

Hazard Analysis

SE 4G06, TRON 4TB6

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Table 1: Revision History

Date	Developer(s)	Change
10/14/22	Azriel G.	Added sections 1, 2, and 3
Date2	Name(s)	Description of changes
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1 Introduction

This document is the hazard analysis for the entirety of Synesthesia Wear. For context, Synesthesia Wear is an inexpensive and non-intrusive hearing aid bracelet with a purpose of improving quality of life by providing users with an alternate channel for sound recognition within their surroundings. Furthermore, this bracelet will have a corresponding application that will be made to be user-friendly so that users can easily access and configure their bracelets to whatever settings they so desire. Lastly, for the purposes of this document, the Synesthesia Wear developers believe that the definition of a hazard is one that is derived from Nancy Leveson's work. With that in mind, a hazard is any property or condition within the Synesthesia Wear system where after pairing up with any conditions in the environment, a potential for loss to the system now exists.

2 Scope and Purpose of Hazard Analysis

The scope of this document is to identify any and all possible hazards within the system, clarify the mitigation steps of each identified hazard, determine the causes and effects of all failures, and define all safety and security requirements that have resulted from the overall analysis.

3 System Boundaries and Components

The hazard analysis will be conducted on the Synesthesia Wear system which will be comprised of the following components:

1. The Bracelet which also consists of:
 - (a) Vibration Motor
 - (b) Sound Sensor
 - (c) Microcontroller
2. The Application to be installed on the users' devices which consists of:
 - (a) User Interface
 - (b) Bracelet Settings Configuration
3. The Device that runs the application
 - (a) Operating System

With the above in mind, the system boundary is limited to the above 3 components with each having their own respective subcomponents. Furthermore, it is important to note that not all components in the above list can be controlled (i.e. Device's Operating System) by the Synesthesia Wear developers. However, these components still needed to be listed down in the system boundary as the potential for a hazard can still be correlated to them.

4 Critical Assumptions

[These assumptions that are made about the software or system. You should minimize the number of assumptions that remove potential hazards. For instance, you could assume a part will never fail, but it is generally better to include this potential failure mode. —SS]

5 Failure Mode and Effect Analysis

System: Wearable Device Phase/Mode: System Requirements									
Sub Sys-tem	Design Func-tion	Failure Mode	Effects of Failure	Causes of Failure	Recommended actions	RPN	SR	Ref.	
Battery	Power the various components of the device	Battery stops delivering power to the device	Device loses all functionalities	<ol style="list-style-type: none"> 1. Battery was not charged. 2. Battery fails and stops holding charge. 3. Battery gets disconnected from the controller 	<ol style="list-style-type: none"> 1. Inform users of best-charging practices to avoid battery failure i.e (only charge to 80%, don't leave it plugged in when the battery is full, etc.) 2. The microcontroller should throw an error code if it detects battery disconnection 3. Have a CMOS battery in the Microcontroller in case of power loss 			H1-1	
		Battery supplies incorrect power	Devices may lose some functionality or may work in a low power mode. The internal components may get damaged.	<ul style="list-style-type: none"> • Battery failure • Low charge in the battery 	<ul style="list-style-type: none"> - Hardware should be able to cut off the battery in case of excess current - Microcontroller can signal the user in case of low battery. 			H1-2	
		Battery overheats	-Device contains a battery management system (BMS) to monitor the battery temperature and prevent overheating conditions. -Battery can melt other components of wearable device -Burn the user -Damage future battery performance	<ul style="list-style-type: none"> • Device operates in temperatures outside the working conditions of the battery • Battery failure 	<ul style="list-style-type: none"> - Refer to H1-2 a. - Install a battery that can operate in the working conditions of the device - refer to H1-1 b. 			H1-3	
Microphone	Sound detection	Sound is not detected	-Device is not able to perform the primary function	<ul style="list-style-type: none"> • Excessive current draw • Microphone is damaged 	<ul style="list-style-type: none"> • Microcontroller can throw an error code in case of microphone disconnection • User can check the microphone output on the app to see if it is functional 			H2-1	
		Sound is falsely detected	-Device functions incorrectly	<ul style="list-style-type: none"> • Loose connections • Microphone is damaged 	<ul style="list-style-type: none"> • Refer to H2-1 b. 			H2-2	

Bluetooth Module	Provide a communication stream between mobile phone and wearable device.	<ul style="list-style-type: none"> - Mobile device loses connection with bluetooth module 	<ul style="list-style-type: none"> - Sound processing capabilities are mobile phone and other devices signal to provide a notification to the user. - Vibration motor is not working properly. - Other signals such as wifi, microwave, etc. are not received by the device. 	<ul style="list-style-type: none"> - Device is not notified about the high or low battery level. - Microcontroller is not able to receive the signal from the device and phone when signal is not received. - Ensure that the signal is not blocked by the device. 	H3-1	
		<ul style="list-style-type: none"> - Invalid message 	<ul style="list-style-type: none"> - Unexpected or incorrect output from device 	<ul style="list-style-type: none"> - Message corrupted during transmission - Message corrupted during reception 	<ul style="list-style-type: none"> - Add a checksum into the bluetooth signal to check for message integrity. - Only accept predefined messages, discard foreign/ undefined messages. 	H3-2
Vibration Module	Provide haptic notification to user.	Motor does not vibrate	<ul style="list-style-type: none"> - User does not get notified 	<ul style="list-style-type: none"> - loose connections - defective vibration motor 	<ul style="list-style-type: none"> - Microcontroller can signal the user in case of motor failure. - Refer to H4-2. 	H4-1
		Incorrect vibration	<ul style="list-style-type: none"> - User incorrectly identifies the sound 	<ul style="list-style-type: none"> - defective vibration motor 	<ul style="list-style-type: none"> - User can calibrate the vibration intensity and check the output 	H4-3
		Vibration too intense	<ul style="list-style-type: none"> - Painful or annoying to the user 	<ul style="list-style-type: none"> - Motor drawing excess current 	<ul style="list-style-type: none"> - Refer to H4-3. - Hardware connection is current limited. 	H4-4

[Include your FMEA table here —SS]

6 Safety and Security Requirements

[Newly discovered requirements. These should also be added to the SRS. (A rationale design process how and why to fake it.) —SS]

7 Roadmap

[Which safety requirements will be implemented as part of the capstone timeline? Which requirements will be implemented in the future? —SS]