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```
[p_sat,T_sat,rho_vap,h_w,~,c_p]=SatWater;  
k.n_cell    = 15;  
k.switch    = -1;
```

INTEGRATION PARAMETERS

```
%k.T        = 3600*24;  
k.T         = 2000*1;
```

AMBIENT CONDITIONS

```
k.p_amb      = 1E05;           % Ambient pressure [Pa]  
k.T_amb      = 10 + 273.15;    % Ambient temperature [K]
```

SOLID WASTE PARAMETERS

Molar mass of the waste elemental components [kg/kmol] in the combustable fraction

```
k.Mw_w      = [12.011;          % C
                1.0079;         % H
                32.06;          % S
                35.45;          % Cl
                14.007;         % N
                15.999;         % O
                18.998];        % F
k.nc_w      = length(k.Mw_w);
```

```
% Specific heat capacity [J/kgK]
k.cp_w      = 2.26e+03;
```

GAS PARAMETERS

Molar mass [kg/kmol]

```
k.Mw_gas    = [k.Mw_w(2)*2+k.Mw_w(6);    % H2O
                k.Mw_w(5)*2;              % N2
                k.Mw_w(1)+k.Mw_w(6)*2;    % CO2
                k.Mw_w(6)*2;              % O2
                k.Mw_w(1)+k.Mw_w(2)*4;    % CH4
                k.Mw_w(2)*2;              % H2
                k.Mw_w(1)+k.Mw_w(6);      % CO
                k.Mw_w(3)+k.Mw_w(6)*2;    % SO2
                k.Mw_w(2)+k.Mw_w(4);      % HCl
                k.Mw_w(2)+k.Mw_w(7);      % HF
                k.Mw_w(5)+k.Mw_w(6)*2;    % NO2
                k.Mw_w(5)+k.Mw_w(2)*3];   % NH3
k.nc_gas    = length(k.Mw_gas);
% Specific heat capacity [J/kgK]
k.cp_fg     = 1.23e+03;
% Universal gas constant [J/kmol K]
k.R         = 8.314462175*1E3;
```

LIQUID WATER PARAMETERS

```
k.cp_water  = 4.2E+03; % [J/kg K]
k.rho_water = 1E+03;   % [kg/m3]
k.Mw_water  = k.Mw_gas(1);
```

WASTE IN

```
k.w_w_in    = [26;          % Moisture (H2O)
                20.8;
                3;
                0.3;
```

```

0.2;
0.4;
17.5;
0.01;
23.8]./100; % Ashes
k.w_w_in = k.w_w_in./sum(k.w_w_in);

```

GRATE

GEOMETRY data from "Ryu, C., Yang, Y.B., Nasserzadeh, V. and Swithenbank, J., 2004 "Thermal reaction modeling of a large municipal solid waste incinerator." Combustion Science and Technology, 176(11), pp.1891-1907.

```

k.W      = 3.76; % Width of the grate
k.L      = 9.84; % total grate lenght
k.A      = k.W*k.L;
k.v_grate = 7.38./3600; % [m/s]
k.rho_w   = 500; % density of waste [kg/m3]
h_grate   = 0.3; % Height of the grate[m] --> assumed
value
k.A_grate = k.W.*h_grate;
% Waste and methal conductivity
k.k_w     = 0.1;
k.k_grate = 50;
% Other data
k.sigma    = 5.67051e-8; % Stefan-Boltzmann constant [J/(m2 s
K4)]
k.epsilon_gt= 0.88; % Emissivity of flue gas (WHAT VALUES
SHOULD BE HERE??)
k.alpha_gt = k.epsilon_gt; % Absorptivity of flue gas (WHAT
VALUES SHOULD BE HERE??)

```

Zone dimensions

```

k.M_steel_grate = 1500; % Mass of steel in the different
zones of the furnace (this is just a random number)

```

FREE BOARD

```

k.V_FreeBoard = k.W.*k.L*1.5;
k.M_steel_FB = 2000; % Mass of steel in the free board
(this is just a random number)

```

PRIMARY AIR

```

RH_aI      = 90; % The air is taken from the waste
bunker --> very humid
k.w_a      = CALC_w_ha(k.T_amb,RH_aI,k.Mw_gas); % The temperature of
the air in the bunker is assumed equal to ambient temperature
k.T_aI     = 110 + 273.15; % Pre-heating of primary air

```

```
y_a          = CALC_y_a(k.w_a,k.Mw_gas);  
Mw_a        = sum(k.Mw_gas.*y_a);
```

Primary air fan

```
k.Pmax_aI = 114.1.*1e3; % maximum power the fan can deliver [W]  
k.I_aI = 82.8; % moment of inertia [kg*m^2]  
rpm_T_p = 400; % lowest value of rpm for which Torque equals Power/  
omega  
k.omega_T_aI = rpm_T_p*2*pi/60;  
% estimating volume flow as function of rpm, assuming a linear  
relationship  
  
% insert data points from fan data  
Q_est = [1136 747 447]; % [m^3/min]  
rpm_est1 = [1383 931 560]; % [rpm]  
k.map_aI = mean(Q_est./rpm_est1); % propornality constant [m^3/  
(min*rpm)]  
  
% estimating torque drag function, assumed to be quadratic (T =  
% alpha*omega^2)  
  
% insert datapoints from torque diagram  
torq_est_fg = [370]; % [N*m]  
% insert corresponding rpm  
rpm_est2_fg = [931]; % [rpm]  
omega_est_fg = rpm_est2_fg.*(2*pi/60); % change to angular velocity  
[rad/s]  
k.alpha_est_aII = mean(torq_est_fg./(omega_est_fg.^2)); % estimated  
propotionality constant [J*s]  
  
rpm_in_p = 1; % initial rotation  
omega_in_p = rpm_in_p*2*pi/60;  
  
k.mu_eff = 0.8;
```

Secondary air fan

```
k.Pmax_aII = 34.4; % maximum power the fan can deliver [kW]  
k.I_aII = 3.13; % moment of inertia [kg*m^2]  
rpm_T_s = 500; % lowest value of rpm for which Torque equals Power/  
omega  
k.omega_T_aII = rpm_T_s*2*pi/60;  
  
% estimating volume flow as function of rpm, assuming a linear  
relationship  
  
% insert data points from fan data  
Q_est = [333]; % [m^3/min]  
rpm_est1 = [2960]; % [rpm]  
k.map_aII = mean(Q_est./rpm_est1); % propornality constant [m^3/  
(min*rpm)]
```

```

% estimating torque drag function, assumed to be quadratic (T =
% alpha*omega^2)

% insert datapoints from torque diagram
torq_est_fg = [111.4]; % [N*m]
% insert corresponding rpm
rpm_est2_fg= [2960]; % [rpm]
omega_est_fg = rpm_est2_fg.*(2*pi/60); % change to angular velocity
[rad/s]
k.alpha_est_s = mean(torq_est_fg./(omega_est_fg.^2)); % estimated
propotionality constant [J*s]

rpm_in_s = 1; % initial rotation
omega_in_s = rpm_in_s*2*pi/60;

```

INITIAL CONDITIONS

Zone 1

```

k.T_0      = 850+273.15;
k.M_fg_IC  = k.p_amb.*k.V_FreeBoard./(k.R.*k.T_0).*Mw_a;

```

EVAPORATOR GEOMETRY (need data here)

```

k.p_drum    = 51e5;
M_H2O_l     = 148e3; % Mass of liquid water in the boiler
[kg] at T=T_amb
k.V_H2O     = M_H2O_l./k.rho_water; % Volume of the vessel occupied by
water [m3]
k.V_EVA     = 203; % Volume of vessel
k.V_gas     = k.V_EVA-k.V_H2O; % Volume of the vessel eccupied by air
y_sat       = CALC_xsats(k.T_amb);
p_vap       = y_sat*k.p_amb;
rho_steam   = interp1(T_sat,rho_vap,k.T_amb,'linear','extrap');
p_steam     = interp1(T_sat,p_sat,k.T_amb,'linear','extrap');
Z_steam     = p_steam.*k.Mw_water./(rho_steam.*k.R.*k.T_amb);
M_H2O_v     = p_vap.*k.V_gas./(Z_steam.*k.R.*k.T_amb).*k.Mw_water;
k.M_H2O     = M_H2O_l + M_H2O_v;
k.x_vap_0   = M_H2O_v/k.M_H2O;
k.epsilon_EVA=0.7; % Evaporator effectiveness
k.M_steel   = 200000; % Total mass of metal in the boiler
[kg]
k.cp_steel  = 460; % Heat capacity steel [J/kg K]

k.N_air     = (k.p_amb-p_vap).*(k.V_gas)/(k.R.*k.T_amb);
k.Mw_air    = 28.014.*0.79 + 15.999*0.21;
k.M_air     = k.N_air.*k.Mw_air;

```

GLOBAL HEAT EXCHANGER EFFICIENCY

```

k.eff_HE    = 0.96;

```

ECONOMIZER

```
k.epsilon_ECO= 0.72;           % Economizer effectiveness
k.eta_ECO    = 0.9;
```

HEAT EXCHANGER WITH UTILITIES

```
k.epsilon_HE= 0.953;          % HE effectiveness
```

SUPERHEATER

```
k.epsilon_SH= 0.95;
```

DRUM

```
Liquid water enthalpy

h_w_sat    = interp1(p_sat,h_w,k.p_amb,'linear','extrap');
h_water    = h_w_sat - k.cp_water.*(373.15-k.T_amb);
% Vapour water enthalphy
h_vap      = interp1(T_sat,h_w,k.T_amb,'linear','extrap');
% Initial energy stored in the boiler
k.A_0      = (k.M_H2O.*(1-k.x_vap_0).*h_water +
    k.M_H2O.*k.x_vap_0.*h_vap - k.p_amb.*k.V_EVA );
k.T_guess  = 300;
k.x_guess  = 0;
```

TURBINE

```
k.p_HP     = (-0.256 + 1).*1e5;
k.p_LP     = (-0.546 + 1).*1e5;
k.eta_TURB = 0.9;
```

HEAT OF REACTIONS

```
k = CALC_DeltaH(k);
```

GAS CLEANING SYSTEM

```
k.epsilon_HE1 = 0.054;
k.epsilon_HE2 = 0.70;
k.eff_HE2     = 0.83;
k.epsilon_HE3 = 0.47;
k.epsilon_HE4 = 0.69;
```

DYNAMIC PARAMETERS FROM PROCESS DATA

```
data2 = importdata('Data_Boiler.txt');
```

```

data3      = importdata('Data_Fg.txt');
data4      = importdata('Data_Turbine.txt');

% Time (in seconds) between data points in the excel files, and also
the
% total time span of the process data
delta_t    = 5*60;
max_t      = 60*60*24;

```

Primary air

temperature

```

data_ex = Find_val('1HLA30DT001_PV',data2); % Read process data from
t=0 to
% t = max_t
T_aI.signals.values = data_ex + 273.15; % Celsius to Kelvin
T_aI.time = delta_t*[0:(length(T_aI.signals.values)-1)];
% Flow rate of primary air to the different zones. each zone is given
a
% struct
data_ex = Find_val('1HLA41FF001_',data2); %left 1
data_ex_r = Find_val('1HLA51FF001_',data2);
% merge and scale to [kg/s]
F_aI_z1.signals.values = (data_ex + data_ex_r)./(3600*22.414).*28.966;
F_aI_z1.time = delta_t*[0:(length(F_aI_z1.signals.values)-1)];
% repeat for the other 4
data_ex = Find_val('1HLA42FF001_',data2); %left 2
data_ex_r = Find_val('1HLA52FF001_',data2); % right 2
F_aI_z2.signals.values = (data_ex + data_ex_r)./(3600*22.414).*28.966;
F_aI_z2.time = delta_t*[0:(length(F_aI_z2.signals.values)-1)];
data_ex = Find_val('1HLA43FF001_',data2); %left 1
data_ex_r = Find_val('1HLA53FF001_',data2); % right 1
F_aI_z3.signals.values = (data_ex + data_ex_r)./(3600*22.414).*28.966;
F_aI_z3.time = delta_t*[0:(length(F_aI_z3.signals.values)-1)];
data_ex = Find_val('1HLA44FF001_',data2); %left 1
data_ex_r = Find_val('1HLA54FF001_',data2); % right 1
F_aI_z4.signals.values = (data_ex + data_ex_r)./(3600*22.414).*28.966;
F_aI_z4.time = delta_t*[0:(length(F_aI_z4.signals.values)-1)];
data_ex = Find_val('1HLA45FF001_',data2); %left 1
data_ex_r = Find_val('1HLA55FF001_',data2); % right 1
F_aI_z5.signals.values = (data_ex + data_ex_r)./(3600*22.414).*28.966;
F_aI_z5.time = delta_t*[0:(length(F_aI_z5.signals.values)-1)];
% merge all to one struct as well
F_aI.signals.values = [F_aI_z1.signals.values, F_aI_z2.signals.values,
F_aI_z3.signals.values, F_aI_z4.signals.values,
F_aI_z5.signals.values];
F_aI.signals.dimensions = 5;
F_aI.time = delta_t*[0:(length(F_aI_z5.signals.values)-1)];
% total air flow from primary air source
F_aI.totave = sum(mean(F_aI.signals.values));
% total primary air struct
F_aI_tot.signals.values = sum(F_aI.signals.values,2);

```

```
F_aI_tot.time = F_aI.time;
```

Secondary air

```
data_ex = Find_val('1HLA81CF001_F_',data2);  
% Flow secondary air front wall  
data_ex_r = Find_val('1HLA82CF001_F_',data2);  
% Flow secondary air rear wall  
F_aII.signals.values = (data_ex + data_ex_r)./(3600*22.414).*28.966;  
% Secondary air flows from both walls are summed  
F_aII.time = delta_t*[0:(length(F_aII.signals.values)-1)]';  
F_aII.totave = mean(F_aII.signals.values);  
F_a_tot = (F_aII.signals.values  
+F_aI_tot.signals.values).*(3600*22.414)./28.966;  
% Temperature  
data_ex = Find_val('1HLA80CT001_F_',data2); %(correct??)  
T_aII.signals.values = data_ex + 273.15;  
% Celsius to Kelvin  
T_aII.time = delta_t*[0:(length(T_aII.signals.values)-1)]';
```

Waste

```
data_ex = Find_val('1HFB10FF002',data2); % rear wall  
F_w_in.signals.values = (data_ex) ./3.6;  
F_w_in.time = delta_t*[0:(length(F_aII.signals.values)-1)]';
```

Grate cooling

Temperature upstream grate cooling

```
T_c      = Find_val('1HLC03CT001_',data2);  
% Cooling water flow in the different zones  
F_z1     = Find_val('1HLC51CF001_',data2);  
F_z2     = Find_val('1HLC52CF001_',data2);  
F_z3     = Find_val('1HLC53CF001_',data2);  
% Cooling water temperature in the different zones  
T_z1     = Find_val('1HLC51CT001_',data2);  
T_z2     = Find_val('1HLC52CT001_',data2);  
T_z3     = Find_val('1HLC53CT001_',data2);  
% C_min in the different zones  
C_z1     = F_z1.*4.2e3;  
C_z2     = F_z2.*4.2e3;  
C_z3     = F_z3.*4.2e3;  
% Heat exchanged in the different zones  
Q_z1     = C_z1.*(T_z1-T_c);  
Q_z2     = C_z2.*(T_z2-T_c);  
Q_z3     = C_z3.*(T_z3-T_c);  
% Make bus signals  
Q_grate.signals.values = [Q_z1,Q_z2,Q_z3];  
Q_grate.time           = delta_t*[0:  
(length(Q_grate.signals.values)-1)]';
```

District heating water

```
F_from_DH.signals.values= Find_val('1NDA10CF010_A',data4); %  
    Water flow in district heating  
F_from_DH.time          = delta_t*[0:  
(length(F_from_DH.signals.values)-1)]';  
T_from_DH.signals.values= Find_val('1NDB10CT003_',data4) + 273.15; %  
    Water flow in district heating  
T_from_DH.time          = delta_t*[0:  
(length(T_from_DH.signals.values)-1)]';
```

Controller

```
% Controller type  
%  
% Open, AB, Cascade or MPC. Is used by the ChooseController block.  
%  
reg.controller_type = ControllerType.AB;  
  
% Operating values  
%  
% The controller action happens around these operating values.  
%  
reg.op_F_O2 = 4.6345; % Oxygen flow (kg/s)  
reg.op_F_st = 10.761; % Steam flow (kg/s)  
reg.op_HHV = 4.133444255e+07; % Heat value (J/s?)  
reg.op_F_aII = 14; % Secondary air (kg/s)  
reg.op_F_aI = 18; % Total primary air (kg/s)  
reg.op_v_grate = 0.0025; % Grate speed (m/s)  
reg.op_F_w_in = 4; % Waste feed (kg/s)  
reg.op_MVs = [...  
    reg.op_F_aII;...  
    reg.op_F_aI;... % Needed for backwards  
    compatibility.  
    reg.op_v_grate;... % Should be fixed.  
    reg.op_F_w_in...  
];  
reg.MV_names = ["F_aII" "F_aI"... % Needed for backwards  
    compatibility.  
    "v_grate" "F_w"]; % Should be fixed.  
  
% Constant input values  
%  
% These are used when the corresponding variable has  
% input_type set to InputType.Constant.  
%  
reg.const_F_aI = reg.op_F_aI; % Total primary air  
    (kg/s)  
reg.const_v_grate = reg.op_v_grate; % Grate speed (m/s)  
reg.const_F_w_in = reg.op_F_w_in; % Waste feed (kg/s)  
reg.const_F_aII = reg.op_F_aII; % Secondary air (kg/s)
```

```

reg.const_T_aI = 380; % Primary air
    temperature (K)
reg.const_T_aII = 300; % Secondary air
    temperature (K)
reg.const_Q_grate = [1.0e+05 2.2e+05 2.5e+05]; % Grate heat exchange
    (J?)
reg.const_F_from_DH = 130; % Flow from district
    heating (kg/s?)
reg.const_T_from_DH = 320; % Temperature of flow
    from district heating (K)
%
% Primary air flow distribution
%
% The relative distribution between primary air zones.
%
reg.const_F_aI_dist = [0.05 0.3 0.38 0.24 0.03];

% Input signal type
%
% Set the input type for different process variables. Is used by the
% ChooseSignal block.
%   Constant: The signal is determined by reg.const_<variable>.
%   Experimental: The signal is loaded from process data.
%   Controlled: The signal is determined by the controller.
% Note that not all variables can be Controlled.
%
% Controllable:
%
reg.input_type_F_aII = InputType.Controlled; % Secondary air
reg.input_type_F_aI = InputType.Controlled; % Primary air
reg.input_type_v_grate = InputType.Controlled; % Grate speed
reg.input_type_F_w_in = InputType.Controlled; % Waste feed
reg.input_type_HHV = InputType.Controlled; % Heating value
reg.input_type_AB = InputType.Controlled; % Primary-secondary
    air ratio
%
% Not controllable:
%
reg.input_type_T_aI = InputType.Constant; % Primary air
    temperature
reg.input_type_T_aII = InputType.Constant; % Secondary air
    temperature
reg.input_type_Q_grate = InputType.Constant; % Grate heat exchange
reg.input_type_F_from_DH = InputType.Constant; % Flow from district
    heating
reg.input_type_T_from_DH = InputType.Constant; % Temperature from
    district heating
%
% Heat value setpoint override
%
% Set to true if you are using the cascade controller want to control
the
% HHV setpoint manually using reg.op_HHV, instead of getting it from
the

```

```

% primary air PID. This is useful (and necessary) when tuning the
% slave
% loop.
%
reg.override_sp_HHV = false;

% PID parameters
%
% The critical value is an estimate of the P-constant
% required to get 30% overshoot when performing the SIMC tuning. It
% will
% probably need some adjustment.
%
% Oxygen controller
%
reg.Kp_O2 = 1.9769;           % Critical: 34
reg.Ki_O2 = 0.5054;          % Critical: 0
%
% Steam controller (no cascade)
%
reg.Kp_st = 45.8596;          % Critical: 125
reg.Ki_st = 0.8579;          % Critical: 0
reg.Kd_st = 0;               % Critical: 0
%
% AB ratio controller (no cascade)
%
reg.Kp_AB = -0.0010;          % Critical: -0.0002
reg.Ki_AB = -2.9786e-05;      % Critical: 0
%
% Heat value controller
%
reg.Kp_HHV = 2.1723e-07;      % Critical: ?
reg.Ki_HHV = 1.4988e-07;      % Critical: 0
%
% Steam controller (cascade)
%
reg.Kp_st_HHV = 1.2459e+07;    % Critical: ?
reg.Ki_st_HHV = 2.4691e+05;    % Critical: 0
reg.Kd_st_HHV = 0;            % Critical: 0
%
% AB ratio controller (cascade)
%
reg.Kp_AB_HHV = -0.0010;       % Critical: -0.001
reg.Ki_AB_HHV = -2.9786e-05;   % Critical: 0
%
% Fan controllers
%
reg.Kp_fan = 15;               % Critical: ?
reg.Ki_fan = 15;               % Critical: 0
%
% AB ratio controller output distribution
%
% The PID output is multiplied with these constants to determine their
% control signals.

```

```

%
reg.F_w_ratio = 400;
reg.v_grate_ratio = 1;

% Set points
%
% The controller setpoints. Add to these values to witness the
  controller
% response to setpoint changes.
%
reg.sp_F_O2 = reg.op_F_O2;      % Oxygen setpoint (kg/s)
reg.sp_F_st = reg.op_F_st;      % Steam setpoint (kg/s)
reg.sp_AB = 1.286;              % AB setpoint
reg.sp_HHV = reg.op_HHV;        % HHV setpoint, not used by the
  controller,
                                % only the tuning script

% Waste feed perturbation
%
% A square wave is applied to the waste feed input
% to emulate composition variation. Set the amplitude to 0 to disable,
  and
% set the frequency to a large value to create a step disturbance.
  Note
% that the square wave is offset 50% down on the y axis.
%
reg.F_w_pert_amp = 0*4*0.1;      % Peak-to-peak amplitude (kg/s)
reg.F_w_pert_freq = 1/400000;    % Frequency (s)

% PID output low pass filters
%
% The discrete PIDs and the MPC create stepping outputs, which can
  upset
% the differentiator. A first order low pass filter is used, but the
% effectiveness of this approach is not determined. Set higher time
% constants to increase smoothing.
%
reg.T_O2_LPF = 1e-01;    % Oxygen PID smoothing
reg.T_st_LPF = 1e-01;    % Steam PID smoothing
reg.T_AB_LPF = 1e-01;    % AB PID smoothing
reg.T_MPC_LPF = 1e-01;   % MPC smoothing

% Initial values
%
% Needed by fan model to avoid spikes at startup.
%
reg.F_aII_fan_PID_int = 1.01e+03;    % Secondary air PID integrator
reg.F_aII_fan_model_int = 16.8;      % Secondary air model
  integrator
reg.F_aI_fan_PID_int = 1.66e+03;     % Primary air PID integrator
reg.F_aI_fan_model_int = 16.8;       % Primary air model integrator

% MPC variables

```

```
%  
% The linear system and MPC object is stored between runs. To create  
% new  
% versions, just overwrite the corresponding file.  
%  
load('linsys.mat');      % Linear system, see linearize_model.m  
load('lmpc.mat');        % MPC object, see config_mpc.m
```

Additional part added by Jorn

```
set_post_step_values; % Set the values after a step  
reg.stepTime = 17e3;  
reg.include_noise = false;  
load("last_mpc_params.mat"); % Parameter for the MPC are needed to  
% keep the system from crashing (and the last MPC controller)  
mpc_function_type = mpc_params.mpc_function_parameter_type;  
unpack_mpc_params("mpc_params.mpc_function_params")  
reg.enforce_parameter_limits = false;
```

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