

Lecture 2. Computational methods

Markov Chain Monte Carlo

7.04.2025-8.04.2025 Instructors: Alina Bazarova, Jose Robledo

Why computational methods?

Recall that in our target formula for posterior $p(\theta | x) = \frac{p(\theta)p(x | \theta)}{\int_{\mathbb{R}} p(\theta)p(x | \theta)d\theta}$

where θ are our parameters. The **integral** below can get **really nasty**!

BUT: this integral is just a constant! Rewrite $p(\theta | x) = \frac{1}{Z}p(x, \theta)$, where Z is just a normalising constant, although possibly varying over a large range.

What to do?

Markov Chain Monte Carlo (MCMC) algorithm

Monte Carlo integration.

Assume we want to compute $E f(\theta | X) = \frac{\int f(\theta) p(\theta) p(X | \theta) d\theta}{\int p(\theta) p(X | \theta) d\theta}$

where f is some function of parameters θ given the data X .

Markov Chain Monte Carlo (MCMC) algorithm

Monte Carlo integration.

Assume we want to compute $E f(\theta | X) = \frac{\int f(\theta) p(\theta) p(X | \theta) d\theta}{\int p(\theta) p(X | \theta) d\theta}$

where f is some function of parameters θ given the data X .

Monte Carlo integration evaluates this integral by drawing **independent samples** $\{\theta_t, t = 1, \dots, n\}$ from posterior distribution $p(\theta | X)$

Markov Chain Monte Carlo (MCMC) algorithm

Monte Carlo integration.

Assume we want to compute $E f(\theta | X) = \frac{\int f(\theta) p(\theta) p(X | \theta) d\theta}{\int p(\theta) p(X | \theta) d\theta}$

where f is some function of parameters θ given the data X .

Monte Carlo integration evaluates this integral by drawing **independent samples** $\{\theta_t, t = 1, \dots, n\}$ from posterior distribution $p(\theta | X)$ and then approximating $E f(\theta | X) \approx \frac{1}{n} \sum_{t=1}^n f(\theta_t)$

Markov Chain Monte Carlo (MCMC) algorithm

Monte Carlo integration.

Assume we want to compute $E f(\theta | X) = \frac{\int f(\theta) p(\theta) p(X | \theta) d\theta}{\int p(\theta) p(X | \theta) d\theta}$

where f is some function of parameters θ given the data X .

Monte Carlo integration evaluates this integral by drawing **independent samples** $\{\theta_t, t = 1, \dots, n\}$ from posterior distribution $p(\theta | X)$ and then approximating $E f(\theta | X) \approx \frac{1}{n} \sum_{t=1}^n f(\theta_t)$

(law of large numbers)

Markov Chain Monte Carlo (MCMC) algorithm

However:

1. $p(\theta | X)$ can be non-standard, and hence sampling independently from it would not be feasible.

Markov Chain Monte Carlo (MCMC) algorithm

However:

1. $p(\theta | X)$ can be non-standard, and hence sampling independently from it would not be feasible.
2. Good news: $\{\theta_t\}$ does not necessarily need to be independent. One of the ways of tackling the above problem is to

Markov Chain Monte Carlo (MCMC) algorithm

However:

1. $p(\theta | X)$ can be non-standard, and hence sampling independently from it would not be feasible.
2. Good news: $\{\theta_t\}$ does not necessarily need to be independent. One of the ways of tackling the above problem is to do it through a Markov chain having $p(\theta | X)$ as its stationary distribution.

This is called Markov chain Monte Carlo.

MCMC algorithm II

Markov chain. Suppose we generate a sequence of random variables $\{\theta_0, \theta_1, \dots\}$.

MCMC algorithm II

Markov chain. Suppose we generate a sequence of random variables $\{\theta_0, \theta_1, \dots\}$.

Each time $t \geq 0$ the next state θ_{t+1} is sampled from a distribution $P(\theta_{t+1} \mid \theta_t)$, which depends **only on the current state of the chain** θ_t and does not depend on its history $\{\theta_0, \dots, \theta_{t-1}\}$.

MCMC algorithm II

Markov chain. Suppose we generate a sequence of random variables $\{\theta_0, \theta_1, \dots\}$.

Each time $t \geq 0$ the next state θ_{t+1} is sampled from a distribution $P(\theta_{t+1} | \theta_t)$, which depends **only on the current state of the chain** θ_t and does not depend on its history $\{\theta_0, \dots, \theta_{t-1}\}$.

Subject to certain conditions the chain will gradually “**forget**” **its initial state** θ_0 and the distribution $P(\theta_t | \theta_0)$ will not depend on t or θ_0 and converge to a unique stationary distribution

MCMC algorithm II

Markov chain. Suppose we generate a sequence of random variables $\{\theta_0, \theta_1, \dots\}$.

Each time $t \geq 0$ the next state θ_{t+1} is sampled from a distribution $P(\theta_{t+1} | \theta_t)$, which depends **only on the current state of the chain** θ_t and does not depend on its history $\{\theta_0, \dots, \theta_{t-1}\}$.

Subject to certain conditions the chain will gradually “**forget**” **its initial state** θ_0 and the distribution $P(\theta_t | \theta_0)$ will not depend on t or θ_0 and converge to a unique stationary distribution

Hence, after **sufficiently long burn-in** of m iterations points of $\{\theta_t, t = m + 1, \dots, n\}$ will be samples from the stationary distribution and the desired integral can be re-written as

MCMC algorithm II

Markov chain. Suppose we generate a sequence of random variables $\{\theta_0, \theta_1, \dots\}$.

Each time $t \geq 0$ the next state θ_{t+1} is sampled from a distribution $P(\theta_{t+1} | \theta_t)$, which depends **only on the current state of the chain** θ_t and does not depend on its history $\{\theta_0, \dots, \theta_{t-1}\}$.

Subject to certain conditions the chain will gradually “**forget**” its **initial state** θ_0 and the distribution $P(\theta_t | \theta_0)$ will not depend on t or θ_0 and converge to a unique stationary distribution

Hence, after **sufficiently long burn-in** of m iterations points of $\{\theta_t, t = m + 1, \dots, n\}$ will be samples from the stationary distribution and the desired integral can be re-written as

$$E f(\theta | X) \approx \frac{1}{n - m} \sum_{t=m+1}^n f(\theta_t)$$

MCMC algorithm II

Markov chain. Suppose we generate a sequence of random variables $\{\theta_0, \theta_1, \dots\}$.

Each time $t \geq 0$ the next state θ_{t+1} is sampled from a distribution $P(\theta_{t+1} | \theta_t)$, which depends **only on the current state of the chain** θ_t and does not depend on its history $\{\theta_0, \dots, \theta_{t-1}\}$.

Subject to certain conditions the chain will gradually “**forget**” its **initial state** θ_0 and the distribution $P(\theta_t | \theta_0)$ will not depend on t or θ_0 and converge to a unique stationary distribution

Hence, after **sufficiently long burn-in** of m iterations points of $\{\theta_t, t = m + 1, \dots, n\}$ will be samples from the stationary distribution and the desired integral can be re-written as

$$E f(\theta | X) \approx \frac{1}{n - m} \sum_{t=m+1}^n f(\theta_t)$$

Important: We can construct an MCMC algorithm which will have $p(\theta | X)$ as the stationary distribution!

Metropolis-Hastings sampler

At each time t the next state θ_{t+1} is chosen by first sampling a candidate Y from a ***proposal*** distribution $q(\cdot | \theta_t)$ which **depends only on the current state θ_t** (or not even that)

Metropolis-Hastings sampler

At each time t the next state θ_{t+1} is chosen by first sampling a candidate Y from a ***proposal*** distribution $q(\cdot | \theta_t)$ which **depends only on the current state** θ_t (or not even that)

Candidate Y is then accepted to be the next state of the chain with probability $\alpha(\theta_t, Y)$,
where $\alpha(\theta, Y) = \min \left(1, \frac{p(Y)p(X|Y)q(\theta|Y)}{p(\theta)p(X|\theta)q(Y|\theta)} \right)$.

Metropolis-Hastings sampler

At each time t the next state θ_{t+1} is chosen by first sampling a candidate Y from a ***proposal*** distribution $q(\cdot | \theta_t)$ which **depends only on the current state** θ_t (or not even that)

Candidate Y is then accepted to be the next state of the chain with probability $\alpha(\theta_t, Y)$,
where $\alpha(\theta, Y) = \min \left(1, \frac{p(Y)p(X|Y)q(\theta|Y)}{p(\theta)p(X|\theta)q(Y|\theta)} \right)$.

Now denote $\pi(\theta) = p(\theta | X)$

Metropolis-Hastings sampler

At each time t the next state θ_{t+1} is chosen by first sampling a candidate Y from a ***proposal*** distribution $q(\cdot | \theta_t)$ which **depends only on the current state** θ_t (or not even that)

Candidate Y is then accepted to be the next state of the chain with probability $\alpha(\theta_t, Y)$,
where $\alpha(\theta, Y) = \min \left(1, \frac{p(Y)p(X|Y)q(\theta|Y)}{p(\theta)p(X|\theta)q(Y|\theta)} \right)$.

Now denote $\pi(\theta) = p(\theta | X) = \frac{p(\theta)p(X|\theta)}{\int p(\theta)p(X|\theta)d\theta}$

$$P(\theta_{t+1} | \theta_t) = q(\theta_{t+1} | \theta_t)\alpha(\theta_t, \theta_{t+1}) + I(\theta_{t+1} = \theta_t)[1 - \int q(Y | \theta_t)\alpha(\theta_t, Y)dY] \quad (1)$$

Metropolis-Hastings sampler

At each time t the next state θ_{t+1} is chosen by first sampling a candidate Y from a **proposal** distribution $q(\cdot | \theta_t)$ which **depends only on the current state** θ_t (or not even that)

Candidate Y is then accepted to be the next state of the chain with probability $\alpha(\theta_t, Y)$,
where $\alpha(\theta, Y) = \min \left(1, \frac{p(Y)p(X|Y)q(\theta|Y)}{p(\theta)p(X|\theta)q(Y|\theta)} \right)$.

Now denote $\pi(\theta) = p(\theta | X) = \frac{p(\theta)p(X|\theta)}{\int p(\theta)p(X|\theta)d\theta}$

$$P(\theta_{t+1} | \theta_t) = q(\theta_{t+1} | \theta_t) \alpha(\theta_t, \theta_{t+1}) + I(\theta_{t+1} = \theta_t) \left[1 - \int q(Y | \theta_t) \alpha(\theta_t, Y) dY \right] \quad (1)$$

acceptance of candidate $Y = \theta_{t+1}$

Metropolis-Hastings sampler

At each time t the next state θ_{t+1} is chosen by first sampling a candidate Y from a **proposal** distribution $q(\cdot | \theta_t)$ which **depends only on the current state** θ_t (or not even that)

Candidate Y is then accepted to be the next state of the chain with probability $\alpha(\theta_t, Y)$,
where $\alpha(\theta, Y) = \min \left(1, \frac{p(Y)p(X|Y)q(\theta|Y)}{p(\theta)p(X|\theta)q(Y|\theta)} \right)$.

Now denote $\pi(\theta) = p(\theta | X) = \frac{p(\theta)p(X|\theta)}{\int p(\theta)p(X|\theta)d\theta}$

$$P(\theta_{t+1} | \theta_t) = q(\theta_{t+1} | \theta_t)\alpha(\theta_t, \theta_{t+1}) + I(\theta_{t+1} = \theta_t)[1 - \int q(Y | \theta_t)\alpha(\theta_t, Y)dY] \quad (1)$$

acceptance of candidate $Y = \theta_{t+1}$

rejection of all possible candidates Y

Metropolis-Hastings sampler II

Recall $\alpha(\theta, Y) = \min \left(1, \frac{\pi(Y)q(\theta | Y)}{\pi(\theta)q(Y | \theta)} \right)$, and hence

$$\pi(\theta_t)q(\theta_{t+1} | \theta_t)\alpha(\theta_t, \theta_{t+1}) = \pi(\theta_{t+1})q(\theta_t | \theta_{t+1})\alpha(\theta_{t+1}, \theta_t) \quad (2)$$

Metropolis-Hastings sampler II

Recall $\alpha(\theta, Y) = \min \left(1, \frac{\pi(Y)q(\theta | Y)}{\pi(\theta)q(Y | \theta)} \right)$, and hence

$$\pi(\theta_t)q(\theta_{t+1} | \theta_t)\alpha(\theta_t, \theta_{t+1}) = \pi(\theta_{t+1})q(\theta_t | \theta_{t+1})\alpha(\theta_{t+1}, \theta_t) \quad (2)$$

Hint: one of the α s in the equality above is equal to 1. Moreover, multiply (1) by $\pi(\theta_t)$

Metropolis-Hastings sampler II

Recall $\alpha(\theta, Y) = \min \left(1, \frac{\pi(Y)q(\theta | Y)}{\pi(\theta)q(Y | \theta)} \right)$, and hence

$$\pi(\theta_t)q(\theta_{t+1} | \theta_t)\alpha(\theta_t, \theta_{t+1}) = \pi(\theta_{t+1})q(\theta_t | \theta_{t+1})\alpha(\theta_{t+1}, \theta_t) \quad (2)$$

Hint: one of the α s in the equality above is equal to 1. Moreover, multiply (1) by $\pi(\theta_t)$

$$\pi(\theta_t)P(\theta_{t+1} | \theta_t) = \pi(\theta_t)q(\theta_{t+1} | \theta_t)\alpha(\theta_t, \theta_{t+1}) + \pi(\theta_t)I(\theta_{t+1} = \theta_t)[1 - \int q(Y | \theta_t)\alpha(\theta_t, Y)dY] \quad (3)$$

Metropolis-Hastings sampler II

Recall $\alpha(\theta, Y) = \min \left(1, \frac{\pi(Y)q(\theta | Y)}{\pi(\theta)q(Y | \theta)} \right)$, and hence

$$\pi(\theta_t)q(\theta_{t+1} | \theta_t)\alpha(\theta_t, \theta_{t+1}) = \pi(\theta_{t+1})q(\theta_t | \theta_{t+1})\alpha(\theta_{t+1}, \theta_t) \quad (2)$$

Hint: one of the α s in the equality above is equal to 1. Moreover, multiply (1) by $\pi(\theta_t)$

$$\pi(\theta_t)P(\theta_{t+1} | \theta_t) = \pi(\theta_t)q(\theta_{t+1} | \theta_t)\alpha(\theta_t, \theta_{t+1}) + \pi(\theta_t)I(\theta_{t+1} = \theta_t)[1 - \int q(Y | \theta_t)\alpha(\theta_t, Y)dY] \quad (3)$$

$$\pi(\theta_{t+1})P(\theta_t | \theta_{t+1}) = \pi(\theta_{t+1})q(\theta_t | \theta_{t+1})\alpha(\theta_{t+1}, \theta_t) + \pi(\theta_{t+1})I(\theta_{t+1} = \theta_t)[1 - \int q(Y | \theta_{t+1})\alpha(\theta_{t+1}, Y)dY] \quad (4)$$

Metropolis-Hastings sampler II

Recall $\alpha(\theta, Y) = \min \left(1, \frac{\pi(Y)q(\theta | Y)}{\pi(\theta)q(Y | \theta)} \right)$, and hence

$$\pi(\theta_t)q(\theta_{t+1} | \theta_t)\alpha(\theta_t, \theta_{t+1}) = \pi(\theta_{t+1})q(\theta_t | \theta_{t+1})\alpha(\theta_{t+1}, \theta_t) \quad (2)$$

Hint: one of the α s in the equality above is equal to 1. Moreover, multiply (1) by $\pi(\theta_t)$

$$\pi(\theta_t)P(\theta_{t+1} | \theta_t) = \pi(\theta_t)q(\theta_{t+1} | \theta_t)\alpha(\theta_t, \theta_{t+1}) + \pi(\theta_t)I(\theta_{t+1} = \theta_t)[1 - \int q(Y | \theta_t)\alpha(\theta_t, Y)dY] \quad (3)$$

$$\pi(\theta_{t+1})P(\theta_t | \theta_{t+1}) = \pi(\theta_{t+1})q(\theta_t | \theta_{t+1})\alpha(\theta_{t+1}, \theta_t) + \pi(\theta_{t+1})I(\theta_{t+1} = \theta_t)[1 - \int q(Y | \theta_{t+1})\alpha(\theta_{t+1}, Y)dY] \quad (4)$$

The first terms on the right-hand side of (3) and (4) are equal by (2), and the second ones by equality $\theta_t = \theta_{t+1}$, therefore

Metropolis-Hastings sampler II

Recall $\alpha(\theta, Y) = \min \left(1, \frac{\pi(Y)q(\theta | Y)}{\pi(\theta)q(Y | \theta)} \right)$, and hence

$$\pi(\theta_t)q(\theta_{t+1} | \theta_t)\alpha(\theta_t, \theta_{t+1}) = \pi(\theta_{t+1})q(\theta_t | \theta_{t+1})\alpha(\theta_{t+1}, \theta_t) \quad (2)$$

Hint: one of the α s in the equality above is equal to 1. Moreover, multiply (1) by $\pi(\theta_t)$

$$\pi(\theta_t)P(\theta_{t+1} | \theta_t) = \pi(\theta_t)q(\theta_{t+1} | \theta_t)\alpha(\theta_t, \theta_{t+1}) + \pi(\theta_t)I(\theta_{t+1} = \theta_t)[1 - \int q(Y | \theta_t)\alpha(\theta_t, Y)dY] \quad (3)$$

$$\pi(\theta_{t+1})P(\theta_t | \theta_{t+1}) = \pi(\theta_{t+1})q(\theta_t | \theta_{t+1})\alpha(\theta_{t+1}, \theta_t) + \pi(\theta_{t+1})I(\theta_{t+1} = \theta_t)[1 - \int q(Y | \theta_{t+1})\alpha(\theta_{t+1}, Y)dY] \quad (4)$$

The first terms on the left-hand side of (3) and (4) are equal by (2), and the second ones by equality $\theta_t = \theta_{t+1}$, therefore

$\pi(\theta_t)P(\theta_{t+1} | \theta_t) = \pi(\theta_{t+1})P(\theta_t | \theta_{t+1})$. Let us integrate both sides with respect to θ_t

Metropolis-Hastings sampler II

Recall $\alpha(\theta, Y) = \min \left(1, \frac{\pi(Y)q(\theta | Y)}{\pi(\theta)q(Y | \theta)} \right)$, and hence

$$\pi(\theta_t)q(\theta_{t+1} | \theta_t)\alpha(\theta_t, \theta_{t+1}) = \pi(\theta_{t+1})q(\theta_t | \theta_{t+1})\alpha(\theta_{t+1}, \theta_t) \quad (2)$$

Hint: one of the α s in the equality above is equal to 1. Moreover, multiply (1) by $\pi(\theta_t)$

$$\pi(\theta_t)P(\theta_{t+1} | \theta_t) = \pi(\theta_t)q(\theta_{t+1} | \theta_t)\alpha(\theta_t, \theta_{t+1}) + \pi(\theta_t)I(\theta_{t+1} = \theta_t)[1 - \int q(Y | \theta_t)\alpha(\theta_t, Y)dY] \quad (3)$$

$$\pi(\theta_{t+1})P(\theta_t | \theta_{t+1}) = \pi(\theta_{t+1})q(\theta_t | \theta_{t+1})\alpha(\theta_{t+1}, \theta_t) + \pi(\theta_{t+1})I(\theta_{t+1} = \theta_t)[1 - \int q(Y | \theta_{t+1})\alpha(\theta_{t+1}, Y)dY] \quad (4)$$

The first terms on the left-hand side of (3) and (4) are equal by (2), and the second ones by equality $\theta_t = \theta_{t+1}$, therefore

$\pi(\theta_t)P(\theta_{t+1} | \theta_t) = \pi(\theta_{t+1})P(\theta_t | \theta_{t+1})$. Let us integrate both sides with respect to θ_t

$$\int \pi(\theta_t)P(\theta_{t+1} | \theta_t)d\theta_t = \pi(\theta_{t+1}) \quad \textbf{Meaning:} \text{ if } \theta_t \text{ is from the distribution } \pi(.), \text{ then } \theta_{t+1} \text{ will be also.}$$

Metropolis-Hastings sampler II

Recall $\alpha(\theta, Y) = \min \left(1, \frac{\pi(Y)q(\theta | Y)}{\pi(\theta)q(Y | \theta)} \right)$, and hence

$$\pi(\theta_t)q(\theta_{t+1} | \theta_t)\alpha(\theta_t, \theta_{t+1}) = \pi(\theta_{t+1})q(\theta_t | \theta_{t+1})\alpha(\theta_{t+1}, \theta_t) \quad (2)$$

Hint: one of the α s in the equality above is equal to 1. Moreover, multiply (1) by $\pi(\theta_t)$

$$\pi(\theta_t)P(\theta_{t+1} | \theta_t) = \pi(\theta_t)q(\theta_{t+1} | \theta_t)\alpha(\theta_t, \theta_{t+1}) + \pi(\theta_t)I(\theta_{t+1} = \theta_t)[1 - \int q(Y | \theta_t)\alpha(\theta_t, Y)dY] \quad (3)$$

$$\pi(\theta_{t+1})P(\theta_t | \theta_{t+1}) = \pi(\theta_{t+1})q(\theta_t | \theta_{t+1})\alpha(\theta_{t+1}, \theta_t) + \pi(\theta_{t+1})I(\theta_{t+1} = \theta_t)[1 - \int q(Y | \theta_{t+1})\alpha(\theta_{t+1}, Y)dY] \quad (4)$$

The first terms on the left-hand side of (3) and (4) are equal by (2), and the second ones by equality $\theta_t = \theta_{t+1}$, therefore

$\pi(\theta_t)P(\theta_{t+1} | \theta_t) = \pi(\theta_{t+1})P(\theta_t | \theta_{t+1})$. Let us integrate both sides with respect to θ_t

$$\int \pi(\theta_t)P(\theta_{t+1} | \theta_t)d\theta_t = \pi(\theta_{t+1}) \quad \textbf{Meaning:}$$
 if θ_t is from the distribution $\pi(\cdot)$, then θ_{t+1} will be also.

Hence, once sample from stationary has been obtained, all subsequent samples are going to be from it. This means MCMC has converged. The period before convergence is called burn-in

Metropolis-Hastings: how it works in practice

1. Start at **current position** X .
2. Propose moving to a **new position** Y using proposal $q(Y|X)$
3. Accept/Reject the new position based on the position's adherence to the data and prior distributions using $\alpha(X, Y)$
 - If you accept: Move to the new position Y . Return to Step 1.
 - Else: Do not move to new position, stay at X . Return to Step 1.
4. After a large number of iterations, return **all accepted positions**.

Metropolis-Hastings sampler III

The natural question: **what should be the proposal distribution $q(Y | \theta)$?**

Metropolis-Hastings sampler III

The natural question: **what should be the proposal distribution $q(Y | \theta)$?**

1. The rate of convergence to the stationary distribution depends on it! And hence the **compute time**.

Metropolis-Hastings sampler III

The natural question: **what should be the proposal distribution $q(Y | \theta)$?**

1. The rate of convergence to the stationary distribution depends on it! And hence the **compute time**.
2. Even if the chain converged it may **mix** slowly (move around the states). And hence one needs to **run it for longer** to obtain **reliable estimates**.

Metropolis-Hastings sampler III

The natural question: **what should be the proposal distribution $q(Y | \theta)$?**

1. The rate of convergence to the stationary distribution depends on it! And hence the **compute time**.
2. Even if the chain converged it may **mix** slowly (move around the states). And hence one needs to **run it for longer** to obtain **reliable estimates**.
3. Proposal has to **explore the space efficiently**, sometimes it requires to perform experimentation and craftsmanship to construct a good one.

Jupyter notebook 2

Typical proposal distributions

Most typical one: **random walk**, $q(Y | \theta) = q(|Y - \theta|)$.

Typical proposal distributions

Most typical one: **random walk**, $q(Y | \theta) = q(|Y - \theta|)$.

Example: $Y \sim N(\theta_t, s)$, where N is a normal distribution and s is the custom standard deviation

Typical proposal distributions

Most typical one: **random walk**, $q(Y | \theta) = q(|Y - \theta|)$.

Example: $Y \sim N(\theta_t, s)$, where N is a normal distribution and s is the custom standard deviation

Important property: **acceptance rate** - how frequently the proposal gets accepted. Ideally should be 0.2-0.4

Typical proposal distributions

Most typical one: **random walk**, $q(Y | \theta) = q(|Y - \theta|)$.

Example: $Y \sim N(\theta_t, s)$, where N is a normal distribution and s is the custom standard deviation

Important property: **acceptance rate - how frequently the proposal gets accepted. Ideally should be 0.2-0.4**

This can be tuned during the **burn-in** period. In general:

Typical proposal distributions

Most typical one: **random walk**, $q(Y | \theta) = q(|Y - \theta|)$.

Example: $Y \sim N(\theta_t, s)$, where N is a normal distribution and s is the custom standard deviation

Important property: **acceptance rate - how frequently the proposal gets accepted. Ideally should be 0.2-0.4**

This can be tuned during the **burn-in** period. In general:

1. Acceptance **too high** -> chain mixes slowly. Acceptance **too low** -> chain stops moving.

Typical proposal distributions

Most typical one: **random walk**, $q(Y | \theta) = q(|Y - \theta|)$.

Example: $Y \sim N(\theta_t, s)$, where N is a normal distribution and s is the custom standard deviation

Important property: **acceptance rate - how frequently the proposal gets accepted. Ideally should be 0.2-0.4**

This can be tuned during the **burn-in** period. In general:

1. Acceptance **too high** -> chain mixes slowly. Acceptance **too low** -> chain stops moving.
2. **The larger the variance** of the proposal is the lower the acceptance rate is.

Typical proposal distributions

Most typical one: **random walk**, $q(Y | \theta) = q(|Y - \theta|)$.

Example: $Y \sim N(\theta_t, s)$, where N is a normal distribution and s is the custom standard deviation

Important property: **acceptance rate - how frequently the proposal gets accepted. Ideally should be 0.2-0.4**

This can be tuned during the **burn-in** period. In general:

1. Acceptance **too high** -> chain mixes slowly. Acceptance **too low** -> chain stops moving.
2. **The larger the variance** of the proposal is the lower the acceptance rate is.
3. This can be used during burn-in **to reach the desired acceptance** rate.

Single component MH and Gibbs sampler

Instead of updating θ *en bloc* it is often more convenient and computationally efficient to divide θ into components $\{\theta_1 \dots \theta_h\}$ and update them one by one.

Single component MH and Gibbs sampler

Instead of updating θ *en bloc* it is often more convenient and computationally efficient to divide θ into components $\{\theta_1 \dots \theta_h\}$ and update them one by one.

This means that instead of $q(Y | \theta)$ we will have $q(Y_i | \theta_{-i}, \theta_i)$, where $\theta_{-i} = \{\theta_1 \dots \theta_{i-1}, \theta_{i+1} \dots \theta_h\}$.

Single component MH and Gibbs sampler

Instead of updating θ *en bloc* it is often more convenient and computationally efficient to divide θ into components $\{\theta_1 \dots \theta_h\}$ and update them one by one.

This means that instead of $q(Y | \theta)$ we will have $q(Y_i | \theta_{-i}, \theta_i)$, where $\theta_{-i} = \{\theta_1 \dots \theta_{i-1}, \theta_{i+1} \dots \theta_h\}$.

Acceptance probability will then be $\alpha(\theta_{-i}, \theta_i, Y_i) = \min \left(1, \frac{\pi(Y_i | \theta_{-i}) q(\theta_i | Y_i, \theta_{-i})}{\pi(\theta_i | \theta_{-i}) q(Y_i | \theta_i, \theta_{-i})} \right)$

Single component MH and Gibbs sampler

Instead of updating θ *en bloc* it is often more convenient and computationally efficient to divide θ into components $\{\theta_1 \dots \theta_h\}$ and update them one by one.

This means that instead of $q(Y | \theta)$ we will have $q(Y_i | \theta_{-i}, \theta_i)$, where $\theta_{-i} = \{\theta_1 \dots \theta_{i-1}, \theta_{i+1} \dots \theta_h\}$.

Acceptance probability will then be $\alpha(\theta_{-i}, \theta_i, Y_i) = \min \left(1, \frac{\pi(Y_i | \theta_{-i}) q(\theta_i | Y_i, \theta_{-i})}{\pi(\theta_i | \theta_{-i}) q(Y_i | \theta_i, \theta_{-i})} \right)$

Gibbs sampler: $q(Y_i | \theta_i, \theta_{-i}) = \pi(Y_i | \theta_{-i})$. **Acceptance probability in this case is always equals to 1!**

Single component MH and Gibbs sampler

Instead of updating θ *en bloc* it is often more convenient and computationally efficient to divide θ into components $\{\theta_1 \dots \theta_h\}$ and update them one by one.

This means that instead of $q(Y | \theta)$ we will have $q(Y_i | \theta_{-i}, \theta_i)$, where $\theta_{-i} = \{\theta_1 \dots \theta_{i-1}, \theta_{i+1} \dots \theta_h\}$.

Acceptance probability will then be $\alpha(\theta_{-i}, \theta_i, Y_i) = \min \left(1, \frac{\pi(Y_i | \theta_{-i}) q(\theta_i | Y_i, \theta_{-i})}{\pi(\theta_i | \theta_{-i}) q(Y_i | \theta_i, \theta_{-i})} \right)$

Gibbs sampler: $q(Y_i | \theta_i, \theta_{-i}) = \pi(Y_i | \theta_{-i})$. **Acceptance probability in this case is always equal to 1!**

Gibbs sampling uses the property of tractability of all **conditional** posterior distributions to get samples from the unknown **full** posterior distribution of all model variables.

Gibbs sampling scheme

Assume we have data $X \sim p(X | \theta_1, \theta_2)$

1. Randomly initialize $\theta_1^{(0)}$ and sample $\theta_2^{(0)} \sim p(\theta_2 | X, \theta_1^{(0)})$

2. For step $t = 1, \dots, T$

(a) Sample $\theta_1^{(t)} \sim p(\theta_1 | X, \theta_2^{t-1})$

(b) Sample $\theta_2^{(t)} \sim p(\theta_2 | X, \theta_1^t)$