1 Numerical Method Break Down

Our conservative update is, for our equations is

$$\bar{q}_j^{n+1} = \bar{q}_j^n - \frac{\Delta t}{\Delta x} \left[F_{j+\frac{1}{2}} - F_{j-\frac{1}{2}} \right]$$

This converts to (both analytical and numerical)

$$\mathcal{M}q_j^{n+1} = \mathcal{M}q_j^n - \frac{\Delta t}{\Delta x} \left[\mathcal{F}^{q,v} v_j + \mathcal{F}^{q,q} q_j - \mathcal{F}^{q,v} v_{j-1} - \mathcal{F}^{q,q} q_{j-1} \right]$$

$$\mathcal{M}q_j^{n+1} = \mathcal{M}q_j^n - \frac{\Delta t}{\Delta x} \left[\mathcal{F}^{q,v}v_j + \mathcal{F}^{q,q}q_j - \mathcal{F}^{q,v}e^{-ik\Delta x}v_j - \mathcal{F}^{q,q}e^{-ik\Delta x}q_j \right]$$

Defining $\mathcal{D}_x = 1 - e^{-ik\Delta x}$

$$\mathcal{M}q_j^{n+1} = \mathcal{M}q_j^n - \frac{\Delta t}{\Delta x} \left[\mathcal{D}_x \mathcal{F}^{q,v} v_j + \mathcal{D}_x \mathcal{F}^{q,q} q_j \right]$$

So we have

$$q_j^{n+1} = q_j^n - \frac{\mathcal{D}_x \Delta t}{\mathcal{M} \Delta x} \left[\mathcal{F}^{q,v} v_j + \mathcal{F}^{q,q} q_j \right]$$

Thus we have

$$\begin{bmatrix} h \\ \mathcal{G}u \end{bmatrix}_{j}^{n+1} = \begin{bmatrix} h \\ \mathcal{G}u \end{bmatrix}_{j}^{n} - \frac{\mathcal{D}_{x}\Delta t}{\mathcal{M}\Delta x} \begin{bmatrix} \mathcal{F}^{h,h} & \mathcal{F}^{h,u} \\ \mathcal{F}^{u,h} & \mathcal{F}^{u,u} \end{bmatrix} \begin{bmatrix} h \\ u \end{bmatrix}_{j}^{n}$$
$$\begin{bmatrix} h \\ u \end{bmatrix}_{j}^{n+1} = \begin{bmatrix} h \\ u \end{bmatrix}_{j}^{n} - \frac{\mathcal{D}_{x}\Delta t}{\mathcal{M}\Delta x} \begin{bmatrix} \mathcal{F}^{h,h} & \mathcal{F}^{h,u} \\ \frac{1}{\mathcal{G}}\mathcal{F}^{u,h} & \frac{1}{\mathcal{G}}\mathcal{F}^{u,u} \end{bmatrix} \begin{bmatrix} h \\ u \end{bmatrix}_{j}^{n}$$

Lets define

$$\mathbf{F} = \frac{\mathcal{D}_x}{\mathcal{M}\Delta x} \begin{bmatrix} \mathcal{F}^{h,h} & \mathcal{F}^{h,u} \\ \frac{1}{\mathcal{G}}\mathcal{F}^{u,h} & \frac{1}{\mathcal{G}}\mathcal{F}^{u,u} \end{bmatrix}$$
$$\begin{bmatrix} h \\ u \end{bmatrix}_i^{n+1} = \begin{bmatrix} h \\ u \end{bmatrix}_i^n - \Delta t \mathbf{F} \begin{bmatrix} h \\ u \end{bmatrix}_i^n$$

$$\begin{bmatrix} h \\ u \end{bmatrix}_{i}^{n+1} = (\mathbf{I} - \Delta t \mathbf{F}) \begin{bmatrix} h \\ u \end{bmatrix}_{i}^{n}$$

Thats our Euler Step, the difference between this and the previous version is we didn't divide that bottom Row by \mathcal{G} So we have to change our approximation stuff. Also we would like the know what the analytic value of \mathbf{F} is and approximations to it.

1.1 Analytic

$$\frac{\mathcal{D}_a}{\Delta x \mathcal{M}_a} \mathcal{F}_a^{h,u} = ikH$$

$$\frac{\mathcal{D}_a}{\Delta x \mathcal{M}_a} \mathcal{F}_a^{h,h} = 0$$

$$\frac{\mathcal{D}_a}{\mathcal{G}_a \Delta x \mathcal{M}_a} \mathcal{F}_a^{u,h} = \frac{ikgH}{H + \frac{H^3}{3}k^2} = i\frac{k}{H}gH\frac{3}{3 + H^2k^2}$$
 using $\omega = \pm k\sqrt{gH}\sqrt{\frac{3}{H^2k^2+3}}$, $\omega^2 = k^2gH\frac{3}{H^2k^2+3}$
$$\frac{\mathcal{D}_a}{\mathcal{G}\Delta x \mathcal{M}_a} \mathcal{F}_a^{u,h} = i\frac{k}{H}\frac{\omega^2}{k^2} = -i\frac{\omega^2}{kH}$$

$$\frac{\mathcal{D}_a}{\mathcal{G}\Delta x \mathcal{M}_a} \mathcal{F}_a^{u,u} = 0$$

So we have

$$m{F} = \left[egin{array}{cc} 0 & ikH \ rac{\omega^2}{ikH} & 0 \end{array}
ight] = rac{1}{ikH} \left[egin{array}{cc} 0 & -k^2H^2 \ \omega^2 & 0 \end{array}
ight]$$

We can diagonalise this $(A = PDP^{-1})$ with the following matricers

$$\mathbf{F} = \frac{1}{ikH} \begin{bmatrix} -\frac{ikH}{\omega} & \frac{ikH}{\omega} \\ 1 & 1 \end{bmatrix} \begin{bmatrix} -ikH\omega & 0 \\ 0 & ikH\omega \end{bmatrix} \begin{bmatrix} -\frac{ikH}{\omega} & \frac{ikH}{\omega} \\ 1 & 1 \end{bmatrix}^{-1}$$

$$\mathbf{F} = \begin{bmatrix} -\frac{ikH}{\omega} & \frac{ikH}{\omega} \\ 1 & 1 \end{bmatrix} \begin{bmatrix} -\omega & 0 \\ 0 & \omega \end{bmatrix} \begin{bmatrix} -\frac{ikH}{\omega} & \frac{ikH}{\omega} \\ 1 & 1 \end{bmatrix}^{-1}$$

We will use the following notation

$$m{W}_a = \left[egin{array}{cc} -\omega & 0 \ 0 & \omega \end{array}
ight] \ m{S}_a = \left[egin{array}{cc} -rac{ikH}{\omega} & rac{ikH}{\omega} \ 1 & 1 \end{array}
ight]$$

So we have

$$\boldsymbol{F}_a = \boldsymbol{S}_a \boldsymbol{W}_a \boldsymbol{S}_a^{-1}$$

1.2 First Order

$$\frac{\mathcal{D}}{\Delta x \mathcal{M}_1} \mathcal{F}_1^{h,u} = iHk - \frac{iHk^3}{6} (\Delta x)^2 + O(\Delta x^3)$$
$$\frac{\mathcal{D}}{\Delta x \mathcal{M}_1} \mathcal{F}_1^{h,h} = \frac{k^2 \sqrt{gH}}{2} \Delta x + O(\Delta x^2)$$

$$\frac{\mathcal{D}}{\mathcal{G}_{1}\Delta x \mathcal{M}_{1}} \mathcal{F}_{1}^{u,h} = \frac{gH}{2} \frac{1 - e^{-ik\Delta x}}{\Delta x} \left(1 + e^{ik\Delta x}\right) \left[H - \frac{H^{3}}{3} \left(\frac{2\cos\left(k\Delta x\right) - 2}{\Delta x^{2}}\right)\right]^{-1}$$

$$\frac{\mathcal{D}}{\mathcal{G}_{1}\Delta x \mathcal{M}_{1}} \mathcal{F}_{1}^{u,h} = \frac{3igk}{H^{2}k^{2} + 3} - \frac{igk^{3}(H^{2}k^{2} + 6)}{4(H^{2}k^{2} + 3)^{2}} \Delta x^{2} + O(\Delta x^{3})$$

$$\frac{\mathcal{D}}{\mathcal{G}_{1}\Delta x \mathcal{M}_{1}} \mathcal{F}_{1}^{u,u} = -\frac{\sqrt{gH}}{2} \frac{1 - e^{-ik\Delta x}}{\Delta x} \left[e^{ik\Delta x} - 1\right]$$

$$\frac{\mathcal{D}}{\mathcal{G}_{1}\Delta x \mathcal{M}_{1}} \mathcal{F}_{1}^{u,u} = \frac{1}{2}k^{2}\sqrt{gH}\Delta x + O(\Delta x^{2})$$

So

$$\boldsymbol{F} = \begin{bmatrix} \frac{k^2 \sqrt{gH}}{2} \Delta x + O(\Delta x^2) & iHk - \frac{iHk^3}{6} (\Delta x)^2 + O(\Delta x^3) \\ \frac{3igk}{H^2k^2 + 3} - \frac{igk^3 (H^2k^2 + 6)}{4(H^2k^2 + 3)^2} \Delta x^2 + O(\Delta x^3) & \frac{1}{2}k^2 \sqrt{gH} \Delta x + O(\Delta x^2) \end{bmatrix}$$

$$\mathbf{F} = \begin{bmatrix} \frac{k^2 \sqrt{gH}}{2} \Delta x + O(\Delta x^2) & iHk - \frac{iHk^3}{6} (\Delta x)^2 + O(\Delta x^3) \\ i\frac{\omega^2}{Hk} - i\frac{\omega^2}{4kH} \frac{(H^2k^2 + 6)}{(H^2k^2 + 3)} \Delta x^2 + O(\Delta x^3) & \frac{1}{2}k^2 \sqrt{gH} \Delta x + O(\Delta x^2) \end{bmatrix}$$

$$\mathbf{F} = \begin{bmatrix} \frac{k^2 \sqrt{gH}}{2} \Delta x + O(\Delta x^2) & iHk - \frac{iHk^3}{6} (\Delta x)^2 + O(\Delta x^3) \\ i\frac{\omega^2}{Hk} - i\frac{\omega^2}{4kH} \left[1 + \frac{3}{H^2k^2 + 3} \right] \Delta x^2 + O(\Delta x^3) & \frac{1}{2} k^2 \sqrt{gH} \Delta x + O(\Delta x^2) \end{bmatrix}$$

$$\boldsymbol{F} = \begin{bmatrix} \frac{k^2 \sqrt{gH}}{2} \Delta x + O(\Delta x^2) & iHk - \frac{iHk^3}{6} (\Delta x)^2 + O(\Delta x^3) \\ i\frac{\omega^2}{Hk} - i\frac{\omega^2}{4kH} \left[1 + \frac{\omega^2}{k^2gH} \right] \Delta x^2 + O(\Delta x^3) & \frac{1}{2}k^2 \sqrt{gH} \Delta x + O(\Delta x^2) \end{bmatrix}$$

$$\boldsymbol{F} = \begin{bmatrix} \frac{k^2 \sqrt{gH}}{2} \Delta x & iHk - \frac{iHk^3}{6} (\Delta x)^2 \\ i\frac{\omega^2}{Hk} - i\frac{\omega^2}{4kH} \left[1 + \frac{\omega^2}{k^2 gH} \right] \Delta x^2 & \frac{k^2 \sqrt{gH}}{2} \Delta x \end{bmatrix} + O(\Delta x^2)$$

$$\boldsymbol{F} = \begin{bmatrix} \frac{k^2 \sqrt{gH}}{2} \Delta x & iHk - \frac{iHk^3}{6} (\Delta x)^2 \\ i\frac{\omega^2}{Hk} - i\frac{\omega^2}{4kH} \left[1 + \frac{\omega^2}{k^2 gH} \right] \Delta x^2 & \frac{k^2 \sqrt{gH}}{2} \Delta x \end{bmatrix} + O(\Delta x^2)$$

$$\mathbf{F} = \begin{bmatrix} \frac{k^2 \sqrt{gH}}{2} \Delta x & iHk \\ i\frac{\omega^2}{Hk} & \frac{k^2 \sqrt{gH}}{2} \Delta x \end{bmatrix} + O(\Delta x^2)$$

We neglect the $O(\Delta x^2)$ terms and get

$$\boldsymbol{F}_1 = \begin{bmatrix} \frac{k^2 \sqrt{gH}}{2} \Delta x & iHk \\ i\frac{\omega^2}{Hk} & \frac{k^2 \sqrt{gH}}{2} \Delta x \end{bmatrix}$$

which has the following eigenvalues

$$\lambda_{1,\pm} = \frac{\pm 2ikH\omega + Hk^3\sqrt{gH}\Delta x}{2Hk}$$

So

$$oldsymbol{F}_1 = oldsymbol{S}_1 \left[egin{array}{cc} \lambda_{1,-} & 0 \ 0 & \lambda_{1,+} \end{array}
ight] oldsymbol{S}_1^{-1}$$

$$\begin{bmatrix} h \\ u \end{bmatrix}_{j}^{n+1} = \left(\mathbf{I} - \Delta t \mathbf{S}_{1} \begin{bmatrix} \lambda_{1,-} & 0 \\ 0 & \lambda_{1,+} \end{bmatrix} \mathbf{S}_{1}^{-1} \right) \begin{bmatrix} h \\ u \end{bmatrix}_{j}^{n}$$

$$\mathbf{S}_{1}^{-1} \left(\begin{bmatrix} h \\ u \end{bmatrix}_{j}^{n+1} \right) = \left(\mathbf{S}_{1}^{-1} - \Delta t \begin{bmatrix} \lambda_{1,-} & 0 \\ 0 & \lambda_{1,+} \end{bmatrix} \mathbf{S}_{1}^{-1} \right) \begin{bmatrix} h \\ u \end{bmatrix}_{j}^{n}$$

$$\mathbf{S}_{1}^{-1} \mathcal{D}^{t} \left(\begin{bmatrix} h \\ u \end{bmatrix}_{j}^{n} \right) = -\Delta t \begin{bmatrix} \lambda_{1,-} & 0 \\ 0 & \lambda_{1,+} \end{bmatrix} \mathbf{S}_{1}^{-1} \begin{bmatrix} h \\ u \end{bmatrix}_{j}^{n}$$

$$\frac{\mathcal{D}^{t}}{\Delta t} \left(\mathbf{S}_{1}^{-1} \begin{bmatrix} h \\ u \end{bmatrix}_{j}^{n} \right) = -\begin{bmatrix} \lambda_{1,-} & 0 \\ 0 & \lambda_{1,+} \end{bmatrix} \left(\mathbf{S}_{1}^{-1} \begin{bmatrix} h \\ u \end{bmatrix}_{j}^{n} \right)$$
so
$$\frac{\mathcal{D}^{t}}{\Delta t} = -\lambda_{1,\pm}$$
So
$$\frac{\mathcal{D}^{t}}{\Delta t} = -\frac{\pm 2ikH\omega + Hk^{3}\sqrt{gH}\Delta x}{2Hk}$$

$$\frac{\mathcal{D}^{t}}{\Delta t} = -(\pm i\omega + \frac{1}{2}k^{2}\sqrt{gH}\Delta x)$$

$$\frac{\mathcal{D}^{t}}{\Delta t} = \mp i\omega - \frac{1}{2}k^{2}\sqrt{gH}\Delta x$$

$$\frac{\mathcal{D}^{t}}{\Delta t} + \frac{1}{2}k^{2}\sqrt{gH}\Delta x = \mp i\omega$$

$$\pm i \left(\frac{\mathcal{D}^{t}}{\Delta t} + \frac{1}{2}k^{2}\sqrt{gH}\Delta x \right) = \omega$$

Can we do it with full analytic values? Ok our matrix is the following

$$\frac{\mathcal{D}}{\Delta x \mathcal{M}_1} \mathcal{F}_1^{h,u} = \frac{1 - e^{-ik\Delta x}}{\Delta x} H \frac{e^{ik\Delta x} + 1}{2}$$
$$\frac{\mathcal{D}}{\Delta x \mathcal{M}_1} \mathcal{F}_1^{h,h} = -\frac{\sqrt{gH}}{2} \frac{1 - e^{-ik\Delta x}}{\Delta x} \left[e^{ik\Delta x} - 1 \right]$$

$$\frac{\mathcal{D}}{\Delta x \mathcal{G}_1 \mathcal{M}_1} \mathcal{F}_1^{u,h} = \frac{gH}{2} \frac{1 - e^{-ik\Delta x}}{\Delta x} \left(1 + e^{ik\Delta x} \right) \left[H - \frac{H^3}{3} \left(\frac{2\cos(k\Delta x) - 2}{\Delta x^2} \right) \right]^{-1}$$

$$\frac{\mathcal{D}}{\mathcal{G}_1 \Delta x \mathcal{M}_1} \mathcal{F}_1^{u,u} = -\frac{\sqrt{gH}}{2} \frac{1 - e^{-ik\Delta x}}{\Delta x} \left[e^{ik\Delta x} - 1 \right]$$

$$\boldsymbol{F} = \frac{1 - e^{-ik\Delta x}}{\Delta x} \left[\begin{array}{c} -\frac{\sqrt{gH}}{2} \left[e^{ik\Delta x} - 1 \right] & H\frac{e^{ik\Delta x} + 1}{2} \\ \frac{g}{2} \left(1 + e^{ik\Delta x} \right) \left[1 - \frac{H^2}{3} \left(\frac{2\cos(k\Delta x) - 2}{\Delta x^2} \right) \right]^{-1} & -\frac{\sqrt{gH}}{2} \left[e^{ik\Delta x} - 1 \right] \end{array} \right]$$

1.3 Second Order

$$\begin{bmatrix} h \\ u \end{bmatrix}_{j}^{1} = (\mathbf{I} - \Delta t \mathbf{F}) \begin{bmatrix} h \\ u \end{bmatrix}_{j}^{n}$$

$$\begin{bmatrix} h \\ u \end{bmatrix}_{j}^{2} = (\mathbf{I} - \Delta t \mathbf{F}) \begin{bmatrix} h \\ u \end{bmatrix}_{j}^{1}$$

$$\begin{bmatrix} h \\ u \end{bmatrix}_{j}^{n+1} = \frac{1}{2} \left(\begin{bmatrix} h \\ u \end{bmatrix}_{j}^{n} + \begin{bmatrix} h \\ u \end{bmatrix}_{j}^{2} \right)$$

$$\begin{bmatrix} h \\ u \end{bmatrix}_{j}^{n+1} = \frac{1}{2} \left(\begin{bmatrix} h \\ u \end{bmatrix}_{j}^{n} + (\mathbf{I} - \Delta t \mathbf{F})^{2} \begin{bmatrix} h \\ u \end{bmatrix}_{j}^{n} \right)$$

$$\begin{bmatrix} h \\ u \end{bmatrix}_{j}^{n+1} = \frac{1}{2} \left(\mathbf{I} + (\mathbf{I} - \Delta t \mathbf{F})^{2} \right) \begin{bmatrix} h \\ u \end{bmatrix}_{j}^{n}$$

$$\begin{bmatrix} h \\ u \end{bmatrix}_{j}^{n+1} = \frac{1}{2} \left(\mathbf{I} + \mathbf{I} - 2\Delta t \mathbf{F} + \Delta t^{2} \mathbf{F}^{2} \right) \begin{bmatrix} h \\ u \end{bmatrix}_{j}^{n}$$

$$\begin{bmatrix} h \\ u \end{bmatrix}_{j}^{n+1} = \frac{1}{2} \left(2\mathbf{I} - 2\Delta t \mathbf{F} + \Delta t^{2} \mathbf{F}^{2} \right) \begin{bmatrix} h \\ u \end{bmatrix}_{j}^{n}$$

lets say we have

$$oldsymbol{F}_2 = oldsymbol{S}_2 \left[egin{array}{cc} \lambda_{2,-} & 0 \ 0 & \lambda_{2,+} \end{array}
ight] oldsymbol{S}_2^{-1}$$

$$\begin{bmatrix} h \\ u \end{bmatrix}_{j}^{n+1} = \frac{1}{2} \left(2\boldsymbol{I} - 2\Delta t \boldsymbol{S}_{2} \begin{bmatrix} \lambda_{2,-} & 0 \\ 0 & \lambda_{2,+} \end{bmatrix} \boldsymbol{S}_{2}^{-1} + \Delta t^{2} \boldsymbol{S}_{2} \begin{bmatrix} \lambda_{2,-}^{2} & 0 \\ 0 & \lambda_{2,+}^{2} \end{bmatrix} \boldsymbol{S}_{2}^{-1} \right) \begin{bmatrix} h \\ u \end{bmatrix}_{j}^{n}$$

$$\boldsymbol{S}_{2}^{-1} \begin{bmatrix} h \\ u \end{bmatrix}_{j}^{n+1} = \frac{1}{2} \left(2\boldsymbol{S}_{2}^{-1} - 2\Delta t \begin{bmatrix} \lambda_{2,-} & 0 \\ 0 & \lambda_{2,+} \end{bmatrix} \boldsymbol{S}_{2}^{-1} + \Delta t^{2} \begin{bmatrix} \lambda_{2,-}^{2} & 0 \\ 0 & \lambda_{2,+}^{2} \end{bmatrix} \boldsymbol{S}_{2}^{-1} \right) \begin{bmatrix} h \\ u \end{bmatrix}_{j}^{n}$$

$$\boldsymbol{S}_{2}^{-1} \left[\begin{array}{c} h \\ u \end{array} \right]_{j}^{n+1} = \frac{1}{2} \left(2\boldsymbol{S}_{2}^{-1} + \left[\begin{array}{cc} \Delta t^{2}\lambda_{2,-}^{2} - 2\Delta t\lambda_{2,-} & 0 \\ 0 & \Delta t^{2}\lambda_{2,+}^{2} - 2\Delta t\lambda_{2,-} \end{array} \right] \boldsymbol{S}_{2}^{-1} \right) \left[\begin{array}{c} h \\ u \end{array} \right]_{j}^{n}$$

$$e^{i\omega\Delta t}\left(\boldsymbol{S}_{2}^{-1}\left[\begin{array}{c}h\\u\end{array}\right]_{j}^{n}\right)=\frac{1}{2}\left(2+\left[\begin{array}{cc}\Delta t^{2}\lambda_{2,-}^{2}-2\Delta t\lambda_{2,-}&0\\0&\Delta t^{2}\lambda_{2,+}^{2}-2\Delta t\lambda_{2,-}\end{array}\right]\right)\left(\boldsymbol{S}_{2}^{-1}\left[\begin{array}{c}h\\u\end{array}\right]_{j}^{n}\right)$$

$$e^{i\omega\Delta t} \left(\boldsymbol{S}_{2}^{-1} \begin{bmatrix} h \\ u \end{bmatrix}_{j}^{n} \right) = \frac{1}{2} \begin{bmatrix} 2 + \Delta t^{2} \lambda_{2,-}^{2} - 2\Delta t \lambda_{2,-} & 0 \\ 0 & 2 + \Delta t^{2} \lambda_{2,+}^{2} - 2\Delta t \lambda_{2,-} \end{bmatrix} \left(\boldsymbol{S}_{2}^{-1} \begin{bmatrix} h \\ u \end{bmatrix}_{j}^{n} \right)$$

So we have

$$e^{i\omega\Delta t} = 1 + \frac{1}{2}\Delta t^2 \lambda_{2,\pm}^2 - \Delta t \lambda_{2,\pm}$$

1.4 Third Order

$$\begin{bmatrix} h \\ u \end{bmatrix}^{1} = (\mathbf{I} - \Delta t \mathbf{F}_{3}) \begin{bmatrix} h \\ u \end{bmatrix}^{n}$$

$$\begin{bmatrix} h \\ u \end{bmatrix}^{2} = (\mathbf{I} - \Delta t \mathbf{F}_{3}) \begin{bmatrix} h \\ u \end{bmatrix}^{1}$$

$$\begin{bmatrix} h \\ u \end{bmatrix}^{3} = \frac{3}{4} \begin{bmatrix} h \\ u \end{bmatrix}^{n} + \frac{1}{4} \begin{bmatrix} h \\ u \end{bmatrix}^{2}$$

$$\begin{bmatrix} h \\ u \end{bmatrix}^{4} = (\mathbf{I} - \Delta t \mathbf{F}_{3}) \begin{bmatrix} h \\ u \end{bmatrix}^{3}$$

$$\begin{bmatrix} h \\ u \end{bmatrix}^{n+1} = \frac{1}{3} \begin{bmatrix} h \\ u \end{bmatrix}^{n} + \frac{2}{3} \begin{bmatrix} h \\ u \end{bmatrix}^{4}$$

$$\begin{bmatrix} h \\ u \end{bmatrix}^{3} = \frac{3}{4} \begin{bmatrix} h \\ u \end{bmatrix}^{n} + \frac{1}{4} (I - \Delta t F_{3})^{2} \begin{bmatrix} h \\ u \end{bmatrix}^{n}$$

$$\begin{bmatrix} h \\ u \end{bmatrix}^{3} = \left(\frac{3}{4} I + \frac{1}{4} (I - \Delta t F_{3})^{2}\right) \begin{bmatrix} h \\ u \end{bmatrix}^{n}$$

$$\begin{bmatrix} h \\ u \end{bmatrix}^{n+1} = \frac{1}{3} \begin{bmatrix} h \\ u \end{bmatrix}^{n} + \frac{2}{3} (I - \Delta t F_{3}) \left(\frac{3}{4} I + \frac{1}{4} (I - \Delta t F_{3})^{2}\right) \begin{bmatrix} h \\ u \end{bmatrix}^{n}$$

$$\begin{bmatrix} h \\ u \end{bmatrix}^{n+1} = \left(\frac{1}{3} I + \frac{2}{3} (I - \Delta t F_{3}) \left(\frac{3}{4} I + \frac{1}{4} (I - \Delta t F_{3})^{2}\right)\right) \begin{bmatrix} h \\ u \end{bmatrix}^{n}$$

$$\begin{bmatrix} h \\ u \end{bmatrix}^{n+1} = \left(\frac{1}{3} I + (I - \Delta t F_{3}) \left(\frac{1}{2} I + \frac{1}{6} (I - 2\Delta t F_{3} + \Delta t^{2} F_{3}^{2})\right)\right) \begin{bmatrix} h \\ u \end{bmatrix}^{n}$$

$$\begin{bmatrix} h \\ u \end{bmatrix}^{n+1} = \left(\frac{1}{3} I + (I - \Delta t F_{3}) \left(\frac{2}{3} I - \frac{1}{3} \Delta t F_{3} + \frac{1}{6} \Delta t^{2} F_{3}^{2}\right)\right) \begin{bmatrix} h \\ u \end{bmatrix}^{n}$$

$$\begin{bmatrix} h \\ u \end{bmatrix}^{n+1} = \left(\frac{1}{3} I + \frac{2}{3} I - \frac{1}{3} \Delta t F_{3} + \frac{1}{6} \Delta t^{2} F_{3}^{2} + (-\Delta t F_{3}) \left(\frac{2}{3} I - \frac{1}{3} \Delta t F_{3} + \frac{1}{6} \Delta t^{2} F_{3}^{2}\right)\right) \begin{bmatrix} h \\ u \end{bmatrix}^{n}$$

$$\begin{bmatrix} h \\ u \end{bmatrix}^{n+1} = \left(I - \frac{1}{3} \Delta t F_{3} + \frac{1}{6} \Delta t^{2} F_{3}^{2} - \frac{2}{3} \Delta t F_{3} + \frac{1}{3} \Delta t F_{3} - \frac{1}{6} \Delta t^{2} F_{3}^{2} \Delta t F_{3}\right) \begin{bmatrix} h \\ u \end{bmatrix}^{n}$$

$$\begin{bmatrix} h \\ u \end{bmatrix}^{n+1} = \left(I - F_{3} + \frac{1}{6} \Delta t^{2} F_{3}^{2} + \frac{1}{3} \Delta t^{2} F_{3}^{2} - \frac{1}{6} \Delta t^{3} F_{3}^{3}\right) \begin{bmatrix} h \\ u \end{bmatrix}^{n}$$

$$\begin{bmatrix} h \\ u \end{bmatrix}^{n+1} = \left(I - F_{3} + \frac{1}{6} \Delta t^{2} F_{3}^{2} + \frac{1}{3} \Delta t^{2} F_{3}^{2} - \frac{1}{6} \Delta t^{3} F_{3}^{3}\right) \begin{bmatrix} h \\ u \end{bmatrix}^{n}$$

lets say we have

$$F_3 = S_3 D_3 S_3^{-1}$$

$$\begin{bmatrix} h \\ u \end{bmatrix}^{n+1} = \left(\boldsymbol{I} - \Delta t \boldsymbol{S}_3 \boldsymbol{D}_3 \boldsymbol{S}_3^{-1} + \frac{1}{2} \Delta t^2 \boldsymbol{S}_3 \boldsymbol{D}_3^2 \boldsymbol{S}_3^{-1} - \frac{1}{6} \Delta t^3 \boldsymbol{S}_3 \boldsymbol{D}_3^3 \boldsymbol{S}_3^{-1} \right) \begin{bmatrix} h \\ u \end{bmatrix}^n$$

$$\boldsymbol{S}_{3}^{-1} \begin{bmatrix} h \\ u \end{bmatrix}^{n+1} = \left(\boldsymbol{S}_{3}^{-1} - \Delta t \boldsymbol{D}_{3} \boldsymbol{S}_{3}^{-1} + \frac{1}{2} \Delta t^{2} \boldsymbol{D}_{3}^{2} \boldsymbol{S}_{3}^{-1} - \frac{1}{6} \Delta t^{3} \boldsymbol{D}_{3}^{3} \boldsymbol{S}_{3}^{-1} \right) \begin{bmatrix} h \\ u \end{bmatrix}^{n}$$

$$e^{i\omega\Delta t}\boldsymbol{S}_{3}^{-1}\left[\begin{array}{c}h\\u\end{array}\right]^{n}=\left(\boldsymbol{I}-\Delta t\boldsymbol{D}_{3}+\frac{1}{2}\Delta t^{2}\boldsymbol{D}_{3}^{2}-\frac{1}{6}\Delta t^{3}\boldsymbol{D}_{3}^{3}\right)\boldsymbol{S}_{3}^{-1}\left[\begin{array}{c}h\\u\end{array}\right]^{n}$$

$$e^{i\omega\Delta t} \mathbf{S}_{3}^{-1} \begin{bmatrix} h \\ u \end{bmatrix}^{n} = \begin{bmatrix} 1 - \Delta t \lambda_{3,-} + \frac{\Delta t^{2}}{2} \lambda_{3,-}^{2} - \frac{\Delta t^{3}}{6} \lambda_{3,-}^{3} & 0 \\ 0 & 1 - \Delta t \lambda_{3,+} + \frac{\Delta t^{2}}{2} \lambda_{3,+}^{2} - \frac{\Delta t^{3}}{6} \lambda_{3,+}^{3} \end{bmatrix} \mathbf{S}_{3}^{-1} \begin{bmatrix} h \\ u \end{bmatrix}^{n} = \begin{bmatrix} 1 - \Delta t \lambda_{3,-} + \frac{\Delta t^{2}}{2} \lambda_{3,-}^{2} - \frac{\Delta t^{3}}{6} \lambda_{3,-}^{3} & 0 \\ 1 - \Delta t \lambda_{3,+} + \frac{\Delta t^{2}}{2} \lambda_{3,+}^{2} - \frac{\Delta t^{3}}{6} \lambda_{3,+}^{3} \end{bmatrix} \mathbf{S}_{3}^{-1} \begin{bmatrix} h \\ u \end{bmatrix}^{n} = \begin{bmatrix} 1 - \Delta t \lambda_{3,-} + \frac{\Delta t^{2}}{2} \lambda_{3,-}^{2} - \frac{\Delta t^{3}}{6} \lambda_{3,-}^{3} & 0 \\ 1 - \Delta t \lambda_{3,+} + \frac{\Delta t^{2}}{2} \lambda_{3,+}^{2} - \frac{\Delta t^{3}}{6} \lambda_{3,+}^{3} \end{bmatrix} \mathbf{S}_{3}^{-1} \begin{bmatrix} h \\ u \end{bmatrix}^{n} = \begin{bmatrix} 1 - \Delta t \lambda_{3,-} + \frac{\Delta t^{2}}{2} \lambda_{3,-}^{2} - \frac{\Delta t^{3}}{6} \lambda_{3,-}^{3} & 0 \\ 1 - \Delta t \lambda_{3,+} + \frac{\Delta t^{2}}{2} \lambda_{3,+}^{2} - \frac{\Delta t^{3}}{6} \lambda_{3,+}^{3} \end{bmatrix} \mathbf{S}_{3}^{-1} \begin{bmatrix} h \\ u \end{bmatrix}^{n} = \begin{bmatrix} 1 - \Delta t \lambda_{3,-} + \frac{\Delta t^{2}}{2} \lambda_{3,-}^{2} - \frac{\Delta t^{3}}{6} \lambda_{3,+}^{3} & 0 \\ 1 - \Delta t \lambda_{3,+} + \frac{\Delta t^{2}}{2} \lambda_{3,+}^{2} - \frac{\Delta t^{3}}{6} \lambda_{3,+}^{3} \end{bmatrix} \mathbf{S}_{3}^{-1} \begin{bmatrix} h \\ u \end{bmatrix}^{n}$$