

## MATH 437 Homework 4 (20 points)

1. (5 points) Use the Adams-Bashforth four-step method to solve

$$\frac{dy}{dt} = te^{3t} - 2y$$

on the interval  $0 \leq t \leq 1$  with initial condition  $y(0) = 0$ . Use step size  $h = 0.2$  and starting values based on the exact solution

$$y(t) = \frac{t}{5}e^{3t} - \frac{1}{25}e^{3t} + \frac{1}{25}e^{-2t}.$$

Output the discrete solution  $y_n$  at each timestep  $t_n$ .

*Hint.* See `problem_1.py` in the `code-templates`. □

2. (5 points) Derive the Adams-Moulton two-step implicit method by using the appropriate form of an interpolating polynomial.

*Hint.* Multi-step methods to solve problems of the form

$$y'(t) = f(t, y(t))$$

start by integrating both sides from  $t_n$  to  $t_{n+1}$ :

$$y(t_{n+1}) - y(t_n) = \int_{t_n}^{t_{n+1}} f(t, y(t)) dt.$$

Now, the idea is to replace the function  $\phi(t) := f(t, y(t))$  by a Lagrange polynomial based on the discrete time points  $t_n$ . For the Adams-Moulton 2-step method, the points used are  $t_{n-1}$ ,  $t_n$ , and  $t_{n+1}$ . To simplify the computations, assume that  $t_n - t_{n-1} = t_{n+1} - t_n = h$ . Let  $L_{n-1}$ ,  $L_n$ , and  $L_{n+1}$  be the Lagrange polynomials interpolating  $\phi(t)$  at the points  $t_{n-1}$ ,  $t_n$ , and  $t_{n+1}$ . To compute the integrals of these polynomials, it's useful to make a change of variables  $t \mapsto s = (t - t_{n-1})/(t_n - t_{n-1})$  and then integrate with respect to  $s$  from 0 to 1. □

3. (5 points) Investigate the stability of the difference method

$$w_{i+1} = w_i + hf(t_i, w_i) + h^2 f(t_{i-1}, w_{i-1}).$$

Assume that  $f$  satisfies a Lipschitz condition on  $\{(t, w) \mid a \leq t \leq b \text{ and } -\infty < w < \infty\}$  in the variable  $w$  with constant  $L > 0$ , and assume that  $f$  is continuous in  $t$ . See section 5.10 in the textbook. In particular, see the discussion on multi-step methods. Also, see Lecture 10 in the class notes.

*Hint.* For stability of this multi-step method, rewrite the equation in the form

$$w_{i+1} = w_i + hF(h, t_i, w_i, w_{i-1}).$$

Then, to investigate the stability of this method, we verify the following:

- (a) If  $f = 0$ , then  $F = 0$ .
- (b)  $F$  satisfies a Lipschitz condition in  $w_i$  and  $w_{i-1}$ : there is a constant  $C > 0$  such that

$$|F(h, t_i, w_i, w_{i-1}) - F(h, t_i, z_i, z_{i-1})| \leq C(|w_i - z_i| + |w_{i-1} - z_{i-1}|).$$

- (c) Determine the characteristic polynomial  $p(\lambda)$  of the method, and check its roots. See Definitions 5.22 and 5.23 in the book.

If the first 2 conditions are not satisfied, the method is unstable. If the first 2 conditions are satisfied, then check Definitions 5.22 and 5.23 to determine if the method is unstable, weakly stable, or strongly stable.  $\square$

4. (5 points) Solve the following stiff differential equation

$$y' = -20y + 21e^t$$

on the interval  $0 \leq t \leq 1$  with initial condition  $y(0) = 2$ . Use the explicit Euler and implicit Euler methods step sizes  $h = 0.1$  and  $h = 0.01$ . Turn in plots of the solutions and the exact solution  $y(t) = e^t + e^{-20t}$ .

*Hint.* See `problem_4.py` in the `code-templates`.  $\square$