

COM303: Digital Signal Processing

Lecture 5: The Discrete Fourier Transform

Overview

- ▶ the Fourier basis for \mathbb{C}^N (recap)
- ▶ the DFT: definition and examples
- ▶ interpreting a DFT plot

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- ▶ the DFT: definition and examples
- ▶ interpreting a DFT plot

The canonical (time) basis for \mathbb{C}^N

- ▶ in “signal” notation: $\delta_k[n] = \delta[n - k]$, $n, k = 0, 1, \dots, N - 1$
- ▶ in vector notation: $\{\delta^{(k)}\}_{k=0,1,\dots,N-1}$ with $\delta_n^{(k)} = \delta[n - k]$

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The Fourier (frequency) basis for \mathbb{C}^N

► in “signal” notation: $w_k[n] = e^{j\frac{2\pi}{N}nk}$, $n, k = 0, 1, \dots, N-1$

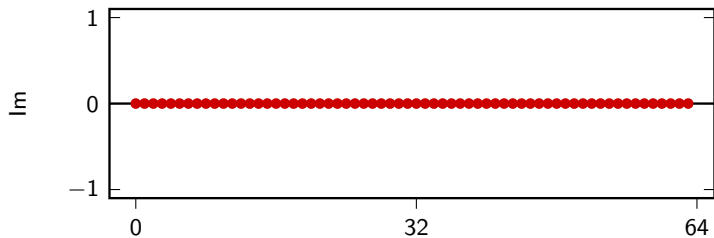
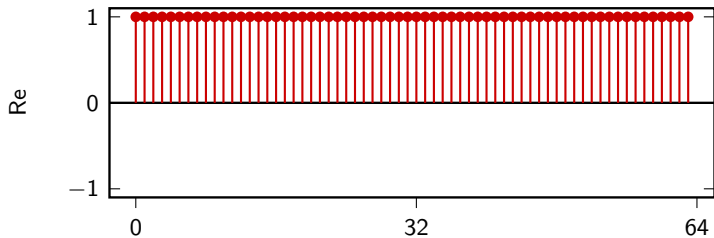
► in vector notation: $\{\mathbf{w}^{(k)}\}_{k=0,1,\dots,N-1}$ with $w_n^{(k)} = e^{j\frac{2\pi}{N}nk}$

The Fourier (frequency) basis for \mathbb{C}^N

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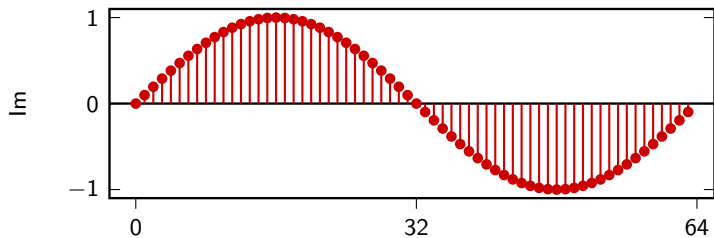
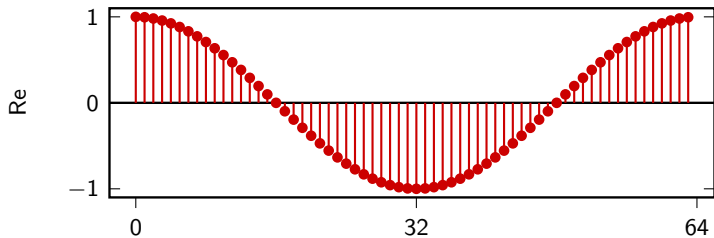
Basis vector $\mathbf{w}^{(0)} \in \mathbb{C}^{64}$

$$\omega = (2\pi/64) \cdot 0$$



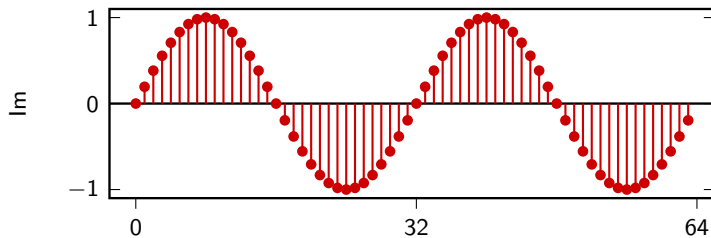
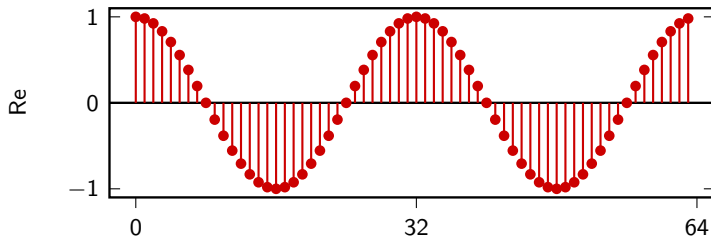
Basis vector $\mathbf{w}^{(1)} \in \mathbb{C}^{64}$

$$\omega = (2\pi/64) \cdot 1$$



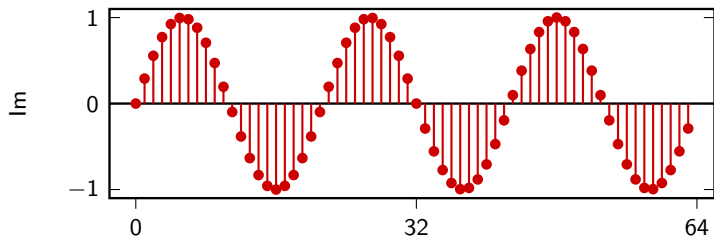
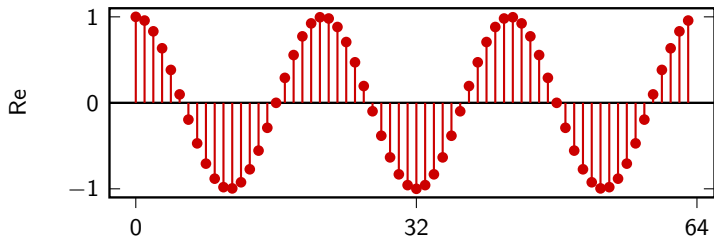
Basis vector $\mathbf{w}^{(2)} \in \mathbb{C}^{64}$

$$\omega = (2\pi/64) \cdot 2$$



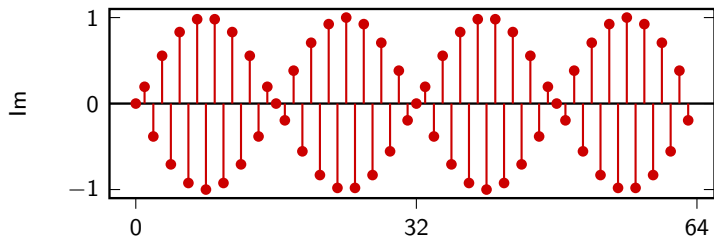
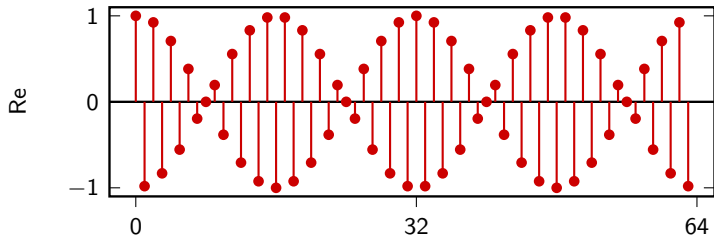
Basis vector $\mathbf{w}^{(3)} \in \mathbb{C}^{64}$

$$\omega = (2\pi/64) \cdot 3$$



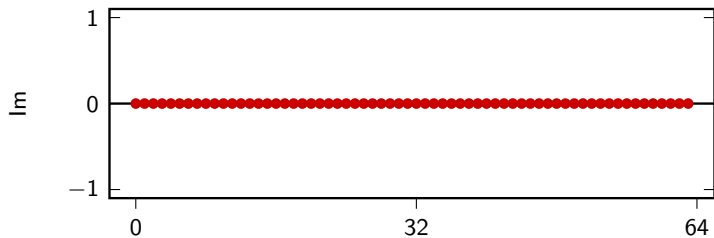
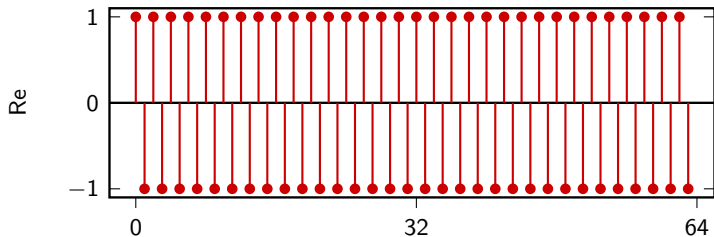
Basis vector $\mathbf{w}^{(30)} \in \mathbb{C}^{64}$

$$\omega = (2\pi/64) \cdot 30$$



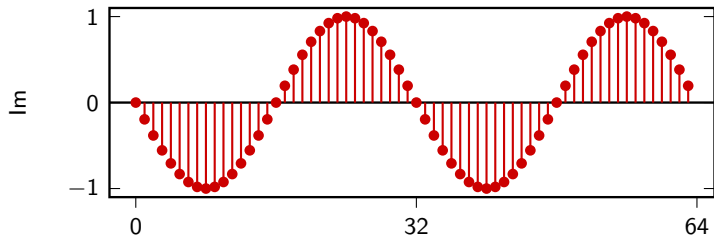
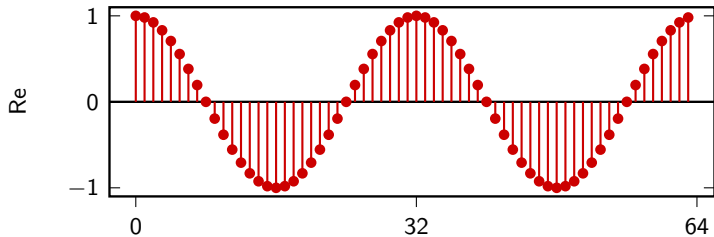
Basis vector $\mathbf{w}^{(32)} \in \mathbb{C}^{64}$

$$\omega = (2\pi/64) \cdot 32$$



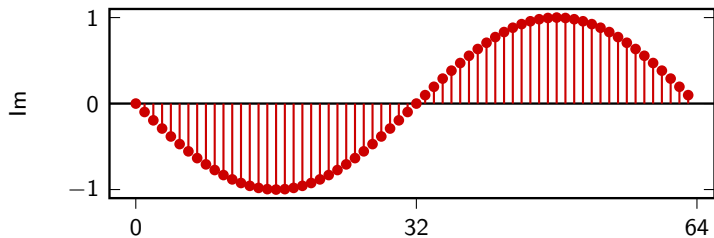
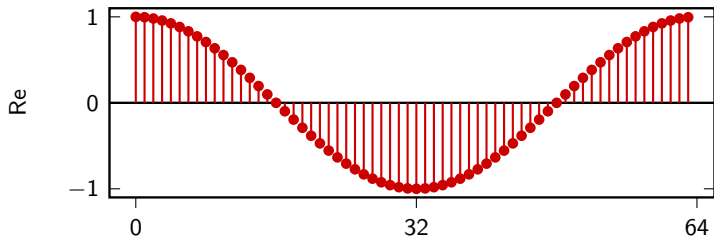
Basis vector $\mathbf{w}^{(62)} \in \mathbb{C}^{64}$

$$\omega = (2\pi/64) \cdot 62$$



Basis vector $\mathbf{w}^{(63)} \in \mathbb{C}^{64}$

$$\omega = (2\pi/64) \cdot 63$$



Proof of orthogonality

$$\begin{aligned}\langle \mathbf{w}^{(k)}, \mathbf{w}^{(h)} \rangle &= \sum_{n=0}^{N-1} (e^{j\frac{2\pi}{N}nk})^* e^{j\frac{2\pi}{N}nh} \\ &= \sum_{n=0}^{N-1} e^{j\frac{2\pi}{N}(h-k)n} \\ &= \begin{cases} N & \text{for } h = k \\ \frac{1 - e^{j2\pi(h-k)}}{1 - e^{j\frac{2\pi}{N}(h-k)}} = 0 & \text{otherwise} \end{cases}\end{aligned}$$

The Fourier Basis for \mathbb{C}^N

- ▶ N orthogonal vectors \longrightarrow basis for \mathbb{C}^N
- ▶ vectors are not *orthonormal*. Normalization factor would be $1/\sqrt{N}$
- ▶ will keep normalization factor explicit in DFT formulas

Basis expansion

Analysis formula:

$$X_k = \langle \mathbf{w}^{(k)}, \mathbf{x} \rangle$$

Synthesis formula:

$$\mathbf{x} = \frac{1}{N} \sum_{k=0}^{N-1} X_k \mathbf{w}^{(k)}$$

Basis expansion (signal notation)

Analysis formula:

$$X[k] = \sum_{n=0}^{N-1} x[n] e^{-j\frac{2\pi}{N}nk}, \quad k = 0, 1, \dots, N-1$$

N -point signal in the *frequency domain*

Synthesis formula:

$$x[n] = \frac{1}{N} \sum_{k=0}^{N-1} X[k] e^{j\frac{2\pi}{N}nk}, \quad n = 0, 1, \dots, N-1$$

N -point signal in the *"time" domain*

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$$x[n] = \frac{1}{N} \sum_{k=0}^{N-1} X[k] e^{j\frac{2\pi}{N}nk}, \quad n = 0, 1, \dots, N-1$$

N -point signal in the *“time” domain*

Change of basis in matrix form

Define $W_N = e^{-j\frac{2\pi}{N}}$
(or simply W when N is evident from the context)

Change of basis matrix \mathbf{W} with $\mathbf{W}[n, m] = W_N^{nm}$:

$$\mathbf{W} = \begin{bmatrix} 1 & 1 & 1 & 1 & \dots & 1 \\ 1 & W^1 & W^2 & W^3 & \dots & W^{N-1} \\ 1 & W^2 & W^4 & W^6 & \dots & W^{2(N-1)} \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & W^{N-1} & W^{2(N-1)} & W^{3(N-1)} & \dots & W^{(N-1)^2} \end{bmatrix}$$

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Change of basis in matrix form

Analysis formula:

$$\mathbf{X} = \mathbf{W}\mathbf{x}$$

Synthesis formula:

$$\mathbf{x} = \frac{1}{N} \mathbf{W}^H \mathbf{X}$$

$$W_N^m = W_N^{(m \bmod N)}$$

e.g. $W_8^{11} = W_8^3$

$$W_N^m = W_N^{(m \bmod N)}$$

$$\text{e.g. } W_8^{11} = W_8^3$$

Small DFT matrices: $N = 2, 3$

$$W_2 = e^{-j\frac{2\pi}{2}} = -1$$

$$\mathbf{W}_2 = \begin{bmatrix} 1 & 1 \\ 1 & W \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$$

$$W_3 = e^{-j\frac{2\pi}{3}} = -(1 + j\sqrt{3})/2$$

$$\mathbf{W}_3 = \begin{bmatrix} 1 & 1 & 1 \\ 1 & W & W^2 \\ 1 & W^2 & W^4 \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 \\ 1 & W & W^2 \\ 1 & W^2 & W \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 \\ 1 & -(1 + j\sqrt{3})/2 & -(1 - j\sqrt{3})/2 \\ 1 & -(1 - j\sqrt{3})/2 & (1 - j\sqrt{3})/2 \end{bmatrix}$$

Small DFT matrices: $N = 4$

$$W_4 = e^{-j\frac{2\pi}{4}} = e^{-j\frac{\pi}{2}} = -j$$

$$\mathbf{W}_4 = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & W & W^2 & W^3 \\ 1 & W^2 & W^4 & W^6 \\ 1 & W^3 & W^6 & W^9 \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & W & W^2 & W^3 \\ 1 & W^2 & 1 & W^2 \\ 1 & W^3 & W^2 & W \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & -j & -1 & j \\ 1 & -1 & 1 & -1 \\ 1 & j & -1 & -j \end{bmatrix}$$

Small DFT matrices: $N = 5$

$$\mathbf{W}_5 = \begin{bmatrix} 1 & 1 & 1 & 1 & 1 \\ 1 & W & W^2 & W^3 & W^4 \\ 1 & W^2 & W^4 & W^6 & W^8 \\ 1 & W^3 & W^6 & W^9 & W^{12} \\ 1 & W^4 & W^8 & W^{12} & W^{16} \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & 1 & 1 \\ 1 & W & W^2 & W^3 & W^4 \\ 1 & W^2 & W^4 & W & W^3 \\ 1 & W^3 & W & W^4 & W^2 \\ 1 & W^4 & W^3 & W^2 & W \end{bmatrix}$$

Small DFT matrices: $N = 6$

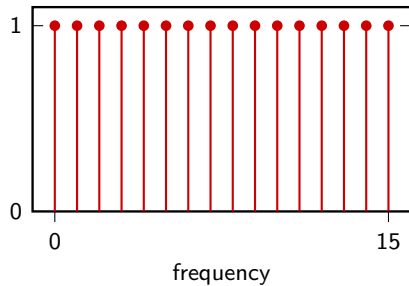
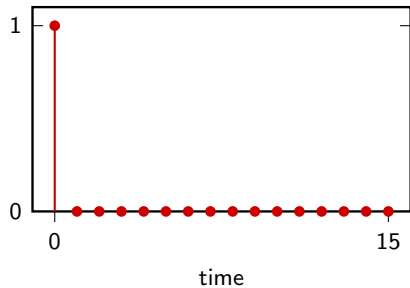
$$\mathbf{W}_6 = \begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & W & W^2 & W^3 & W^4 & W^5 \\ 1 & W^2 & W^4 & W^6 & W^8 & W^{10} \\ 1 & W^3 & W^6 & W^9 & W^{12} & W^{15} \\ 1 & W^4 & W^8 & W^{12} & W^{16} & W^{20} \\ 1 & W^5 & W^{10} & W^{15} & W^{20} & W^{25} \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & W & W^2 & W^3 & W^4 & W^5 \\ 1 & W^2 & W^4 & 1 & W^2 & W^4 \\ 1 & W^3 & 1 & W^3 & 1 & W^3 \\ 1 & W^4 & W^2 & 1 & W^4 & W^2 \\ 1 & W^5 & W^4 & W^3 & W^2 & W \end{bmatrix}$$

DFT is obviously linear

$$\text{DFT} \{ \alpha x[n] + \beta y[n] \} = \alpha \text{DFT} \{ x[n] \} + \beta \text{DFT} \{ y[n] \}$$

DFT of $\delta[n] \in \mathbb{C}^N$

$$\sum_{n=0}^{N-1} \delta[n] e^{-j\frac{2\pi}{N}nk} = 1 \quad \forall k$$



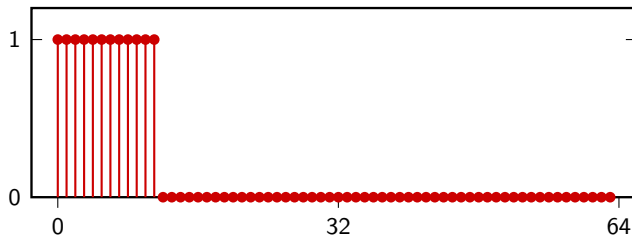
DFT of $\delta^{(m)} = \delta[n - m] \in \mathbb{C}^N$

$$\sum_{n=0}^{N-1} \delta[n - m] e^{-j\frac{2\pi}{N}nk} = e^{-j\frac{2\pi}{N}mk}$$

$$\text{DFT} \left\{ \delta^{(m)} \right\} = (\mathbf{w}^{(m)})^*$$

DFT of length- M step in \mathbb{C}^N

$$x[n] = \sum_{h=0}^{M-1} \delta[n - m], \quad n = 0, 1, \dots, N - 1$$



DFT of length- M step in \mathbb{C}^N

$$\begin{aligned} X[k] &= \sum_{m=0}^{M-1} \text{DFT} \{ \delta[n - m] \} = \sum_{m=0}^{M-1} e^{-j\frac{2\pi}{N}mk} \\ &= \frac{1 - e^{-j\frac{2\pi}{N}kM}}{1 - e^{-j\frac{2\pi}{N}k}} \\ &= \frac{e^{-j\frac{\pi}{N}kM} \left[e^{j\frac{\pi}{N}kM} - e^{-j\frac{\pi}{N}kM} \right]}{e^{-j\frac{\pi}{N}k} \left[e^{j\frac{\pi}{N}k} - e^{-j\frac{\pi}{N}k} \right]} \\ &= \frac{\sin\left(\frac{\pi}{N}Mk\right)}{\sin\left(\frac{\pi}{N}k\right)} e^{-j\frac{\pi}{N}(M-1)k} \end{aligned}$$

DFT of length- M step in \mathbb{C}^N

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DFT of length- M step in \mathbb{C}^N

$$X[k] = \frac{\sin\left(\frac{\pi}{N}Mk\right)}{\sin\left(\frac{\pi}{N}k\right)} e^{-j\frac{\pi}{N}(M-1)k}$$

- ▶ $X[0] = M$, from the definition of the sum
- ▶ $X[k] = 0$ if Mk/N integer ($0 \leq k < N$)
- ▶ $\angle X[k]$ linear in k (except at sign changes for the real part)

DFT of length- M step in \mathbb{C}^N

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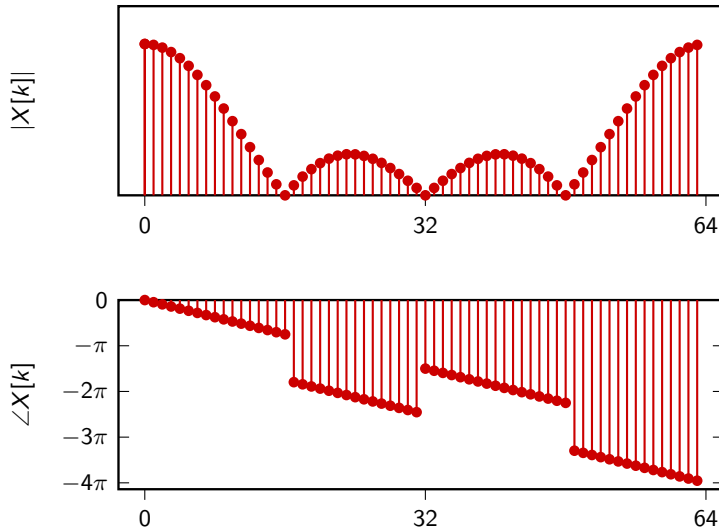
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DFT of length-4 step in \mathbb{C}^{64}

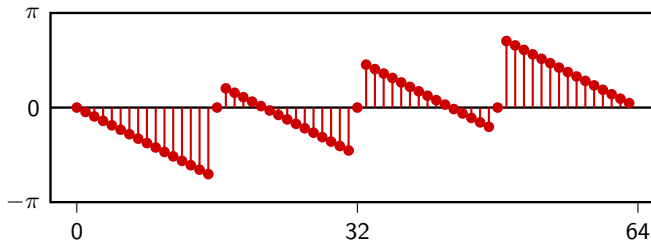
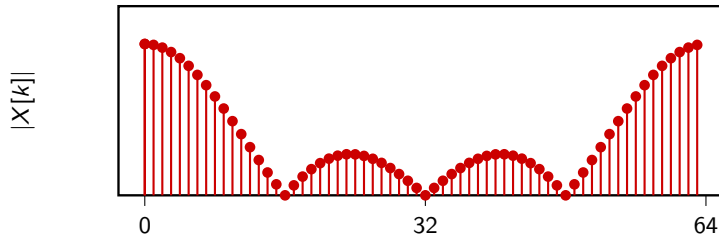


Wrapping the phase

Often the phase is displayed "wrapped" over the $[-\pi, \pi]$ interval.

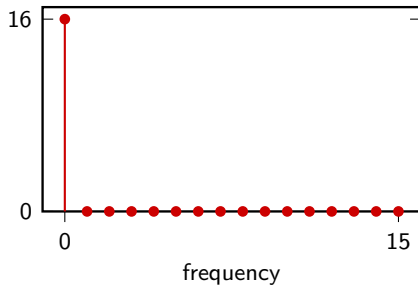
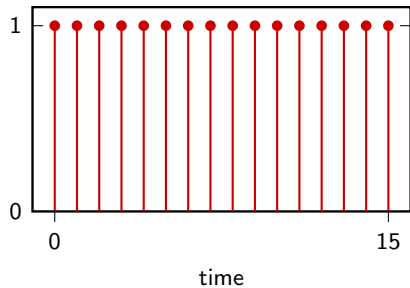
- ▶ most numerical packages return wrapped phase
- ▶ phase can be unwrapped by adding multiples of 2π

DFT of length-4 step in \mathbb{C}^{64} (phase wrapped)



DFT of $x[n] = 1$, $x[n] \in \mathbb{C}^N$

$$X[k] = \sum_{n=0}^{N-1} e^{-j\frac{2\pi}{N}nk} = N\delta[k]$$



DFT of harmonic oscillations

$$\text{DFT} \left\{ e^{j\frac{2\pi}{N}mn} \right\} = \langle \mathbf{w}^{(k)}, \mathbf{w}^{(m)} \rangle = N\delta[m - k]$$

DFT of $x[n] = 3 \cos(2\pi/16 n)$, $x[n] \in \mathbb{C}^{64}$

$$\begin{aligned}x[n] &= 3 \cos\left(\frac{2\pi}{16} n\right) \\&= 3 \cos\left(\frac{2\pi}{64} 4 n\right) \\&= \frac{3}{2} \left[e^{j\frac{2\pi}{64} 4n} + e^{-j\frac{2\pi}{64} 4n} \right] \\&= \frac{3}{2} \left[e^{j\frac{2\pi}{64} 4n} + e^{j\frac{2\pi}{64} 60n} \right] \\&= \frac{3}{2} (w_4[n] + w_{60}[n])\end{aligned}$$

DFT of $x[n] = 3 \cos(2\pi/16 n)$, $x[n] \in \mathbb{C}^{64}$

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DFT of $x[n] = 3 \cos(2\pi/16 n)$, $x[n] \in \mathbb{C}^{64}$

$$\begin{aligned}x[n] &= 3 \cos\left(\frac{2\pi}{16} n\right) \\&= 3 \cos\left(\frac{2\pi}{64} 4 n\right) \\&= \frac{3}{2} \left[e^{j\frac{2\pi}{64} 4n} + e^{-j\frac{2\pi}{64} 4n} \right] \\&= \frac{3}{2} \left[e^{j\frac{2\pi}{64} 4n} + e^{j\frac{2\pi}{64} 60n} \right] \\&= \frac{3}{2} (w_4[n] + w_{60}[n])\end{aligned}$$

DFT of $x[n] = 3 \cos(2\pi/16 n)$, $x[n] \in \mathbb{C}^{64}$

$$\begin{aligned} X[k] &= \langle w_k[n], x[n] \rangle \\ &= \langle w_k[n], \frac{3}{2}(w_4[n] + w_{60}[n]) \rangle \\ &= \frac{3}{2} \langle w_k[n], w_4[n] \rangle + \frac{3}{2} \langle w_k[n], w_{60}[n] \rangle \\ &= \begin{cases} 96 & \text{for } k = 4, 60 \\ 0 & \text{otherwise} \end{cases} \end{aligned}$$

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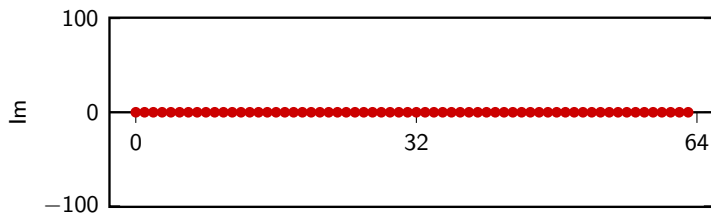
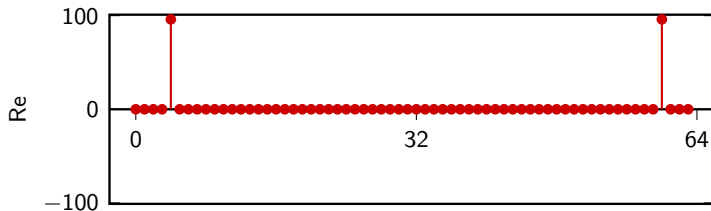
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DFT of $x[n] = 3 \cos(2\pi/16 n)$, $x[n] \in \mathbb{C}^{64}$



DFT of $x[n] = 3 \cos(2\pi/16 n + \pi/3)$, $x[n] \in \mathbb{C}^{64}$

$$\begin{aligned}x[n] &= 3 \cos\left(\frac{2\pi}{16} n + \frac{\pi}{3}\right) \\&= 3 \cos\left(\frac{2\pi}{64} 4 n + \frac{\pi}{3}\right) \\&= \frac{3}{2} \left[e^{j\frac{2\pi}{64} 4n} e^{j\frac{\pi}{3}} + e^{-j\frac{2\pi}{64} 4n} e^{-j\frac{\pi}{3}} \right] \\&= \frac{3}{2} (e^{j\frac{\pi}{3}} w_4[n] + e^{-j\frac{\pi}{3}} w_{60}[n])\end{aligned}$$

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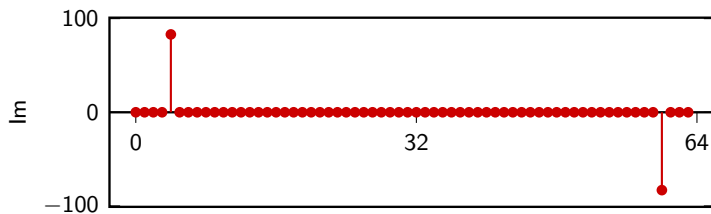
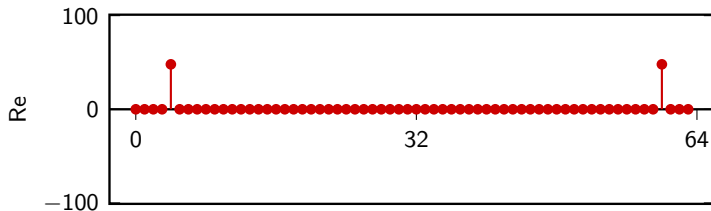
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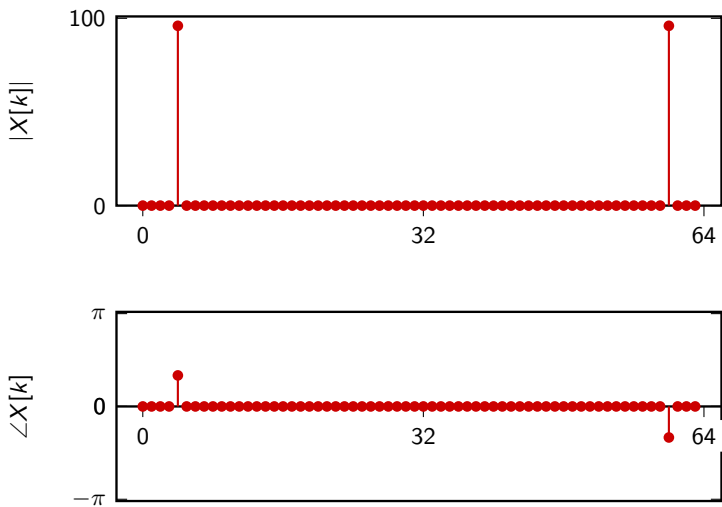
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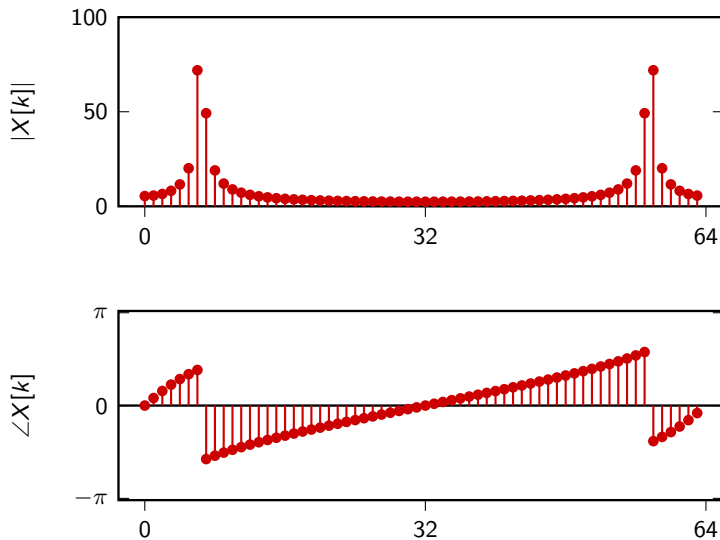
DFT of $x[n] = 3 \cos(2\pi/10 n)$, $x[n] \in \mathbb{C}^{64}$

$$\frac{2\pi}{64} 6 < \frac{2\pi}{10} < \frac{2\pi}{64} 7$$

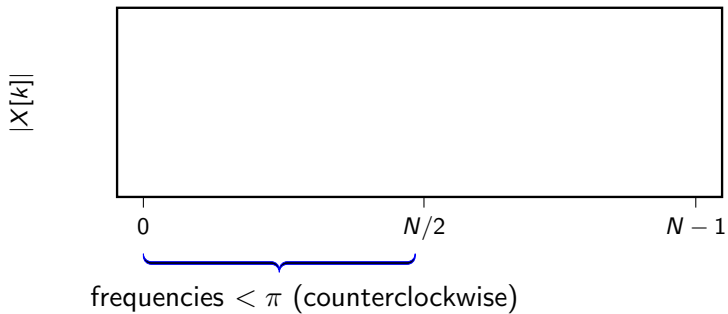
The DFT is an algorithm!

$$X[k] = \sum_{n=0}^{N-1} x[n] e^{-j\frac{2\pi}{N}nk}, \quad k = 0, 1, \dots, N-1$$

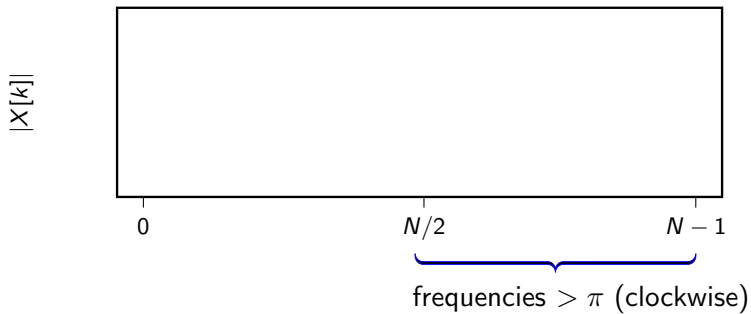
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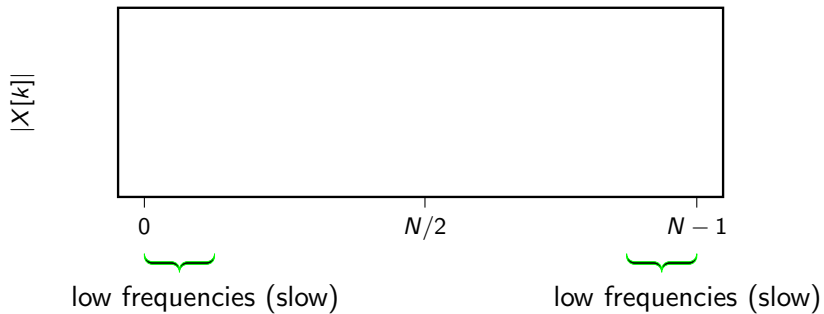
Interpreting a DFT plot



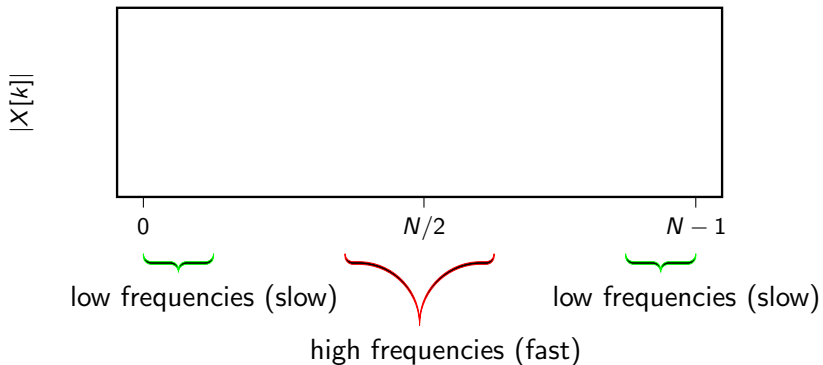
Interpreting a DFT plot



Interpreting a DFT plot

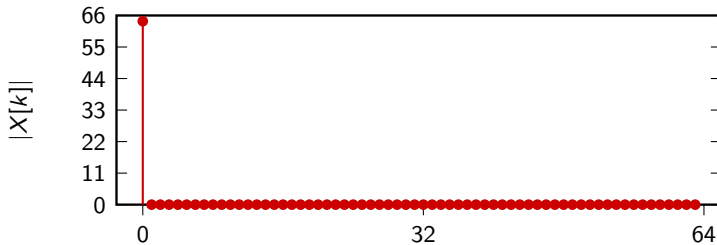


Interpreting a DFT plot



Interpreting a DFT plot

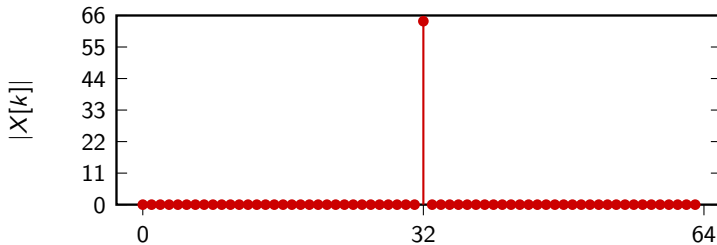
$x[n] = 1$ (slowest signal)



only lowest frequency

Interpreting a DFT plot

$$x[n] = \cos \pi n = (-1)^n \text{ (fastest signal)}$$



only highest frequency

Energy distribution

Recall Parseval's Theorem: $\|\mathbf{x}\|^2 = \sum |\alpha_k|^2$

$$\sum_{n=0}^{N-1} |x[n]|^2 = \frac{1}{N} \sum_{k=0}^{N-1} |X[k]|^2$$

square magnitude of k -th DFT coefficient
proportional to signal's energy at frequency $\omega = (2\pi/N)k$

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Energy distribution

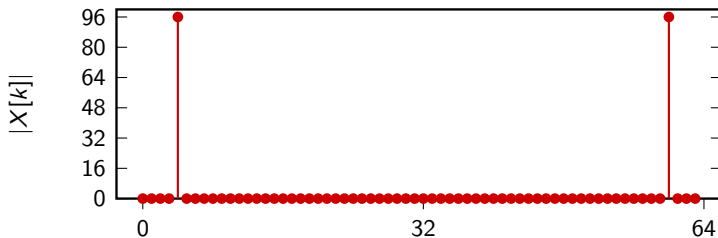
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Interpreting a DFT plot

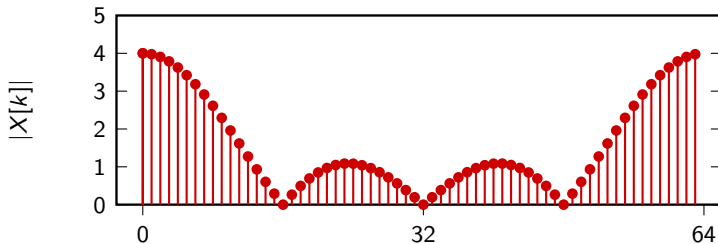
$$x[n] = 3 \cos(2\pi/16 n) \text{ (sinusoid)}$$



energy concentrated on single frequency
(counterclockwise and clockwise combine to give real signal)

Interpreting a DFT plot

$$x[n] = u[n] - u[n - 4] \text{ (step)}$$

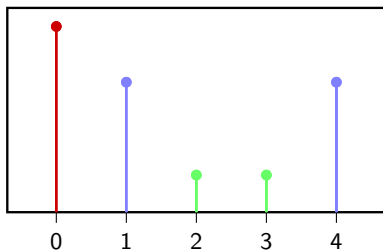


energy mostly in low frequencies

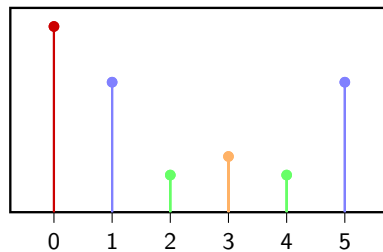
DFT of real signals

For real signals the DFT is “symmetric” in magnitude:

$$|X[k]| = |X[N - k]| \text{ for } k = 1, 2, \dots, \lfloor N/2 \rfloor$$



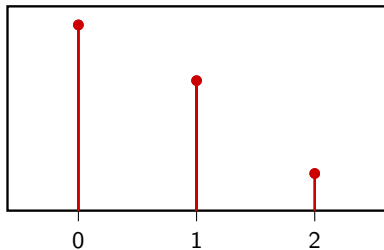
$N = 5$, odd length



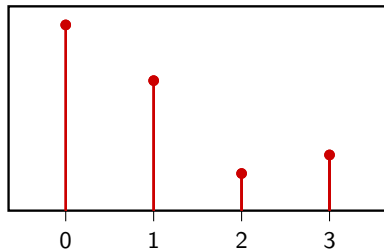
$N = 6$, even length

DFT of real signals

For real signals, magnitude plots need only $\lfloor N/2 \rfloor + 1$ points



$N = 5$, odd length



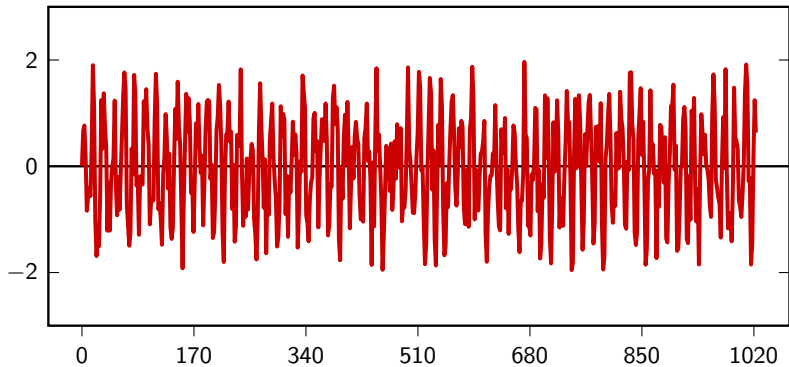
$N = 6$, even length

the DFT as an analysis tool

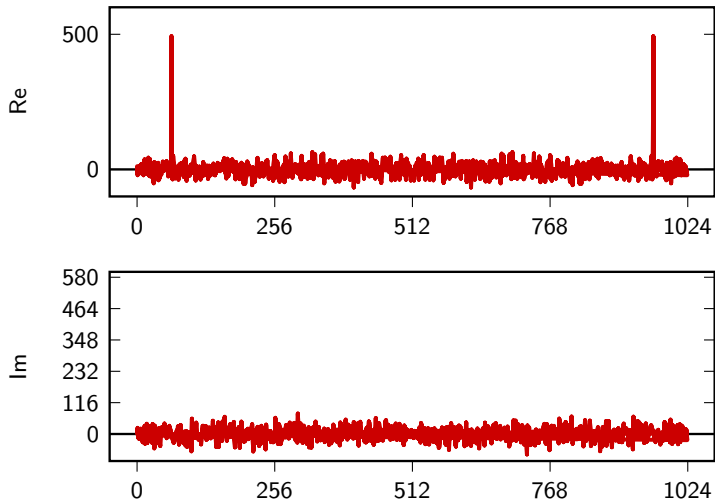
Overview

- ▶ DFT analysis examples
- ▶ Labeling the DFT axes

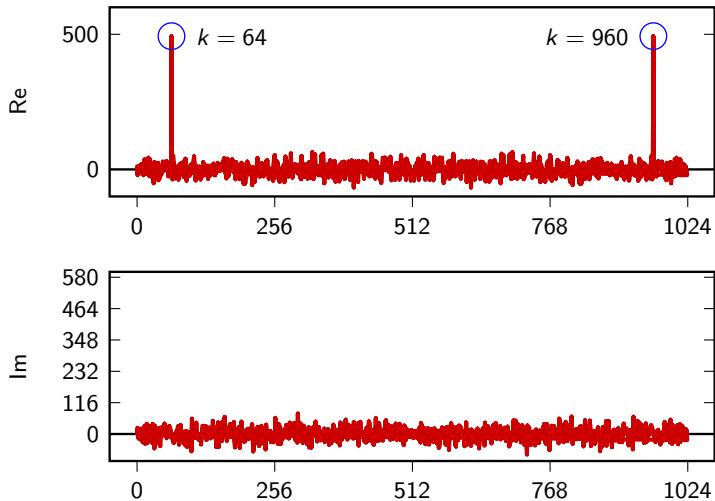
Mystery signal revisited



Mystery signal revisited



Mystery signal revisited



Mystery signal revisited

$$x[n] = \cos(\omega n + \phi) + \eta[n]$$

with

$$\begin{aligned}\phi &= 0 \\ \omega &= \frac{2\pi}{1024} 64\end{aligned}$$

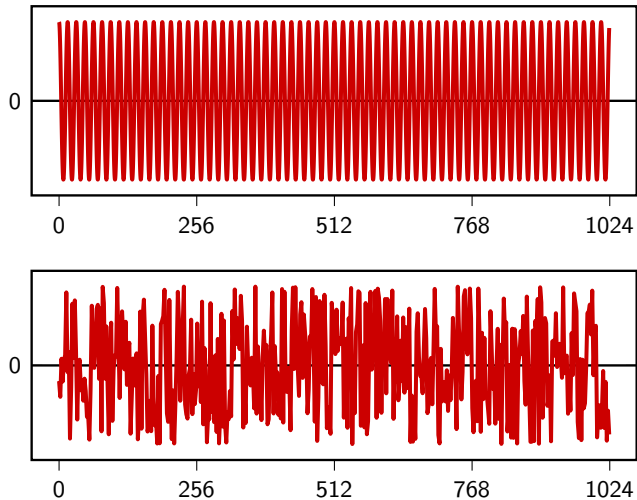
Mystery signal revisited

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Mystery signal unveiled



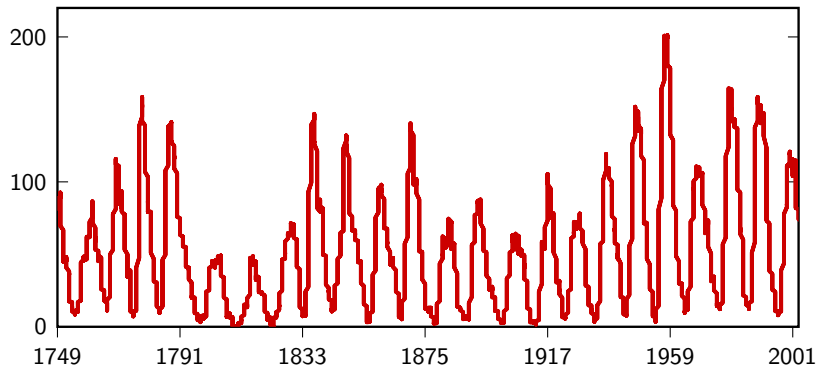
Solar spots

- ▶ sunspot number: $s = 10 \times \# \text{ of clusters} + \# \text{ of spots}$
- ▶ data set from 1749 to 2003, 2904 months

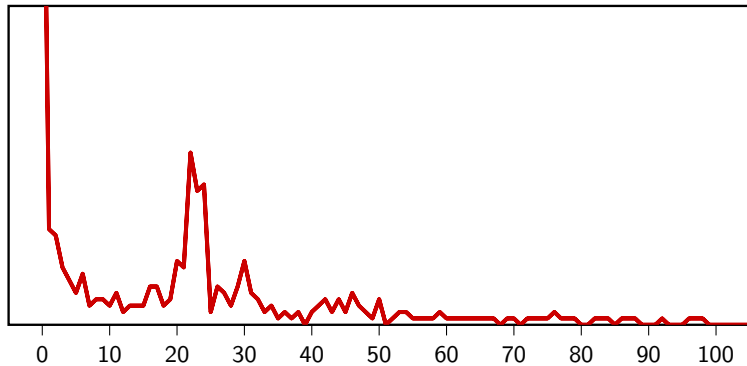
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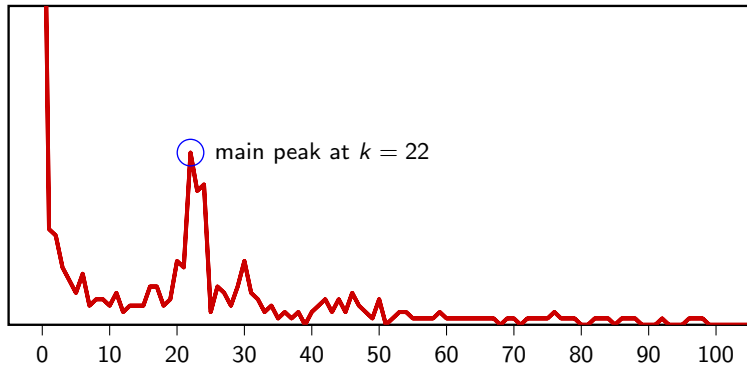
Solar spots



Solar spots



Solar spots



Solar spots

- ▶ DFT main peak for $k = 22$
- ▶ 22 cycles over 2904 months
- ▶ period: $\frac{2904}{22} \approx 11$ years

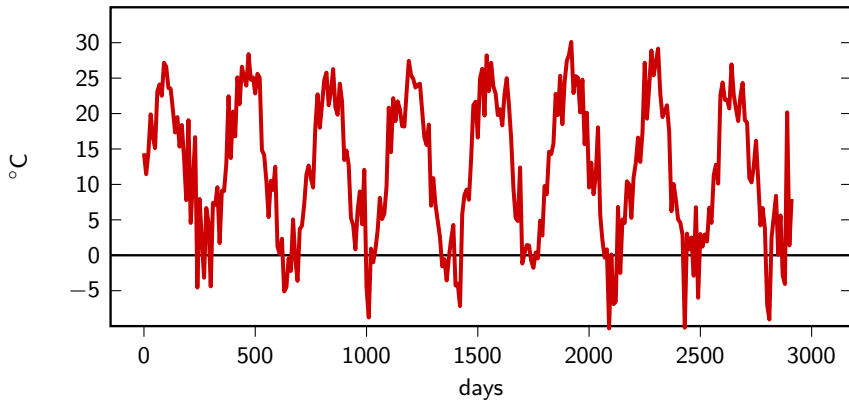
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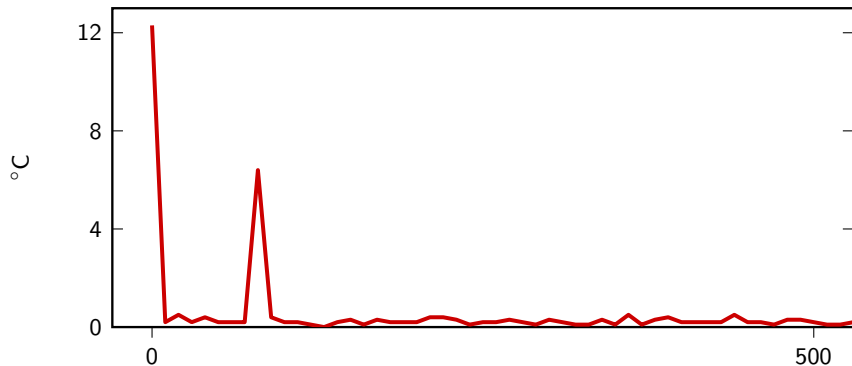
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Daily temperature (2920 days)

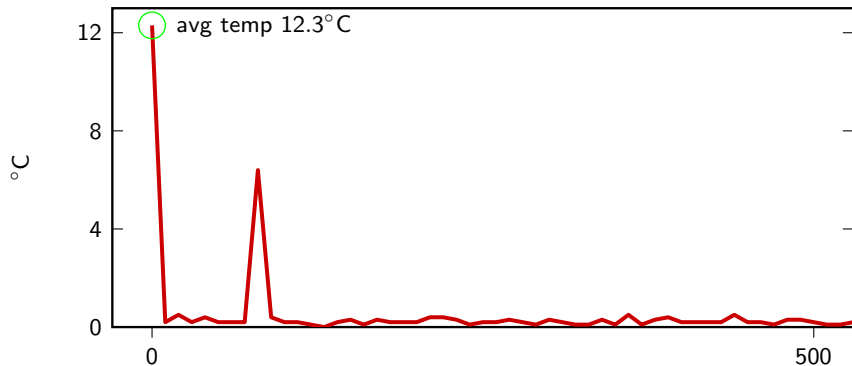


Daily temperature: DFT



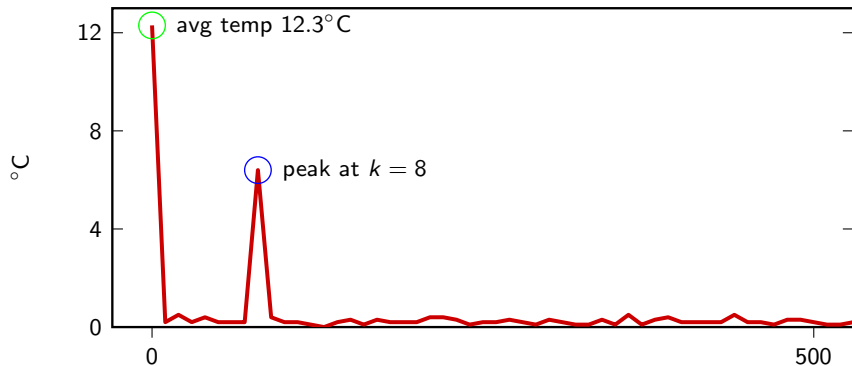
first few hundred DFT coefficients
(in magnitude and normalized by the length of the temperature vector)

Daily temperature: DFT



first few hundred DFT coefficients
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Daily temperature: DFT



first few hundred DFT coefficients
(in magnitude and normalized by the length of the temperature vector)

Daily temperature

- ▶ average value (0-th DFT coefficient): 12.3°C
- ▶ DFT main peak for $k = 8$, value 6.4°C
- ▶ 8 cycles over 2920 days
- ▶ period: $\frac{2920}{8} = 365$ days
- ▶ temperature excursion: $12.3^{\circ}\text{C} \pm 12.8^{\circ}\text{C}$

Daily temperature

In case you're wondering why $\pm 12.8^\circ$:

$$\text{DFT} \left\{ A \cos \left(\frac{2\pi}{N} M n \right) \right\} [k] = \begin{cases} \frac{A}{2} N & \text{for } k = M, N - M \\ 0 & \text{otherwise} \end{cases}$$

Labeling the frequency axis

If we know the “clock” of the system T_s (or its frequency F_s)

- ▶ fastest (positive) frequency is $\omega = \pi$
- ▶ sinusoid at $\omega = \pi$ needs two samples to do a full revolution
- ▶ time between samples: $T_s = 1/F_s$ seconds
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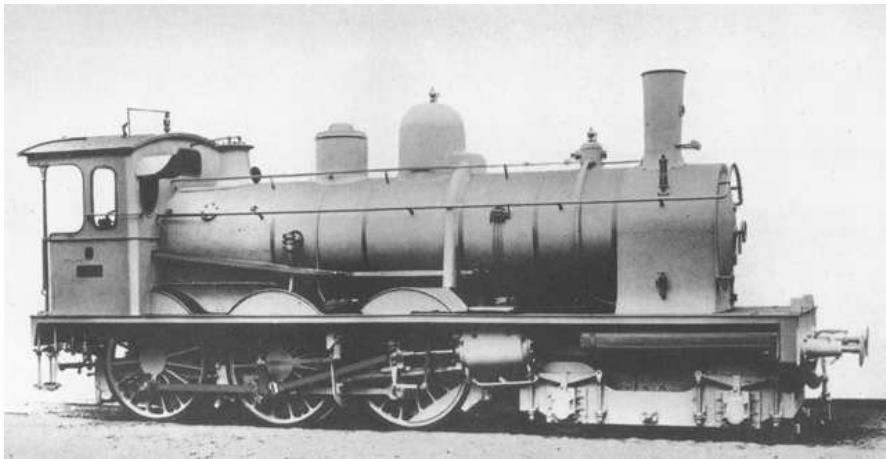
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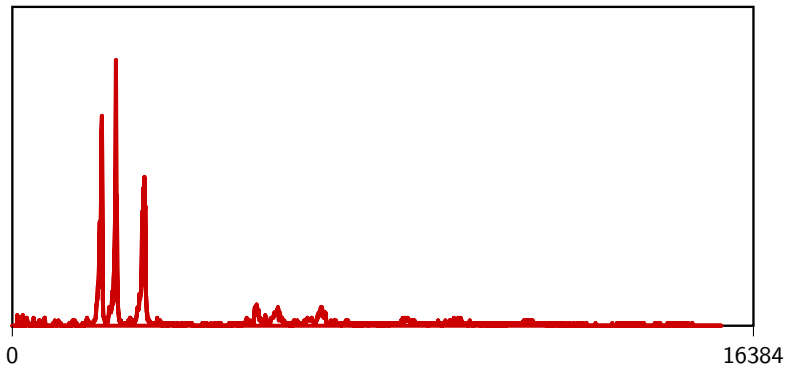
Example: train whistle



Play

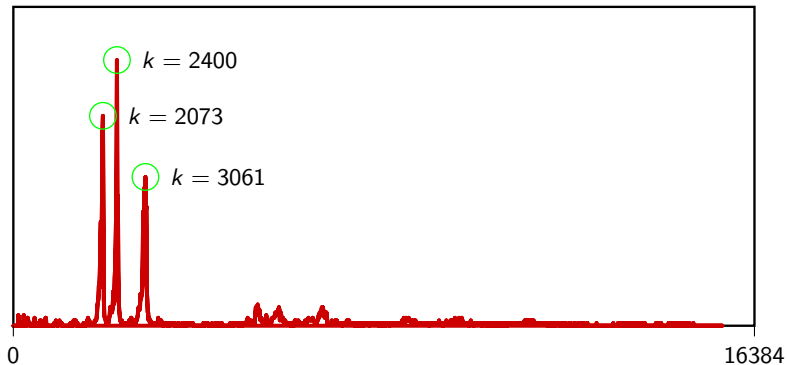
Example: train whistle

32768 samples (the “clock” of the system $F_s = 8000\text{Hz}$)



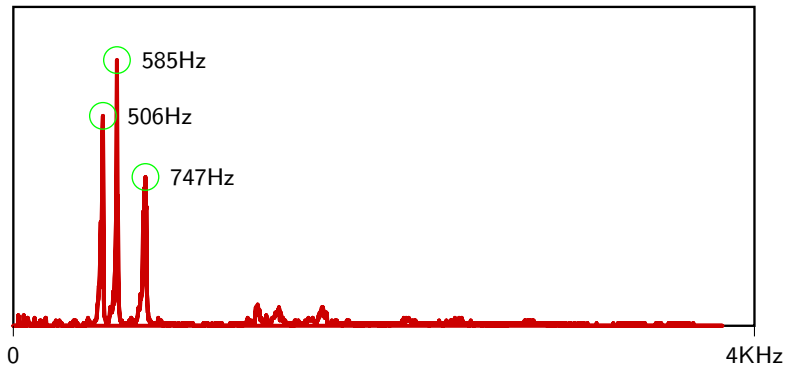
Example: train whistle

32768 samples (the “clock” of the system $F_s = 8000\text{Hz}$)



Example: train whistle

the “clock” of the system $F_s = 8000\text{Hz}$



Example: train whistle

if we look up the frequencies:



B minor chord

the DFT as a synthesis tool

DFT formulas

Analysis formula:

$$X[k] = \sum_{n=0}^{N-1} x[n] e^{-j\frac{2\pi}{N}nk}, \quad k = 0, 1, \dots, N-1$$

N -point signal in the *frequency domain*

Synthesis formula:

$$x[n] = \frac{1}{N} \sum_{k=0}^{N-1} X[k] e^{j\frac{2\pi}{N}nk}, \quad n = 0, 1, \dots, N-1$$

N -point signal in the *“time” domain*

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N -point signal in the *frequency domain*

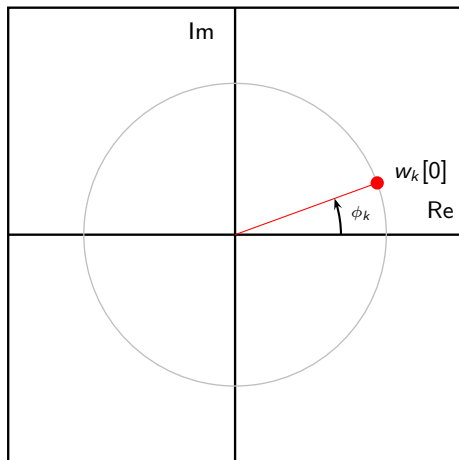
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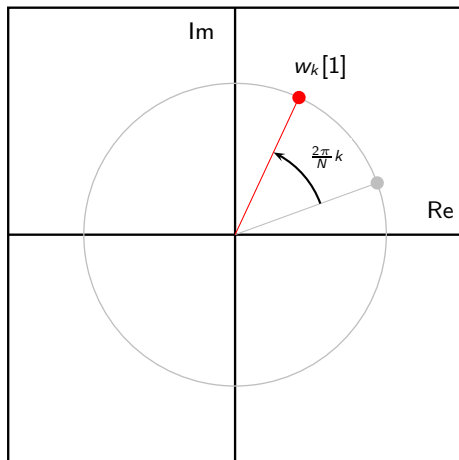
Synthesis: the sinusoidal generator

$$w_k[n] = e^{j(\frac{2\pi}{N}kn + \phi_k)}$$



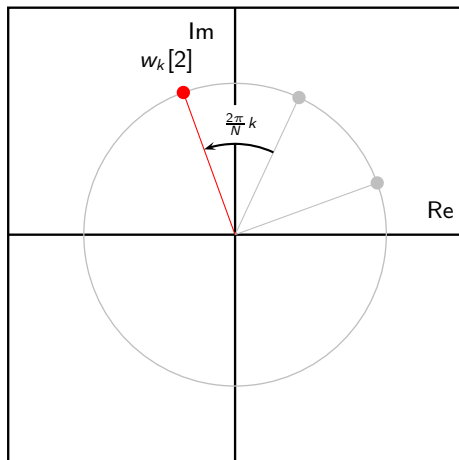
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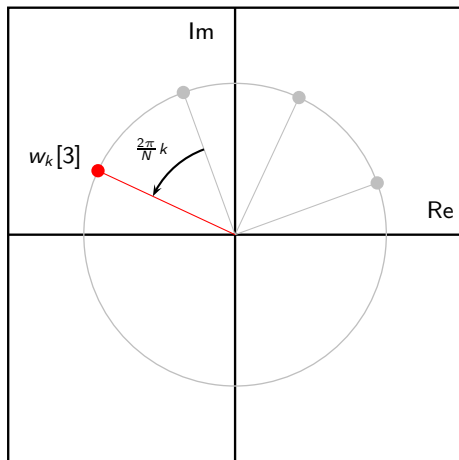
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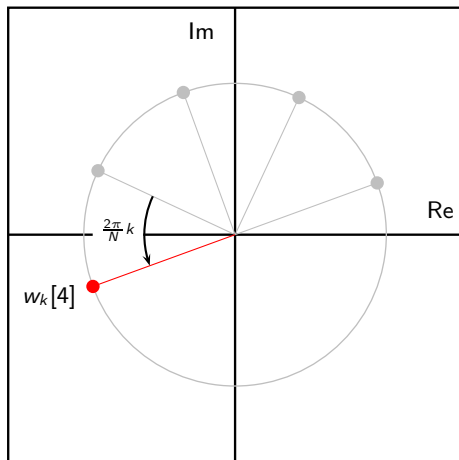
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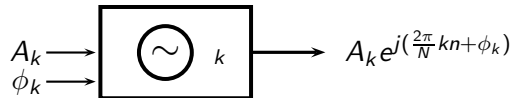


Synthesis: the sinusoidal generator

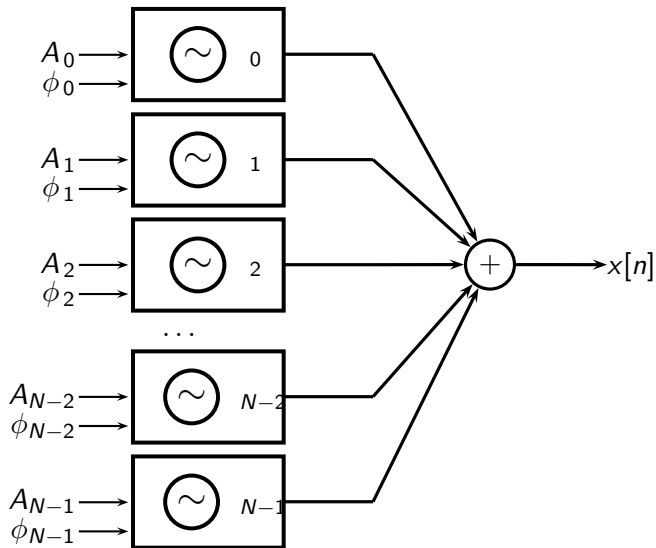
$$w_k[n] = e^{j(\frac{2\pi}{N}kn + \phi_k)}$$



Synthesis: the sinusoidal generator



DFT synthesis formula



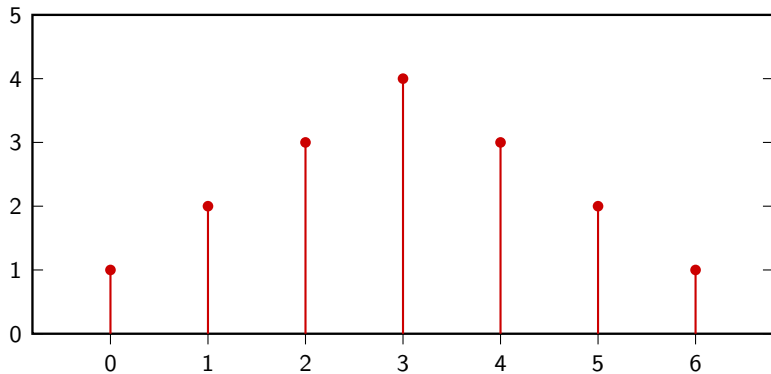
Initializing the machine

$$A_k = |X[k]|/N$$

$$\phi_k = \angle X[k]$$

Example

$$\mathbf{x} = [1 \ 2 \ 3 \ 4 \ 3 \ 2 \ 1]^T$$



Example

k	A_k	ϕ_k
0	2.2857	0.0000
1	0.7213	-2.6928
2	0.0440	0.8976
3	0.0919	-1.7952
4	0.0919	1.7952
5	0.0440	-0.8976
6	0.7213	2.6928

Example

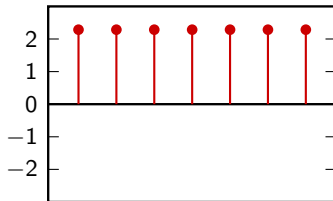
$$k = 0$$

$$A_k e^{j(\frac{2\pi}{N}kn + \phi_k)}$$

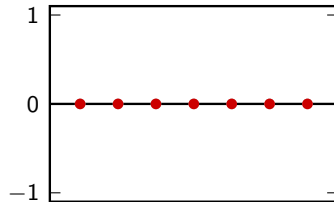
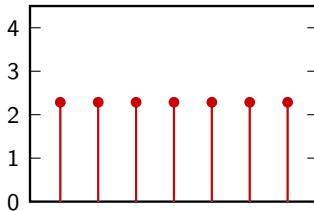
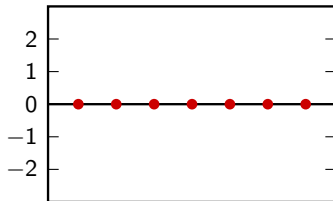
$$A_0 = 2.28, \phi_0 = 0$$

$$\sum_{k=0}^0 A_k e^{j(\frac{2\pi}{N}kn + \phi_k)}$$

Re



Im



Example

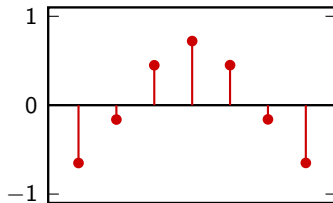
$$k = 1$$

$$A_k e^{j(\frac{2\pi}{N}kn + \phi_k)}$$

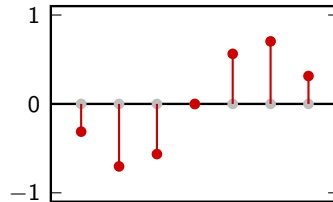
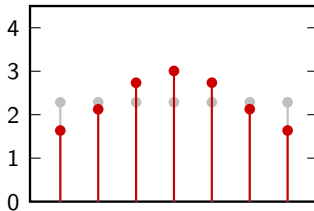
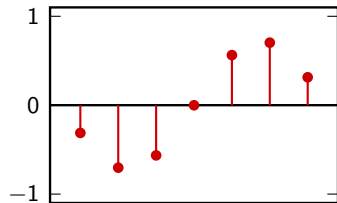
$$A_1 = 0.72, \phi_1 = -2.69$$

$$\sum_{k=0}^1 A_k e^{j(\frac{2\pi}{N}kn + \phi_k)}$$

Re



Im



Example

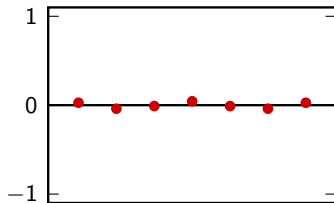
$$k = 2$$

$$A_k e^{j(\frac{2\pi}{N}kn + \phi_k)}$$

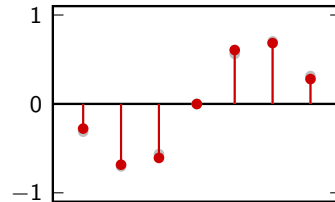
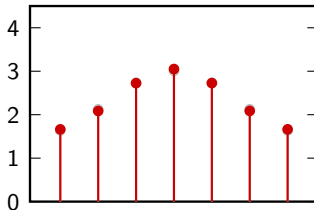
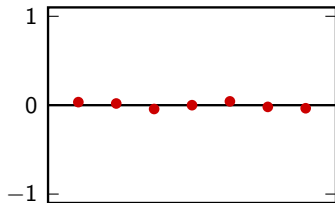
$$A_2 = 0.04, \phi_2 = 0.89$$

$$\sum_{k=0}^2 A_k e^{j(\frac{2\pi}{N}kn + \phi_k)}$$

Re



Im



Example

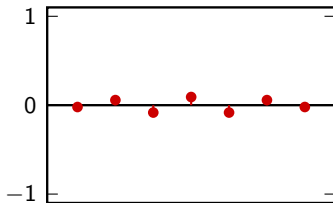
$$k = 3$$

$$A_k e^{j(\frac{2\pi}{N}kn + \phi_k)}$$

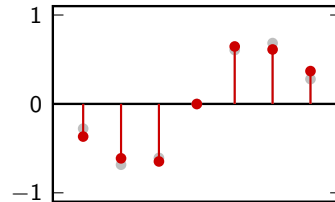
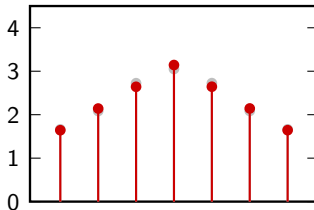
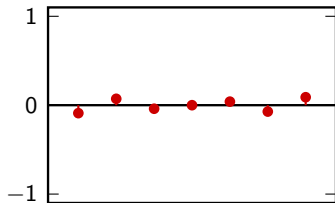
$$A_3 = 0.09, \phi_3 = -1.79$$

$$\sum_{k=0}^3 A_k e^{j(\frac{2\pi}{N}kn + \phi_k)}$$

Re



Im



Example

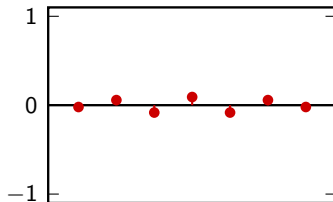
$$k = 4$$

$$A_k e^{j(\frac{2\pi}{N}kn + \phi_k)}$$

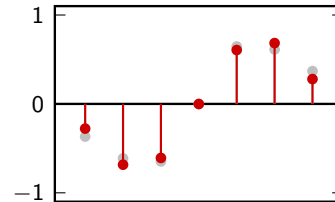
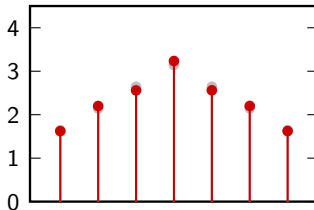
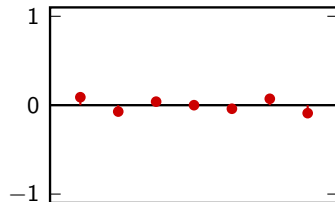
$$A_4 = 0.09, \phi_4 = 1.79$$

$$\sum_{k=0}^4 A_k e^{j(\frac{2\pi}{N}kn + \phi_k)}$$

Re



Im



Example

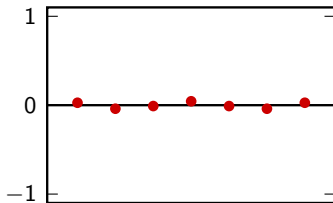
$$k = 5$$

$$A_k e^{j(\frac{2\pi}{N}kn + \phi_k)}$$

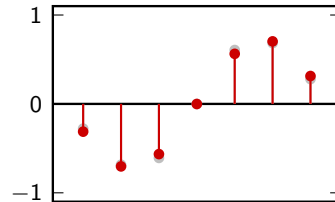
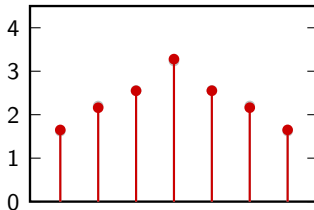
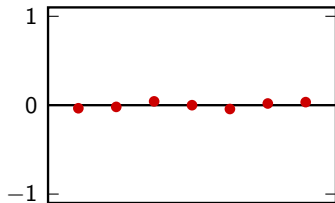
$$A_5 = 0.04, \phi_5 = -0.89$$

$$\sum_{k=0}^5 A_k e^{j(\frac{2\pi}{N}kn + \phi_k)}$$

Re



Im



Example

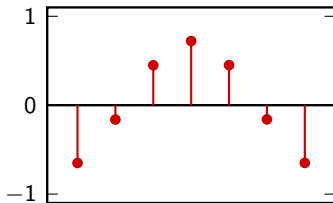
$$k = 6$$

$$A_k e^{j(\frac{2\pi}{N}kn + \phi_k)}$$

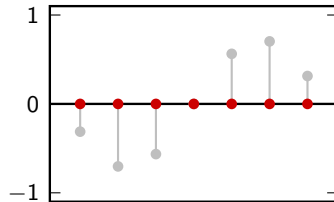
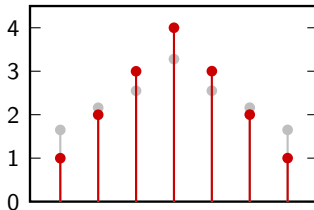
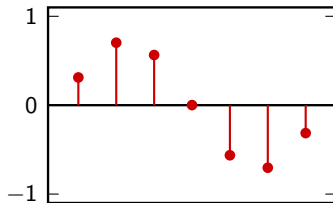
$$A_6 = 0.72, \phi_6 = 2.69$$

$$\sum_{k=0}^6 A_k e^{j(\frac{2\pi}{N}kn + \phi_k)}$$

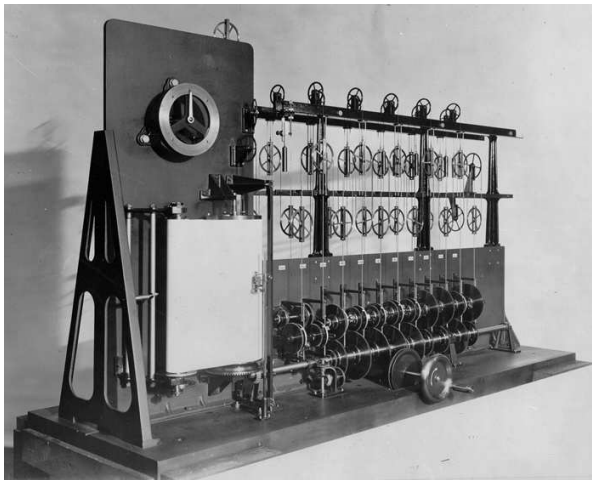
Re



Im



The machine before DSP



tide-predicting machine (originally invented by Lord Kelvin)

Wonderful website

<http://jackschaedler.github.io/circles-sines-signals>

Running the machine too long...

$$x[n + N] = x[n]$$

output signal is N -periodic!

Inherent periodicities in the DFT

the synthesis formula:

$$x[n] = \frac{1}{N} \sum_{k=0}^{N-1} X[k] e^{j\frac{2\pi}{N}nk}, \quad n = 0, 1, \dots, N-1$$

produces an N -point signal in the time domain

the analysis formula:

$$X[k] = \sum_{n=0}^{N-1} x[n] e^{-j\frac{2\pi}{N}nk}, \quad k = 0, 1, \dots, N-1$$

produces an N -point signal in the frequency domain

Inherent periodicities in the DFT

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$$x[n] = \frac{1}{N} \sum_{k=0}^{N-1} X[k] e^{j\frac{2\pi}{N}nk}, \quad n \in \mathbb{Z}$$

produces an ***N*-periodic** signal in the time domain

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$$X[k] = \sum_{n=0}^{N-1} x[n] e^{-j\frac{2\pi}{N}nk}, \quad k \in \mathbb{Z}$$

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Discrete Fourier Series (DFS)

DFS = DFT with periodicity explicit

- ▶ the DFS maps an N -periodic signal onto an N -periodic sequence of Fourier coefficients
- ▶ the inverse DFS maps an N -periodic sequence of Fourier coefficients a set onto an N -periodic signal
- ▶ the DFS of an N -periodic signal is mathematically equivalent to the DFT of one period

Finite-length time shifts revisited

The DFS helps us understand how to define time shifts for finite-length signals.

For an N -periodic sequence $\tilde{x}[n]$:

- ▶ $\tilde{x}[n - M]$ is well-defined for all $M \in \mathbb{N}$
- ▶ $\text{DFS} \{ \tilde{x}[n - M] \} = e^{-j\frac{2\pi}{N}Mk} \tilde{X}[k]$ (easy derivation)
- ▶ $\text{IDFS} \{ \tilde{X}[k] \} = \tilde{x}[n - M]$

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 a delay in time becomes a *linear phase* factor in frequency

Finite-length time shifts revisited

For an N -point signal $x[n]$:

► $x[n - M]$ is *not* well-defined

► what is IDFT $\left\{ e^{-j\frac{2\pi}{N}Mk} X[k] \right\}$?

Finite-length time shifts revisited

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Finite-length time shifts revisited

$$\begin{aligned}\text{IDFT} \left\{ e^{-j\frac{2\pi}{N}Mk} X[k] \right\} [n] &= \frac{1}{N} \sum_{k=0}^{N-1} X[k] e^{-j\frac{2\pi}{N}Mk} e^{j\frac{2\pi}{N}nk} \\ &= \frac{1}{N} \sum_{k=0}^{N-1} \left(\sum_{m=0}^{N-1} x[m] e^{-j\frac{2\pi}{N}mk} \right) e^{-j\frac{2\pi}{N}Mk} e^{j\frac{2\pi}{N}nk} \\ &= \frac{1}{N} \sum_{m=0}^{N-1} x[m] \sum_{k=0}^{N-1} e^{j\frac{2\pi}{N}(n-M-m)k}\end{aligned}$$

Finite-length time shifts revisited

$$\begin{aligned}\text{IDFT} \left\{ e^{-j\frac{2\pi}{N}Mk} X[k] \right\} [n] &= \frac{1}{N} \sum_{k=0}^{N-1} X[k] e^{-j\frac{2\pi}{N}Mk} e^{j\frac{2\pi}{N}nk} \\ &= \frac{1}{N} \sum_{k=0}^{N-1} \left(\sum_{m=0}^{N-1} x[m] e^{-j\frac{2\pi}{N}mk} \right) e^{-j\frac{2\pi}{N}Mk} e^{j\frac{2\pi}{N}nk} \\ &= \frac{1}{N} \sum_{m=0}^{N-1} x[m] \sum_{k=0}^{N-1} e^{j\frac{2\pi}{N}(n-M-m)k}\end{aligned}$$

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We've seen something like this before...

$$\sum_{n=0}^{N-1} e^{-j\frac{2\pi}{N}nk} = \begin{cases} N & \text{if } k \text{ multiple of } N \\ 0 & \text{otherwise} \end{cases}$$

(remember the orthogonality proof for the DFT basis)

Finite-length time shifts revisited

$$\sum_{k=0}^{N-1} e^{j\frac{2\pi}{N}((n-M)-m)k} = \begin{cases} N & \text{for } ((n-M) - m) \text{ multiple of } N \\ 0 & \text{otherwise} \end{cases}$$

is there an m such that $0 \leq m < N$ and $((n-M) - m)$ multiple of N ?

Finite-length time shifts revisited

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Modulo operator

given $C \in \mathbb{N}$, find m such that $0 \leq m < N$ and $C - m$ is a multiple of N

any integer C can be written as $C = pN + (C \bmod N)$, $p \in \mathbb{N}$:

- ▶ $0 \leq (C \bmod N) < N$
- ▶ $C - (C \bmod N)$ is a multiple of N

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Finite-length time shifts revisited

$$\sum_{k=0}^{N-1} e^{j\frac{2\pi}{N}(n-M-m)k} = \begin{cases} N & \text{for } m = (n - M) \bmod N \\ 0 & \text{otherwise} \end{cases}$$

$$\begin{aligned} \text{IDFT} \left\{ e^{-j\frac{2\pi}{N}Mk} X[k] \right\} [n] &= \frac{1}{N} \sum_{m=0}^{N-1} x[m] \sum_{k=0}^{N-1} e^{j\frac{2\pi}{N}(n-M-m)k} \\ &= x[(n - M) \bmod N] \end{aligned}$$

shifts for finite-length signals are “naturally” circular

Finite-length time shifts revisited

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