

# Differential Manifolds

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**José Sá**

<sup>1</sup>*DAMTP, University of Cambridge, UK*

*E-mail:* [jac295@cam.ac.uk](mailto:jac295@cam.ac.uk)

ABSTRACT: Abstract test...

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# 1 Differential Manifolds and differentiable maps

## 1.1 Review of General Topology

Let  $S$  be a set.

**Definition 1.1.** A topology is a collection  $\mathcal{T}$  of subsets of  $S$ , called the open sets, such that:

- (i)  $\phi, S \in \mathcal{T}$ , where  $\phi \equiv \{ \}$  is the empty set.
- (ii) if  $U_\alpha \in \mathcal{T}$ , for  $\alpha \in A$ , then  $\bigcup_{\alpha \in A} U_\alpha \in \mathcal{T}$
- (iii) if  $U_1, \dots, U_n \in \mathcal{T}$ ,  $n \in \mathbb{N}$ , then  $\bigcap_{i=1}^n U_n \in \mathcal{T}$

**Example 1.1.**

- 1)  $S = \mathbb{R}^n$ ,  $U \in \mathcal{T}$  iff  $U \subseteq S$  is open in the usual sense.
- 2) If  $(S, d)$  is a metric space, then it is a topological space.

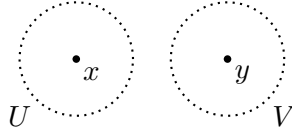
**Definition 1.2.** Let  $(S, \mathcal{T})$  be a topological space. A basis for the topology of  $S$  if the collection  $B \subseteq \mathcal{T}$  so that any  $U \in \mathcal{T}$  is the union of sets from  $B$ .

**Example 1.2.**

- 1)  $\{ B(x; \epsilon) \mid x \in \mathbb{R}^n, \epsilon \in \mathbb{R}^+ \}$  is a basis for the usual topology in  $\mathbb{R}^n$ .
- 2)  $\{ B(x; \epsilon) \mid x \in \mathbb{Q}^n, \epsilon \in \mathbb{Q}^+ \}$  is a countable basis for  $\mathbb{R}^n$ .

**Definition 1.3.**  $(S, \mathcal{T})$  is second countable if the topology  $\mathcal{T}$  has a countable basis.

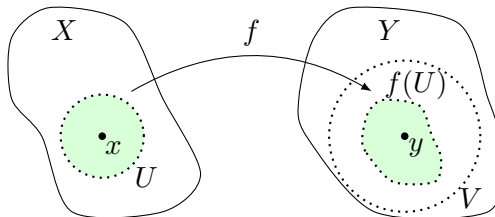
**Definition 1.4.**  $(S, \mathcal{T})$  is Hausdorff if for all  $x, y \in S$ , with  $x \neq y$ , there are open sets  $U, V \subseteq S$  so that  $x \in U$ ,  $y \in V$  and  $U \cap V = \phi$ .



In a Hausdorff space, we can always distinguish two points by enclosing them on open balls that do not intersect.

Let's now define continuity in terms using topology language. Let  $X, Y$  be any two topological spaces.

**Definition 1.5.**  $f : X \longrightarrow Y$  is continuous at  $x \in X$  if for any open  $V \subseteq Y$  containing  $y$ , there exists a open  $U \subseteq X$  containing  $x$  so that  $f(U) \subseteq V$ .



**Definition 1.6.**  $f : X \rightarrow Y$  is continuous if it is continuous at all  $x \in X$ .

**Proposition 1.1.**  $f : X \rightarrow Y$  is continuous iff for all open  $V \subseteq Y$ , the preimage  $f^{-1}(V) \equiv \{x \in X \mid f(x) \in V\} \subseteq X$  is open in  $X$ .

**Definition 1.7.**  $F \subseteq X$  is closed if  $X \setminus F \subseteq X$  is open.

**Proposition 1.2.**  $f : X \rightarrow Y$  is continuous iff  $f^{-1}(F) \subseteq X$  is closed in  $X$ , for every closed  $F \subseteq Y$  in  $Y$ .

**Definition 1.8.** A continuous map  $f : X \rightarrow Y$  is called a homeomorphism iff it has a continuous inverse  $g : Y \rightarrow X$ , such that  $f \circ g = \text{id}_Y$  and  $g \circ f = \text{id}_X$ . We say that  $X$  and  $Y$  are homeomorphic. We write  $g = f^{-1}$  and  $X \cong Y$ .

## 1.2 Differential Manifolds

**Definition 1.9.** A topological manifold of dimension  $m$  is a second countable, Hausdorff topological space  $M$ , so that any  $p \in M$  has a open neighborhood  $x \ni U \subseteq M$ , which is homeomorphic with  $\mathbb{R}^m$ .

*Remark.* We might as well have said homeomorphic with an open subset of  $\mathbb{R}^m$ , because  $B(0, \epsilon) = \{x \in \mathbb{R}^m \mid \|x\| < \epsilon\} \cong \mathbb{R}^m$ . To see that we can use the function

$$f : B(0, \epsilon) \rightarrow \mathbb{R}^m$$

$$x \mapsto \frac{x}{\epsilon - \|x\|}$$

*Remark.* The *Theorem of Invariance of Domain* states that if  $\phi : \mathbb{R}^m \xrightarrow{\cong} \mathbb{R}^n$ , then  $m = n$ . Hence the definition is consistent.