# Goal Oriented Action Planning Al

PERSONAL PROGRAMMING PROJECT FINAL PRESENTATION BY JORDAN MARTIN

#### Objectives

- Create a GOAP AI system in Unreal
- Integrate the GOAP AI system into an agent-based simulation
- Try applying the system to a theme park game demonstration

#### Stretch Goals:

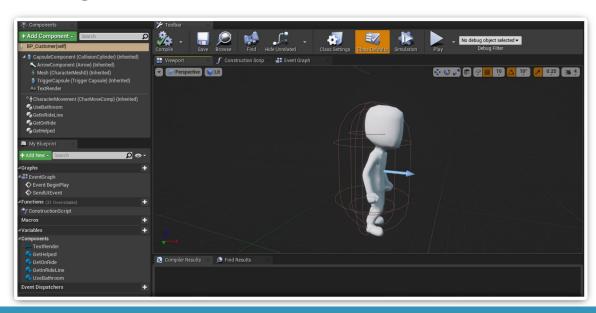
Incorporate game mechanics into the simulation



#### Mid-Semester Recap

- GOAP System created in C++ classes from scratch (no behavior trees)
- Multi-step plans and multiple agents
- Inventories
- Game elements: RTS Camera, UI Watch Window, Speed
- Unreal C++: Collision, Spawning, Data Structures, Delegates

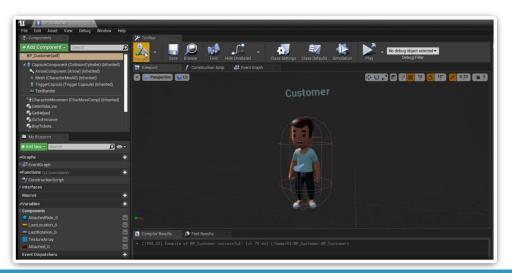




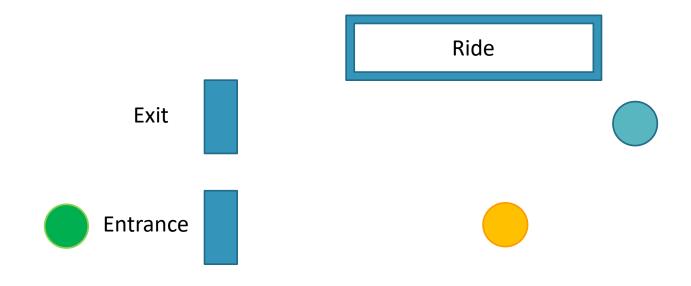
#### Final Progress

- Expanded on GOAP system: DuringPerform() and Animations
- Smart Objects added to Inventories
- Ride animations/socketing and Queueing system for agents
- Additional actions: Use Restroom, Take Break, Leave Park, etc.
- UI Watch Window Additions
- Unreal C++: Collision, Animations/State Machine, Socketing



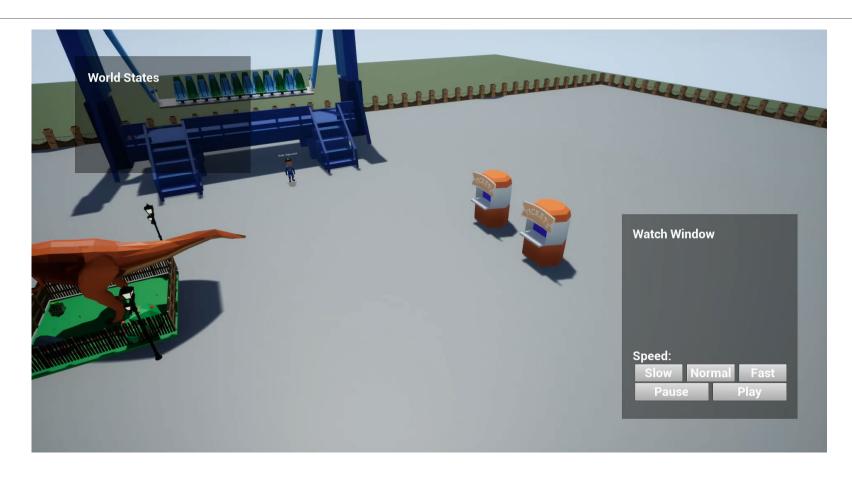


### Home Park Example



#### Live Demo

#### Demo Video



#### Schedule

Goal	Week	Previous Schedule	Actual Schedule
Integrating GOAP System into Agent- Based Simulation	Week 6	<ul> <li>Update Presentation</li> <li>Complete multi-step plans</li> <li>Flesh out UI Window</li> <li>Animate State</li> </ul>	<ul><li>Update Presentation</li><li>Complete multi-step plans</li><li>Flesh out UI Window</li><li>Animate State</li></ul>
	Week 7	<ul> <li>Adding "Smart Objects" to the world</li> <li>Add objects that can be used to fulfill goals</li> </ul>	<ul><li>Adding "Smart Objects" to the world</li><li>Add objects that can be used to fulfill goals</li><li>Agent animations</li></ul>
	Week 8	<ul> <li>Revalidation of plans</li> <li>Add changes to the world state that require plan changes</li> </ul>	<ul> <li>Revalidation of plans</li> <li>Add changes to the world state that require plan changes</li> <li>Ride animations</li> </ul>
Applications towards Games and Simulation	Week 9	<ul> <li>Priority of Goals for agents</li> <li>Execute plans while having competing priorities</li> </ul>	<ul> <li>Priority of Goals for agents</li> <li>Execute plans while having competing priorities</li> <li>Queueing multiple agents onto rides</li> </ul>
	Week 10	<ul> <li>Create a Theme Park Simulation</li> <li>Implement all agents and actions</li> <li>Integrate GOAP system into Demo Scene</li> <li>Time for fixes and polish</li> </ul>	<ul> <li>Create a Theme Park Simulation</li> <li>Implement all agents and actions</li> <li>Integrate GOAP system into Demo Scene</li> <li>Time for fixes and polish</li> </ul>
	Week 11	Final Presentations	Final Presentations

#### Positive Outcomes

- Understanding of GOAP systems
- System benefits realized:
  - Modular actions
  - Competing priorities
  - Inventory system for both resources and items
- •More experience in Unreal Engine / C++





#### Problems Faced

- GOAP Difficulties:
  - Difficult to debug when actions are hidden behind planner
    - Creating debug tools early on is critical
- Unreal Engine difficulties:
  - Collision, animations, socketing, communicating C++ with BPs
  - Standard library containers, Smart Pointers
- Performance issues
  - Agent continuously accesses the planner on tick if preconditions are not met



#### Next Steps

- Expand the system to work with shops and rides
  - Eat/drink food
  - Additional rides
- Add more of the planned characters
  - Mechanics and Entertainers
- UI Improvements
  - Inventory of each agent in the menu



## Thank you!