Project Planner: AGV-Project

<u> </u>	Plan Duration		Actual Start		% Complete		Actual (beyond plan)		% Complete	(beyond plan)								
ACTIVITY	ASSIGNED TO	PLAN START	PLAN DURATION	ACTUAL START	ACTUAL DURATION	PERCENT COMPLETE	01/10/2018 1	08/10/2018 2	15/10/2018 3	22/10/2018 4	28/10/2018 5	05/11/2018 6	12/11/2018	19/11/2018 8	26/11/2018 9	03/12/2018	10/12/2018 11	17/12/2018 12
Hardware Diagram	Jordi	1	1	1		100%												
Gantt Diagram	Jordi	1	1	1	1	100%												
Class Diagram	Flemming	1	1	1		100%												
Communication Diagram	Rasmus	1	1	1		100%												
Simulation research	All	1	4	1		0%												
Control algorithms research	All	2	2			0%												
Path planning algorithms research	All	2	2			0%												
Task planning algorithms research	All	2	2			0%												
Make report algorithms	All	2	2			0%												
Hardware Assembly	All	4	1			0%												
RPI3 - Arduino Communication Test	All	4	2			0%												
Arduino - Motors Test	All	4	2			0%												
Arduino - Encoders Test	All	4	2			0%												
RPI3 - VICON Test	All	4	2			0%												
Testing Report	All	4	2			0%												
Mapping  Make robot do a route	All	6	1			0%												
(Routing)	All	6	3			0%												
algorithms  Task planning	All	6	3			0%												
algorithms  Report of all the tests	All	6	3			0%												
done Final prototype	All	10	1			0%												
integration  Last validation tests	All	11	2			0%												
Write final report	All	10	3			0%												