Methods 3: Multilevel Statistical Modeling and Machine Learning

Week 7: Linear regression revisited (machine learning)
November 9, 2021

by: Lau Møller Andersen

These slides are distributed according to the CC BY 4.0 licence:

https://creativecommons.org/licenses/by/4.0/



Attribution 4.0 International (CC BY 4.0)

Last time – Mid-way evaluation

- 1) Write something you liked about the course so far
- 2) Write something you did not like about the course so far
- 3) What would you change?

Summary

summary of student feedback

LIKE

Good amount of practical exercises (n=3)

Hands-on coding (n=8)

GitHub introduction (n=3)

Lau is answering questions (n=9)

That we go into depth (n=1)

Peer-review (n=1) Good readings (n=5)

Involvement of students (n=2) Lectures are interesting (n=2)

Good structure of classes (n=4)

Lau is engaged (n=4)

Exercises tied with papers (n=1)

Allow more time for clarification (n=1)

Easy to get help (n=3)

Pace too slow (n=1)

Explaining lecture goals (n=1)

Demystifying math (n=2)

DID NOT LIKE

Portfolio too challenging or too many questions (n=8)

GitHub is not worth it (n=1)

Math is hard - Explain math more (n=5)

Coding is hard (n=2)

Too many slides, not enough time (n=4)

Questions not clear enough in portfolio (n=9)

Connection between lecture and readings (n=5)

Bad structure of classes (n=1)

Exercises that have not been explicitly covered in class (n=5)

Not clear why we are doing the assignments (n=1)

That Lau is not in all classes (n=2)

Methods 1, 2 and 3 are not well connected (n=2) Lau talking too fast and not loud enough (n=1)

CHANGE

Closer match between lectures and classes (n=2)

List main concepts in syllabus (n=1)

Better deadlines needed (n=5)

More explanation on portfolios (n=1)

More feedback on exercises (n=3)

Programming together (n=1)

Go through papers that exercises are based on (n=1)

Total n = 29

https://github.com/ualsbombe/github_methods_3/blob/main/week_07/mid-way_evaluation.pdf

Summary – what you liked

- Top 3
 - 1) Lau is answering questions (n=9)
 - 2) Good readings (n=5)
 - 3) Lau is engaged (n=4) Good structure of classes (n=4)

Total n = 29

Summary – what you did not like

- Top 3
 - 1) Questions not clear enough in portfolio (n=9)
 - 2) Portfolio too challenging or too many questions (n=8)
 - 3) Math is hard explain math more (n=5) Connection between lecture and readings (n=5) Exercises not explicitly covered in class (n=5)

Total n = 29

Summary – to change

CHANGE

Closer match between lectures and classes (n=2)

List main concepts in syllabus (n=1)

Better deadlines needed (n=5)

More explanation on portfolios (n=1)

More feedback on exercises (n=3)

Programming together (n=1)

Go through papers that exercises are based on (n=1)

Summary – what I promise to change

I will be very careful and aim at writing questions that are easy to understand

Exercise for you: In tomorrow's exercise: For each question indicate whether you understood what was required of you.

Summary – what I promise to change

Connection between lectures and class will be closer – we will be following the textbook more closely

Summary – a discussion

Lau is answering questions (n=9)

Too many slides, not enough time (n=4)

This is a classic conundrum (which we should still try to solve)

Summary – a discussion

What is the optimal balance between me going through the slides and me answering questions?

Discuss for 3-5 minutes

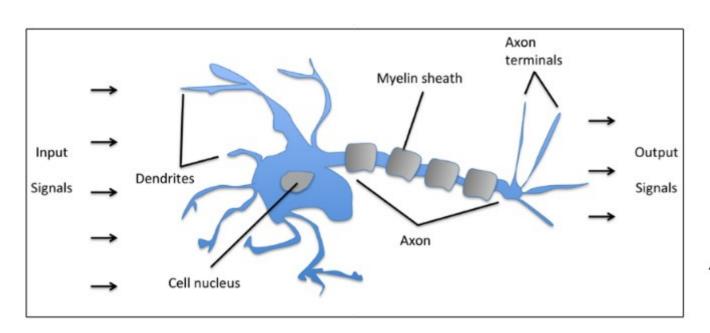
What should our balance be?

Learning goals

Linear regression revisited (machine learning)

- 1) Learning some early classification methods
- 2) Learning how linear regression (with biasing penalties) can be constructed and cross-validated
- 3) Understanding that biasing in-sample solutions can improve out-of-sample predictions

Black box idea



$$\boldsymbol{w} = \begin{bmatrix} w_1 \\ \vdots \\ w_m \end{bmatrix}, \quad \boldsymbol{x} = \begin{bmatrix} x_1 \\ \vdots \\ x_m \end{bmatrix}$$

$$z = w_1 x_1 + \ldots + w_m x_m$$

Question: what do x, w and z correspond to in the above picture of the *Perceptron*?

Prediction/classification rule

$$\phi(z) = \begin{cases} 1 & \text{if } z \ge \theta \\ -1 & \text{otherwise} \end{cases}$$
 Perceptron fires

θ is a pre-specified threshold

(Raschka, 2015)

Prediction/classification rule

$$w_0 = -\theta$$
$$x_0 = 1$$

$$z = w_0 x_0 + w_1 x_1 + \ldots + w_m x_m = \boldsymbol{w}^T \boldsymbol{x}$$

$$z = -\theta + w_1 x_1 + ... + w_m x_m = \mathbf{w}^T \mathbf{x}$$

$$\phi(z) = \begin{cases} 1 & \text{if } z \ge 0 \\ -1 & \text{otherwise} \end{cases}$$
 Perceptron fires

(Raschka, 2015)

Perceptron classification

Bonus info

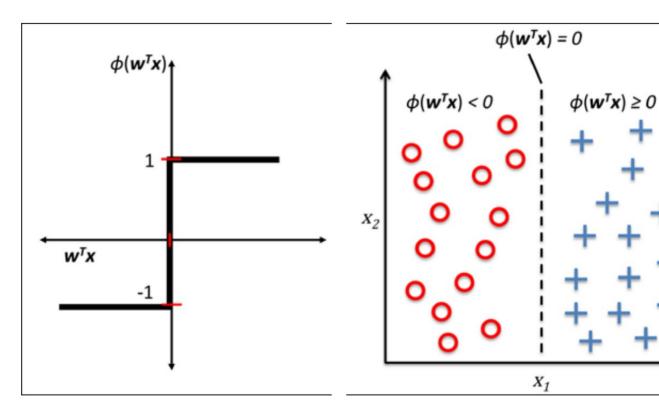
$$f(x) = a + rac{b-a}{1+e^{rac{c-x}{d}}}$$

Practical exercise 5...

$$a=-1$$
 $b=1$

$$c=0$$

d going to 0



(p. 21: Raschka, 2015)

We want to find **w**^T**x** that achieves this separation

In Python

```
class Perceptron(object):
    """ Perceptron classifier
    Parameters
    eta: float
        Learning rate (between 0.0 and 1.0)
    n iter : int
        Passes over the training dataset.
    Attributes
    w : 1d-array
        Weights after fitting.
    errors : list
        Number of misclassifications in every epoch.
    11 11 11
```

Special definition that indicates what the object (*Perceptron*) can be initialised with

```
def __init__(self, eta=0.01, n_iter=10):
    self.eta = eta
    self.n_iter = n_iter
```

```
ppn = Perceptron(eta=0.1, n_iter=10)
```

Specifying methods of *Perceptron*

- 1. Initialize the weights to 0 or small random numbers.
- 2. For each training sample $oldsymbol{x}^{(i)}$ perform the following steps:
 - 1. Compute the output value \hat{y} .
 - 2. Update the weights.

```
def fit(self, X, y):
    """ Fit training data.
   Parameters
   X : {array-like}, shape = [n samples, n features]
        Traing vectors, where n samples
        is the number of samples and
        n features is the number of features.
   y : array-like, shape = [n samples]
        Target values.
   Returns
    self : object
    self.w = np.zeros(1 + X.shape[1])
    self.errors = []
    for in range(self.n iter):
        errors = 0
        for xi, target in zip(X, y):
            update = self.eta * (target - self.predict(xi))
            self.w [1:] += update * xi
            self.w [0] += update
            errors += int(update != 0.0)
        self.errors .append(errors)
    return self
```

Compute the output value \hat{y}

```
def net_input(self, X):
    """Calculate net input"""
    return np.dot(X, self.w_[1:]) + self.w_[0]

def predict(self, X):
    """Return class label after unit step"""
    return np.where(self.net_input(X) >= 0.0, 1, -1)
```

$$\phi(z) = \begin{cases} 1 & \text{if } z \ge \theta \\ -1 & \text{otherwise} \end{cases}$$

When we are right

$$\Delta w_j = \eta \left(-1 - 1 \right) x_j^{(i)} = 0$$
 predicted label

$$\Delta w_j = \eta \left(1 - 1 \right) x_j^{(i)} = 0$$

predicted label

 Δw_i : change in weight

 η : learning rate

When we are wrong

$$\Delta w_j = \eta \left(1 - 1 \right) x_j^{(i)} = \eta \left(2 \right) x_j^{(i)}$$
predicted label

real label

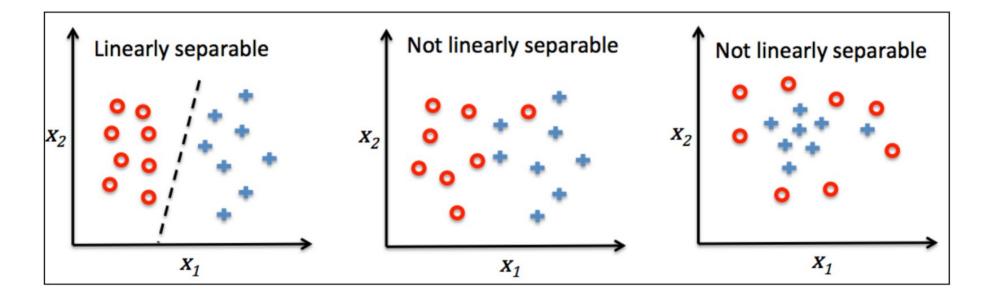
$$\Delta w_j = \eta \left(-1 - 1 \right) x_j^{(i)} = \eta \left(-2 \right) x_j^{(i)}$$

predicted label

 Δw_i : change in weight

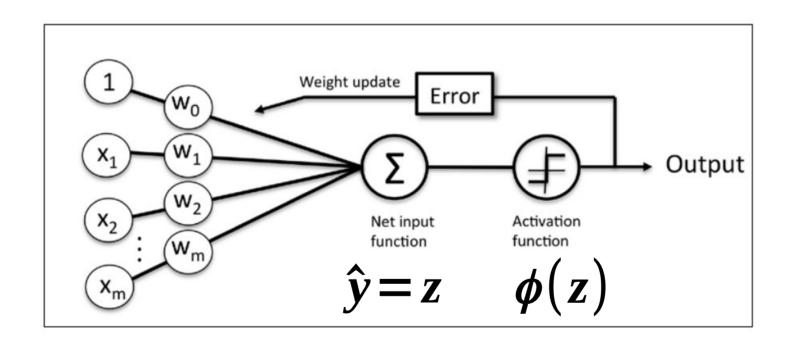
 η : learning rate

Convergence only possible when linearly separable



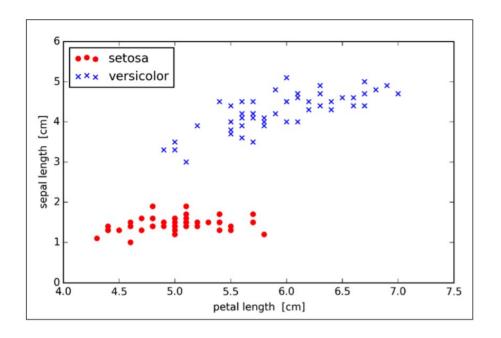
(p. 23: Raschka, 2015)

Perceptron: Graphical summary



(p. 24: Raschka, 2015)

An example



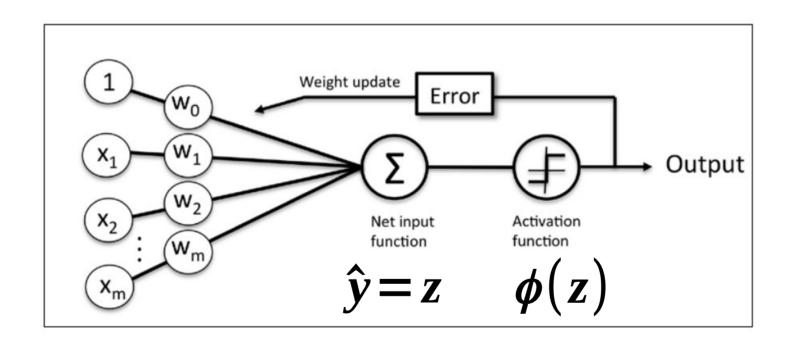
```
In [4]: ppn.w_
Out[4]: array([-0.4 , -0.68, 1.82])
```

$$\hat{y} = -0.4 - 0.68 \cdot 4.9 + 1.82 \cdot 1.4 = -1.184$$

```
In [11]: ppn.net_input(X[1, :])
Out[11]: -1.1839999999999975
```

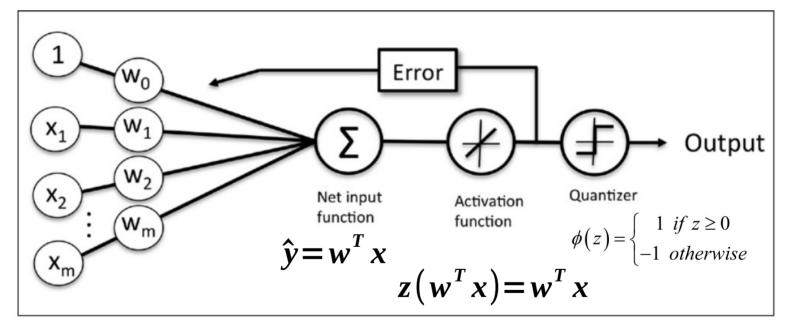
(p. 29 & p. 32: Raschka, 2015)

Perceptron: Graphical summary



(p. 24: Raschka, 2015)

ADAptive Linear NEuron (ADALINE)



$$\mathbf{w}^{T} \mathbf{x} = w_{0} x_{0} + w_{1} x_{1} + \dots + w_{m-1} x_{m-1} + w_{m} x_{m}$$
(p. 33: Raschka, 2015)

ADALINE Gradient descent

```
def __init__(self, eta=0.01, n_iter=50):
    self.eta = eta
    self.n_iter = n_iter
```

```
class AdalineGD(object):
    """ ADAptive LInear NEuron classifier
   Parameters
   eta: float
       Learning rate (between 0.0 and 1.0)
   n iter : int
       Passes over the training dataset.
   Attributes
   w : 1d-array
       Weights after fitting.
   errors : list
       Number of misclassifications in every epoch.
    0.00
```

Methods

$$\hat{y} = w^T x$$

$$z(w^Tx)=w^Tx$$

$$\phi(z) = \begin{cases} 1 & \text{if } z \ge 0 \\ -1 & \text{otherwise} \end{cases}$$

```
def net_input(self, X):
    """Calculate net input"""
    return np.dot(X, self.w_[1:]) + self.w_[0]

def activation(self, X):
    """Computer linear activation"""
    return self.net_input(X)

def predict(self, X):
    """Return class label after unit step"""
    return np.where(self.activation(X) >= 0.0, 1, -1)
```

The fit method

eta: learning rate (a constant) output: $X \beta = \hat{y}$

errors: $y - \hat{y}$

CC BY Licence 4.0: Lau Møller Andersen

X.T.dot(errors): $X^T \cdot (y - \hat{y})$

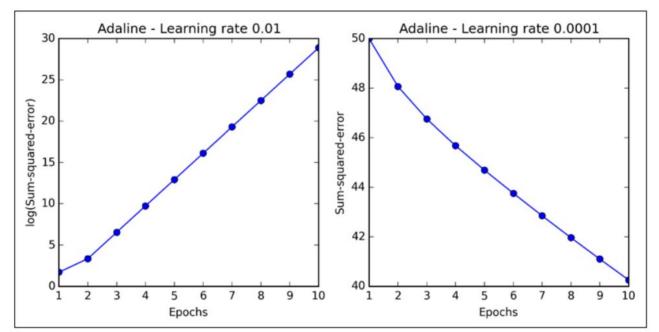
$$X^{T} \cdot (y - \hat{y}) = \Delta w_{1} + \Delta w_{2} + \dots + \Delta w_{m-1} + \Delta w_{m}$$

cost function: $(\sum (y - \hat{y})^2)/2$

```
def fit(self, X, y):
    """ Fit training data.
    Parameters
    X : {array-like}, shape = [n samples, n features]
        Traing vectors, where n samples
        is the number of samples and
        n features is the number of features.
    v : arrav-like, shape = [n samples]
        Target values.
    Returns
    self : object
    self.w = np.zeros(1 + X.shape[1])
    self.cost = []
    for i in range(self.n iter):
        output = self.net input(X)
        errors = (y - output)
        self.w [1:] += self.eta * X.T.dot(errors)
        self.w [0] += self.eta * errors.sum()
        cost = (errors**2).sum() / 2.0
        self.cost .append(cost)
    return self
```

Learning rate

Overshooting the global minimum

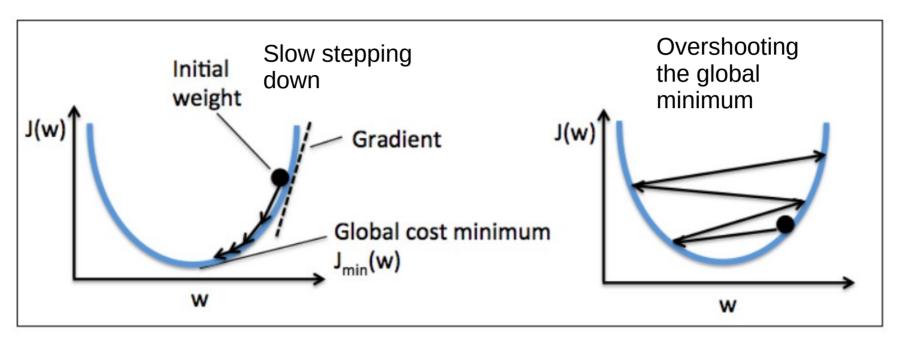


Slow stepping down

Always check whether it converges

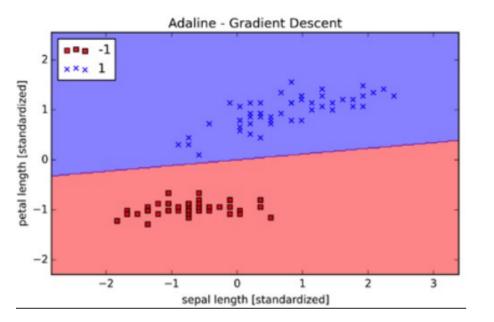
(p. 40: Raschka, 2015)

Gradient descent



$$J(w) = (\sum (y - \hat{y})^2)/2$$

(p. 40: Raschka, 2015)



(p. 42: Raschka, 2015)

```
In [50]: X_std[1, :]
Out[50]: array([-0.89430898, -1.01435952])
```

```
In [38]: ada.w_
Out[38]: array([ 1.59872116e-16, -1.26256159e-01, 1.10479201e+00])
```

$$\hat{y} \approx 0 - 0.127 \cdot (-0.894) + 1.10 \cdot (-1.014) = -1.01$$

In [49]: ada.net_input(X_std[1, :])
Out[49]: -1.0077442758158444

How does this relate to linear regression?

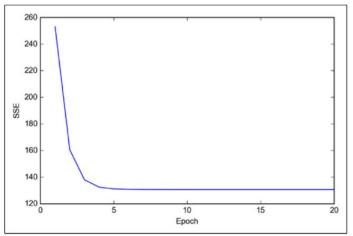
From ADALINE

$$\mathbf{w}^{T} \mathbf{x} = \mathbf{w}_{0} \mathbf{x}_{0} + \mathbf{w}_{1} \mathbf{x}_{1} + \dots + \mathbf{w}_{m-1} \mathbf{x}_{m-1} + \mathbf{w}_{m} \mathbf{x}_{m}$$

Very similar to ADALINE and when converged will be virtually identical to the ordinary least squares solution

$$\hat{\beta} = (X^T X)^{-1} X^T y$$

Convergence

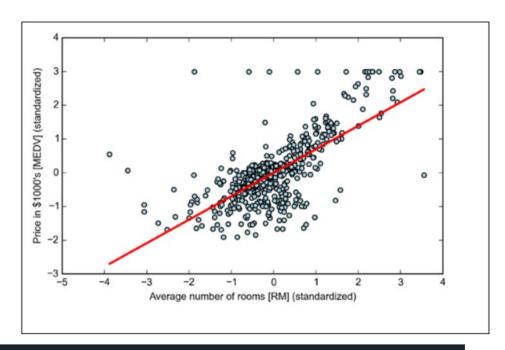


```
class LinearRegressionGD(object):
    def init (self, eta=0.001, n iter=20):
       self.eta = eta
        self.n iter = n iter
    def fit(self, X, y):
        self.w = np.zeros(1 + X.shape[1])
        self.cost = []
        for i in range(self.n iter):
            output = self.net input(X)
            errors = (y - output)
            self.w [1:] += self.eta * X.T.dot(errors)
            self.w [0] += self.eta * errors.sum()
            cost = (errors**2).sum() / 2.0
            self.cost .append(cost)
        return self
    def net input(self, X):
        return np.dot(X, self.w [1:]) + self.w [0]
    def predict(self, X):
        return self.net input(X)
```

What we have seen before

```
lr = LinearRegressionGD()
lr.fit(X_std, y_std)
```

(p. 288: Raschka, 2015)



```
In [8]: lr.w_
Out[8]: array([-4.68958206e-16, 6.95359426e-01])
```



In scikit-learn 1.0, we decided to deprecate the sklearn.datasets.load_boston function because the design of this dataset casually assumes that people prefer to buy housing in racially segregated neighborhoods.

(p. 229: Raschka, 2015)

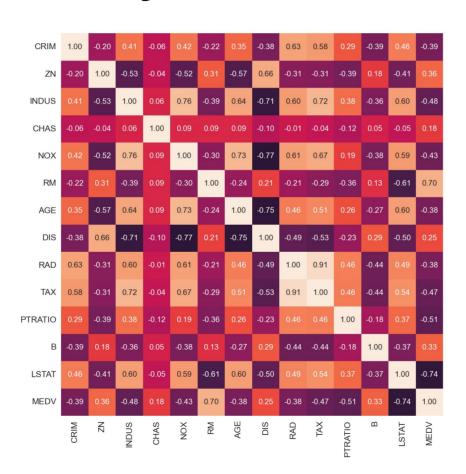
The features of the 506 samples may be summarized as shown in the excerpt of the dataset description:

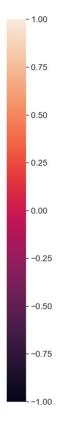
- **CRIM**: This is the per capita crime rate by town
- **ZN**: This is the proportion of residential land zoned for lots larger than 25,000 sq.ft.
- **INDUS**: This is the proportion of non-retail business acres per town
- **CHAS**: This is the Charles River dummy variable (this is equal to 1 if tract bounds river; 0 otherwise)
- **NOX**: This is the nitric oxides concentration (parts per 10 million)
- **RM**: This is the average number of rooms per dwelling
- AGE: This is the proportion of owner-occupied units built prior to 1940
- **DIS**: This is the weighted distances to five Boston employment centers
- **RAD**: This is the index of accessibility to radial highways
- TAX: This is the full-value property-tax rate per \$10,000
- **PTRATIO**: This is the pupil-teacher ratio by town
- **B**: This is calculated as $1000(Bk 0.63)^2$, where Bk is the proportion of people of African American descent by town
- LSTAT: This is the percentage lower status of the population
- MEDV: This is the median value of owner-occupied homes in \$1000s

Multiple linear regression

$$\begin{split} & M \hat{EDV} = w_{0} x_{0} + w_{1} CRIM + w_{2} ZN + w_{3} INDUS + w_{4} CHAS \\ & + w_{5} NOX + w_{6} RM + w_{7} AGE + w_{8} DIS \\ & + w_{9} RAD + w_{10} TAX + w_{11} PTRATIO + w_{12} B + w_{13} LSTAT + \epsilon \end{split}$$

Collinearity – correlation matrix

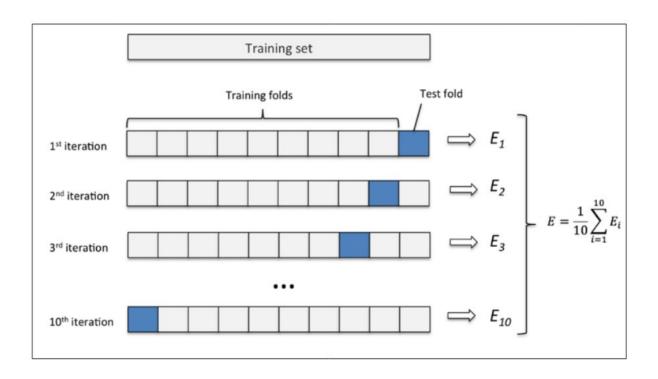




Because of the collinearity, we know we are prone to overfitting, so we do **out-of-sample** prediction instead of validating our model with traditional measures like R^2 and maximum likelihood

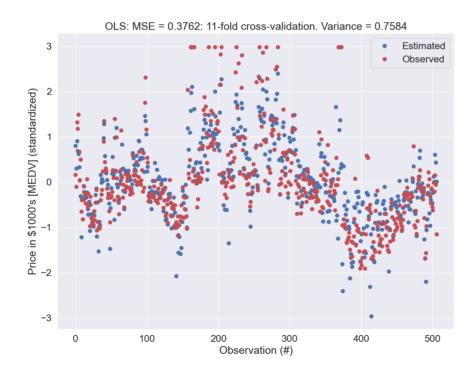
How to choose the **out-of-sample** dataset?

Cross-validation



(p. 176: Raschka, 2015)

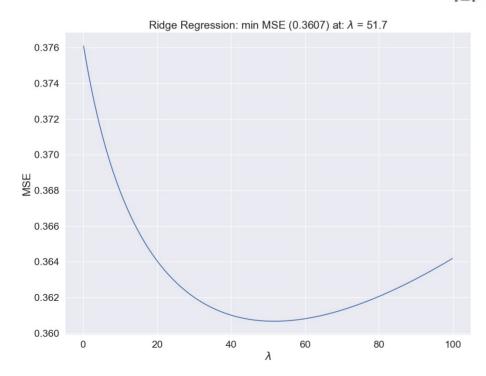
```
OLS = LinearRegression()
OLS.fit(X_std, y_std)
MSE = np.mean(cross_validate(OLS, X_std, y_std, k=11))
```

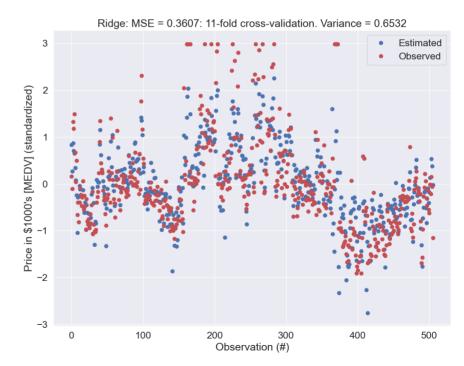


We can impose penalties

(but not on the intercept)

$$J(w)_{Ridge} = \sum_{i=1}^{n} (y^{(i)} - \hat{y}^{(i)})^{2} + \lambda \| w \|_{2}^{2}$$

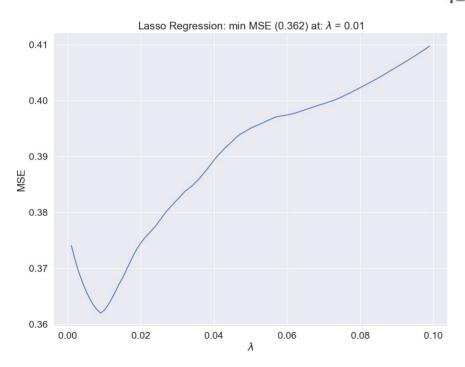


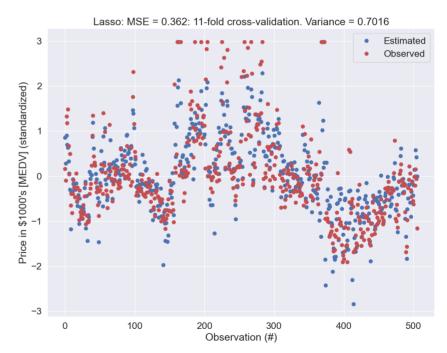


We can impose penalties

(but not on the intercept)

$$J(w)_{LASSO} = \sum_{i=1}^{n} (y^{(i)} - \hat{y}^{(i)})^{2} + \lambda \|w\|_{1}$$





Coefficients are shrunk

```
In [131]: OLS.coef
Out[131]:
array([-0.09874812, 0.12473758, 0.02386168, 0.06945318, -0.22231612,
       0.2911837 , 0.0325356 , -0.32907266, 0.34212986, -0.28361575,
       -0.21482076, 0.09763631, -0.43131412])
In [132]: RR.coef
array([-0.07536542, 0.08180161, -0.03182673, 0.07855868, -0.13185121,
       0.31082552, 0.00548938, -0.23491485, 0.112424<u>08, -0.0959682</u>,
       -0.18436614, 0.09154233, -0.36579723])
In [133]: lasso.coef
Out[133]:
array([-0.07348948, 0.09107936, -0. , 0.07003181, -0.17110318,
       0.30950805, 0. , -0.29010247, 0.16456993, -0.1319311 ,
       -0.19668957, 0.09063304, -0.41664587])
```

We can impose penalties

(but not on the intercept)

$$J(w)_{ElasticNet} = \sum_{i=1}^{n} (y^{(i)} - \hat{y}^{(i)})^{2} + \lambda_{1} \sum_{j=1}^{m} w_{j}^{2} + \lambda_{2} \sum_{j=1}^{m} |w_{j}|$$

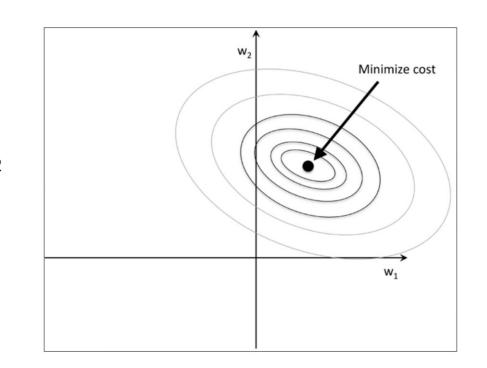
Did you learn?

Linear regression revisited (machine learning)

- 1) Learning some early classification methods
- Learning how linear regression (with biasing penalties) can be constructed and crossvalidated
- 3) Understanding that biasing in-sample solutions can improve out-of-sample predictions

Extra slides on regularization

$$J(w) = \sum_{i=1}^{n} (y_i - \hat{y}_i)^2$$



(p. 113: Raschka, 2015)

L2 regularization

Why is the *budget* round?

Compare with a circle centred at (0,0)

$$x^{2}+y^{2}=r^{2}$$

$$w_{1}^{2}+w_{2}^{2}=r^{2}$$

$$||w||_{2}=\sqrt{(w_{1}^{2}+w_{2}^{2})}$$

Minimize cost **Budget** $\lambda ||\mathbf{w}||_2^2$ Minimize cost + penalty Minimize penalty

(p. 114: Raschka, 2015)

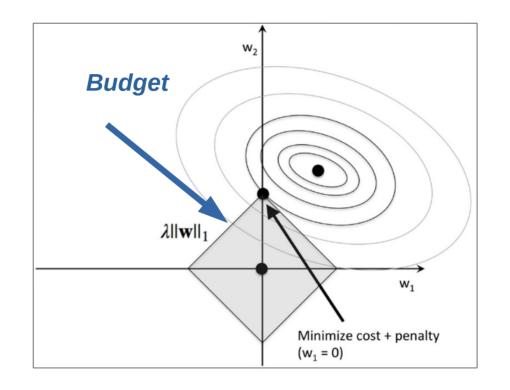
$$J(w)_{Ridge} = \sum_{i=1}^{n} (y^{(i)} - \hat{y}^{(i)})^{2} + \lambda \| w \|_{2}^{2}$$

L1 regularization

Why is the *budget* square?

$$||w||_1 = |w_1| + |w_2|$$

if $w_1 = max(w_1)$ then $w_2 = 0$
if $w_2 = max(w_2)$ then $w_1 = 0$



$$J(w)_{LASSO} = \sum_{i=1}^{n} (y^{(i)} - \hat{y}^{(i)})^{2} + \lambda \|w\|_{1}$$

References

Raschka, S., 2015. Python Machine Learning.
 Packt Publishing Ltd.