

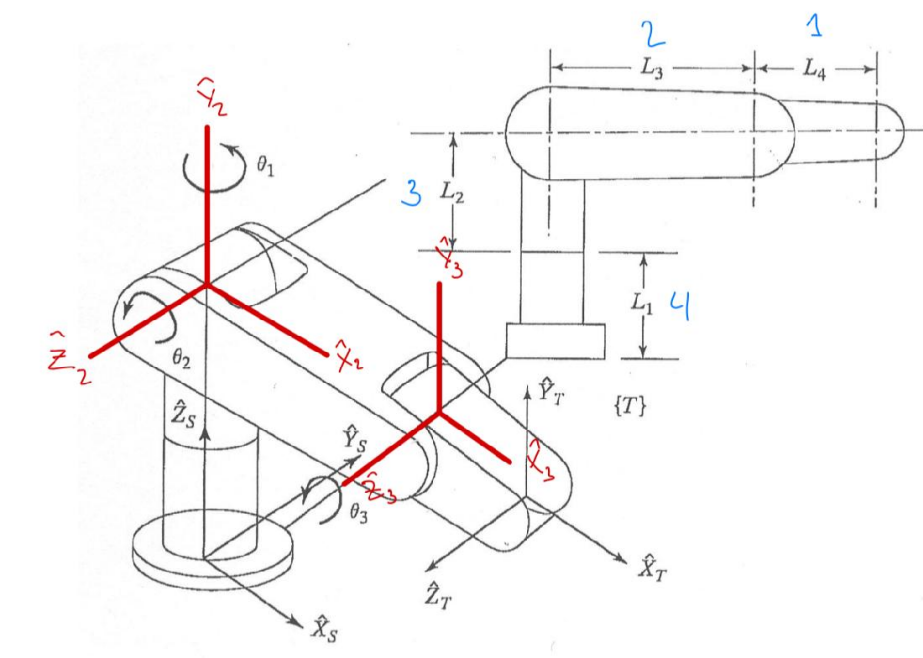
FORWARD KINEMATICS

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FRAMES



DH PARAMETERS

```
clear
mdl_3L_me
p3LCraigh
```

```
p3LCraigh =
3L-Craigh-Ivan&Jose [Unimation]:: 3 axis, RRR, stdDH, slowRNE
- Craigh;
```

j	theta	d	a	alpha	offset
1	q1	7	0	1.5708	0
2	q2	0	2	0	0
3	q3	0	1	0	0

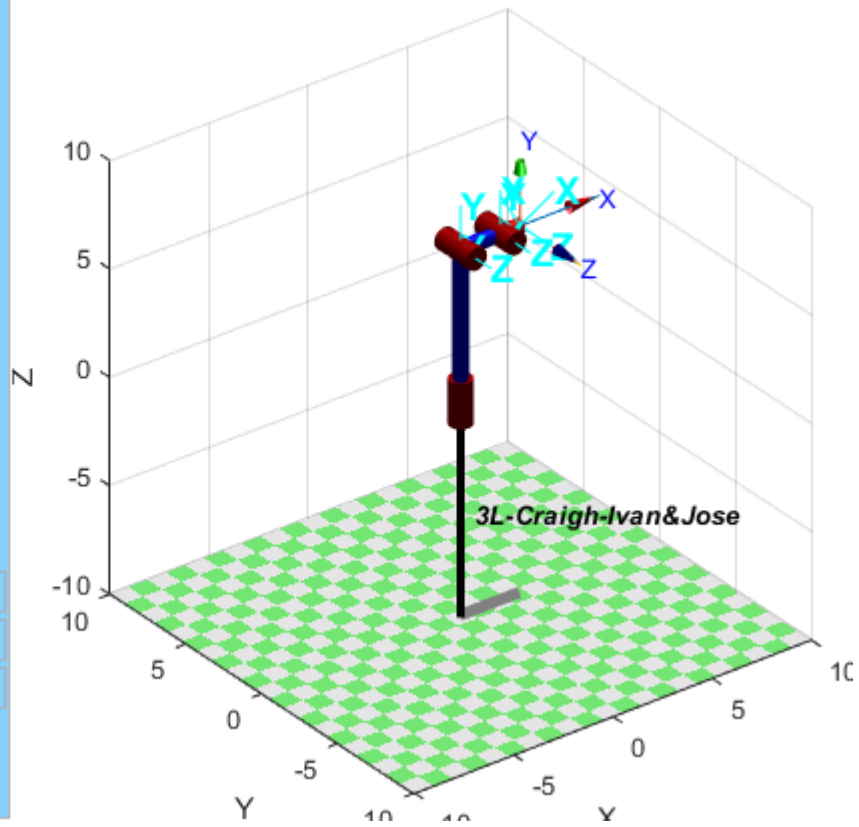
```
figure
p3LCraigh.plot([0,0,0], 'zoom',1.5)
```

Teach

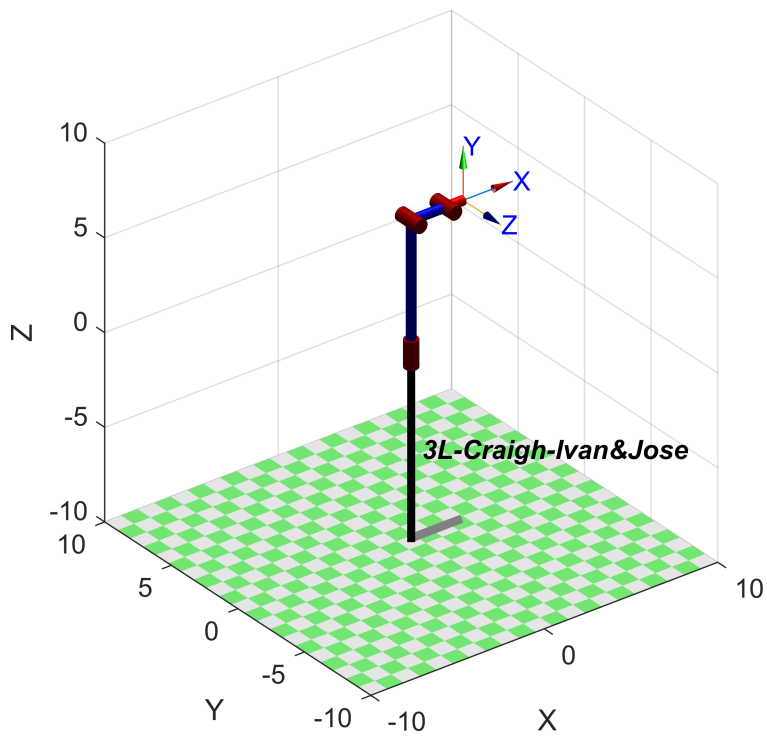
X: 3.000
Y: 0.000
Z: 7.000

R: -0.000
P: 0.000
Y: 90.000

q1 0
q2 0
q3 0



hold off

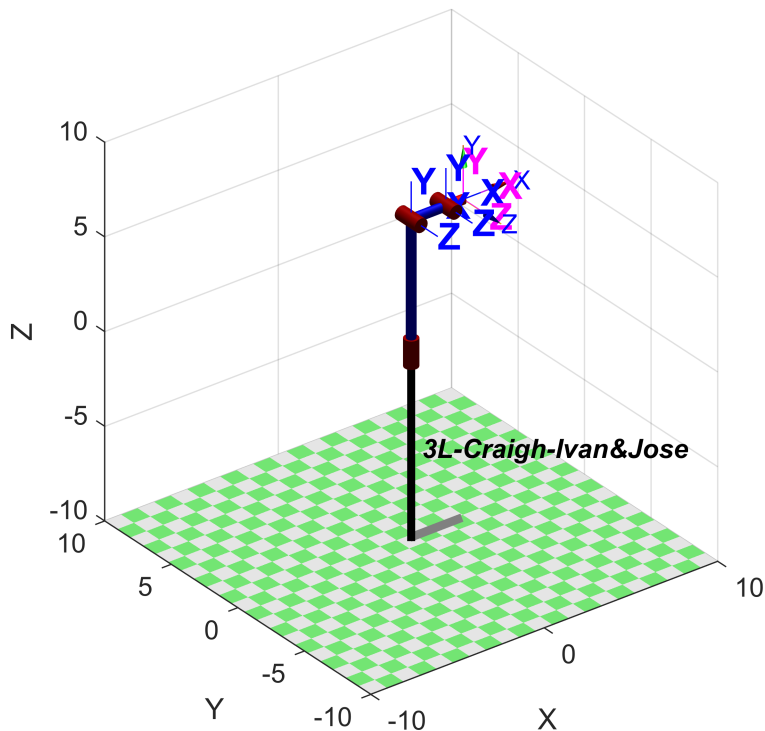


IMPLEMENT T_S

```
T_S_T = eye(4);
T_2_3 = T_S_T * link_A_B_Std(pi/2, 0, 7, 0);
T_1_2 = T_2_3 * link_A_B_Std(0, 2, 0, 0);
T_0_1 = T_1_2 * link_A_B_Std(0, 1, 0, 0);

T_EE_HANDMADE = T_0_1;

hold on
trplot(T_EE_HANDMADE, 'length', 2, 'width', 0.5, 'color', 'magenta', 'text_opts',
{'FontSize', 14, 'FontWeight', 'bold'})
trplot(T_2_3, 'length', 2, 'width', 0.5, 'color', 'blue', 'text_opts', {'FontSize',
14, 'FontWeight', 'bold'})
trplot(T_1_2, 'length', 2, 'width', 0.5, 'color', 'blue', 'text_opts', {'FontSize',
14, 'FontWeight', 'bold'})
hold off
```



a) (0,0,0)

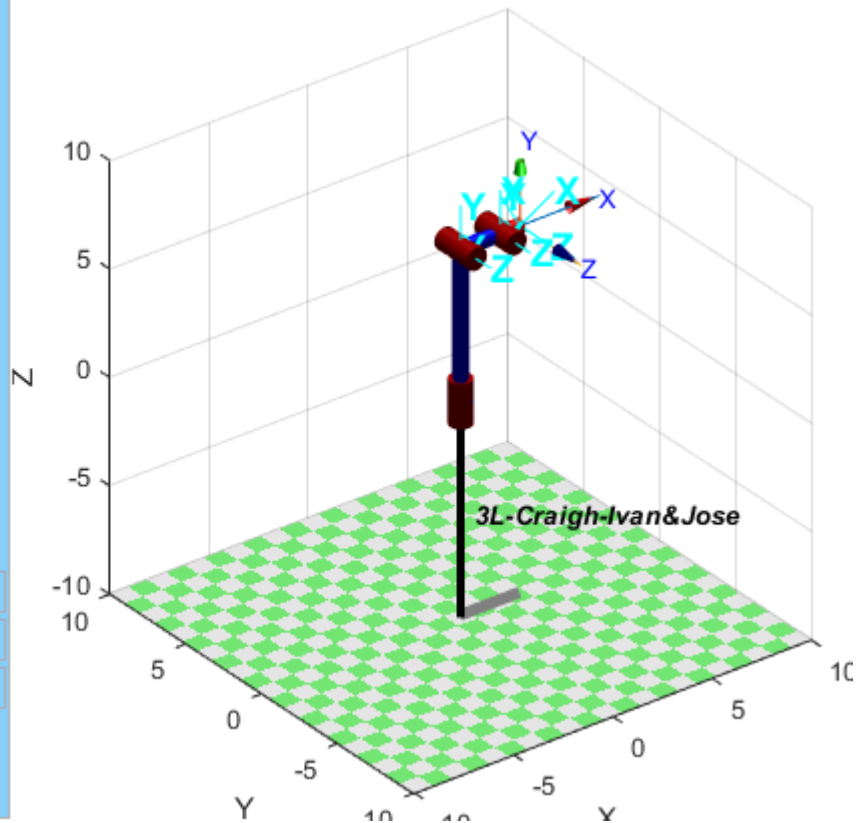
```
clf
p3LCraigh.teach
```

Teach

X: 3.000
Y: 0.000
Z: 7.000

R: -0.000
P: 0.000
Y: 90.000

q1 0
q2 0
q3 0

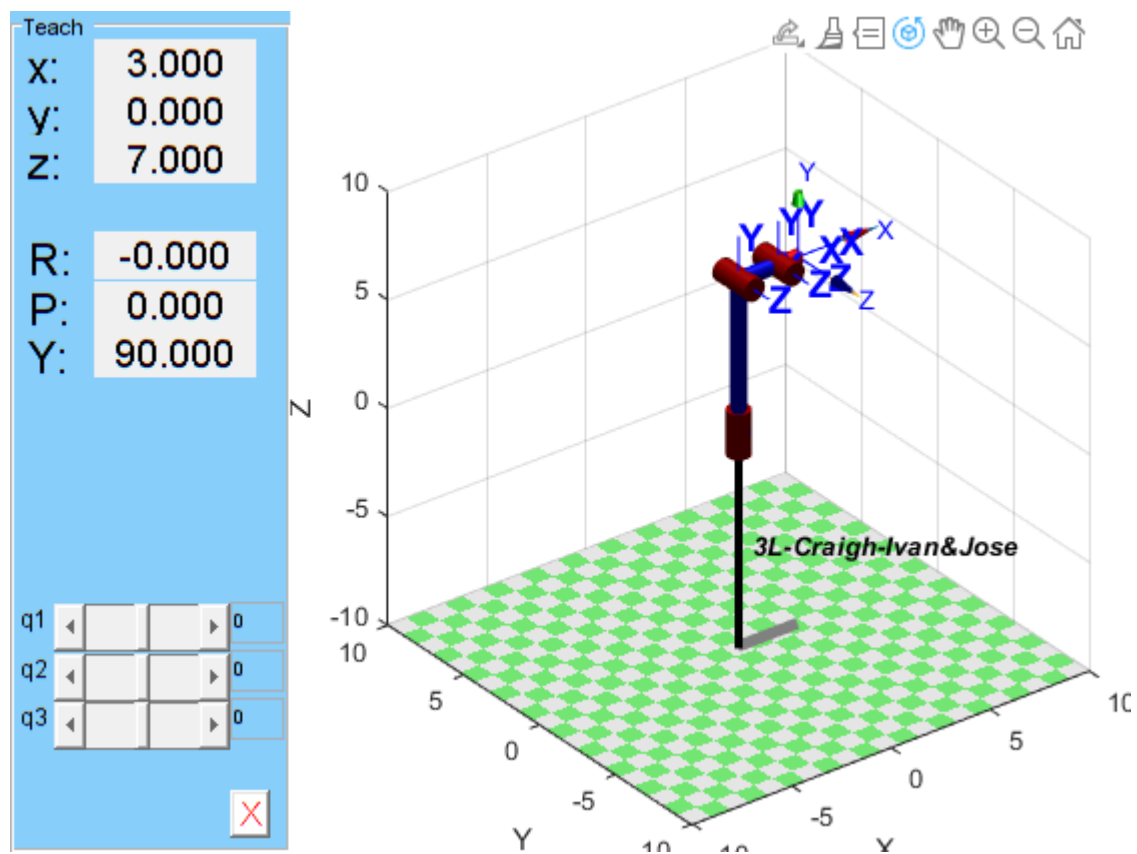


```
hold on
T_2_3_a = T_2_3 * troz(0);
T_1_2_a = T_1_2 * troz(0);
T_0_1_a = T_0_1 * troz(0);

T_S_T_a = T_0_1_a * T_1_2_a * T_2_3_a
```

```
T_S_T_a = 4x4
    1     0     0     5
    0     0     1    -7
    0    -1     0     0
    0     0     0     1
```

```
%trplot(T_EE_HANDMADE, 'length', 2, 'width', 0.5, 'color', 'magenta', 'text_opts',
{'FontSize', 14, 'FontWeight', 'bold'})
trplot(T_2_3_a, 'length', 2, 'width', 0.5, 'color', 'blue', 'text_opts',
{'FontSize', 14, 'FontWeight', 'bold'})
trplot(T_1_2_a, 'length', 2, 'width', 0.5, 'color', 'blue', 'text_opts',
{'FontSize', 14, 'FontWeight', 'bold'})
trplot(T_0_1_a, 'length', 2, 'width', 0.5, 'color', 'blue', 'text_opts',
{'FontSize', 14, 'FontWeight', 'bold'})
```



```
T_EE_1 = p3LCraig.fkine([0,0,0])
```

```
T_EE_1 =
    1     0     0     3
    0     0    -1     0
    0     1     0     7
    0     0     0     1
```

b) $(0, \pi/2, 0)$

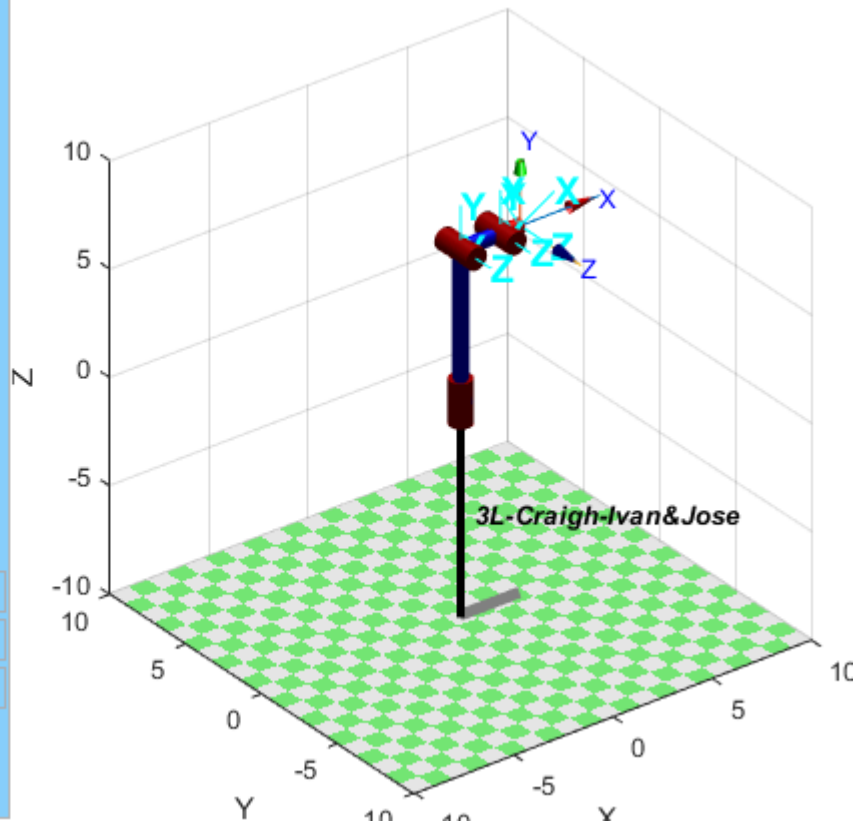
```
clf
p3LCraig.teach
```

Teach

X: 3.000
Y: 0.000
Z: 7.000

R: -0.000
P: 0.000
Y: 90.000

q1 0
q2 0
q3 0



```
hold on
T_2_3_b = T_2_3 * troz(0);
T_1_2_b = T_1_2 * troz(pi/2);
T_0_1_b = T_0_1 * troz(0);

T_S_T_b = T_0_1_b * T_1_2_b * T_2_3_b
```

```
T_S_T_b = 4x4
    0    0    1    5
   -1    0    0   -7
    0   -1    0    0
    0    0    0    1
```

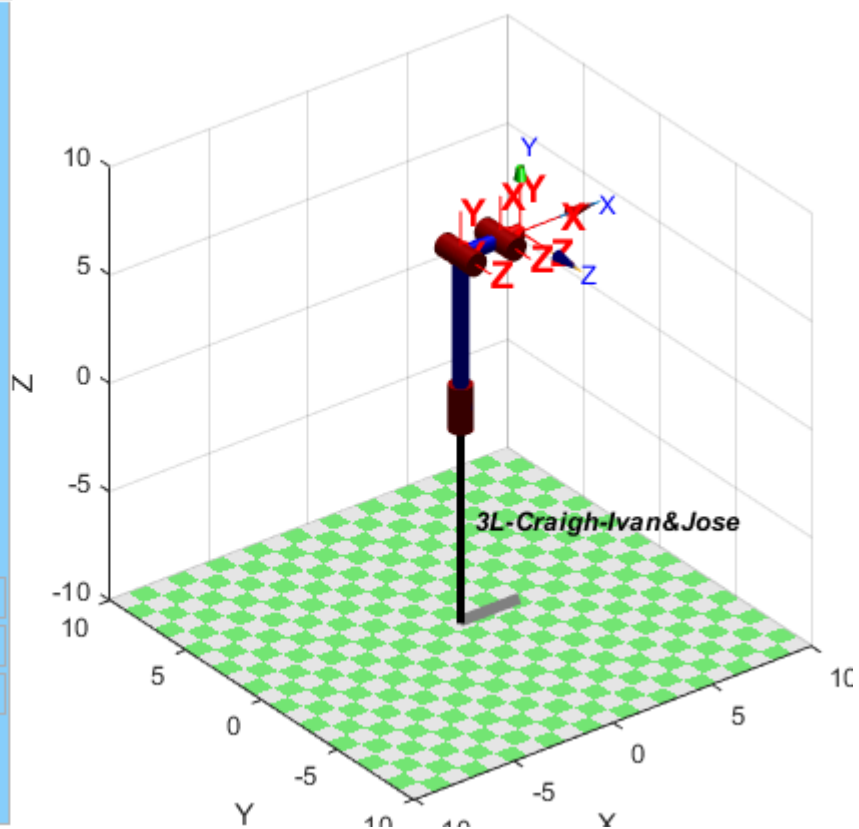
```
trplot(T_2_3_b, 'length', 2, 'width', 0.5, 'color', 'red', 'text_opts',
{'FontSize', 14, 'FontWeight', 'bold'})
trplot(T_1_2_b, 'length', 2, 'width', 0.5, 'color', 'red', 'text_opts',
{'FontSize', 14, 'FontWeight', 'bold'})
trplot(T_0_1_b, 'length', 2, 'width', 0.5, 'color', 'red', 'text_opts',
{'FontSize', 14, 'FontWeight', 'bold'})
hold off
```

Teach

X: 3.000
Y: 0.000
Z: 7.000

R: -0.000
P: 0.000
Y: 90.000

q1 0
q2 0
q3 0



c) $(0, \pi/2, \pi/6)$

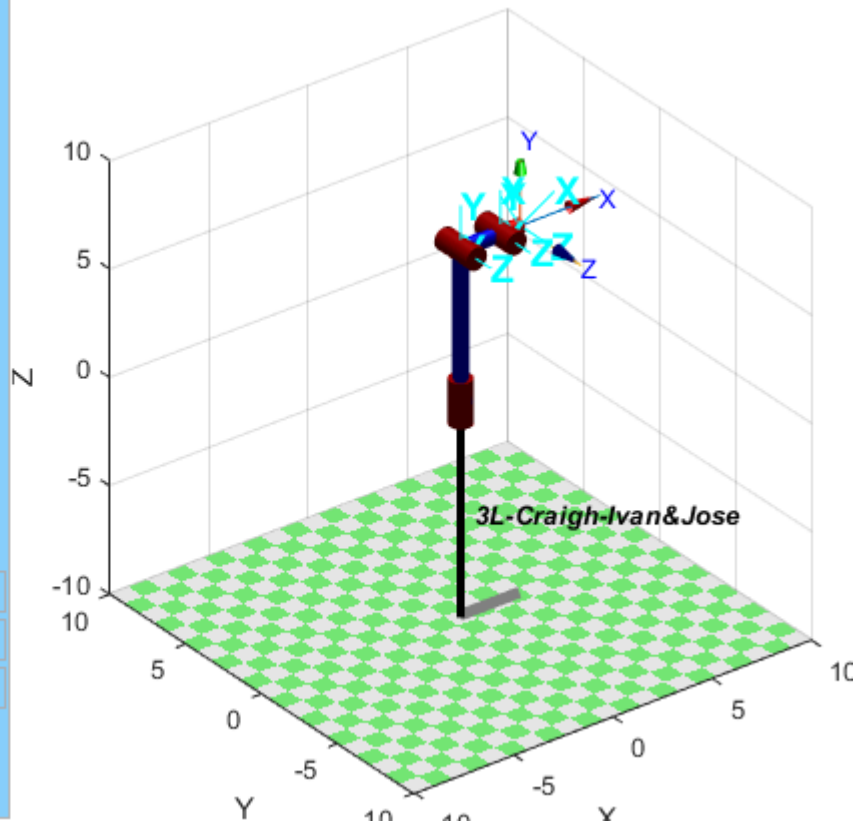
clf
p3LCraig.teach

Teach

X: 3.000
Y: 0.000
Z: 7.000

R: -0.000
P: 0.000
Y: 90.000

q1 0
q2 0
q3 0



```
hold on
T_2_3_c = T_2_3 * troz(0);
T_1_2_c = T_1_2 * troz(pi/2);
T_0_1_c = T_0_1 * troz(pi/6);

T_S_T_c = T_0_1_c * T_1_2_c * T_2_3_c
```

```
T_S_T_c = 4x4
    0    0.5000    0.8660    8.2321
   -1.0000    0    0    -7.0000
    0   -0.8660    0.5000    1.9378
    0    0    0    1.0000
```

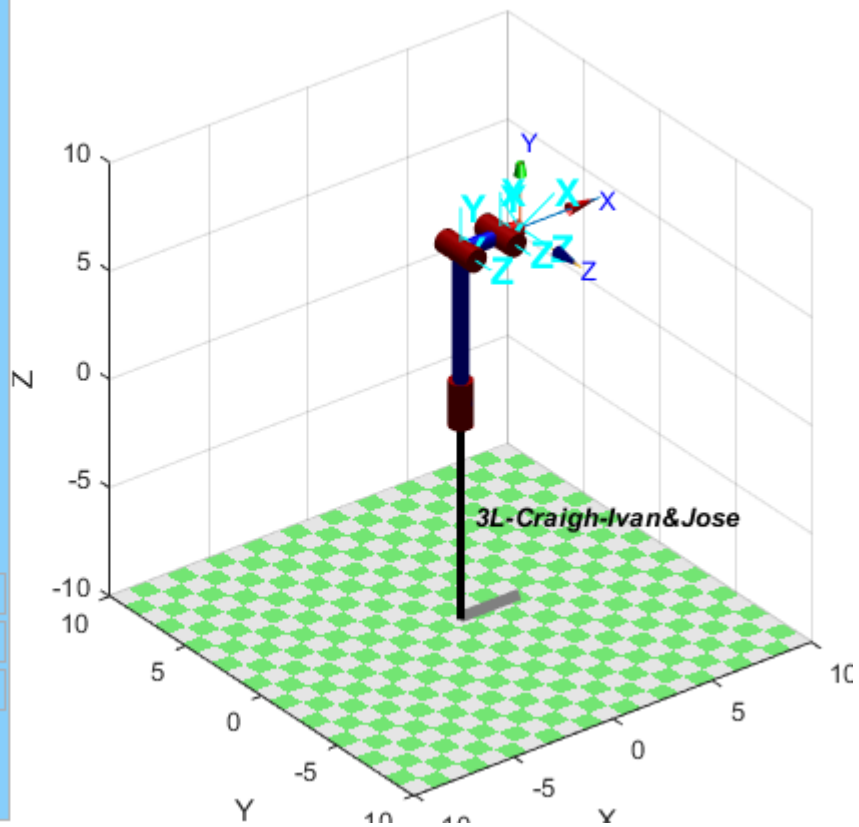
```
trplot(T_2_3_c, 'length', 2, 'width', 0.5, 'color', 'cyan', 'text_opts',
{'FontSize', 14, 'FontWeight', 'bold'})
trplot(T_1_2_c, 'length', 2, 'width', 0.5, 'color', 'cyan', 'text_opts',
{'FontSize', 14, 'FontWeight', 'bold'})
trplot(T_0_1_c, 'length', 2, 'width', 0.5, 'color', 'cyan', 'text_opts',
{'FontSize', 14, 'FontWeight', 'bold'})
```


Teach

X: 3.000
Y: 0.000
Z: 7.000

R: -0.000
P: 0.000
Y: 90.000

q1 0
q2 0
q3 0



Used Functions

```
function T_b_a=link_A_B_Std(alpha,a,d,theta)
T_b_a=trotz(theta)*transl(0,0,d)*transl(a,0,0)*trotx(alpha);
end
```