1 Introduction

The general model for the elastic energy per unit length for a mixed dislocation dissociated into two partials can be given as [1]:

$$E_D(\theta) = E_S(\theta) + E_I(\theta, \Delta) + E_F(\Delta, \gamma) \tag{1}$$

" E_S " is the self-energy, " E_I " is the interaction energy, and " E_F " is the fault-energy. " θ " is the angle between the Burgers vector and the unit line vector, Δ is the separation between two line segments, γ is the stacking-fault energy.

A general expression can be given for each energy.

$$E_S(\theta) = \frac{\mu b^2}{4\pi} \left(1 - \nu \cos^2 \theta \right) \ln \left(\frac{R}{r_0} \right)$$
 (2a)

$$E_I(\theta) = \frac{\mu b^2}{2\pi} \left(\alpha + \frac{\beta}{1 - \nu} \right) \ln \left(\frac{R}{\Delta} \right) - \frac{\mu}{2\pi (1 - \nu)} \psi \tag{2b}$$

$$E_F = \gamma \Delta \tag{2c}$$

 r_0 and R are the inner and outer cutoff radii, respectively. μ , b, and ν are the shear modulus, the Burgers vector of the dislocation, and the Poisson ratio.

Equation 2b is the interaction energy between two parallel dislocation segments separated by a vector $\vec{\Delta}$. α , β , and ψ are related to the Burgers vectors and the line direction vectors of the two dislocations. Δ is the vector pointing from one dislocation segment to the second.

 γ is the stacking-fault energy

2 Interaction energy between two parallel inplane dislocation segments

The interaction energy between two parallel dislocations is defined from eq.(5-16)[2]. It has the same form as defined in eq.(2b). As such α , β , and ψ are defined as:

$$\alpha = \left(\vec{b}_1 \cdot \hat{l}\right) \left(\vec{b}_2 \cdot \hat{l}\right) \tag{3a}$$

$$\beta = \left(\vec{b}_1 \wedge \hat{l}\right) \cdot \left(\vec{b}_2 \wedge \hat{l}\right) \tag{3b}$$

$$\psi = \frac{1}{\Delta^2} \left[\left(\vec{b}_1 \wedge \hat{l} \right) \cdot \vec{\Delta} \right] \left[\left(\vec{b}_2 \wedge \hat{l} \right) \cdot \vec{\Delta} \right]$$
 (3c)

For our case, the dislocations also exist in the same plane since they are partials. Hence $\vec{b}_i \wedge \hat{l} \perp \vec{\Delta} \Rightarrow \psi = 0$ for our model.

The form of the elastic energy is then

$$E_D(\theta) = E_S(\theta) + E_I(\theta, \Delta) + \gamma \Delta$$
$$= E_S(\theta) + \frac{\mu}{2\pi} \left(\alpha + \frac{\beta}{1 - \nu} \right) \ln \frac{R}{\Delta} + \gamma \Delta$$

Taking the partial derivative wrt Δ to find the equilibrium separation d

$$\frac{\partial E_D}{\partial \Delta} \bigg|_{\Delta = d} = \frac{\mu}{2\pi} \left(\alpha + \frac{\beta}{1 - \nu} \right) \frac{-1}{d} + \gamma$$
$$0 = \frac{\mu}{2\pi} \left(\alpha + \frac{\beta}{1 - \nu} \right) \frac{-1}{d} + \gamma$$

Which gives the relation between the equilibrium separation and the interaction energy coefficients

$$\gamma d = \frac{\mu}{2\pi} \left(\alpha + \frac{\beta}{1 - \nu} \right) \tag{6}$$

Replacing equation 6 in equation 1 we get the general form

$$E_D(\theta) = E_S(\theta + \phi) + E_S(\theta - \phi) + \gamma d \ln \frac{R}{d} + \gamma d$$
 (7)

3 Shockley dislocation $(\theta, \phi = \pm \pi/6)$

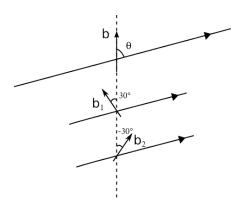


Figure 1: Representation of a Shockley pair

3.1 Self-energy

Using equation (2a) we can show that the self-energy for a pair of Shockley partials is given as

$$E_S\left(\theta + \frac{\pi}{6}\right) + E_S\left(\theta - \frac{\pi}{6}\right) \cong 2 - \nu\cos^2\left(\theta + \frac{\pi}{6}\right) - \nu\cos^2\left(\theta - \frac{\pi}{6}\right)$$
 (8)

Using the identity:

$$\cos^2(A+B) + \cos^2(A-B) = 2(\cos^2 A \cos^2 B + \sin^2 A \sin^2 B) \tag{9}$$

And letting $A = \theta, B = \pi/6$ we get

$$\cos^2\left(\theta + \frac{\pi}{6}\right) + \cos^2\left(\theta - \frac{\pi}{6}\right) = 2\left(\frac{3}{4}\cos^2\theta + \frac{1}{4}\sin^2\theta\right)$$
$$= \frac{1}{2}(3\cos^2\theta + \sin^2\theta)$$
$$= \frac{1}{2}(1 + 2\cos^2\theta)$$

Replacing in equation 8 gives:

$$E_{S}\left(\theta + \frac{\pi}{6}\right) + E_{S}\left(\theta - \frac{\pi}{6}\right) = \frac{\mu b^{2}}{4\pi} \ln\left(\frac{R}{r_{0}}\right) \frac{1}{1-\nu} \left[2 - \frac{\nu}{2}(1 + 2\cos^{2}\theta)\right]$$

$$= \frac{\mu b^{2}}{8\pi} (4 - \nu - 2\nu\cos^{2}\theta) \ln\frac{R}{r_{0}}$$
(11)

3.2 Interaction energy

Hirth [2](eq.10-15) defines the equilibrium separation between two Shockley partials as:

$$\gamma_B d_B = \frac{\mu b^2}{8\pi} \frac{2 - \nu}{1 - \nu} \left(1 - \frac{2\nu \cos 2\theta}{2 - \nu} \right) \tag{12}$$

3.3 Full expression

Replacing equations 12 and 11 in equation 7 we get the elastic energy of a pair of Shockley partial dislocations

$$E_D^B(\theta, \nu, \gamma) = \frac{\mu b^2}{8\pi} \frac{4 - \nu - 2\cos^2\theta}{1 - \nu} \ln\frac{R}{r_0} + \frac{\mu b^2}{8\pi} \left(1 - \frac{2\nu\cos 2\theta}{2 - \nu}\right) \left(\ln\frac{R}{d_B} + 1\right)$$
(13)

where d_B is defined in equation 12.

4 Prismatic dislocation $(\theta, \phi = 0)$

4.1 Self-energy

The self energy of a pair of dislocations with equal Burgers vectors ($\phi = 0$) is just double that for a single

$$E_S(\theta) = 2 \cdot \frac{\mu b^2}{4\pi} \frac{1 - \nu \cos^2 \theta}{1 - \nu} \ln \frac{R}{r_0}$$
 (14)

4.2 Interaction energy

There is no equation in [2] similar to that of 12, so we will derive it here. The equilibrium separation between the pair of dislocations in the prismatic plane can be obtained from equation 3

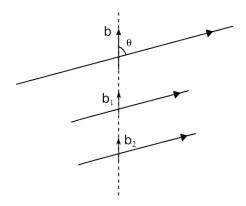


Figure 2: Representation of a prismatic pair

$$\alpha = b^2 \cos^2 \theta$$
$$\beta = b^2 \sin^2 \theta$$

Replacing in equation 6 gives

$$\gamma d = \frac{\mu b^2}{2\pi} \left(\cos^2 \theta + \frac{\sin^2 \theta}{1 - \nu} \right)
= \frac{\mu b^2}{2\pi} \frac{1}{1 - \nu} (\cos^2 \theta - \nu \cos^2 \theta + \sin^2 \theta)
= \frac{\mu b^2}{2\pi} \frac{1}{1 - \nu} (1 - \nu \cos^2 \theta)
= \frac{\mu b^2}{2\pi} \frac{1}{1 - \nu} \left(1 - \nu \frac{\cos 2\theta + 1}{2} \right)
= \frac{\mu b^2}{4\pi} \frac{1}{1 - \nu} (2 - \nu \cos 2\theta - \nu)$$

And we get

$$\gamma_P d_P = \frac{\mu b^2}{4\pi} \frac{2 - \nu}{1 - \nu} \left(1 - \frac{\nu \cos 2\theta}{2 - \nu} \right)$$
 (15a)

which is quite similar to equation 12 up to the constant inside the paranthases.

4.3 Full expression

If we combine equations 15a and 14 we get

$$E_D^P(\theta, \nu, \gamma) = \frac{\mu b^2}{4\pi} \frac{2}{1 - \nu} (1 - \nu \cos^2 \theta) \ln \frac{R}{r_0} + \frac{\mu b^2}{4\pi} \frac{2 - \nu}{1 - \nu} \left(1 - \frac{\nu \cos 2\theta}{2 - \nu} \right) \left(\ln \frac{R}{d_P} + 1 \right)$$
(16)

where d_P is defined in equation 15a.

5 Implementation for the case of Zr

We will take $E_0 = [\mu a^2/\pi] = [J/m]$ as units of energy and a as units of distance. This allows us to define the dimensionless stacking-fault energies γ' as

$$\gamma' = \frac{\gamma}{E_0/a} = \frac{\gamma \pi}{\mu a} \tag{17}$$

We use the parameters $\mu=131$ GPa, a=3.232 Å $\gamma_P=135$ mJ/m², $\gamma_B=198$ mJ/m² to define the prismatic and basal stacking fault-energies for zirconium

$$\gamma_P' = 0.000100$$
 $\gamma_B' = 0.000147$
(18)

For the radii let $r_0 = a$ and let $R = 10^n r_0$. We also specify d = d'.a. This choice of parameters allows to identify the dimensionless value d' and gives the following useful approximations to the natural logarithm:

$$\ln \frac{R}{r_0} = \ln \frac{a \cdot 10^n}{a} = \ln 10^n = 2.3n$$

$$\ln \frac{R}{d} = \ln \frac{10^n a}{d' \cdot a} = \ln 10^n - \ln(d') = 2.3n - \ln(d')$$
(19)

Without any loss in generality we let n=3 and using equations 19, 18, 16, and 13 we show in figure 3 the elastic energy of a dissociated dislocation in the basal plane as a function of θ and we compare with that of a dissociated dislocation in the prismatic plane.

We note that the screw dislocation $(\theta=0)$ in the prismatic plane (green curve) has the lowest energy. The energy difference between the screw dislocation in the basal and the prismatic plane is roughly $\Delta_{PB}(\theta=0)=504~\frac{\mu a^2}{\pi}$. Using the same values for the parameters of zirconium listed above μ and a we get $\Delta_{PB}(\theta=0)=6753.6~\mathrm{J/m}$

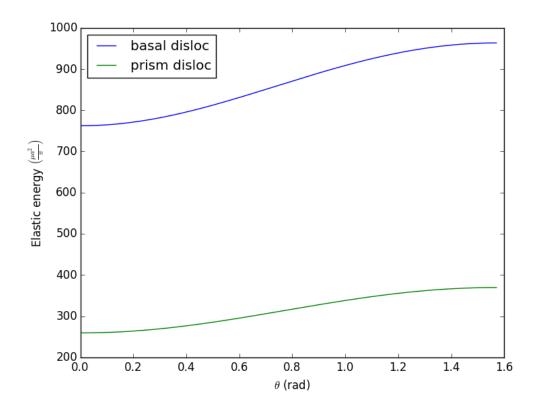


Figure 3: Elastic energy as a function of dislocation character. Case of zirconium. $\gamma_P'=0.000100,\gamma_B'=0.000147,\nu=1/3$

References

- [1] D. J. Bacon. The effect of dissociation on dislocation energy and line tension. Philosophical Magazine A, 38(3):333-339, 1978.
- [2] J.P. Hirth and J. Lothe. *Theory of Dislocations*. Krieger Publishing Company, 1982.