

M-Estimation, I: Introduction and Asymptotic Properties

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Outline

Introduction

Nonlinear Regression

- Identification

- Estimation

M-Estimation

Asymptotic Properties of M-Estimators

- Consistency

- Normality

Introduction

Nonlinear Estimation Chapters

- ▶ W. Chapters 12–13: Abstract and technical.
- ▶ But generality can be useful!
- ▶ Unified framework for estimation.
 - ▶ **Ex:** OLS, Nonlinear LS, Maximum likelihood...
- ▶ There will be no exam questions in Ch. 12–13 *specifically*.
- ▶ But important—and required—background knowledge.

Steps in Econometric Analysis

1. **Identification:** Given distribution of observables, (how) can we uniquely recover parameters?

2. **Estimation:** Given sample, how to construct parameter estimates?

Consistency, rates of convergence

3. **Inference:** Confidence intervals, prediction intervals, hypothesis testing, etc.

Steps in Econometrics Analysis

- ▶ **Identification:** Has nothing to do with sample.
- ▶ **Estimation:** What formula(e)/algorithm to follow?
- ▶ **Inference:** Requires (asymptotic) distribution theory.

Steps highly interdependent.

- ▶ Identification method may suggest estimator.
- ▶ Inference method hinges on estimation method.

Nonlinear Regression

Nonlinear Regression Model

- ▶ y : scalar outcome.
- ▶ \mathbf{x} : K -vector of explanatory variables.
- ▶ $m(\mathbf{x}, \theta)$ candidate estimators **parametric model** for $E(y|\mathbf{x})$.
- ▶ $\Theta \subseteq \mathbb{R}^P$ parameter space. Fixed dim P .
- ▶ **Mean** model **correctly specified** if

expected value of y given \mathbf{x} is exactly given by our model thereof at
\theta_0 -> for all past realisations of \mathbf{x}

$$E(y|\mathbf{x}) = m(\mathbf{x}, \theta_o) \quad \text{X} \quad (1)$$

candidate parameter

holds for **some** $\theta_o \in \Theta$.

- ▶ θ_o often called “true value of θ .”

Examples of Functional Form

Ex. $m(x, \theta) = x\theta$
(linear)

- like income
- **Ex.** If y nonnegative, may take

$$m(\mathbf{x}, \boldsymbol{\theta}) = \exp(\mathbf{x}\boldsymbol{\theta}). \quad (\text{exponential regression})$$

- **Ex.** If $y \in \{0, 1\}$, may take

$$m(\mathbf{x}, \boldsymbol{\theta}) = \frac{1}{1 + \exp(-\mathbf{x}\boldsymbol{\theta})}. \quad (\text{logistic regression})$$

sigmoid-function?

- Here: $K = P$. But $K \geq P$ allowed.

no of explanatory variables (K) = no of candidate parameters (P)

Error Formulation

- ▶ Assume correct specification (NLS.1).

- ▶ Defining $u := y - m(\mathbf{x}, \boldsymbol{\theta}_o)$, may write

$$y = m(\mathbf{x}, \boldsymbol{\theta}_o) + u, \quad E(u | \mathbf{x}) = 0.$$

- ▶ $E(u | \mathbf{x}) = 0$ a consequence of model.

- ▶ Not an additional assumption.

- ▶ Error formulation useful for abbreviations.

Discussion

- ▶ $E(u|\mathbf{x}) = 0$ does *not* imply u and \mathbf{x} independent.
- ▶ ... only cond'l *mean* independence.
 - ▶ May have $\text{var}(u|\mathbf{x})$ nonconstant (in \mathbf{x}).
heteroskedasticity
 - ▶ If $y \geq 0$, must have $u \geq -m(\mathbf{x}, \theta_o) \dots$
- ▶ Error formulation yields *semiparametric* model for $y|\mathbf{x}$.
 - ▶ Parametric model for $E(y|\mathbf{x})$.
 - ▶ But haven't specified parametric distribution for $u|\mathbf{x}$.

Identification

Identification

We'll show: θ_o solves **population problem (PP)**

$$\min_{\theta \in \Theta} E \{ [y - m(\mathbf{x}, \theta)]^2 \}.$$

- ▶ Model m + parameter space Θ known quantities.
- ▶ Hence, **IF** given distribution of (y, \mathbf{x}) , PP problem known.
- ▶ θ_o identified if PP solution *unique*.

there is one and only one solution to the population
-> there cannot be another set of parameters that solves the population problem

Identification

$\pm m(\mathbf{x}, \theta_o)$ and expanding square,

$$\begin{aligned} [y - m(\mathbf{x}, \theta)]^2 &= \{[y - \overset{u}{m}(\mathbf{x}, \theta_o)] - [m(\mathbf{x}, \theta) - \overset{u}{m}(\mathbf{x}, \theta_o)]\}^2 \\ &= [y - m(\mathbf{x}, \theta_o)]^2 + [m(\mathbf{x}, \theta) - m(\mathbf{x}, \theta_o)]^2 \\ &\quad - 2u[m(\mathbf{x}, \theta) - m(\mathbf{x}, \theta_o)]. \end{aligned}$$

Taking expectations,

$$\begin{aligned} E\{[y - m(\mathbf{x}, \theta)]^2\} &= E\{[y - m(\mathbf{x}, \theta_o)]^2\} \\ &\quad + E\{[m(\mathbf{x}, \theta) - m(\mathbf{x}, \theta_o)]^2\}. \end{aligned}$$

Critera @ θ

$E(u(x)) = 0$
Criteria @ θ_o

Identification

Have shown

"Population criterion function"

$$E\{[y - m(\mathbf{x}, \theta)]^2\} = E\{[y - m(\mathbf{x}, \theta_o)]^2\} + E\{[m(\mathbf{x}, \theta) - m(\mathbf{x}, \theta_o)]^2\}.$$

Handwritten red annotations: A bracket above the first term on the right, an arrow pointing from the second term to the right, and a red ≥ 0 with an arrow pointing to the second term.

It follows that

$$E\{[y - m(\mathbf{x}, \theta)]^2\} \geq E\{[y - m(\mathbf{x}, \theta_o)]^2\} \text{ for all } \theta \in \Theta.$$

$\Rightarrow \theta_o$ solves PP.

Handwritten red text: $\theta_o \text{ argmin } E[y - m(\mathbf{x}, \theta)]^2$
 $(=)$

Q: Uniqueness? does not yield uniqueness

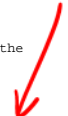
Identification Condition

Have shown

$$E\{ [y - m(\mathbf{x}, \theta)]^2 \} = E\{ [y - m(\mathbf{x}, \theta_o)]^2 \} + E\{ [m(\mathbf{x}, \theta) - m(\mathbf{x}, \theta_o)]^2 \}.$$

the true value of theta is A minimizer of the population problem

expected square distance between our two models for the conditional mean (no 1 is cond.mean for candidate regressors, no 2 is the 'true' cond.mean)



θ_o uniquely solves PP if and only if

$$E\{ [m(\mathbf{x}, \theta) - m(\mathbf{x}, \theta_o)]^2 \} > 0 \text{ for all } \theta \in \Theta \setminus \{\theta_o\}.$$

Q: When will identification fail?

Whenever we have multiple solutions to the population problem

Identification Failures / Successes

Example: Linear regression, $m(\mathbf{x}, \boldsymbol{\theta}) = \mathbf{x}\boldsymbol{\theta}$ with $\Theta = \mathbb{R}^K$.

Here

$$\begin{aligned} E\{ [m(\mathbf{x}, \boldsymbol{\theta}) - m(\mathbf{x}, \boldsymbol{\theta}_0)]^2 \} &= E\{ [\mathbf{x}(\boldsymbol{\theta} - \boldsymbol{\theta}_0)]^2 \} \\ &= (\boldsymbol{\theta} - \boldsymbol{\theta}_0)' E(\mathbf{x}'\mathbf{x}) (\boldsymbol{\theta} - \boldsymbol{\theta}_0). \end{aligned}$$

for all $\boldsymbol{\theta}$ diff than $\boldsymbol{\theta}_0$

- ▶ > 0 if $E(\mathbf{x}'\mathbf{x})$ positive definite.

columns must be linearly independent

"FULL RANK"

- ▶ Just usual (population) rank condition.

OLS.2 (?)

If $E(\mathbf{x}'\mathbf{x})$ singular

$\exists \mathbf{v} \neq \mathbf{0}$ s.t.

$$\begin{aligned} E(\mathbf{x}'\mathbf{x})\mathbf{v} &= \mathbf{0} \quad \cdot \quad \boldsymbol{\theta} = \boldsymbol{\theta}_0 + \mathbf{v} \\ &= \mathbf{v}' E(\mathbf{x}'\mathbf{x}) \mathbf{v} = 0. \end{aligned}$$

Identification Failures

= multiple solution to the population problem!

Example: *Nonlinear* regression with

$$m(\mathbf{x}, \boldsymbol{\theta}) = \theta_1 + \theta_2 x_2 + \theta_3 x_3^{\theta_4}.$$

- ▶ Suppose $\theta_{o3} = 0$. (Truth linear.)
- ▶ At $\boldsymbol{\theta}$ with $\theta_3 = 0 (= \theta_{o3})$...
- ▶ ... criterion function *independent of* θ_4 .
- ▶ For this $\boldsymbol{\theta}_o$, identification fails.
- ▶ Example of **poorly identified model**.

"\theta_4 disappears"

Estimation

Estimation

ANALOGY PRINCIPLE

TURN THE POPULATION PROBLEM INTO ITS SAMPLE COUNTERPART

θ_o solves PP,

$$\theta_o \in \operatorname{argmin}_{\theta \in \Theta} E \{ [y - m(\mathbf{x}, \theta)]^2 \}.$$

Analogy principle suggests,

$$\hat{\theta} = \hat{\theta}_N \in \operatorname{argmin}_{\theta \in \Theta} \frac{1}{N} \sum_{i=1}^N [y_i - m(\mathbf{x}_i, \theta)]^2.$$

Nonlinear least squares (NLS) estimator.

For now, assume existence (but not uniqueness) of solution.

Consistency? $\hat{\theta}_N \xrightarrow{p} \theta_o$

Q: Does NLS consistently estimate θ_o ?

It turns out answer is “yes,” provided (roughly)

1. θ_o is identified,
2. Criterion function convergence

$$\frac{1}{N} \sum_{i=1}^N [y_i - m(\mathbf{x}_i, \boldsymbol{\theta})]^2 \xrightarrow{p} E\{[y - m(\mathbf{x}, \boldsymbol{\theta})]^2\}$$

... in suitable sense.

'a heuristic convergence' = in a calculated-guess kind of sense

Next: More detail in general setting.

M-Estimation

M-Estimand

"Target estimation"

We now consider more abstract setting.

Let $q(\mathbf{w}, \theta)$ denote function of

1. random vector \mathbf{w} [observables, e.g. $\mathbf{w} = (\mathbf{y}, \mathbf{x})$],
2. parameters θ .

True parameter θ_o assumed unique solution to PP

$$\theta_o = \underset{\theta \in \Theta}{\operatorname{argmin}} E [q(\mathbf{w}, \theta)] .$$

“M” short for “minimization.”

► Or “maximization” (sign change).

q sometimes called loss function.

M-Estimator

Given random (as in i.i.d.) sample $\{\mathbf{w}_i\}_1^N$.

Analogy principle suggests **sample problem (SP)**

$$\min_{\theta \in \Theta} \frac{1}{N} \sum_{i=1}^N q(\mathbf{w}_i, \theta).$$

Definition: Any SP solution is an **M-estimator** of θ_o .

Example M-Estimators

- ▶ OLS: $q(\mathbf{w}, \boldsymbol{\theta}) = (y - \mathbf{x}\boldsymbol{\theta})^2$.
- ▶ NLS: $q(\mathbf{w}, \boldsymbol{\theta}) = [y - m(\mathbf{x}, \boldsymbol{\theta})]^2$.
- ▶ Maximum likelihood: $q(\mathbf{w}, \boldsymbol{\theta}) = -\ln f(y | \mathbf{x}; \boldsymbol{\theta})$.
- ▶ Least absolute deviations (LAD): $q(\mathbf{w}, \boldsymbol{\theta}) = |y - \mathbf{x}\boldsymbol{\theta}|$.
- ▶ ...and many, many more.

Scope of Framework

Observables \mathbf{w}_i allow scalar/vector outcome.

- ▶ One equation, one cross section \Rightarrow scalar y_i .
- ▶ Multiple equations, one cross section \Rightarrow vector \mathbf{y}_i .
 - ▶ **Ex:** Joint labor supply decision (wife/husband),

y_i^w = labor supply, wife, family i ,

y_i^h = labor supply, husband, family i .

- ▶ One equation, panel data \Rightarrow vector $\mathbf{y}_i = (y_{i1}, \dots, y_{iT})'$.
 - ▶ FE: $q(\mathbf{w}_i, \boldsymbol{\theta}) = \sum_{t=1}^T (\ddot{y}_{it} - \ddot{\mathbf{x}}_{it}\boldsymbol{\theta})^2$

Formulation very general!

Asymptotic Properties of M-Estimators

Recap: Setting

M-estimand solves population problem (PP),

$$\theta_o \in \operatorname{argmin}_{\theta \in \Theta} E[q(\mathbf{w}, \theta)] .$$

M-estimator solves sample problem (SP),

$$\hat{\theta} \in \operatorname{argmin}_{\theta \in \Theta} \frac{1}{N} \sum_{i=1}^N q(\mathbf{w}_i, \theta) .$$

Q: Properties?

Consistency

Informal Look at Consistency

Criterion functions (minimands) and minimizers:

$$N^{-1} \sum_{i=1}^N q(\mathbf{w}_i, \boldsymbol{\theta})$$

$$E [q(\mathbf{w}, \boldsymbol{\theta})]$$

$$\hat{\boldsymbol{\theta}}$$

$$\boldsymbol{\theta}_o$$

Q: Relationships?

Informal Look at Consistency

By definition of M-estimand and M-estimator:

$$N^{-1} \sum_{i=1}^N q(\mathbf{w}_i, \boldsymbol{\theta})$$

argmin

$$\hat{\boldsymbol{\theta}}$$

$$E[q(\mathbf{w}, \boldsymbol{\theta})]$$

argmin

$$\boldsymbol{\theta}_o$$

Informal Look at Consistency

By (weak) law of large numbers,

$$\underset{\hat{\boldsymbol{\theta}}}{\operatorname{argmin}} N^{-1} \sum_{i=1}^N q(\mathbf{w}_i, \boldsymbol{\theta}) \xrightarrow{P} \underset{\boldsymbol{\theta}_o}{\operatorname{argmin}} E[q(\mathbf{w}, \boldsymbol{\theta})]$$

Informal Look at Consistency

$$\begin{array}{ccc} N^{-1} \sum_{i=1}^N q(\mathbf{w}_i, \boldsymbol{\theta}) & \xrightarrow{P} & E[q(\mathbf{w}, \boldsymbol{\theta})] \\ \text{argmin} & & \text{argmin} \\ \hat{\boldsymbol{\theta}} & \xrightarrow[\text{?}]{P} & \boldsymbol{\theta}_o \end{array}$$

Seems reasonable...

Q: When does *minimand* convergence imply *minimizer* convergence (in prob).

Formal Look at Consistency

Q: When is $\hat{\boldsymbol{\theta}}$ consistent for $\boldsymbol{\theta}_o$?

Suffices (essentially) following two conditions hold:

1. **Identification:** $\boldsymbol{\theta}_o$ is identified.
2. **Uniform Law of Large Numbers:** S minimand converges to P equivalent *uniformly in probability*,

$$\max_{\boldsymbol{\theta} \in \Theta} \left| \frac{1}{N} \sum_{i=1}^N q(\mathbf{w}_i, \boldsymbol{\theta}) - E[q(\mathbf{w}, \boldsymbol{\theta})] \right| \xrightarrow{P} 0.$$

Identification Assumption

At this level of abstractness, *assume* identification, i.e.

$$E[q(\mathbf{w}, \theta)] > E[q(\mathbf{w}, \theta_o)] \text{ for all } \theta \in \Theta \setminus \{\theta_o\}.$$

any theta different than the true one

In words: θ_o unique solution to PP.

- May make less abstract in applications (later).

Uniform Law of Large Numbers

May *deduce* minimand convergence using:

Theorem (W. Theorem 12.1)

If

1. $\Theta \subseteq \mathbb{R}^P$ compact (i.e. closed + bounded),
2. $q(\mathbf{w}, \cdot)$ continuous (in θ), no matter the value of \mathbf{w} (random vector of observables)

and additional technical conditions hold, then

$$\max_{\theta \in \Theta} \left| \frac{1}{N} \sum_{i=1}^N q(\mathbf{w}_i, \theta) - E[q(\mathbf{w}, \theta)] \right| \xrightarrow{P} 0.$$

sample criterion function converges in probability to its
population equivalent

Uniform law of large numbers (ULLN).

Consistency Theorem

Theorem (W. Theorem 12.2)

Under the assumptions of W. Theorem 12.1 (ULLN) and assuming identification of θ_o ,

1. $\hat{\theta}$ solves SP, and
2. $\hat{\theta}$ is consistent for θ_o , $\hat{\theta} \rightarrow_p \theta_o$.

More Formal Consistency Argument

Proof Sketch:

1. Compact $\Theta + q(\mathbf{w}, \cdot)$ continuous \Rightarrow SP solution exists.

Weierstrass Ext Value Thm.

► Why?

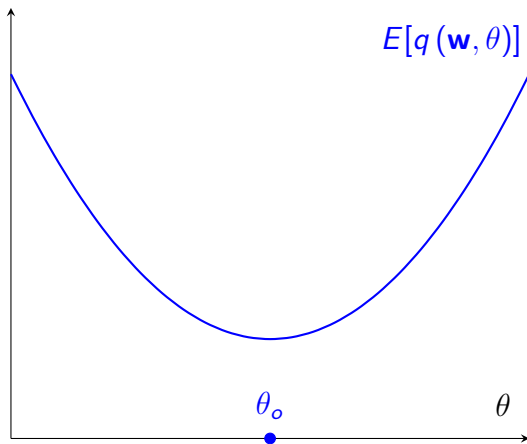
cont'd fctn defined on compact space attains its extrema.

2. ULLN \Rightarrow in limit, S/P minimands coincide (in prob).

(maxima/minima)

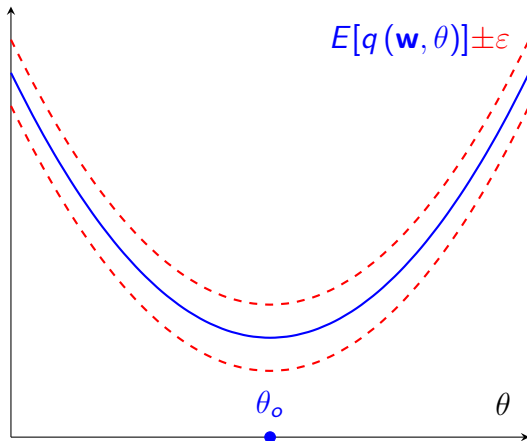
3. Identification implies unique PP solution, so must have $\hat{\theta} \rightarrow_p \theta_o$.

Graphical Illustration of Consistency

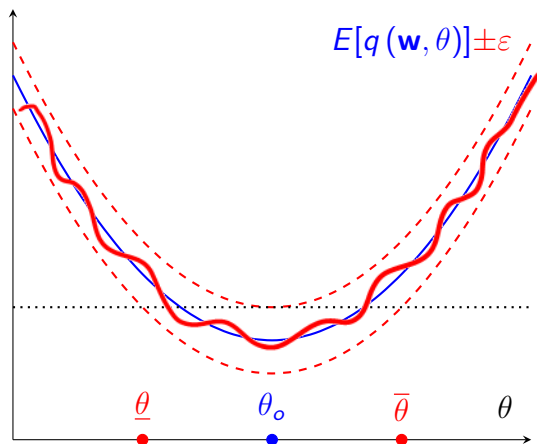


Graphical Illustration of Consistency

When minimand difference $\leq \varepsilon$, S minimand in “sleeve”




Graphical Illustration of Consistency



$\hat{\theta}$ “squeezed in”

Role of Uniform Convergence

Consider (deterministic) functions

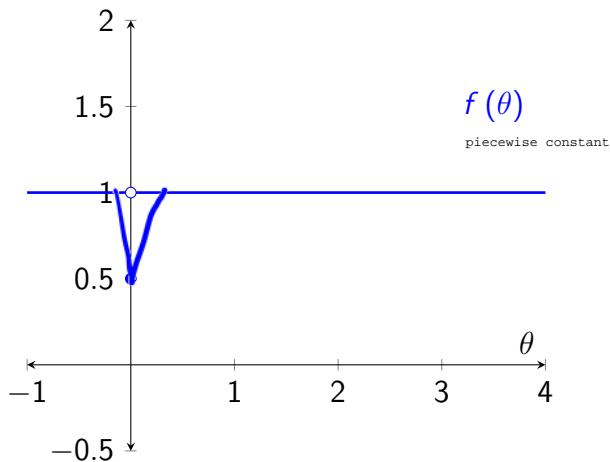
$$f_n(\theta) := \begin{cases} \frac{1}{2}, & \theta = 0, \\ 0, & \theta = n, \\ 1, & \text{otherwise.} \end{cases} \implies \operatorname{argmin} f_n = \underline{n} \quad (\approx \hat{\theta})$$


For **each** θ , $f_n(\theta) \rightarrow f(\theta)$ where

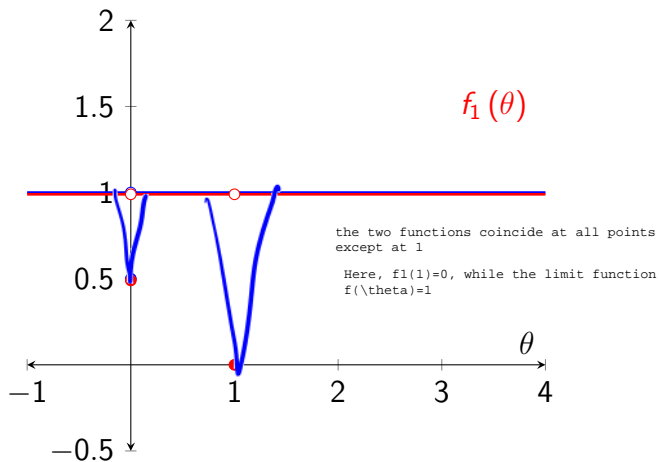
$$f(\theta) := \begin{cases} \frac{1}{2}, & \theta = 0, \\ 1, & \theta \neq 0. \end{cases} \implies \operatorname{argmin} f = \underline{0}$$

► Minimizer? escaping to the horizon. The sequence of minimizers grows without bound

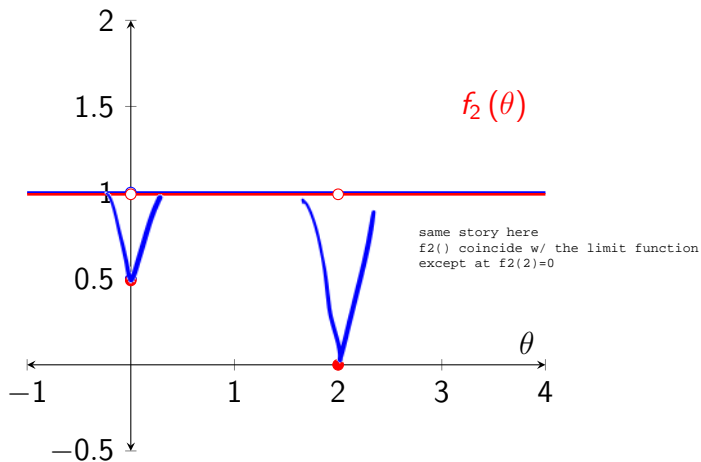
Escape to Horizon



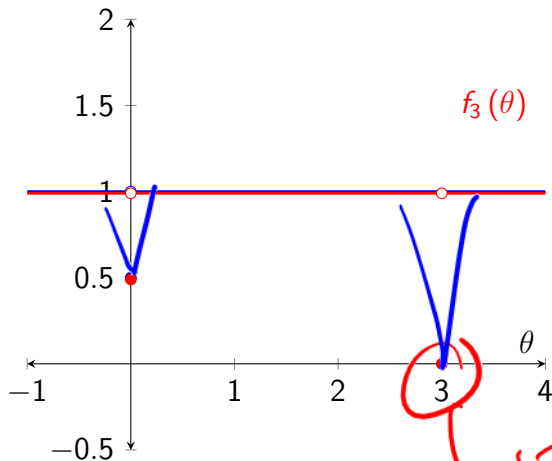
Escape to Horizon



Escape to Horizon



Escape to Horizon



Role of Uniform Convergence

- **Problem?** why don't we see minimizer convergence? Convergence is not sufficiently uniform.

$$\max_{\theta \in \mathbb{R}} |f_n(\theta) - f(\theta)| = \underline{1} \quad |f_n(n) - f(n)| = |0 - 1| = 1$$

they coincide at every point,
except at a single point

the difference being 1 for all n as n grows without
bound

- Similar problem with f_n stochastic.

- Example ruled out by **compactness**.

compact = closed and bounded (?)

- $\Theta = \mathbb{R}$ *unbounded*.

since it is unbounded, it is not compact
in other words, it is not continuous?

Necessity of Uniform Convergence

- ▶ Uniform convergence sufficient but not necessary.
- ▶ Think: Linear model + squared loss

$$q(\mathbf{w}, \theta) = (y - \mathbf{x}\theta)^2.$$

- ▶ Natural parameter space entire \mathbb{R}^P .
- ▶ Estimator in closed form.
- ▶ Uniform convergence/compactness not needed.
- ▶ Here: We use it to *deduce* minimizer convergence.

Normality

Additional Assumptions

Have for **consistency** invoked:

- ▶ θ_o identified unique solution/minimizer of the population objective function
- ▶ Θ compact
A compact set is for example $[0,1]$, but not $(0,1)$ -> we have closed endpoints
need to have finite amount of parameters in the parameter space
- ▶ $q(\mathbf{w}, \cdot)$ continuous
- ▶ (+ technical...)

Asymptotic normality requires *stronger* assumptions.

Additional Assumptions

For **asymptotic normality**, add:

- ▶ θ_o interior to Θ . [Draw]
- ▶ $q(\mathbf{w}, \cdot)$ twice continuously differentiable on $\text{int } \Theta$

Remarks:

- ▶ Interiority requires $\text{int } \Theta$ nonempty
- ▶ ... used to expand around θ_o
- ▶ **Twice** cont' diff' facilitates **second**-order expansion.

Additional Assumptions

Abbreviate

$$\text{Score: } \mathbf{s}(\mathbf{w}, \boldsymbol{\theta}) := \frac{\partial}{\partial \boldsymbol{\theta}} q(\mathbf{w}, \boldsymbol{\theta}), \quad (P \times 1)$$

implies we are looking at
the transposed derivative
of q w.r.t θ

$$\text{Hessian: } \mathbf{H}(\mathbf{w}, \boldsymbol{\theta}) := \frac{\partial^2}{\partial \boldsymbol{\theta} \partial \boldsymbol{\theta}'} q(\mathbf{w}, \boldsymbol{\theta}). \quad (P \times P)$$

"
 $\frac{\partial}{\partial \boldsymbol{\theta}'} s(\mathbf{w}, \boldsymbol{\theta})$

Further add:

$$\blacktriangleright E[\mathbf{s}(\mathbf{w}, \boldsymbol{\theta}_o)] = \mathbf{0},$$

score func evaluated at the true value of θ is zero

$$\blacktriangleright E[\mathbf{H}(\mathbf{w}, \boldsymbol{\theta}_o)] \text{ positive definite.}$$

Full rank condition

No linearly dependent columns \rightarrow all columns are linearly independent

\blacktriangleright Essentially follow from FOC/SOC of minimization.

Let \mathbf{A} be an $(n \times K)$ matrix with $\text{rank}(\mathbf{A}) = K$:

$\mathbf{A}'\mathbf{A}$ is always positive definite and therefore nonsingular.

Asymptotic Normality of M-Estimators

Theorem (W. Thm 12.3)

Provided

- ▶ θ_o identified + interior to Θ compact, convexity
- ▶ $q(\mathbf{w}, \cdot)$ cont' + twice cont' diff' on int Θ ,
- ▶ $E[\mathbf{s}(\mathbf{w}, \theta_o)] = \mathbf{0}$, and $E[\mathbf{H}(\mathbf{w}, \theta_o)]$ positive definite, } ~ FOC / SOC
- ▶ (+ technical),

= ✓

$$\sqrt{N}(\hat{\theta} - \theta_o) \xrightarrow{d} N(\mathbf{0}, \mathbf{A}_o^{-1} \mathbf{B}_o \mathbf{A}_o^{-1}),$$
$$\mathbf{A}_o := E[\mathbf{H}(\mathbf{w}, \theta_o)],$$
$$\mathbf{B}_o := E[\mathbf{s}(\mathbf{w}, \theta_o) \mathbf{s}(\mathbf{w}, \theta_o)'] .$$

Mean Value Theorem

- ▶ Normality proof relies on *mean value theorem*.
- ▶ Consider *scalar* case ($P = 1$).

Mean Value Theorem (MVT):

- ▶ Let $f : [a, b] \rightarrow \mathbb{R}$ continuous + differentiable on (a, b) .
- ▶ Then for some $c \in (a, b)$,

$$f(b) - f(a) = f'(c)(b - a).$$

- ▶ Slope of secant attained somewhere in between. [Draw]

Proof Sketch

- ▶ In scalar ($P = 1$) case,

$$s(\mathbf{w}, \theta) = \frac{\partial}{\partial \theta} q(\mathbf{w}, \theta), \quad H(\mathbf{w}, \theta) = \frac{\partial^2}{\partial^2 \theta} q(\mathbf{w}, \theta).$$

- ▶ Twice cont' diff' + MVT with $f = \text{score average}$,

$$\frac{1}{N} \sum_{i=1}^N s(\mathbf{w}_i, \hat{\theta}) - \frac{1}{N} \sum_{i=1}^N s(\mathbf{w}_i, \theta_o) = \frac{1}{N} \sum_{i=1}^N H(\mathbf{w}_i, \bar{\theta}) (\hat{\theta} - \theta_o).$$

- ▶ $\hat{\theta} \in \text{int } \Theta$ w.p.a.1. (consistency)

- ▶ solves SP, so LHS vanishes. (FOC.)

Proof Sketch

Have argued:

$$-\frac{1}{N} \sum_{i=1}^N s(\mathbf{w}_i, \theta_o) = \frac{1}{N} \sum_{i=1}^N H(\mathbf{w}_i, \bar{\theta}) (\hat{\theta} - \theta_o).$$

Isolate $\hat{\theta} - \theta_o$ and $\times \sqrt{N}$:

$$\sqrt{N}(\hat{\theta} - \theta_o) = \left[-\frac{1}{\sqrt{N}} \sum_{i=1}^N s(\mathbf{w}_i, \theta_o) \right] / \left[\frac{1}{N} \sum_{i=1}^N H(\mathbf{w}_i, \bar{\theta}) \right].$$

Analyze each RHS factor in turn.

Proof Sketch

$$\sqrt{N}(\hat{\theta} - \theta_o) = \left[-\frac{1}{\sqrt{N}} \sum_{i=1}^N s(\mathbf{w}_i, \theta_o) \right] / \left[\frac{1}{N} \sum_{i=1}^N H(\mathbf{w}_i, \bar{\theta}) \right].$$

- ▶ $\bar{\theta}$ trapped between $\hat{\theta}$ and $\theta_o \Rightarrow \bar{\theta} \rightarrow_p \theta_o$.
- ▶ So $N^{-1} \sum_{i=1}^N H(\mathbf{w}_i, \bar{\theta}) \approx N^{-1} \sum_{i=1}^N H(\mathbf{w}_i, \theta_o)$ (ULLN).
- ▶ $N^{-1} \sum_{i=1}^N H(\mathbf{w}_i, \theta_o) \rightarrow_p E[H(\mathbf{w}, \theta_o)] = A_o > 0$ (p.d.),

$$\Rightarrow 1 / \left[\frac{1}{N} \sum_{i=1}^N H(\mathbf{w}_i, \bar{\theta}) \right] \xrightarrow{p} 1/A_o. \quad (\text{CMT/Slutsky})$$

Proof Sketch

$$\sqrt{N}(\hat{\theta} - \theta_o) = \left[-\frac{1}{\sqrt{N}} \sum_{i=1}^N s(\mathbf{w}_i, \theta_o) \right] / \left[\frac{1}{N} \sum_{i=1}^N H(\mathbf{w}_i, \bar{\theta}) \right].$$

► Mean zero scores + CLT ensure

$$\frac{1}{\sqrt{N}} \sum_{i=1}^N s(\mathbf{w}_i, \theta_o) \xrightarrow{d} N(0, B_o), \quad B_o = E[s(\mathbf{w}, \theta_o)^2].$$

Proof Sketch

Harvesting our results,

$$\begin{aligned}\sqrt{N}(\hat{\theta} - \theta_o) &= \underbrace{\left[-\frac{1}{\sqrt{N}} \sum_{i=1}^N s(\mathbf{w}_i, \theta_o) \right]}_{\rightarrow_d N(0, B_o)} / \underbrace{\left[\frac{1}{N} \sum_{i=1}^N H(\mathbf{w}_i, \bar{\theta}) \right]}_{\rightarrow_p 1/A_o} \\ &\stackrel{d}{\rightarrow} N(0, B_o) / A_o \quad (\text{product rule/Slutsky}) \\ &\stackrel{d}{=} N(0, B_o / A_o^2) .\end{aligned}$$

Handwritten blue notes: A blue checkmark is under the final result. To the right, the expression $A_o^{-1} B_o A_o^{-1}$ is written in blue.

► Vector-case proof follows similarly:

1. Linear approximation (MVT)
2. Convergence of inverse Hessian term (ULLN+CMT)
3. CLT + Product rule.

Discussion

- ▶ Thm. gives conditions for *any* M-estimator to be asymptotically normal.
- ▶ Implies sandwich form

$$\text{Avar}(\hat{\boldsymbol{\theta}}) = \mathbf{A}_o^{-1} \mathbf{B}_o \mathbf{A}_o^{-1} / N.$$

- ▶ Akin to earlier results (with estimators in closed form).
- ▶ Note: $\text{Avar}(\hat{\boldsymbol{\theta}})$ depends on \boldsymbol{q} .
- ▶ We prefer low variance.

Discussion

Q: \mathbf{A}_0 must be invertible? How does this work in a HD-setting?

- ▶ $\mathbf{A}_o = E[\mathbf{H}(\mathbf{w}, \boldsymbol{\theta}_o)]$ assumed **positive definite**.
- ▶ Zero on diagonal \approx infinite variance (through \mathbf{A}_o^{-1})
- ▶ Failure of p.d \approx P minimand flat around $\boldsymbol{\theta}_o$
- ▶ \approx Identification failure.

Role of Interiority

We used $\boldsymbol{\theta}_o \in \text{int } \Theta$ for differentiation

Q: What if $\boldsymbol{\theta}_o$ on boundary of parameter space?

A: No reason to expect \sqrt{N} -asymptotic normality.

Example: Parameter on Boundary

Let $y_i \sim \text{i.i.d.}(\theta_o, 1)$ with θ_o known ≥ 0 .

Nonnegativity enforced

$$\hat{\theta} = \underset{\theta \geq 0}{\operatorname{argmin}} \frac{1}{N} \sum_{i=1}^N (y_i - \theta)^2 = \max(0, \bar{y}),$$

If $\theta_o = 0$ (boundary case), then $\sqrt{N}(\hat{\theta} - 0) \geq 0$.

$\sqrt{N}(\hat{\theta} - 0)$ does $\rightarrow_d \dots$ but not to normal. [Whiteboard]