

TFM_PIKAN_GPU

June 20, 2025

```
[1]: !pip install tensorboard
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```
Collecting tensorboard
  Using cached tensorboard-2.19.0-py3-none-any.whl.metadata (1.8 kB)
Collecting absl-py>=0.4 (from tensorboard)
  Using cached absl_py-2.3.0-py3-none-any.whl.metadata (2.4 kB)
Collecting grpcio>=1.48.2 (from tensorboard)
  Downloading grpcio-1.73.0-cp312-cp312-win_amd64.whl.metadata (4.0 kB)
Collecting markdown>=2.6.8 (from tensorboard)
  Downloading markdown-3.8.2-py3-none-any.whl.metadata (5.1 kB)
Requirement already satisfied: numpy>=1.12.0 in
c:\users\jorge\anaconda3\envs\kan_pytorch\lib\site-packages (from tensorboard)
(2.0.1)
Requirement already satisfied: packaging in
c:\users\jorge\anaconda3\envs\kan_pytorch\lib\site-packages (from tensorboard)
(24.2)
Collecting protobuf!=4.24.0,>=3.19.6 (from tensorboard)
  Using cached protobuf-6.31.1-cp310-abi3-win_amd64.whl.metadata (593 bytes)
Requirement already satisfied: setuptools>=41.0.0 in
c:\users\jorge\anaconda3\envs\kan_pytorch\lib\site-packages (from tensorboard)
(75.8.0)
Requirement already satisfied: six>1.9 in
c:\users\jorge\anaconda3\envs\kan_pytorch\lib\site-packages (from tensorboard)
(1.17.0)
Collecting tensorboard-data-server<0.8.0,>=0.7.0 (from tensorboard)
  Using cached tensorboard_data_server-0.7.2-py3-none-any.whl.metadata (1.1 kB)
Collecting werkzeug>=1.0.1 (from tensorboard)
  Using cached werkzeug-3.1.3-py3-none-any.whl.metadata (3.7 kB)
Requirement already satisfied: MarkupSafe>=2.1.1 in
c:\users\jorge\anaconda3\envs\kan_pytorch\lib\site-packages (from
werkzeug>=1.0.1->tensorboard) (2.1.5)
Using cached tensorboard-2.19.0-py3-none-any.whl (5.5 MB)
Using cached absl_py-2.3.0-py3-none-any.whl (135 kB)
Downloading grpcio-1.73.0-cp312-cp312-win_amd64.whl (4.3 MB)
----- 0.0/4.3 MB ? eta -:-:--
----- 4.3/4.3 MB 43.8 MB/s eta 0:00:00
Downloading markdown-3.8.2-py3-none-any.whl (106 kB)
Using cached protobuf-6.31.1-cp310-abi3-win_amd64.whl (435 kB)
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Using cached tensorboard_data_server-0.7.2-py3-none-any.whl (2.4 kB)
 Using cached werkzeug-3.1.3-py3-none-any.whl (224 kB)
 Installing collected packages: werkzeug, tensorboard-data-server, protobuf,
 markdown, grpcio, absl-py, tensorboard
 Successfully installed absl-py-2.3.0 grpcio-1.73.0 markdown-3.8.2
 protobuf-6.31.1 tensorboard-2.19.0 tensorboard-data-server-0.7.2 werkzeug-3.1.3

```
[2]: import torch
      from torch import autograd
      from torch.utils.tensorboard import SummaryWriter
```

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[3]: device = "cuda:0" if torch.cuda.is_available() else "cpu"
```

```
[4]: from tqdm import tqdm
      import matplotlib.pyplot as plt
      from kan import KAN, LBFGS

      device = torch.device(device)
      print("Using device:", device)

      rho = torch.tensor(1.0, device=device, requires_grad=False)
      nu = torch.tensor(0.01, device=device, requires_grad=False)
      eps = torch.tensor(1e-8, device=device, requires_grad=False)

      width, height = 10.0, 2.0
      num_points_x, num_points_y = 100, 20

      x = torch.linspace(0, width, num_points_x, device=device, requires_grad=False)
      y = torch.linspace(0, height, num_points_y, device=device, requires_grad=False)
      X, Y = torch.meshgrid(x, y, indexing='ij')
      coordinates = torch.stack([X.flatten(), Y.flatten()], dim=1).to(device)
      coordinates.requires_grad = True # Ensure coordinates require grad

      model = KAN(width=[2,3,3, 3], grid=5, k=10, grid_eps=1.0,
                  noise_scale=0.25).to(device)

      def batch_jacobian(func, x, create_graph=False):
          def _func_sum(x):
              return func(x).sum(dim=0)
          return autograd.functional.jacobian(_func_sum, x,
          ↪ create_graph=create_graph).permute(1, 0, 2)

      def batch_hessian(func, x):
          jacobian = batch_jacobian(func, x, create_graph=True)
          hessians = []
          for i in range(jacobian.size(1)):
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        grad = autograd.grad(jacobian[:, i].sum(), x, create_graph=True,
↪retain_graph=True)[0]
        hessians.append(grad.unsqueeze(1))
        return torch.cat(hessians, dim=1)

def navier_stokes_residuals(coords):
    coords = coords.clone().detach().requires_grad_(True) # Ensure coords
↪require grad
    y_pred = model(coords)
    grads = batch_jacobian(model, coords, create_graph=True)
    hessians = batch_hessian(model, coords)

    u, v, p = y_pred[:, 0], y_pred[:, 1], y_pred[:, 2]
    u_x, u_y = grads[:, 0, 0], grads[:, 0, 1]
    v_x, v_y = grads[:, 1, 0], grads[:, 1, 1]
    p_x, p_y = grads[:, 2, 0], grads[:, 2, 1]

    u_xx, u_yy = hessians[:, 0, 0], hessians[:, 0, 1]
    v_xx, v_yy = hessians[:, 1, 0], hessians[:, 1, 1]

    continuity = u_x + v_y + eps * p
    x_momentum = u * u_x + v * u_y + (1 / rho) * p_x - nu * (u_xx + u_yy)
    y_momentum = u * v_x + v * v_y + (1 / rho) * p_y - nu * (v_xx + v_yy)

    no_slip_mask = (coords[:, 1] == 0) | (coords[:, 1] == height)
    inlet_mask = (coords[:, 0] == 0)
    outlet_mask = (coords[:, 0] == width)

    no_slip_loss = torch.mean(u[no_slip_mask] ** 2 + v[no_slip_mask] ** 2)
    inlet_loss = torch.mean((u[inlet_mask] - 1) ** 2)
    outlet_pressure_loss = torch.mean(p[outlet_mask] ** 2)

    bc_loss = no_slip_loss + inlet_loss + outlet_pressure_loss
    total_loss = torch.mean(continuity ** 2 + x_momentum ** 2 + y_momentum **
↪2) + bc_loss
    return total_loss

writer = SummaryWriter()

def train():
    optimizer = LBFGS(model.parameters(), lr=1,
                        history_size=10, line_search_fn="strong_wolfe",
↪tolerance_grad=1e-32, tolerance_change=1e-32, tolerance_ys=1e-32)

    steps = 20 # 20 steps are enough 200 in the original 2h9min version
    pbar = tqdm(range(steps), desc='Training Progress')

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for step in pbar:
    def closure():
        optimizer.zero_grad()
        loss = navier_stokes_residuals(coordinates)
        loss.backward()
        return loss

    optimizer.step(closure)
    if step % 5 == 0:
        current_loss = closure().item()
        pbar.set_description("Step: %d | Loss: %.3f" %
                             (step, current_loss))
        writer.add_scalar('Loss/train', current_loss, step)

train()

writer.close()

```

Using device: cuda:0

checkpoint directory created: ./model

saving model version 0.0

Step: 15 | Loss: 0.026: 100%| | 20/20 [05:49<00:00, 17.48s/it]

```

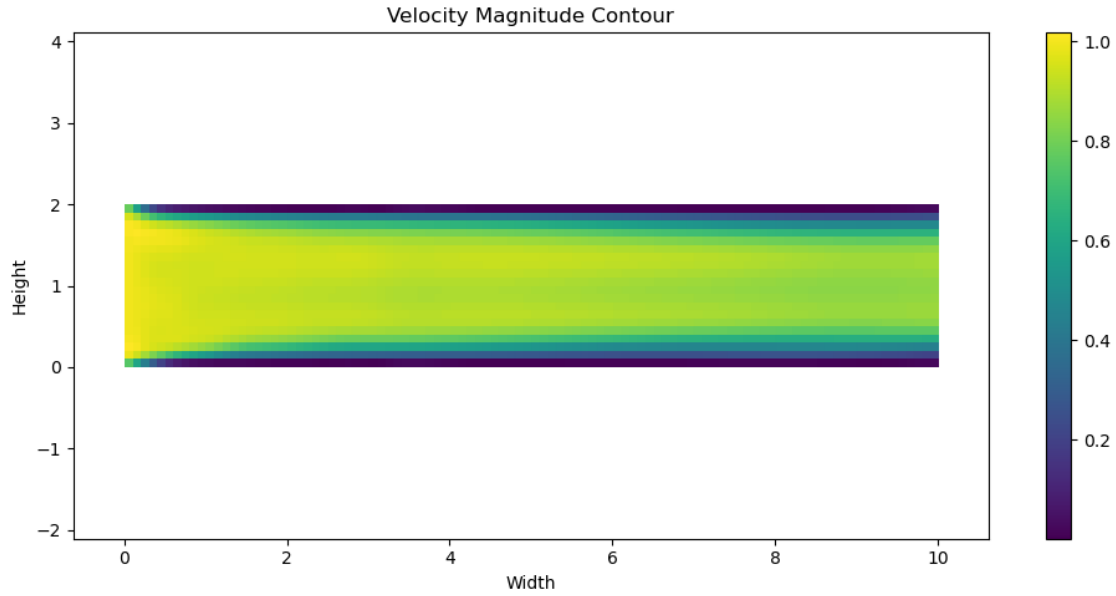
[5]: u_pred = model(coordinates)[: , 0].detach().reshape(
      num_points_x, num_points_y).T

v_pred = model(coordinates)[: , 1].detach().reshape(
      num_points_x, num_points_y).T

magnitude = torch.sqrt(u_pred ** 2 + v_pred ** 2)
magnitude = magnitude.detach().cpu().numpy()

plt.figure(figsize=(10, 5)) # Set the figure size as needed
plt.imshow(magnitude, extent=(0, width, 0, height), origin='lower',
           cmap='viridis')
plt.colorbar() # Add a colorbar to show the magnitude scale
plt.title('Velocity Magnitude Contour')
plt.xlabel('Width')
plt.ylabel('Height')
plt.axis('equal') # Ensure the plot has equal scaling
plt.tight_layout() # Adjust layout to prevent overlap
plt.show()

```



```
[6]: # Extracting predictions
u_pred = model(coordinates[:, 0]).detach().reshape(num_points_x, num_points_y).T
v_pred = model(coordinates[:, 1]).detach().reshape(num_points_x, num_points_y).T
p_pred = model(coordinates[:, 2]).detach().reshape(num_points_x, num_points_y).T

# Velocity Magnitude
magnitude = torch.sqrt(u_pred ** 2 + v_pred ** 2)

magnitude = magnitude.detach().cpu().numpy()
u_pred = u_pred.detach().cpu().numpy()
v_pred = v_pred.detach().cpu().numpy()
p_pred = p_pred.detach().cpu().numpy()

# Plotting all subplots
fig, axs = plt.subplots(2, 2, figsize=(15, 10))

# Velocity Magnitude
im0 = axs[0, 0].imshow(magnitude, extent=(0, width, 0, height), origin='lower',
    cmap='viridis')
fig.colorbar(im0, ax=axs[0, 0])
axs[0, 0].set_title('Velocity Magnitude Contour')
axs[0, 0].set_xlabel('Width')
axs[0, 0].set_ylabel('Height')
axs[0, 0].axis('equal')

# u Component
```

```

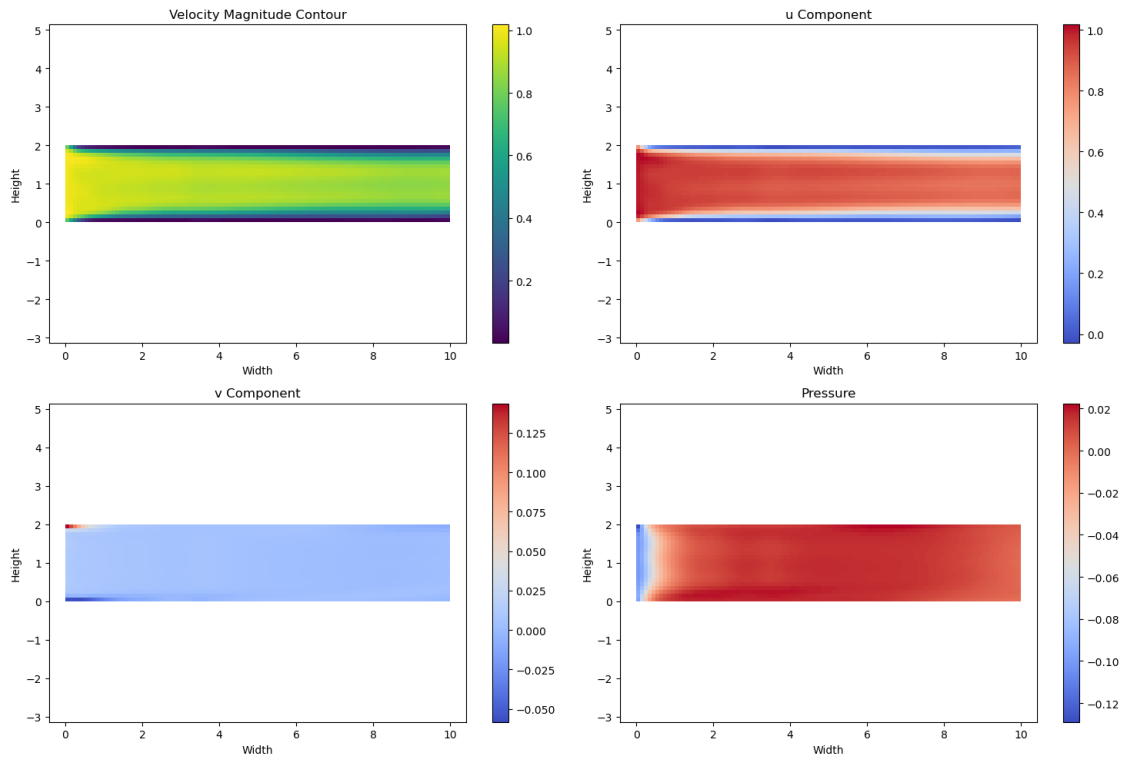
im1 = axs[0, 1].imshow(u_pred, extent=(0, width, 0, height), origin='lower',
    cmap='coolwarm')
fig.colorbar(im1, ax=axs[0, 1])
axs[0, 1].set_title('u Component')
axs[0, 1].set_xlabel('Width')
axs[0, 1].set_ylabel('Height')
axs[0, 1].axis('equal')

# v Component
im2 = axs[1, 0].imshow(v_pred, extent=(0, width, 0, height), origin='lower',
    cmap='coolwarm')
fig.colorbar(im2, ax=axs[1, 0])
axs[1, 0].set_title('v Component')
axs[1, 0].set_xlabel('Width')
axs[1, 0].set_ylabel('Height')
axs[1, 0].axis('equal')

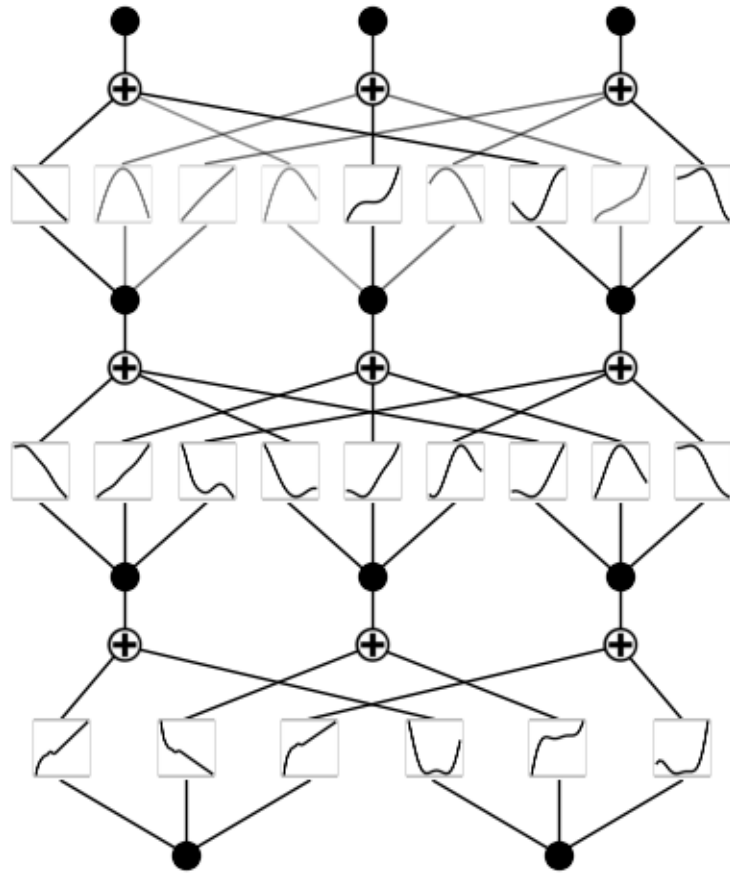
# Pressure
im3 = axs[1, 1].imshow(p_pred, extent=(0, width, 0, height), origin='lower',
    cmap='coolwarm')
fig.colorbar(im3, ax=axs[1, 1])
axs[1, 1].set_title('Pressure')
axs[1, 1].set_xlabel('Width')
axs[1, 1].set_ylabel('Height')
axs[1, 1].axis('equal')

plt.tight_layout() # Adjust layout to prevent overlap
plt.show()

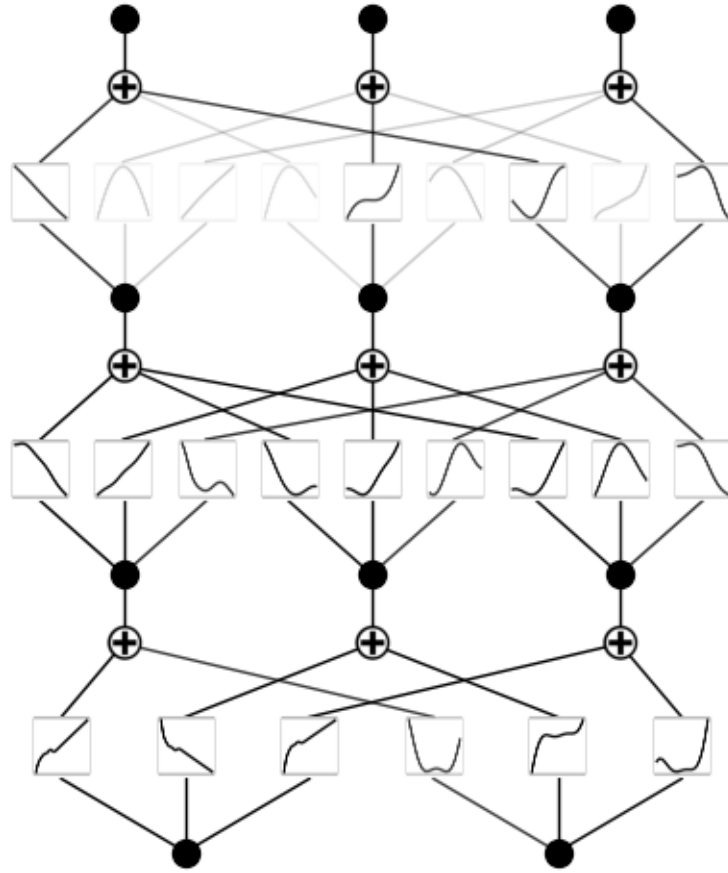
```



```
[7]: model.plot(beta=10)
```



```
[8]: model.plot()
```

```
[9]: model.auto_symbolic()
```

```
fixing (0,0,0) with x, r2=0.9735497236251831, c=1
fixing (0,0,1) with 0, r2=0.0, c=0
fixing (0,0,2) with 0, r2=0.0, c=0
fixing (0,1,0) with 0, r2=0.0, c=0
fixing (0,1,1) with 0, r2=0.0, c=0
fixing (0,1,2) with 0, r2=0.0, c=0
fixing (1,0,0) with sin, r2=0.9986881613731384, c=2
fixing (1,0,1) with x, r2=0.992422342300415, c=1
fixing (1,0,2) with 0, r2=0.0, c=0
fixing (1,1,0) with 0, r2=0.0, c=0
fixing (1,1,1) with 0, r2=0.0, c=0
fixing (1,1,2) with cos, r2=0.9962447285652161, c=2
fixing (1,2,0) with 0, r2=0.0, c=0
fixing (1,2,1) with 0, r2=0.0, c=0
fixing (1,2,2) with sin, r2=0.9975288510322571, c=2
fixing (2,0,0) with sin, r2=1.000000238418579, c=2
fixing (2,0,1) with sin, r2=0.9994560480117798, c=2
```

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fixing (2,0,2) with x^2, r2=0.999975860118866, c=2
fixing (2,1,0) with 0, r2=0.0, c=0
fixing (2,1,1) with 0, r2=0.0, c=0
fixing (2,1,2) with cos, r2=0.9997799396514893, c=2
fixing (2,2,0) with 0, r2=0.0, c=0
fixing (2,2,1) with 0, r2=0.0, c=0
fixing (2,2,2) with 0, r2=0.0, c=0
saving model version 0.1

```

```
[10]: from kan.utils import ex_round
```

```
[11]: formula1, formula2, formula3 = model.symbolic_formula()[0]
```

```
[12]: ex_round(formula1,2)
```

```
[12]: 1.08 sin (1.71 sin (0.17x1 - 4.46) + 8.52) + 0.48
```

```
[13]: ex_round(formula2,2)
```

```
[13]: -0.01 sin (2.96 sin (0.17x1 - 4.46) - 9.56)
```

```
[14]: ex_round(formula3,2)
```

```
[14]: -0.03 (1 - 0.42 sin (0.17x1 - 4.46))2 - 0.05 cos (0.12x1 + 8.95) - 0.01
```