

# Industrial Design Project 3

## DES370S

Project Title: Blue OpenOcean Explorer (BOO-E)

Subtitle: Project Management Presentation

Student Initial and Surname: JF Williams

Student Number: 221343687

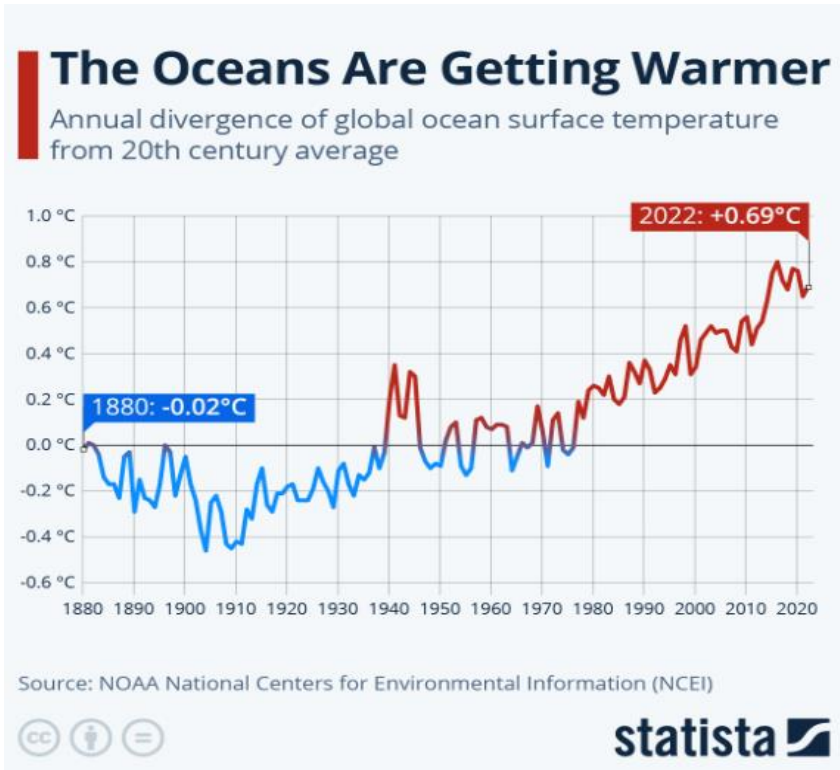
Lecturer: Dr M. Mnguni

Date of Evaluation: 23/05/2024

# Outline

- Introduction
- Proposed Plan
- System overview
- Benefits of Open-source Technology
- Budget Management
- Risk Analysis
- Time and Change Management
- Quality Assurance
- Economics Principles
- Evaluation of Project Outcomes
- Conclusion

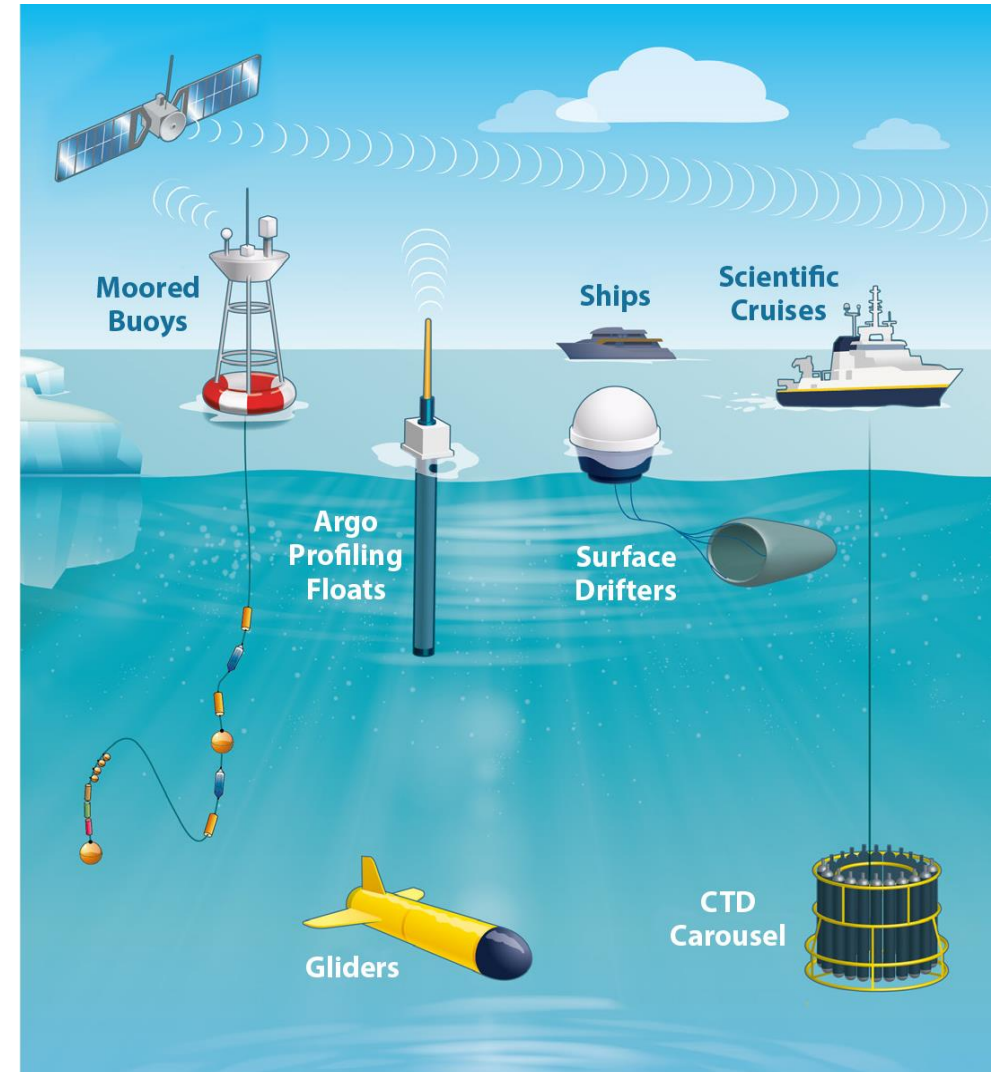
# Introduction



[1]



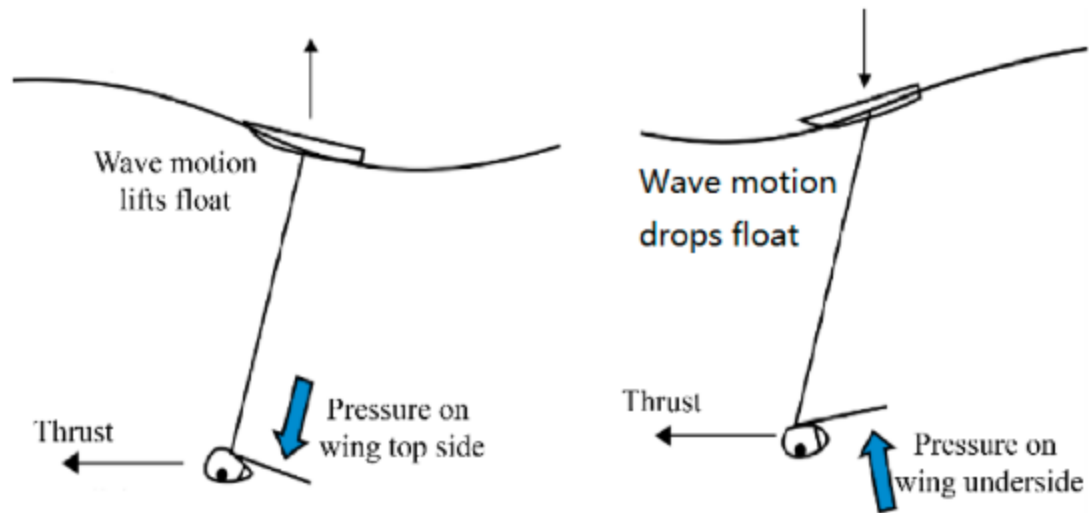
[3]



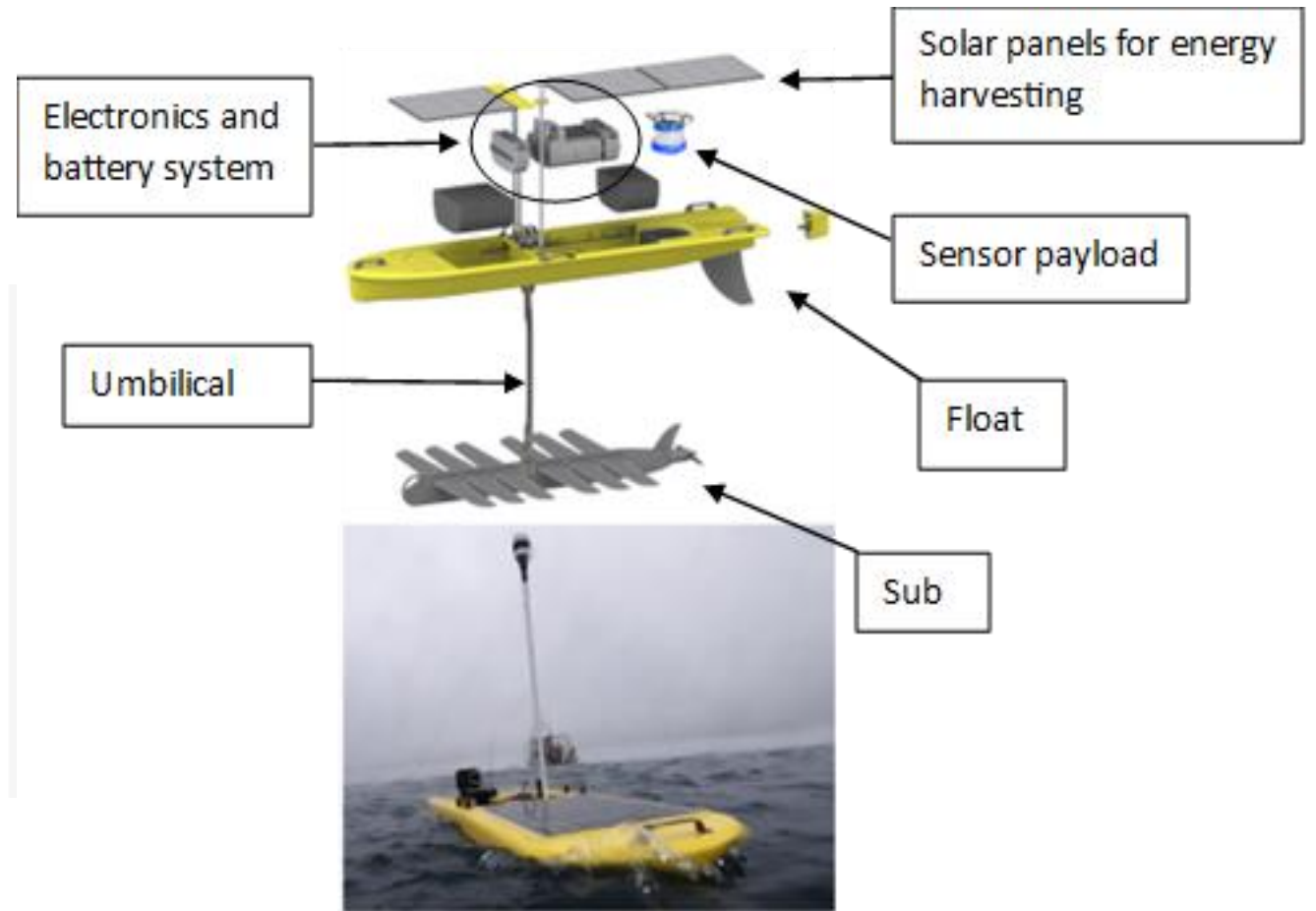
[11]

# Proposed Plan

## Blue OpenOcean Explorer (BOO-E)



[9]



Liquid Robotics SV2 Wave Glider [6]

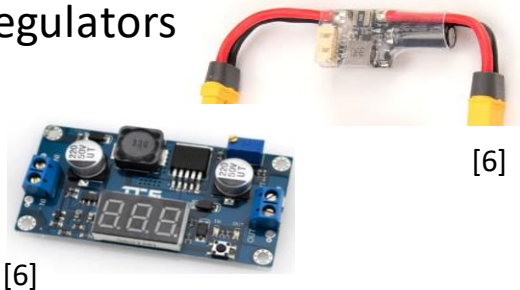
# System overview

## Power management

Harvesting: Solar and battery storage



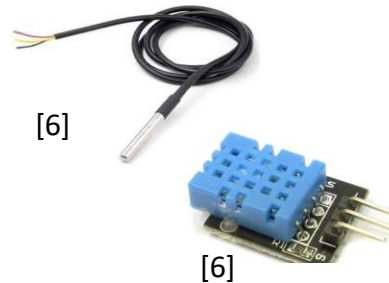
Management: PDB's, DC-DC regulators



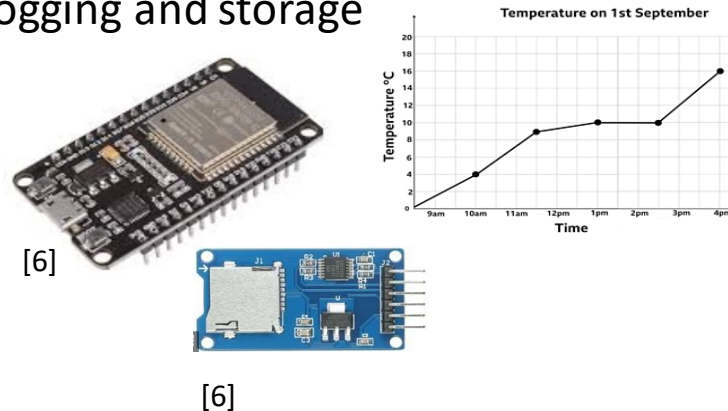
## Open-source based ASV project

## Data collection

Sensors:  
Temp  
Salinity  
Atmospheric data



## Logging and storage

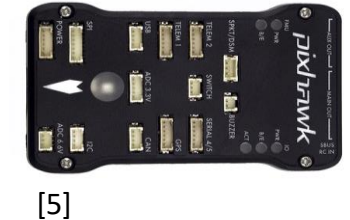


## Navigation

Inputs: GPS, Compass, IMU, Pilot



## Flight controller

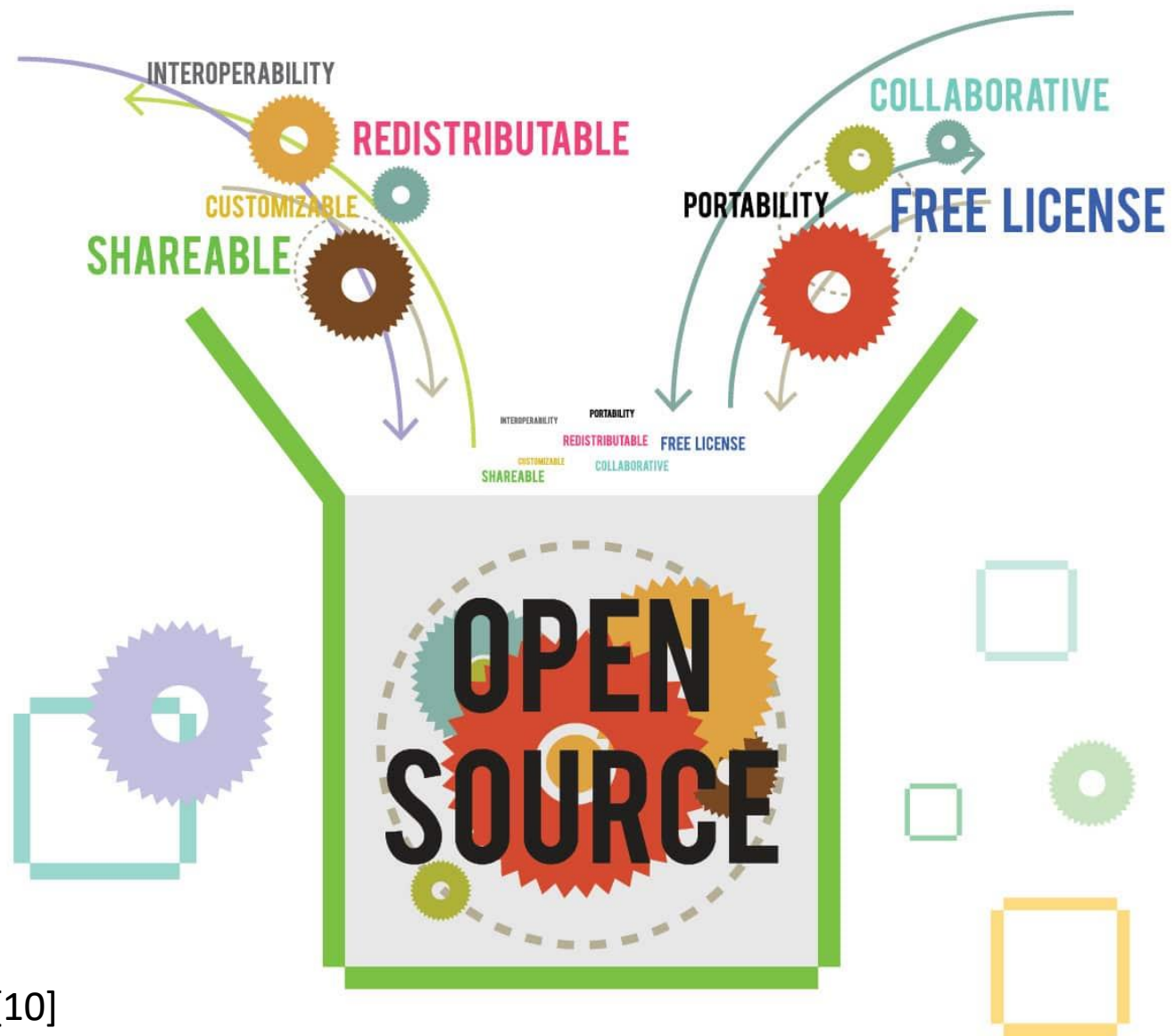


Outputs: Rudder angle  
Thruster control  
Sail angle



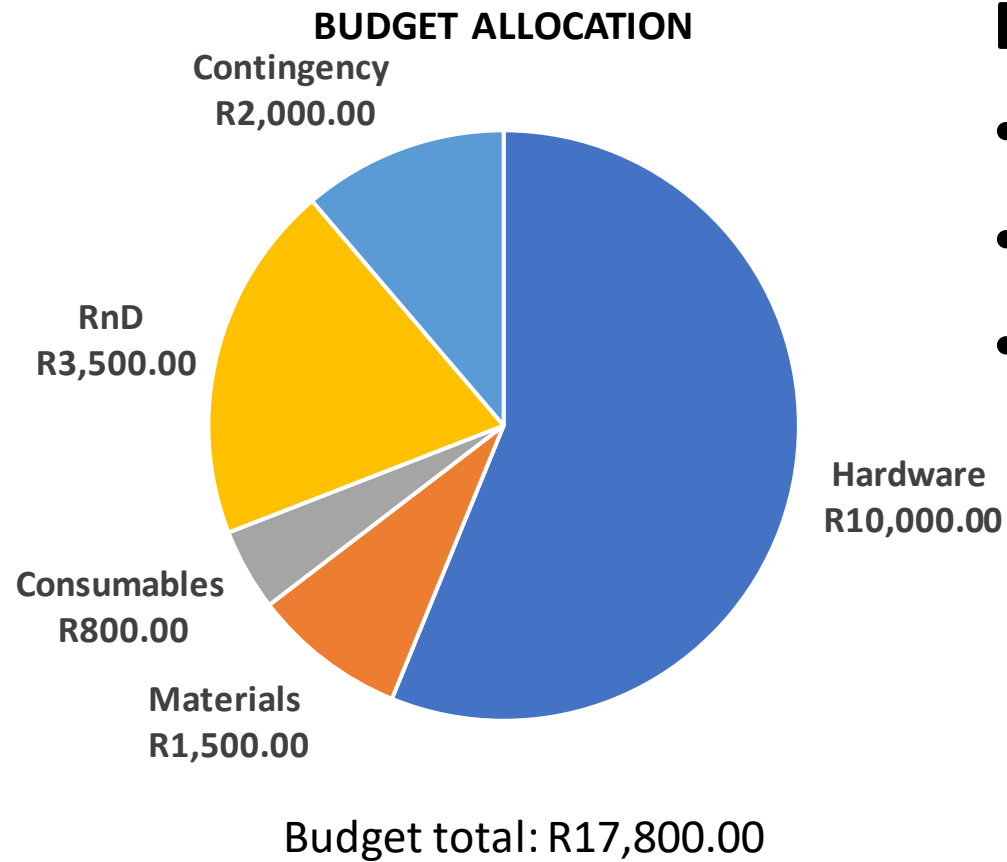
# Benefits of Open-Source technology

- Cost reduction
- Collaboration
- Flexibility
- Sustainability





# Budget Management



## Evaluation of Adherence to Budget

- Securing sponsorships for companies (4, 7)
- Use inhouse resources
- Eliminate unnecessary expenses through risk assessment



[4]



[7]

# Hardware cost breakdown

System	Hardware	description	Quantity	price	link
Navigation	Pixhawk pro flight controller			R3,999.00	<a href="https://microbotsa.co.za/index.php?route=product/product&amp;path=97&amp;product_id=96">https://microbotsa.co.za/index.php?route=product/product&amp;path=97&amp;product_id=96</a>
	GPS and Compass	Pixhawk flight controlller set	1		<a href="https://neotronics.co.za/index.php?route=product/product&amp;path=104&amp;product_id=565">https://neotronics.co.za/index.php?route=product/product&amp;path=104&amp;product_id=565</a>
	RF telemetry	Communication and manual contr	1	R1,483.50	<a href="https://neotronics.co.za/index.php?route=product/product&amp;path=104&amp;product_id=260">https://neotronics.co.za/index.php?route=product/product&amp;path=104&amp;product_id=260</a>
	VHF antenna	AIS antenna	1	-	In house
	AIS	Automatic Identification	1	R2,100.00	<a href="https://shop.wegmatt.com/collections/frontpage/products/daisy-2-dual-channel-ais-receiver-with-nmea-0183">https://shop.wegmatt.com/collections/frontpage/products/daisy-2-dual-channel-ais-receiver-with-nmea-0183</a>
Power	Solar regulator	Regulate battery charge	1	R180.00	<a href="https://www.communica.co.za/products/bdd-dc-dc-buck-mppt-solar-5a-dis?variant=45944865849644">https://www.communica.co.za/products/bdd-dc-dc-buck-mppt-solar-5a-dis?variant=45944865849644</a>
	Lithium ion Batteries	12V battery packs	2	R680.00	<a href="https://www.communica.co.za/products/batt-12-8v7-scp">https://www.communica.co.za/products/batt-12-8v7-scp</a>
	DC-DC regulator	Regulate input power	2	R60.00	<a href="https://www.communica.co.za/products/hkd-dc-dc-buck-boost-1-25-35v-4a?variant=44293669519660">https://www.communica.co.za/products/hkd-dc-dc-buck-boost-1-25-35v-4a?variant=44293669519660</a>
Data	ESP32	Controller	1	R 160.00	<a href="https://www.communica.co.za/products/hkd-esp-32-wifi-b-t-dev-board">https://www.communica.co.za/products/hkd-esp-32-wifi-b-t-dev-board</a>
	MicroSD card module	Data logging	1	R 25.00	<a href="https://www.communica.co.za/products/hkd-d1-mini-micro-sd-card-modul?variant=39341863960649">https://www.communica.co.za/products/hkd-d1-mini-micro-sd-card-modul?variant=39341863960649</a>
	SD card 16GB		1	R 55.00	<a href="https://www.communica.co.za/products/hkv-hs-tfc1-16gb-adpt">https://www.communica.co.za/products/hkv-hs-tfc1-16gb-adpt</a>
	Anodes (Salinity test)	in house design	2	R -	2 conductive rods (ie copper)
	Temperature sensor	temperature probe. DS18B20	2	R27.00	<a href="https://www.communica.co.za/products/hkd-temperature-probe-ds18b20-1m">https://www.communica.co.za/products/hkd-temperature-probe-ds18b20-1m</a>
Safety	Leak detectors	detect water (In house design)	4	R20.00	In house
	4ch 5V/36V relay	power control	3	R82.00	<a href="https://www.communica.co.za/products/bdd-relay-board-4ch-3-3v?variant=47620050485548">https://www.communica.co.za/products/bdd-relay-board-4ch-3-3v?variant=47620050485548</a>
	LDR	Light dependent resistor	2	R5.00	Componnet shop
	Strobe light	safety light	1	R382.00	<a href="https://www.communica.co.za/products/0550ydwlh">https://www.communica.co.za/products/0550ydwlh</a>
	Strobe light mounting bracket	Mounting plate	1	R135.00	<a href="https://www.communica.co.za/products/0550tbphk?variant=20112145907785">https://www.communica.co.za/products/0550tbphk?variant=20112145907785</a>



# RISK ANALYSIS



[2]



[3]

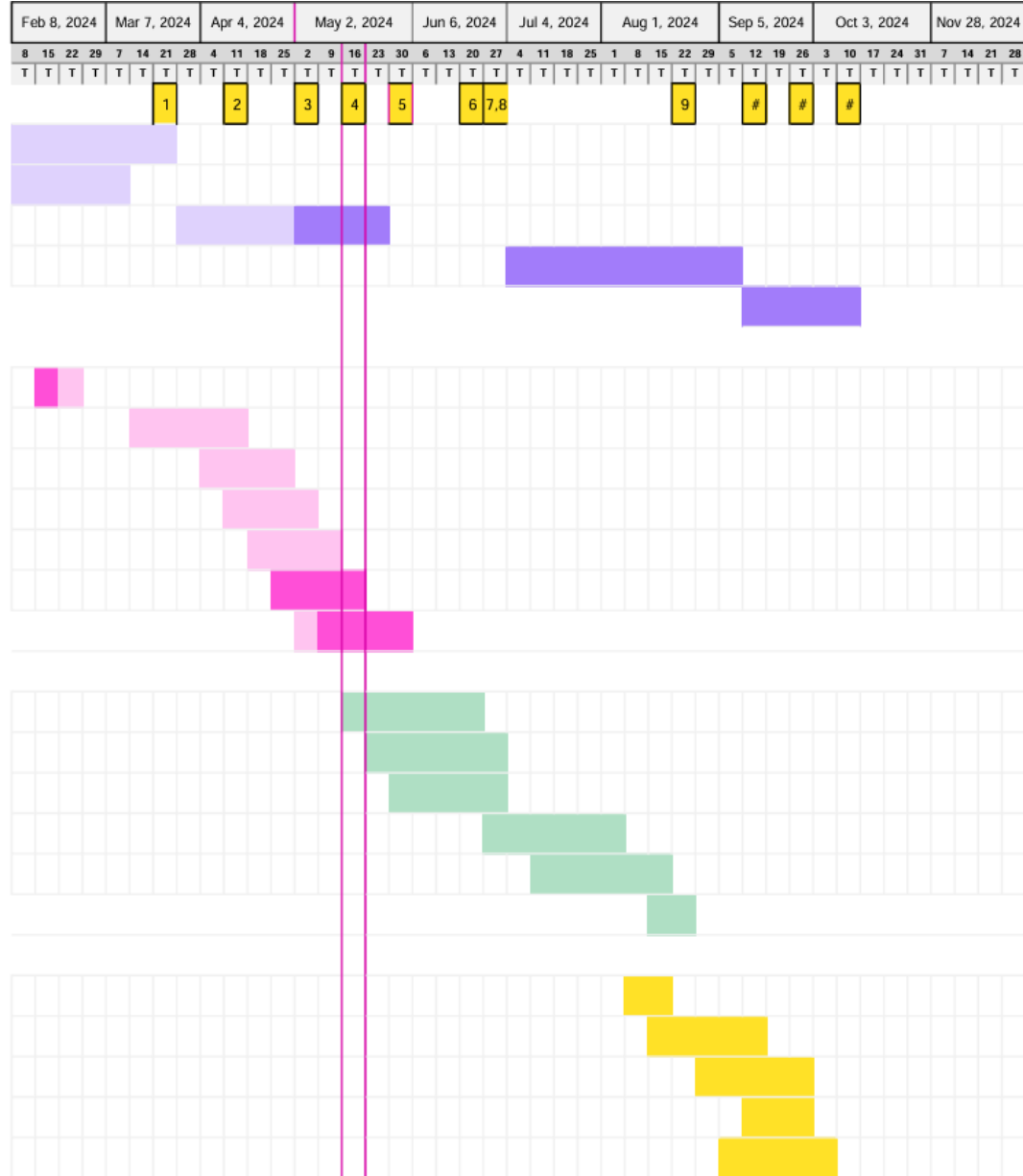
Category	Risk	Assesment	Likelihood rating	Mitigation plan	Priority rating
Technical	Component failure	Component failure could cause a malfunction and loss of operations	2	Rigorously test the components before final mounting	4
	Navigation error	Unable to navigate and could cause damage	3	Calibrate GPS before use and add redundancy	5
	Electrical faults	Components shorting out can destroy controllers and cause loss of operations	2	Use protection devices to mitigate potential damage	5
	Software intergration	Software bugs and communication issues	3	Rigorously test and scan for bugs before final version release	4
Resource	Funds	Limited personal funds	4	Seek sponsorships and/or partners	5
	Available time	Limited free time alongside full time studies	3	Use any availalbe time to make progress with the project	3
	Component availability	Some components are not commonly available or need to be shipped in	1	Request quotes with lead time well in advance to plan around	3
	Access to labs and testing facilities	Access to labs requires a supervisor present. Thus access is dependent on someone else	2	Create a schedule for when the labs will be available	3
Operational	Operating Environment	Exposed to harsh conditions, corrosive sea water, direct UV rays, wave impacts	5	Mount components in IP68 rugged enclosure with waterproofing techniques	5
	External interference	Human and animal interference	3	Place warning stickers to stop people from interfering with the vehicle.	2
	Communication loss	Loss of communication or sight of vehicle	3	Mount antennas on a mast to improve range and use a flashing warning light to improve visibility	3
Environment and safety	Collision	Other vessels could collide with it if they don't see it	1	Use a method of vessel identification such as AIS	4
	personal safety	Handling equipment, testing, exposed to electric currents	2	Take precaution when working and use PPE	2
	Environmental impact	Little to no interference with environment	1	Secure all items so nothing falls off while in operation	1

# Time and Change Management

- Monitoring Progress
- Time Estimation for Each Task
- Milestones and Deadlines

# Monitoring Progress

TASK	Next step	PROGRESS	START	END
<b>Initial planing and management</b>		65%		
Create project proposal	completed	100%	8-Feb-24	21-Mar-24
Initial research	completed	100%	7-Feb-24	7-Mar-24
Management Presentation	25/04 lecture	60%	28-Mar-24	23-May-24
Progress Presentation		0%	5-Jul-24	5-Sep-24
Final report			12-Sep-24	10-Oct-24
<b>Planning and design</b>		73%		
System overview	Completed	100%	21-Feb-24	28-Feb-24
List of components	completed	100%	14-Mar-24	12-Apr-24
Develop budget	Finalise with Supervisor	100%	4-Apr-24	25-Apr-24
Define milestones and time lines	Finalise with Supervisor	100%	11-Apr-24	2-May-24
Identify risks	Finalise with Supervisor	100%	18-Apr-24	9-May-24
Quality and economical assuraty	Finalise with Supervisor	0%	25-Apr-24	16-May-24
circuit and wiring diagrams		10%	2-May-24	30-May-24
<b>Prototyping and testing</b>		0%		
Navigation system initial setup and calibration	Speak to supervisor about purchasing	0%	16-May-24	21-Jun-24
Data collection system initial setup and testing		0%	23-May-24	27-Jun-24
Power system setup and testing		0%	30-May-24	27-Jun-24
Integrate navigation and data system with sensors and test/simulate		0%	27-Jun-24	1-Aug-24
Integrate data retrieval method		0%	16-Jul-24	15-Aug-24
Bench test entire system		0%	15-Aug-24	22-Aug-24
<b>Vehicle intergration and final testing</b>		0%		
Install navigation and data logging system into the vehicle		0%	8-Aug-24	20-Aug-24
Test overall system and find improvements		0%	16-Aug-24	12-Sep-24
Field test vehicle and gather real-world data		0%	29-Aug-24	26-Sep-24
Final changes		0%	12-Sep-24	26-Sep-24
Gather feedback		0%	5-Sep-24	4-Oct-24



MILESTONE	DEADLINE
1. Submit proposal	21-Mar
2. Submit list of hardware	11-Apr
3. Implement management system	2-May
4. Order majority of components	16-May
5. conceptual and circuit designs	30-May
6. Establish comms with GNS, GPS and flight controller	21-Jun
7. Establish first successful sample and log of data	27-Jun
8. Establish steady power supply	27-Jun
9. Bench test and simulate system	22-Aug
10. Marry electronics and chassis and overall systems tests	12-Sep
11. Real world test	26-Sep
12: Final presentation	10-Oct

# Time Estimation for Each Task

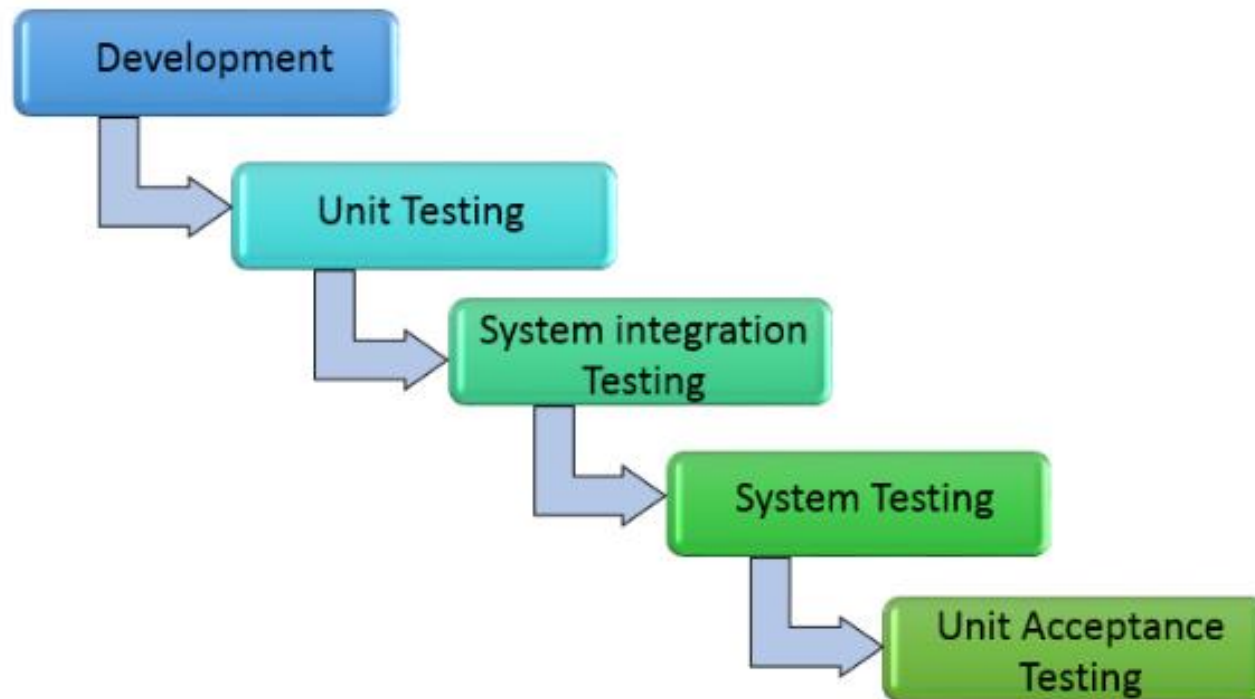
TASK	Next step	PROGRESS	START	END
<b>Initial planing and management</b>		75%		
Create project proposal	completed	100%	8-Feb-24	21-Mar-24
Initial research	completed	100%	7-Feb-24	7-Mar-24
Management Presentation	Completed	100%	28-Mar-24	23-May-24
Progress Presentation		0%	5-Jul-24	5-Sep-24
Final report			12-Sep-24	10-Oct-24
<b>Planning and design</b>		80%		
System overview	Completed	100%	21-Feb-24	28-Feb-24
List of components	completed	100%	14-Mar-24	12-Apr-24
Develop budget	completed	100%	4-Apr-24	25-Apr-24
Define milestones and time lines	completed	100%	11-Apr-24	2-May-24
Identify risks	completed	100%	18-Apr-24	9-May-24
Quality and economical assuaty	completed	0%	25-Apr-24	16-May-24
circuit and wiring diagrams	Transfer to CAD	60%	2-May-24	30-May-24

TASK	Next step	PROGRESS	START	END
<b>Prototyping and testing</b>		0%		
Navigation system initial setup and calibration	Waiting for parts to arrive	0%	16-May-24	21-Jun-24
Data collection system initial setup and testing	Waiting for parts to arrive	0%	23-May-24	27-Jun-24
Power system setup and testing	Waiting for parts to arrive	0%	30-May-24	27-Jun-24
Integrate navigation and data system with sensors and test/simulate		0%	27-Jun-24	1-Aug-24
Integrate data retrieval method		0%	16-Jul-24	15-Aug-24
Bench test entire system		0%	15-Aug-24	22-Aug-24
<b>Vehicle intergration and final testing</b>		0%		
Install navigation and data logging system into the vehicle		0%	8-Aug-24	20-Aug-24
Test overall system and find improvements		0%	16-Aug-24	12-Sep-24
Field test vehicle and gather real-world data		0%	29-Aug-24	26-Sep-24
Gather feedback		0%	5-Sep-24	4-Oct-24
Final changes		0%	12-Sep-24	26-Sep-24

MILESTONE	DEADLINE	Status
1. Submit proposal	21-Mar	Done
2. Submit list of hardware	11-Apr	Done
3. Implement management system	2-May	Done
4. Order majority of components	16-May	Done
5. conceptual and circuit designs	30-May	In progress
6. Establish comms with GNS, GPS and flight controller	21-Jun	
7. Establish first successful sample and log of data	27-Jun	
8. Establish steady power supply	27-Jun	
9. Bench test and simulate system	22-Aug	
10. Marry electronics and chassis and overall systems tests	12-Sep	
11. Real world test	26-Sep	
12: Final presentation	10-Oct	

# Quality Assurance

Systematic procedure of testing and integrating components



Detailed documentation



[6]

Staying within Industry standards



[6]

[6]

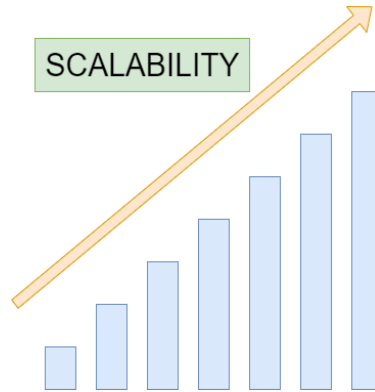
23/05/2024



# Economics Principles



[3]

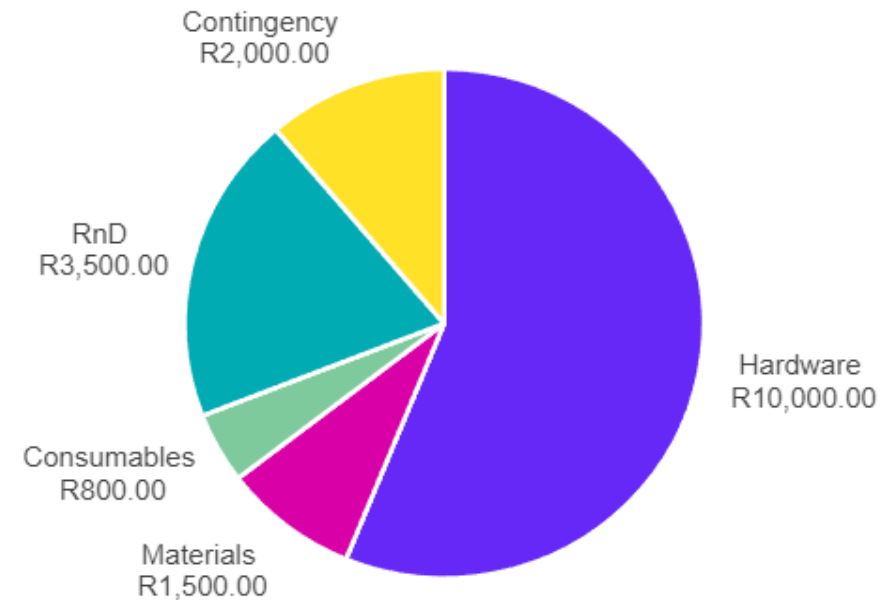


[3]

COST ↑		<ul style="list-style-type: none"> <li>• Branded hardware               <ul style="list-style-type: none"> <li>• AIS system</li> <li>• Pixhawk controller</li> <li>• PV system</li> </ul> </li> </ul>
		<ul style="list-style-type: none"> <li>• Hardware clones</li> <li>• Legacy components</li> <li>• Open-Source resources</li> <li>• Decommissioned glider chassis</li> <li>• Microcontrollers</li> </ul>
	VALUE →	

Item	<input checked="" type="checkbox"/>	Sum of Actual spend	Sum of difference	Sum of Allocated
Hardware		R 8,565.00	R 1,435.00	R 10,000.00
RnD				R 3,500.00
Materials				R 1,500.00
Contingency				R 2,000.00
Consumables				R 800.00
<b>Grand Total</b>		<b>R 8,565.00</b>	<b>R 1,435.00</b>	<b>R 17,800.00</b>

BUDGET ALLOCATION



# Expected Outcomes

Deployable Proof of Concept

Autonomous  
Navigation

Data  
Collection

Waypoint  
follow

Real time  
feedback

Sample  
from  
sensors

Store data  
with time  
stamps

# Conclusion

Proprietary < Open-Source



[3]



[3]

- The more we understand the behaviour of our oceans the better we can plan for our future.



[3]

# Thank you for you attention.

## Any questions?

Contact details: Jordan Williams

Cell: +27 78 136 7086

Email: [221343687@mycput.ac.za](mailto:221343687@mycput.ac.za) /  
[jordanwilliaams12@gmail.com](mailto:jordanwilliaams12@gmail.com)

# References

- [1] K. Buchholz, “Infographic: The Oceans Are Getting Warmer,” *Statista Infographics*, Jan. 15, 2021. <https://www.statista.com/chart/19418/divergence-of-ocean-temperatures-from-20th-century-average/>
- [2] Sonardyne, “Redirect Notice,” *Google.com*, 2024. [https://www.google.com/url?sa=i&url=https%3A%2F%2Fwww.sonardyne.com%2Fapplications%2Focean-currents%2F&psig=AOvVaw3xA\\_cL7y7ZwGlRjGevBaFK&ust=1716401004345000&source=images&cd=vfe&opi=89978449&ved=OCBIQjRxqFwoTCJDbzZiqn4YDFQAAAAAdAAAAABAE](https://www.google.com/url?sa=i&url=https%3A%2F%2Fwww.sonardyne.com%2Fapplications%2Focean-currents%2F&psig=AOvVaw3xA_cL7y7ZwGlRjGevBaFK&ust=1716401004345000&source=images&cd=vfe&opi=89978449&ved=OCBIQjRxqFwoTCJDbzZiqn4YDFQAAAAAdAAAAABAE) (accessed May 21, 2024).
- [3] Clipart library , <https://clipart-library.com/>
- [4] Sea Technology Services, “Sea Technology Services,” *Sea Technology Services*. <https://www.seatechnology.co.za/> (accessed May 21, 2024).
- [5] Ardupilot, “Open Source Drone Software. Versatile, Trusted, Open. ArduPilot.,” *ardupilot.org*. <https://ardupilot.org/>
- [6] Communica south africa, “Communica South Africa,” *Communica South Africa*. <https://www.communica.co.za/>
- [7] “Council for Scientific and Industrial Research (CSIR) - Overview,” *nationalgovernment.co.za*. <https://nationalgovernment.co.za/units/view/212/council-for-scientific-and-industrial-research-csir>
- [8] T. Morris *et al.*, “Monitoring Boundary Currents Using Ocean Observing Infrastructure | Oceanography,” *Frontiers in Ocean Observing: Documenting Ecosystems, Understanding Environmental Changes, Forecasting Hazards*, vol. 34, no. 4, Jan. 2022, doi: <https://doi.org/10.5670/oceanog.2021..>
- [9] X. Chen, M. Hong, S. Wu, K. Liu, and K. Mao, “Design of Wave Glider Optimal Parameters Suitable for the Northwest Pacific Ocean, the North Indian Ocean, and the South China Sea,” *Journal of Marine Science and Engineering*, vol. 9, no. 4, p. 408, Apr. 2021, doi: <https://doi.org/10.3390/jmse9040408>.
- [10] S. Kolhe, “The Benefits of Open Source Products,” *opensourceforu*, Sep. 20, 2015. <https://www.opensourceforu.com/2015/09/the-benefits-of-open-source-products/?amp> (accessed May 21, 2024).
- [11] Van Lancker and M. Baeye, “Wave Glider Monitoring of Sediment Transport and Dredge Plumes in a Shallow Marine Sandbank Environment,” *PLOS ONE*, vol. 10, no. 6, p. 5/15, Jun. 2015, doi: <https://doi.org/10.1371/journal.pone.0128948>.