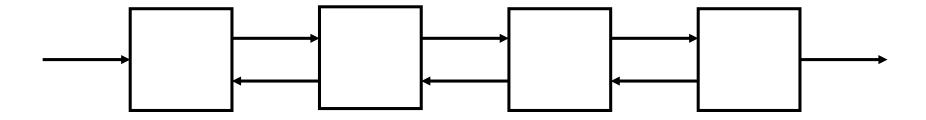
Parallel Computing

Processors with Connections

Systolic Arrays

The Simplest Systolic Array:

- *n* simple processors
- Arranged in a row
- Each processor can exchange information only to its neighbours on its left and right
- Processor 1 takes an input
- Processor n give an output

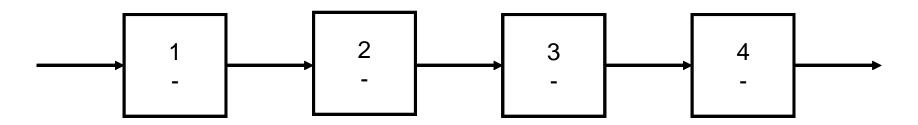


Even the simplest systolic array can solve many problems much more quickly than a single processor. E.g.:

- n-body problem Compute the path of n bodies moving through space under the influence of their mutual and combined gravitational attractions
- A sequential computer, can solve this in $O(n^2)$ steps since there are $(n^2 n)/2$ attractions
- A systolic array can achieve this in O(n) steps

- Each cycle of an n-body computation would involve calculating, for each body, the summed attractions of the other n-1 bodies
- Assume each processor carries a program to calculate these attractions: $F_{ij} = k m_i m_j / d_{ij}^2$, given values for k, m_i , m_j , and the co-ordinates of i and j
- For each body, starting with B_n , co-ordinates and mass is inputted to P_1 they are then passed rightwards until each processor, P_i holds the co-ordinates and mass of a unique body, B_i This takes n steps

- There is then the same input, but this time, as the information for each new body B_j arrives from the left, P_i executes (using B_i from before):
 - Calculate d_{ii}
 - Calculate the Force F_{ij}
 - Add F_{ij} to the force previously calculated
- It takes 2n steps to complete this process:



- Another program shifts the final F values across to the output
- Absorbing n more steps

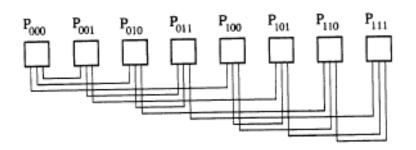
Using a Systolic Array takes 4n steps if each shift of information and execution of the algorithm takes 1 unit of time

Clearly this can be computed in linear, O(n), time

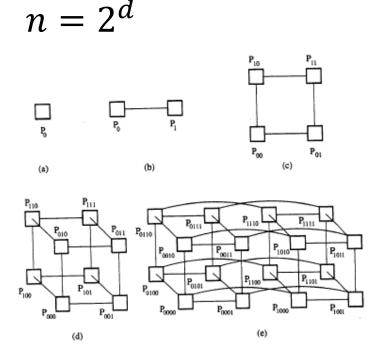
Systolic Arrays

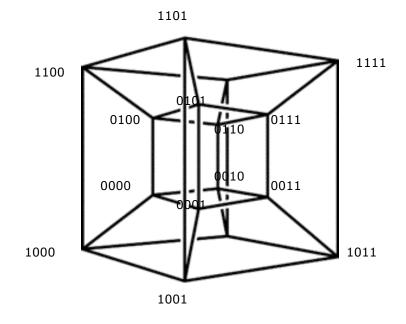
- In reality, systolic arrays are much more sophisticated than a single row of processors, and there are other types of parallel computers
- More general and powerful schemes can be represented by a cube-connected computer

Hypercubes



- A d-dimensional hypercube allows the connection between n processors in a cubeconnected computer
- Each processor is a vertex of the cube, giving





- Something like a hypercube can also help us to solve some problems more quickly than with a sequential machine – E.g. Matrix Multiplication:
- Given two $n \times n$ arrays X and Y, it would take a sequential computer somewhere between $O(n)^2$ and $O(n)^3$ steps to produce the n^2 elements in the product, Z

For each element of the product matrix Z:

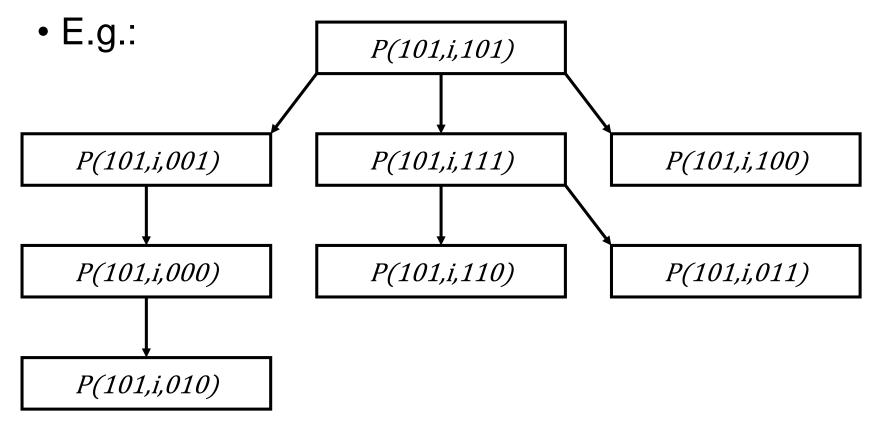
$$Z_{ij} = \sum_{k=1}^{\infty} x_{ik} y_{kj}$$

- The optimal number of processors is n^3
- d separate links are required so that one processor might communicate with another
- Hence $d = log n^3 = 3 log n$
- So any communication between processors alone will require O(logn) steps

- The first step is to distribute the array elements from X and Y throughout the n^3 processors so that P(k,i,j) contains x_{ik} and y_{kj}
- This is done by transmitting the x_{ik} data from P(0,i,j) to P(k,i,j) by a route of fewer than logn processors
- At each stage of the journey, the next processor it goes to is the one that has an index that is 1 bit closer to k E.g. where k = 5 = 101:

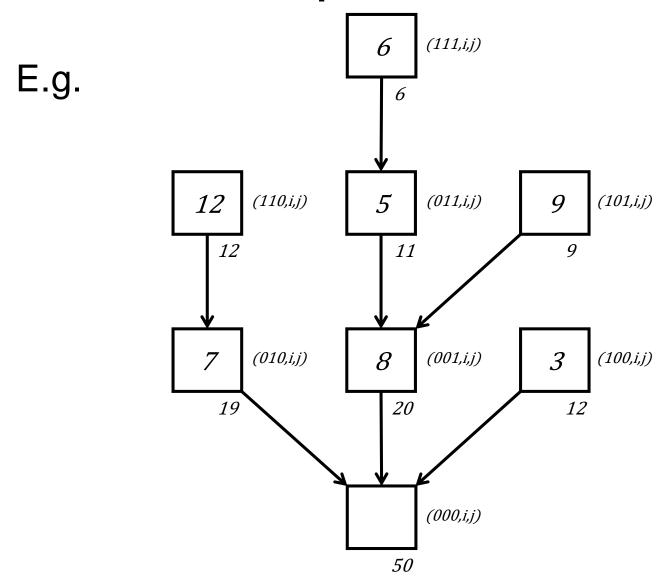
$$P(000, i, j) \rightarrow P(100, i, j) \rightarrow P(101, i, j)$$

• Now that P(k,i,j) has received x_{ik} , it is broadcasted to (k,i,0), (k,i,1), ..., (k,i,n)



• Now the product $x_{ik} \times y_{kj}$ is calculated and stored in the relevant processor

- The products are drawn from all the processors P(1,i,j), P(2,i,j), ..., P(n,i,j) and stored in P(0,i,j)
- This is done by a continual 'fanning in' of accumulated sums, always changing one of the bits to 0
- All transmission and summing are carried out in parallel so the number of steps is bounded by the maximum distance between two processors, logn



• Using a cube-connected computer, matrix multiplication can now be solved in O(logn) steps rather than $O(n)^{2.61}$