

HW3: 1d energy balance model

November 28, 2022

Link to github repository. Main file to run is `analytic_benchmark.py`, outputting plots for solutions from the implicit Euler method. Setting variable `ie` to False in the main for loop of this file instead outputs solutions from explicit method with ODEINT.

Let T_0 be an initial (meridionally-averaged) temperature distribution, set to be $T_0(x) = 10^\circ C$ for all $x \in [0, 1]$, the meridional coordinate. We assume that the temperature $T(t, x)$ of the system evolves according to

$$\partial_t T = QS(x)a(x) - (A + BT) + \mathbb{D}[T] \quad (1)$$

$$\text{subject to } T(t, x) \Big|_{t=0} = T_0 \quad (2)$$

$$(1 - x^2) \frac{\partial T}{\partial x}(t, x) \Big|_{x=0,1} = 0. \quad (3)$$

where Q is the solar constant, $S(x)$ the solar radiation distribution, and $a(x)$ the co-albedo; together they comprise a term modelling the incoming energy radiated from the sun. The term which representing the outgoing radiation from earth, modeled by the Stefan-Boltzmann law, is linearized as $\sigma T^4 \sim (A + BT)$ for some parameters A and B . In atmospheric temperature ranges like $[-10, 40]^\circ C$, this linearization is a good approximation. Furthermore, the diffusion operator \mathbb{D} takes the form

$$\mathbb{D}[f](x) \doteq D \frac{\partial}{\partial x} \left((1 - x^2) \frac{\partial f}{\partial x} \right). \quad (4)$$

for some positive parameter D , the diffusion coefficient. To this second-order differential operator with boundary conditions (3), we might consider the associated eigenvalue problem

$$\mathbb{D}[f](x) = -\lambda f(x). \quad (5)$$

Note that we have taken the following special forms for the solar radiation and albedo terms:

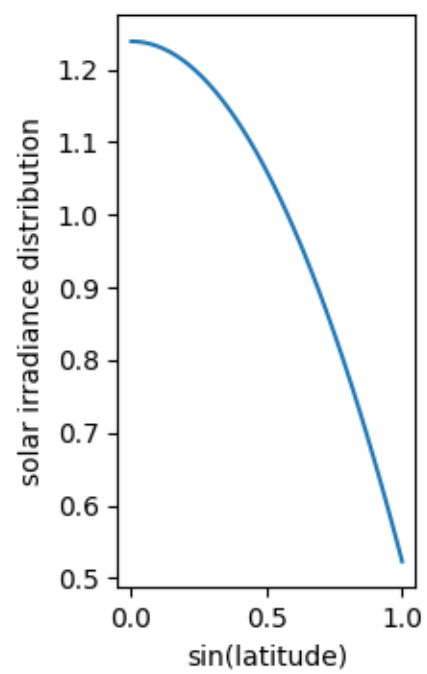
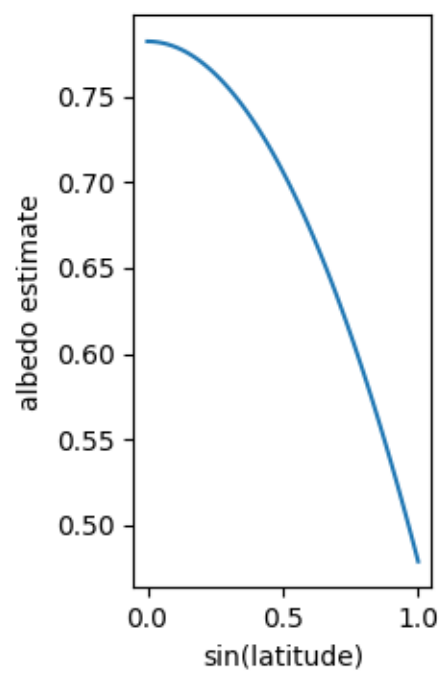
$$S(x) = S_0 + S_2 P_2(x) \quad (6)$$

$$a(x) = a_0 + a_2 P_2(x) \quad (7)$$

subject to the constraint

$$\int_0^1 S(x) = 1. \quad (8)$$

We think of S as a distribution of solar irradiance over the meridional coordinate. The co-albedo coefficient $a(x)$ likewise has some spatial dependence. In this way, with $QS(x)a(x)$ the average power per meter squared, the power density at x is modulated by the distributions of solar irradiance as well as the co-albedo. The net difference between these effects forces the heat equation above. Plots of both as a function of $\sin(\theta)$ with $\theta \in [0, \frac{\pi}{2}]$ are below.



0.1 1d heat equation with ODEINT

Here we describe some of the code in `energy_bal1d.py`. In particular, we focus on the diffusion operator, in which the boundary conditions of the model are encoded. At the equator grid-point, $i = 0$, we use the boundary condition to rewrite diffusion operator. We invoke a GHOST POINT at $i = -1$, where the no-flux condition, implemented via a leapfrog difference, is enforced:

$$\left. \frac{\partial T}{\partial x} \right|_{x=0} \sim D_h^{leap}[T][0] \doteq 1/(2h)(T[1] - T[-1]) = 0. \quad (9)$$

Therefore, this boundary condition introduces the constraint $T[0] = T[2]$. We may then use to re-write the only non-degenerate portion of the discretized diffusion operator $\mathbb{D}_h[T]$ at $i = 0$, i.e., the second-order term of the central-difference operator approximating the term $\frac{\partial^2 T}{\partial x^2}$:

$$\mathbb{D}_h[T][0] = D(T[1] - 2T[0] + T[-1])/(h^2) = 2D(T[1] - T[0])/(h^2) \quad (10)$$

At the pole, since $x[N] = 1$ here, the only non-degenerate part of the diffusion operator is the first-order term:

$$\frac{\partial T}{\partial x}(t, 1) = (1 - 1^2) \frac{\partial^2 T(t, 1)}{\partial x^2} - 2 \frac{\partial T(t, 1)}{\partial x} = -2 \frac{\partial T(1)}{\partial x} \quad (11)$$

which is implemented via a one-sided difference of $O(h)$ accuracy. The interior updates are discretized by a combination of a central-difference scheme for the second-order term and a leap-frog difference scheme for the first-order term.

A plot of the solution found with ODEINT is included below, using a grid resolution of $n = 100$, over a time period of 30 years with monthly time steps:

We want to benchmark this solution against the analytic solution. The code for this is in `analytic_benchmarking.py`. This is described in the third section.

0.2 Implicit euler scheme

Discretizing first in space, we consider the first-order (in time) ODE

$$\frac{d}{dt}T(t, x[i]) = QS(x[i])a(x[i]) - (A + BT)(x[i]) + \mathbb{D}_h[T]_i(x). \quad (12)$$

We now have, for each grid point $x[i]$, $i = 0, \dots, N$ an ODE to solve given initial condition $T_0(x[i]) = 10$. We discretize this according to the implicit Euler, for the stability properties of its solutions. With k denoting a time grid-point and i denoting a spatial grid-point, (12) becomes

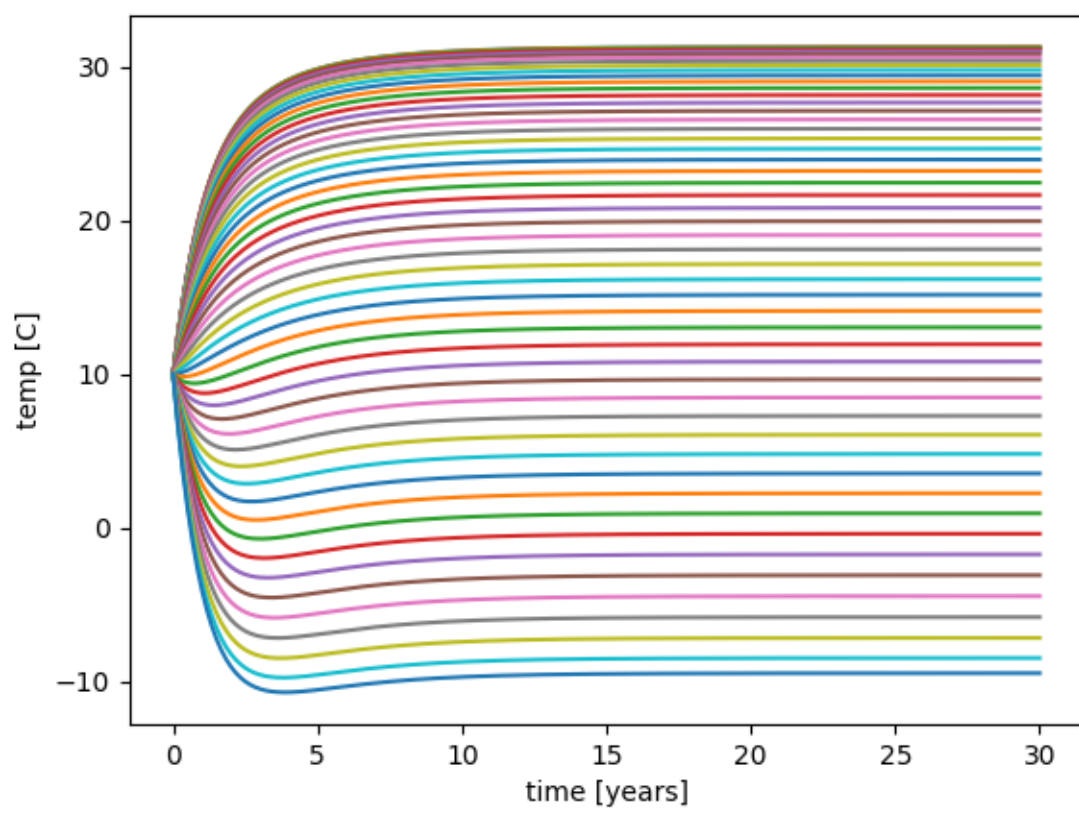
$$(T[k+1, :] - T[k, :]) = \frac{dt}{c_w} (QSa - (A + BT[k+1, :]) + \mathbb{D}_h[T[k+1, :]]) \quad (13)$$

To construct the matrix $\mathbb{D}_h[\cdot]$, recall that the i -th column of a matrix A in standard basis coordinates is given by $A[e_i]$. So given the operator defined in the function `diffusion`, we define another function which outputs the matrix $(A[e_i])_i$, with A here standing for the right-hand-side of (12). Then:

$$\left(I + \frac{dt}{c_w} (B - \mathbb{D}_h) \right) T[k+1, :] = T[k, :] + \frac{dt}{c_w} (QSa - A) \quad (14)$$

For $\frac{dt}{c_w} \|B - \mathbb{D}_h\|_{op} \leq \frac{1}{2}$ we may invert the matrix on the right-hand side yielding:

$$T[k+1, :] = \left(I + \frac{dt}{c_w} (B - \mathbb{D}_h) \right)^{-1} \left(T[k, :] + \frac{dt}{c_w} (QSa - A) \right). \quad (15)$$



Thus, we may write an advance mapping $T[k+1, :]$ given $T[k, :]$ and explicit forms for the matrices in the equality above; this is done in the function `advance` in the file `energy_bal1dIE.py`. For the first matrix on the right-hand side of (15) to be invertible, we require that

$$\left\| \frac{dt}{c_w} (B - \mathbb{D}_h) \right\|_{\ell^\infty} \leq \frac{1}{2} \quad (16)$$

$$\Leftrightarrow dt \leq \frac{c_w}{2} \|B - \mathbb{D}_h\|_{\ell^\infty}^{-1}. \quad (17)$$

Therefore, given a grid resolution h , we choose $dt \doteq \frac{c_w}{10} \|B - \mathbb{D}_h\|_{\ell^\infty}^{-1}$ with an additional loss by a factor of $\frac{1}{5}$ for safety.

0.3 Error benchmarking

The two solution methods above are compared against an analytically-derived steady-state solution in the file `analytic_benchmark.py`. Given the nonlinearities are represented by Legendre basis functions which are defined such that they solve the eigenvalue problem (5), we may try to construct solutions to the steady-state problem out of these basis functions. The analytic function is defined from the canvas-page code in `analytic1d.py`. From this process, the output of solutions using implicit Euler, as well as the benchmark itself seem to be outputting non-sensical values. I have tried to de-bug each of these but unsuccessfully. A next step is to try and solve for the analytic solution via Legendre basis elements. Note that repeating this task for arbitrary N , initially set to 2 (with the odd component stemming from $\phi_1(x)$ removed), would allow us to solve for analytic steady states for more general $S(x)$ and $a(x)$ distributions.

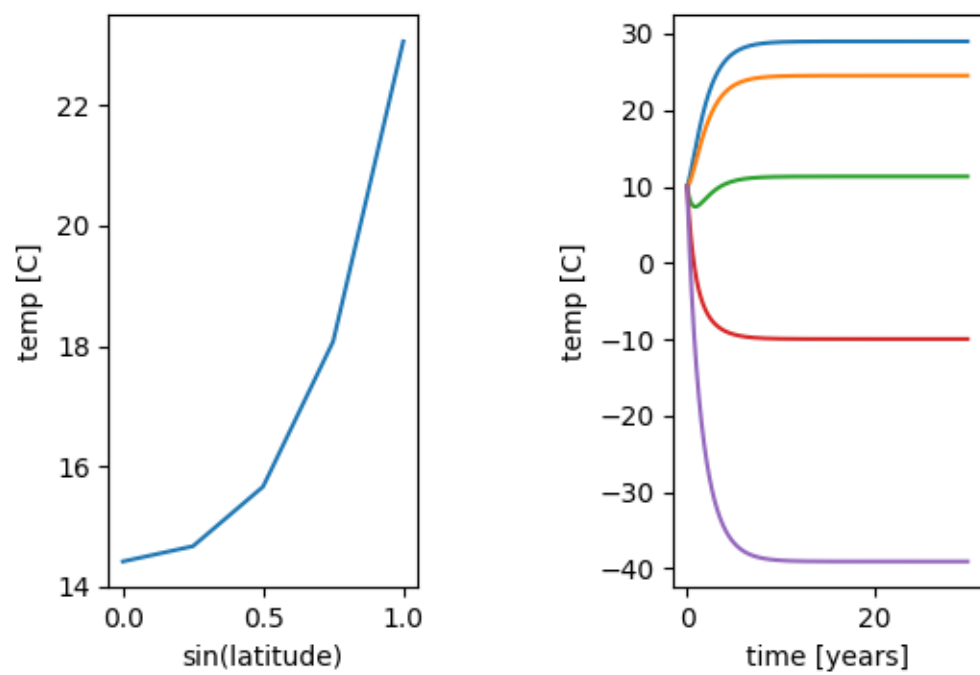


Figure 1: $n = 2^2$

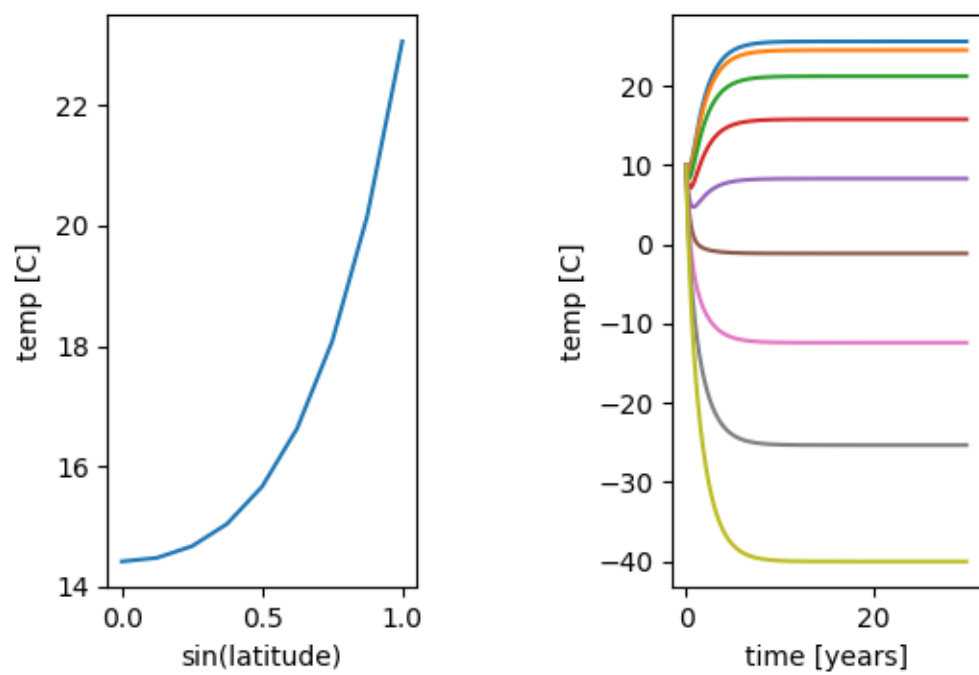


Figure 2: $n = 2^3$

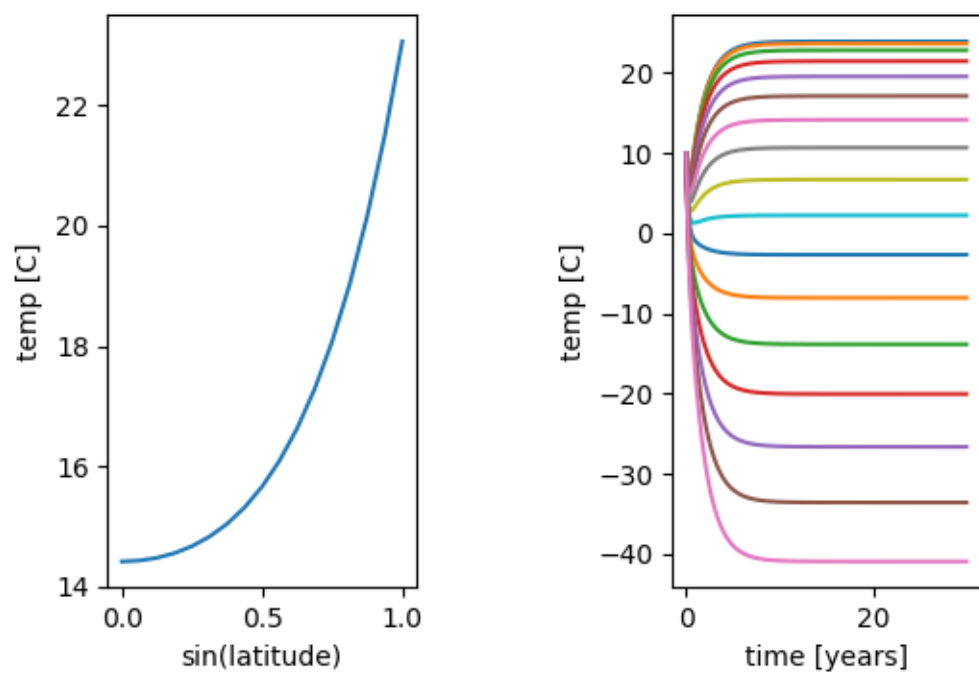


Figure 3: $n = 2^4$

