

# **Quantile Regression**

Advanced Microeconometrics

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### Plan for lectures: Helicopter

Part I: Linear methods.  $\checkmark$ 

Part II: High-dimensional methods. ✓

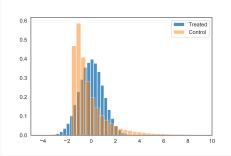
Part III: M-estimation, theory ✓

 $\textbf{Part IV:} \ \ \text{M-estimation, examples} \leftarrow$ 

### Where are we in the course?

Part	Topic	Parameterization non-linear	Estimation non-linear	Dimension $dim(x)$	Numerical optimization	M-estimation (Part III)	Outcome $(y_i)$	Panel $(c_i)$
I	OLS	÷	÷	low	÷	✓	$\mathbb{R}$	✓
Ш	LASSO	÷	✓	high	✓	÷	$\mathbb{R}$	÷
IV	Probit	√	✓	low	✓	✓	{0,1}	÷
	Logit	√	✓	low	✓	✓	$\{1,2,,J\}$	÷
	Tobit	√	√	low	✓	✓	[0;∞)	÷
	Simulated Likelihood	✓	✓	low	✓	✓	Any	✓
	Quantile Regression	÷	✓	(low)	✓	✓	R	÷
	Non-parametric	<b>←</b>	(√)	∞	÷	÷	R	÷

#### Discussion time!



In the example in the graph, the average treatment effect is zero.

### Question

What else can we say about the impact of treatment based on this graph?

# Topic for today

- Most empirical work focuses on the conditional mean...
- Today: explore conditional quantiles.

### Outline

### 1. Empirical Questions

- 2. Intro: Quantiles
- 3. Model
- 4. Criterion Function
- Features of Interest
- Specific Issues
  - 6.1. Kinky objective function
  - 6.2. Standard errors

### **Earnings Example**

- Bitler, Gelbach, & Hoynes (2006; AER): The effect on earnings of Connecticut's Job First waiver program.
- Finding: Behind the mean response lies a large response by a small group.

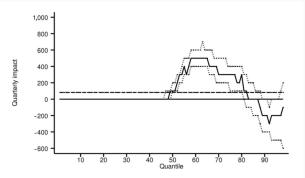
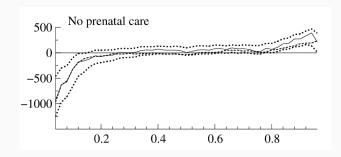


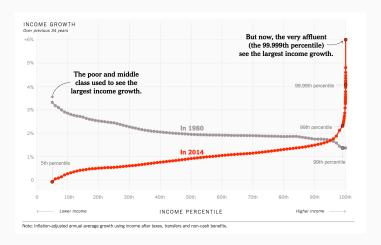
FIGURE 3. QUANTILE TREATMENT EFFECTS ON THE DISTRIBUTION OF EARNINGS, QUARTERS 1–7 Notes: Solid line is QTE; dotted lines provide bootstrapped 90-percent confidence intervals; dashed line is mean impact; all statistics computed using inverse propensity-score weighting. See text for more details.

## Birth weight example

- Abrevaya & Dahl (2008): Birth weight of newborns.
- Example: No prenatal visits makes a big difference at bottom quantiles (the "at risk" babies).



## Income Inequality



Source: David Leonhardt, NYTimes, nytimes.com

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#### Introduction

Normally: we are interested in the conditional mean,

$$\mathbb{E}(y|\mathbf{x}) = \mathbf{x}\boldsymbol{\beta}_m$$

• Instead: we might consider

$$Median(y|\mathbf{x}) = \mathbf{x}\boldsymbol{\beta}_{0.5}$$

• More generally: conditional au-percentiles,  $au \in (0;1)$ 

$$Percentile_{\tau}(y|\mathbf{x}) = \mathbf{x}\boldsymbol{\beta}_{\tau}$$

### Quantiles

#### Definition: quantile

The au'th quantile  $( au \in (0;1))$  of y is  $\mu_{ au}$  such that

$$au = \Pr(y \leq \mu_{\tau}) \equiv F_y(\mu_{\tau}).$$

Hence

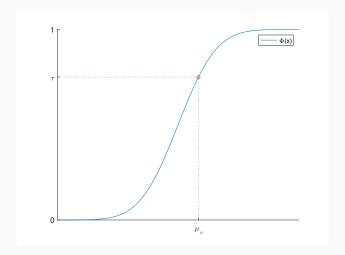
$$\mu_{\tau} = F_{y}^{-1}(\tau).$$

#### Definition: percentile

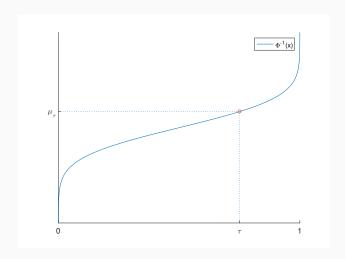
The  $\tau$ 'th quantile is the  $100\tau$ 'th percentile.

E.g., the 0.23 quantile and the 23 rd percentile are the same.

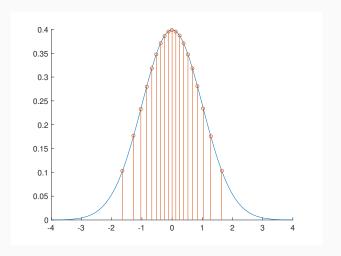
# Graphically, $\tau \equiv F_y(\mu_\tau)$ : The CDF



# Graphically, $\mu_{\tau} = F^{-1}(\tau)$ : The Quantile Function



# Quantiles {.05, .1, .15, ..., .95}



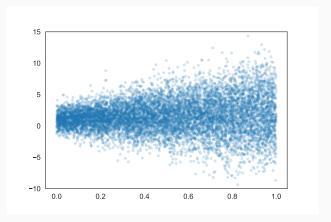
## **Conditional Quantiles**

### Definition: conditional quantile

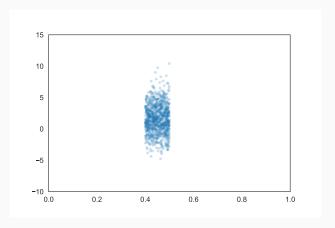
The conditional  $\tau$  quantile of y is

$$\mu_{\tau}(\mathbf{x}) = F_{y|\mathbf{x}}^{-1}(\tau|\mathbf{x}).$$

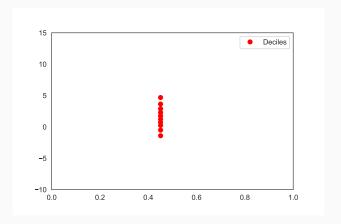
# **Conditional Quantiles: Dataset**

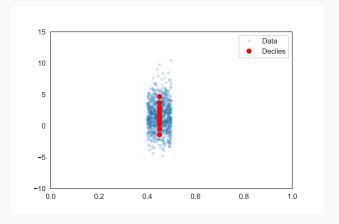


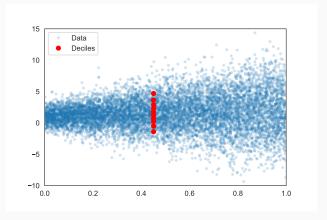
# Conditional Quantiles: Focus on x<sub>i</sub>

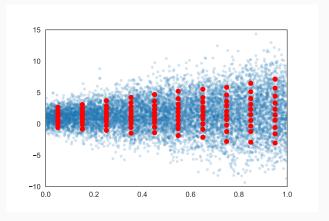


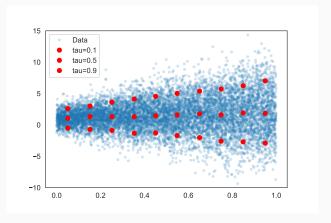
# Conditional Quantiles, 0, 5, 10, ..., 100

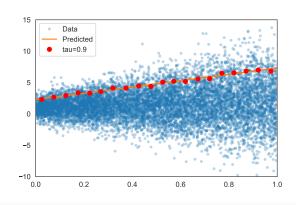






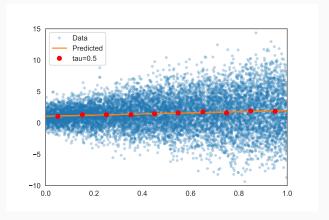


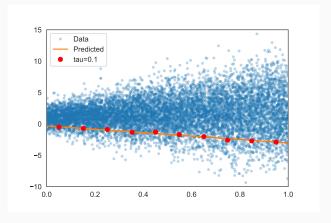


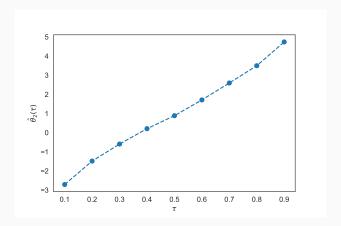


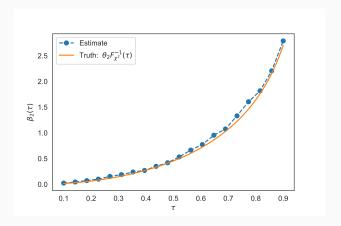
why are the dots below the line

well, finite sample had we access to an infinitely large dataset, we could essentially have dots perfectly line up with the line itself









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- 2. Intro: Quantiles
- 3. Model
- 4. Criterion Function
- 5 Features of Interest
- 6. Specific Issues
  - 6.1. Kinky objective function
  - 6.2 Standard errors

#### Model

- Will cover two specific models as examples;
  - 1. Heteroscedasticity model,

Pro: error-term form,

2. Heterogenous parameter model.

Pro: simpler to grasp what we estimate.

• **Finally:** Will cover the more general model.

# Heteroscedasticity model (cf. C&T)

#### Model

$$y = \mathbf{x}\beta + u$$
  
 $u = (\mathbf{x}\alpha)\varepsilon, \quad \varepsilon \sim F_{\varepsilon},$ 

where we assume  $\mathbf{x}\alpha > 0$ .

■ Goal: Derive an expression for  $\mu_{\tau}(\mathbf{x}, \boldsymbol{\beta}, \boldsymbol{\alpha})$ .

$$\begin{split} \tau &=& \operatorname{Pr}\left[y \leq \mu_{\tau}(\mathbf{x}, \boldsymbol{\beta}, \boldsymbol{\alpha})\right] \\ &=& \operatorname{Pr}\left[\mathbf{x}\boldsymbol{\beta} + (\mathbf{x}\boldsymbol{\alpha})\,\varepsilon \leq \mu_{\tau}(\mathbf{x}, \boldsymbol{\beta}, \boldsymbol{\alpha})\right] \\ &=& \operatorname{Pr}\left\{\varepsilon \leq \frac{1}{\mathbf{x}\boldsymbol{\alpha}}\left[\mu_{\tau}(\mathbf{x}, \boldsymbol{\beta}, \boldsymbol{\alpha}) - \mathbf{x}\boldsymbol{\beta}\right]\right\} \\ &\equiv& F_{\varepsilon}\left\{\frac{1}{\mathbf{x}\boldsymbol{\alpha}}\left[\mu_{\tau}(\mathbf{x}, \boldsymbol{\beta}, \boldsymbol{\alpha}) - \mathbf{x}\boldsymbol{\beta}\right]\right\}. \end{split}$$

• **Qs**: Where did we need  $x\alpha > 0$ ?

# Heteroscedasticity model (cf. C&T)

We have

$$\tau = F_{\varepsilon} \left\{ \frac{1}{x\alpha} \left[ \mu_{\tau}(x, \beta, \alpha) - x\beta \right] \right\}.$$

It follows,

$$F_{\varepsilon}^{-1}(\tau) = \frac{1}{\mathsf{x}\alpha} \left[ \mu_{\tau}(\mathsf{x}, \beta, \alpha) - \mathsf{x}\beta \right]$$

$$\Leftrightarrow \mu_{\tau}(\mathsf{x}, \beta, \alpha) = \frac{\mathsf{x}\beta + (\mathsf{x}\alpha)F_{\varepsilon}^{-1}(\tau)}{\mathsf{mu's are scaled up or down(?)}}$$

#### Discussion

$$\mu_{\tau}(\mathbf{x}, \boldsymbol{\beta}, \boldsymbol{\alpha}) = \mathbf{x}\boldsymbol{\beta} + (\mathbf{x}\boldsymbol{\alpha})F_{\varepsilon}^{-1}(\tau).$$

Suppose  $\mathbf{x}_i \alpha = 1$  for all i.

#### **Discuss**

What is the difference between two quantile regression lines in this case?

## Heterogenous parameter model

#### Model

there is no error term OR whatever \tau we draw is 'the error term'  $y_i = \mathbf{x}_i \beta(\tau_i), \quad \tau_i \sim \mathrm{Uniform}(0,1),$ 

where  $\beta(\cdot)$  maps [0;1] into  $\mathbb{R}^K$  subject to the *no quantile crossing* restriction [next slide].

- $\tau_i$  is interpreted as the conditional **quantile draw** of *i*.
- Alternatively, we can think of the model as

$$y_i = \mathbf{x}_i \boldsymbol{\beta} + e_i, \quad e_i \equiv \mathbf{x}_i \boldsymbol{\beta}(\tau_i) - \mathbf{x}_i \boldsymbol{\beta}.$$

• we then require  $Pr(e_i \le \tau_i | \mathbf{x}_i) = 0$ .

#### No quantile crossing

The mapping,  $\tau_i \mapsto \mathbf{x}_i \boldsymbol{\beta}(\tau_i)$  must be monotonic for all  $\tau_i \in (0;1)$  where  $\mathbf{x}_i$  has support (almost surely). You can't have that the 90th percentile is below 10th percentile

#### Discussion

#### Discuss

Why do we need the no quantile crossing property?

[hint, consider the "constant only," example where  $\mathbf{x}_i=1$ , so

## Heteroscedasticity DGP in Python

```
1 def sim_data(theta, N, alpha):
      K = theta.size
2
      assert alpha.size == K, f'alpha must be same size as beta'
3
4
      # 1. regressors
5
      oo = np.ones((N.1))
6
      xx = np.random.uniform(size=(N,K-1)) # uniform => ensures posit
7
      x = np.hstack([oo, xx])
8
9
10
      # 2. error term
      epsilon = np.random.normal(size=(N,))
11
      sigma_i = x@alpha # individual variance (function of x)
12
      u = sigma i * epsilon # heteroskedastic error
13
14
      # 3. outcome
15
      y = x@theta + u
16
      return y,x
17
```

• Note: we estimate  $\hat{\beta}(\tau)$ , but the DGP requires  $\theta_o$  (K-vector) and  $\alpha_o$  (K-vector)

```
1 def sim_data(theta, N, icdf):
      K = theta.size
2
      assert K == 2 # for simplicity
3
      assert callable(icdf)
5
      oo = np.ones((N,1))
6
      xx = np.random.uniform(size=(N,1)) + theta[0]
7
      x = np.hstack([oo, xx]) # (N,K)
8
9
      tau = np.random.uniform(size=(N,1))
10
      beta2 = icdf(tau) * theta[1] INVERSE CDE!!
11
      beta1 = np.ones((N,1)) # first coefficient constant across quar
12
      beta = np.hstack([beta1, beta2]) # (N,K)
13
14
      y = np.sum(x * beta, axis=1)
15
      return y,x
16
```

■ **Note**: we estimate  $\hat{\beta}(\tau)$ , but the DGP requires  $\theta_o$  (*K*-vector) and  $F^{-1}(\cdot)$  (function)

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#### Overview

- Recall: We minimize  $\mathbb{E}[(y-\mu)^2]$  by setting  $\mu=\mathbb{E}(y)$ . minimizing sq distances = mean
- Similarly: We minimize  $\mathbb{E}|y-\mu|$  by setting  $\mu=\mathrm{Median}(y)$ .  $rac{ exttt{minimizing abs dist =}}{ exttt{median}}$
- **Regression:** We minimize  $\mathbb{E}[(y \mu(x))^2 | x]$  by setting  $\mu(x) = \mathbb{E}(y | x)$ .
  - Typically, we then further assume  $\mathbb{E}(y|x) = \mathbf{x}\beta$ .
- Median regression: minimize  $\mathbb{E}(|y \mu(x)|x)$  by setting  $\mu(x) = \text{Median}(y|x)$ .
  - Similarly, we might assume  $\operatorname{Median}(y|x) = \mathbf{x}\beta$ .

# Criterion function: rewriting the C&T form

In C&T: They write

$$Q(\beta_{\tau}) = \sum_{i: y_i \geq \mathbf{x}_i \beta_{\tau}} \tau |y_i - \mathbf{x}_i \beta_{\tau}| + \sum_{i: y_i < \mathbf{x}_i \beta_{\tau}} (1 - \tau) |y_i - \mathbf{x}_i \beta_{\tau}|.$$

• Equivalently, we can write this as

$$Q(\beta_{\tau}) = \sum_{i=1}^{N} \left[ \mathbf{1}_{\{y_i \geq \mathbf{x}_i \beta_{\tau}\}} \tau | y_i - \mathbf{x}_i \beta_{\tau}| + \mathbf{1}_{\{y_i < \mathbf{x}_i \beta_{\tau}\}} (1 - \tau) | y_i - \mathbf{x}_i \beta_{\tau}| \right]$$

■ **Getting** rid of the "| · |",

$$Q(\beta_{\tau}) = \sum_{i=1}^{N} \left[ \mathbf{1}_{\{y_{i} \geq \mathbf{x}_{i}\beta_{\tau}\}} \tau(y_{i} - \mathbf{x}_{i}\beta_{\tau}) + \mathbf{1}_{\{y_{i} < \mathbf{x}_{i}\beta_{\tau}\}} (\tau - \mathbf{1})(y_{i} - \mathbf{x}_{i}\beta_{\tau}) \right]$$

In my slides and everywhere else,

$$Q(\beta_{\tau}) = \sum_{i=1}^{N} \left(\tau - \mathbf{1}_{\{y_{i} < \mathbf{x}_{i}\beta_{\tau}\}}\right) (y_{i} - \mathbf{x}_{i}\beta_{\tau})$$

$$\equiv \sum_{i=1}^{N} p_{\tau}(y_{i} - \mathbf{x}_{i}\beta_{\tau}). \text{"CHECK FUNCTION"}$$

at the 90th percentile (\tau = 0.9)

we punish obs above prediction much more harshly than we

do for obs below prediction

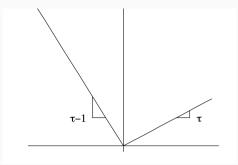
For all obs where y is above predicted, we penalize by \tau

when below, we penalize by 1-\tau

# More generally

### **Definition: Check function**

$$\rho_{\tau}(u) \equiv \left(\tau - \mathbf{1}_{\{u < 0\}}\right) u.$$



From Koenker (2000).

### Criterion function

#### Criterion function

$$q(y_i, \mathbf{x}_i, \boldsymbol{\beta}_{\tau}) = \rho_{\tau}(y_i - \mathbf{x}_i \boldsymbol{\beta}_{\tau}),$$

where  $\rho_{\tau}$  is the *check function*.

- Claim:  $\beta_{\tau} = \arg \min_{\beta} \mathbb{E}[q(y_i, \mathbf{x}_i, \beta) | \mathbf{x}_i].$
- ... we will show this for the intercept-only model.
  - [not the full proof]

#### Minimizer

- To show:  $\beta_{0\tau} = \arg\min_{\beta_0} \mathbb{E}[\rho_{\tau}(y-\beta_0)|x].$
- Idea: Split up  $(-\infty, \infty)$  into  $(-\infty, \beta_0] \cup [\beta_0, \infty)$  to get rid of  $1\{\cdot\}$ .
- Re-write

$$\mathbb{E}[\rho_{\tau}(y - \beta_{0})|x] \equiv \int_{-\infty}^{\infty} [\tau - \mathbf{1}\{y - \beta_{0} < 0\}] (y - \beta_{0}) \, dF(y)$$

$$= \int_{-\infty}^{\beta_{0}} [\tau - \mathbf{1}\{y < \beta_{0}\}] (y - \beta_{0}) \, dF(y)$$

$$+ \int_{\beta_{0}}^{\infty} [\tau - \mathbf{1}\{y < \beta_{0}\}] (y - \beta_{0}) \, dF(y)$$

$$= (\tau - 1) \int_{-\infty}^{\beta_{0}} (y - \beta_{0}) \, dF(y)$$

$$+ \tau \int_{\beta_{0}}^{\infty} (y - \beta_{0}) \, dF(y).$$

## Step 2: FOC

We have

$$\mathbb{E}[\rho_{\tau}(y-\beta_{0})|x] = (\tau-1) \int_{-\infty}^{\beta_{0}} (y-\beta_{0}) dF(y) + \tau \int_{\beta_{0}}^{\infty} (y-\beta_{0}) dF(y).$$

FOCs imply

$$\frac{\partial \mathbb{E}[\rho_{\tau}(y - \beta_0)|x]}{\partial \beta_0} = 0$$

$$[...]$$

$$\Leftrightarrow F(\beta_0) = \tau.$$

- Intuition: Choose  $\beta_0$  so that  $\tau$  of the mass is to the left.
  - $[cdf(x) \equiv % \text{ of mass to the left of } x]$

### Identification

- Intuitively: similar to OLS.
- Further details get much more complicated.

#### Question

Why can I not identify a model with two intercepts?

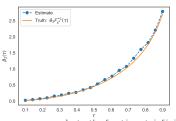
```
suppose I know the true parameters \label{eq:normalizero} \mbox{Not changing "x", yields the same value criterion -> thus unable to identify a model with two intercept (?)}
```

#### Discussion

#### Model

$$y_i = \mathbf{x}_i \boldsymbol{\beta}(\tau_i), \quad \tau_i \sim \text{Uniform}(0, 1),$$

where  $\beta_0(\tau) = 1 \forall \tau$  and  $\beta_1(\tau) = F^{-1}(\tau)$ , and F is the  $\chi^2$  cdf.



we can evaluate the function at infinitely many points

#### **Discuss**

What are the parameter estimates? A vector? A function?

the thing we are going to learn about is a function (see above) -

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### **Features of Interest**

- If we are interested in how  $x_{ik}$  affects conditional quantiles...
  - ... it is linear!
- That is,

$$\frac{\partial \mu_{\tau}(\mathbf{x}_{i}, \boldsymbol{\beta}_{\tau})}{\partial \mathbf{x}_{ik}} = \beta_{\tau k}.$$

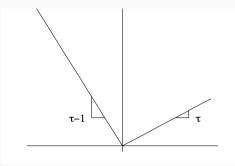
- Often we will plot all the estimates together, comparing with OLS.
  - [see examples earlier]

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### Definition: Check function

$$\rho_{\tau}(u) \equiv [\tau - \mathbf{1}\{u < 0\}] u.$$



From Koenker (2000).

### **Criterion function**

### **Criterion function**

$$q(y_i, \mathbf{x}_i, \boldsymbol{\beta}_{\tau}) = \rho_{\tau}(y_i - \mathbf{x}_i \boldsymbol{\beta}_{\tau}),$$

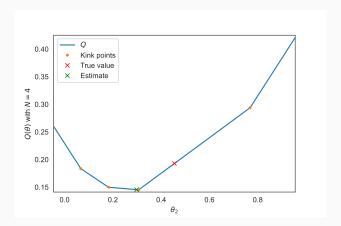
where 
$$\rho_{\tau}(u) \equiv [\tau - \mathbf{1}\{u < 0\}] u$$
.

- Two problems;
  - 1. Non-differentiable at  $y_i = \mathbf{x}_i \boldsymbol{\beta}_{\tau}$ ,
  - 2. Hessian is zero everywhere. second derivatives are all zero
- Implications:

Newton-method is bad (step-sizes are gonna be too large, f'/f'' are infinitely large)

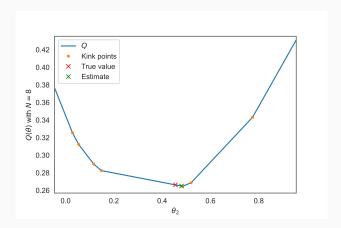
- 1. Optimization may be hard. are infinitely
- 2. Theorem 12.3 doesn't guarantee asymptotic normality,

Figure 1: N=4



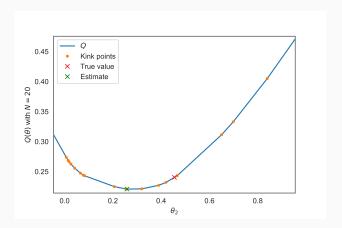
## **Criterion for various** *N*

Figure 2: N = 8



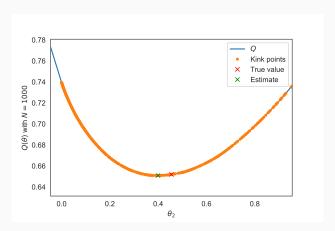
## **Criterion for various** *N*

Figure 3: N = 20



## Criterion for various N

**Figure 4:** N = 1000



#### **Discuss**

#### **Discuss**

Which problems do we face here:

- 1. The gradients may point the wrong way,

  even though we can't see,
- 2. We cannot divide by the Hessian,
- 3. There are local optima. function will never problem with this

**Also:** Does the primary problem get better or worse as  $N \to \infty$ ? Why?

USE NON-GRADIENT BASED OPTIMIZER
NELDER MEAD

#### Standard errors

- Note: Criterion is not smooth,
  - Non-differentiable at  $y_i = \mathbf{x}_i \boldsymbol{\beta}_{\tau}$ ,
  - Hessian is zero everywhere else.
- Fortunately: Normality still comes about...

$$\sqrt{N}(\hat{\boldsymbol{\beta}}_{\tau} - \boldsymbol{\beta}_{\tau}^{o}) \stackrel{d}{\to} \mathcal{N}(0, \mathbf{A}^{-1}\mathbf{B}\mathbf{A}^{-1}).$$

- $\bullet \quad \mathbf{A}_o = \operatorname{plim} \frac{1}{N} \sum_{i=1}^{N} f_{u_\tau \mid x}(0 \mid \mathbf{x}_i) \mathbf{x}_i \mathbf{x}_i',$
- $\bullet \quad \mathbf{B}_o = \operatorname{plim} \frac{1}{N} \sum_{i=1}^{N} \tau(1-\tau) \mathbf{x}_i \mathbf{x}_i',$
- $u_{\tau} \equiv y x \beta_{\tau}, f_{u_{\tau}|x}$  is the conditional pdf of  $u_{\tau}$  given  $x_{i}$ .

# Variance estimation in practice

- Bootstrap: Use when in doubt.
- Many variants exist (non-parametric, parametric, block, ...).

### **Bootstrap**

- 1. Draw a new dataset with replacement from the original dataset,
- 2. Estimate parameters,  $\hat{\beta}_{\tau}^{b}$ ,
- 3. Repeat 1–2 for b = 1, ..., B.
- 4. The distribution of  $\{\hat{\beta}_{\tau}^b\}_{b=1}^B$  is the approximation of the asymptotic distribution of  $\hat{\beta}_{\tau}$ .

#### Intuition

- Original dataset was an IID draw from the population.
- Thus, IID draws from this sub-population will match the original distribution closely.
- Panel data: Do the bootstrap sampling over i (not i, t);
  - i.e. take entire T-paths for individual i when he is drawn.