

COM303: Digital Signal Processing

Lecture 18: Multirate signal processing

- ▶ ideal and practical sampling and interpolation
- ▶ bandpass sampling
- ▶ multirate signal processing

advanced topics in sampling

From Continuous to Discrete Time

$$x_c(t) \longrightarrow x[n]$$

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ideally

in practice

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$$x[n] = \langle x_c(t), \text{sinc}\left(\frac{t - nT_s}{T_s}\right) \rangle$$

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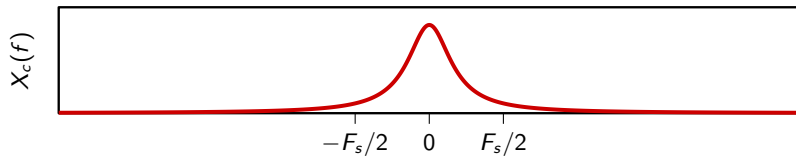
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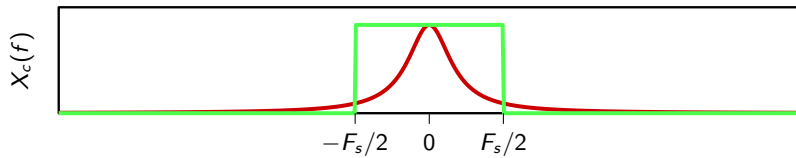
$$X(e^{j\omega}) = F_s X_c\left(\frac{\omega}{2\pi} F_s\right)$$

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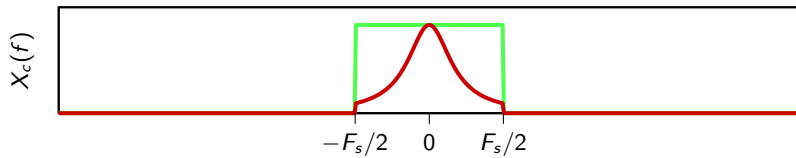
Ideal case



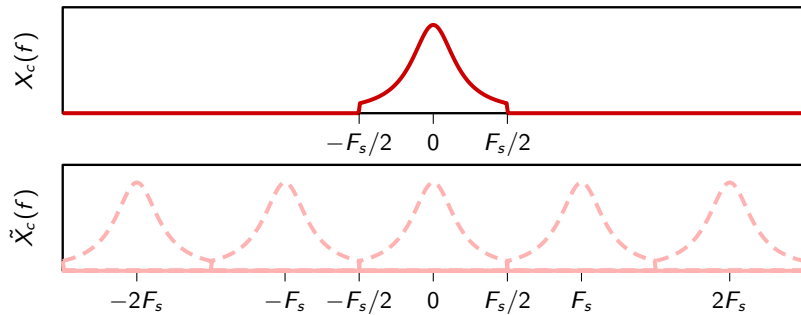
Ideal case



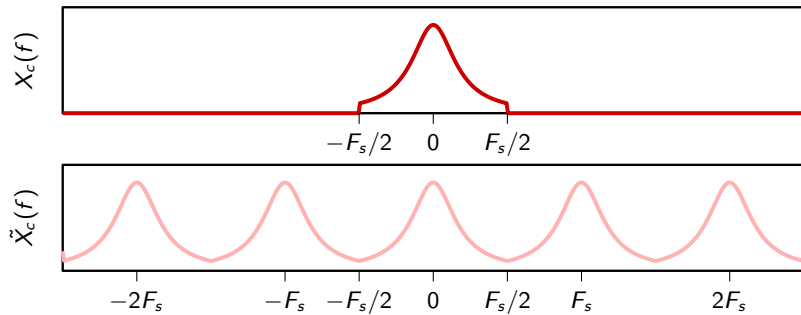
Ideal case



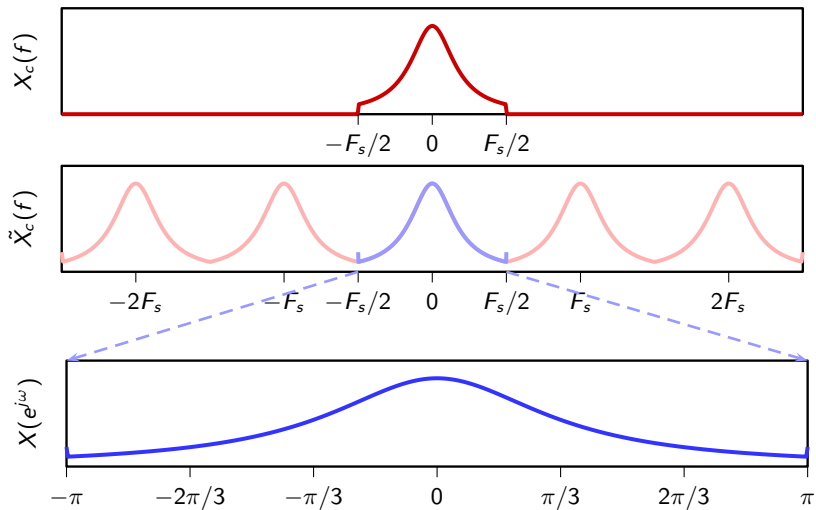
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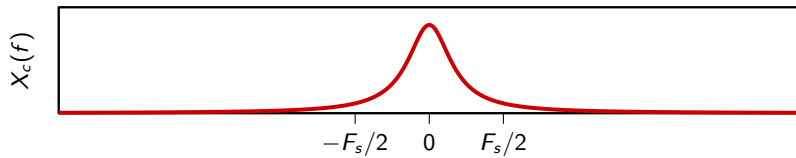
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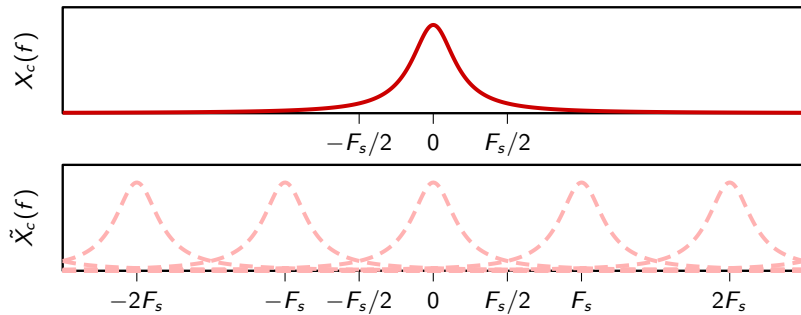
$$x[n] = x_c(nT_s)$$

$$X(e^{j\omega}) = F_s \sum_{k=-\infty}^{\infty} X_c\left(\frac{\omega}{2\pi} F_s - kF_s\right)$$

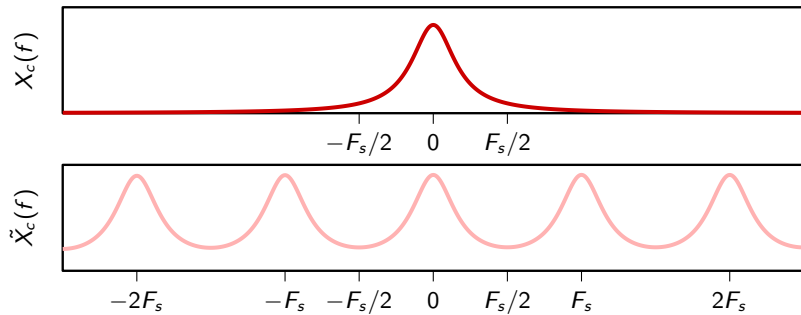
In practice



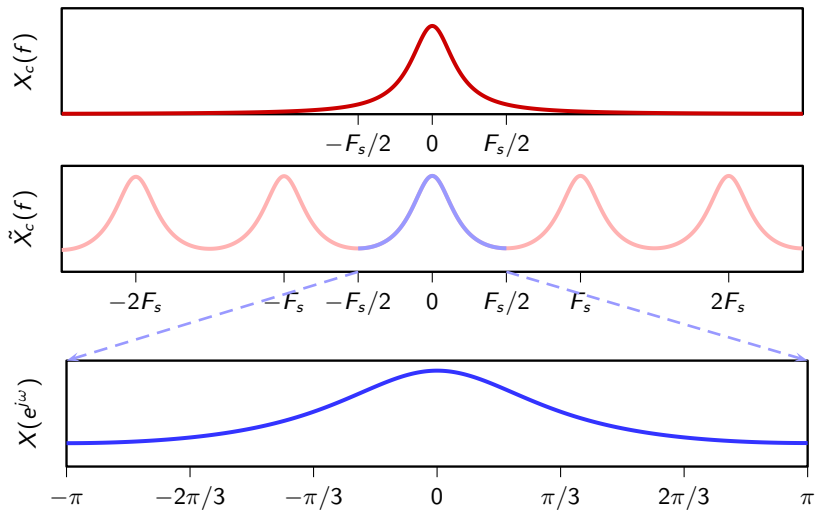
In practice



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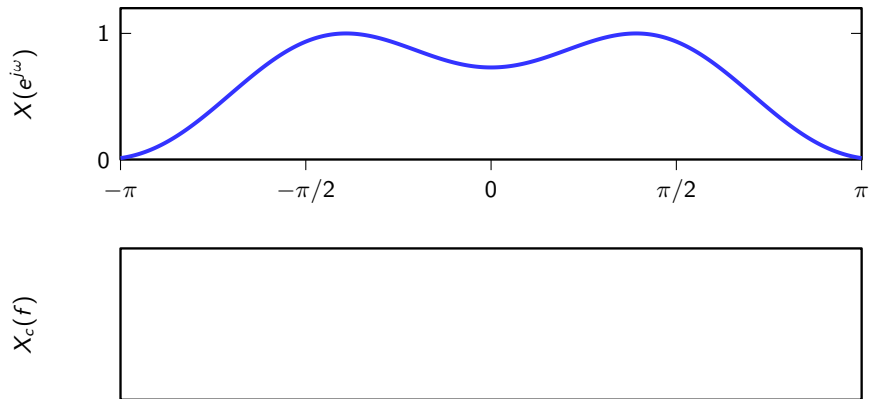
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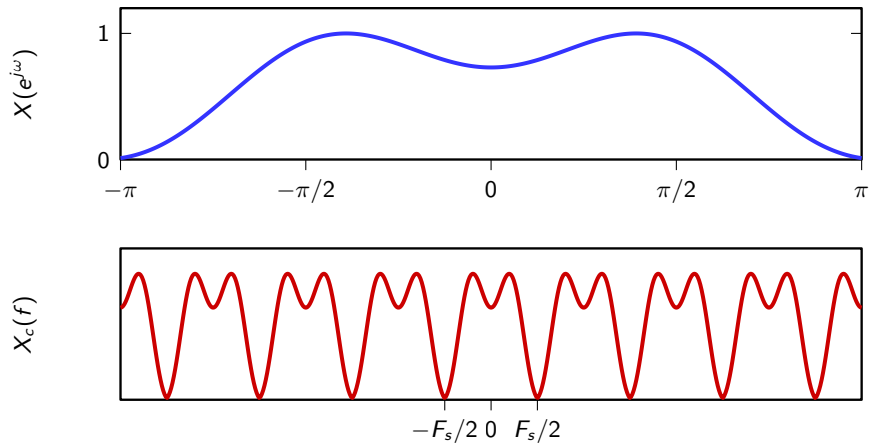
$$x_c(t) = \sum_{n=-\infty}^{\infty} x[n] \operatorname{sinc}\left(\frac{t - nT_s}{T_s}\right)$$

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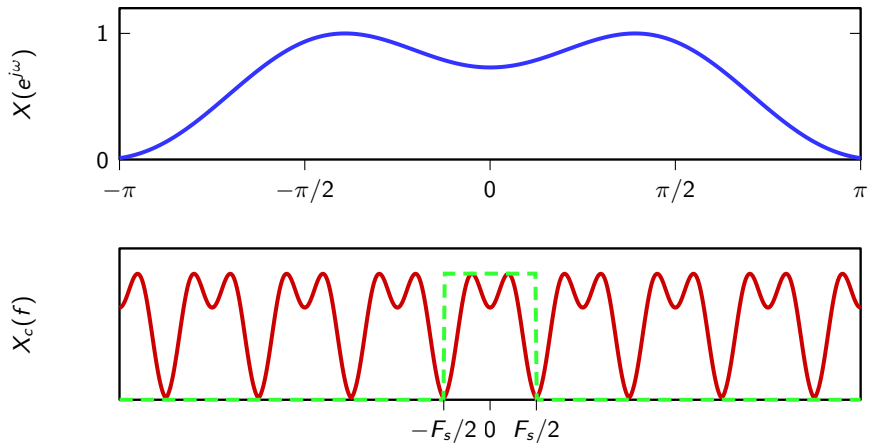
sinc interpolation



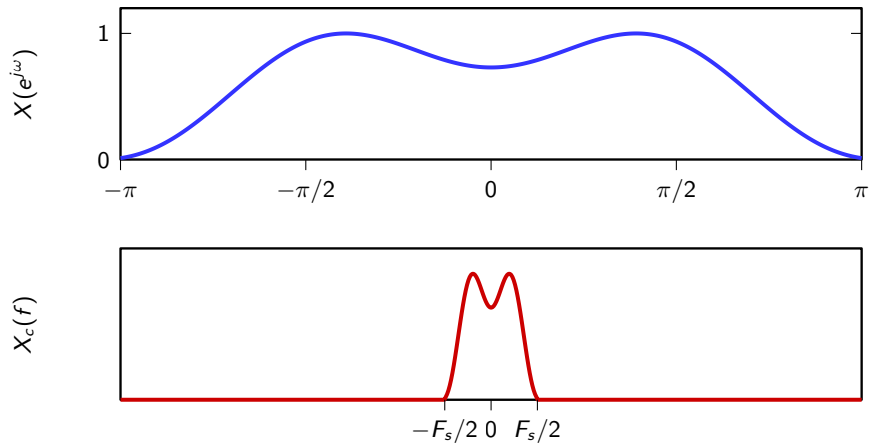
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$$x_c(t) = \sum_{n=-\infty}^{\infty} x[n] i\left(\frac{t - nT_s}{T_s}\right)$$

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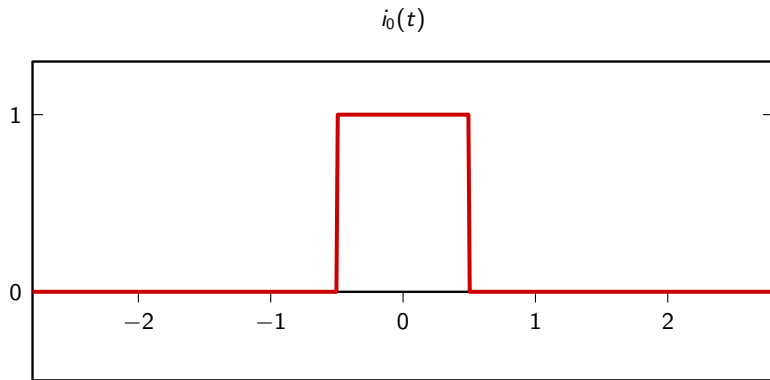
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$$X_c(f) = ?$$

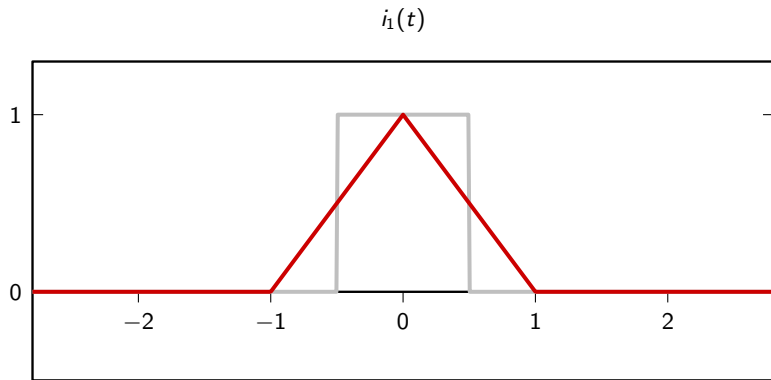
Practical interpolation

$$x_c(t) = \sum_{n=-\infty}^{\infty} x[n] i\left(\frac{t - nT_s}{T_s}\right)$$

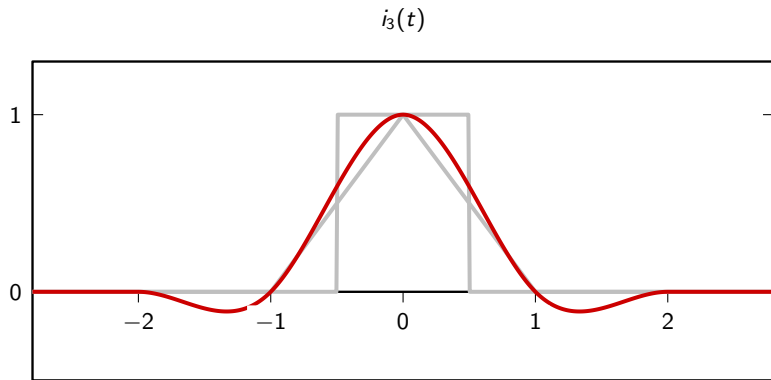
Local interpolators



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Spectral representation (I)

$$\begin{aligned} X_c(f) &= \int_{-\infty}^{\infty} x_c(t) e^{-j2\pi ft} dt \\ &= \int_{-\infty}^{\infty} \sum_{n=-\infty}^{\infty} x[n] i \left(\frac{t - nT_s}{T_s} \right) e^{-j2\pi ft} dt \\ &= \sum_{n=-\infty}^{\infty} x[n] \int_{-\infty}^{\infty} i \left(\frac{t - nT_s}{T_s} \right) e^{-j2\pi ft} dt \end{aligned}$$

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Fourier Transform properties

$$\text{FT} \{x(t/a)\} = aX(af)$$

$$\text{FT} \{x(t - b)\} = X(f) e^{-j2\pi bf}$$

$$\int_{-\infty}^{\infty} i \left(\frac{t - nT_s}{T_s} \right) e^{-j2\pi ft} dt = T_s I(T_s f) e^{-j2\pi n T_s f}$$

Spectral representation (II)

$$\begin{aligned} X(f) &= T_s \sum_{n=-\infty}^{\infty} x[n] l(T_s f) e^{-j2\pi n T_s f} \\ &= \frac{1}{F_s} l\left(\frac{f}{F_s}\right) \sum_{n=-\infty}^{\infty} x[n] e^{-j2\pi n f / F_s} \\ &= \frac{1}{F_s} l\left(\frac{f}{F_s}\right) X(e^{j2\pi f / F_s}) \end{aligned}$$

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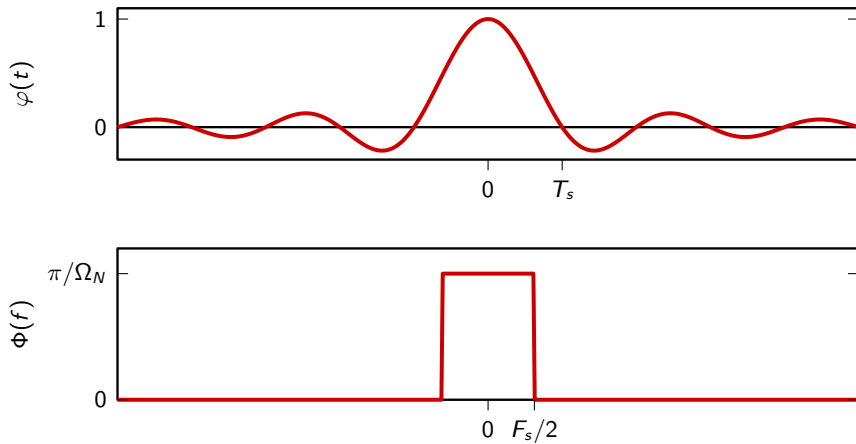
sinc interpolation

$$i(t) = \text{sinc}(t)$$

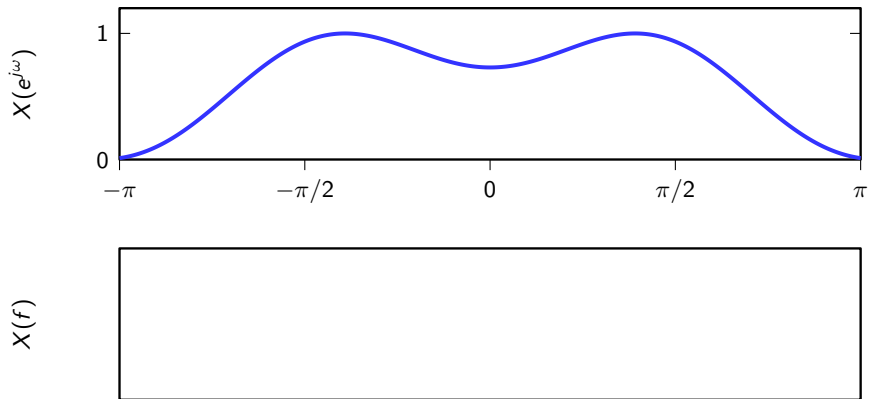
$$I(f) = \text{rect}(f)$$

$$X(f) = \frac{1}{F_s} \text{rect}\left(\frac{f}{F_s}\right) X(e^{j2\pi f/F_s})$$

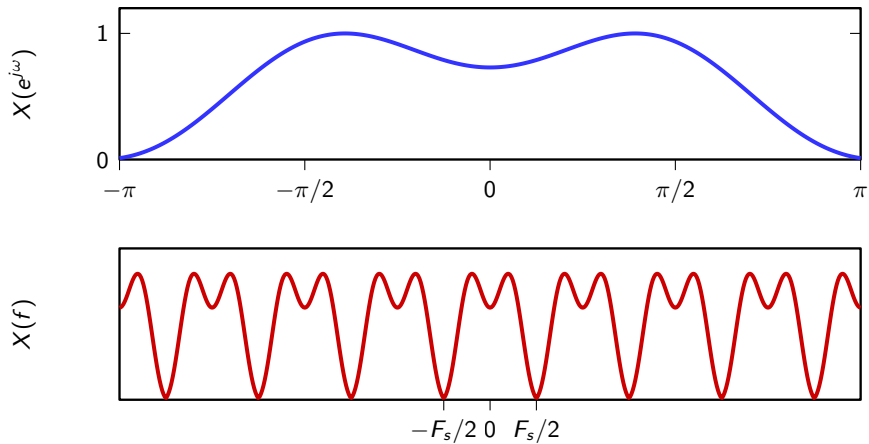
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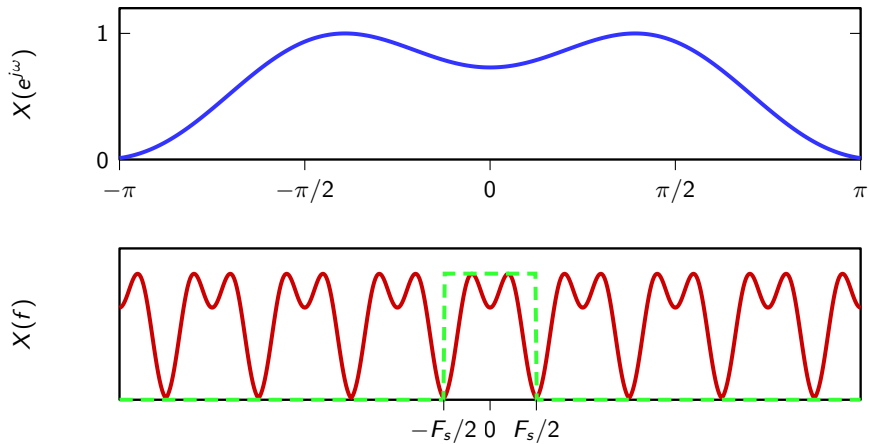
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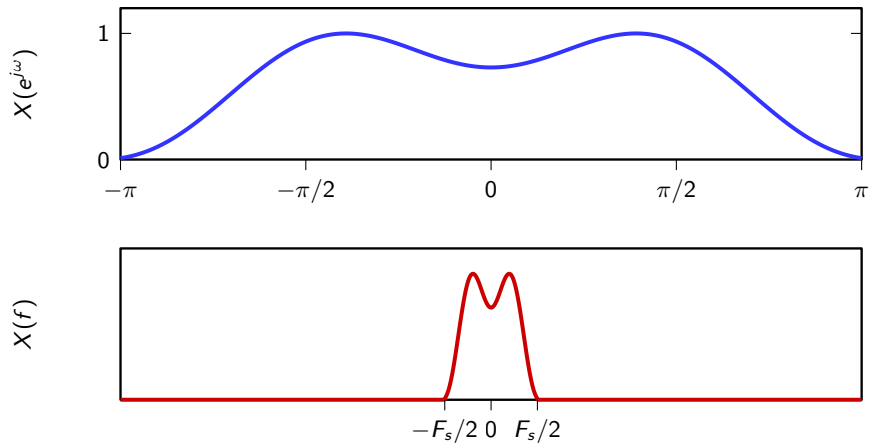
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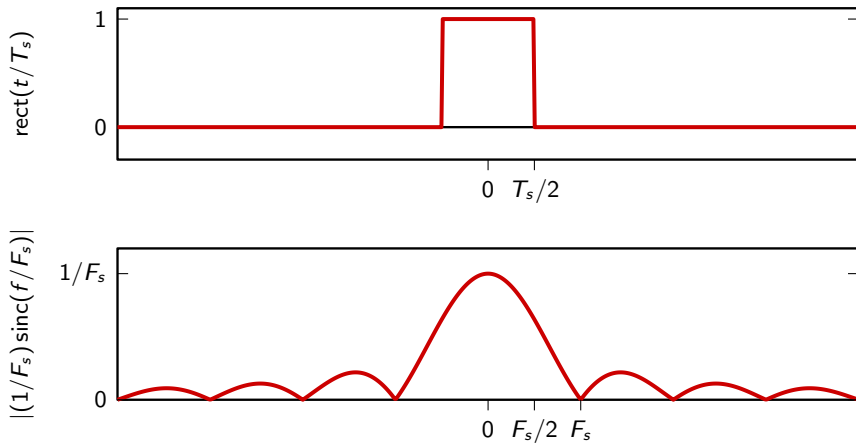
zero-order hold

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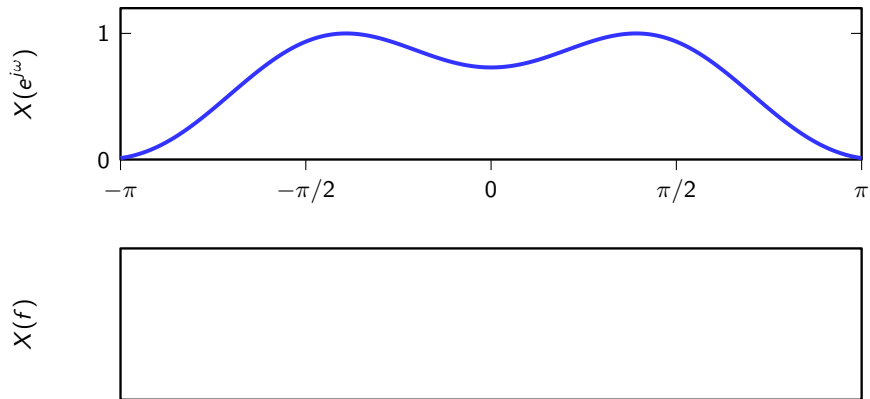
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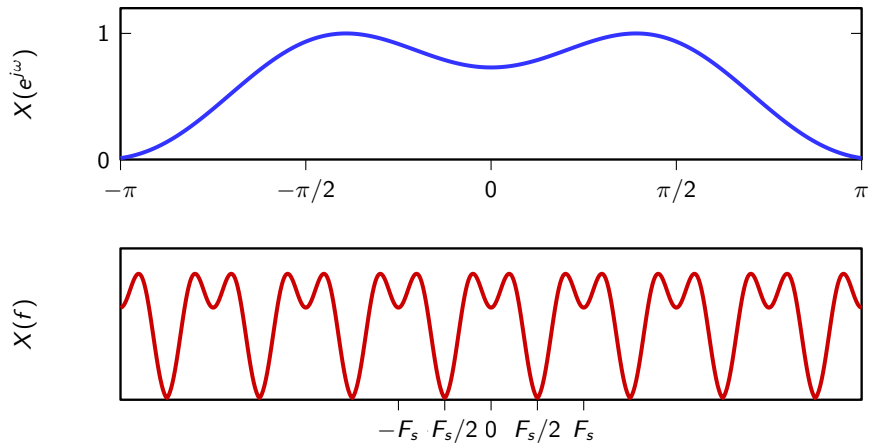
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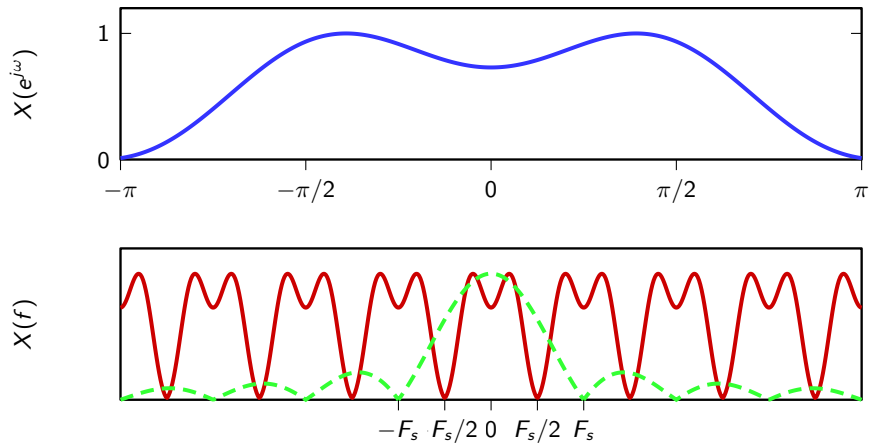
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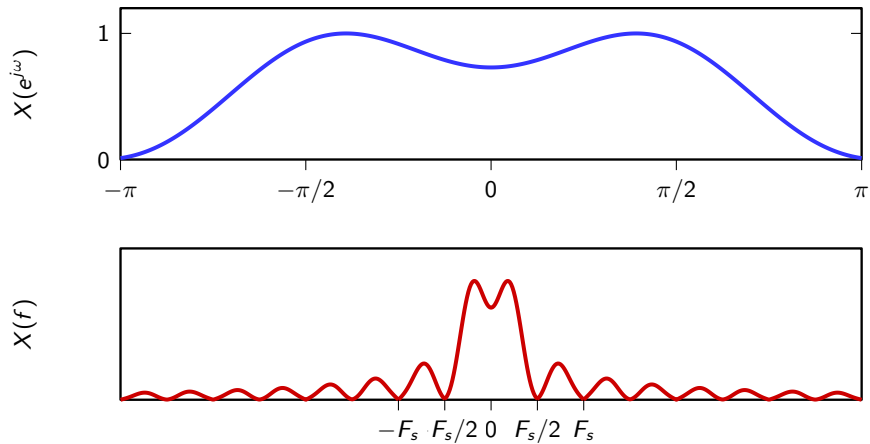
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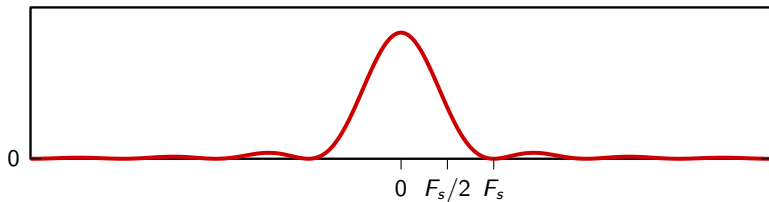
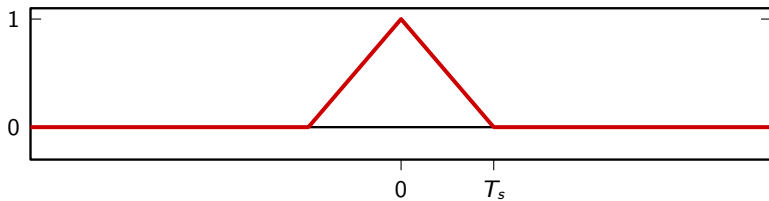
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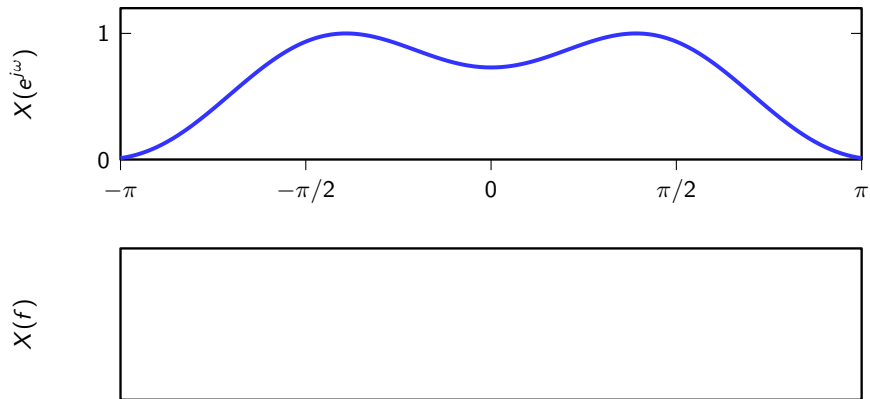
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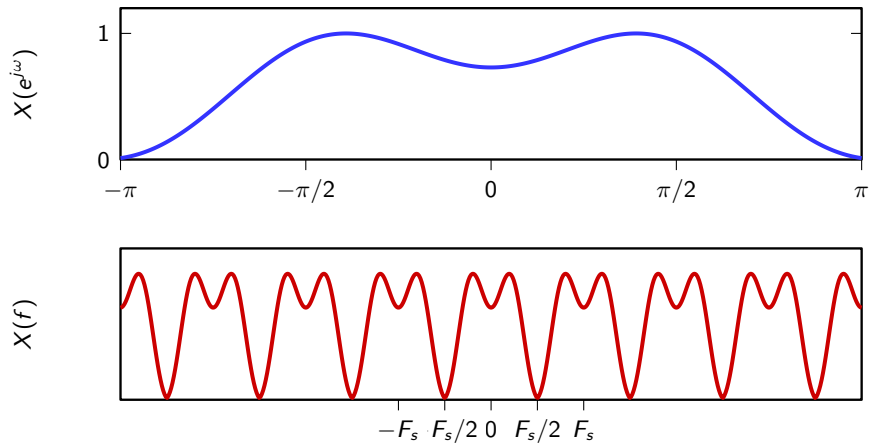
first-order interpolator



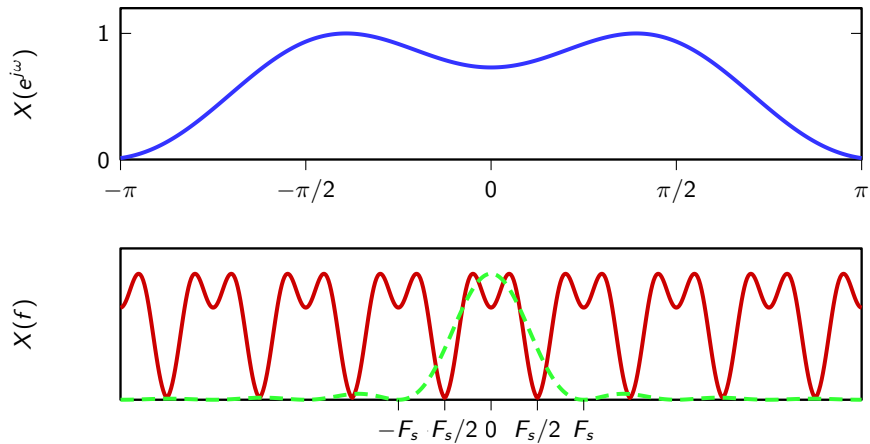
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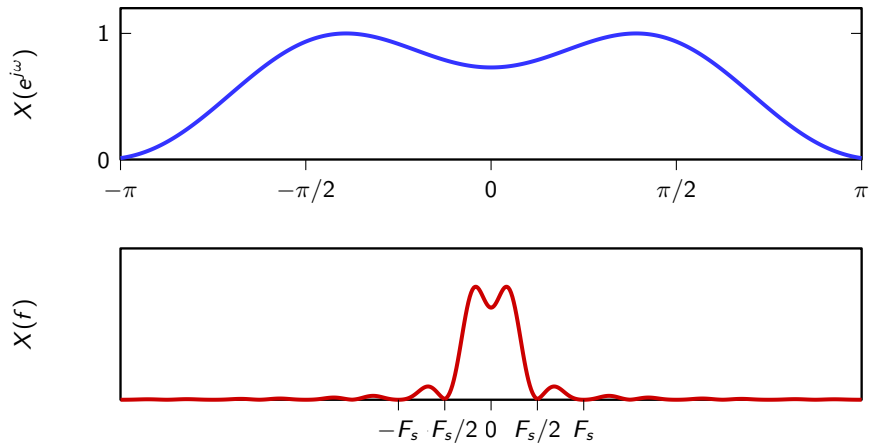
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Bandpass Sampling

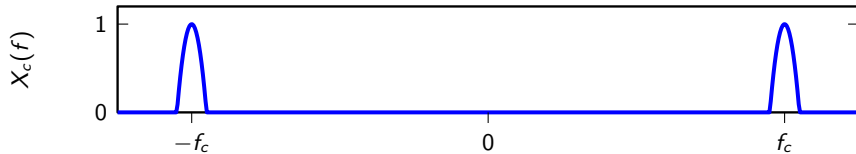
sampling theorem gives a *sufficient* condition

- ▶ in theory, $F_s > 2f_{\max}$
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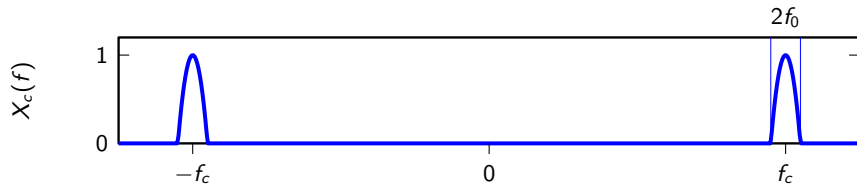
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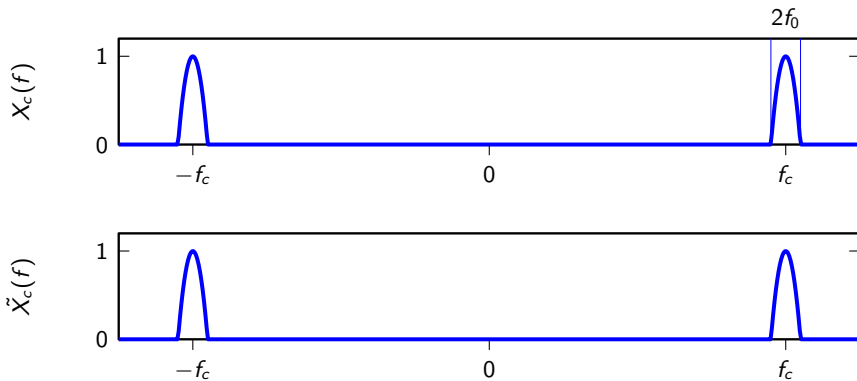
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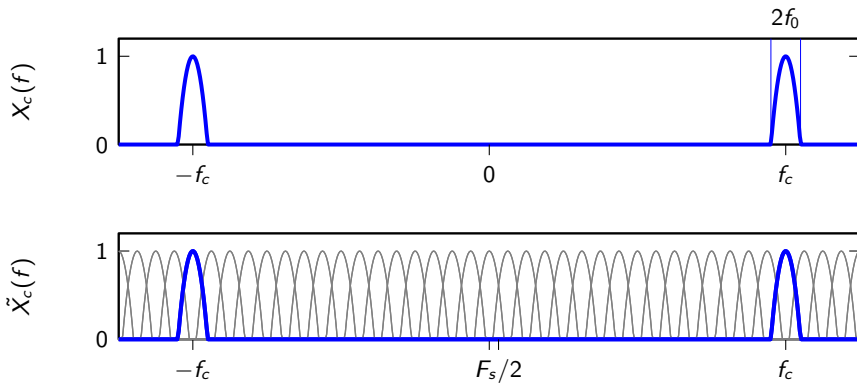
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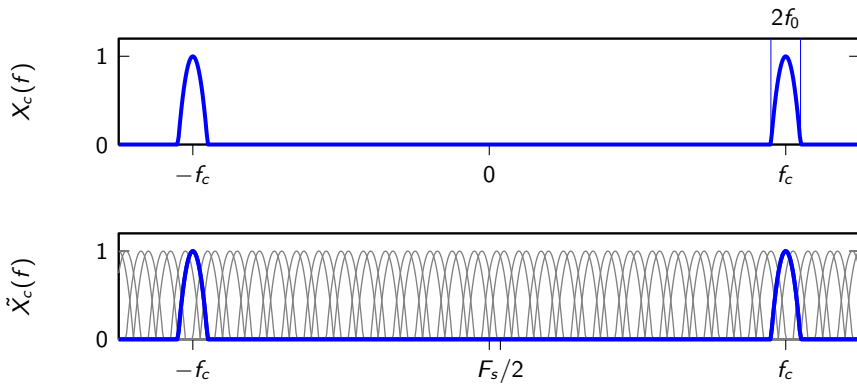
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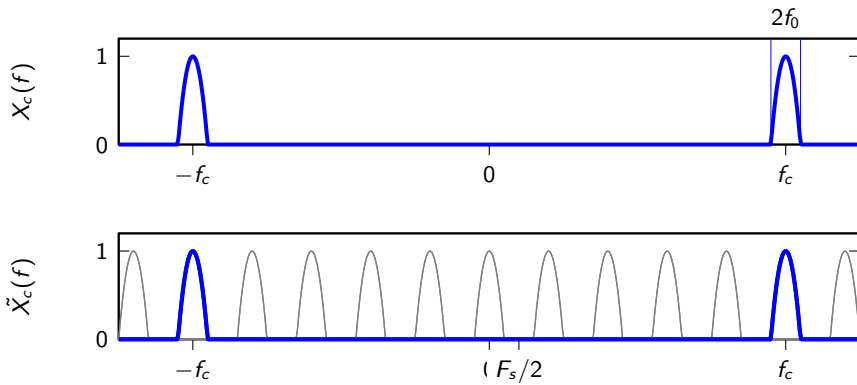
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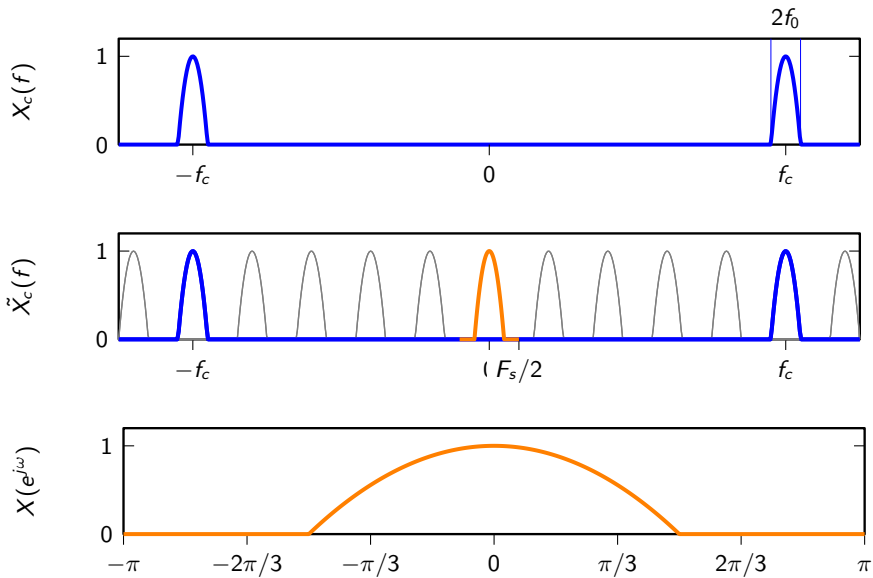
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Bandpass sampling conditions

- ▶ bandpass signal: $X(f) = 0$ for $|f - f_c| > f_0$
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Example: AM Channel

- ▶ AM radio band: 500kHz to 1.6MHz
- ▶ channel width is 9kHz, i.e. $f_0 = 4.5\text{kHz}$
- ▶ take a channel at $f_c = 1.5\text{MHz}$
- ▶ in theory: $F_s \geq 2 * 1,504,500\text{Hz}$, $T_s < 10^{-6}$ seconds!
- ▶ antialias: $F_s \geq 2f_0 \Rightarrow F_s \geq 9\text{kHz}$
- ▶ baseband: $kF_s/2 = 1500\text{kHz}$
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- ▶ antialias: $F_s \geq 2f_0 \Rightarrow F_s \geq 9\text{KHz}$
- ▶ baseband: $kF_s/2 = 1500\text{kHz}$
- ▶ pick $k = 300$
- ▶ $F_s = 10\text{KHz}$, $T_s = 10^{-4}$

Example: AM Channel

- ▶ AM radio band: 500kHz to 1.6MHz
- ▶ channel width is 9kHz, i.e. $f_0 = 4.5\text{KHz}$
- ▶ take a channel at $f_c = 1.5\text{MHz}$
- ▶ in theory: $F_s \geq 2 * 1,504,500\text{Hz}$, $T_s < 10^{-6}$ seconds!
- ▶ antialias: $F_s \geq 2f_0 \Rightarrow F_s \geq 9\text{KHz}$
- ▶ baseband: $kF_s/2 = 1500\text{kHz}$
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multirate signal processing

Overview

- ▶ why multirate?
- ▶ upsampling
- ▶ downsampling
- ▶ applications

Overview

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- ▶ upsampling
- ▶ downsampling
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Overview

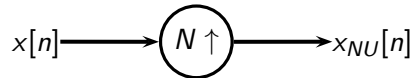
- ▶ why multirate?
- ▶ upsampling
- ▶ downsampling
- ▶ applications

Overview

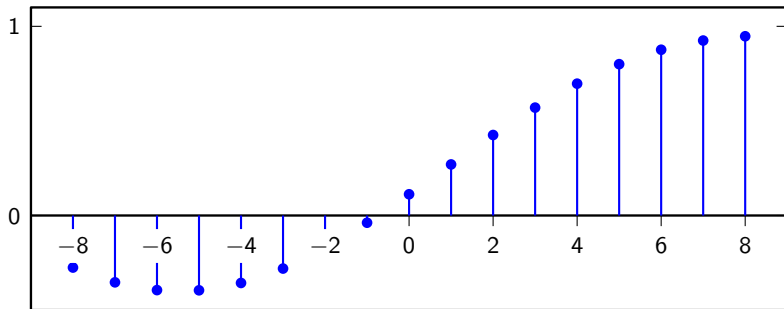
- ▶ why multirate?
- ▶ upsampling
- ▶ downsampling
- ▶ applications

Upsampling

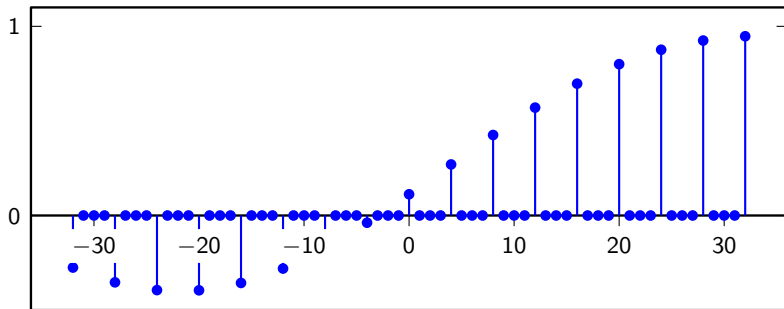
$$x_{NU}[n] = \begin{cases} x[k] & \text{for } n = kN, \quad k \in \mathbb{Z} \\ 0 & \text{otherwise.} \end{cases}$$



Example: upsampling by 4



Example: upsampling by 4



Spectral representation

$$\begin{aligned}X_{NU}(z) &= \sum_{k=-\infty}^{\infty} x_{NU}[k]z^{-k} \\&= \sum_{k=-\infty}^{\infty} x[k]z^{-Nk} \\&= X(z^N)\end{aligned}$$

$$X_{NU}(e^{j\omega}) = X(e^{j\omega N})$$

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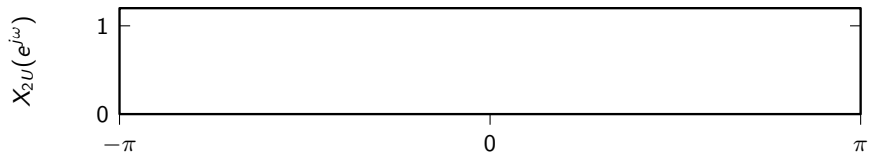
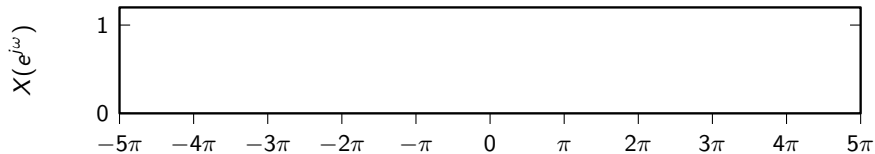
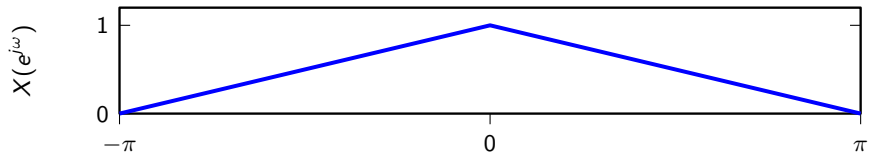
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Spectral representation

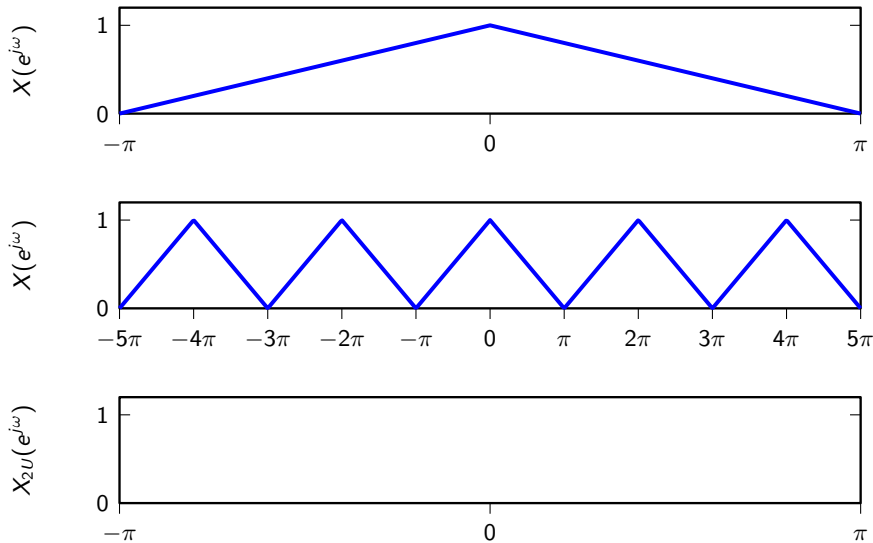
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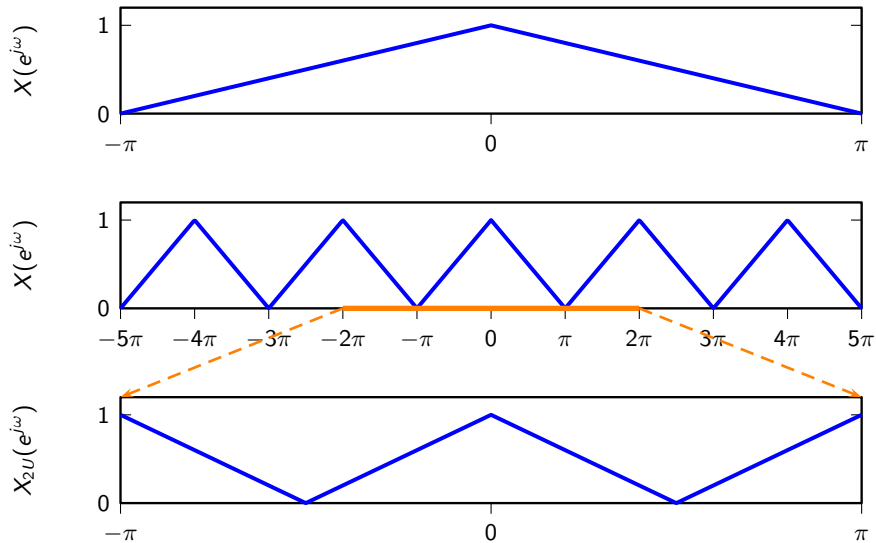
Upsampling by 2



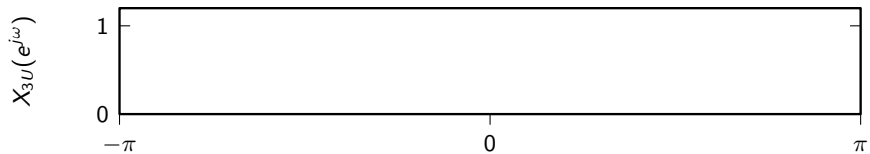
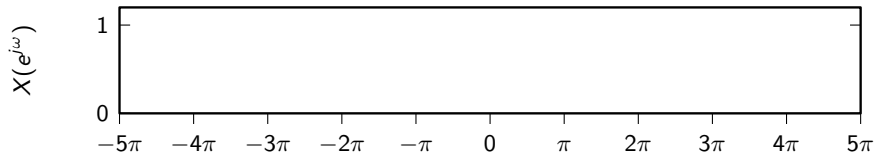
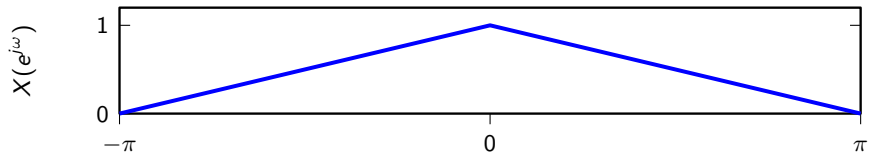
Upsampling by 2



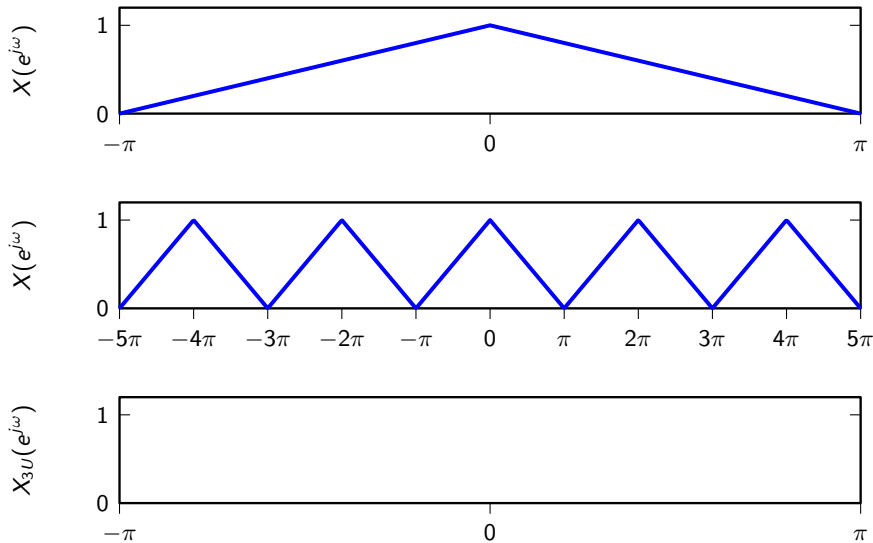
Upsampling by 2



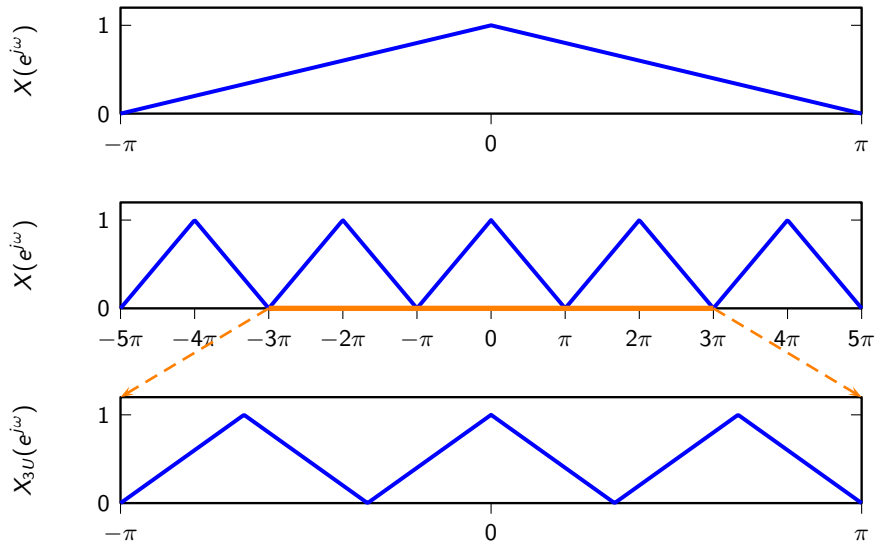
Upsampling by 3



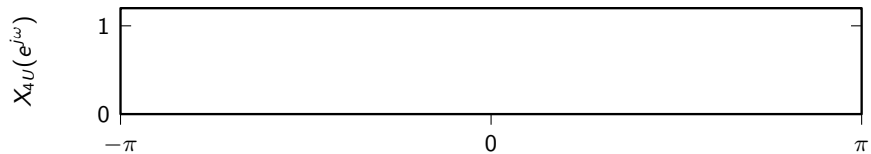
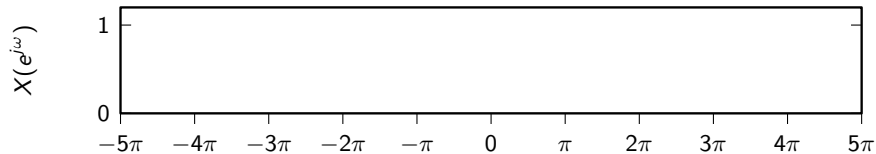
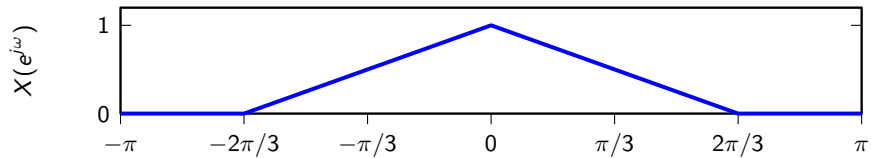
Upsampling by 3



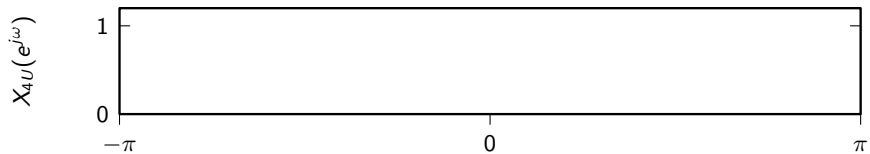
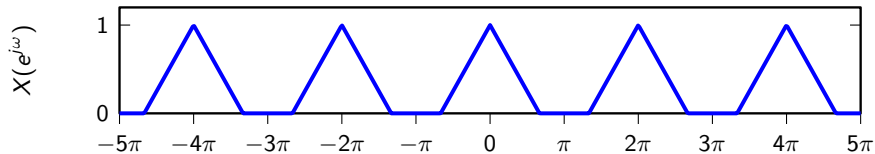
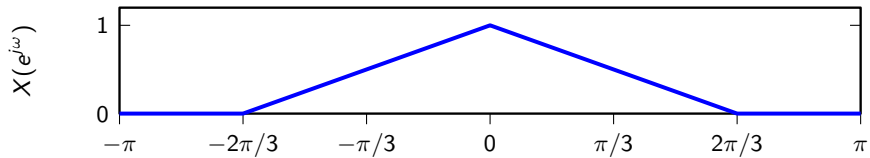
Upsampling by 3



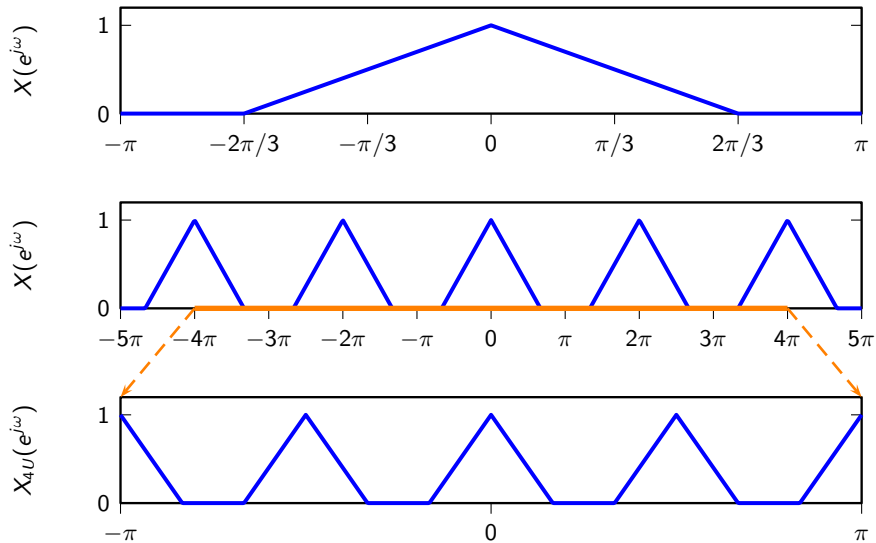
Upsampling by 4



Upsampling by 4



Upsampling by 4



Upsampling: what we don't like

- ▶ in the time domain: zeros between nonzero samples are not “natural”
- ▶ in the frequency domain: extra replicas of the spectrum; can we get rid of them?

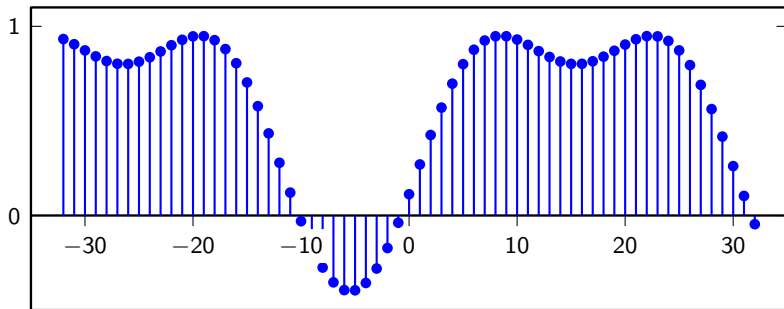
the two problems are the same!

Upsampling: what we don't like

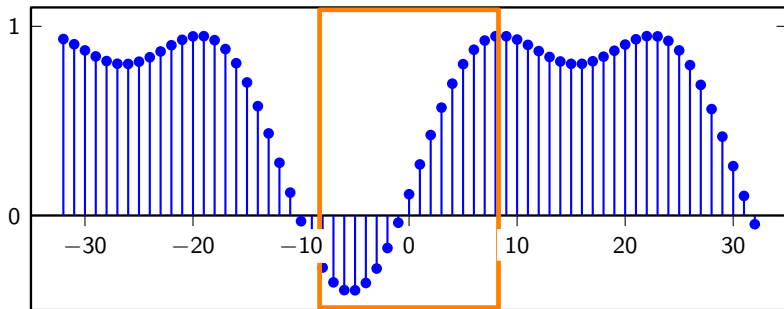
- ▶ in the time domain: zeros between nonzero samples are not “natural”
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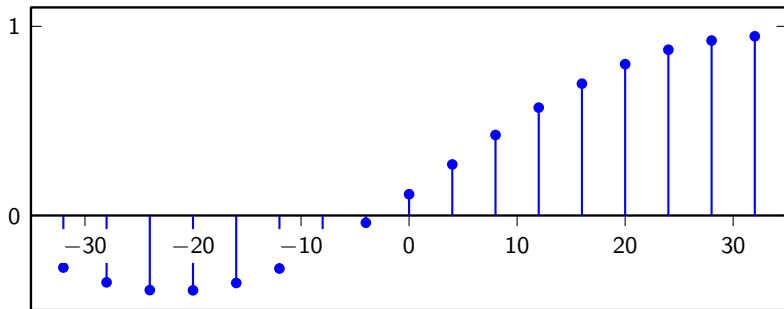
Upsampling in the time domain, revisited



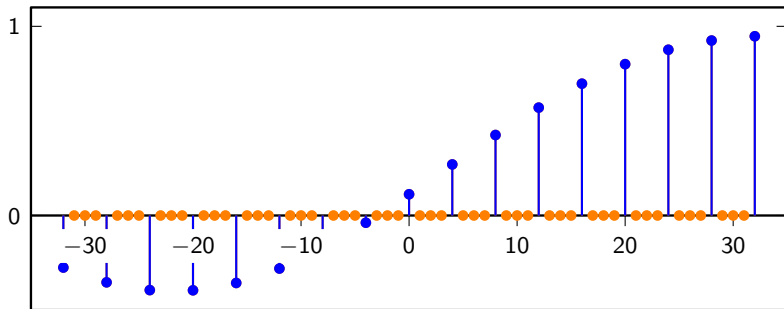
Upsampling in the time domain, revisited



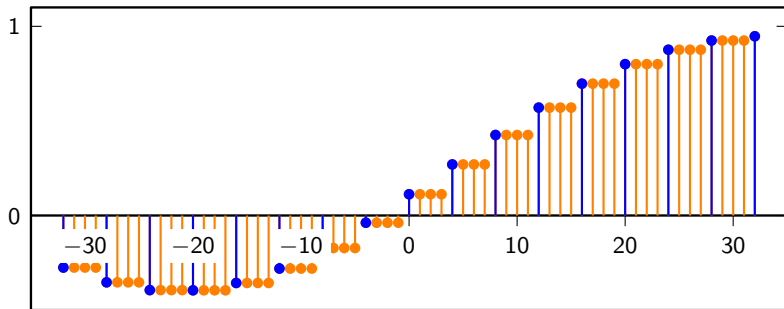
Upsampling in the time domain, revisited



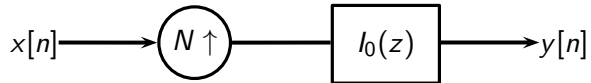
Upsampling in the time domain, revisited



Upsampling in the time domain, revisited

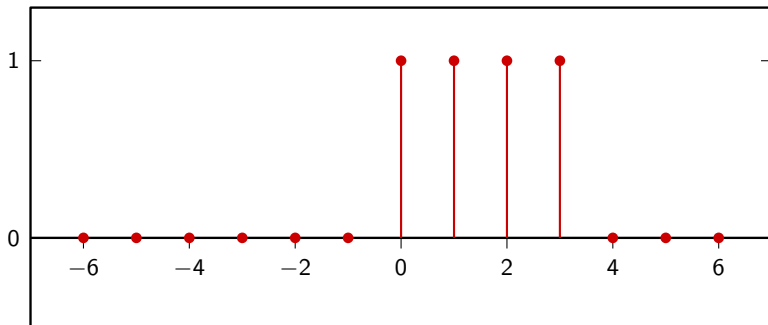


Zero-order interpolator



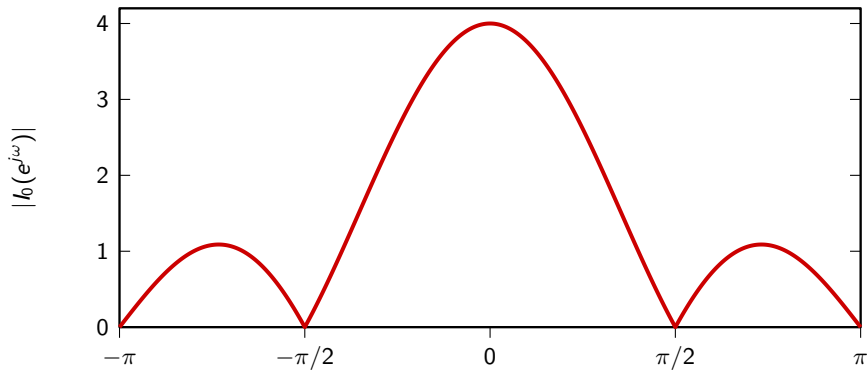
Zero-order interpolator for 4-upsampling

$$i_0[n] = u[n] - u[n - 4]$$

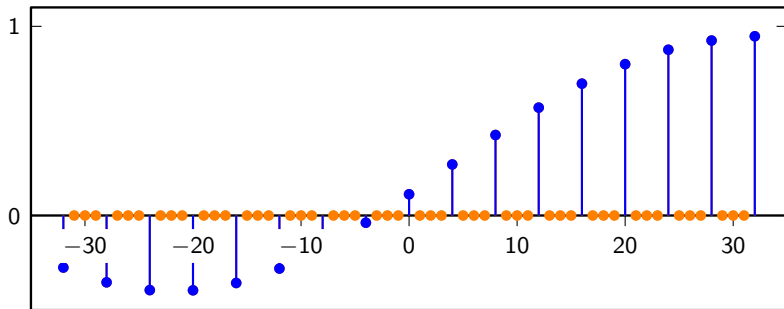


Zero-order interpolator for 4-upsampling

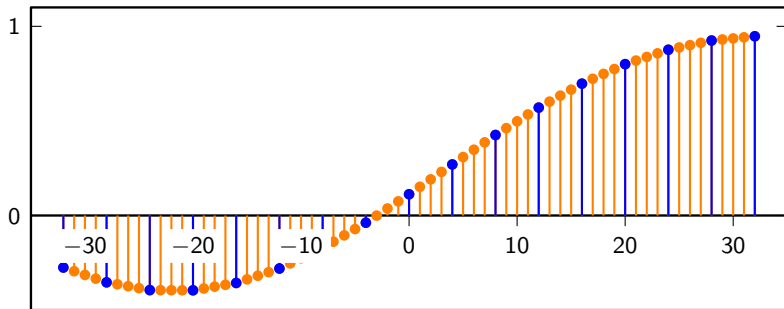
$$|I_0(e^{j\omega})| = \left| \frac{\sin(\frac{\omega}{2}N)}{\sin(\frac{\omega}{2})} \right| \quad N = 4$$



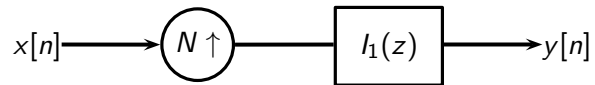
Upsampling in the time domain, revisited



Upsampling in the time domain, revisited

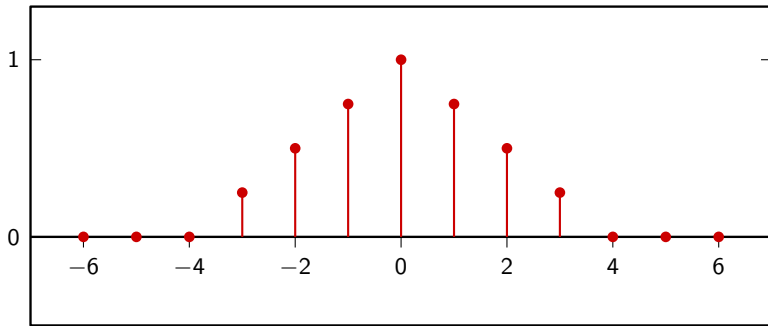


first-order interpolator



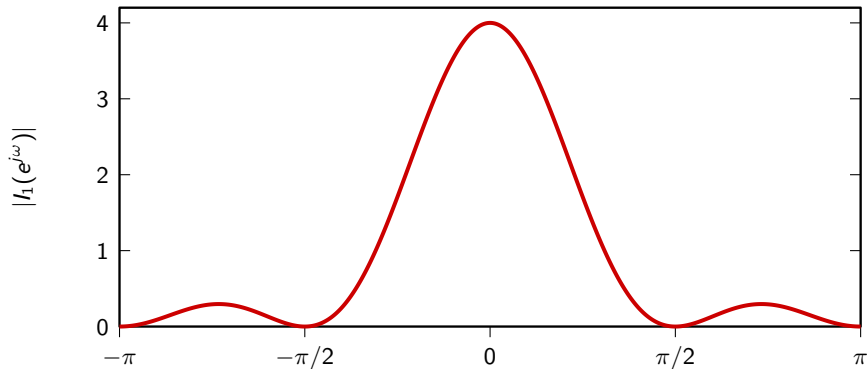
first-order interpolator for 4-upsampling

$$i_1[n] = (i_0[n] * i_0[n])/N$$

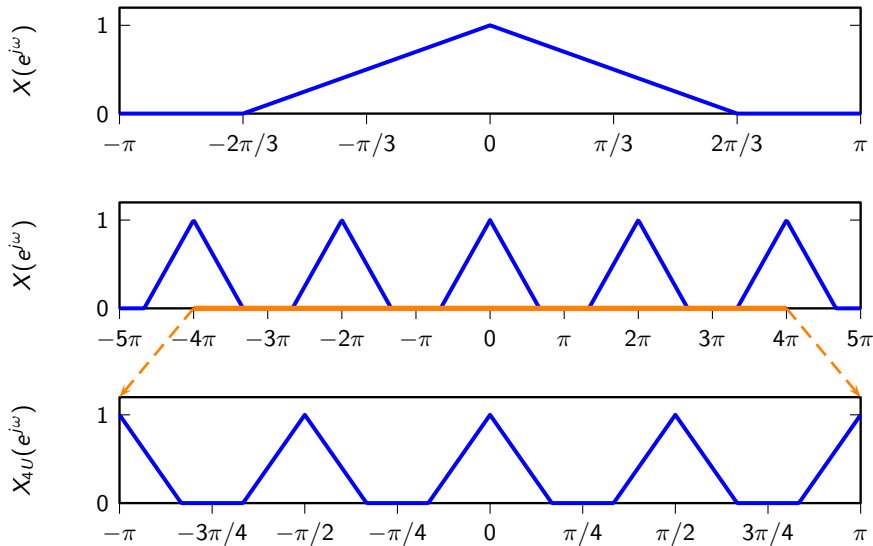


first-order interpolator for 4-upsampling

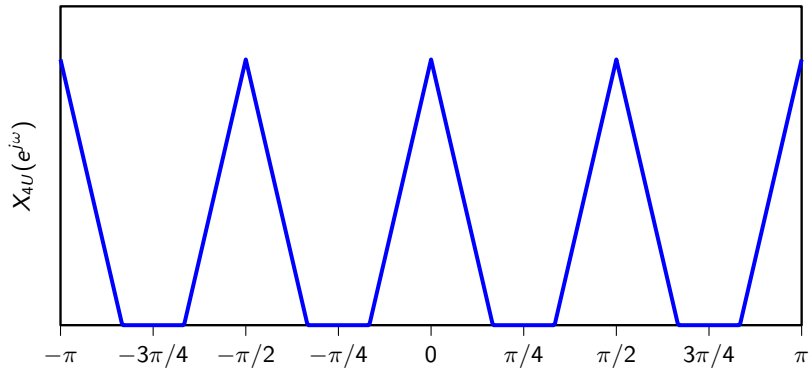
$$|I_1(e^{j\omega})| = |I_0(e^{j\omega})|^2 / N \quad N = 4$$



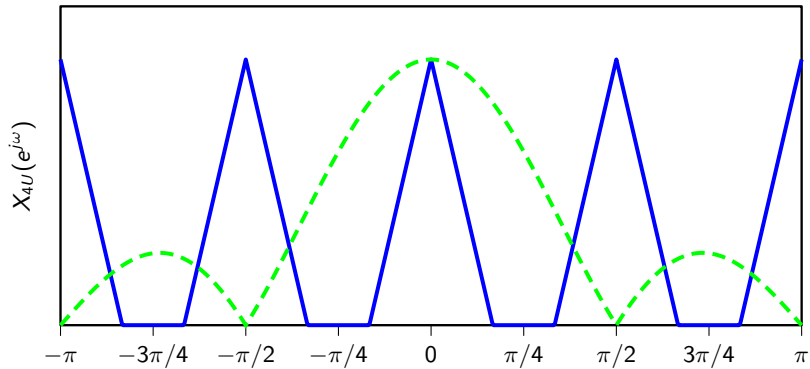
in the frequency domain...



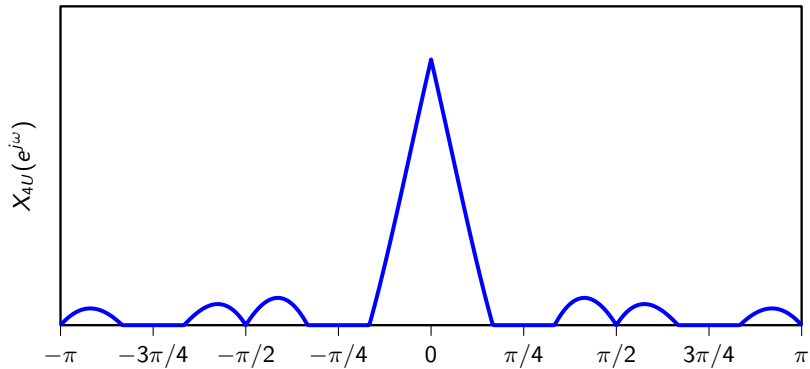
in the frequency domain...



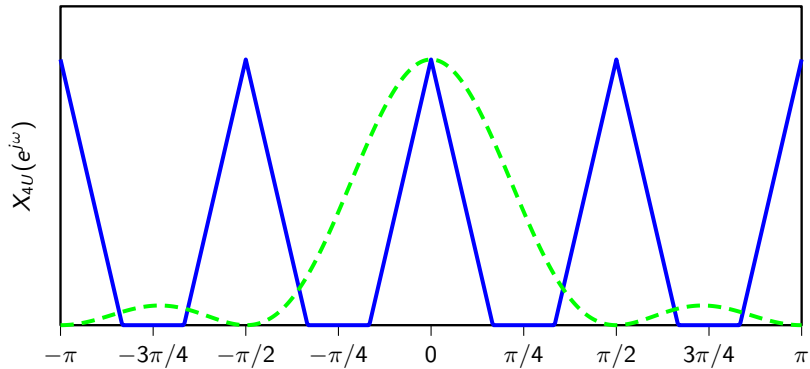
in the frequency domain...



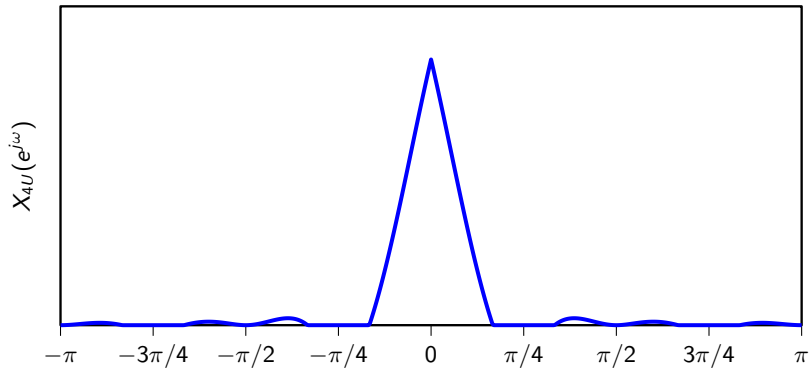
in the frequency domain...



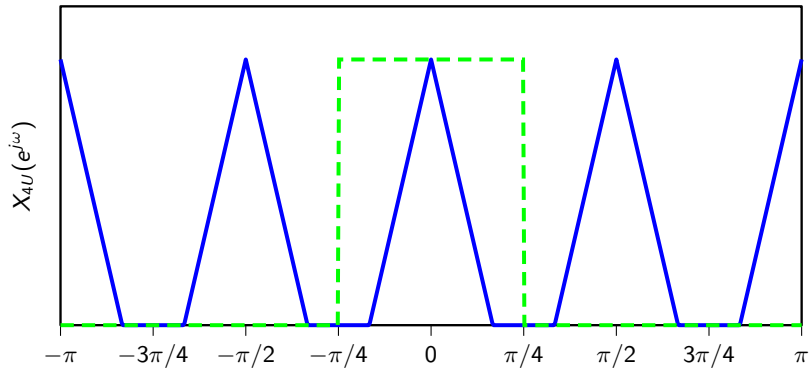
in the frequency domain...



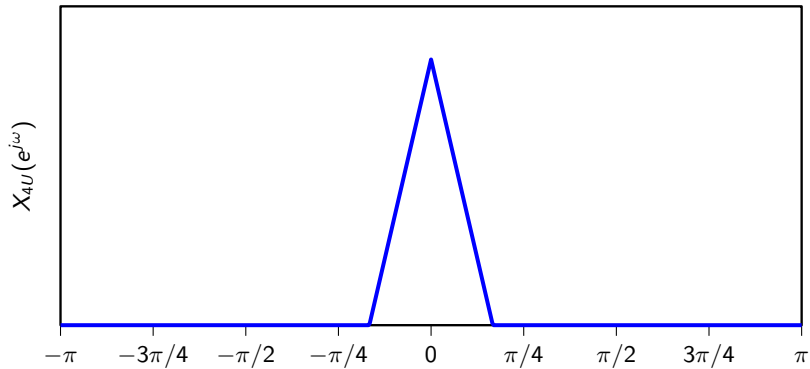
in the frequency domain...



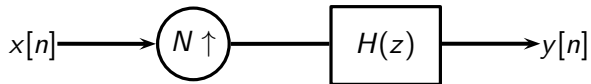
in the frequency domain...



in the frequency domain...



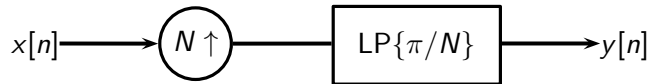
ideal digital interpolator



$$H(e^{j\omega}) = \text{rect}(\omega N / 2\pi)$$

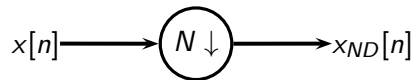
$$h[n] = (1/N) \text{sinc}(n/N)$$

ideal digital interpolator

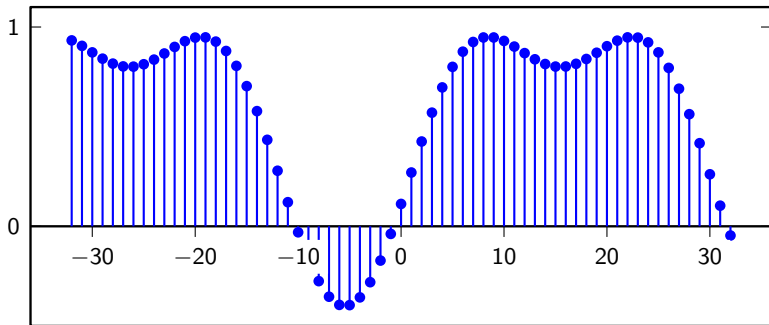


Downsampling

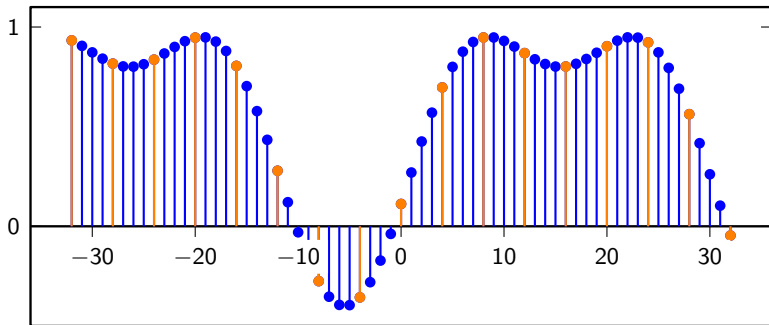
$$x_{ND}[n] = x[nN]$$



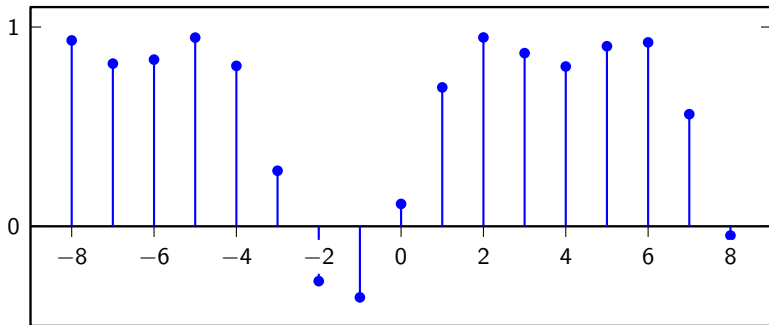
Example: downsampling by 4



Example: downsampling by 4



Example: downsampling by 4



Spectral representation

$$X_{ND}(z) = \sum_{k=-\infty}^{\infty} x[kN]z^{-k} = ?$$

if we can compute

$$A(z) = \sum_{k=-\infty}^{\infty} x[kN]z^{-kN}$$

then

$$X_{ND}(z) = A(z^{1/N})$$

Spectral representation

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Spectral representation

$$\begin{aligned} A(z) &= \sum_{k=-\infty}^{\infty} x[kN]z^{-kN} \\ &= \sum_{k=-\infty}^{\infty} \xi[k]x[k]z^{-k} \end{aligned}$$

$$\xi[n] = \begin{cases} 1 & \text{for } n = kN \\ 0 & \text{otherwise} \end{cases}$$

Spectral representation

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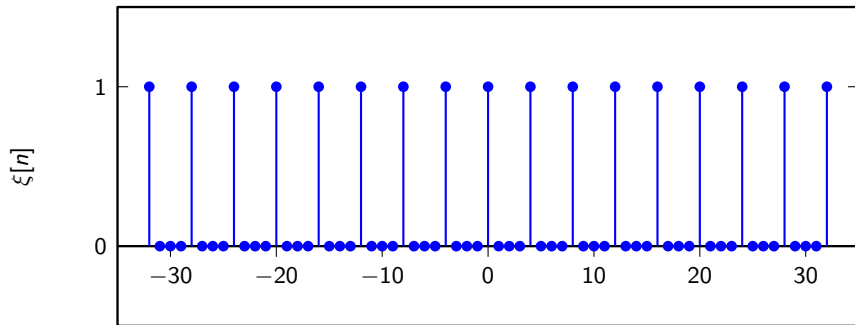
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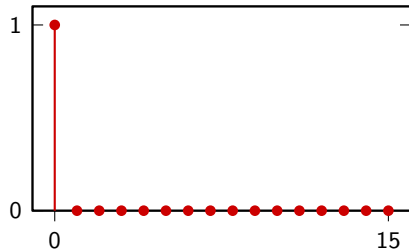
$\xi[n]$ for $N = 4$



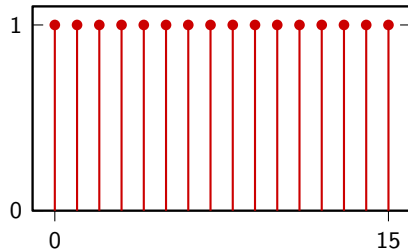
Blast from the past: DFT of $x[n] = \delta[n]$, $x[n] \in \mathbb{C}^N$

$$X[k] = \sum_{n=0}^{N-1} \delta[n] e^{-j\frac{2\pi}{N}nk} = 1$$

$x[n]$

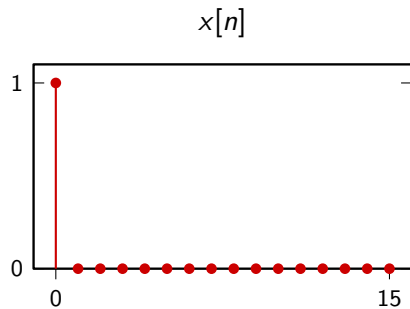
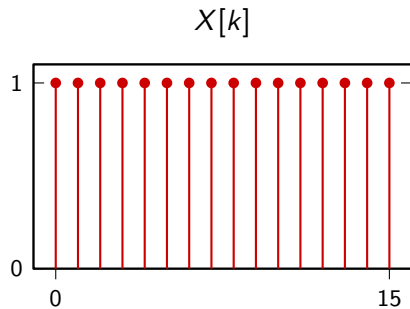


$X[k]$



From the other side:

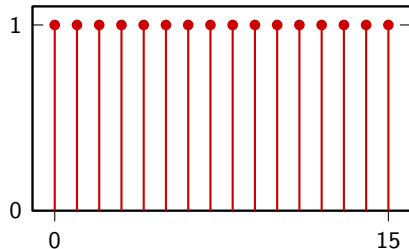
$$\text{IDFT} \{1\} = \frac{1}{N} \sum_{m=0}^{N-1} e^{j\frac{2\pi}{N}mn} = \delta[n]$$



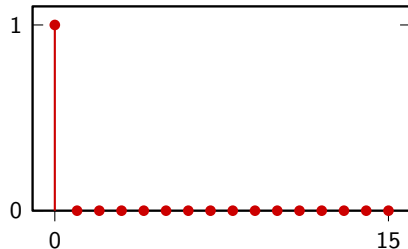
From the other side:

$$\text{IDFT}\{1\} = \frac{1}{N} \sum_{m=0}^{N-1} e^{j\frac{2\pi}{N}mn} = \begin{cases} 1 & \text{for } n = 0 \\ 0 & \text{otherwise} \end{cases} \quad n = 0, \dots, N-1$$

$X[k]$



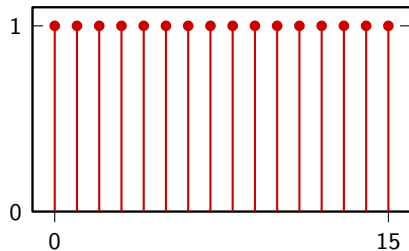
$x[n]$



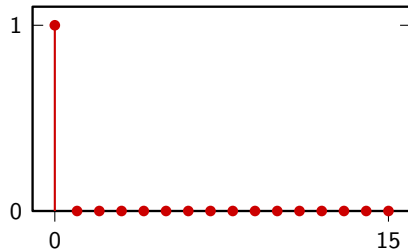
From the other side:

$$\frac{1}{N} \sum_{m=0}^{N-1} e^{j\frac{2\pi}{N}mn} = \begin{cases} 1 & \text{for } n \bmod N = 0 \\ 0 & \text{otherwise} \end{cases}$$

$\tilde{X}[k]$



$\tilde{x}[n]$



Spectral representation

$$\xi[n] = \frac{1}{N} \sum_{m=0}^{N-1} e^{j\frac{2\pi}{N}mn}$$

$$\begin{aligned} A(z) &= \sum_{k=-\infty}^{\infty} \xi[k]x[k]z^{-k} \\ &= \frac{1}{N} \sum_{m=0}^{N-1} \sum_{k=-\infty}^{\infty} x[k]e^{j\frac{2\pi}{N}mk}z^{-k} \\ &= \frac{1}{N} \sum_{m=0}^{N-1} X(e^{-j\frac{2\pi}{N}m}z) \end{aligned}$$

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Spectral representation

$$A(e^{j\omega}) = \frac{1}{N} \sum_{m=0}^{N-1} X(e^{j(\omega - \frac{2\pi}{N}m)})$$

Spectral representation

$$X_{ND}(z) = A(z^{1/N}) = \frac{1}{N} \sum_{m=0}^{N-1} X(e^{-j\frac{2\pi}{N}m} z^{\frac{1}{N}})$$

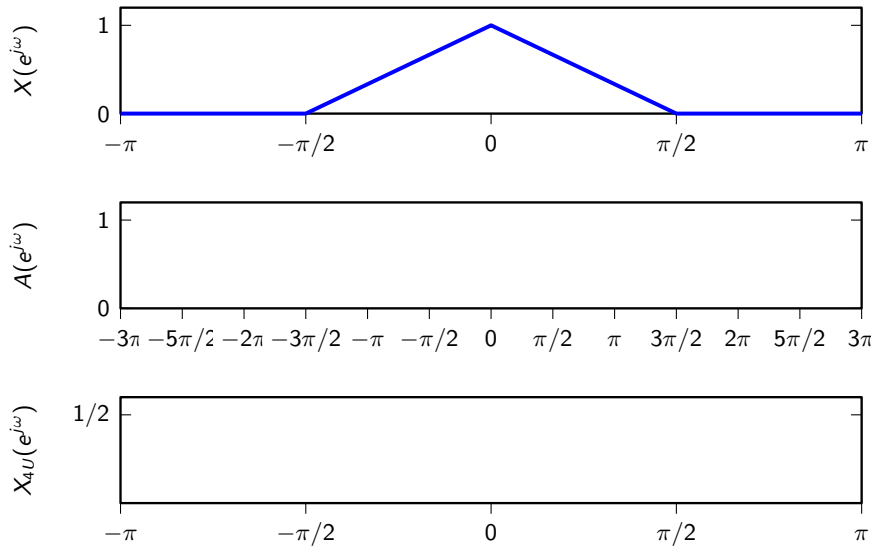
$$X_{ND}(e^{j\omega}) = \frac{1}{N} \sum_{m=0}^{N-1} X(e^{j(\frac{\omega - 2\pi m}{N})})$$

Spectral representation

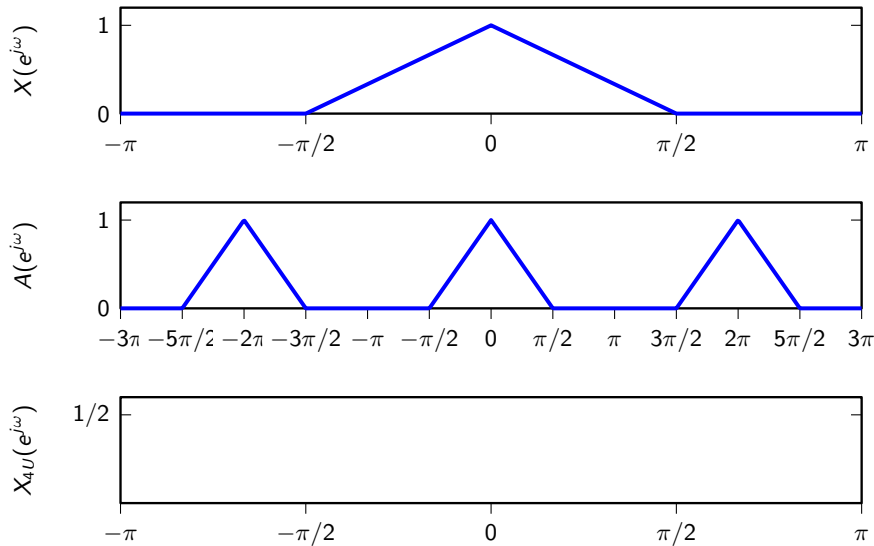
$$X_{ND}(z) = A(z^{1/N}) = \frac{1}{N} \sum_{m=0}^{N-1} X(e^{-j\frac{2\pi}{N}m} z^{\frac{1}{N}})$$

$$X_{ND}(e^{j\omega}) = \frac{1}{N} \sum_{m=0}^{N-1} X(e^{j(\frac{\omega - 2\pi m}{N})})$$

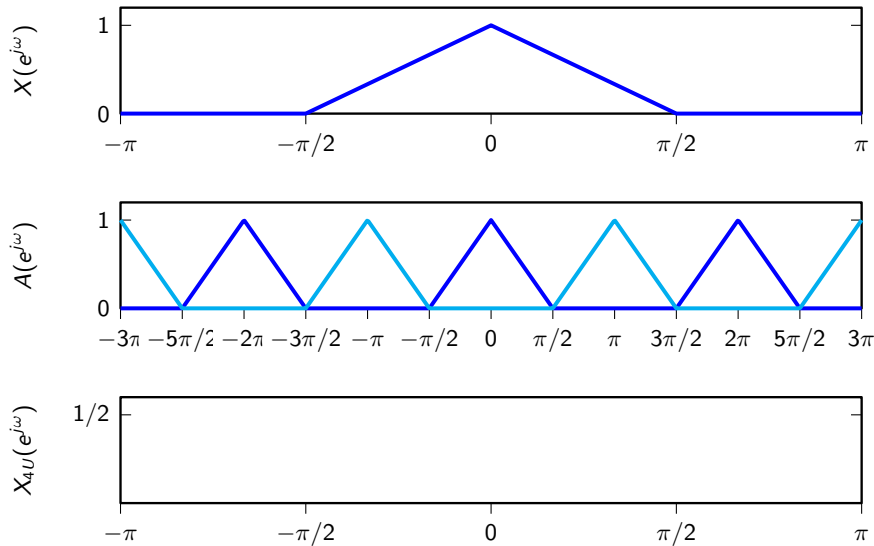
Downsampling by 2



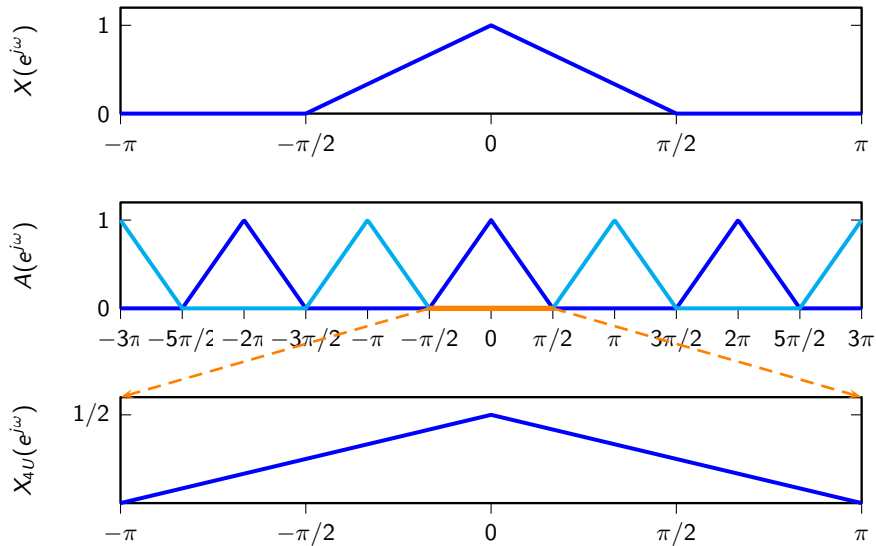
Downsampling by 2



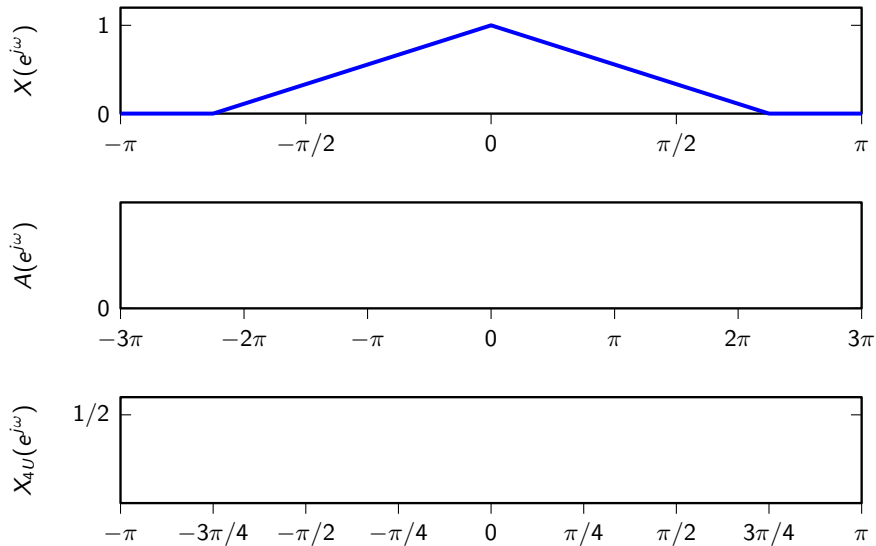
Downsampling by 2



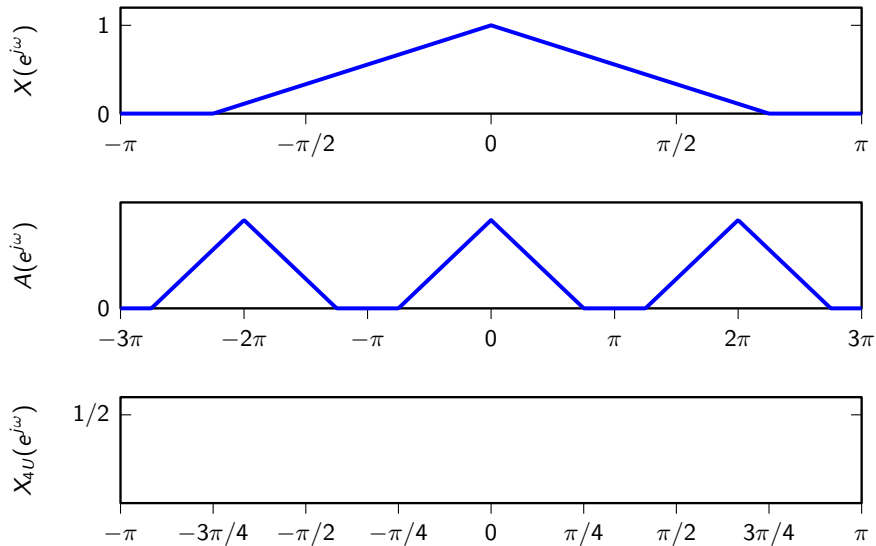
Downsampling by 2



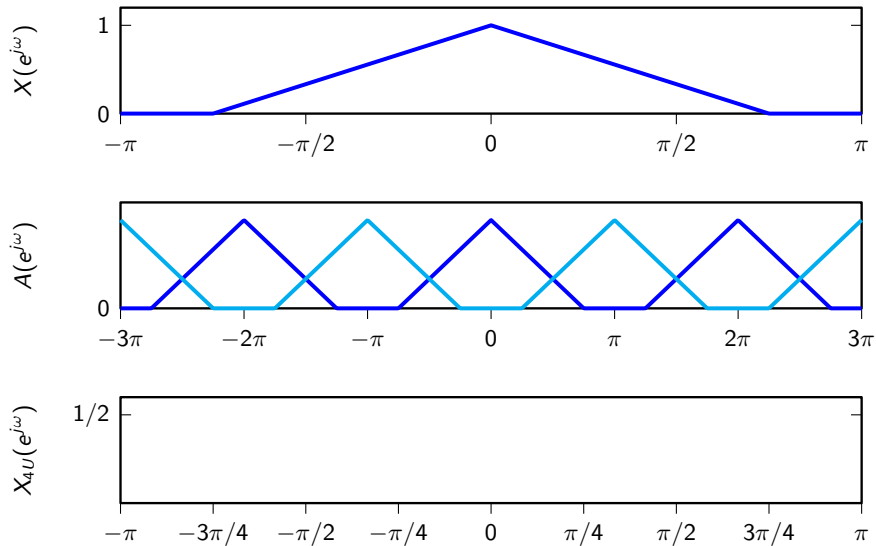
Downsampling by 2 with aliasing



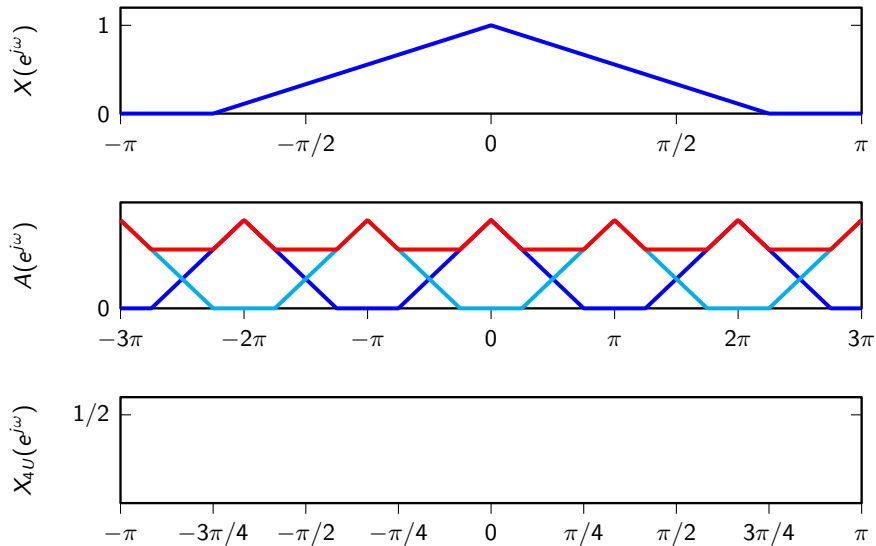
Downsampling by 2 with aliasing



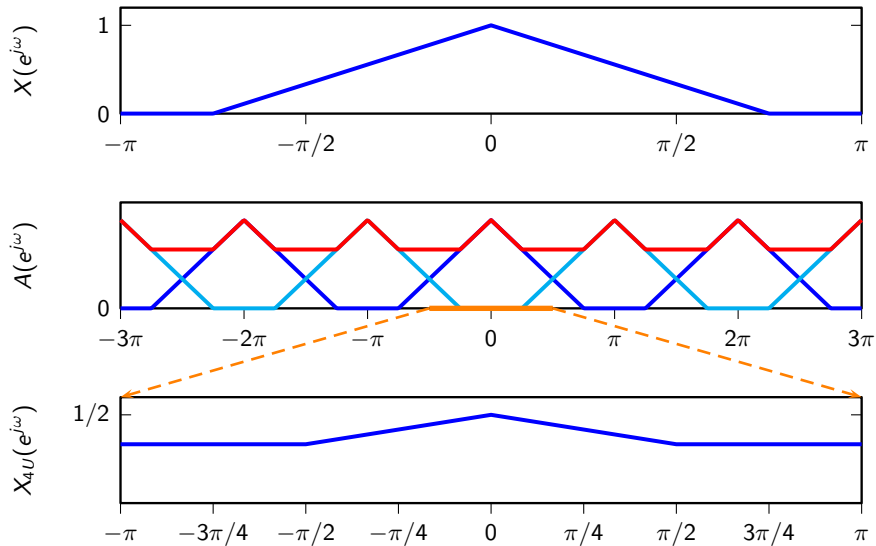
Downsampling by 2 with aliasing



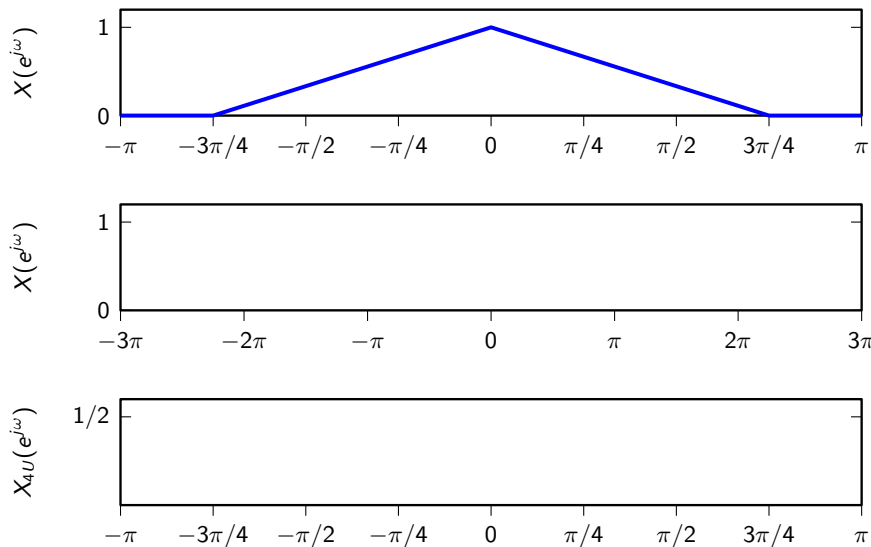
Downsampling by 2 with aliasing



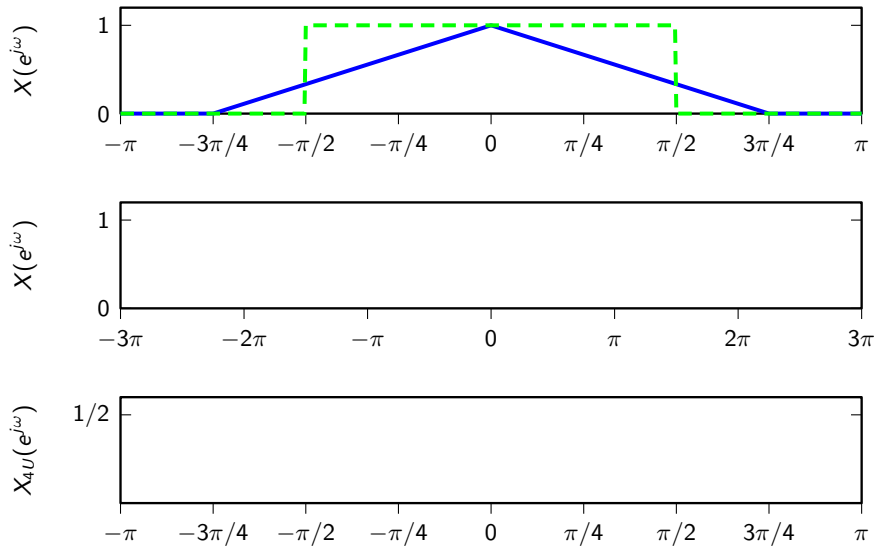
Downsampling by 2 with aliasing



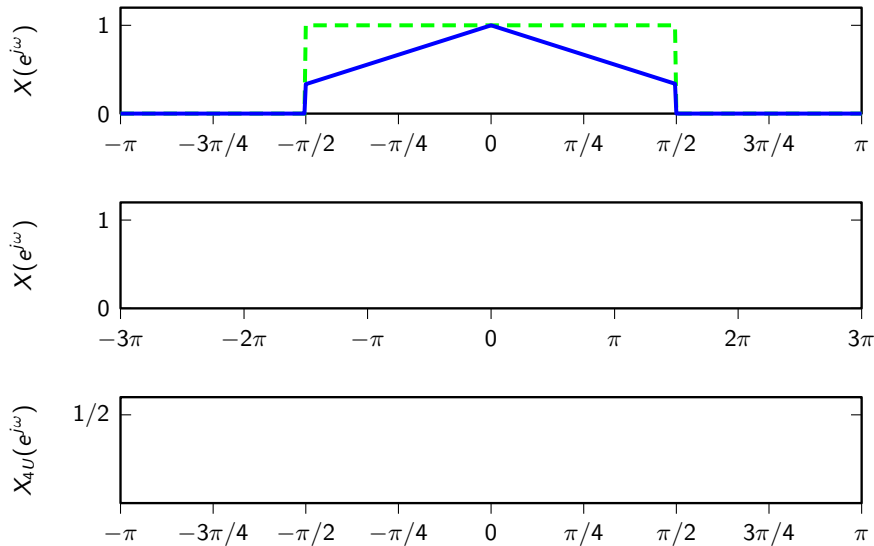
Downsampling by 2 with antialiasing filter



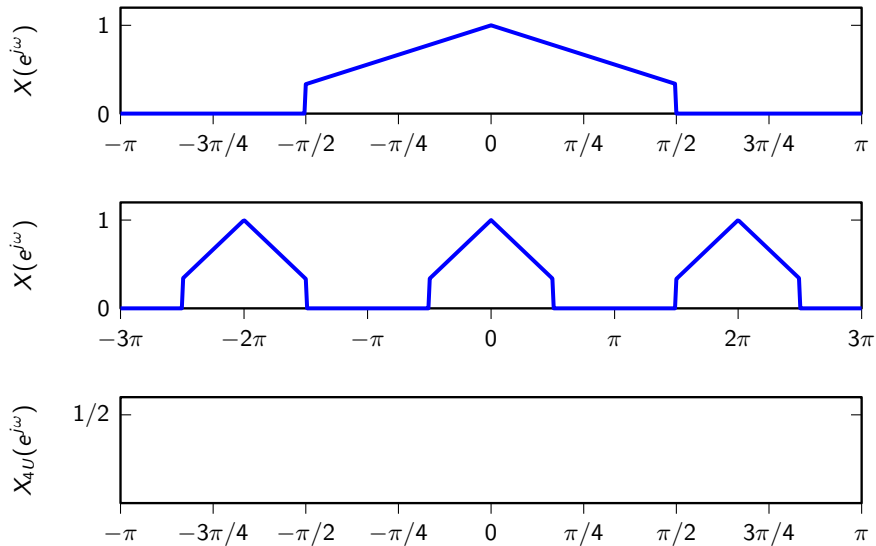
Downsampling by 2 with antialiasing filter



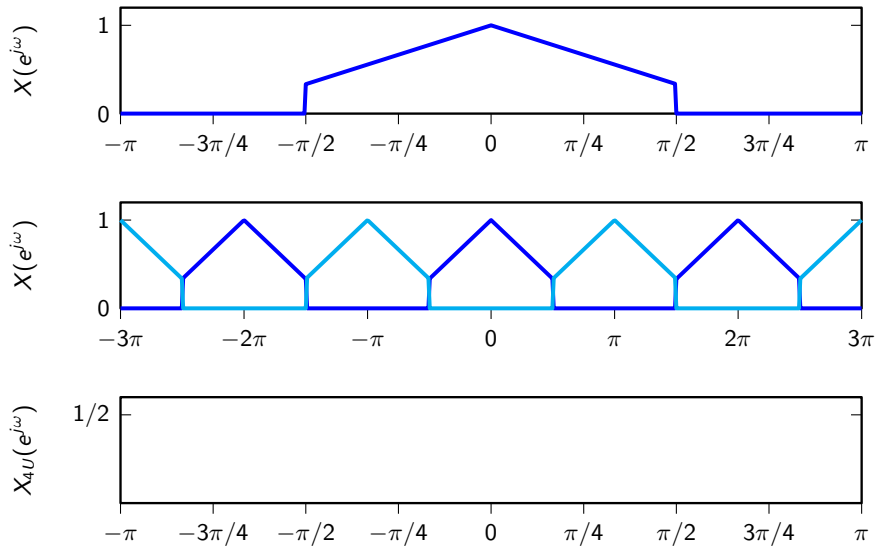
Downsampling by 2 with antialiasing filter



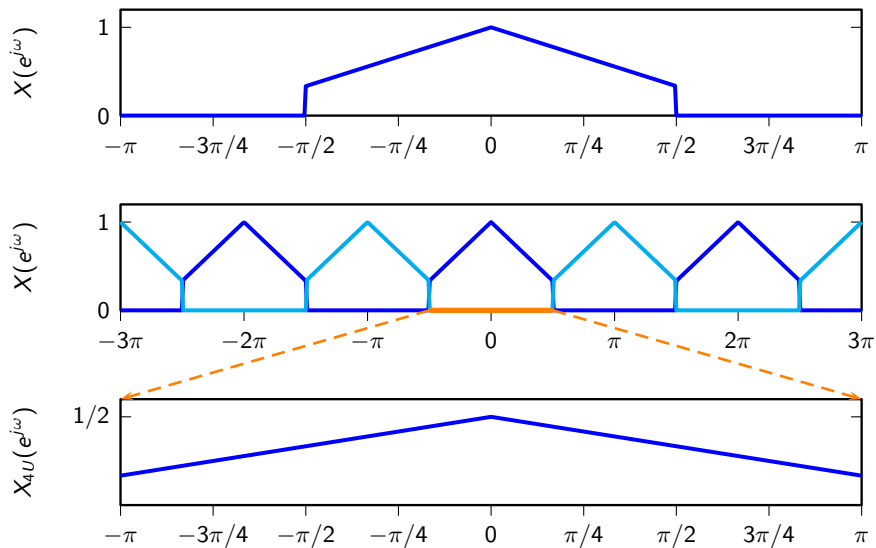
Downsampling by 2 with antialiasing filter



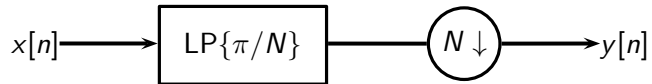
Downsampling by 2 with antialiasing filter



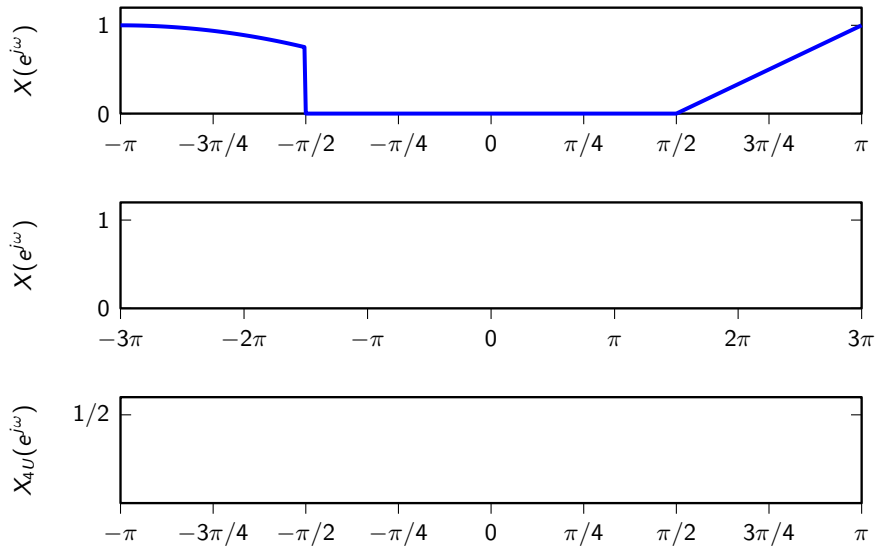
Downsampling by 2 with antialiasing filter



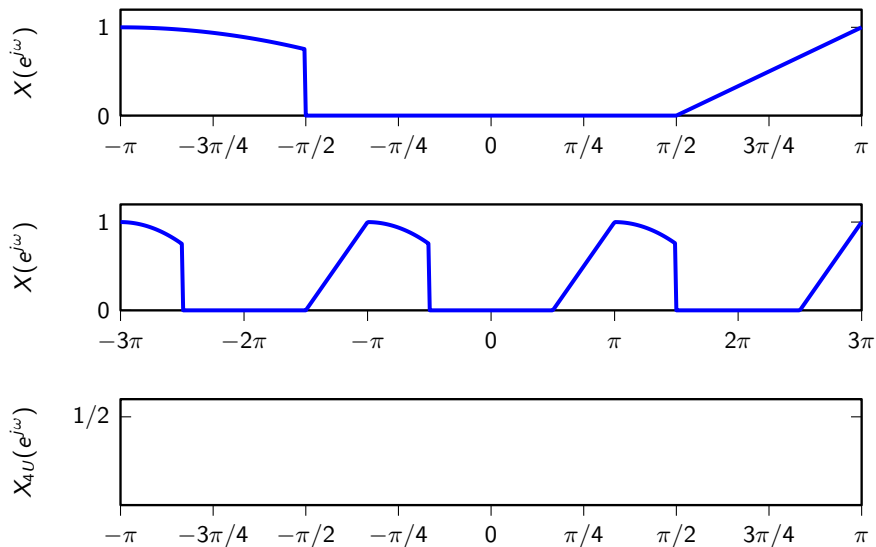
Downsampling



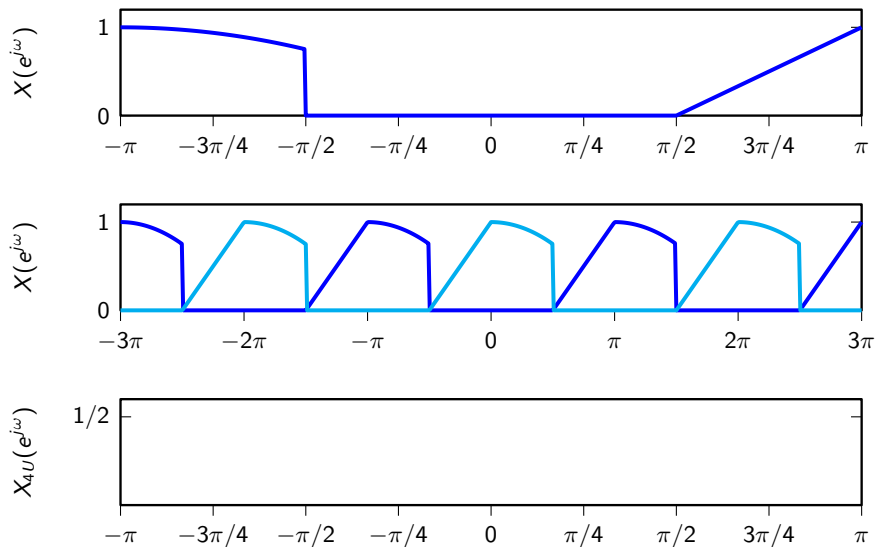
Downsampling by 2, careful with highpass signals



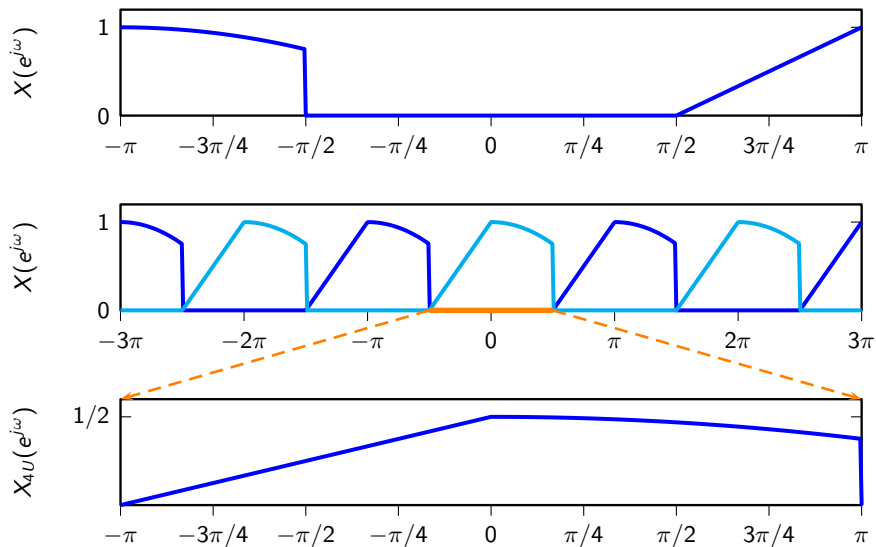
Downsampling by 2, careful with highpass signals



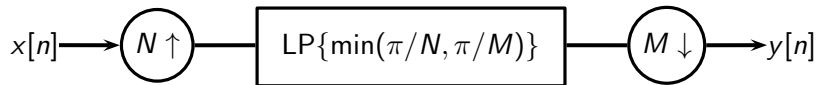
Downsampling by 2, careful with highpass signals



Downsampling by 2, careful with highpass signals



Rational Sampling Rate Change

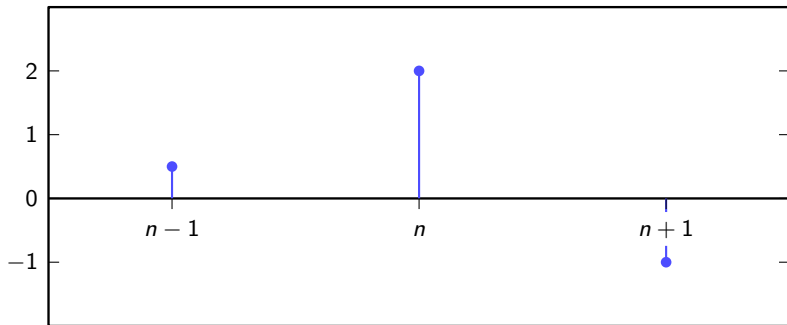


Rational Sampling Rate Change

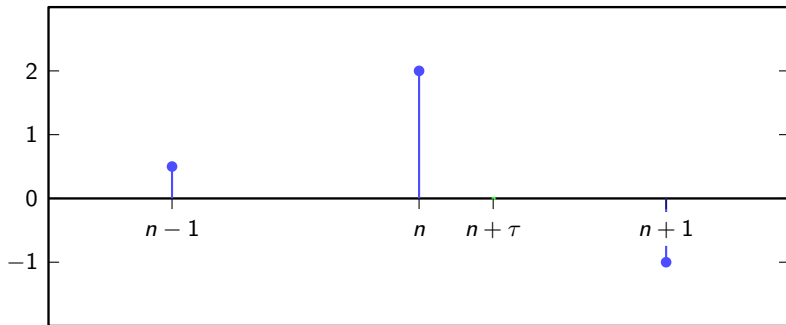
Example CD to DVD:

- ▶ CD: $F_s = 44100\text{Hz}$
- ▶ DVD: $F_s = 48000\text{Hz}$
- ▶ $\frac{N}{M} = \frac{160}{147}$
- ▶ in practice, we use time-varying local interpolation

Subsample Interpolation



Subsample Interpolation



Subsample Interpolation

► we want to compute $x(n + \tau)$, with $|\tau| < 1/2$

► local Lagrange approximation around n

$$x_L(n; t) = \sum_{k=-N}^N x[n + k] L_k^{(N)}(t)$$

$$L_k^{(N)}(t) = \prod_{\substack{i=-N \\ i \neq n}}^N \frac{t - i}{k - i} \quad k = -N, \dots, N$$

► $x(n + \tau) \approx x_L(n; \tau)$

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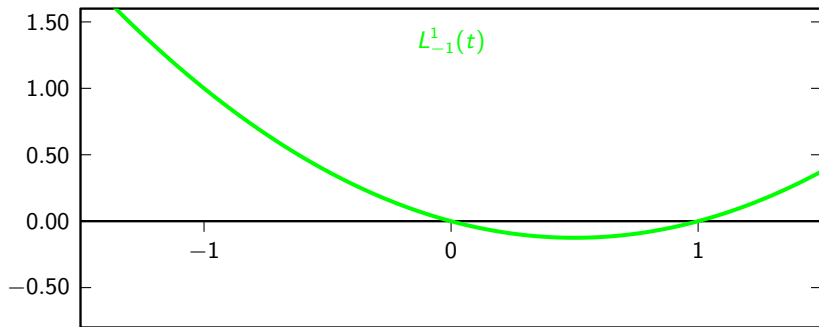
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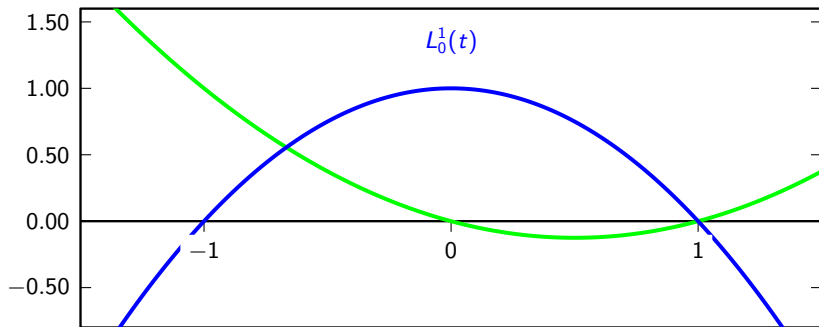
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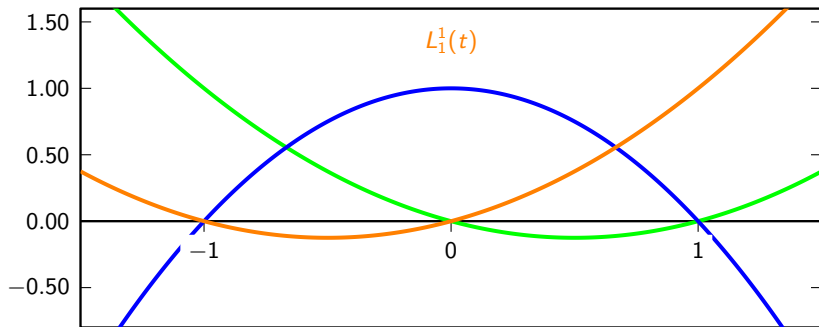
2nd-order Lagrange interpolation polynomials ($N = 1$)



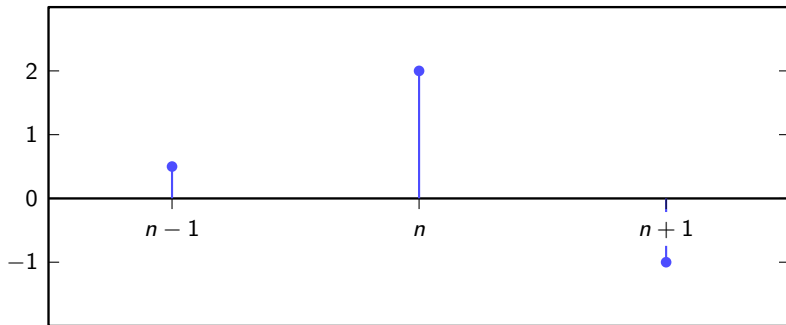
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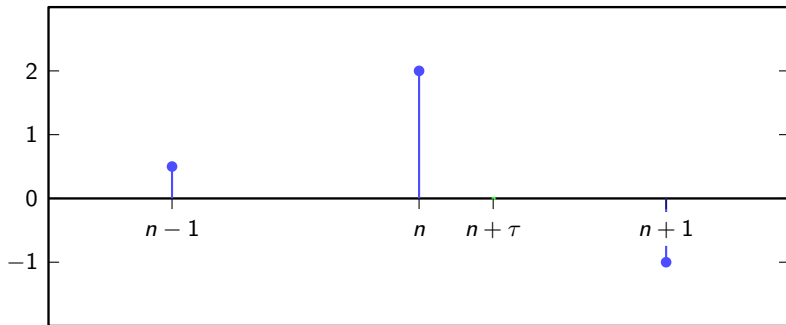
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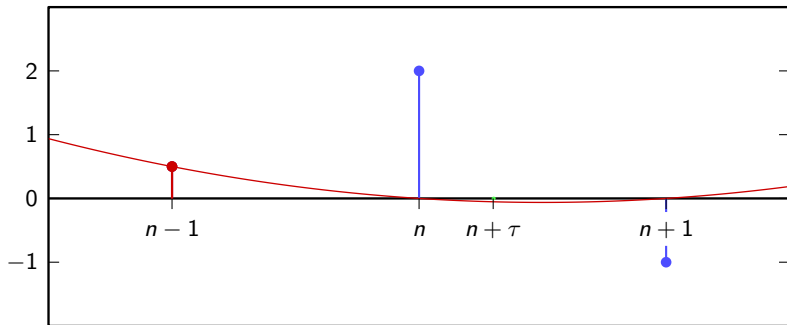
Lagrange interpolation ($N = 1$)



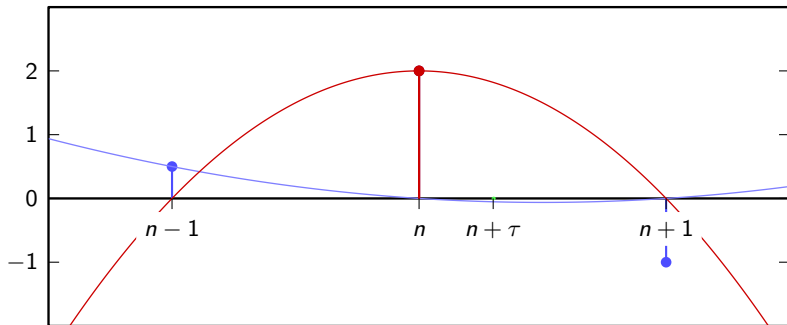
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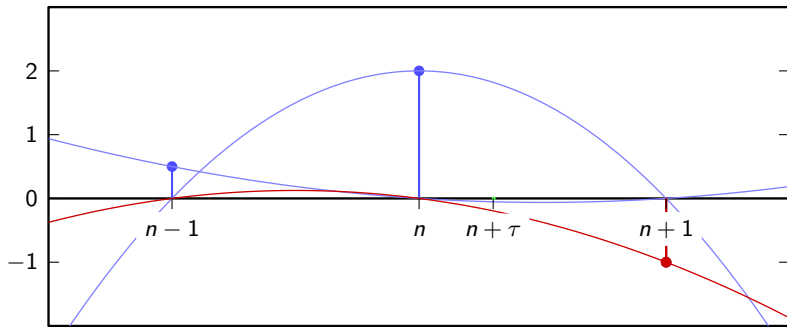
Lagrange interpolation ($N = 1$)



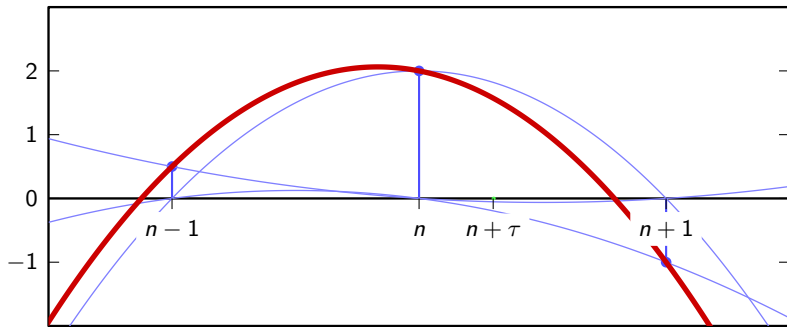
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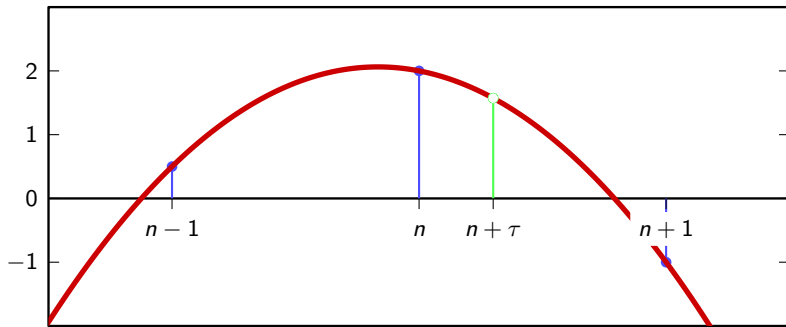
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Lagrange interpolation ($N = 1$)



Lagrange interpolation as an FIR

- ▶ $x(n + \tau) \approx x_L(n; \tau)$
- ▶ $x_L(n; \tau) = \sum_{k=-N}^N x[n + k] L_k^{(N)}(\tau) = \sum_{k=-N}^N x[n - k] L_{-k}^{(N)}(\tau)$
- ▶ define $d_\tau[k] = L_{-k}^{(N)}(\tau)$, $k = -N, \dots, N$
- ▶ $x_L(n; \tau) = \sum_{k=-N}^N x[n - k] d_\tau[k]$
- ▶ $x_L(n; \tau) = (x * d_\tau)[n]$
- ▶ $d_\tau[k]$ is a $(2N + 1)$ -tap FIR (dependent on τ)

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Example ($N = 1$, second order approximation)

$$L_{-1}^{(1)}(t) = t \frac{t-1}{2}$$

$$L_0^{(1)}(t) = (1-t)(1+t)$$

$$L_1^{(1)}(t) = t \frac{t+1}{2}$$

Example ($N = 1$, second order approximation)

$$d_{0.2}[n] = \begin{cases} 0.12 & n = -1 \\ 0.96 & n = 0 \\ -0.08 & n = 1 \\ 0 & \text{otherwise} \end{cases}$$

CD to DVD, revisited

for every 147 CD samples, generate 160 DVD samples

Fractional resampling: algorithm

sampling rate change A/B : for every B input point, generate A output points

Initialization (pattern will repeat every A output points)

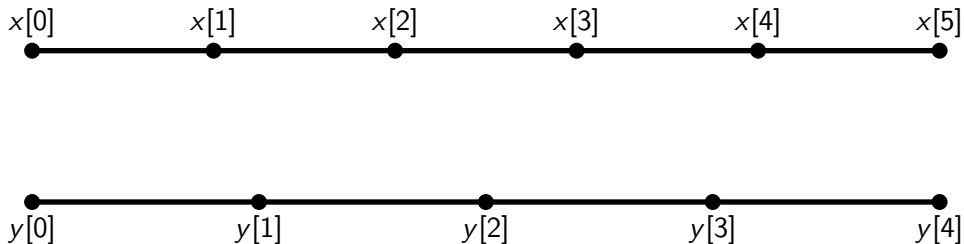
- ▶ for each output index $0 \leq m < A$ find closest (< 0.5) input point
- ▶ generate a FIR interpolation filter using difference between output and anchor

For every block of A output values $y[n]$:

- ▶ use all filters in turn
- ▶ generate output points

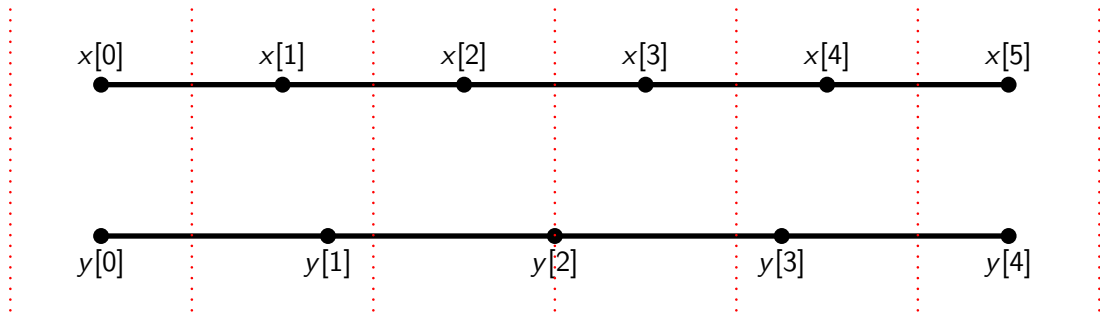
Fractional resampling: sample rate reduction

Downsampling: $\frac{A}{B} = \frac{4}{5}$



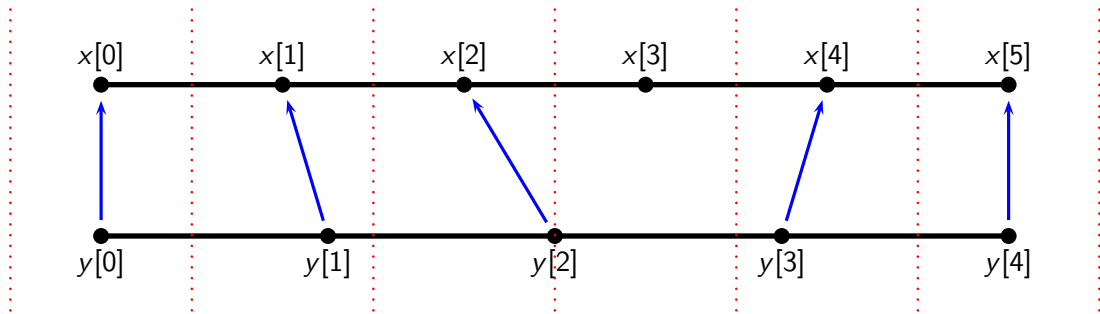
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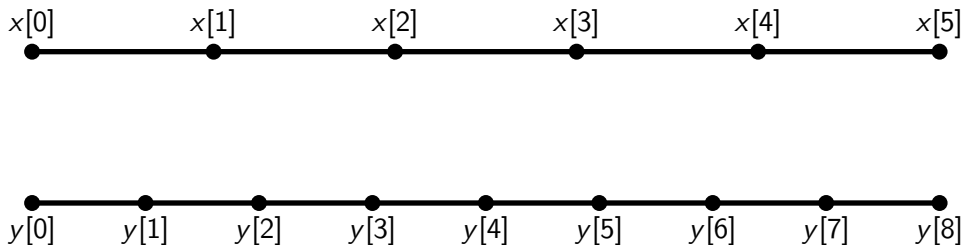
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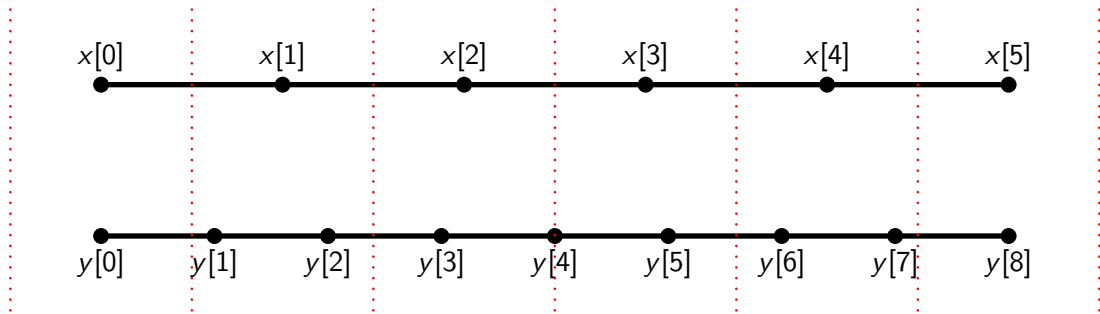
Fractional resampling: sample rate increase

$$\text{Upsampling: } \frac{A}{B} = \frac{8}{5}$$



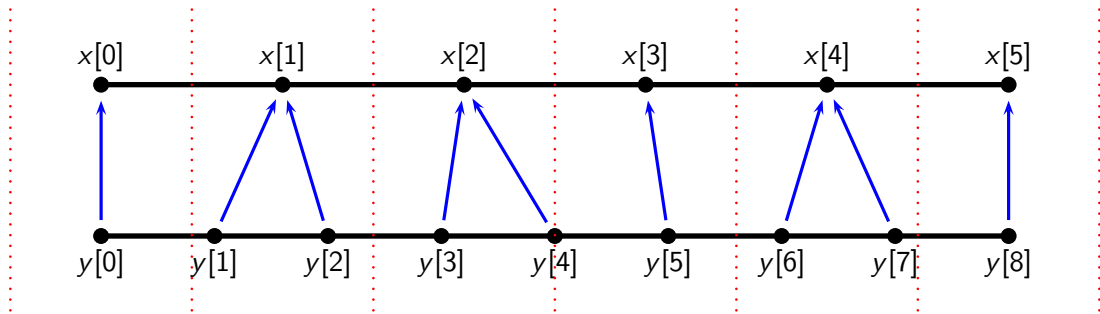
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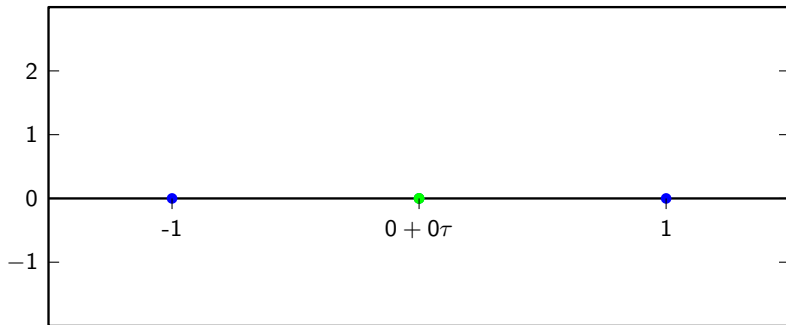


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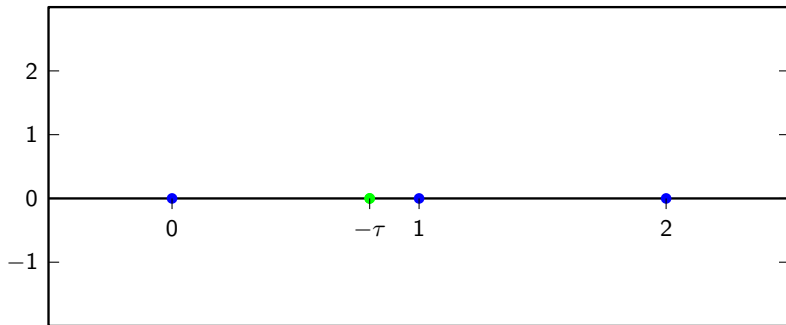
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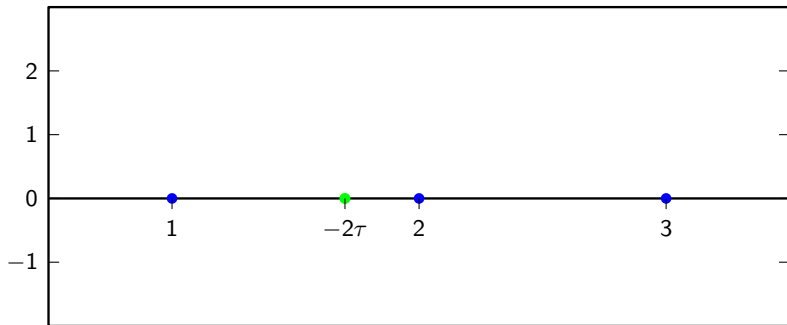
CD to DVD, revisited



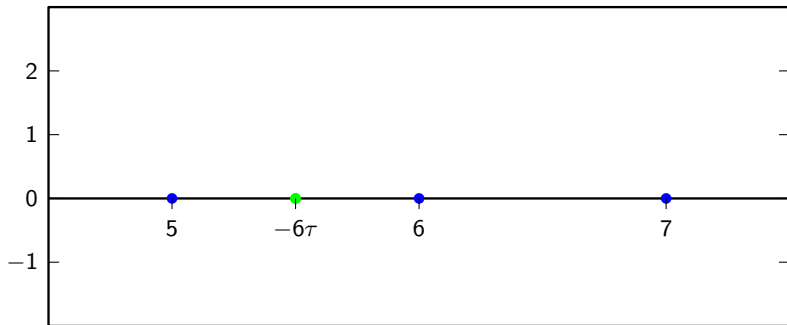
CD to DVD, revisited, $\tau[1] = 0.06875$



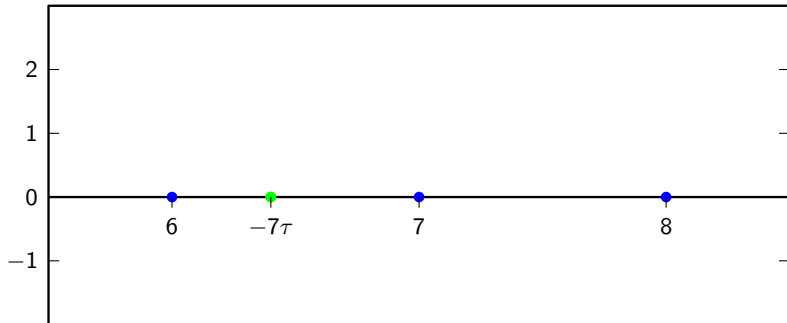
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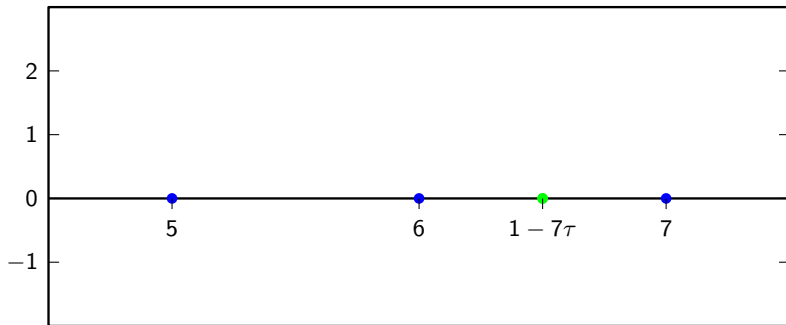


CD to DVD, revisited

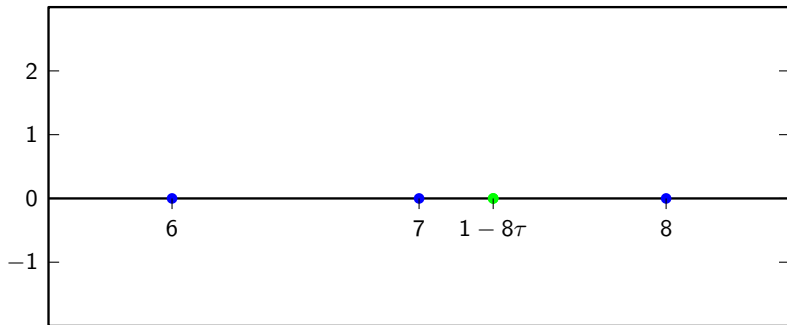


but $-7\tau < -0.5$

CD to DVD, revisited: repeat a sample



CD to DVD, revisited



CD to DVD, revisited

efficient local interpolation with 160 3-tap filters, used in sequence