

Econometrics: non-parametric, lecture notes

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1 Notes on Probability

1.1 On measure space

Let Σ be a set, we want to make sense of $\mathbb{P}(F)$ the probability of the event F , where $F \subseteq \Sigma$.

Definition 1.1. A collection of subsets of Σ is a σ -algebra if:

- $\Sigma \in F$
- $f \in F \implies F^c = \{w \in \Sigma : w \notin F\} \in F$
- For every sequence (F_n) of elements of F , $\bigcup_{n \in \mathbb{N}} F_n \in F$. Note that this property is the same as: $\bigcap_{n \in \mathbb{N}} (F_n^c)^c \in F$

Remark 1.1. In measure theory, one axiomatizes the notion of 'measurable set', insisting that the union of a countable collection of measurable sets is measurable, and that the intersection of a countable collection of measurable sets is also measurable. Also, the complement of a measurable set must be measurable, and the whole space must be measurable. Thus the measurable sets form a sigma-algebra, a structure stable (or 'closed') under countably many set operations. Without the insistence that 'only countably many operations are allowed', measure theory would be self-contradictory - a point lost on certain philosophers of probability¹.

Example 1.1. If $\Sigma = \mathbb{R}^d$, the Borel sigma-algebra, denoted $\mathbb{B}(\mathbb{R}^d)$ is the smallest sigma-algebra of \mathbb{R}^d which contains all open sets.

Definition 1.2. $\mu : F \rightarrow [0, \infty]$ is a measure on Σ, F if:

- $\mu(\emptyset) = 0$
- if for all sequences $(F_n)_{n \in \mathbb{N}}$ of disjoint sets of F we have that $\mu(\bigcap_{n \in \mathbb{N}} F_n) = \sum_{n \in \mathbb{N}} \mu(F_n)$

Definition 1.3. \mathbb{P} is a probability if it is a measure and $\mathbb{P}(\Sigma) = 1$

Definition 1.4. (Σ, F, \mathbb{P}) is a probability triple if F is a sigma-algebra on Σ and \mathbb{P} a probability on (Σ, F) .

Definition 1.5. $X : (\Sigma, F, \mathbb{P}) \rightarrow (\mathbb{R}^d, \mathbb{B}(\mathbb{R}^d))$ is a random vector if $\forall \mathbb{B} \in \mathbb{B}(\mathbb{R}^d), X^{-1}(\mathbb{B} \in F)$. That is, X is f -measurable.

Example 1.2. Measurability of a Random Variable: A Simple Example

Let us consider a sample space $\Omega = \{HH, HT, TH, TT\}$, representing the outcomes of flipping a fair coin twice. Define a random variable $X : \Omega \rightarrow \{0, 1, 2\}$, which takes the following values based on the number of heads in the outcome:

$$X(\omega) = \begin{cases} 0 & \text{if } \omega = TT, \\ 1 & \text{if } \omega = HT \text{ or } \omega = TH, \\ 2 & \text{if } \omega = HH. \end{cases}$$

¹straight copy pasting from the glorious and much helpful book "Probability with martingales" by Williams"

To determine whether X is measurable with respect to a given σ -algebra \mathcal{F} , recall that measurability means for every Borel set $B \subseteq \{0, 1, 2\}$, the preimage $X^{-1}(B) = \{\omega \in \Omega : X(\omega) \in B\}$ must belong to \mathcal{F} .

Suppose \mathcal{H} is the trivial σ -algebra $\{\emptyset, \Omega\}$. For example, consider the preimage $\{X = 2\} = \{HH\}$. Clearly, $\{HH\} \notin \mathcal{H}$, so X is not \mathcal{H} -measurable.

Define a σ -algebra \mathcal{F} where X is measurable. Now, let us construct a σ -algebra \mathcal{F} such that X is measurable. Consider the following σ -algebra:

$$\mathcal{F} = \{\emptyset, \Omega, \{HH\}, \{TH, HT\}, \{TT\}, \{HH, TT\}, \{TH, HT, TT\}, \{HH, TH, HT\}\}.$$

We verify that \mathcal{F} is a σ -algebra (it is closed under complements and countable unions). Next, we check whether X is measurable with respect to \mathcal{F} .

We calculate the preimages of the sets $\{0\}$, $\{1\}$, and $\{2\}$:

$$\{X = 0\} = \{TT\} \in \mathcal{F},$$

$$\{X = 1\} = \{HT, TH\} \in \mathcal{F},$$

$$\{X = 2\} = \{HH\} \in \mathcal{F}.$$

Since the preimages of all singleton sets in the range of X belong to \mathcal{F} , and σ -algebras are closed under unions, the preimages of all Borel subsets of $\{0, 1, 2\}$ also belong to \mathcal{F} . Therefore, X is \mathcal{F} -measurable.

Definition 1.6. Let X be a random vector in \mathbb{R}^d , the sigma-algebra generated by X , denoted $\sigma(X)$ is the smallest sigma-algebra on Σ s.t: $X : (\Sigma, \mathcal{F}, \mathbb{P}) \rightarrow (\mathbb{R}^d, \mathbb{B}(\mathbb{R}^d))$ is measurable.

Example 1.3. Consider a probability space $(\Sigma, \mathcal{F}, \mathbb{P})$ where:

- $\Sigma = \{a, b, c\}$,
- $\mathcal{F} = \{\emptyset, \{a\}, \{b, c\}, \{a, b, c\}\}$,
- $\mathbb{P}(\{a\}) = 0.5, \mathbb{P}(\{b, c\}) = 0.5$.

Define a random variable $X : \Sigma \rightarrow \mathbb{R}^2$ as:

$$X(a) = (1, 2), \quad X(b) = (3, 4), \quad X(c) = (5, 6).$$

We claim X is measurable. To see why, consider any Borel set $B \in \mathbb{B}(\mathbb{R}^2)$:

- If $B = \{(1, 2)\}$, then $X^{-1}(B) = \{a\} \in \mathcal{F}$.
- If $B = \{(3, 4), (5, 6)\}$, then $X^{-1}(B) = \{b, c\} \in \mathcal{F}$.
- If $B = \mathbb{R}^2$, then $X^{-1}(B) = \{a, b, c\} \in \mathcal{F}$.

Since $X^{-1}(B) \in \mathcal{F}$ for all $B \in \mathbb{B}(\mathbb{R}^2)$, X is measurable. This demonstrates how random variables map events in the sample space to measurable subsets of \mathbb{R}^2 .

Remark 1.2. • $x \in \mathbb{R}^d \rightarrow [0, \infty)$

- $x \mapsto \|x\|_2^\rho$, where $\rho > 1$ $\left(\|x\|_2 = \sqrt{\sum_{k=1}^d x_k^2}\right)$ is continuous, as a consequence we can show that $\|x\|_2^\rho$ is a random variable if X is a random vector

Exercise 1

Definition 1.7. We write $X \in L^\rho(\Sigma, \mathcal{F}, \mathbb{P})$ if X is \mathcal{F} -measurable and $\mathbb{E}[\|x\|_2^\rho] < \infty$

Definition 1.8. The distribution law of X , denoted \mathbb{P}_x is the probability on $(\mathbb{R}^d, \mathbb{B}(\mathbb{R}^d))$ such that $\forall B \in \mathbb{B}(\mathbb{R}^d)$, $\mathbb{P}(X \in B) = \mathbb{P}_x(B)$

Definition 1.9. X has density f_x with respect to the Lebesgue measure (dx) on \mathbb{R} if $\mathbb{P}_x(B) = \int_{\mathbb{R}^d} \mathbf{1}\{x \in B\} f_x dx, \forall B \in \mathbb{B}(\mathbb{R}^d)$, where $f_x dx$ is $d\mathbb{P}_x(x)$

Definition 1.10. The support of X (or of \mathbb{P}_x) is defined as: $\text{Supp}(X) = \{x \in \mathbb{R}^d : \forall r > 0, \mathbb{P}(X \in B(x, r)) > 0\}$ where $B(x, r) := \{z : \|x - z\|_2 < r\}$ is an open ball.

Remark 1.3. • $\text{Supp}(X)^c := \{x \in \mathbb{R}^d : \forall r > 0, \mathbb{P}(X \in B(x, r)) = 0\}$ is an open set and hence the $\text{Supp}(X)$ is a closed set.

- $\text{Supp}(X)$ is the longest? $C \in \mathbb{B}(\mathbb{R}^d)$ such that for all ball B such that $B \cap C \neq \emptyset \implies \mathbb{P}_x(B \cap C) > 0$

Exercise: let $Y = Y^* \mathbf{1}\{Y^* \geq \frac{1}{2}\} + \frac{1}{3} \mathbf{1}\{Y^* < \frac{1}{2}\}$ show that:

1. $\text{supp}(Y^*) = [-1, 1]$
2. $\text{supp}(Y) = \frac{1}{3} \cup [\frac{1}{2}, 1]$

Remark 1.4. Note that: $\mathbb{E}[|y|] \leq \sqrt{\mathbb{E}(y^2)}$ by Cauchy-Schwarz so $L^2(\Sigma, \mathcal{F}, \mathbb{P})$, where we can define: $\mathbb{E}(|y|) = \mathbb{E}(Y \cdot \text{sign}(Y))$.

Exercise: If X is a random vector and X_1 the r th entry, then $\sigma(X_1) \subset \sigma(X)$

1.2 Conditional probability

Definition 1.11. For a random variable $X \in L^1(\Omega, \mathcal{F}, P)$, we define the *expectation* $\mathbb{E}(X)$ of X by

$$\mathbb{E}(X) := \int_{\Omega} X dP = \int_{\Omega} X(\omega) P(d\omega).$$

We also define $\mathbb{E}(X) \leq \infty$ for $X \in (\mathbb{R}^d)^+$. In short, $\mathbb{E}(X) = P(X)$.

Definition 1.12. Let $Y \in L^1((\Sigma, \mathcal{F}, \mathbb{P}))$ and X be a random vector in \mathbb{R}^d . We define $z := \mathbb{E}[Y|X]$ is the unique² random v then:

- $z \in L^1(\Sigma, \sigma(x), \mathbb{P})$, where z is both integrable and σ - x -measurable.
- $\forall B \in \mathbb{B}(\mathbb{R}^d) \mathbb{E}(z \cdot \mathbf{1}\{x \in B\}) = \mathbb{E}(y \cdot \mathbf{1}\{x \in B\})$
- The second condition is true $\iff \mathbb{E}((y - z) \cdot \mathbf{1}\{x \in B\}) = 0 \iff \mathbb{E}((y - z) \cdot \Phi(x))$

Remark 1.5. z is $\sigma(x)$ measurable $\iff z = \varphi(x)$ for some $\varphi_i(\mathbb{R}^d, \mathbb{B}(\mathbb{R}^d)) \rightarrow (\mathbb{R}^d, \mathbb{B}(\mathbb{R}^d))$, which in words it means that z is a function of x which in turn is measurable.

Another definition we can find it in the book:

Definition 1.13 (Fundamental Theorem and Definition (Kolmogorov, 1933)). Let (Ω, \mathcal{F}, P) be a triple, and X a random variable with $\mathbb{E}(|X|) < \infty$. Let \mathcal{G} be a sub- σ -algebra of \mathcal{F} . Then there exists a random variable Y such that:

1. Y is \mathcal{G} -measurable,
2. $\mathbb{E}(|Y|) < \infty$,
3. for every set $G \in \mathcal{G}$ (equivalently, for every set G in some π -system which contains Ω and generates \mathcal{G}), we have

$$\int_G Y dP = \int_G X dP, \quad \forall G \in \mathcal{G}.$$

Moreover, if \tilde{Y} is another random variable with these properties, then $\tilde{Y} = Y$, a.s., that is, $P[\tilde{Y} = Y] = 1$. A random variable Y with properties (a) – (c) is called a version of the $\mathbb{E}(X | \mathcal{G})$ of X given \mathcal{G} , and we write $Y = \mathbb{E}(X | \mathcal{G})$, a.s.

Remark 1.6. There are two particular cases:

²unique means that if z and z' satisfy 1 and 2 $\implies z = z'$ a.s

1. $(y, x)'$ with discrete countable support, the definition then coincides with: $\mathbb{E}(Y|X = x) = \sum_{y_j \in \text{supp}_y} y_j \cdot \mathbb{P}(Y = y_j|X = x)$. If x is such that $\mathbb{P}(X = x) > 0$.
2. $(y, x)'$ and X have a density then $\mathbb{E}(y|X = x) = \int_{\mathbb{R}} y \cdot \frac{\{y, x\}}{\{x(x)\}} dy$

exercise Let X and B be random vectors in \mathbb{R}^d such that X and B are independent. Let $g : \mathbb{R}^d \mapsto \mathbb{R}$ be continuous and bounded and $Y = g(x'_i B_i)$, show that then $\mathbb{E}[Y|X = x] = \mathbb{E}[x'_i B_i] \forall x \in \text{supp}(X)$

Exercise: provide the proof of this properties.

1.2.1 Some properties of the conditional expectation function

Note: the idea of the proof of this properties can be found in pages 88 and 89 of the masterful book Probailities with martingales. The development and errors are due only to myself.

1. Let $Y \in L^1((\Sigma, \mathcal{F}, \mathbb{P}))^3$ then $\mathbb{E}[\mathbb{E}[y|x]] = \mathbb{E}[y]$.

Proof. By the definition of conditional expectation, $\mathbb{E}[Y|X]$ satisfies:

$$\int_A \mathbb{E}[Y|X] d\mathbb{P} = \int_A Y d\mathbb{P}, \quad \forall A \in \sigma(X).$$

Setting $A = \Omega$, we have:

$$\int_{\Omega} \mathbb{E}[Y|X] d\mathbb{P} = \int_{\Omega} Y d\mathbb{P}.$$

The left-hand side is $\mathbb{E}[\mathbb{E}[Y|X]]$, and the right-hand side is $\mathbb{E}[Y]$. Thus, we conclude:

$$\mathbb{E}[\mathbb{E}[Y|X]] = \mathbb{E}[Y].$$

□

2. Let $g(\mathbb{R}^d, \mathbb{B}(\mathbb{R}^d)) \rightarrow (\mathbb{R}^d, \mathbb{B}(\mathbb{R}^d))$ measurable such that $\mathbb{E}[g(x)] < \infty$ then $\mathbb{E}[g(x)|x] = g(x) a.s.$

Proof. From Remark 1.5, we know that a random variable Z is $\sigma(X)$ -measurable if and only if $Z = \varphi(X)$ for some measurable function $\varphi : (\mathbb{R}^d, \mathbb{B}(\mathbb{R}^d)) \rightarrow (\mathbb{R}^d, \mathbb{B}(\mathbb{R}^d))$.

Let $Z = g(X)$. By assumption, g is measurable and $\mathbb{E}[|g(X)|] < \infty$, so Z is $\sigma(X)$ -measurable.

It is a property of conditional expectation that if Z is $\sigma(X)$ -measurable and $\mathbb{E}[|Z|] < \infty$, then $\mathbb{E}[Z|X] = Z$ almost surely. Applying this property to $Z = g(X)$, we conclude:

$$\mathbb{E}[g(X)|X] = g(X) \quad \text{a.s.}$$

□

3. $\forall a_1, a_2 \in \mathbb{R}$ and $\mathbb{E}[|Y_1| + |Y_2|] < \infty$ then $\mathbb{E}[a_1 Y_1 + a_2 Y_2] = a_1 \mathbb{E}[Y_1] + a_2 \mathbb{E}[Y_2] a.s$

Proof. Given that $\mathbb{E}[|Y_1| + |Y_2|] < \infty$, the random variables Y_1 and Y_2 are integrable, and their conditional expectations are well-defined. Consider the random variable $a_1 Y_1 + a_2 Y_2$. By the definition of conditional expectation, we have:

$$\mathbb{E}[a_1 Y_1 + a_2 Y_2|X] = \int_A (a_1 Y_1 + a_2 Y_2) d\mathbb{P},$$

for all $A \in \sigma(X)$.

³we assume this throughout this exercise

Using the linearity of the integral, this can be expressed as:

$$\int_A (a_1 Y_1 + a_2 Y_2) d\mathbb{P} = \int_A a_1 Y_1 d\mathbb{P} + \int_A a_2 Y_2 d\mathbb{P}.$$

Taking the constants a_1 and a_2 outside their respective integrals, we get:

$$\mathbb{E}[a_1 Y_1 + a_2 Y_2 | X] = a_1 \int_A Y_1 d\mathbb{P} + a_2 \int_A Y_2 d\mathbb{P}.$$

By the definition of conditional expectation, this becomes:

$$\mathbb{E}[a_1 Y_1 + a_2 Y_2 | X] = a_1 \mathbb{E}[Y_1 | X] + a_2 \mathbb{E}[Y_2 | X].$$

Thus, the result follows:

$$\mathbb{E}[a_1 Y_1 + a_2 Y_2 | X] = a_1 \mathbb{E}[Y_1 | X] + a_2 \mathbb{E}[Y_2 | X] \quad \text{a.s.}$$

□

4. if $y \geq 0$ a.s then $\mathbb{E}[Y | X] \geq 0$ a.s.

Proof. Let $Z = \mathbb{E}[Y | X]$. Suppose $\mathbb{P}(Z < 0) > 0$. Then there exists $G := \{Z < -n^{-1}\}$ for some $n \in \mathbb{N}$ with $\mathbb{P}(G) > 0$ and $G \in \sigma(X)$. By the definition of conditional expectation:

$$\int_G Y d\mathbb{P} = \int_G Z d\mathbb{P}.$$

Since $Y \geq 0$ a.s., $\int_G Y d\mathbb{P} \geq 0$, but $\int_G Z d\mathbb{P} < -n^{-1} \mathbb{P}(G) < 0^4$, a contradiction. Thus, $\mathbb{P}(Z < 0) = 0$, so $Z \geq 0$ a.s. □

5. Let $c : \mathbb{R} \rightarrow \mathbb{R}$ be a convex function such that $\mathbb{E}[|c(y)|] < \infty$ then $\mathbb{E}[c(y) | x] \geq c[\mathbb{E}[y | x]]$ a.s.

We will use the following definition - which requires that function c is continuous (6.6.a in Williams): $c(x) = \sup_{q \in G} [D_{-c}(q)(x - q) + c(q)] = \sup_n (a_n x + b_n)$ for some sequences in $a_n b_n \in \mathbb{R}^5$.

Proof. If we apply this definition to this problem we know that $c(x) = \sup_n (a_n x + b_n)$ and $c(x) \geq (a_n x + b_n)$ for a fixed $n \in \mathbb{N}$. Then we take expectations in both sides: $\mathbb{E}(c(x) | \zeta) \geq (a_n \mathbb{E}(x | \zeta) + b_n)$, where $\zeta \in \sigma(x)$. Then for all n , this is also true by countability property⁶: $\mathbb{E}(c(x) | \zeta) \geq \sup_n (a_n \mathbb{E}(x | \zeta) + b_n) = c(\mathbb{E}(x | \zeta))$. □

6. Let \mathcal{H}, ξ be the sigma-algebra and that $\mathcal{H} \subset \xi$. Then $\mathbb{E}[\mathbb{E}[y | \xi] | \mathcal{H}] = \mathbb{E}[Y | \mathcal{H}]$ a.s.

⁴Since $Z(\omega) \leq -n^{-1}$ for all $\omega \in G$, it follows that $Z(\omega) \leq -n^{-1}$ on G . Therefore, the integral satisfies:

$$\int_G Z d\mathbb{P} \leq \int_G (-n^{-1}) d\mathbb{P} = -n^{-1} \mathbb{P}(G).$$

⁵The definition expresses $c(x)$ as the supremum of affine functions $a_n x + b_n$ for sequences a_n and b_n , which correspond to the subgradients $D_{-c}(q_n)$ and values $c(q_n)$ at points q_n . This means that $c(x)$ can be constructed as the pointwise upper bound of all linear approximations of the function based on its subgradients at various points. Intuitively, each linear function $a_n x + b_n$ is a "supporting hyperplane" to the convex function at a specific point, and the supremum ensures that $c(x)$ is the tightest convex function that satisfies these inequalities.

⁶The countability property allows the supremum over all $n \in \mathbb{N}$ to replace the fixed n case, ensuring the inequality applies to the entire sequence.

Proof. By the definition of conditional expectation, $\mathbb{E}[Y|\xi]$ satisfies $\int_A \mathbb{E}[Y|\xi] d\mathbb{P} = \int_A Y d\mathbb{P}$ for all $A \in \xi$. Now consider $\mathbb{E}[\mathbb{E}[Y|\xi]|\mathcal{H}]$. By the definition of conditional expectation, for any $B \in \mathcal{H}$,

$$\int_B \mathbb{E}[\mathbb{E}[Y|\xi]|\mathcal{H}] d\mathbb{P} = \int_B \mathbb{E}[Y|\xi] d\mathbb{P}.$$

Since $\mathcal{H} \subset \xi$, every $B \in \mathcal{H}$ is also in ξ , so we have

$$\int_B \mathbb{E}[Y|\xi] d\mathbb{P} = \int_B Y d\mathbb{P}.$$

Thus, by the uniqueness of conditional expectation, $\mathbb{E}[\mathbb{E}[Y|\xi]|\mathcal{H}] = \mathbb{E}[Y|\mathcal{H}]$ almost surely. \square

7. Let z be a bounded random variable (i.e. $\exists M \in \mathbb{R} : |z| \leq M$ a.s.) that is y measurable. Then $\mathbb{E}[zy|\xi] = z\mathbb{E}[y|\xi]$ a.s. ⁷

Proof. Fix $G \in \xi$ and let $W = \mathbb{E}[Y|\xi]$. We aim to prove that

$$\mathbb{E}[ZY | G] = \mathbb{E}[Z \cdot W | G].$$

If Z is the indicator function of a set $A \in \xi$, then by the definition of conditional expectation, the result holds:

$$\mathbb{E}[\mathbf{1}_A Y | G] = \mathbf{1}_A \mathbb{E}[Y | G].$$

Linearity of the conditional expectation implies that the result holds for any simple function $Z \in SF^+(\Omega, \xi, \mathbb{P})$. By the monotone convergence theorem⁸, the result extends to non-negative, ξ -measurable random variables. Finally, for a general bounded ξ -measurable random variable Z , we decompose Z into positive and negative parts and apply linearity (proof given above). Thus, the property is proven. \square

Remark 1.7. If $z \in L^p(\Sigma, \xi, \mathbb{P})$ and $y \in L^q((\Sigma, \mathcal{F}, \mathbb{P}))$ where $\xi \subset \Sigma$ and $\frac{1}{p} + \frac{1}{q} = 1$ and $p, q \geq 1$ then $\mathbb{E}[zy|\xi] = z\mathbb{E}[y|\xi]$ a.s.

This is an application of the **Hölder inequality**, which is defined as follows: $\mathbb{E}[|zy|] \leq \mathbb{E}[|z|^p]^{\frac{1}{p}} \mathbb{E}[|y|^q]^{\frac{1}{q}}$ and this is defined $\forall p, q \geq 0 : \frac{1}{p} + \frac{1}{q} = 1$ ⁹

1.3 Some notes on identification (from lecture 2)

Data consists of draws from $\mathbb{P}_{y,x}$ where y and x are vectors that are observed by the econometrician. X is determined outside the model. **A structural econometrics model** consists of:

1. An equation $v(y, \gamma, X, \epsilon; \zeta) = 0$ where v is a vector of functions, γ is a vector of unobserved variables determined inside the model, ϵ unobserved variables determined outside the model and ζ which corresponds vector's function distribution??? **check notes because this makes little sense to me**
2. Restriction: $\zeta \in \mathcal{R}$: for example, then our draw would be $\mathbb{P}_{y,x;\zeta}$ is the distribution of observables generated by ζ .

Example 1.4. 1. $Y = f(X) + \epsilon$, where $\Sigma = \{f, P_X, \epsilon\}$. This is a type of regression.

2. $\mathbb{E}[|f(X)| + |\epsilon|] < \infty$, and $\mathbb{E}[\epsilon | X] = 0$, with f continuous on $\text{supp}(X)$.

In this case, we have:

$$\mathbb{E}[Y | X] = \mathbb{E}[f(X) | X] + \mathbb{E}[\epsilon | X] = f(X),$$

where f is the conditional expectation function (i.e., the regression function).

⁷this is taken from the glorious book that was recommended in class

⁸if $X_n \geq 0$ then if $\mathbb{E}(X_n|\zeta)$ increases, $\mathbb{E}(X_n|\zeta)$ also increases.

⁹when $p=q=2$ this is the Cauchy-Schwarz inequality.

Example 1.5. 1. $Y = f(X) + \varepsilon$, where $\Sigma = \{f, P_{X,Z,\varepsilon}\}$, and the distribution of the observed data is $P_{Y,X,Z}$. Here, Z is determined outside the model.

2. $\mathbb{E}(|f(X)| + |\varepsilon|) < \infty$, $\mathbb{E}[\varepsilon | Z] = 0$, and f is continuous on $\text{supp}(X)$, with additional restrictions.

Example 1.6. We have these two equations:

$$1. Y_1 = \alpha_{12}Y_2 + g_1(X_1) + \varepsilon_1,$$

$$2. Y_2 = \alpha_{21}Y_1 + g_2(X_2) + \varepsilon_2,$$

where:

$$X = \begin{pmatrix} X_1 \\ X_2 \end{pmatrix}, \quad \varepsilon = \begin{pmatrix} \varepsilon_1 \\ \varepsilon_2 \end{pmatrix}, \quad Y = \begin{pmatrix} Y_1 \\ Y_2 \end{pmatrix},$$

and $\alpha_{12}, \alpha_{21} \in \mathbb{R}$, while g_1 and g_2 are unknown functions.

The model can be written as:

$$\gamma(Y, \gamma, X, \varepsilon, \zeta) = 0,$$

where $\zeta = \begin{pmatrix} \alpha_{12} \\ \alpha_{21} \\ g_1 \\ g_2 \\ P_{X,\varepsilon} \end{pmatrix}$ and explicitly:

$$\gamma = \begin{pmatrix} \alpha_{12}Y_2 + g_1(X_1) + \varepsilon_1 - Y_1 \\ \alpha_{21}Y_1 + g_2(X_2) + \varepsilon_2 - Y_2 \end{pmatrix} = 0$$

Case 2: If α_{12} and α_{21} are random, then we can assume ε satisfies one of the following restrictions:

$$\mathbb{E}[\varepsilon | X] = 0, \quad \mathbb{E}[\Sigma | X] = 0, \quad \text{or} \quad \varepsilon \perp X.$$

And now the parameters are where $\zeta = \begin{pmatrix} g_1 \\ g_2 \\ P_{X,\varepsilon} \end{pmatrix}$ $\varepsilon = \begin{pmatrix} \alpha_{12} \\ g_{21} \\ \varepsilon_1 \\ \varepsilon_2 \end{pmatrix}$

Case 3: If $\gamma = \begin{pmatrix} \alpha_{12} \\ \alpha_{21} \end{pmatrix}$, we can be in a setup where the distribution of the observed data is $P_{Y,X,Z}$ and the assumptions $Z \perp Y$ hold in \mathbb{R} .

Example 1.7. This is an example of non-parametric IV that was used by the professor, with not much success, to introduce and convey in us a passion for the assumption of completeness:

1. $Y_1 = f(x) + \epsilon$ and the distribution of the observed data is $\mathbb{P}_{y,x,z}$. We are interested in $\varphi = f$.

2. Restrictions:

- f is continuous on the $\text{supp}(x)$.
- $\mathbb{E}[|f(x)| + |\epsilon|] < \infty$
- $\mathbb{E}[\epsilon | z] = 0$
- **Completeness:** if φ is continuous in the $\text{supp}(x)$ s.t $\mathbb{E}|\varphi(x)| < \infty$ then $\mathbb{E}(\varphi(x)|z) = 0 \implies x \in \text{supp}(x), \varphi(x) = 0$.

Example 1.8. Exercise 4.1 $(x', z')'$ has a finite support such that $\text{supp}(x) = \{x_1, \dots, x_k\}$ and $\text{supp}(z) = \{z_1, \dots, z_l\}$ then show that $\mathbb{E}[\varphi(x)|z = z_l] = 0$.

We can define $\mathbb{E}[\varphi(x)|z = z_l] = \sum_{k=1}^k \varphi(x_k) \mathbb{P}(x = x_k | z = z_l)$. This is equal to 0 iff $\varphi \cdot M_{k,l} = 0$, we can apply the rank theorem¹⁰ to show that this holds only if the k vector φ is equal to 0.

Exercise 4.2 In this exercise we are interested in finding a sufficient condition under which completeness holds. **To complete in another occasion**

¹⁰ $\dim \ker(\mu) + \text{rank}(\mu) = k$

Example 1.9. Let x, β be two random variables in \mathbb{R}^d s.t $x \perp \beta$. Let $g : \mathbb{R}^d \rightarrow \mathbb{R}$ be continuous and bounded. We define $y = g(x'\beta)$, we need to show that $\mathbb{E}(y|X = x) = \mathbb{E}[g(x'\beta)]$. For simplicity we define $\varphi(x) = g(x'\beta)$. The argument needs to proof these two points:

1. $\varphi(x) \in L^1((\Sigma, \mathcal{F}, \mathbb{P}))$. The function is x -measurable.
2. Let $B \in \mathbb{B}(\mathbb{R}^d)$, then $\mathbb{E}[y \mathbf{1}\{x \in B\}] = \mathbb{E}[\mathbb{E}[g(x'\beta)] \mathbf{1}\{x \in B\}]$.

To verify the first point, by definition:

$$\varphi(x) = \int_{\mathbb{R}^d} g(x'\beta) d\mathbb{P}_\beta(b).$$

Since g is continuous and bounded, $g(x'\beta)$ is continuous as a function of x . The integral of a continuous function over β is also continuous in x . This implies that $\varphi(x)$ is a continuous function of x , and thus $\varphi^{-1}(C)$ is in $\mathbb{B}(\mathbb{R}^d)$. Hence, $\varphi(x)$ is measurable.

For the second part, consider $\mathbb{E}_{x,\beta}[g(x'\beta)\mathbf{1}\{x \in B\}]$, where $B \in \mathbb{B}(\mathbb{R}^d)$. By the definition of joint expectation:

$$\mathbb{E}[g(x'\beta)\mathbf{1}\{x \in B\}] = \int_{\mathbb{R}^d} \int_{\mathbb{R}^d} g(x'\beta)\mathbf{1}\{x \in B\} d\mathbb{P}_x(x) d\mathbb{P}_\beta(b).$$

Here, the independence of x and β plays a critical role. Independence implies that the joint probability measure $d\mathbb{P}_{x,\beta}(x, b)$ can be written as $d\mathbb{P}_x(x) \cdot d\mathbb{P}_\beta(b)$. This factorization allows us to separate the expectation as:

$$\int_{\mathbb{R}^d} \int_{\mathbb{R}^d} g(x'\beta)\mathbf{1}\{x \in B\} d\mathbb{P}_x(x) d\mathbb{P}_\beta(b).$$

Using Fubini's theorem¹¹, we can swap the order of integration:

$$\int_{\mathbb{R}^d} \int_{\mathbb{R}^d} g(x'\beta)\mathbf{1}\{x \in B\} d\mathbb{P}_\beta(b) d\mathbb{P}_x(x).$$

The inner integral depends only on β , and the outer integral captures the expectation over x . The outer integral then accounts for the distribution of x , weighted by $\mathbf{1}\{x \in B\}$.

By evaluating the inner integral, it follows that:

$$\mathbb{E}[g(x'\beta)\mathbf{1}\{x \in B\}] = \mathbb{E}[\mathbb{E}[g(x'\beta)]\mathbf{1}\{x \in B\}],$$

which completes the proof.

1.3.1 Definitions of Identification

We often care about $\Psi^* = \Psi(\zeta)$ for a certain $\Psi : \mathcal{R} \rightarrow \zeta$.

Remark 1.8. $\Gamma_{Y,X}(\Psi, \mathcal{R}) = \{P_{Y,X,\zeta} \mid \zeta \in \mathcal{R}, \Psi(\zeta) = \Psi^*\}$. It is the set of all distributions of the observables generated by ζ consistent with \mathcal{R} and Ψ .

Definition 1.14. Let $\Psi, \Psi' \in \zeta$. Ψ and Ψ' are directionally equivalent if: $\Gamma_{Y,X}(\Psi, \mathcal{R}) \cap \Gamma_{Y,X}(\Psi', \mathcal{R}) \neq \emptyset$.

Definition 1.15. Ψ^* is identified in model (\mathcal{R}) if:

$$\forall \Psi \in \zeta, \quad \Gamma_{Y,X}(\Psi, \mathcal{R}) \cap \Gamma_{Y,X}(\Psi^*, \mathcal{R}) \neq \emptyset \implies \Psi = \Psi^*.$$

¹¹This step is valid because the integrand $g(x'\beta)\mathbf{1}\{x \in B\}$ is bounded and the measures \mathbb{P}_x and \mathbb{P}_β are finite.

1.3.2 Completeness (from class 4)

Suppose (x, z) has a density and we define $x = z - \eta$ where $z \perp \eta$ and z and η have densities. We may think of x as miss-measured. Completeness in this situation can be defined as: $\forall \varphi$ continuous such that $\forall z \in \mathbb{R}$:

$$\int f_\eta(z - x)\varphi(x)dx = 0 \implies \forall x \varphi(x) = 0$$

Example 1.10. Example (Economic Context):

Suppose we are interested in estimating a structural model where the true relationship is:

$$y = \beta x + \epsilon,$$

but the observed covariate $z = x + \eta$ is a mismeasured version of x , where η represents classical measurement error. Here, z is the observed variable, and x and η are unobserved. To identify β , we often rely on an instrumental variable w that satisfies the following conditions: 1. $w \perp \epsilon$ (instrument exogeneity), 2. $w \not\perp x$ (relevance), 3. $w \perp \eta$ (independence from the measurement error).

Completeness plays a role in ensuring that x can be uniquely identified from the joint distribution of (z, w) . Specifically, the completeness assumption can be formulated as follows:

Let $\varphi(x)$ be any measurable function such that:

$$\mathbb{E}[\varphi(x) \mid z, w] = 0 \quad \text{a.s.}$$

Completeness implies that $\varphi(x) = 0$ almost surely. This ensures that no non-trivial function of x is orthogonal to all functions of (z, w) , thereby allowing x to be fully recovered from the observed data (z, w) .

Why is this important?

Without completeness, the conditional expectation $\mathbb{E}[y \mid z, w]$ might not provide unique information about x , leading to non-identification of the structural parameter β . Completeness guarantees that the instrument w and the observed covariate z together contain enough information to uniquely identify the true signal x .

Connection to Measurement Error:

In the classical measurement error setting, we have:

$$z = x + \eta,$$

where $\eta \perp x$. The density $f_\eta(z - x)$ "smooths out" the true x , making it harder to identify without additional information (e.g., from an IV). Completeness ensures that the mapping $M : \varphi \mapsto (z \mapsto \int f_\eta(z - x)\varphi(x)dx)$ is injective, preventing loss of information about x .

Remark 1.9. Completeness $\iff M$ is injective, where $M : \varphi \mapsto x \mapsto \int f_\eta(z - x)\varphi(x)dx$. f is injective if $f(x) = f(y) \implies x = y$. If f is linear, checking $f(0) = 0$ is enough to check $f(x) = 0 \implies x = 0$.

Remark 1.10. What is the density of $z + \eta$ when $z \perp \eta$ and z and η have a density? Let $B \in \mathbb{B}(\mathbb{R})$ then $\mathbb{P}(z + \eta) \in B = \int_{\mathbb{R}^2} \mathbf{1}(z + \epsilon \in B) d\mathbb{P}_{z, \eta}$, which by independence assumption is the same as: $\int_{\mathbb{R}^2} \mathbf{1}(z + \epsilon \in B) f_z(z) f_\eta(\eta) dz d\eta$. If we let $u = z + \epsilon$ then we can express this integral as: $\int_{\mathbb{R}^2} \mathbf{1}(u \in B) f_\eta(u - z) f_z(z) du dz$ where we have also applied Fubini to reverse the order of integration. Finally, we can rewrite the last expression as this: $\int_{\mathbb{R}^2} \mathbf{1}(u \in B) \int_{\mathbb{R}} f_\eta(u - z) f_z(z) dz du$ where $\int_{\mathbb{R}} f_\eta(u - z) f_z(z) dz = f_{z+\eta}(u)$ by definition.

Definition 1.16. Characteristic Function: The characteristic function of a random vector x is defined as:

$$\phi_x(t) = \mathbb{E}[\exp(it'x)],$$

where $i^2 = -1$ and $\exp(it) = \cos(t) + i \sin(t)$.

Applying the characteristic function to the previous exercise, we find:

$$\mathbb{E}[\exp(it(z + \eta))] = \mathbb{E}[\exp(itz)] \cdot \mathbb{E}[\exp(it\eta)],$$

because z and η are independent. This simplifies a potentially complex integral into a product of two simpler terms, making it significantly easier to work with.

The characteristic function is useful because it relates expectations to the underlying distributions. Specifically:

$$\mathbb{E}[\exp(itx)] = \mathbb{E}[\exp(itz)] \varphi(t).$$

This allows us to estimate:

$$\mathbb{E}[\exp(itz)] = \frac{\hat{\varphi}(itx)}{\hat{\varphi}(t)}.$$

This relationship demonstrates how characteristic functions can simplify inference problems, particularly when working with convolution or noisy data.

Note: This is the last example where convolution and characteristic functions are specifically useful in our econometric applications.

Example 1.11. Consider the following model:

1. $y_i = x_i' \beta_i + \epsilon_i$,
2. $x_i \perp (\beta_i', \epsilon_i)$.

One feature of interest in this model is f_{β_i} , the distribution of β_i (e.g., to study the distributional effects of a treatment). The distribution f_{β_i} can be expressed as:

$$f_{\beta_i} = \int_{\mathbb{R}^{d-1}} f_{\beta}(b) db_2 \cdots db_d,$$

where d is the dimension of β_i .

Alternatively, this distribution can be estimated using the characteristic function. For a given $t \in \mathbb{R}$, we have:

$$\mathbb{E}[\exp(itx) \mid X = x] = \mathbb{E}[\exp(i(\beta' tx + t\epsilon))].$$

This equality follows because $\mathbb{E}[\exp(itx) \mid X = x]$ is the characteristic function of $(\beta', \epsilon)'$ evaluated at (tx, t) .

Exercise: As a suggested exercise, prove the equality above. Hint: Consider how the independence assumption $x_i \perp (\beta_i', \epsilon_i)$ simplifies the decomposition of the expectation. Good luck!

Definition 1.17. $L^p(\mathbb{R}^d) = (\text{measurable functions from } (\mathbb{R}^d, B(\mathbb{R}^d)) \text{ to } (\mathbb{R}, B(\mathbb{R}))) : \int_{\mathbb{R}^d} |f(x)| dx < \infty$

Remark 1.11. we can also have the following mapping: $(\mathbb{R}^d, B(\mathbb{R}^d)) \mapsto (\mathbf{C}, B(\mathbf{C}))$

Definition 1.18. If $f \in L^1(\mathbb{R}^d)$ the Fourier transform of f $F[f]$ is obtained as $\forall \omega \in \mathbb{R}^d$, $F(f)(\omega) = \int_{\mathbb{R}^d} \exp(i\omega' x) f(x) dx$.

Definition 1.19. If f and g belong to $L^1(\mathbb{R}^d)$, then the **convolution** of f and g , denoted $(f * g)(z) = \int_{\mathbb{R}^d} f(x) g(z - x) dx$.

Remark 1.12. The previous expression is also equal to $\int_{\mathbb{R}^d} f(z - x) g(x) dx$ by change of variables.

Proposition 1.1. If f and g belong to $L^1(\mathbb{R}^d) \implies (f * g)(z) \in L^1(\mathbb{R}^d)$ and $F[f * g](\omega) = F[f](\omega) F[g](\omega)$

Proposition 1.2. if f belong to $L^1(\mathbb{R}^d) \implies F[f]$ is continuous at $\lim_{\|\omega\|_2 \rightarrow \infty} F(f)(\omega) = 0$

Example 1.12. Gaussian Kernel: let $k(x) = \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{x^2}{2}\right)$ then given that $k \in L^1(\mathbb{R}^d)$ and $F[k](\omega) = \exp\left(-\frac{\omega^2}{2}\right)$ is positive

Example 1.13. Box function: Let $k(x) = \frac{1}{2} \mathbf{1}[|x| \leq 1]$ then if $k \in L^1$ and $F[k](\omega) = \frac{1}{2} \int_{-1}^1 \cos(\omega x) dx + \frac{i}{2} \int_{-1}^1 \sin(\omega x) dx$. Where the second integral is 0 and so this becomes: $\frac{1}{2\omega} [\sin(\omega x)]_{-1}^1$.

1.3.3 Properties of the Fourier transform

Suppose f and $F[f]$ belong to L^1 and to $L^{2^{12}}$. Then, the following properties apply:

1. **Plancherel equality:** $\frac{1}{(2\pi)^d} \|F(f)\|_2^2 = \|f\|_2^2$ by Cauchy-Schwarz.
2. **Fourier's inversion formula:** $\forall x \in \mathbb{R}^d, f(x) = \frac{1}{(2\pi)^d} F[F(f)](-x) = \frac{1}{(2\pi)^d} \int_{\mathbb{R}^d} e^{-iw'x} F[f](w) dw$

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Some more notes to motivate completeness, as a titanic effort made by the professor to generate some enthusiasm in class.

Proposition 1.3. *Let φ be a continuous function such that $\varphi \in L^1$, $x = z - \eta$, $z \perp \eta$, and we assume that η has a density. Then $\forall z \in \mathbb{R} \int_{\mathbb{R}} \varphi(x) f_\eta(z - x) dx = 0 \implies \forall x \in \mathbb{R} \varphi(x) = 0$.*

This result shows that the interaction between $\varphi(x)$ and $f_\eta(x)$ vanishes entirely for all z . The convolution integral being zero everywhere implies that $\varphi(x)$ has no "effect" in the domain, forcing it to be identically zero. Completeness ensures no non-zero $\varphi(x)$ can "hide" under such conditions.

Also, $\int_{\mathbb{R}} \varphi(x) f_\eta(z - x) dx = 0 \implies F[\varphi](\omega) F[f_\eta](\omega) = F[0] = 0 \forall \omega$ by properties of the Fourier transform defined above.

By the convolution theorem, the Fourier transform of the convolution is the product of the transforms. If this product is zero, and $F[f_\eta](\omega) \neq 0$, then $F[\varphi](\omega)$ must be zero for all ω . This directly implies $\varphi(x)$ is zero everywhere, given the Fourier transform uniquely determines a function.

Example 1.14. f_η is the density of a mean-zero random variable. Then $[f_\eta](\omega) > 0 \forall \omega$.

The Fourier transform of a mean-zero density does not vanish anywhere, ensuring that any $\varphi(x)$ convolved with $f_\eta(x)$ will reflect entirely in the product $F[\varphi](\omega) F[f_\eta](\omega)$. If $F[\varphi](\omega) = 0$, this enforces that $\varphi(x)$ is zero everywhere.

This implies that $\forall \omega F[\varphi](\omega) = 0 \implies F[\varphi] = 0$. So $\varphi' = 0$ almost everywhere. But given that $\varphi(x)$ is continuous, then $\varphi(x) = 0$.

Example 1.15. $F[f_\eta](w) = \frac{\sin(w)}{w}$, $\forall w \in \mathbb{R}$. Here we also have that $\eta \sim U[-1, 1]$.

Intuition: For the uniform distribution on $[-1, 1]$, the Fourier transform $F[f_\eta](\omega)$ has zeros at $\omega = k\pi$ for $k \in \mathbb{Z} \setminus \{0\}$, corresponding to points where $\sin(w) = 0$.

Let $\zeta = [f_k, k \in \mathbb{Z}]$ be the set of zeros of $F[f_\eta]$. Then by the second property of the previous theorem, $\forall \omega \in \mathbb{R} \setminus \zeta, F[\varphi](\omega) = 0$.

Outside the zeros of $F[f_\eta](\omega)$, the Fourier transform forces $F[\varphi](\omega) = 0$. Continuity of $F[\varphi](\omega)$ ensures this behavior extends across all ω .

Or, similarly, let $\omega = k\pi$ for some $h \in \mathbb{Z}$ and $(\omega_n)_{n \in \mathbb{N}}$ a sequence in $\mathbb{R} \setminus \zeta$ such that $\omega_n \rightarrow \omega$. Because $F[\varphi]$ is continuous, then $\lim_{n \rightarrow \infty} F[\varphi](\omega_n) = F[\varphi](\omega)$. Hence $\forall \omega F[\varphi] = 0$, and we can conclude using a similar argument as before that $\varphi(x) = 0$.

This shows that the zeros of $F[f_\eta]$ do not allow $\varphi(x)$ to escape the conclusion of being identically zero. Continuity bridges gaps at points of zero, solidifying the result.

¹²Important to notice that if we talk about r.v then if $x \in L^2 \subseteq L^1$. This does not apply to functions belonging in L^1 .

2 Non-Parametric Estimation

2.1 Density estimation (Lebesgue)

Let x_1, \dots, x_n be identically distributed random variables. Imagine we want to estimate the density f_x of x which we assume to lie in a large class of densities...

Example 2.1. We have two examples:

1. Densities such that $\forall x, x' \in \mathbb{R}, |f_x(x) - f_x(x')| \geq L|x - x'|$ for a certain $L > 0$.
2. Densities which are monothically increasing on $[\theta, 1]$

A nonparametric estimator is the histogram. Assume $f_x : [0, 1] \mapsto \mathbb{R}$ and divide $[0, 1]$ into non-overlapping intervals that we denote $(A_j)_{j=1}^m$ of length h . We define $n_j = \sum_{i=1}^n \mathbf{1}\{x \in A_j\}$. Then the histogram estimator is just $f_x(x) = \sum_{j=1}^m \frac{n_j}{n \cdot h} \mathbf{1}\{x \in A_j\}$ which depends on h (we want the smaller h as possible...). Then we also have this expression: $f_x(x) = \sum_{j=1}^m \frac{n_j}{n \cdot h} \mathbf{1}\{x \in A_j\} = \frac{1}{n \cdot h} \sum_{i=1}^n \sum_{j=1}^m \mathbf{1}\{x_i \in A_j; X \in A_j\}$

Definition 2.1. Kernel Density estimator Let $k \in L^1(\mathbb{R})$ s.t $\int_{\mathbb{R}} K(u)du = 1$ and $\hat{f}_x(x) = \frac{1}{nh} \sum_{i=1}^m K\left(\frac{X_i - X}{n}\right)$ is called a kernel density estimator with kernel k and bandwidth h .

Example 2.2. We can start with an estimator of the cdf. Let's for example define f_x of x as $F_x(x) = \mathbb{E}[\mathbf{1}\{x_i \leq x\}]$, then $\hat{F}_x(x) = \frac{1}{n} \sum_{i=1}^n \mathbf{1}\{x_i \leq x\}$. We define f_x as the pdf. $\hat{f}_x(x) = \frac{\hat{F}_x(x + \frac{h}{2}) - \hat{F}_x(x - \frac{h}{2})}{h}$ for a given $h > 0$. This is equal to this expression: $\frac{1}{nh} \sum_{i=1}^n \mathbf{1}\{x - \frac{h}{2} < x_i \leq x + \frac{h}{2}\}$. This function is a generalization of the Rosenblatt estimator. For example, we have the following expression:

Remark 2.1. If we take expectation of the Kernel function we have the following expression: $\mathbb{E}(\hat{f}_x(x)) = \frac{1}{hn} \sum_{\mathbb{R}} \mathbb{E}(k(\frac{x_i - x}{h})) = \frac{1}{h} \mathbb{E}(k(\frac{x_i - x}{h})) = \frac{1}{h} \int_{\mathbb{R}} (\frac{y - x}{h}) f_x(y) dy$

Some examples of Kernels are given in the class notes, but are omitted here for brevity.

2.1.1 Mean squared error of kernel estimators

This definition is taken directly from the book by Tsybakov A basic measure of the accuracy of estimator \hat{p}_n is its *mean squared risk* (or *mean squared error*) at an arbitrary fixed point $x_0 \in \mathbb{R}$:

$$\text{MSE} = \text{MSE}(x_0) \triangleq \mathbb{E}_p \left[(\hat{p}_n(x_0) - p(x_0))^2 \right].$$

Here, MSE stands for “mean squared error” and \mathbb{E}_p denotes the expectation with respect to the distribution of (X_1, \dots, X_n) :

$$\mathbb{E}_p \left[(\hat{p}_n(x_0) - p(x_0))^2 \right] \triangleq \int \dots \int (\hat{p}_n(x_0, x_1, \dots, x_n) - p(x_0))^2 \prod_{i=1}^n [p(x_i) dx_i].$$

We have

$$\text{MSE} = b^2(x_0) + \sigma^2(x_0) \tag{1.4}$$

where¹³

$$b(x_0) = \mathbb{E}_p[\hat{p}_n(x_0)] - p(x_0)$$

and

$$\sigma^2(x_0) = \mathbb{E}_p \left[(\hat{p}_n(x_0) - \mathbb{E}_p[\hat{p}_n(x_0)])^2 \right].$$

¹³this is found by plugging in $\mathbb{E}(\hat{f}_n)$ inside the first equations and developing.

Definition 2.2. The quantities $b(x_0)$ and $\sigma^2(x_0)$ are called the bias and the variance of the estimator \hat{p}_n at a point x_0 , respectively.

The quantities $b(x_0)$ and $\sigma^2(x_0)$ are called the bias and the variance of the estimator \hat{p}_n at a point x_0 , respectively.

We will develop here the same reasoning that was developed in the TD.

Bounds of the bias

We have the following expression for the bias:

$$b(x_0) = \mathbb{E} \left(\hat{f}'_n(x_0) \right) - f'(x_0).$$

Using the definition of the kernel estimator, we write:

$$b(x_0) = \mathbb{E} \left[-\frac{1}{nh^2} \sum_{i=1}^n k' \left(\frac{x_i - x_0}{h} \right) \right] - f'(x_0).$$

Since the observations x_i are i.i.d., the expression simplifies to:

$$b(x_0) = -\frac{1}{h^2} \mathbb{E} \left[k' \left(\frac{x_i - x_0}{h} \right) \right] - f'(x_0).$$

Now, applying the definition of expectation, we have:

$$b(x_0) = \int_{\mathbb{R}} -\frac{1}{h^2} k' \left(\frac{z - x_0}{h} \right) f(z) dz - f'(x_0).$$

Using integration by parts for the term $\int_{\mathbb{R}} k' \left(\frac{z - x_0}{h} \right) f(z) dz$, we recall the integration by parts formula:

$$\int u dv = uv \Big|_{-\infty}^{+\infty} - \int v du,$$

and set: $u = f(z)$, so $du = f'(z) dz$, $dv = k' \left(\frac{z - x_0}{h} \right) dz$, so $v = k \left(\frac{z - x_0}{h} \right) \cdot \frac{1}{h}$.

Thus, the integral becomes:

$$\int_{\mathbb{R}} k' \left(\frac{z - x_0}{h} \right) f(z) dz = \left[f(z) \cdot k \left(\frac{z - x_0}{h} \right) \cdot \frac{1}{h} \right]_{-\infty}^{+\infty} - \int_{\mathbb{R}} k \left(\frac{z - x_0}{h} \right) \cdot \frac{1}{h} f'(z) dz.$$

Substituting this result back:

$$b(x_0) = -\frac{1}{h^2} \cdot h \cdot f(z) \cdot k \left(\frac{z - x_0}{h} \right) \Big|_{-\infty}^{+\infty} - \frac{1}{h^2} \cdot h \int_{\mathbb{R}} k \left(\frac{z - x_0}{h} \right) f'(z) dz - f'(x_0).$$

The first term vanishes because the kernel k and the function $f(z)$ are assumed to decay sufficiently fast at infinity, i.e.,

$$\lim_{z \rightarrow \pm\infty} f(z) \cdot k \left(\frac{z - x_0}{h} \right) = 0.$$

Thus, the bias simplifies to:

$$b(x_0) = -\frac{1}{h^2} \cdot h \int_{\mathbb{R}} k' \left(\frac{z - x_0}{h} \right) f'(z) dz - f'(x_0).$$

Now we define $\mu = \frac{z - x_0}{h}$, so that $z = \mu h + x_0$ and $dz = h \cdot d\mu$. Replacing these in the previous expression, we obtain:

$$b(x_0) = -\frac{1}{n} \int_{\mathbb{R}} h \cdot k(\mu) \cdot f'(\mu h + x_0) d\mu - f'(x_0).$$

Using the Taylor expansion for $f'(\mu h + x_0)$ around x_0 , we write:

$$f'(\mu h + x_0) = f'(x_0) + f''(x_0)\mu h + \frac{f'''(x_0)}{2!}(\mu h)^2 + \dots + \frac{f^{(l)}(x_0 + \tau\mu h)}{(l-1)!}(\mu h)^{l-1},$$

where $\tau \in (0, 1)$. Substituting this expansion into the integral gives:

$$b(x_0) = \int_{\mathbb{R}} k(\mu) \left[f'(x_0) + f''(x_0)\mu h + \frac{f'''(x_0)}{2!}(\mu h)^2 + \dots + \frac{f^{(l)}(x_0 + \tau\mu h)}{(l-1)!}(\mu h)^{l-1} \right] d\mu - f'(x_0).$$

Using the property of the kernel function that $\int_{\mathbb{R}} \mu^s k(\mu) d\mu = 0$ for all $s = 1, \dots, l-1$ (where l is the order of the kernel), we simplify the expression to:

$$b(x_0) = \int_{\mathbb{R}} k(\mu) \cdot \frac{f^{(l)}(x_0 + \tau\mu h)}{(l-1)!}(\mu h)^{l-1} d\mu.$$

Now we introduce the Hölder condition for the function f . A function f belongs to the Hölder class of order (l) if:

$$|f^{(l)}(x) - f^{(l)}(x')| \leq L|x - x'|^{\beta-l},$$

which conveys that the norm is bounded and provides information on the smoothness of the function. Using this, we write:

$$b(x_0) = \int_{\mathbb{R}} k(\mu) \left[f^{(l)}(x_0 + \tau\mu h) - f^{(l)}(x_0) \right] \cdot \frac{(\mu h)^{l-1}}{(l-1)!} d\mu.$$

By the triangle inequality, we have:

$$\leq \int_{\mathbb{R}} |k(\mu)| \cdot \left| f^{(l)}(x_0 + \tau\mu h) - f^{(l)}(x_0) \right| \cdot \frac{(\mu h)^{l-1}}{(l-1)!} d\mu.$$

By the Hölder condition:

$$\leq L(\tau\mu h)^{\beta-l}.$$

Thus:

$$b(x_0) < \int_{\mathbb{R}} |k(\mu)| \cdot L(\mu h)^{\beta-l} \cdot \frac{(\mu h)^{l-1}}{(l-1)!} d\mu.$$

Finally, we simplify:

$$b(x_0) = C_1 \cdot h^{\beta-1},$$

where C_1 is a constant depending on the kernel function and L .

Bound of the Variance

This is somewhat easier to show. Again, we start with the initial definition of the variance:

$$\text{Var} = \mathbb{E} \left[\left(\hat{f}'_n(x) - \mathbb{E}(\hat{f}'_n(x)) \right)^2 \right].$$

Using the definition of the kernel derivative estimator, this becomes:

$$\text{Var} = \frac{1}{n} \mathbb{E} \left[\left(\frac{1}{h^2} k' \left(\frac{x_i - x}{h} \right) - \frac{1}{h^2} \mathbb{E} \left(k' \left(\frac{x_i - x}{h} \right) \right) \right)^2 \right].$$

Applying the properties of the variance¹⁴, we can bound the variance as:

¹⁴ $\mathbb{E}[X^2] - (\mathbb{E}[X])^2 \leq \mathbb{E}[X^2]$

$$\text{Var} \leq \frac{1}{n} \mathbb{E} \left[\left(\frac{1}{h^2} k' \left(\frac{x_i - x}{h} \right) \right)^2 \right].$$

Now, using the definition of expectation, we write:

$$\text{Var} \leq \frac{1}{n} \int_{\mathbb{R}} \frac{1}{h^4} \left[k' \left(\frac{z - x}{h} \right) \right]^2 f(z) dz.$$

As before, we make the substitution $\mu = \frac{z-x}{h}$, which implies $z = \mu h + x$ and $dz = h d\mu$. Substituting these into the integral gives:

$$\text{Var} = \frac{1}{n} \int_{\mathbb{R}} \frac{1}{h^4} [k'(\mu)]^2 f(\mu h + x) \cdot h d\mu.$$

Simplifying, we have:

$$\text{Var} \leq \frac{1}{nh^3} \int_{\mathbb{R}} [k'(\mu)]^2 f(\mu h + x) d\mu.$$

Next, we use the assumption that $f(z)$ is bounded by f_{\max} for all $z \in \mathbb{R}$, so:

$$\text{Var} \leq \frac{1}{nh^3} \int_{\mathbb{R}} [k'(\mu)]^2 f_{\max} d\mu.$$

Factoring f_{\max} outside of the integral:

$$\text{Var} \leq \frac{f_{\max}}{nh^3} \int_{\mathbb{R}} [k'(\mu)]^2 d\mu.$$

Finally, defining $C_2 = f_{\max} \int_{\mathbb{R}} [k'(\mu)]^2 d\mu$ as a constant dependent on f_{\max} and the kernel function, we obtain:

$$\text{Var} = C_2 \frac{1}{nh^3}.$$

Conclusion

Thus, the MSE is bounded by: $\text{Var} + \text{Bias}^2 \leq C_2 \frac{1}{nh^3} + C_1^2 \cdot h^{2(\beta-1)}$.

2.1.2 Optimal h

How do we estimate the optimal h ? To gain insight into the trade-off, we examine the upper bound on the mean squared risk. The variance decreases as h grows, whereas the bound on the bias increases (cf. Figure 1). The choice of a small h , corresponding to a large variance, is called *undersmoothing*. Alternatively, with a large h , the bias cannot be reasonably controlled, leading to *oversmoothing*. An optimal value of h that balances bias and variance is located between these two extremes.

Figure 2 illustrates three key scenarios in kernel density estimation:

- **Undersmoothing:** The bandwidth h is too small, resulting in a noisy estimate that overfits the sample points. This leads to high variance.
- **Oversmoothing:** The bandwidth h is too large, causing the estimator to oversimplify the density and miss important features such as modes. This leads to high bias.
- **Correct smoothing:** The bandwidth h is chosen optimally, balancing the trade-off between bias and variance. The estimate captures the essential structure of the density.

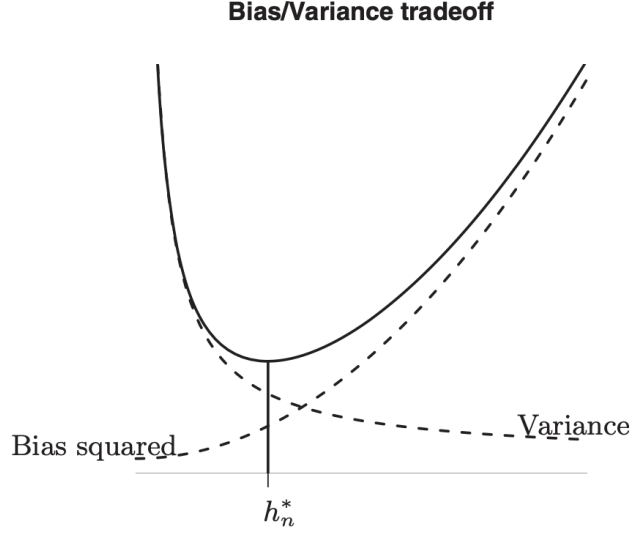


Figure 1.1. Squared bias, variance, and mean squared error (solid line) as functions of h .

Figure 1: Squared bias, variance, and mean squared error (solid line) as functions of h .

The minimum with respect to h of the right-hand side of the MSE bound is attained at:

$$h_n^* = \left(\frac{3C_2}{2(\beta-1)C_1^2} \right)^{\frac{1}{2\beta+1}} n^{-\frac{1}{2\beta+1}}.$$

This differs from the result in the book, which presents:

$$h_n^* = \left(\frac{C_1}{2\beta C_2} \right)^{\frac{1}{2\beta+1}} n^{-\frac{1}{2\beta+1}}.$$

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However, it is important to note that the *rate of convergence* remains the same in both cases. Specifically, the MSE is given by:

$$\text{MSE}(x_0) = O\left(n^{-\frac{2\beta}{2\beta+1}}\right), \quad n \rightarrow \infty,$$

uniformly in x_0 .

Theorem 2.1. Assume that condition (1.5) holds and the assumptions of Proposition 1.2 are satisfied. Fix $\alpha > 0$ and take $h = cn^{-\frac{1}{2\beta+1}}$. Then for $n \geq 1$, the kernel estimator p_n satisfies:

$$\sup_{x_0 \in \mathbb{R}} \sup_{p \in P(\beta, L)} \mathbb{E}_p \left[(p_n(x_0) - p(x_0))^2 \right] \leq Cn^{-\frac{2\beta}{2\beta+1}},$$

where $C > 0$ is a constant depending only on β , L , α , and on the kernel K .

¹⁵This is taken from the book, but we achieve different results because we are analyzing the derivative of the Kernel function.

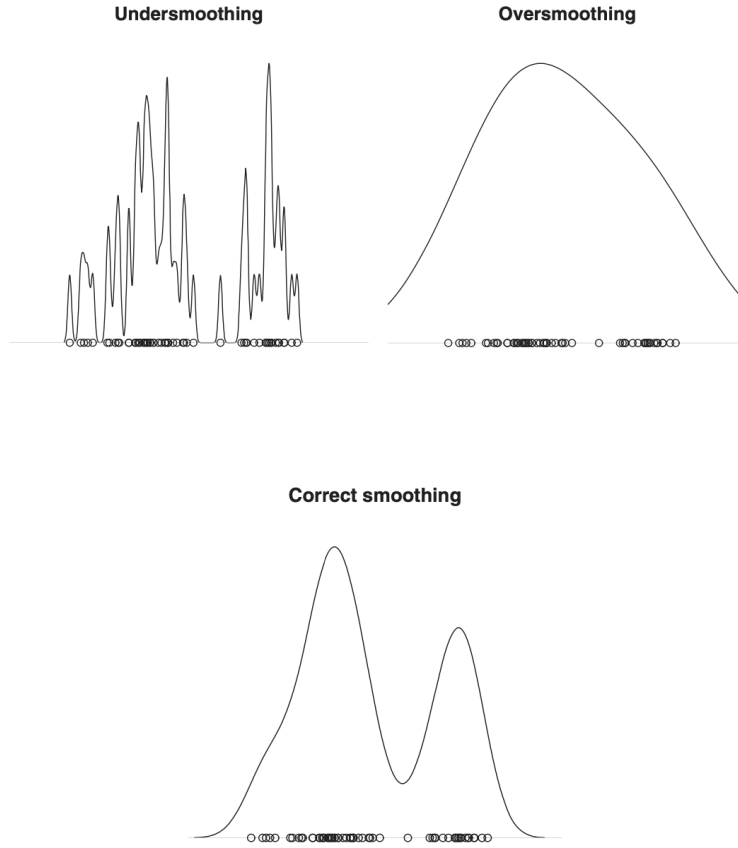


Figure 1.2. Undersmoothing, oversmoothing, and correct smoothing.
The circles indicate the sample points X_i .

Figure 2: Undersmoothing, oversmoothing, and correct smoothing. The circles indicate the sample points X_i .

Proof. Using previous equation and bounding the supremum norm of the kernel density estimate

$$\sup_{x \in \mathbb{R}, p \in P(\beta, L)} |p(x)| \leq p_{\max},$$

where p_{\max} is derived from boundedness properties of the kernel K and its derivatives □

2.1.3 Some definitions from class 6

These are definitions and theorems that were not used in the seminar. Most of the theorems, definitions and proofs given in class 6 were given by the great and informative TD so I omit their repetition.

Proposition 2.2. *Let $f(x) \in \mathbb{P}(\beta, l)$. With $\beta > 0$ and k of order $L > 0$ and $l = \lfloor \beta \rfloor^{16}$ such that $\int_{\mathbb{R}} |\mu|^\beta k(\mu) d\mu < \infty$ Then $\forall x \in \mathbb{R}$ and $\forall h > 0$ $|f(x)| \leq C_1 h^\beta$ where $C_1 := \frac{L}{1} \int_{\mathbb{R}} |\mu|^\beta k(\mu) d\mu$*

Theorem 2.3. *Assume k satisfies the assumptions of the previous proposition and of proposition xx¹⁷ and*

¹⁶In this case, the floor function holds strictly.

¹⁷I need a way to keep track of citations...add labels, lazy boy

choose $h = \alpha n^{-\frac{1}{2\beta+1}}$ for some $\alpha \geq 0$ then:

$$\sup_{x \in \mathbb{R}} \sup_{f(x) \in \mathbb{P}(\beta, l)} \mathbb{E} \left[\left(\hat{f}_x(x) - f_x(x) \right)^2 \right] \leq C n^{\frac{-2\beta}{2\beta+1}}$$

Note that the more variables we have in the analysis the worse it gets...unbounded...

Remark 2.2. Note that the previous theorem can also be expressed as

$$\sup_{\hat{f}_x} \sup_{f(x) \in \mathbb{P}(\beta, l)} \mathbb{E} \left[\left(\hat{f}_x(x) - f_x(x) \right)^2 \right] \geq C n^{\frac{-2\beta}{2\beta+1}}$$

It is optimal up to a constant:

$$\sup_{\hat{f}_x} \sup_{f(x) \in \mathbb{P}(\beta, l)} \mathbb{E} \left[\left(\hat{f}_x(x) - f_x(x) \right)^2 \right] n^{\frac{2\beta}{2\beta+1}} > 0$$

Similarly