Network Dynamics

Event Rate

Hidden Layers

At time t, input $\mathbf{h}^0(t-1)$ is received by the first hidden layer and used to compute its somatic voltages $\mathbf{v}^1(t)$:

$$\mathbf{v}^{1}(t) = \mathbf{W}^{1}\mathbf{h}^{0}(t-1) + \mathbf{b}^{1}$$
 (1)

Then, the *event rates* of the first hidden layer units, $\mathbf{h}^1(t)$, are given by applying the softplus function σ :

$$\mathbf{h}^{1}(t) = \sigma(\mathbf{v}^{1}(t)) \tag{2}$$

Similarly, for all other hidden layers i of the network,

$$\mathbf{v}^{i}(t) = \mathbf{W}^{i}\mathbf{h}^{i-1}(t-1) + \mathbf{b}^{i}$$
(3)

$$\mathbf{h}^{i}(t) = \sigma(\mathbf{v}^{i}(t)) \tag{4}$$

Output Layer

The somatic voltages of output layer k, $\mathbf{v}^k(t)$, are calculated as in equation (3). Unlike hidden layers, output layer units have a rectified linear activation function ψ :

$$\mathbf{h}^{k}(t) = \psi(\mathbf{v}^{k}(t)) \tag{5}$$

During training, a teaching signal \mathbf{t} is randomly presented at the output layer. When the teaching signal is present, the event rates of the final layer are equal to the teaching signal. That is, if a teaching signal arrives at time t^* , the event rates of the output layer k become:

$$\mathbf{r}^k(t^*) = \mathbf{t} \tag{6}$$

Burst Probability & Burst Rate

Output Layer

At the output layer k, we set the *burst probabilities* to be a constant value ω :

$$\mathbf{p}^k(t) = \omega \tag{7}$$

The burst rates of the output layer k at time t are given by:

$$\boldsymbol{\beta}^{k}(t) = \mathbf{p}^{k}(t)\mathbf{h}^{k}(t) \tag{8}$$

Hidden Layers

At time t, for hidden layer i, the apical dendritic voltages $\mathbf{u}^{i}(t)$ are:

$$\mathbf{u}^{i}(t) = \frac{\mathbf{Y}^{i}\boldsymbol{\beta}^{i+1}(t-1)}{\mathbf{Z}^{i}\boldsymbol{\beta}^{i}(t-1)}$$
(9)

where $\beta^{i}(t)$ are the burst rates of layer i at time t (see equation (8)). The burst probabilities of hidden layer i, $\mathbf{p}^{i}(t)$, are given by applying the sigmoid function σ :

$$\mathbf{p}^{i}(t) = \sigma(\mathbf{u}^{i}(t)) \tag{10}$$

Finally, the *burst rates* of hidden layer i are as in equation (8).

Recurrent Weight Updates

The recurrent weights \mathbf{Z}^i are updated continuously in order to descend the loss function $L^{\mathbf{Z}^i}(t)$:

$$L^{\mathbf{Z}^{i}}(t) = \|\mathbf{u}^{i}(t)\|_{2}^{2} + \|\alpha - \mathbf{Z}^{i}\|_{2}^{2}$$
(11)

where α is a constant. The first term will update \mathbf{Z}^i in order to push the apical voltages \mathbf{u}^i toward 0, while the second term is a regularization term that will push \mathbf{Z} toward small values as long as α is small. The parameter α allows us to control how small \mathbf{Z} should be allowed to get. Thus, at every time step t, \mathbf{Z}^i is updated according to:

$$\Delta \mathbf{Z}^{i}(t) = -\eta \frac{\partial L^{\mathbf{Z}^{i}}(t)}{\partial \mathbf{Z}^{i}} \tag{12}$$

$$= \eta \left(\left(\frac{(\mathbf{u}^{i}(t))^{2}}{\mathbf{Z}^{i} \beta^{i}(t-1)} \right) \otimes \beta^{i}(t-1) + (\alpha - \mathbf{Z}^{i}) \right)$$
(13)

Feedback Weight Updates

The feedback weights \mathbf{Y}^i are updated continuously in order to descend the loss function $L^{\mathbf{Y}^i}(t)$:

$$L^{\mathbf{Y}^i}(t) = \|\gamma - \mathbf{u}_{\text{max}}^i\|_2^2 \tag{14}$$

where γ is a constant, and \mathbf{u}_{\max}^i are the maximum possible values for the apical voltages that can be driven by feedback, if recurrent activity is kept fixed:

$$\mathbf{u}_{\max}^{i} := \frac{|\mathbf{Y}^{i}|\mathbf{1}}{\mathbf{Z}^{i}\boldsymbol{\beta}^{i}(t-1)} \tag{15}$$

where **1** is a vector of ones of the same size as layer i+1. Descending this loss function will update \mathbf{Y}^i in order to produce an upper bound and lower bound of \mathbf{u}^i_{\max} and $-\mathbf{u}^i_{\max}$, respectively, for the apical voltages \mathbf{u}^i . The parameter γ allows us to control what value the upper and lower bounds should have. Thus, at every time step t, \mathbf{Y}^i is updated according to:

$$\Delta \mathbf{Y}^{i}(t) = -\eta \frac{\partial L^{\mathbf{Y}^{i}}(t)}{\partial \mathbf{Y}^{i}} \tag{16}$$

$$= \eta \left(\frac{(\gamma - \mathbf{u}_{\text{max}}^i)}{\mathbf{Z}^i \boldsymbol{\beta}^i (t - 1)} | \mathbf{Y}^i | \right)$$
 (17)

Feedforward Weight Updates

For a network with output layer k, the feedforward weights \mathbf{W}^i are updated continuously in order to descend the global loss function L(t):

$$L(t) = \|\boldsymbol{\beta}^{k}(t) - \boldsymbol{\beta}^{k}(t-1)\|_{2}^{2}$$
(18)

First, we will show the feedforward weight updates that would be prescribed by backpropagation of error. For the output layer,

$$\Delta \mathbf{W}^{k}(t) = -\eta \frac{\partial L(t)}{\partial \mathbf{W}^{k}} \tag{19}$$

$$= -\eta \frac{\partial L(t)}{\partial \boldsymbol{\beta}^{k}(t-1)} \frac{\partial \boldsymbol{\beta}^{k}(t-1)}{\partial \mathbf{r}^{k}(t-1)} \frac{\partial \mathbf{r}^{k}(t-1)}{\partial \mathbf{v}^{k}(t-1)} \frac{\partial \mathbf{v}^{k}(t-1)}{\partial \mathbf{W}^{k}}$$
(20)

$$= (\boldsymbol{\beta}^k(t) - \boldsymbol{\beta}^k(t-1))\omega H(\mathbf{v}^k(t-1)) \otimes \mathbf{h}^{k-1}(t-2) \tag{21}$$

where H is the Heaviside step function. Let us denote δ^k as:

$$\delta^{k} := \frac{\partial L(t)}{\partial \boldsymbol{\beta}^{k}(t-1)} \frac{\partial \boldsymbol{\beta}^{k}(t-1)}{\partial \mathbf{r}^{k}(t-1)} \frac{\partial \mathbf{r}^{k}(t-1)}{\partial \mathbf{v}^{k}(t-1)}$$
(22)

For the last hidden layer k-1,

$$\Delta \mathbf{W}^{k-1}(t) = -\eta \frac{\partial L(t)}{\partial \mathbf{W}^{k-1}}$$
 (23)

$$= -\eta \frac{\partial L(t)}{\partial \mathbf{\beta}^{k}(t-1)} \frac{\partial \mathbf{\beta}^{k}(t-1)}{\partial \mathbf{r}^{k}(t-1)} \frac{\partial \mathbf{r}^{k}(t-1)}{\partial \mathbf{v}^{k}(t-1)} \frac{\partial \mathbf{v}^{k}(t-1)}{\partial \mathbf{W}^{k}}$$
(24)

$$= (\boldsymbol{\beta}^{k}(t) - \boldsymbol{\beta}^{k}(t-1))\omega H(\mathbf{v}^{k}(t-1)) \otimes \mathbf{h}^{k-1}(t-2)$$
 (25)