a7

June 23, 2025

1 Paths

2 1) Training

2.0.1 Dataloader

```
import matplotlib.pyplot as plt
import numpy as np

def my_tensor_image_show ( image , label=None ):
    image = image.numpy().transpose((1, 2, 0))
    mean = np.array([0.485, 0.456, 0.406])
    std = np.array([0.229, 0.224, 0.225])
    image = std * image + mean
    image = np.clip(image, 0, 1)
    plt.imshow(image)
    plt.axis('off')
    if label is None :
        plt.title('Image in tensor format.')
    else :
        plt.title(f'Image in tensor format | Class: {label:2d}')
    plt.show()
```

```
[36]: from torch.utils.data import Subset
  import scipy.io
  import os
  import torch

def load_Flowers17_dataset(dataset_path, dataset_split_file_path, my_transform):
```

```
full_dataset = torchvision.datasets.ImageFolder(root=dataset_path,_
 ⇔transform=my_transform)
   mat = scipy.io.loadmat( dataset_split_file_path )
   train ids = mat['trn1'][0] # 'tst1' or 'trn1' or 'val1'
   val_ids = mat['val1'][0] # 'tst1' or 'trn1' or 'val1'
   test ids = mat['tst1'][0] # 'tst1' or 'trn1' or 'val1'
   # Map filenames to indices
   image_paths = [os.path.basename(full_dataset.samples[i][0]) for i in_
 →range(len(full_dataset))]
    id_to_idx = {int(p.split("_")[1].split(".")[0]): i for i, p in_
 ⇔enumerate(image_paths)}
    # Get indices for train/test
   train_indices = [id_to_idx[i] for i in train_ids if i in id_to_idx]
   val_indices = [id_to_idx[i] for i in val_ids if i in id_to_idx]
   test_indices = [id_to_idx[i] for i in test_ids if i in id_to_idx]
    # Create train and test subsets
   train_dataset = Subset(full_dataset, train_indices)
   val dataset = Subset(full dataset, val indices)
   test_dataset = Subset(full_dataset, test_indices)
   dataset = {'train':train_dataset, 'val':val_dataset, 'test':test_dataset}
   return dataset
def create_dataloader(dataset, batch_size):
   # Create DataLoaders
   train_loader = torch.utils.data.DataLoader(dataset['train'],__
 ⇒batch_size=batch_size, shuffle=True)
    val loader = torch.utils.data.DataLoader(dataset['val'] ,...
 ⇒batch_size=batch_size, shuffle=False)
   test_loader = torch.utils.data.DataLoader(dataset['test'] ,__
 ⇒batch_size=batch_size, shuffle=False)
   print(f'Dataset stats:')
   total = 0
   # Example of iterating through train loader
   for images, labels in train_loader:
       total = total + images.shape[0] # Check batch shape and labels
   print(f' - Train: {total} images')
   total = 0
    # Example of iterating through train loader
```

```
for images, labels in val_loader:
    total = total + images.shape[0] # Check batch shape and labels
print(f' - Val: {total} images')
total = 0
# Example of iterating through train loader
for images, labels in test_loader:
    total = total + images.shape[0]
print(f' - Test: {total} images')

dataloader = {'train':train_loader, 'val':val_loader, 'test':test_loader}
return dataloader
```

2.0.2 Training functions

```
[37]: from torch.utils.tensorboard import SummaryWriter
      import torch.optim
      import matplotlib.pyplot as plt
      from datetime import datetime
      from tqdm import tqdm
      import copy
      def plot_layers ( net , writer, epoch ) :
          layers = list(net.classifier.modules())
          layer id = 1
          for layer in layers:
              if isinstance(layer, torch.nn.Linear) :
                  writer.add_histogram('Bias/conv{}'.format(layer_id), layer.bias,
                                      epoch )
                  writer.add_histogram('Weight/conv{}'.format(layer_id), layer.weight,
                                      epoch )
                  writer.add_histogram('Grad/conv{}'.format(layer_id), layer.weight.
       ⇔grad,
                                          epoch )
                  layer_id += 1
      def plot_layers_googlenet(net, writer, epoch):
          layers = list(net.fc.modules())
          layer_id = 1
```

```
for layer in layers:
        if isinstance(layer, torch.nn.Conv2d) or isinstance(layer, torch.nn.
 →Linear):
            writer.add_histogram('Bias/conv{}'.format(layer_id), layer.bias,__
 ⇒epoch)
            writer.add_histogram('Weight/conv{}'.format(layer_id), layer.
 ⇒weight, epoch)
            if layer.weight.grad is not None:
                writer.add_histogram('Grad/conv{}'.format(layer_id), layer.
 →weight.grad, epoch)
            layer_id += 1
def train ( train_loader, test_loader, net, dataset_size, my_device='cpu',
           prefix=None, upper_bound=100.0, save=False, epochs=100,
           lr=1e-1, device='cpu', debug=False, layers2tensorboard=False,
 ⇒batch_size=64) :
    optimizer = torch.optim.AdamW(net.parameters(),lr=lr)
    criterion = torch.nn.CrossEntropyLoss()
   now = datetime.now()
    suffix = now.strftime("%Y%m%d_%H%M%S")
    suffix = suffix if prefix is None else prefix + '-' + suffix
   writer = SummaryWriter( log_dir=tensorboard_path+suffix )
   accuracies = []
   max_accuracy = -1.0
   for epoch in tqdm(range(epochs), desc='Training epochs...') :
       net.train()
       for idx, (train_x, train_label) in enumerate(train_loader):
            train_x = train_x.to(device)
            train_label = train_label.to(device)
           predict_y = net( train_x )
            # Loss:
            error = criterion( predict_y , train_label )
            writer.add_scalar( 'Loss/train', error.cpu().item(),
                                idx+( epoch*(dataset_size//batch_size) ) )
            # Back propagation
            optimizer.zero_grad()
            error.backward()
```

```
optimizer.step()
        # Accuracy:
        predict_ys = torch.max( predict_y, axis=1 )[1]
                 = torch.sum(predict_ys == train_label)
        writer.add_scalar( 'Accuracy/train', correct/train_x.size(0),
                            idx+( epoch*(dataset_size//batch_size) ) )
        if debug and idx \% 10 == 0 :
            print( f'idx: {idx:4d}, _error: {error.cpu().item():5.2f}' )
    if layers2tensorboard :
        plot_layers_googlenet( net, writer, epoch )
    accuracy = validate(net, test_loader, device=device)
    accuracies.append(accuracy)
    writer.add_scalar( 'Accuracy/test', accuracy, epoch )
    if accuracy > max_accuracy :
        best_model = copy.deepcopy(net)
        max_accuracy = accuracy
        print("Saving Best Model with Accuracy: ", accuracy)
    print( f'Epoch: {epoch+1:3d} | Accuracy : {accuracy:7.4f}%' )
    if accuracy > upper_bound :
        break
if save :
    path = f'{models_path}{prefix}-{max_accuracy:.2f}.pkl'
    torch.save(best_model, path)
    print('Model saved in:',path)
plt.plot(accuracies)
writer.flush()
writer.close()
return best_model
```

2.0.3 Validation function

```
[38]: def validate ( model , data , device='cpu') :

model.eval()
```

```
correct = 0
sum = 0

for idx, (test_x, test_label) in enumerate(data) :
    test_x = test_x.to(device)
    test_label = test_label.to(device)
    predict_y = model( test_x ).detach()
    predict_ys = torch.max( predict_y, axis=1 )[1]
    sum = sum + test_x.size(0)
    correct = correct + torch.sum(predict_ys == test_label)
    correct = correct.cpu().item()
```

3 2) Create model and Fine-Tuning process

```
[39]: import torchvision
      from torchvision.models import alexnet, AlexNet_Weights
      my_transform = AlexNet_Weights.IMAGENET1K_V1.transforms()
      # INSERT HERE THE PATH FOR THE DATASET SPLIT FILE AND THE BATCH SIZE
      dataset_split_file = "../a3/flowers_classes-20250415T010641Z-001/
       ⇔flowers_classes/datasplits.mat"
      batch size = 32
      dataset = load_Flowers17_dataset(dataset_path, dataset_split_file, my_transform)
      dataloader = create_dataloader(dataset, batch_size)
     Dataset stats:
      - Train: 680 images
      - Val: 340 images
      - Test: 340 images
     Test the dataloaders
[40]: images, labels = next(iter(dataloader['train']))
      my_tensor_image_show(images[0], label=labels[0])
```

Image in tensor format | Class: 15



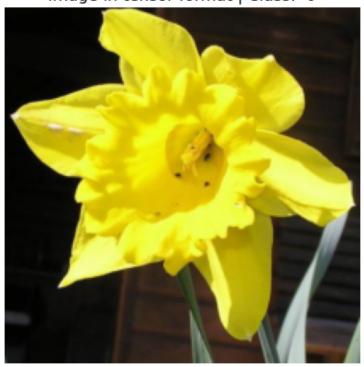
```
[41]: images, labels = next(iter(dataloader['test']))
my_tensor_image_show(images[0], label=labels[0])
```

Image in tensor format | Class: 0



```
[42]: images, labels = next(iter(dataloader['val']))
my_tensor_image_show(images[0], label=labels[0])
```

Image in tensor format | Class: 0



```
[43]: # Execute only if necessarry to clear GPU memory

# del model # Verify if the model object exists

# import gc
# gc.collect()
# torch.cuda.empty_cache()

[44]: # (COMPLETE) Create the model
import torchvision.models as models
import torch.nn as nn

googlenet_imagenet_weights = models.GoogLeNet_Weights.IMAGENETIK_V1
googlenet_transform = googlenet_imagenet_weights.transforms()
model = models.googlenet(weights=googlenet_imagenet_weights)

[45]: # (COMPLETE) Froze all parameters of the model and print the name of the layers
for param in model.parameters():
    param.requires_grad = False
```

```
for name, layer in model.named_modules():
        print(f'Layer: {name}')
Layer:
Layer: conv1
Layer: conv1.conv
Layer: conv1.bn
Layer: maxpool1
Layer: conv2
Layer: conv2.conv
Layer: conv2.bn
Layer: conv3
Layer: conv3.conv
Layer: conv3.bn
Layer: maxpool2
Layer: inception3a
Layer: inception3a.branch1
Layer: inception3a.branch1.conv
Layer: inception3a.branch1.bn
Layer: inception3a.branch2
Layer: inception3a.branch2.0
Layer: inception3a.branch2.0.conv
Layer: inception3a.branch2.0.bn
Layer: inception3a.branch2.1
Layer: inception3a.branch2.1.conv
Layer: inception3a.branch2.1.bn
Layer: inception3a.branch3
Layer: inception3a.branch3.0
Layer: inception3a.branch3.0.conv
Layer: inception3a.branch3.0.bn
Layer: inception3a.branch3.1
Layer: inception3a.branch3.1.conv
Layer: inception3a.branch3.1.bn
Layer: inception3a.branch4
Layer: inception3a.branch4.0
Layer: inception3a.branch4.1
Layer: inception3a.branch4.1.conv
Layer: inception3a.branch4.1.bn
Layer: inception3b
Layer: inception3b.branch1
Layer: inception3b.branch1.conv
Layer: inception3b.branch1.bn
Layer: inception3b.branch2
Layer: inception3b.branch2.0
Layer: inception3b.branch2.0.conv
Layer: inception3b.branch2.0.bn
Layer: inception3b.branch2.1
Layer: inception3b.branch2.1.conv
```

- Layer: inception3b.branch2.1.bn
- Layer: inception3b.branch3
- Layer: inception3b.branch3.0
- Layer: inception3b.branch3.0.conv
- Layer: inception3b.branch3.0.bn
- Layer: inception3b.branch3.1
- Layer: inception3b.branch3.1.conv
- Layer: inception3b.branch3.1.bn
- Layer: inception3b.branch4
- Layer: inception3b.branch4.0
- Layer: inception3b.branch4.1
- Layer: inception3b.branch4.1.conv
- Layer: inception3b.branch4.1.bn
- Layer: maxpool3
- Layer: inception4a
- Layer: inception4a.branch1
- Layer: inception4a.branch1.conv
- Layer: inception4a.branch1.bn
- Layer: inception4a.branch2
- Layer: inception4a.branch2.0
- Layer: inception4a.branch2.0.conv
- Layer: inception4a.branch2.0.bn
- Layer: inception4a.branch2.1
- Layer: inception4a.branch2.1.conv
- Layer: inception4a.branch2.1.bn
- Layer: inception4a.branch3
- Layer: inception4a.branch3.0
- Layer: inception4a.branch3.0.conv
- Layer: inception4a.branch3.0.bn
- Layer: inception4a.branch3.1
- Layer: inception4a.branch3.1.conv
- Layer: inception4a.branch3.1.bn
- Layer: inception4a.branch4
- Layer: inception4a.branch4.0
- Layer: inception4a.branch4.1
- Layer: inception4a.branch4.1.conv
- Layer: inception4a.branch4.1.bn
- Layer: inception4b
- Layer: inception4b.branch1
- Layer: inception4b.branch1.conv
- Layer: inception4b.branch1.bn
- Layer: inception4b.branch2
- Layer: inception4b.branch2.0
- Layer: inception4b.branch2.0.conv
- Layer: inception4b.branch2.0.bn
- Layer: inception4b.branch2.1
- Layer: inception4b.branch2.1.conv
- Layer: inception4b.branch2.1.bn

```
Layer: inception4b.branch3.0
Layer: inception4b.branch3.0.conv
```

Layer: inception4b.branch3.0.bn

Layer: inception4b.branch3.1

Layer: inception4b.branch3.1.conv Layer: inception4b.branch3.1.bn

Layer: inception4b.branch4
Layer: inception4b.branch4.0
Layer: inception4b.branch4.1
Layer: inception4b.branch4.1

Layer: inception4b.branch4.1.bn

Layer: inception4c

Layer: inception4c.branch1

Layer: inception4c.branch1.conv Layer: inception4c.branch1.bn Layer: inception4c.branch2 Layer: inception4c.branch2.0

Layer: inception4c.branch2.0.conv Layer: inception4c.branch2.0.bn Layer: inception4c.branch2.1

Layer: inception4c.branch2.1.conv Layer: inception4c.branch2.1.bn

Layer: inception4c.branch3 Layer: inception4c.branch3.0

Layer: inception4c.branch3.0.conv Layer: inception4c.branch3.0.bn

Layer: inception4c.branch3.1

Layer: inception4c.branch3.1.conv Layer: inception4c.branch3.1.bn Layer: inception4c.branch4

Layer: inception4c.branch4.0 Layer: inception4c.branch4.1

Layer: inception4c.branch4.1.conv Layer: inception4c.branch4.1.bn

Layer: inception4d

Layer: inception4d.branch1

Layer: inception4d.branch1.conv Layer: inception4d.branch1.bn Layer: inception4d.branch2 Layer: inception4d.branch2.0

Layer: inception4d.branch2.0.conv Layer: inception4d.branch2.0.bn Layer: inception4d.branch2.1

Layer: inception4d.branch2.1.conv Layer: inception4d.branch2.1.bn Layer: inception4d.branch3

Layer: inception4d.branch3
Layer: inception4d.branch3.0

```
Layer: inception4d.branch3.0.conv
Layer: inception4d.branch3.0.bn
Layer: inception4d.branch3.1
Layer: inception4d.branch3.1.conv
Layer: inception4d.branch3.1.bn
Layer: inception4d.branch4
Layer: inception4d.branch4.0
Layer: inception4d.branch4.1
Layer: inception4d.branch4.1.conv
Layer: inception4d.branch4.1.bn
Layer: inception4e
Layer: inception4e.branch1
Layer: inception4e.branch1.conv
Layer: inception4e.branch1.bn
Layer: inception4e.branch2
Layer: inception4e.branch2.0
Layer: inception4e.branch2.0.conv
Layer: inception4e.branch2.0.bn
Layer: inception4e.branch2.1
Layer: inception4e.branch2.1.conv
Layer: inception4e.branch2.1.bn
Layer: inception4e.branch3
Layer: inception4e.branch3.0
Layer: inception4e.branch3.0.conv
Layer: inception4e.branch3.0.bn
Layer: inception4e.branch3.1
Layer: inception4e.branch3.1.conv
Layer: inception4e.branch3.1.bn
Layer: inception4e.branch4
Layer: inception4e.branch4.0
Layer: inception4e.branch4.1
Layer: inception4e.branch4.1.conv
Layer: inception4e.branch4.1.bn
Layer: maxpool4
Layer: inception5a
Layer: inception5a.branch1
Layer: inception5a.branch1.conv
Layer: inception5a.branch1.bn
Layer: inception5a.branch2
Layer: inception5a.branch2.0
Layer: inception5a.branch2.0.conv
Layer: inception5a.branch2.0.bn
Layer: inception5a.branch2.1
Layer: inception5a.branch2.1.conv
Layer: inception5a.branch2.1.bn
Layer: inception5a.branch3
Layer: inception5a.branch3.0
```

Layer: inception5a.branch3.0.conv

```
Layer: inception5a.branch3.1
     Layer: inception5a.branch3.1.conv
     Layer: inception5a.branch3.1.bn
     Layer: inception5a.branch4
     Layer: inception5a.branch4.0
     Layer: inception5a.branch4.1
     Layer: inception5a.branch4.1.conv
     Layer: inception5a.branch4.1.bn
     Layer: inception5b
     Layer: inception5b.branch1
     Layer: inception5b.branch1.conv
     Layer: inception5b.branch1.bn
     Layer: inception5b.branch2
     Layer: inception5b.branch2.0
     Layer: inception5b.branch2.0.conv
     Layer: inception5b.branch2.0.bn
     Layer: inception5b.branch2.1
     Layer: inception5b.branch2.1.conv
     Layer: inception5b.branch2.1.bn
     Layer: inception5b.branch3
     Layer: inception5b.branch3.0
     Layer: inception5b.branch3.0.conv
     Layer: inception5b.branch3.0.bn
     Layer: inception5b.branch3.1
     Layer: inception5b.branch3.1.conv
     Layer: inception5b.branch3.1.bn
     Layer: inception5b.branch4
     Layer: inception5b.branch4.0
     Layer: inception5b.branch4.1
     Layer: inception5b.branch4.1.conv
     Layer: inception5b.branch4.1.bn
     Layer: avgpool
     Layer: dropout
     Layer: fc
[46]: # (COMPLETE) Replace the last layer to a new liner layer with the number of
      →classes of your target problem.
      model.fc = nn.Linear(in features=model.fc.in features, out features=17)
[47]: # (COMPLETE) Free the parameters of specific layers to train.
      for name, param in model.named_parameters():
          if 'inception5a' in name or 'inception5b' in name:
              param.requires_grad = True
      for name, param in model.named_parameters():
          if param.requires_grad == True:
```

Layer: inception5a.branch3.0.bn

print(name, param.requires_grad)

```
inception5a.branch1.conv.weight True
     inception5a.branch1.bn.weight True
     inception5a.branch1.bn.bias True
     inception5a.branch2.0.conv.weight True
     inception5a.branch2.0.bn.weight True
     inception5a.branch2.0.bn.bias True
     inception5a.branch2.1.conv.weight True
     inception5a.branch2.1.bn.weight True
     inception5a.branch2.1.bn.bias True
     inception5a.branch3.0.conv.weight True
     inception5a.branch3.0.bn.weight True
     inception5a.branch3.0.bn.bias True
     inception5a.branch3.1.conv.weight True
     inception5a.branch3.1.bn.weight True
     inception5a.branch3.1.bn.bias True
     inception5a.branch4.1.conv.weight True
     inception5a.branch4.1.bn.weight True
     inception5a.branch4.1.bn.bias True
     inception5b.branch1.conv.weight True
     inception5b.branch1.bn.weight True
     inception5b.branch1.bn.bias True
     inception5b.branch2.0.conv.weight True
     inception5b.branch2.0.bn.weight True
     inception5b.branch2.0.bn.bias True
     inception5b.branch2.1.conv.weight True
     inception5b.branch2.1.bn.weight True
     inception5b.branch2.1.bn.bias True
     inception5b.branch3.0.conv.weight True
     inception5b.branch3.0.bn.weight True
     inception5b.branch3.0.bn.bias True
     inception5b.branch3.1.conv.weight True
     inception5b.branch3.1.bn.weight True
     inception5b.branch3.1.bn.bias True
     inception5b.branch4.1.conv.weight True
     inception5b.branch4.1.bn.weight True
     inception5b.branch4.1.bn.bias True
     fc.weight True
     fc.bias True
[48]: # (COMPLETE) Check layer parameters stats.
      from torchinfo import summary
      summary(model, input_size=(batch_size, 3, 224, 224), device='cpu')
```

Layer (type:depth-idx)	Output Shape	Param #
=======================================	=======================================	
GoogLeNet	[32, 17]	
BasicConv2d: 1-1	[32, 64, 112, 112]	
Conv2d: 2-1	[32, 64, 112, 112]	(9,408)
BatchNorm2d: 2-2	[32, 64, 112, 112]	(128)
MaxPool2d: 1-2	[32, 64, 56, 56]	
BasicConv2d: 1-3	[32, 64, 56, 56]	
Conv2d: 2-3	[32, 64, 56, 56]	(4,096)
BatchNorm2d: 2-4	[32, 64, 56, 56]	(128)
BasicConv2d: 1-4	[32, 192, 56, 56]	
Conv2d: 2-5	[32, 192, 56, 56]	(110,592)
BatchNorm2d: 2-6	[32, 192, 56, 56]	(384)
MaxPool2d: 1-5	[32, 192, 28, 28]	
Inception: 1-6	[32, 256, 28, 28]	
BasicConv2d: 2-7	[32, 64, 28, 28]	
Conv2d: 3-1	[32, 64, 28, 28]	(12,288)
BatchNorm2d: 3-2	[32, 64, 28, 28]	(128)
Sequential: 2-8	[32, 128, 28, 28]	
BasicConv2d: 3-3	[32, 96, 28, 28]	(18,624)
BasicConv2d: 3-4	[32, 128, 28, 28]	(110,848)
Sequential: 2-9	[32, 32, 28, 28]	
BasicConv2d: 3-5	[32, 16, 28, 28]	(3,104)
BasicConv2d: 3-6	[32, 32, 28, 28]	(4,672)
Sequential: 2-10	[32, 32, 28, 28]	
MaxPool2d: 3-7	[32, 192, 28, 28]	
BasicConv2d: 3-8	[32, 32, 28, 28]	(6,208)
Inception: 1-7	[32, 480, 28, 28]	
BasicConv2d: 2-11	[32, 128, 28, 28]	
Conv2d: 3-9	[32, 128, 28, 28]	(32,768)
BatchNorm2d: 3-10	[32, 128, 28, 28]	(256)
Sequential: 2-12	[32, 192, 28, 28]	
BasicConv2d: 3-11	[32, 128, 28, 28]	(33,024)
BasicConv2d: 3-12	[32, 192, 28, 28]	(221,568)
Sequential: 2-13	[32, 96, 28, 28]	
BasicConv2d: 3-13	[32, 32, 28, 28]	(8,256)
BasicConv2d: 3-14	[32, 96, 28, 28]	(27,840)
Sequential: 2-14	[32, 64, 28, 28]	
MaxPool2d: 3-15	[32, 256, 28, 28]	(46, 540)
BasicConv2d: 3-16	[32, 64, 28, 28]	(16,512)
MaxPool2d: 1-8	[32, 480, 14, 14]	
Inception: 1-9	[32, 512, 14, 14]	
BasicConv2d: 2-15	[32, 192, 14, 14]	(00.160)
Conv2d: 3-17	[32, 192, 14, 14]	(92,160)

Dot sh Normand. 2 10	[20 100 14 14]	(204)
BatchNorm2d: 3-18	[32, 192, 14, 14]	(384)
Sequential: 2-16	[32, 208, 14, 14]	(46,070)
BasicConv2d: 3-19	[32, 96, 14, 14]	(46,272)
BasicConv2d: 3-20	[32, 208, 14, 14]	(180,128)
Sequential: 2-17	[32, 48, 14, 14]	
BasicConv2d: 3-21	[32, 16, 14, 14]	(7,712)
BasicConv2d: 3-22	[32, 48, 14, 14]	(7,008)
Sequential: 2-18	[32, 64, 14, 14]	
MaxPool2d: 3-23	[32, 480, 14, 14]	
BasicConv2d: 3-24	[32, 64, 14, 14]	(30,848)
Inception: 1-10	[32, 512, 14, 14]	
BasicConv2d: 2-19	[32, 160, 14, 14]	
Conv2d: 3-25	[32, 160, 14, 14]	(81,920)
BatchNorm2d: 3-26	[32, 160, 14, 14]	(320)
Sequential: 2-20	[32, 224, 14, 14]	
BasicConv2d: 3-27	[32, 112, 14, 14]	(57,568)
BasicConv2d: 3-28	[32, 224, 14, 14]	(226,240)
Sequential: 2-21	[32, 64, 14, 14]	
BasicConv2d: 3-29	[32, 24, 14, 14]	(12,336)
BasicConv2d: 3-30	[32, 64, 14, 14]	(13,952)
Sequential: 2-22	[32, 64, 14, 14]	
MaxPool2d: 3-31	[32, 512, 14, 14]	
BasicConv2d: 3-32	[32, 64, 14, 14]	(32,896)
Inception: 1-11		(32,090)
BasicConv2d: 2-23	[32, 512, 14, 14]	
Conv2d: 3-33	[32, 128, 14, 14]	
	[32, 128, 14, 14]	(65,536)
BatchNorm2d: 3-34	[32, 128, 14, 14]	(256)
Sequential: 2-24	[32, 256, 14, 14]	(25 700)
BasicConv2d: 3-35	[32, 128, 14, 14]	(65,792)
BasicConv2d: 3-36	[32, 256, 14, 14]	(295,424)
Sequential: 2-25	[32, 64, 14, 14]	
BasicConv2d: 3-37	[32, 24, 14, 14]	(12,336)
BasicConv2d: 3-38	[32, 64, 14, 14]	(13,952)
Sequential: 2-26	[32, 64, 14, 14]	
MaxPool2d: 3-39	[32, 512, 14, 14]	
BasicConv2d: 3-40	[32, 64, 14, 14]	(32,896)
Inception: 1-12	[32, 528, 14, 14]	
BasicConv2d: 2-27	[32, 112, 14, 14]	
Conv2d: 3-41	[32, 112, 14, 14]	(57,344)
BatchNorm2d: 3-42	[32, 112, 14, 14]	(224)
Sequential: 2-28	[32, 288, 14, 14]	
BasicConv2d: 3-43	[32, 144, 14, 14]	(74,016)
BasicConv2d: 3-44	[32, 288, 14, 14]	(373,824)
Sequential: 2-29	[32, 64, 14, 14]	
BasicConv2d: 3-45	[32, 32, 14, 14]	(16,448)
BasicConv2d: 3-46	[32, 64, 14, 14]	(18,560)
Sequential: 2-30	[32, 64, 14, 14]	
	,, ,	

MaxPool2d: 3-47	[32, 512, 14, 14]	
BasicConv2d: 3-48	[32, 64, 14, 14]	(32,896)
Inception: 1-13	[32, 832, 14, 14]	
BasicConv2d: 2-31	[32, 256, 14, 14]	
Conv2d: 3-49	[32, 256, 14, 14]	(135,168)
BatchNorm2d: 3-50	[32, 256, 14, 14]	(512)
Sequential: 2-32	[32, 320, 14, 14]	
BasicConv2d: 3-51	[32, 160, 14, 14]	(84,800)
BasicConv2d: 3-52	[32, 320, 14, 14]	(461,440)
Sequential: 2-33	[32, 128, 14, 14]	
BasicConv2d: 3-53	[32, 32, 14, 14]	(16,960)
BasicConv2d: 3-54	[32, 128, 14, 14]	(37,120)
Sequential: 2-34	[32, 128, 14, 14]	
MaxPool2d: 3-55	[32, 528, 14, 14]	
BasicConv2d: 3-56	[32, 128, 14, 14]	(67,840)
MaxPool2d: 1-14	[32, 832, 7, 7]	
Inception: 1-15	[32, 832, 7, 7]	
BasicConv2d: 2-35	[32, 256, 7, 7]	
Conv2d: 3-57	[32, 256, 7, 7]	212,992
BatchNorm2d: 3-58	[32, 256, 7, 7]	512
Sequential: 2-36	[32, 320, 7, 7]	
BasicConv2d: 3-59	[32, 160, 7, 7]	133,440
BasicConv2d: 3-60	[32, 320, 7, 7]	461,440
Sequential: 2-37	[32, 128, 7, 7]	
BasicConv2d: 3-61	[32, 32, 7, 7]	26,688
BasicConv2d: 3-62	[32, 128, 7, 7]	37,120
Sequential: 2-38	[32, 128, 7, 7]	
MaxPool2d: 3-63	[32, 832, 7, 7]	
BasicConv2d: 3-64	[32, 128, 7, 7]	106,752
Inception: 1-16	[32, 1024, 7, 7]	
BasicConv2d: 2-39	[32, 384, 7, 7]	
Conv2d: 3-65	[32, 384, 7, 7]	319,488
BatchNorm2d: 3-66	[32, 384, 7, 7]	768
Sequential: 2-40	[32, 384, 7, 7]	
BasicConv2d: 3-67	[32, 192, 7, 7]	160,128
BasicConv2d: 3-68	[32, 384, 7, 7]	664,320
Sequential: 2-41	[32, 128, 7, 7]	
BasicConv2d: 3-69	[32, 48, 7, 7]	40,032
BasicConv2d: 3-70	[32, 128, 7, 7]	55,552
Sequential: 2-42	[32, 128, 7, 7]	
MaxPool2d: 3-71	[32, 832, 7, 7]	
BasicConv2d: 3-72	[32, 128, 7, 7]	106,752
AdaptiveAvgPool2d: 1-17	[32, 1024, 1, 1]	
Dropout: 1-18	[32, 1024]	
Linear: 1-19	[32, 17]	17,425

========

Total params: 5,617,329 Trainable params: 2,343,409 Non-trainable params: 3,273,920 Total mult-adds (Units.GIGABYTES): 47.92 _____ Input size (MB): 19.27 Forward/backward pass size (MB): 1651.80 Params size (MB): 22.47 Estimated Total Size (MB): 1693.54 []: # (COMPLETE) Set the device and transfer the model to it. my_device = 'cuda' if torch.cuda.is_available() else 'cpu' model = model.to(my_device) # (COMPLETE) Set the train parameters epochs = 20lr = 1e-4dataset name = 'flowers' prefix = 'GoogLeNet-FT1-{}-e-{}-lr-{}'.format(dataset_name, epochs, lr) net = train(dataloader['train'], dataloader['val'], model,__ →len(dataset['train']), epochs=epochs, device=my_device, save=True, prefix=prefix, lr=lr, layers2tensorboard=True, →batch_size=batch_size) | 0/20 [00:00<?, ?it/s] Training epochs...: 0%1 Training epochs...: 5% l | 1/20 [00:56<17:50, 56.34s/it] Saving Best Model with Accuracy: 65.88235294117646 Epoch: 1 | Accuracy : 65.8824% Training epochs...: 10% | 2/20 [01:52<16:52, 56.25s/it] Saving Best Model with Accuracy: 84.11764705882354 2 | Accuracy : 84.1176% Epoch: Training epochs...: 15% | 3/20 [02:51<16:20, 57.67s/it] Saving Best Model with Accuracy: 89.11764705882354 Epoch: 3 | Accuracy : 89.1176% | 4/20 [03:48<15:12, 57.06s/it] Training epochs...: 20% Saving Best Model with Accuracy: 90.29411764705883 Epoch: 4 | Accuracy : 90.2941%

Training epochs...: 25% | 5/20 [04:49<14:41, 58.79s/it]

Saving Best Model with Accuracy: 91.17647058823529

Epoch: 5 | Accuracy: 91.1765%

Training epochs...: 30% | 6/20 [05:53<14:06, 60.47s/it]

Saving Best Model with Accuracy: 91.47058823529412

Epoch: 6 | Accuracy : 91.4706%

Training epochs...: 35% | 7/20 [06:57<13:20, 61.58s/it]

Saving Best Model with Accuracy: 91.76470588235294

Epoch: 7 | Accuracy: 91.7647%

Training epochs...: 40% | 8/20 [08:03<12:35, 62.97s/it]

Saving Best Model with Accuracy: 92.94117647058823

Epoch: 8 | Accuracy : 92.9412%

Training epochs...: 45% | 9/20 [09:08<11:39, 63.58s/it]

Saving Best Model with Accuracy: 93.23529411764706

Epoch: 9 | Accuracy: 93.2353%

Training epochs...: 50% | 10/20 [10:13<10:39, 64.00s/it]

Saving Best Model with Accuracy: 94.11764705882354

Epoch: 10 | Accuracy: 94.1176%

Training epochs...: 55% | 11/20 [11:17<09:37, 64.13s/it]

Epoch: 11 | Accuracy: 93.2353%

Training epochs...: 60% | 12/20 [12:22<08:35, 64.38s/it]

Epoch: 12 | Accuracy: 93.5294%

Training epochs...: 65% | | 13/20 [13:29<07:34, 64.98s/it]

Epoch: 13 | Accuracy: 92.9412%

Training epochs...: 70% | 14/20 [14:35<06:32, 65.42s/it]

Epoch: 14 | Accuracy: 93.5294%

Training epochs...: 75% | 15/20 [15:41<05:28, 65.73s/it]

Epoch: 15 | Accuracy: 94.1176%

Training epochs...: 80% | 16/20 [16:56<04:33, 68.30s/it]

Epoch: 16 | Accuracy: 94.1176%

Training epochs...: 85% | 17/20 [18:12<03:32, 70.77s/it]

Saving Best Model with Accuracy: 94.70588235294117

Epoch: 17 | Accuracy: 94.7059%

Training epochs...: 90% | 18/20 [19:26<02:23, 71.79s/it]

Epoch: 18 | Accuracy: 93.8235%

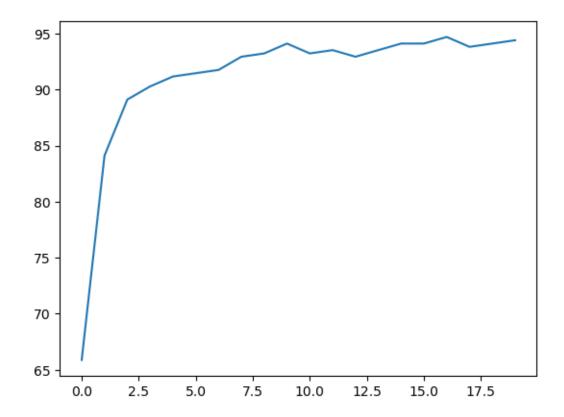
Training epochs...: 95% | 19/20 [20:46<01:14, 74.04s/it]

Epoch: 19 | Accuracy: 94.1176%

Training epochs...: 100% | 20/20 [22:03<00:00, 66.17s/it]

Epoch: 20 | Accuracy: 94.4118%

Model saved in: models/GoogLeNet-FT1-flowers-e-20-lr-0.0001-94.71.pkl



```
[]: def sample_and_predict ( net, dataset, my_transform, seed=None ) :
    if seed is not None :
        np.random.seed(seed)

my_transform = AlexNet_Weights.IMAGENET1K_V1.transforms()
    i = np.random.randint(len(dataset['test']))

sample, label = dataset['test'][i]

my_tensor_image_show(sample, label=label)
```

```
print( f'Sample id: {i:3d}' )
   x = my_transform(sample)
   # print(x.shape)
   x = x.unsqueeze_(0)
   # print(x.shape)
   x = x.to(my_device)
   output = net ( x )
   predictions = output.squeeze(0).softmax(0)
   predicted_class = torch.argmax(predictions)
   predicted_class = predicted_class.data.cpu().item()
   confidence = predictions[predicted_class]
   confidence = confidence.data.cpu().item()
   if predicted_class == label : print('Hit')
   else: print('Miss')
   print(f"Predicted: {predicted_class} | Corrected: {label} | Confidence:

√{confidence*100:.2f}%"
)
   # return dataset_classes[y], dataset_classes[data[i][1]], confidence
sample_and_predict(net, dataset, my_transform)
```

Image in tensor format | Class: 15



```
Sample id: 165
Hit
Predicted: 15 | Corrected: 15 | Confidence: 87.02%
```

```
[51]: test_accuracy = validate(net, dataloader['test'], my_device)
print(f'Model accuracy on test split of the dataset: {test_accuracy:.2f}%')
```

Model accuracy on test split of the dataset: 95.29%

4 3) Image Retrieval

```
[52]: %matplotlib inline
  import matplotlib.pyplot as plt
  from PIL import Image
  import numpy as np
  from tqdm import trange
  import random
```

```
import scipy.io
import tqdm
```

4.0.1 Image Display

```
[53]: def show_top_images ( dataset_path, indices , id_test , ids , labels ) :
          label = (ids[id test] - 1) // 80
          name = dataset_path + '/jpg/' + str(label) + '/image_' + str(ids[id_test]).
       ⇔zfill(4) + '.jpg'
          image = Image.open( name )
          top = 0
          show_image_label(top, image, labels[id_test], ids[id_test] )
          accuracy = 0
         for i in indices[0] :
              label_i = labels[i]
              name = dataset_path + '/jpg/' + str(label_i) + '/image_' + str(ids[i]).
       ⇔zfill(4) + '.jpg'
              image = Image.open( name )
              show_image_label(top, image, label_i, ids[i] )
              top = top + 1
      def show_image_label ( top, image, label , image_id ) :
          plt.figure(figsize = (5,5))
          plt.imshow(image, aspect='auto')
          plt.axis('off')
          plt.title(f'{top} - Image id {image_id} with label {label}.')
          plt.show()
```

4.0.2 Generate descriptors

```
[54]: def create_deep_descriptors (image, model, my_transform, my_device='cpu') :
    model_input = my_transform(image)
    model_input = model_input.unsqueeze_(0)

model = model.to(my_device)
    model_input = model_input.to(my_device)
```

```
model.eval()
with torch.no_grad():
    desc_deep = model(model_input).squeeze(0)
return desc_deep.to('cpu')
```

4.0.3 Data

```
[55]: def represent_dataset( dataset_path, model, my_transform, my_device ) :
          mat = scipy.io.loadmat( dataset path+'/datasplits.mat' )
          ids = mat['tst1'][0] # 'tst1' or 'trn1' or 'val1'
          space = []
          labels = []
          for id in tqdm.tqdm(ids, desc='Processing test set') :
              label = (id - 1) // 80
              name = dataset_path + '/jpg/' + str(label) + '/image_' + str(id).
       ⇒zfill(4) + '.jpg'
              image = Image.open( name )
              if image is None:
                  print(f'Reading image Error. Path: {name}')
                  return None
              desc_deep = create_deep_descriptors(image, model, my_transform,__
       →my_device)
              space.append(desc_deep)
              labels.append(label)
          print( ' -> [I] Space Describing Info:\n',
              '\nNumber of images: ', len(space),
              '\nNumber of labels: ', len(labels),
              '\nDimension: ', len(space[0])
              )
          return space , labels
```

```
knn = NearestNeighbors(n_neighbors=top+1).fit(space)
  mat = scipy.io.loadmat( dataset_path+'/datasplits.mat' )
  ids = mat['tst1'][0] # 'tst1' or 'trn1' or 'val1'
  accuracy t = 0
  for id_test in tqdm.tqdm(ids, desc='running the test phase') :
      label = (id test - 1) // 80
      name = dataset_path + '/jpg/' + str(label) + '/image_' + str(id_test).
⇒zfill(4) + '.jpg'
      image = Image.open( name )
      desc_deep = create_deep_descriptors(image, model, my_transform,__

y_device)

      indices = knn.kneighbors(desc_deep.reshape(1, -1))[1]
      labels_top = [ labels[i] for i in indices[0] ]
      accuracy = sum( np.equal(labels_top, label) )
      accuracy = ((accuracy-1)/(top)) * 100
      accuracy_t = accuracy_t + accuracy
  print(f'Average accuracy in the test set: {accuracy_t/len(ids):5.2f}%')
```

4.0.4 Experimental evaluation

```
if image is None:
      print(f'Reading image Error. Path: {name}')
      return None
  desc_deep = create_deep_descriptors(image, model, my_transform, my_device)
  distances, indices = knn.kneighbors(desc_deep.reshape(1, -1))
  show_top_images(dataset_path, indices, id_test, ids, labels)
  labels_top = [ int(labels[i]) for i in indices[0] ]
  accuracy = sum( np.equal( label , labels_top ) )
  accuracy = ((accuracy-1)/(top)) * 100
  print(f'Accuracy for image id {ids[id_test]}: {accuracy:5.2f}%')
  print(name)
  print(f'Image: {ids[id_test]} with label {labels[id_test]}')
  print(f'Closest image: {ids[indices[0][0]]} with distance {distances[0][0]}
→and label {labels[indices[0][0]]}')
  print('Distances: ',distances)
  print('Indices: ',indices[0])
  print('Labels: ',labels_top)
```

4.0.5 Create and load weights of the Descriptor model

```
if torch.cuda.is_available():
    my_device = torch.device("cuda:0")
else:
    my_device = torch.device("cpu")

print(f"Running on {my_device.type}.")
```

Running on cpu.

4.0.6 Execution

Processing test set: 100% | 340/340 [00:29<00:00, 11.54it/s]

-> [I] Space Describing Info:

Number of images: 340 Number of labels: 340

Dimension: 1024

running the test phase: 100% | 340/340 [00:30<00:00, 11.01it/s]

Average accuracy in the test set: 89.50%

```
[]: # For a random image of the testing split of the dataset, use the image as the
      \hookrightarrow query
     # for the image retrieval problem, i.e., describe the image using the model \Box
      \hookrightarrow descriptor,
     # and search for the k closest descriptors of the images in the testing split_{\sqcup}
     # After that, measure the accuracy of the image retrieval by counting how many u
      \hookrightarrow of the k
     # retrieved images has the same label of the query image, and divide it by k.
     # This result will be the accuracy of the image retrieval result for that \Box
      ⇔specific image.
     # Also display the query image, and all k images returned by the image_\sqcup
      \hookrightarrowretrieval problem.
     # For each returned image, also display its class, and the Euclidean distance
      ⇔between its
     # descriptor and the descriptor of the query image.
     \# Since the query image also is in the testing split of the dataset, it is \sqcup
      ⇔expected that
     # the first returned image is the query image itself, and the distance between \square
      \hookrightarrow the
     # descriptors to be zero.
     retrieve_single_image( space, labels, dataset_path_cbir, model_descriptor,_
      →my_transform, my_device)
```

Complete the table with the results from the run test cell

Results:

Model	Accuracy	Descriptor dim
Sift	20.94%	100
Orb	18.03%	100
Random	11.94%	100
Grid 50x50	12.00%	100
LBP	07.00%	100
AlexNet	54.50%	4096
VGG16	51.41%	4096
GoogLeNet	56.82%	1024
GoogLeNet FT	89.50%	1024