Hazard Analysis SE 4G06, TRON 4TB6

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Revision History

Date	Developer(s)	Change
10/19/22	Jordan, Abdallah, Udeep	Worked on Sections 5 / General Editing
10/14/22	Azriel G.	Added sections 1, 2, and 3
04/04/23	Taranjit.	Updated Feedback And Formated Table
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1 Introduction

This document is the hazard analysis for the entirety of Synesthesia Wear. For context, Synesthesia Wear is an inexpensive and non-intrusive hearing aid wearable device with a purpose of improving quality of life by providing users with an alternate channel for sound recognition within their surroundings. Furthermore, this wearable device will have a corresponding application that will be made to be user-friendly so that users can easily access and configure their wearable devices to whatever settings they so desire. Lastly, for the purposes of this document, the Synesthesia Wear developers believe that the definition of a hazard is one that is derived from Nancy Leveson's work. With that in mind, a hazard is any property or condition within the Synesthesia Wear system where after pairing up with any conditions in the environment, a potential for loss to the system now exists.

2 Scope and Purpose of Hazard Analysis

The scope of this document is to identify any and all possible hazards within the system, clarify the mitigation steps of each identified hazard, determine the causes and effects of all failures, and define all safety and security requirements that have resulted from the overall analysis.

3 System Boundaries and Components

The hazard analysis will be conducted on the Synesthesia Wear system which will be comprised of the following components:

- 1. The wearable device consists of:
 - (a) Vibration Motor
 - (b) Microphone
 - (c) Microcontroller
 - (d) Bluetooth module
- 2. The Application to be installed on the users' devices consists of:
 - (a) User Interface
 - (b) Wearable device Settings Configuration
- 3. The Device that runs the application
 - (a) Operating System

With the above in mind, the system boundary is limited to the above 3 components with each having their own respective subcomponents. Furthermore, it is important to note that not all components in the above list can be controlled (i.e. Device's Operating System) by the Synesthesia Wear developers. However, these components still needed to be listed down in the system boundary as the potential for a hazard can still be correlated to them.

4 Critical Assumptions

- CA1. The battery will not need to be replaced during product lifespan.
- CA2. Signal input devices will be consistent with the results they produce.
- CA3. Software application failure will not diminish usage of product.
- CA4. The microphone is not blocked and has full access to the environment.

5 Failure Mode and Effect Analysis

Put the table in landscape mode

Table 1: Wearable Device Failure Modes and Effects Analysis

				e Failure Modes and	J			
v	earable Devi							
	· · · · · · · · · · · · · · · · · · ·	equirements						
Sub-	Design	Failure	Effects of	Causes of Fail-	Recommended	Risk	Safety	Ref
\mathbf{System}	Func-	Mode	Failure	ure	Actions	Priority	Re-	
	tion					Number	quire-	
						(RPN)	\mathbf{ment}	
Battery	Power	Battery	1.Device loses	1.Battery was not	1.Inform users	Severity:	SIR4,	H1-1
	the	stops deliv-	all functionali-	charged	of best charging	10	SIR2	
	various	ering power	ties	2.Battery fails	practices to avoid	Occurrence		
	compo-	to the device		and stops holding	battery failure i.e	Likeli-		
	nents			charge	(only charge to	hood: 3		
	of the			3.Battery gets	80%, don't leave	Detection		
	device			disconnected from	it plugged in when	Likeli-		
				the controller	battery is full etc.)	hood: 1		
					2.Microcontroller	Total: 30		
					should throw error			
					code if it detects			
					battery disconnec-			
					tion			
					3.Have CMOS			
					battery in the Mic-			
					ocontroller incase of			
					power loss			
		Battery	1.Devices may	1.Battery Failure	1.Hardware should	Total: 32	SIR2	H1-2
		supplies	lose some func-	2.Low charge in	be able to cut off the			
		incorrect	tionality or	the battery	battery in case of			
		power	may work in-	3.Issue in the bat-	excess current draw			
		_	correctly. The	tery management	2.Microcontroller			
			internal com-	system (BMS)	can signal the user			
			ponents may		in case of low bat-			
			get damaged		tery			

System: We								
Phase/Mode		tequirements						
Sub-	Design	Failure	Effects of	Causes of Fail-	Recommended	Risk	Safety	Ref
System	Func-	Mode	Failure	ure	Actions	Priority	Re-	
	${f tion}$					Number	quire-	
						(RPN)	ment	
Battery	Power	Battery	1.Device con-	1.Device operates	1.Insure proper cool-	Total: 40	SIR3	H1-3
	the	overheats	tainer can melt	in temperatures	ing or heat dissipa-			
	various		2.Battery can	outside the oper-	tion of the microcon-			
	compo-		melt other	ating conditions	troller			
	nents		components of	of the battery	2.Refer to H1-2 a			
	of the		wearable device	2.Battery failure	3.Install a battery			
	device		3.Burn the user	3.Excessive cur-	that can operate in			
			4.Damage fu-	rent draw	the working condi-			
			ture battery	4.Loose connec-	tions of the device			
			performance	tions	4.refer to H1-1 b.			
Microphone		Sound is not	1. Device is not	1.Loose connec-	1.Microcontroller	Total: 30	IR6	H2-1
	detec-	detected	able to perform	tions	can throw an error			
	tion		the primary	2.Microphone is	code in case of mi-			
			function Device	damaged	crophone disconnect			
			is unable to rec-		2.User can check the			
			ognize sounds		microphone output			
					on the app to see			
					if it is functioning			
					correctly			
		Sound is	1.Device func-	1.Loose connec-	1.Refer to H2-1.b	Total: 80	IR6	H2-2
		falsely de-	tions incor-	tions				
		tected	rectly	2.Microphone is				
				damaged				

System: Wearable Device

Phase/Mode: System Requirements

		Requirements	De t	C C D 11	D 1.1	D. I	G C .	D.C
Sub-	Design	Failure	Effects of	Causes of Fail-	Recommended	Risk	Safety	Ref
System	Func-	Mode	Failure	ure	Actions	Priority	Re-	
	tion					Number	quire-	
						(RPN)	ment	
Bluetooth	Provide	Mobile de-	1.Sound pro-	1.Signal between	1.Provide a notifi-	Total: 20	NFR-8	H3-1
Module	a com-	vice loses	cessing capabil-	mobile phone and	cation to the user			
	muni-	connec-	ities are lost	device is lost due	when the signal			
	cation	tion with	2.Vibration	to higher than	strength is dimin-			
	stream	bluetooth	motor wont	rated distances	ished			
	between	module	receive signal	2. Signal is blocked	2.Include auto-			
	mobile		to provide/not	due to external	reconnection with			
	phone		provide haptic	factors such as a	the device and			
	and		feedback	faraday cage	phone when signal			
	wear-			3.Other signals	is found			
	able			such as wifi,	3.Ensure final design			
	device			microwave etc.	of the product has			
				cause interference	adequate clearing			
				with bluetooth	for the bluetooth			
				signal	antennas such that			
				4.Connected	it maximizes signal			
				phone loses power	strength			
		Invalid mes-	1.Unexpected	1.Message cor-	1.Add a checksum	Total: 15	IR7	H3-2
		sage	or incorrect	rupted during	into the bluetooth			
			output from	transmission	signal to check for			
			device	2.Message cor-	message integrity			
				rupted during	2.Only accept prede-			
				reception	fined messages, dis-			
					card foreign/ unde-			
					fined messages			

System: Wearable Device Phase/Mode: System Requirements Sub-Design Failure Effects Causes of Fail-Recommended Risk Safety Ref Failure System Func-Mode ure Actions Priority Retion Number quire-(RPN) ment 1.User does not Vibration Provide Vibrations 1.Not 1.User can calibrate Total: 7 ACR1 H4-1 enough Motor haptic not noticeget alerted power supplied the intensity of the able by user notificamotor tion to user Motor does 1.User does not 1.Loose connec-1.Microcontroller Total: 20 SIR4 H4-2 can signal the user not vibrate get alerted tions 2.Defective vibrain case of motor tion motor disconnect 2.Refer to H4-2 1.User can calibrate SIR4 Incorrect vi-1.User incor-1.Defective vibra-Total: 18 H4-3 bration rectly identifies tion motor the vibration intensity and check the the sound output 1.Motor drawing Vibration 1.Painful or an-1.Refer to H4-3 Total: 8 ACR1 H4-4 too intense noying to the excess current 2.Hardware connecuser tion is current limited

Table 2: Application Failure Modes and Effects Analysis

Phase/Mode			DC / C	0 (1)	D 1.1	D' I	G C t	D.C
Sub- System	Design Func- tion	Failure Mode	Effects of Failure	Causes of Failure	Recommended Actions	Risk Priority Number (RPN)	Safety Re- quire- ment	Ref
Signal Processing	Classify sound	Sound is incorrectly classified	1.Incorrectly notify user about sound 2.No noti- fication for detected sound	1.Insufficient training data 2.Model param- eters not fully optimized 3.Outlier sound received	1.user can help with calibration by adding more samples 2.Filter outlier noise	Total: 168	ACR2, IR6	S1-1
		Sound is not classified	1.No noti- fication for detected sound	1.Error/bug with signal processing code	1.Refer to S1-1.a	Total: 105	IR6	S1-2
Graphical User In- terface	Give visual rep- resen- tation of the applica- tion to the end user	Incompatibility between different mobile devices	y 1.Formatting errors when resizing 2.Unable to download ap- plication 3.Loss of func- tionality or crashing	1.Button hit box detection may be lost/compromised 2.Mobile OS may not support application 3.Processing power of phone may be too inadequate for required signal processing 4.Mobile phone may not support bluetooth connec-	1.Provide end users with a list of certified compatible devices 2.Code/Style the application such that resizing is done automatically as the application detects screen size 3.Update the application on a regular basis to ensure compatibility with latest releases of the OS	Total: 20	NFR-7	S2-1

System: Mobile Application Phase/Mode: System Requirements Sub-Design Failure Effects of Causes of Fail-Recommended Risk Safety Ref System Func-Mode Failure ure Actions **Priority** Re-Number tion quire-(RPN) ment Graphical Give Combination 1.Loss of saved 1.User chooses in-1.System should Total: 48 ACR3 S2-2 User Invisual of user indata correct bluetooth recognize invalid terface 2.Abrupt inputs from users repputs device to connect crashing of the and provide helpful resento 2.User force closes tation application error messages of $_{
m the}$ application before 2. Application should applicaapplying changes provide warning tion to when entries are the end not saved before allowing a force user close. Warnings should require user confirmation before allowing the event Abnormal S3-3 1.Loss of saved 1.User 1.Communication Total: 40 IR3 closes closing ofdata application while protocol between application data is the device and the 2.Incorrect being communication transferred application should 2.System preempof data have error handling tively forces the in case of errors in application data transmission

close

6 Safety and Security Requirements

Bold statements are an extension of the SRS document safety requirements which should have been included in revision 1.

6.1 System Isolation Requirements

- SIR1. Product is isolated from electrical components at contact locations. Using wire isolation material
- SIR2. Auto shut-off when electrical malfunction detected.
- SIR3. Product has sufficient heat dissipation such that all the electrical components stay in their working temperatures.

SIR4. System can perform a hard reboot to reset all hardware components. The built in temperature control system within the Arduino

6.2 Access Requirements

- ACR1. Authorized users can access preferred vibration/sensitivity settings through application site.
- ACR2. Authorized users can retrain the device through application site.
- ACR3. Users given error message if invalid inputs are entered in application.

6.3 Integrity Requirements

- IR1. Only required variables will be given access to change.
- IR2. Data will be accessible by authorized users. IR3 After synchronization, a copy of data is loaded to system application. IR3. After synchronization, a copy of the Arduino signal data is loaded to system application.
- IR4. No pairs of modes allowed identical settings.
- IR5. Stored data overridden only at synchronization request.
- IR6. Application can detect if there is an issue with the microphone.
- IR7. Unknown messages from Bluetooth module prompt an error to the user and are rejected.

6.4 Privacy Requirements

- PPR1. Personalized access code will be created for user application accessibility.
- PRR2. Data is not transferable between accounts.

7 Roadmap

The requirements implemented according to the hardware research milestone created in the development plan are as listed, system isolation requirements and privacy requirements. With access requirements, integrity requirements and privacy requirements being researched in the future development plan.