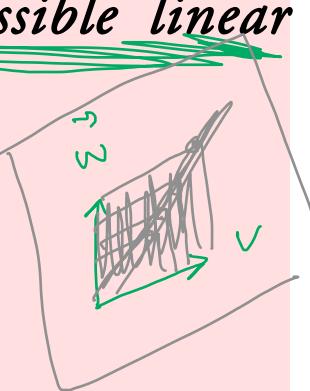


1.2 The Span of a Set of Vectors

Definition: The *Span* of a non-empty set of vectors $S = \{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k\}$ from \mathbb{R}^n is the set of all possible linear combinations of the vectors in the set. We write:

$$\text{Span}(S) = \text{Span}(\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k\})$$

$$= \left\{ x_1 \vec{v}_1 + x_2 \vec{v}_2 + \dots + x_k \vec{v}_k \mid x_1, x_2, \dots, x_k \in \mathbb{R} \right\}.$$



We note that the individual vectors $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k$ are all members of $\text{Span}(S)$, where we let $x_i = 1$ and all the other coefficients 0 in order to produce \vec{v}_i . Similarly, the zero vector $\vec{0}_n$ is also a member of $\text{Span}(S)$, where we make all the coefficients x_i zero to produce $\vec{0}_n$.

Theorem: In any \mathbb{R}^n : $Span\left(\left\{\vec{0}_n\right\}\right) = \left\{\vec{0}_n\right\}$.

$$x \vec{0} = \vec{0}$$



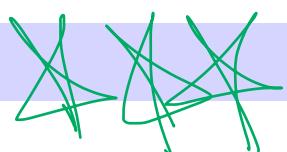
Theorem: For all $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k \in \mathbb{R}^n$:

(c+1)

$$\begin{aligned} &Span\left(\left\{\vec{0}_n, \vec{v}_1, \vec{v}_2, \dots, \vec{v}_k\right\}\right) \\ &= Span(\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k\}). \end{aligned}$$



Theorem: $\mathbb{R}^n = Span(\{\vec{e}_1, \vec{e}_2, \dots, \vec{e}_n\})$.



already proved!

B/c: $\langle x_1, x_2, \dots, x_n \rangle = x_1 \vec{e}_1 + x_2 \vec{e}_2 + \dots + x_n \vec{e}_n$

The Span of One Vector in \mathbb{R}^2

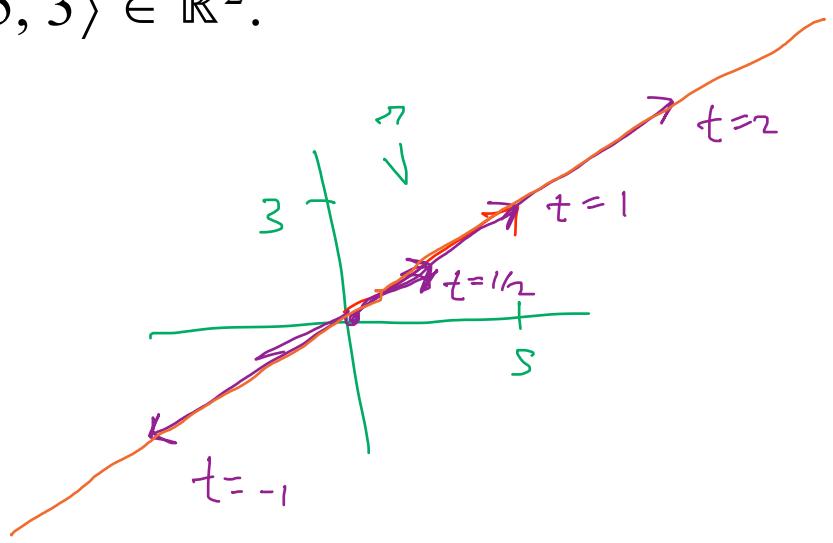
Example: Suppose that $\vec{v} = \langle 5, 3 \rangle \in \mathbb{R}^2$.

Describe $\text{Span}(\{\vec{v}\})$.

$$= \{ t\vec{v} \mid t \in \mathbb{R} \}$$

get a line!

in plane

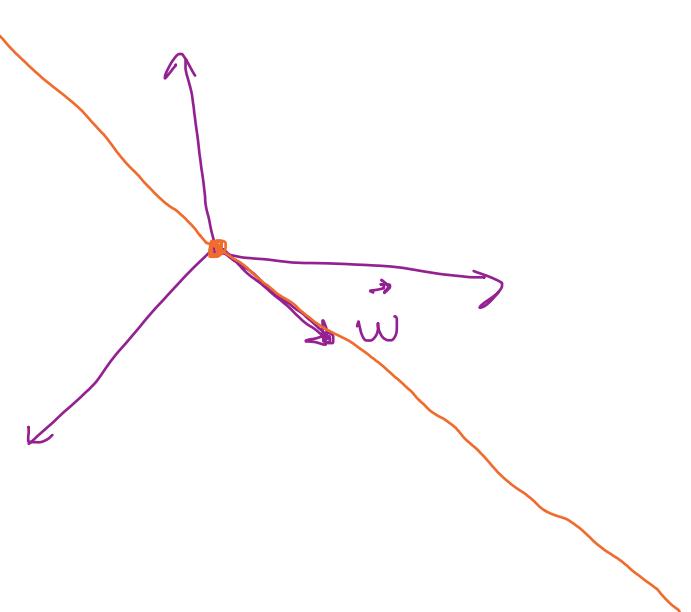


The Span of One Vector in \mathbb{R}^3

Example: Suppose that $\vec{w} = \langle -2, 1, -4 \rangle \in \mathbb{R}^3$. Describe $\text{Span}(\{\vec{v}\})$

$$= \{ t\vec{v} \mid t \in \mathbb{R} \}$$

get a line in space!



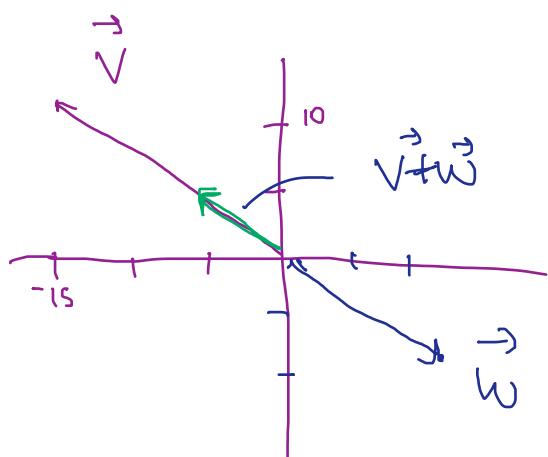
Lines in \mathbb{R}^n

Definition — Axiom for a Line:

If $\vec{v} \in \mathbb{R}^n$ is a **non-zero** vector, then $\overbrace{\text{Span}(\{\vec{v}\})}$ is "geometrically a line L in \mathbb{R}^n passing through the origin."

The Span of Two Parallel Vectors

Example: Suppose that $\vec{v} = \langle -15, 10 \rangle$ and $\vec{w} = \langle 12, -8 \rangle \in \mathbb{R}^2$. Describe Span($\{\vec{u}, \vec{v}\}$).



$\text{Span}(\{\vec{v}, \vec{w}\}) = \text{a line!}$

$\vec{v} \parallel \vec{w} ?$
Recall def. of \parallel :

$\exists k \in \mathbb{R}$ so that

$$\vec{v} = k \vec{w} \quad \checkmark$$

$$\langle -15, 10 \rangle = k \langle 12, -8 \rangle ?$$

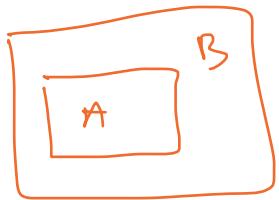
$$\begin{aligned} -15 &= k \cdot 12 \rightarrow k = -\frac{5}{4} \quad \checkmark \\ 10 &= k(-8) \rightarrow k = \frac{10}{-8} = -\frac{5}{4} \quad \checkmark \end{aligned}$$

Theorem: If \vec{u} and \vec{v} are non-zero vectors in some \mathbb{R}^n which are parallel to each other, then:

$$\underset{A}{Span}(\{\vec{u}, \vec{v}\}) = \underset{B}{Span}(\{\vec{v}\}) = \underset{C}{Span}(\{\vec{u}\}).$$

- * $x_1 \vec{u} + x_2 \vec{v} \in \text{span}(\{\vec{u}, \vec{v}\})$
- * $\vec{u} \parallel \vec{v} \exists k \in \mathbb{R} \text{ so that } \vec{u} = k \vec{v}$

$$\begin{aligned} x_1 \vec{u} + x_2 \vec{v} &= x_1 (k \vec{v}) + x_2 \vec{v} \\ &= \underbrace{(x_1 k + x_2)}_{\text{scalar}} \vec{v} \end{aligned}$$



this says $x_1 \vec{u} + x_2 \vec{v} \in \text{span}(\{\vec{v}\})$.

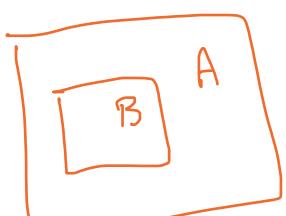
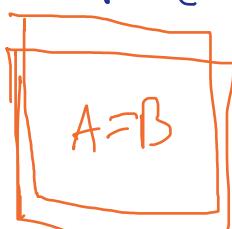
$$\text{So } \text{Span}(\{\vec{u}, \vec{v}\}) \subseteq \text{Span}(\{\vec{v}\})$$

- * WTS: $\text{Span}(\{\vec{u}\}) \subseteq \text{Span}(\{\vec{u}, \vec{v}\})$.

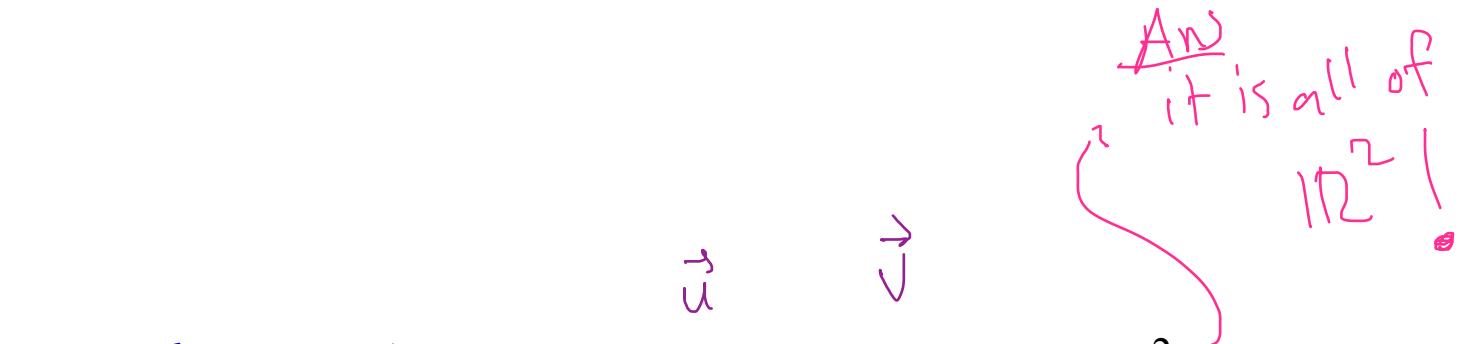
let $x_1 \vec{u} \in \text{Span}(\{\vec{v}\})$. let $x_2 = 0$ Then

$$x_1 \vec{u} = x_1 \vec{u} + 0 \vec{v} = \underbrace{x_1 \vec{u} + x_2 \vec{v}}_{\in \text{Span}(\{\vec{u}, \vec{v}\})} \in \text{Span}(\{\vec{u}, \vec{v}\})$$

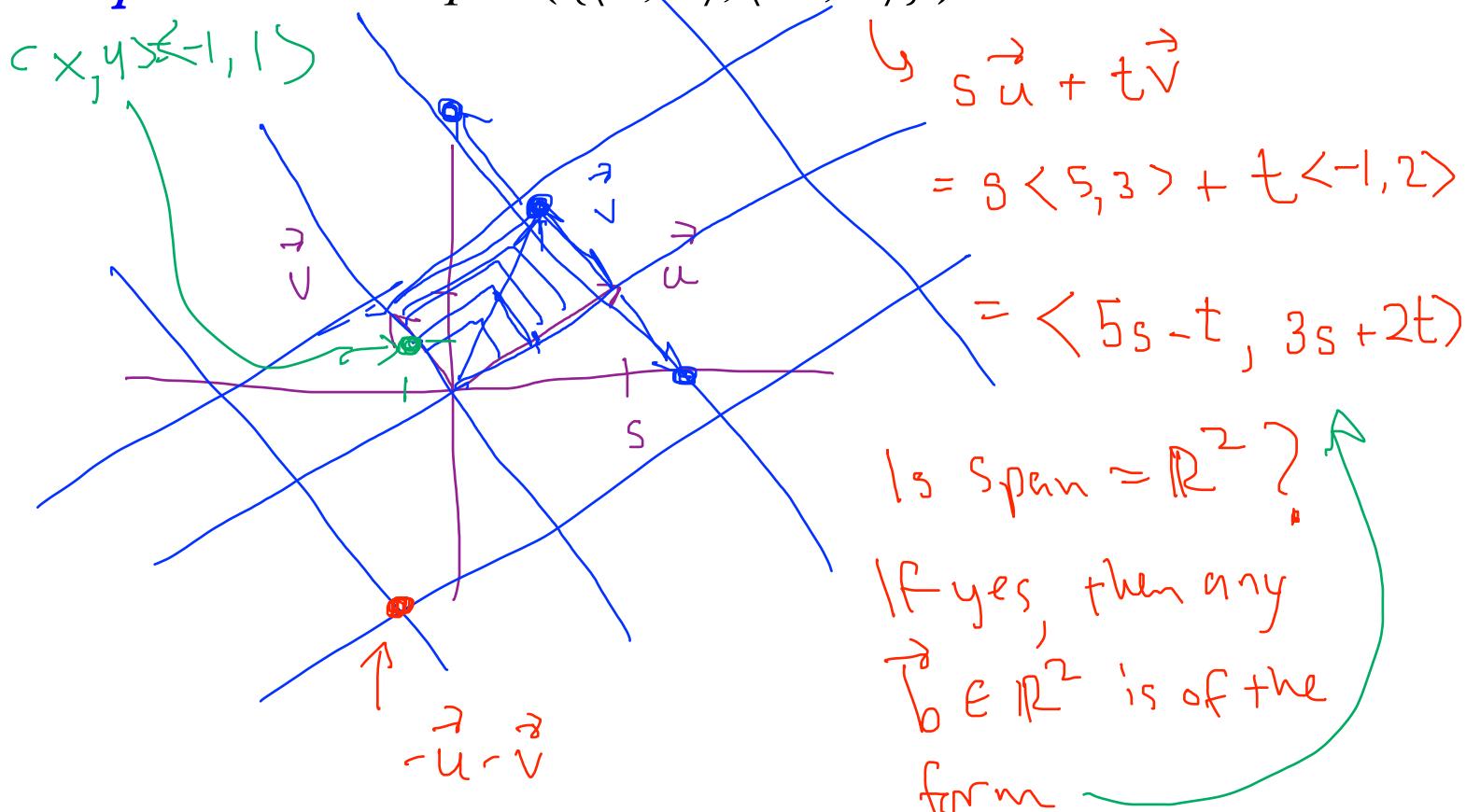
This proves $\text{Span}(\{\vec{u}\}) \subseteq \text{Span}(\{\vec{u}, \vec{v}\})$.



The Span of Two Non-Parallel Vectors in \mathbb{R}^2



Example: Describe $\text{Span}(\langle\langle 5, 3 \rangle, \langle -1, 2 \rangle\rangle)$ in \mathbb{R}^2 .



So, write $\vec{b} = \langle x, y \rangle$. If yes, then

$$\langle x, y \rangle = \vec{b} = \langle 5s - t, 3s + 2t \rangle$$

(on board)

$$S = \frac{2x+y}{\sqrt{3}}$$

In general:

$$t = 5 \left[\frac{2x+y}{\sqrt{3}} \right] - x$$

Theorem: If $\vec{u}, \vec{v} \in \mathbb{R}^2$ are non-parallel vectors, then:

$$\text{Span}(\{\vec{u}, \vec{v}\}) = \mathbb{R}^2.$$

↗ yay!

In other words, *any vector* $\vec{w} \in \mathbb{R}^2$ can be expressed as a linear combination:

$$\vec{w} = r\vec{u} + s\vec{v},$$

for some scalars r and s .

↗ if $\vec{w} \in \mathbb{R}^2$ then

$$\vec{w} \in \text{Span}(\{\vec{u}, \vec{v}\})$$

then

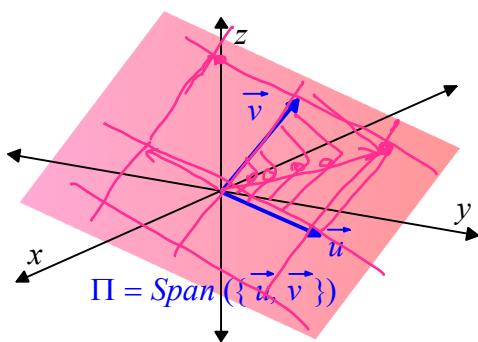
$$\vec{w} = r\vec{u} + s\vec{v}$$

The Span of Two Non-Parallel Vectors in \mathbb{R}^3

Definition — Axiom for a Plane in Cartesian Space:

If \vec{u} and \vec{v} are vectors in \mathbb{R}^3 that are not parallel to each other, then $\text{Span}(\{\vec{u}, \vec{v}\})$ is geometrically a plane Π in Cartesian space that passes through the origin (Π is the capital form of the lowercase Greek letter π).

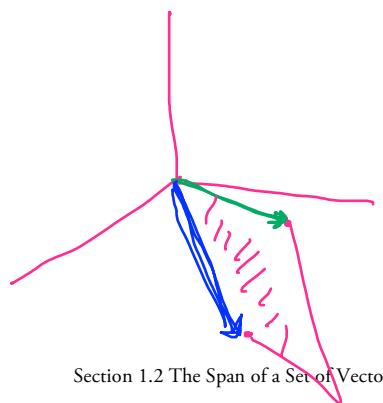
" Π " "Π" in Greek.



$$\text{Span}(\{\vec{u}, \vec{v}\}) = \Pi$$

Example: $\text{Span}(\langle\langle -2, 1, -3 \rangle, \langle 5, 4, -3 \rangle\rangle)$.

plane through the origin.



The Cartesian Equation of a Plane

Definition: The *Cartesian equation* of a plane through the origin in Cartesian space, given in the form $\Pi = \text{Span}(\{\vec{u}, \vec{v}\})$, where \vec{u} and \vec{v} are not parallel, has the form:

$$ax + by + cz = 0, \quad \langle a, b, c \rangle \cdot \langle x, y, z \rangle = 0$$

for some constants, a , b and c , where at least one coefficient is non-zero.

Vector Eq Plane

$$\Pi = \left\{ r\vec{u} + s\vec{v} \mid r, s \in \mathbb{R} \right\}$$

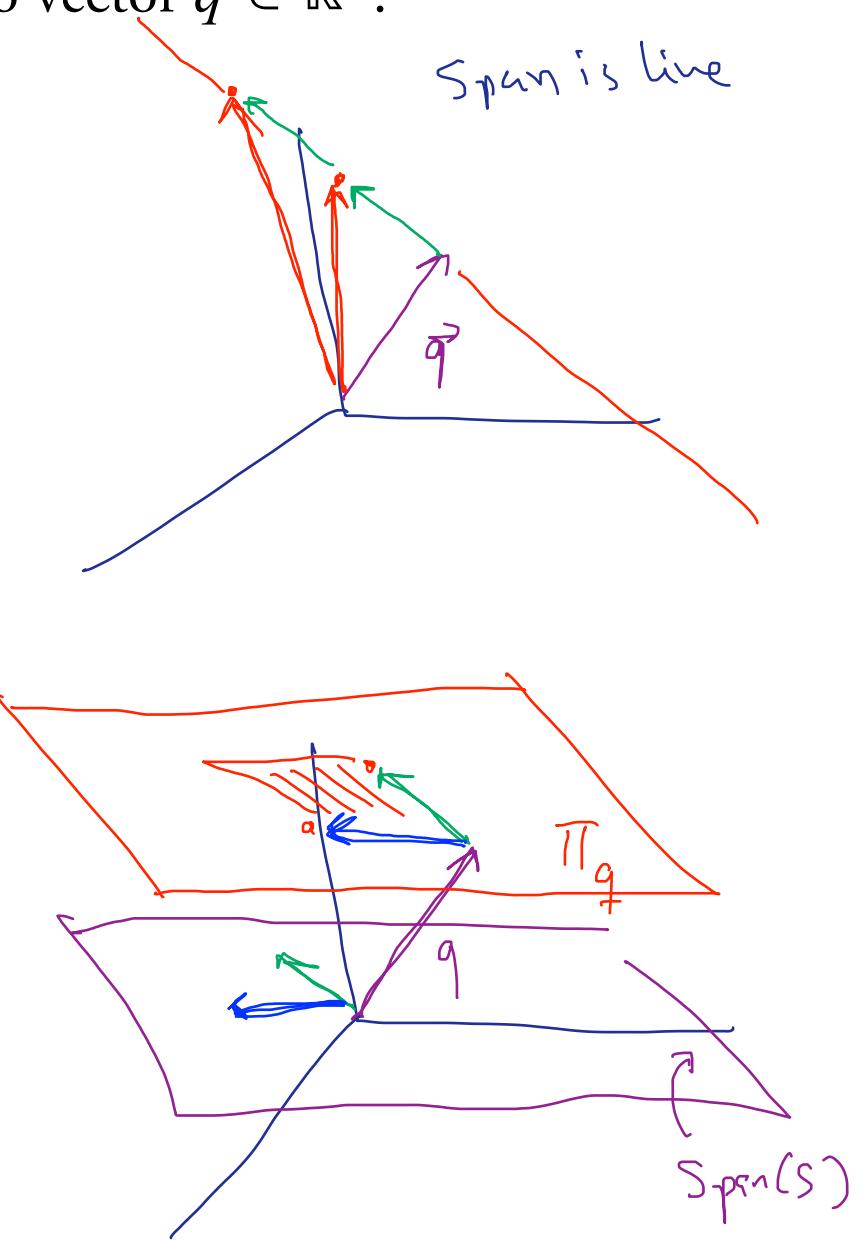
Translation of a Span

$$Q = \{ \vec{q} + \vec{v} \mid \vec{v} \in \text{Span}(S) \},$$

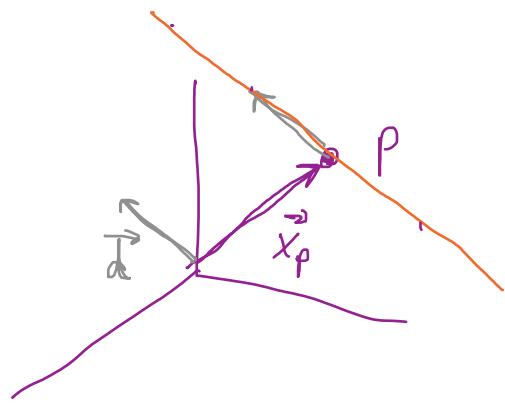
$$= \{ \vec{q} + t \vec{v} \mid t \in \mathbb{R} \}$$

\vec{v} fixed some vector in Span .

for some **fixed** non-zero vector $\vec{q} \in \mathbb{R}^n$.



General Lines in \mathbb{R}^n



Definitions: A **line** L in \mathbb{R}^n is the translate of the Span of a single **non-zero** vector $\vec{d} \in \mathbb{R}^n$:

$$L = \left\{ \vec{x}_p + t\vec{d} \mid t \in \mathbb{R} \right\},$$

Ex Line passing
point P in the
direction of \vec{d}

for some vector $\vec{x}_p \in \mathbb{R}^n$. We may think of \vec{d} as a **direction vector** of L , and any non-zero multiple of \vec{d} can also be used as a direction vector for L .

We see that by setting t to zero that \vec{x}_p is a **particular** vector on the line L . We will also say that two **distinct** lines are **parallel** to each other if they are different translates of the same line through the origin.

General Lines in \mathbb{R}^3

Example: Consider the line L in Cartesian space passing through the point $(-5, 2, -3)$ and pointing in the direction of $\langle 2, 4, -7 \rangle$.

Definition: A line L in Cartesian space passing through the point (x_0, y_0, z_0) , and with non-zero direction vector $\vec{d} = \langle a, b, c \rangle$ can be specified using a *vector equation*, in the form:

$$\boxed{\langle x, y, z \rangle = \langle x_0, y_0, z_0 \rangle + t \langle a, b, c \rangle, \text{ where } t \in \mathbb{R}.}$$

If none of the components of \vec{d} are zero, we can obtain *symmetric equations* for L , of the form:

$$\boxed{\frac{x - x_0}{a} = \frac{y - y_0}{b} = \frac{z - z_0}{c}.}$$

; e solve for t

Assume
 $a, b, c \neq 0$

$$\begin{aligned} x &= x_0 + t a & \rightarrow t &= \frac{x - x_0}{a} \\ y &= y_0 + t b & \rightarrow t &= \frac{y - y_0}{b} \\ z &= z_0 + t c & \rightarrow t &= \frac{z - z_0}{c} \end{aligned}$$

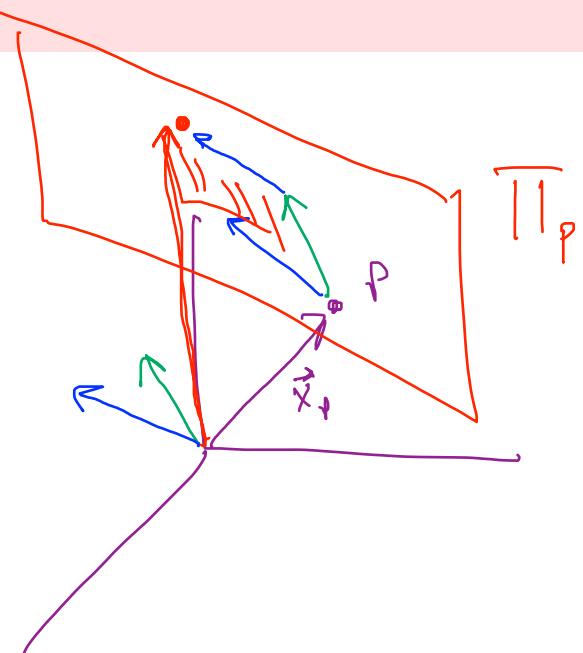
General Planes in \mathbb{R}^n

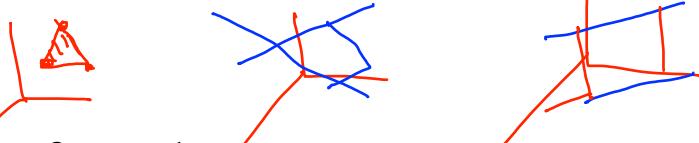
Definition: A *plane* Π in \mathbb{R}^n is the translate of a Span of two *non-parallel* vectors \vec{u} and $\vec{v} \in \mathbb{R}^n$:

$$\Pi_p = \{ \vec{x} = \vec{x}_p + r\vec{u} + s\vec{v} \mid r, s \in \mathbb{R} \},$$

for some $\vec{x}_p \in \mathbb{R}^n$.

"parametric Eqs of
a plane"





Some creative ways to specify a plane in Cartesian space:

- requiring the plane to contain three non-collinear points.
- requiring the plane to contain two intersecting lines.
- requiring the plane to contain two parallel lines.

Example: Find parametric equations and a Cartesian equation for the plane Π passing through $A(1, -3, 2)$, $B(-1, -2, 1)$ and $C(2, 3, -1)$.

$$\Pi = \left\{ \vec{x}_A + s\vec{u} + t\vec{v} \mid s, t \in \mathbb{R} \right\}$$

The diagram illustrates the three points A, B, and C in 3D space. Point A is at the top, B is at the bottom right, and C is at the bottom left. Vector $\vec{u} = \vec{AC}$ is shown from A to C. Vector $\vec{v} = \vec{AB}$ is shown from A to B. The plane Π passes through points A, B, and C.

Definition: A plane Π in Cartesian space can be specified using a *Cartesian equation*, in the form:

$$ax + by + cz = d,$$

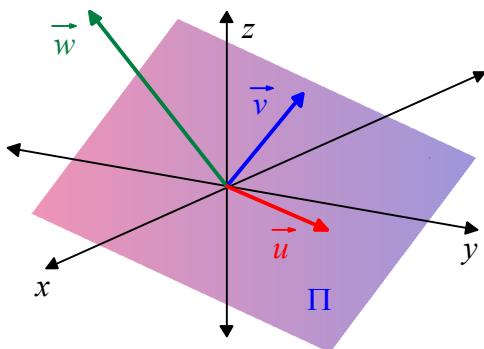
for some constants, a , b , c and d , where either a or b or c is non-zero. It is not unique, because we can multiply all the coefficients in the equation by the same non-zero constant k , and the resulting equation will again be a Cartesian equation for Π . The plane passes through the origin *if and only if* $d = 0$.

The Span of Three Non-Coplanar Vectors

Theorem: If \vec{u} , \vec{v} and \vec{w} are **non-coplanar** vectors in \mathbb{R}^3 , that is, none of these vectors is on the plane determined by the two others, then:

$$\text{Span}(\{\vec{u}, \vec{v}, \vec{w}\}) = \mathbb{R}^3.$$

In other words, any vector $\vec{z} \in \mathbb{R}^3$ can be expressed as a linear combination, $\vec{z} = r\vec{u} + s\vec{v} + t\vec{w}$, for some scalars r , s and t .



If \vec{u} , \vec{v} and \vec{w} Are **Non-Coplanar** Vectors in \mathbb{R}^3 ,

Then $\text{Span}(\{\vec{u}, \vec{v}, \vec{w}\}) = \mathbb{R}^3$