1) Consider the problem

Where f is continuously differentiable over the $\{x \mid x \geq 0, e^*x = 1\}$. Prove that x^* is a stationary point if and only if

$$\frac{\partial f}{\partial x_i}(x^*) \begin{cases} = \mathcal{M} & x_i^* > 0 \\ \ge \mathcal{M} & x_i^* = 0 \end{cases}$$

Proof, (\Rightarrow) $\nabla f(x^*)^t(x-x^*) \ge 0$ $\forall x s.t. e^t x = 1 x \ge 0$

$$\Rightarrow \nabla f(x^*)^t \times - \nabla f(x^*)^t \times^* = 0$$

$$\Rightarrow \sum_{v} \frac{\partial x_{i}^{*}}{\partial t} x^{v} - \sum_{v} \frac{\partial x_{i}^{*}}{\partial t} x^{v}_{i} = 0$$

$$\Rightarrow \sum_{i=1}^{n} \frac{\partial x_{i}^{*}}{\partial x_{i}^{*}} \chi_{i} \geq \sum_{i=1}^{n} \frac{\partial f}{\partial x_{i}^{*}} \chi_{i}^{*}$$

Since $\sum_{i=1}^{n} x_i = \sum_{i=1}^{n} x_i^* = 1$ this implies the last inequality can only hold if the value of each component of $\nabla f(x^*)$

is either
$$\geq \mu \in \mathbb{R}$$
 for $\chi_i^* = 0$ or $= \mu \text{ if } \chi_i^* > 0$.

(\Leftarrow) For the other direction assume $\frac{\partial f}{\partial x_i}(x^*)$ $\begin{cases} = \mu x_i^* > 0 \\ \frac{\partial f}{\partial x_i^*}(x^*) \end{cases}$

If $x_i^* > 0$ $\forall i$ and $e^t x^* = e^t x = 1$ and let $\frac{e^t}{\partial x_i^*} = \mu$ $\forall i$, then

μ[°]_ξχ; - μ[°]_ξχ^{*} = μ-μ =0

If $x_i^* = 1$ and $x_i^* = 0$ $\forall i \neq j$ and let $\partial x_i^* = \lambda = M$ $\forall i \neq j$ then

Without loss of generality assume j=1

$$\lambda \chi_{i} + \sum_{i=2}^{n} \mu \chi_{i} + \lambda \chi_{i}^{*} + \sum_{i=2}^{n} \mu \chi_{i}^{*}$$

$$= \lambda$$

$$= \lambda$$

$$= 0$$

2) Let f be a strongly convex function over a closed convex set $S \subseteq \mathbb{R}^n$ w/ strong covexity parameter G, i.e.

 $f(y) = f(x) + \nabla f(x)^{t}(y-x) + = ||x-y||^{2} \quad \forall x, y \in S$ Assume $f \in C_{L}^{1,1}(s)$. Consider min { f(x): x ∈ S} where s is a closed convex set. Let {x,3, be the sequence generated by the gradient projection method for Solving the problem w/ constant stepsize to \(\frac{1}{2} \).

Let x* be the optimal solution and f* the optimal value.

Prove 3 c∈(0,1) s.t. for k≥0

$$\|\chi_{\kappa+1} - \chi^*\| \leq c \|\chi_{\kappa} - \chi^*\|$$

Find an explicit expression for C.

Proof:

Since $f \in C_L^{1,1}(s)$ we can use the descent lemma:

$$f(\chi_{k+1}) \leq f(\chi_k) + \langle \nabla f(\chi_k), \chi_{k+1} - \chi_k \rangle + \frac{L}{2} \|\chi_k - \chi_{k+1}\|^2$$

Also, since f is strongly convex:

$$\frac{1}{2}\|x_{\nu}x^{*}\|+f(x_{\nu})+\nabla f(x_{\nu})^{t}(x^{*}-x)\leq f(x^{*})$$

$$\Rightarrow f(x_{\kappa}) \in f(x_{\star}) - \Delta f(x_{\kappa})_{+} (x_{\star} - x_{\kappa}) - \tilde{s} \|x_{\kappa} - x_{\star}\|_{s}$$

$$\Rightarrow f(x_{\nu}) \in f(x^*) + \nabla f(x_{\nu})^{\dagger}(x_{\nu} - x^*) - \mathbb{E} \|x_{\nu} - x^*\|^2$$

Now plugging these into Thm 9.16

Now plugging these into 1 hm 9.16 $\frac{2}{2}(f(x_{k+1})-f(x^*)) \leq ||x_k-x^*||^2 - ||x_{k+1}-x^*||^2$ $\frac{2}{2}(f(x^*)+\nabla f(x_k)^t(x_k-x^*)-\frac{2}{2}||x_k-x^*||^2-f(x^*)] \leq ||x_k-x^*||^2-||x_{k+1}-x^*||^2$ $\frac{2}{2}\nabla f(x_k)^t(x_k-x^*)\leq ||x_k-x^*||^2+\frac{2}{2}||x_k-x^*||^2-||x_{k+1}-x^*||^2$ $\frac{2}{2}\nabla f(x_k)^t(x_k-x^*)\leq ||x_k-x^*||^2+\frac{2}{2}||x_k-x^*||^2-||x_{k+1}-x^*||^2$ $\frac{2}{2}\nabla f(x_k)^t(x_k-x^*)\leq ||x_k-x^*||^2+\frac{2}{2}||x_k-x^*||^2-||x_{k+1}-x^*||^2$ Now since x^* is an optimal point this implies it is stationary and hence the RHS is ≥ 0 therefore:

3) Consider the problem

min $x_1^2 + 2x_2^2 + x_1$ s.t. $x_1 + x_2 \le a$ for $a \in \mathbb{R}$

(i) Prove $\forall a \in \mathbb{R}$ the problem has a unique optimal solution.

Proof: clearly as lixed > 0 the function increases without bound and is by definition coercive. Now by them 2-32, attainment under coerciveness, we have

attainment under coerciveness, we have a continuous coercive function defined on a nonempty closed space, in this case the half space $x_1 + x_2 = a$, which implies that f has a global minimum over this half space.

However, this does not imply that the global minimum is unique. For this we will recall that if f is strictly convex then there exists at most one optimal solution, (Things.3). Therefore to prove the desired we need only show that f is strictly convex.

f can be written in quadratic form as $f(x_1, x_2) = [x_1, x_2] \begin{bmatrix} 1 & 0 \\ c & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} 1 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$

 $= \left[\chi_{1} \quad 2\chi_{2} \right] \left[\chi_{2} \right] + \chi_{1}$

 $= \chi_1^2 + 2\chi_2^2 + \chi_1$

Thum 7.10 says that for a quadratic function $f(x) = x^t A x + 2b^t x + C$

if A > 0 then f is strictly convex which since $A = \begin{bmatrix} 62 \\ 1 \end{bmatrix}$ is diagonal with all strictly positive diagonal entries this implies A > 0 (lemma 2.19).

Therefore f is strictly convex and there exists at most one optimal solution.

exists at most one optimal solution.

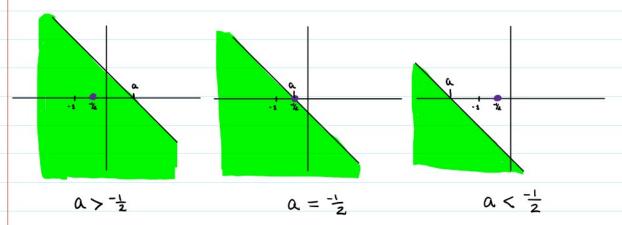


Since we know that there exists a unique global min lets first consider what it would be for the associated unconstrained problem.

$$\nabla f(x) = \begin{pmatrix} 2x_1 + 1 \\ 4x_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Rightarrow \chi_1 = \frac{-1}{2}$$

x* = (-\frac{1}{2},0) is the only critical point which is what we expected and we know by the argument above in (i) that it is a global minimum.

Now consider what happens taking into account the constraint x,+x2 =a:



For $a \ge -\frac{1}{2}$ the optimal point is $(-\frac{1}{2},0)$, but when $a < -\frac{1}{2}$ the optimal point will be on

when $0 < -\frac{1}{2}$ the optimal point will be on the boundary $x_1 + x_2 = a$. We can solve for ∞_2 and plug into the original function. We now have a simple 1D minimization problem.

$$x_{2} = \alpha - x_{1}$$

$$f(x_{1}) = x_{1}^{2} + 2(\alpha - x_{1})^{2} + x_{1}$$

$$= 3x_{1}^{2} + (1 - 4\alpha)x_{1} + 2\alpha^{2}$$

$$f'(x_{1}) = 6x_{1} + 1 - 4\alpha = 0$$

$$\Rightarrow x_{1} = \frac{4\alpha - 1}{6}$$

$$\Rightarrow x_{2} = \frac{2\alpha + 1}{6}$$

$$\therefore \text{ the optimal Solution for } \alpha < -\frac{1}{2}$$

$$x^{*} = \left(\frac{4\alpha - 1}{6}, \frac{2\alpha + 1}{6}\right)$$

(iii) Let f(a) be the optimal value of the problem with parameter a. Write an explicit expression for f and prove it is a convex function.

$$f(x_1, x_2) = x_1^2 + 2x_2^2 + x_1$$

$$f(\frac{1}{2}, 0) = (\frac{1}{2})^2 + 2(0) + (\frac{1}{2}) = \frac{1}{4}$$

$$f(\alpha) = \begin{cases} -\frac{1}{4} & \text{for } \alpha \ge -\frac{1}{2} \\ \left(\frac{4\alpha - 1}{6}\right)^2 + 2\left(\frac{2\alpha + 1}{6}\right)^2 + \left(\frac{4\alpha - 1}{6}\right) & \text{for } \alpha < -\frac{1}{2} \end{cases}$$

f(a) is convex if

$$f(\lambda a + (1-\lambda)b) \leq \lambda f(a) + (1-\lambda)f(b) \forall a,b \in \mathbb{R}$$

 $\lambda \in [c,i]$

First Simplify f(a)

$$f(\alpha) = \begin{cases} -\frac{1}{4} & \text{for } \alpha \ge \frac{-1}{2} \\ \frac{2}{3}a^2 + \frac{32}{9}a - \frac{33}{36} & \text{for } \alpha < \frac{-1}{2} \end{cases}$$

$$f''(a) = \begin{cases} 0 & \text{for } a \ge \frac{-1}{2} \\ \frac{4}{3} & \text{for } a < \frac{-1}{2} \end{cases}$$

Both cases have a nonnegative second derivative therefore f(a) is convex.