for the set of all languages decidable in polynomial deterministic space

Def: *PSPACE* is the set of all languages decidable in deterministic polynomial space.

$$PSPACE = \bigcup_{k} SPACE(n^{k})$$

- We know PSPACE = NPSPACE by Savitch's theorem. Any problem ∈ P can access at most polynomial space, and any problem ∈ NP can access at most nondeterministic polynomial space (NPSPACE)
- ► Let *EXPTIME* be the set of all problems solvable in deterministic exponential time

Class subsets and *PSPACE*-completeness

$$P \subseteq NP \subseteq PSPACE = NPSPACE \subseteq EXPTIME$$

- Researchers think that all the ⊆ above are actually ⊊, but we don't know yet
- We know that at least one is proper

Def: A language *B* is *PSPACE*-**complete** if it satisfies the following two conditions:

- 1. $B \in PSPACE$, and
- 2. Every $A \in PSPACE$ is polynomial-time reducible to B

If only the second holds, we say B is PSPACE-hard.

L and NL

- ► Since *PSPACE* = *NPSPACE*, we need a new thing to care about
- ► What about logarithmic space?

Def: L is the class of languages decidable in logarithmic deterministic space. NL is the class of languages decidable in logarithmic nondeterministic space.

$$L = SPACE(log(n))$$

 $NL = NSPACE(log(n))$

NL-completeness also exists

