



Dynamics in Linear Panel Data

Advanced Microeconometrics

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2022



1. Intro
2. Dynamic Models
3. Sequential Exogeneity
4. GMM
5. Arellano-Bond

Intro

Where are we in the course?

Part	Topic	Parameterization non-linear	Estimation non-linear	Dimension $\dim(x)$	Numerical optimization	M-estimation (Part III)	Outcome (y_i)	Panel (c_i)
I	OLS	÷	÷	low	÷	✓	\mathbb{R}	✓
II	LASSO	÷	✓	high	✓	÷	\mathbb{R}	÷
IV	Probit	✓	✓	low	✓	✓	$\{0, 1\}$	÷
	Tobit	✓	✓	low	✓	✓	$[0; \infty)$	÷
	Logit	✓	✓	low	✓	✓	$\{1, 2, \dots, J\}$	÷
	Sample selection	✓	✓	low	✓	✓	\mathbb{R} and $\{0, 1\}$	÷
	Simulated Likelihood	✓	✓	low	✓	✓	Any	✓
	Quantile Regression	÷	✓	(low)	✓	✓	\mathbb{R}	÷
	Non-parametric	✓	(✓)	∞	÷	÷	\mathbb{R}	÷

The case for active labor market policies

Data shows that there is a *correlation* between low earnings and exposure to long spells of unemployment. Many countries have programmes to push unemployed into work. Randomly pick a side and argue with your neighbor:

1. ALPs prevent a self-reinforcing negative spiral (e.g. self-confidence, human capital, network, ...)
2. ALPs are wasteful due to selection (e.g. meaningless bureaucratic tasks for those unable to work)

Relate the discussion to the Dynamic FE model below.

Dynamic FE Model

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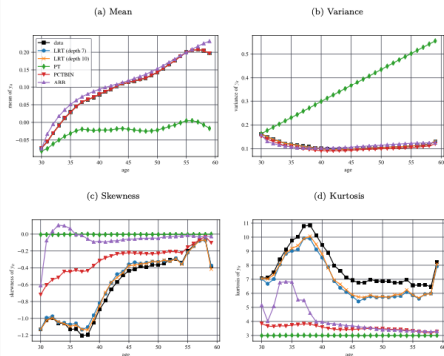
Discuss

What's observably different between

1. High σ_c and low ρ , (“unobserved heterogeneity”)
2. High ρ , low σ_c (“true state dependence”).

What is the role of unemployment insurance depending on which regime is true?

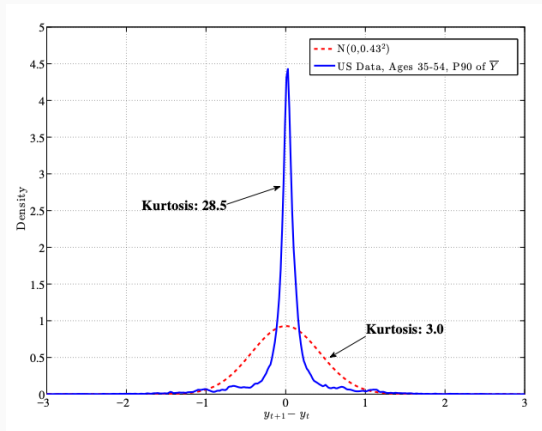
Figure 3.1: Log income over the life-cycle



- First four moments of the cross-sectional income distribution over the life-cycle.
- Black = data, green = model used in nearly all macro models.

Source: Druedahl & Munk-Nielsen (2020)

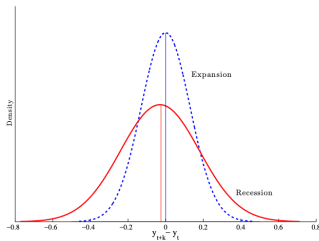
New insights into old issues



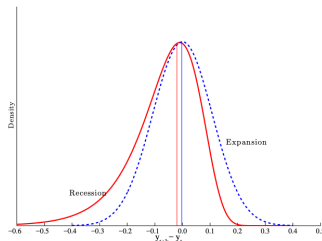
- Income growth is a lot more heavy-tailed than a log normal can produce.

Source: Guvenen 2016

Myth: countercyclical variance



Fact: procyclical skewness



■ Interpretation:

- Myth: in recessions, the (symmetric) income risk increases.
- Fact: in recessions, you risk a large drop and probably will not get a bonus.

Source: Guvenen 2016

Figure 1: AR(1) Estimate: POLS

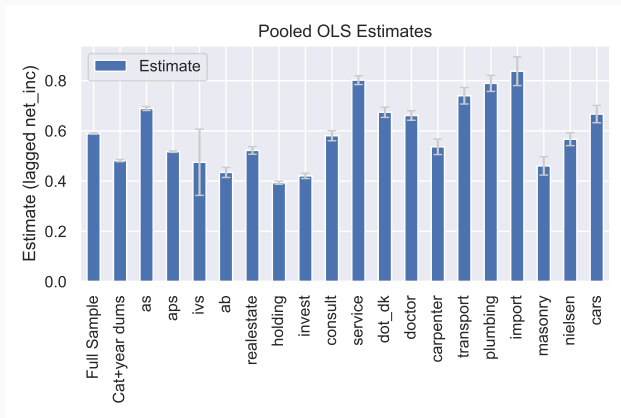
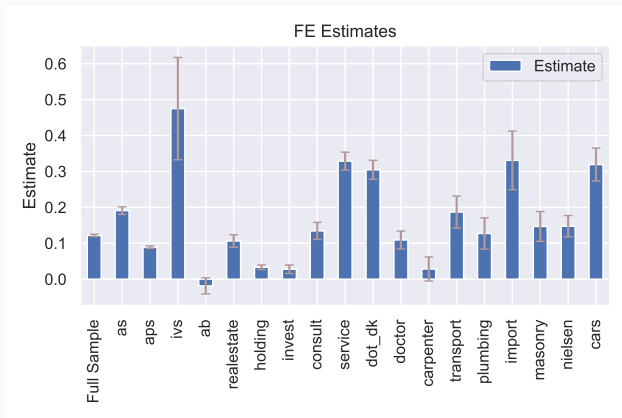


Figure 2: AR(1) Estimate: FE



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- **The Arellano-Bond Estimator:** FD estimation of an AR(1) model with fixed effects using instruments.
- **Put differently**, the plan is
 1. Why FD and FE don't work,
 2. Why we can rescue FD with IV,
 3. How we can do big brain IV.

Dynamic Models

In this section:

1. Including y_{it-1} as regressor causes strict exogeneity (SE) breakdown
2. FE requires SE
3. FD requires something slightly weaker
4. What about y_{i0} ? (initial conditions)

Dynamic RE Model

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- **RE:** if $E(c_i \mathbf{x}_{it}) \neq \mathbf{0}$, we cannot use RE or POLS.
- **Strict exogeneity:** $E(u_{it} | \mathbf{Z}_i, c_i) = 0 \Rightarrow$ FE/FD are consistent.
 - Generally, we assume $c_i \perp\!\!\!\perp u_{it}$, so $E(u_{it} | \mathbf{Z}_i, c_i) = E(u_{it} | \mathbf{Z}_i)$
(" $\perp\!\!\!\perp$ " signifies independence)

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- **Problem:** y_{it} is in \mathbf{z}_{it+1} , and y_{it} is a function of u_{it} , so future regressors have information on the current outcome...
 - ... proved mathematically on next slide \rightarrow

Dynamic panel data model

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Define the “regressors” $\mathbf{z}_{it} \equiv (y_{it-1}, \mathbf{x}_{it})$.

- **Proposition:** strict exogeneity (SE), $E(u_{it}|\mathbf{z}_{i1}, \dots, \mathbf{z}_{iT}) = 0$, breaks down when y_{it-1} is a regressor.

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- **Proof:** Note that if SE holds, then in particular $E(u_{it}\mathbf{z}_{is}) = \mathbf{0}$ must hold for all (t, s) .
- **Consider** $s = t + 1$. Then $\mathbf{z}_{it+1} = (y_{it}, \mathbf{x}_{it+1})$, so

$$\begin{aligned} E(u_{it}y_{it}) &= E[\mathbf{u}_{it}(\rho y_{it-1} + \mathbf{x}_{it+1}\beta + c_i + u_{it})] \\ &= E(u_{it}^2) = \sigma_u^2 > 0. \quad \blacksquare \end{aligned}$$

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 - \Rightarrow unobserved effects induce **spurious state dependence**:
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- \Rightarrow POLS is inconsistent.

Note: It doesn't have to be an AR(1) model; regressors can have dynamics.

Static model with feedback

$$y_{it} = \mathbf{z}_{it}\beta + \delta h_{it} + c_i + u_{it}$$

$$h_{it} = \mathbf{z}_{it}\xi + \eta y_{it-1} + r_{it}$$

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- **Claim:** Strict exogeneity is violated by h_{it} .
- **Proof:** take h_{it+1} and u_{it} :

$$\begin{aligned} E(u_{it} h_{it+1}) &= E[(z_{it+1}\xi + \eta y_{it} + r_{it+1})u_{it}] \\ &= \dots + \underbrace{\eta E(u_{it} u_{it})}_{\neq 0} + \dots \quad \blacksquare \end{aligned}$$

Claim

FE requires $E(u_{it}|\mathbf{z}_i) = 0$ (strict exogeneity) for consistency.

- **Why?** The transformed error term, $\ddot{u}_{it} \equiv u_{it} - \bar{u}_i$, must be exogenous to transformed regressors, $\ddot{\mathbf{z}}_{it} \equiv \mathbf{z}_{it} - \bar{\mathbf{z}}_i$.

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- Writing out:

$$\begin{aligned} E(\ddot{\mathbf{z}}'_{it} \ddot{u}_{it}) &= E[(\mathbf{z}_{it} - \bar{\mathbf{z}}_i)'(u_{it} - \bar{u}_i)] \\ &= E(\mathbf{z}'_{it} u_{it}) + E(\bar{\mathbf{z}}'_i \bar{u}_i) - E(\bar{\mathbf{z}}'_i u_{it}) - E(\mathbf{z}'_{it} \bar{u}_i). \end{aligned}$$

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- Take e.g. $E(\bar{\mathbf{z}}'_i u_{it}) = T^{-1} \sum_{s=1}^T E(\mathbf{z}'_{is} u_{it})$.
 - Hence, if $E(u_{it} \mathbf{z}_{is}) \neq 0$ for some s , then $E(\bar{\mathbf{z}}'_i u_{it}) \neq 0$.

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FD only requires $E(u_{it} | \mathbf{z}_{it+1}, \mathbf{z}_{it}, \mathbf{z}_{it-1}) = 0$ for consistency.

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- **Contemporaneous exogeneity** only implies $E(\mathbf{z}_{it} u_{it}) = 0$ and $E(\mathbf{z}_{it-1} u_{it-1}) = 0$.

AR(1) model

$$y_{it} = \rho y_{it-1} + c_i + u_{it}, \quad u_{it} \sim \text{IID}(0, \sigma_u^2), c_i \sim \text{IID}(0, \sigma_\alpha^2).$$

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- **Transforming** with FD, we get

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- **Transforming** with FD, we get

$$\Delta y_{it} = \rho \Delta y_{it-1} + \Delta u_{it}.$$

- **Check exogeneity:**

$$\begin{aligned} E(\Delta y_{it-1} \Delta u_{it}) &= E(y_{it-1} u_{it}) - E(y_{it-1} u_{it-1}) \\ &\quad - E(y_{it-2} u_{it}) + E(y_{it-2} u_{it-1}). \end{aligned}$$

- Enough to show that $E(y_{it-1} u_{it-1}) \neq 0$ to show $E(\Delta y_{it-1} \Delta u_{it}) \neq 0$.

Claim

$$E(y_{it-1}u_{it-1}) \neq 0$$

- **Proof:** note that

$$\begin{aligned} E(y_{it-1}u_{it-1}) &= E[(\rho y_{it-2} + c_i + u_{it-1})u_{it-1}] \\ &= \underbrace{E(\rho y_{it-2}u_{it-1})}_{=0} \underbrace{(*)} + \underbrace{E(c_i u_{it-1})}_{=0} + \underbrace{E(u_{it-1}^2)}_{=\sigma_u^2} \end{aligned}$$

- where $E(c_i u_{it}) = 0$ for all t (by independence assumption)

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(*)

- where $E(c_i u_{it}) = 0$ for all t (by independence assumption)
- **In conclusion:** $E(y_{it-1}u_{it-1}) = \sigma_u^2 > 0$. ■

- **Continuing** the recursion yields $j \rightarrow \infty$ consider the first term

$$\begin{aligned} E(\rho y_{it-2} u_{it-1}) &= \rho E[(\rho y_{it-3} + c_i + u_{it-2}) u_{it-1}] \\ &= \rho^2 E(y_{it-3} u_{it-1}) = \dots = \rho^{t-1} E(y_{i1} u_{it-1}). \end{aligned}$$

- Continuing the recursion yields $y_{it-1} = \rho y_{it-2} + c_i + u_{it-1}$. Consider the first term

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- Challenge:** What happens in the first period?

$$y_{i1} = \rho y_{i0} + \mathbf{x}_{i1}' \beta + c_i + u_{i1}.$$

- What to assume about y_{i0} ?
- We need $E(y_{i0} u_{it-1}) = 0$.
 - Although $\rho^{t-1} \rightarrow 0$, so the problem becomes smaller if T is large.

Conclusion: Consistency

Assumption	Consistency of		
	FE	FD	AB
$E(u_{it} \mathbf{z}_i) = 0$ (strict exogeneity)	✓	✓	✓
$E(u_{it} \mathbf{z}_{it}) = 0$ (contemporaneous exogeneity)	÷	÷	÷
$E(u_{it} \mathbf{z}_{it}, \mathbf{z}_{it-1}, \dots, \mathbf{z}_{i1}) = 0$ (sequential exogeneity)	÷	÷	✓
$E(u_{it} \mathbf{z}_{it-1}, \mathbf{z}_{it}, \mathbf{z}_{it+1}) = 0$	÷	✓	✓

- Here, ✓ means “consistent” and ÷ means “inconsistent.”
- **Arellano Bond (AB):** possible to recover consistency by using instruments...
 - A GMM estimator.

Sequential Exogeneity

Assumption: Sequential Exogeneity

$$E(u_{it} | \mathbf{z}_{i1}, \dots, \mathbf{z}_{it}) = 0.$$

- **Note:** Both the FE and FD estimators are still inconsistent under *sequential* exogeneity.

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- **FE:** the inconsistency of FE is of order $O(T^{-1})$ as $T \rightarrow \infty$
 - That is, it dies out.

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- **FE:** the inconsistency of FE is of order $O(T^{-1})$ as $T \rightarrow \infty$
 - That is, it dies out.
- **FD:** the inconsistency of FD does not die out.
- **However:** In this course, we assume *fixed* T but $N \rightarrow \infty$, so we do not care much about this (apart from mathematical joy)

- **However:** sequential exogeneity implies that z_{it-k} for $k \geq 1$ may be useful as *instruments*...
 - **Sequential exogeneity** tells us that y_{it-2} is a *valid* instrument.
 - **Relevance:** An empirical question whether it has any explanatory power...

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- **IV idea:** For the model

$$y_{it} = \rho y_{it-1} + c_i + u_{it},$$

estimate

$$\Delta y_{it} = \rho \Delta y_{it-1} + \Delta u_{it},$$

and use y_{it-2} (or Δy_{it-2}) as an instrument for Δy_{it-1} .

- \Rightarrow see exercises.

GMM

Plan for this section:

1. Intro to linear GMM
2. Two step estimator
 - 2.1 Estimate with simple weight matrix
 - 2.2 Update weight-matrix and re-estimate
3. Test of over-identifying restrictions.
4. The Arellano-Bond Estimator

- **Model:**

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- **Assume** we have access to a set of **instruments**, \mathbf{Z}_i ($T \times r$ with $r \geq K$), that are **exogenous**, i.e.

$$E(\mathbf{Z}_i'\mathbf{u}_i) = \mathbf{0}_{r \times 1}.$$

- These are our **moment conditions**.

- **Model:**

$$y_{it} = \mathbf{x}_{it}\beta + u_{it}$$

- **Stacking** over T gives

$$\mathbf{y}_i = \mathbf{X}_i\beta + \mathbf{u}_i.$$

- **Assume** we have access to a set of **instruments**, \mathbf{Z}_i ($T \times r$ with $r \geq K$), that are **exogenous**, i.e.

$$E(\mathbf{Z}_i'\mathbf{u}_i) = \mathbf{0}_{r \times 1}.$$

- These are our **moment conditions**.
- **Example:** Suppose $K = r = 1$. Then the moment conditions are $E(z_{it}u_{it}) = 0$ for $t = 1, \dots, T$.

- **Model:**

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- **Example:** Suppose $K = r = 1$. Then the moment conditions are $E(z_{it}u_{it}) = 0$ for $t = 1, \dots, T$.
- **Idea:** Replace “E” with “ $N^{-1} \sum_i$ ” and \mathbf{u}_i with $\mathbf{y}_i - \mathbf{X}_i\beta$, and choose β to minimize

$$\|\sum_{i=1}^N \mathbf{Z}_i(\mathbf{y}_i - \mathbf{X}_i\beta) - \mathbf{0}_{r \times 1}\|_W,$$

where $\|\mathbf{a}\|_W \equiv \mathbf{a}'\mathbf{W}\mathbf{a}$.

Panel GMM Estimator

$$\hat{\beta}_{\text{PGMM}} = \arg \min_{\beta} Q_N(\beta),$$

$$\text{where } Q_N(\beta) = \left[\sum_{i=1}^N \mathbf{z}_i'(\mathbf{y}_i - \mathbf{x}_i\beta) \right]' \mathbf{W}_N \left[\sum_{i=1}^N \mathbf{z}_i'(\mathbf{y}_i - \mathbf{x}_i\beta) \right].$$

- \mathbf{W}_N ($r \times r$) is a *weighting matrix*
 - **Default** (in practice): $\mathbf{W}_N = \mathbf{I}_{r \times r}$ (identity matrix).
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- **Argmin?** the argument (input) that minimizes
 - Here: turns out to be solvable in closed form
 - Later: solve more general problems

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- **Turns out** that the linearity implies a **closed form solution** to the minimization problem.
- **Example:** if $K = r = T = 1$ and $\mathbf{W}_N = 1$

$$\min_{\beta} \left[\sum_{i=1}^N z_i (y_i - x_i \beta) \right]^2$$

$$\Rightarrow \text{FOC} : 2 \left[\sum_i z_i (y_i - x_i \hat{\beta}) \right] \left[\sum_i z_i (-x_i) \right] = 0$$

$$\Leftrightarrow \left(\sum_i z_i x_i \right) \left(\sum_i z_i x_i \right) \hat{\beta} = \left(\sum_i z_i x_i \right) \left(\sum_i z_i y_i \right)$$

$$\Leftrightarrow \hat{\beta} = \left[\left(\sum_i z_i x_i \right) \left(\sum_i z_i x_i \right) \right]^{-1} \left(\sum_i z_i x_i \right) \left(\sum_i z_i y_i \right).$$

Linear Panel GMM Estimator

$$\hat{\beta}_{\text{PGMM}} = \left[\left(\sum_i \mathbf{x}_i' \mathbf{z}_i \right) \mathbf{W}_N \left(\sum_i \mathbf{z}_i' \mathbf{x}_i \right) \right]^{-1} \left(\sum_i \mathbf{x}_i' \mathbf{z}_i \right) \mathbf{W}_N \left(\sum_i \mathbf{z}_i' \mathbf{y}_i \right).$$

- In matrix form, with $\underbrace{\mathbf{X}}^{NT \times K}$, $\underbrace{\mathbf{Z}}^{NT \times r}$, $\underbrace{\mathbf{W}_N}_{r \times r}$, $\underbrace{\mathbf{Y}}^{NT \times 1}$

$$\hat{\beta}_{\text{PGMM}} = (\mathbf{X}' \mathbf{Z} \mathbf{W}_N \mathbf{Z}' \mathbf{X})^{-1} (\mathbf{X}' \mathbf{Z} \mathbf{W}_N \mathbf{Z}' \mathbf{Y}).$$

1-step GMM

Estimate $\hat{\beta}_{PGMM}$ using $\mathbf{W}_N = (N^{-1} \sum_i \mathbf{Z}_i' \mathbf{Z}_i)^{-1}$.

- **Motivation:** Identical to running 2-stage least squares (2SLS):
 1. Regress \mathbf{X}_i on \mathbf{Z}_i , compute prediction
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 - **Problem:** with $NT > 100,000$, \mathbf{P}_Z takes more memory than is available on a typical laptop to store.

2-step GMM

1. Obtain a consistent (but inefficient) estimate of β using $\hat{\beta}_{1\text{step}}$ and compute $\hat{\mathbf{u}}_i \equiv \mathbf{y}_i - \mathbf{X}_i\beta$.
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$$\text{where } \hat{\mathbf{S}} = N^{-1} \sum_{i=1}^N \mathbf{z}_i' \hat{\mathbf{u}}_i \hat{\mathbf{u}}_i' \mathbf{z}_i \quad (r \times r).$$

- **Efficiency?** It turns out that we minimize $V(\hat{\beta}_{\text{PGMM}})$ by setting $\mathbf{W}_N = \mathbf{S}^{-1}$.
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- **Hence:** if $\hat{\mathbf{S}}$ is consistent for $\mathbf{S} \equiv E(\mathbf{z}_i' \mathbf{u}_i \mathbf{u}_i' \mathbf{z}_i)$, then using $\mathbf{W}_N = \hat{\mathbf{S}}^{-1}$ works best.

- The PGMM estimator is defined as

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- **Intuition** for variance: let

$$\mathbf{C} \equiv \left[\left(\sum_i \mathbf{x}_i' \mathbf{z}_i \right) \mathbf{W}_N \left(\sum_i \mathbf{x}_i' \mathbf{z}_i \right) \right]^{-1} \left(\sum_i \mathbf{x}_i' \mathbf{z}_i \right) \mathbf{W}_N.$$

$$V(\hat{\beta}_{\text{PGMM}} | \mathbf{X}, \mathbf{Z}) = \mathbf{C} \mathbf{S} \mathbf{C}'.$$

Panel-robust PGMM Variance Estimator

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- **More generally:** we might have $E(\mathbf{u}|\mathbf{Z}) = \mathbf{0}_{T \times 1} \dots$
 - ... this condition implies $E(\mathbf{Z}'\mathbf{u}) = \mathbf{0}$, but also $E[f(\mathbf{Z})'\mathbf{u}] = \mathbf{0}$
 - i.e. \mathbf{u} is uncorrelated with any function of \mathbf{Z} .

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- **Alternative:** many things can cause $E(\mathbf{Z}'_i \mathbf{u}_i) \neq \mathbf{0}_{r \times 1}$, including
 - Incorrect functional form,
 - Endogeneity for one or more of our instruments,
 - etc.

- **Question:** can we test whether $E(\mathbf{Z}'_i \mathbf{u}_i) = \mathbf{0}_{r \times 1}$ is satisfied?
- **Just identified case:** when $r = K$, we are able to set $\frac{1}{N} \sum_i \mathbf{Z}'_i \hat{\mathbf{u}}_i = \mathbf{0}_{r \times 1}$ exactly.
 - i.e. we can make the instruments and the residual exactly uncorrelated.
 - (like how the OLS residual is uncorrelated with the residual by construction)
- When $r > K$, we have $r - K$ instruments “too many.”
 - We say that “we have $r - K$ **overidentifying restrictions**”
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 - Incorrect functional form,
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 - etc.
- **Intuition:** if all moments are valid but some are not needed, the true β can satisfy them all... up to sampling noise.

The Sargen Test of Overidentifying Restrictions

Under the null hypothesis, $\mathcal{H}_0 : E(\mathbf{Z}'_i \mathbf{u}_i) = \mathbf{0}$, and for \mathbf{Z} satisfying the rank condition, the test statistic

$$\text{OIR} \equiv \left(\sum_i \mathbf{Z}'_i \hat{\mathbf{u}}_i \right)' (N\hat{\mathbf{S}})^{-1} \left(\sum_i \mathbf{Z}'_i \hat{\mathbf{u}}_i \right)$$

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- **Robustness:** $\hat{\mathbf{S}} = N^{-1} \sum_{i=1}^N \mathbf{Z}'_i \hat{\mathbf{u}}_i \hat{\mathbf{u}}'_i \mathbf{Z}_i$ is robust to
 - Heteroskedasticity,
 - Serial correlation of u_{it} over t (within a given i).

Arellano-Bond

Model

$$y_{it} = \rho y_{it-1} + \mathbf{x}_{it}\beta + c_i + u_{it}.$$

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- **Motivation:** we showed that strict exogeneity is invalidated *by construction*
- **Goal:** recover consistency for FD under *sequential* exogeneity
 - FE cannot be saved, strict exogeneity is required.
 - FD is salvageable.

Model in First Differences

$$\Delta y_{it} = \rho \Delta y_{it-1} + \Delta \mathbf{x}_{ti}' \beta + \Delta u_{it}.$$

- **The problem:** by construction, $\Delta y_{it-1} \equiv y_{it-1} - y_{it-2}$ is correlated with $\Delta u_{it} \equiv u_{it} - u_{it-1}$.

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- **Solution:** use y_{it-2} as an instrument in period it .
 - I.e. use $E(y_{it-2} \Delta u_{it}) = 0$ as an orthogonality condition.
- **Validity** comes from the fact that u_{it} are IID and thus serially uncorrelated:

$$\begin{aligned} E(y_{it-2} \Delta u_{it}) &= E[(\rho y_{it-3} + \mathbf{x}_{it-2}' \beta + c_i + u_{it-2})(u_{it} - u_{it-1})] \\ &= \rho E(y_{it-3} \Delta u_{it}) = \dots = \rho^{t-2-1} E(y_{i1} \Delta u_{it}) = 0 \end{aligned}$$

- since our data has no y_{i0} .

More Instruments for Δy_{it-1} ?

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 - No instruments available for $t = 1, 2$.
- **Telescoping** list of instruments:

$$\mathbf{z}_{i3} = (y_{i1})$$

$$\mathbf{z}_{i4} = (y_{i1} \quad y_{i2})$$

$$\mathbf{z}_{i5} = (y_{i1} \quad y_{i2} \quad y_{i3})$$

$$\mathbf{z}_{i6} = (y_{i1} \quad y_{i2} \quad y_{i3} \quad y_{i4})$$

$$\vdots$$

$$\mathbf{z}_{iT} = (y_{i1} \quad y_{i2} \quad y_{i3} \quad y_{i4} \quad \cdots \quad y_{iT-2})$$

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- **Sequentially exogenous (or predetermined):** if only

$E(u_{it} | \mathbf{x}_{i1}, \dots, \mathbf{x}_{it}) = 0$, we can use only $(\mathbf{x}_{i1}, \dots, \mathbf{x}_{it})$ as an instrument for $\Delta \mathbf{x}_{it}$.

Example: Female Labor Supply and Fertility

$$y_{it} = \rho y_{it-1} + \beta_0 + \beta_1 k_{it} + \beta_2 f_{it} + c_i + u_{it},$$

where $y_{it} = \mathbf{1}\{\text{work in year } t\}$, $k_{it} = \mathbf{1}\{\text{kids aged } [2; 6]\}$ and $f_{it} = \mathbf{1}\{\text{gives birth in year } t\}$.

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- **Fertility** (f_{it}) is likely
 - contemporaneously endogenous: $E(f_{it} u_{it}) \neq 0$
 - correlated with individual effects: $E(f_{it} c_i) \neq 0$
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 - we can use $(k_{i1}, \dots, k_{it-1})$ in period t
 - correlated with individual effects, $E(k_{it} c_i) \neq 0$.
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- **Full matrix** when y_{it-1} is the only regressor

$$\mathbf{Z}_i = \begin{pmatrix} y_{i1} & 0 & 0 & 0 & 0 & 0 & \cdots & \cdots \\ 0 & y_{i1} & y_{i2} & 0 & 0 & 0 & \cdots & \cdots \\ 0 & 0 & 0 & y_{i1} & y_{i2} & y_{i3} & \cdots & \cdots \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \end{pmatrix}$$

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- With **vector notation**:

$$\mathbf{Z}_i = \begin{pmatrix} \mathbf{z}_{i3} & \mathbf{0}_{1 \times 2} & \mathbf{0}_{1 \times 3} & \cdots & \mathbf{0}_{1 \times T-2} \\ 0 & \mathbf{z}_{i4} & \mathbf{0}_{1 \times 3} & \cdots & \mathbf{0}_{1 \times T-2} \\ 0 & \mathbf{0}_{1 \times 2} & \mathbf{z}_{i5} & \cdots & \mathbf{0}_{1 \times T-2} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & \mathbf{0}_{1 \times 2} & \mathbf{0}_{1 \times 3} & \cdots & \mathbf{z}_{iT} \end{pmatrix}.$$

- **Note:** the \mathbf{Z}_i has $T - 2$ rows and $\sum_{t=3}^T (t - 2)$ rows.

Arellano-Bond Estimator

$$\hat{\beta}_{AB} = \left[\left(\sum_i \tilde{\mathbf{X}}_i' \mathbf{Z}_i \right) \mathbf{W}_N \left(\sum_i \mathbf{Z}_i' \tilde{\mathbf{X}}_i \right) \right]^{-1} \left(\sum_i \tilde{\mathbf{X}}_i' \mathbf{Z}_i \right) \mathbf{W}_N \left(\sum_i \mathbf{Z}_i' \tilde{\mathbf{y}}_i \right).$$

- where $\tilde{\mathbf{X}}_i$ is the $T - 2 \times K + 1$ matrix with t 'th row $(\Delta y_{it-1}, \Delta \mathbf{x}_{it}')'$, and $\tilde{\mathbf{y}}_i$ is the $T - 2 \times 1$ vector with rows Δy_{it}

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- **Problem:** how to estimate the weighting Matrix?
 1. Initial guess: $\mathbf{W}_N = \left(N^{-1} \sum_i \mathbf{Z}_i' \mathbf{Z}_i \right)^{-1}$
 2. Optimal weight: should be an estimate of \mathbf{S}^{-1} , where $\mathbf{S} = E(\mathbf{Z}_i' \mathbf{u} \mathbf{u}' \mathbf{Z}_i)$.
 - **Problem:** to estimate \mathbf{S} , we need “residuals”, so we need parameters.
 - **Solution:** get a first-stage *consistent* but *inefficient* estimate, and use those in a second stage.

Arellano-Bond Two-step Estimator

1. Compute $\hat{\beta}_{AB}$ setting $\mathbf{W}_N = (N^{-1} \sum_i \mathbf{Z}_i' \mathbf{Z}_i)^{-1}$.
(this is the 2SLS estimator)
2. Re-estimate $\hat{\beta}_{AB}$ with $\mathbf{W}_N = (N^{-1} \sum_i \mathbf{Z}_i' \hat{\mathbf{u}}_i \hat{\mathbf{u}}_i' \mathbf{Z}_i)^{-1}$.

- **Assuming** that u_{it} are IID, the two-step estimator is asymptotically efficient.

- **Instruments** in general have to satisfy
 1. **Exogeneity**: follows from model structure and the assumption that u_{it} is serially uncorrelated.
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Instrument relevance?

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 - ... after all, we are hoping for the level of y_{it} to predict future changes, Δy_{it+2}
- **However**: relevant e.g. for the *heterogeneous income profiles* (HIP) model:

$$y_{it} = c_i + \beta_i t + p_{it} + u_{it}$$

$$p_{it} = p_{it-1} + \epsilon_{it},$$

where $(c_i, \beta_i)' \sim \mathcal{N}(\mathbf{0}, \Sigma)$, and ϵ_{it}, u_{it} are IID, and p_{it} is unobserved.

- Here, the *level* and *changes* in y_{it} become increasingly correlated over the life-cycle.
- See Druedahl & Munk-Nielsen (2018).

(a) Data

