Imageprocessing 1.0

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		0.2.1		nain	
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## **Chapter 1**

## **Test List**

Impulsive\_uniform\_noise(nivel1);

```
Member Image::Dimension() basic_funcions.cpp
                   Image I;
                   I.Dimension();
Member Image::Filtering(arma::mat, int, int) filtering_median.cpp filtering_mean.cpp
                   mat matrix;
                   int I = 5;
                   int flag = 0;
                   Filtering(matrix, I, flag);
Member Image::Four_windows_opencv(const char *, const char
                   main.cpp
                   const char* imag1= "src/Resources/images_salt_and_pepper/lady_256_0_1.pgm";
                   const char* imag2= "src/Resources/images_salt_and_pepper/lady_256_1.pgm";
                   const char* imag3= "src/Resources/images_salt_and_pepper/lady_256_10.pgm";
                   const char* imag4= "src/Resources/images_salt_and_pepper/lady_256_100.pgm";
                   Four_windows_opencv(imag1, imag2, imag3, imag4, label1, label2, label3, la-
                   bel4);
Member Image::Gaussian_noise(double) gaussian_noise.cpp
                   int nivel=0.1;
```

2 Test List

```
Member Image::Get_pixel(int, int) basic_funcions.cpp
     Image I;
     int row=5;
     int col=5;
     I.Get_pixel(row, col);
Member Image::Get_pixels() basic_funcions.cpp
     Image I;
     I.Get_pixels();
Member Image::Image() basic_funcions.cpp
     Image I;
     I.Dimension();
Member Image::Image load(arma::mat, std::string) basic funcions.cpp
     mat matrix;
     string ruta = "src/Resources/images/house.256.pgm";
     Image_load(matrix, ruta);
Member Image::Impulsive_uniform_noise(int) uniform_impulsive_noise.cpp
     int nivel=0.1;
     Impulsive uniform noise(nivel);
Member Image::Lost_pixels_noise(int) lost_Pixels_noise.cpp
     int nivel=0.1;
     Lost_pixels_noise(nivel);
Member Image::MAE(arma::mat, arma::mat) filtering mean.cpp
     mat matrix_r;
     mat matriz_f;
     MAE(matrix r, matriz f);
Member Image::MSE(arma::mat, arma::mat) filtering_mean.cpp
     mat matrix_r;
     mat matriz_f;
     MSE(matrix r, matriz f);
```

```
Member Image::Noise_remover(arma::mat, int) noise_remover.cpp
     mat matrix;
     int image_tam = 256;
     Noise_remover(matrix, image_tam);
Member Image::Overlap(arma::mat) overlap.cpp
     mat matrix;
     Overlap(matrix);
Member Image::PSNR(arma::mat, arma::mat) filtering_mean.cpp
     mat matrix r;
     mat matriz_f;
     PSNR(matrix_r, matriz_f);
Member Image::Salt_and_pepper_noise(int) salt_pepper.cpp
     int nivel=0.1;
     Salt and pepper noise(nivel);
Member Image::SaveImage(arma::mat, std::string) gaussian_noise.cpp
     mat matrix;
     string ruta= "src/Resources/images/house.256.pgm";
     SaveImage(matrix, ruta);
Member Image::Two_windows_opencv(const char *, const char *, std::string, std::string)
     main.cpp
     const char* imag1= "src/Resources/images_salt_and_pepper/lady_256_0_1.pgm";
     const char* imag2= "src/Resources/images_salt_and_pepper/lady_256_1.pgm";
     string label1 = "Imagen1";
     string label2 = "Imagen2";
     Two_windows_opencv(imag1, imag2, label1, label2);
```

4 Test List

# Chapter 2

# **Class Index**

## 2.1 Class List

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Image .																																9

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# **Chapter 3**

# File Index

## 3.1 File List

Here is a list of all files with brief descriptions:

examples/basic_funcions.cpp
examples/filtering_mean.cpp
examples/filtering_median.cpp
examples/gaussian_noise.cpp
examples/idtc_Robusta_mean.cpp
examples/idtc_Robusta_median.cpp
examples/lost_Pixels_noise.cpp
examples/noise_remover.cpp
examples/overlap.cpp
examples/salt_pepper.cpp
examples/uniform_impulsive_noise.cpp
include/Image.hpp
src/Four_windows_opencv.cpp
src/lmage_load.cpp
src/main.cpp
src/Two_windows_opencv.cpp

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## **Chapter 4**

## **Class Documentation**

## 4.1 Image::h Class Reference

The documentation for this class was generated from the following file:

• include/Image.hpp

## 4.2 Image Class Reference

```
#include <Image.hpp>
```

#### **Classes**

class h

## **Public Member Functions**

• arma::mat Image\_load (arma::mat, std::string)

Carga de Imagen pgm a mat.

• Image ()

Constructor de la clase.

- Image (arma::mat)
- void Dimension ()

Obtiene las dimensiones de la matriz.

int Get\_pixel (int, int)

Obtiene el valor de un pixel.

void Get\_pixels ()

Imprime todos los pixeles de la matriz imagen.

• arma::mat Gaussian noise (double)

Aplica Ruido Gaussiano a una matriz.

arma::mat Lost pixels noise (int)

Aplica Perdida de pixeles a una matriz.

arma::mat Salt\_and\_pepper\_noise (int)

Aplica Ruido Sal y Pimienta a una matriz.

• arma::mat Impulsive\_uniform\_noise (int)

Aplica Ruido Impulsivo Uniforme a una matriz.

void SaveImage (arma::mat, std::string)

Guarda la matriz en formato pgm.

• double PSNR (arma::mat, arma::mat)

Calculo del PSNR.

double MAE (arma::mat, arma::mat)

Calculo del MAE.

• double MSE (arma::mat, arma::mat)

Calculo del MSE.

arma::mat Filtering (arma::mat, int, int)

Aplica un filtrado usando el promedio o la mediana para remover ruido.

void Four\_windows\_opencv (const char \*, const char \*)

Carga cuatro imagenes en una ventana de opencv.

• void Two\_windows\_opencv (const char \*, const char \*, std::string, std::string)

Carga dos imagenes en una ventana de opencv.

arma::mat Noise\_remover (arma::mat, int)

Remocion de Ruido no solapado (ventana 8x8)

• arma::mat Overlap (arma::mat)

Remocion de Ruido solapado (ventana 8x8)

- arma::mat ldtc\_Robusta (arma::mat, int)
- double wmedianf (arma::vec &, arma::vec &)
- arma::mat Diccionary ()
- arma::vec Fast\_awmr (arma::vec &y, arma::mat &A, int sparsity, int itmax, double beta, double tol, double epsilon, int numcoefperiter, double Kpar)
- $\sim$ Image ()

#### **Private Attributes**

- int cols
- int rows
- · arma::mat matrix

#### 4.2.1 Constructor & Destructor Documentation

```
4.2.1.1 Image::Image ( )
```

Constructor de la clase.

Descripcion: Constructor de la clase Image para acceder a sus metodos internos

#### Test

```
basic_funcions.cpp
Image I;
I.Dimension();

4.2.1.2 Image::Image ( arma::mat )

4.2.1.3 Image::~Image ( )

4.2.2 Member Function Documentation

4.2.2.1 mat Image::Diccionary ( )

4.2.2.2 void Image::Dimension ( )
```

Obtiene las dimensiones de la matriz.

Descripcion: Permite obtener la dimension nxn de la matriz.

#### Returns

Retorna la dimension de la imagen nxn.

#### Test

```
basic_funcions.cpp
Image I;
I.Dimension();
```

4.2.2.3 vec Image::Fast\_awmr ( arma::vec & y, arma::mat & A, int sparsity, int itmax, double beta, double tol, double epsilon, int numcoefperiter, double Kpar )

```
4.2.2.4 mat Image::Filtering ( arma::mat , int , int )
```

Aplica un filtrado usando el promedio o la mediana para remover ruido.

Descripcion: Permite aplicar un filtrado a una matriz, utilizando el sparse. Se selecciona una ventana de lxl a la cual se le aplica un promedio o la mediana para restaurar la imagen. Se calcula utilizando el tamaño de la ventana I y el pixel central de la ventana, luego se aplica el promedio o mediana de los pixels adyacentes al central.

#### **Parameters**

matrix	es la matriz con ruido a la cual se le aplicara el filtrado.
1	es el tamaño de la ventana
flag	es la bandera que indica si se efectua el promedio o la mediana. Donde el
	promedio es igual 0 y la mediana igual a 1

#### Returns

filt\_matrix: Retorna la matriz con el filtrado.

#### Test

```
filtering_median.cpp filtering_mean.cpp
mat matrix;
int I = 5;
int flag = 0;
Filtering(matrix, I, flag);
```

```
4.2.2.5 void Image::Four_windows_opencv ( const char * imag1, const char * imag2, const char * imag3, const char * imag4, const char * label1, const char * label2, const char * label3, const char * label4 )
```

Carga cuatro imagenes en una ventana de opencv.

Descripcion: Permite cargar cuatro imagenes en una ventana de opencv

#### **Parameters**

imag1	es la ruta o ubicación de la imagen1
imag2	es la ruta o ubicación de la imagen2Imag3 Imag4
label1	es el nombre de la imagen1
label2	es el nombre de la imagen2Imag3 Imag4

#### Returns

Abre la ventana opency con cuatro imagenes

#### **Test**

#### main.cpp

```
const char* imag1= "src/Resources/images_salt_and_pepper/lady_256_0_1.pgm"; const char* imag2= "src/Resources/images_salt_and_pepper/lady_256_1.pgm"; const char* imag3= "src/Resources/images_salt_and_pepper/lady_256_10.pgm"; const char* imag4= "src/Resources/images_salt_and_pepper/lady_256_100.pgm"; Four_windows_opencv(imag1, imag2, imag3, imag4, label1, label2, label3, label4);
```

4.2.2.6 mat Image::Gaussian\_noise ( double nivel )

Aplica Ruido Gaussiano a una matriz.

Descripcion: Permite aplicarle Ruido Gaussiano a una matriz. El Ruido Gaussiano es una matriz de media 0 y con una desviacion estandar variable.

#### **Parameters**

nivel	es el nivel de varianza variable
	Parametros Internos:
	A es una matriz gaussiana de dimensiones iguales a la matriz y de media 0
	y varianza 1
	B es una matriz donde se almacena la matriz gaussiana de media 0 y el
	calculo de una varianza determinada
	std es la desviacion estandar

#### Returns

value: Retorna la matriz con el ruido aplicado

#### Test

```
gaussian_noise.cpp
int nivel=0.1;
Impulsive_uniform_noise(nivel1);
4.2.2.7 int Image::Get_pixel ( int row, int col )
```

Obtiene el valor de un pixel.

Descripcion: Permite obtener el valor de un pixel de la matriz de la imagen original

### **Parameters**

ro	es el numero de filas de la matriz	
C	es el numero de columnas de la matriz	

#### Returns

Retorna el valor (value) de un pixel

#### **Test**

```
basic_funcions.cpp
Image I;
int row=5;
int col=5;
I.Get_pixel(row, col);
```

4.2.2.8 void Image::Get\_pixels ( )

Imprime todos los pixeles de la matriz imagen.

Descripcion: Permite obtener e imprimir todos los pixeles de la imagen.

#### **Returns**

value: Retorna todos los pixeles.

#### **Test**

```
basic_funcions.cpp
Image I;
I.Get_pixels();

4.2.2.9 mat Image::Idtc_Robusta ( arma::mat , int )

4.2.2.10 mat Image::Image_load ( arma::mat , std::string )
```

Carga de Imagen pgm a mat.

Descripcion: Permite cargar la imagen en formato pgm a mat

#### **Parameters**

matrix	es la matriz que contine los pixeles de la imagen.
ruta	es la ubicacion o localizacion de la imagen.

#### **Returns**

Retorna si la matriz fue cargada o si hubo problemas en la carga.

#### **Test**

```
basic_funcions.cpp
mat matrix;
string ruta = "src/Resources/images/house.256.pgm";
Image_load(matrix, ruta);
```

4.2.2.11 mat Image::Impulsive\_uniform\_noise ( int nivel )

Aplica Ruido Impulsivo Uniforme a una matriz.

Descripcion: Permite aplicarle Ruido Impulsivo Uniforme a una matriz

#### **Parameters**

```
nivel es el porcentaje de ruido.
```

#### Returns

value: Retorna la matriz con el ruido aplicado.

#### **Test**

```
uniform_impulsive_noise.cpp
int nivel=0.1;
```

```
Impulsive_uniform_noise(nivel);
```

4.2.2.12 mat Image::Lost\_pixels\_noise ( int nivel )

Aplica Perdida de pixeles a una matriz.

Descripcion: Permite aplicarle Perdida de Pixeles a una matriz

#### **Parameters**

```
nivel es el porcentaje de ruido
```

#### Returns

value: Retorna la matriz con el ruido aplicado

#### **Test**

```
lost_Pixels_noise.cpp
int nivel=0.1;
Lost_pixels_noise(nivel);
4.2.2.13 double Image::MAE ( arma::mat , arma::mat )
```

Calculo del MAE.

Descripcion: Permite calcular el MAE (Error promedio absoluto) de una imagen con ruido y una imagen filtrada

#### **Parameters**

matrix_r	es la matriz con ruido.
matriz_f	es la matriz filtrada o recuperada

#### Returns

Calculo del MSE.

Retorna el valor del MAE

#### **Test**

```
filtering_mean.cpp
mat matrix_r;
mat matriz_f;
MAE(matrix_r, matriz_f);

4.2.2.14 double Image::MSE ( arma::mat , arma::mat )
```

Descripcion: Permite calcular el MSE (Error cuadratico medio) de una imagen con ruido y una imagen filtrada

#### **Parameters**

matrix_r	es la matriz con ruido.
matriz_f	es la matriz filtrada o recuperada

#### **Returns**

Retorna el valor del MSE

#### **Test**

```
filtering_mean.cpp
mat matrix_r;
mat matriz_f;
MSE(matrix_r, matriz_f);
```

4.2.2.15 mat Image::Noise\_remover ( arma::mat , int )

Remocion de Ruido no solapado (ventana 8x8)

Descripcion: Permite remover ruido mediante el uso de una ventana 8x8 no solapado

#### **Parameters**

matrix	es la matriz que se le removerá el ruido.	
image_tam	es el tamaño de la imagen.	

#### **Returns**

removermatrix: Retorna la matriz sin ruido.

#### **Test**

```
noise_remover.cpp
mat matrix;
int image_tam = 256;
Noise_remover(matrix, image_tam);
```

4.2.2.16 mat Image::Overlap ( arma::mat )

Remocion de Ruido solapado (ventana 8x8)

Descripcion: Permite remover ruido mediante el uso de una ventana 8x8 solapado

#### **Parameters**

matrix	es la matriz que se le removerá el ruido.

#### Returns

removermatrix: Retorna la matriz sin ruido.

#### Test

```
overlap.cpp
mat matrix;
Overlap(matrix);
```

4.2.2.17 double Image::PSNR ( arma::mat , arma::mat )

Calculo del PSNR.

Descripcion: Permite calcular el PSNR de una imagen con ruido y una imagen filtrada

#### **Parameters**

```
matrix_r es la matriz con ruido.

matriz_f es la matriz filtrada o recuperada
```

#### Returns

Retorna el valor del PSNR

#### **Test**

```
filtering_mean.cpp
mat matrix_r;
mat matriz_f;
PSNR(matrix_r, matriz_f);
```

4.2.2.18 mat Image::Salt\_and\_pepper\_noise ( int nivel )

Aplica Ruido Sal y Pimienta a una matriz.

Descripcion: Permite aplicarle Ruido Sal y Pimienta a una matriz

#### **Parameters**

```
nivel es el porcentaje de ruido
```

#### Returns

Retorna la matriz con el ruido (RG)

#### Test

```
salt_pepper.cpp
int nivel=0.1;
Salt_and_pepper_noise(nivel);
```

4.2.2.19 void Image::SaveImage ( arma::mat , std::string )

Guarda la matriz en formato pgm.

Descripcion: Permite guardar una matriz mat en formato pgm

#### **Parameters**

matrix	matriz que contine los pixeles de la imagen.
ruta	ubicacion o localizacion de la imagen.

#### **Returns**

Retorna si la matriz fue guardada o si hubo problemas al guardar.

#### **Test**

```
gaussian_noise.cpp
mat matrix;
string ruta= "src/Resources/images/house.256.pgm";
SaveImage(matrix, ruta);

4.2.2.20 void Image::Two_windows_opencv ( const char * , const char * , std::string , std::string )
```

Carga dos imagenes en una ventana de opencv.

Descripcion: Permite cargar dos imagenes en una ventana de opency con sus respectivas etiquetas (label).

#### **Parameters**

imag1	es la ruta o ubicación de la imagen1.
imag2	es la ruta o ubicación de la imagen2.
label1	es el nombre de la imagen1.
label2	es el nombre de la imagen2.

#### **Returns**

Abre la ventana opency con dos imagenes.

#### **Test**

```
main.cpp
```

```
const char* imag1= "src/Resources/images_salt_and_pepper/lady_256_0_1.pgm"; const char* imag2= "src/Resources/images_salt_and_pepper/lady_256_1.pgm"; string label1 = "lmagen1"; string label2 = "lmagen2"; Two_windows_opencv(imag1, imag2, label1, label2);
```

```
4.2.2.21 double Image::wmedianf (arma::vec & , arma::vec & )
4.2.3 Member Data Documentation
4.2.3.1 int Image::cols [private]
4.2.3.2 arma::mat Image::matrix [private]
4.2.3.3 int Image::rows [private]
```

The documentation for this class was generated from the following files:

- include/Image.hpp
- src/Four\_windows\_opencv.cpp
- src/Image\_load.cpp
- src/Two\_windows\_opencv.cpp

## **Chapter 5**

## **File Documentation**

## 5.1 examples/basic\_funcions.cpp File Reference

```
#include "../include/Image.hpp"
#include <iostream>
#include <armadillo>
```

#### **Functions**

• int main ()

#### 5.1.1 Function Documentation

```
5.1.1.1 int main ( )
```

## 5.2 examples/filtering\_mean.cpp File Reference

```
#include <iostream>
#include <armadillo>
#include "Image.hpp"
```

#### **Functions**

• int main ()

### 5.2.1 Function Documentation

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```
5.2.1.1 int main ( )
```

## 5.3 examples/filtering\_median.cpp File Reference

```
#include <iostream>
#include <armadillo>
#include "Image.hpp"
```

#### **Functions**

• int main ()

#### 5.3.1 Function Documentation

```
5.3.1.1 int main ( )
```

## 5.4 examples/gaussian\_noise.cpp File Reference

```
#include <iostream>
#include <armadillo>
#include "Image.hpp"
```

#### **Functions**

• int main ()

#### 5.4.1 Function Documentation

```
5.4.1.1 int main ( )
```

## 5.5 examples/idtc\_Robusta\_mean.cpp File Reference

```
#include <iostream>
#include <armadillo>
#include "Image.hpp"
```

#### **Functions**

• int main ()

#### 5.5.1 Function Documentation

```
5.5.1.1 int main ( )
```

## 5.6 examples/idtc\_Robusta\_median.cpp File Reference

```
#include <iostream>
#include <armadillo>
#include "Image.hpp"
```

#### **Functions**

• int main ()

### 5.6.1 Function Documentation

```
5.6.1.1 int main ( )
```

## 5.7 examples/lost\_Pixels\_noise.cpp File Reference

```
#include <iostream>
#include <armadillo>
#include "Image.hpp"
```

#### **Functions**

• int main ()

#### 5.7.1 Function Documentation

```
5.7.1.1 int main ( )
```

## 5.8 examples/noise\_remover.cpp File Reference

```
#include <iostream>
#include <armadillo>
#include "Image.hpp"
```

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```
Functions
```

```
• int main ()
```

#### 5.8.1 Function Documentation

```
5.8.1.1 int main ( )
```

## 5.9 examples/overlap.cpp File Reference

```
#include <iostream>
#include <armadillo>
#include "Image.hpp"
```

#### **Functions**

• int main ()

#### 5.9.1 Function Documentation

```
5.9.1.1 int main ( )
```

## 5.10 examples/salt\_pepper.cpp File Reference

```
#include <iostream>
#include <armadillo>
#include "Image.hpp"
```

#### **Functions**

• int main ()

#### 5.10.1 Function Documentation

```
5.10.1.1 int main ( )
```

## 5.11 examples/uniform\_impulsive\_noise.cpp File Reference

```
#include <iostream>
#include <armadillo>
```

```
#include "Image.hpp"
```

#### **Functions**

• int main ()

#### 5.11.1 Function Documentation

```
5.11.1.1 int main ( )
```

### 5.12 include/Image.hpp File Reference

```
#include <iostream>
#include <armadillo>
```

#### Classes

· class Image

## 5.13 src/Four\_windows\_opencv.cpp File Reference

```
#include "../include/Image.hpp"
#include <opencv2/imgproc/imgproc.hpp>
#include <opencv2/core/core.hpp>
#include <opencv2/highgui/highgui.hpp>
#include <opencv2/core/utility.hpp>
#include <iostream>
```

## 5.14 src/Image\_load.cpp File Reference

```
#include "../include/Image.hpp"
#include <iostream>
#include <armadillo>
```

#### **Functions**

double Average\_Median (vec vector, int flag)
 Calcula el promedio y la mediana.

#### 5.14.1 Function Documentation

```
5.14.1.1 double Image::Average_Median ( vec vector, int flag )
```

Calcula el promedio y la mediana.

Descripcion: Permite calcular el promedio y la mediana.

#### **Parameters**

vector	vectores el vector al cual se le calculará el promedio o la medianaflagcuando flag = 0 se calcula el promedio y cuando flag = 1 se calcula la medi-	
flag		
	ana	

#### Returns

```
value: Retorna la matriz con el ruido
vec B;
Average_Median(B, 0); //Promedio-Media
Average_Median(B, 1); //Mediana
```

## 5.15 src/main.cpp File Reference

```
#include <iostream>
#include <armadillo>
#include "../include/Image.hpp"
```

#### **Functions**

```
• int main ()
```

Titulo: Funcion de Inicio.

#### 5.15.1 Function Documentation

```
5.15.1.1 int main ( )
```

Titulo: Funcion de Inicio.

Descripcion: Comienzo de codigo.

FA = I.Filtering(SC, 5);

## 5.16 src/Two\_windows\_opencv.cpp File Reference

```
#include "../include/Image.hpp"
```

```
#include <opencv2/imgproc/imgproc.hpp>
#include <opencv2/core/core.hpp>
#include <opencv2/highgui/highgui.hpp>
#include <opencv2/core/utility.hpp>
#include <iostream>
```

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