# Jordi Gonzalez Cano

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#### **Profile**

I am a **Software Engineer** with high interests in Machine Learning and Robotics technologies. I have recently completed my bachelor in Computer Science Engineering and I am looking for a job related to my studies.

### **Employment History**

Feb 2018 - Jul 2018

Student Software Developer

SANT CUGAT DEL VALLES

HP Inc.

A 6 months internship consisting of researching the area of **Colour Management** using **Machine Learning**, such as regression methods and different Neural Networks architectures.

#### Education

Sep 2014 - Jun 2018

Computer Science Engineering (Grade: 8/10)

BELLATERRA DEL VALLES

Universitat Autonoma de Barcelona

During my bachelor I have learned team working methods such as **SCRUM**, problem solving and several programming languages. I have specialized on computation which consisted on:

- Computer Vision
- Optimization Algorithms, such as Greedy
- Artificial Intelligence
- Graphical design and interaction, using OpenGL
- Robotics
- Compilers

Sep 2016 - Feb 2017

ERASMUS+

ENSCHEDE

University of Twente

The ERASMUS consisted on two projects:

- 1. Android game with the **Unity** platform with **C#**: Polluto.
- 2. Robotics and Smart Cities in C++: Pipeline inspection with a swarm of robots

Sep 2018 - Now

Master in Autonomous Systems

COPENHAGEN

Aalborg University



## **Projects**

Sep 2016 - Dec 2016

ENSCHEDE

Serious Game: Polluto

University of Twente

The game was a *Serious game* about Pollution. This means, that after playing the game the way of thinking of the player about pollution should have changed or at least make the player think about the topic. Done with **C#** using the **Unity** platform

Can be tried at:

https://github.com/jordigc2/My-projects/tree/master/Serious%20Gaming

Dec 2016 - Feb 2017

Smart Cities: Pipeline inspection with a swarm of robots

ENSCHEDE University of Twente

We had to develop an idea of how the explore the pipelines of Enschede using a **swarm of robots**. As it was a proof of concept we made a simulation using **C++** with threads to

control each robot independently. Simulation video and poster:

https://github.com/jordigc2/My-projects/tree/master/Smart%20Cities

Sep 2018 - Now

**Bachelor Thesis** 

BELLATERRA DEL VALLES SANT CUGAT DEL VALLES Universitat Autonoma de Barcelona / HP Inc.

 $\mathbb{C}++$ 

I had to find an alternative for the existing **Color Management** transformation between two colour spaces using **Machine Learning**, such as *Neural Network* models. I worked with **C++** to create the data sets and transformed images. I also used **Python** to create the different ML models, using the **SKLearn** and **Tensorflow** libraries.

Report and poster link:

https://aithub.com/iordiac2/Mv-projects/tree/master/Bachelor%20thesis

Skills

 $\subset$ 

Java

R

Open GL

Python C#

Machine Learning: (Classification and Regression using Neural Networks models,

clustering models, linear-polynomial-SVM

HTML regression models)

CSS PHP Color Management

JavaScript SQL SCRUM methodology

Tensorflow Little CMS Object-Oriented Programming

## Languages

Catalan: Native

English: C1 level

Spanish: Native