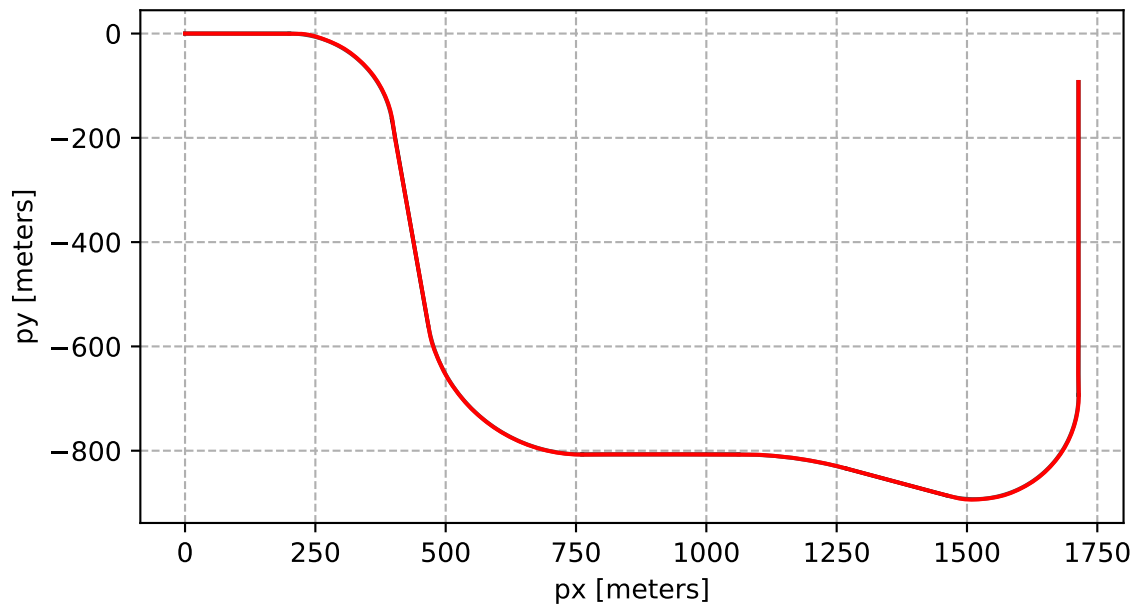


Showing the road and the (px,py) trajectory



— road — trajectory of vehicle