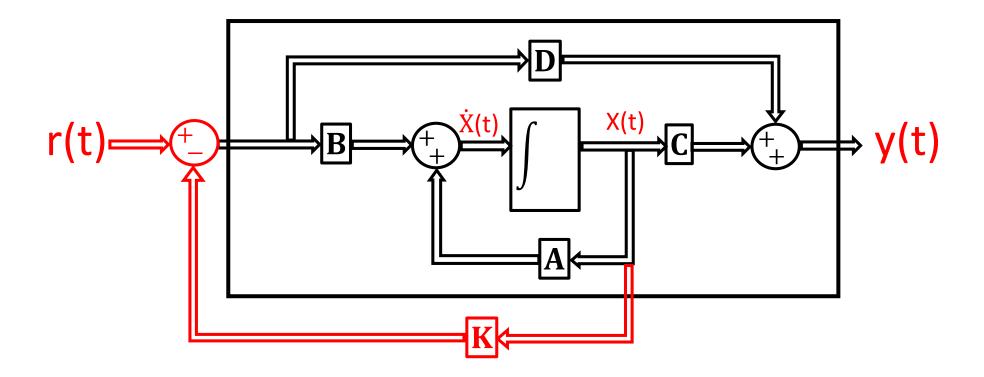
Diseño de Observadores de estado



Escuela de Ciencias Exactas e Ingeniería

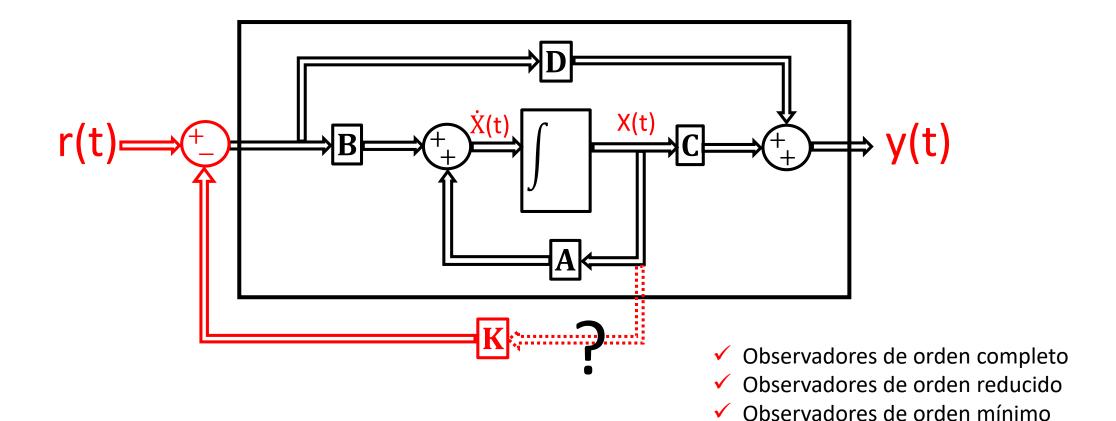


Observadores de estado



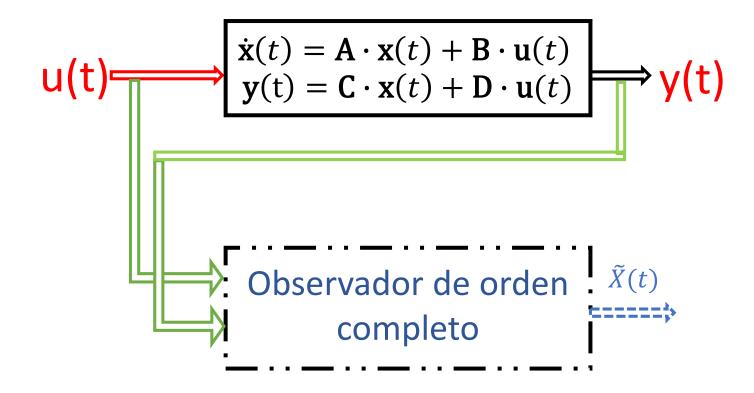


Observadores de estado

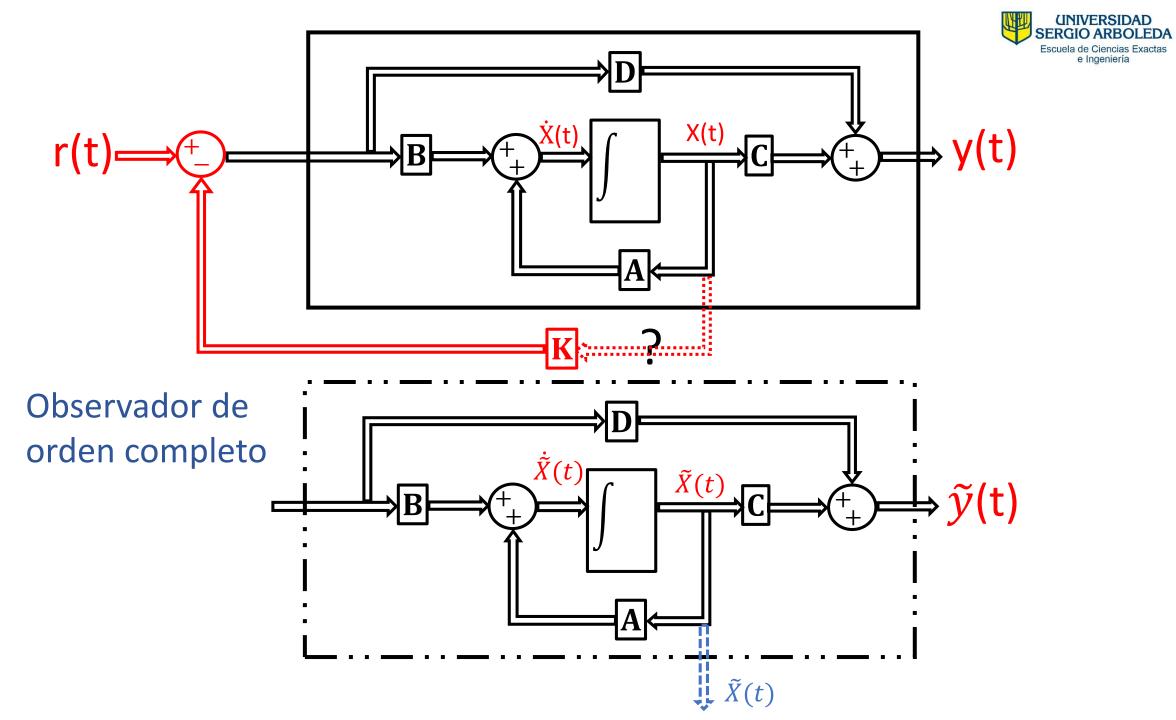


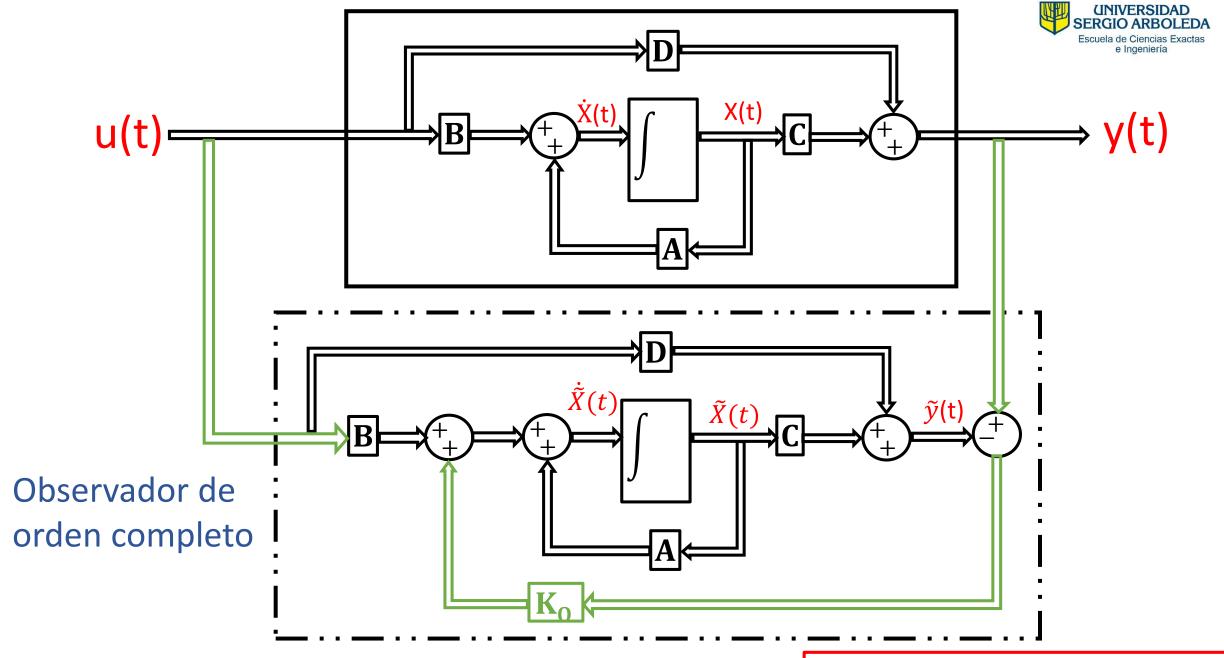


Observadores de orden completo

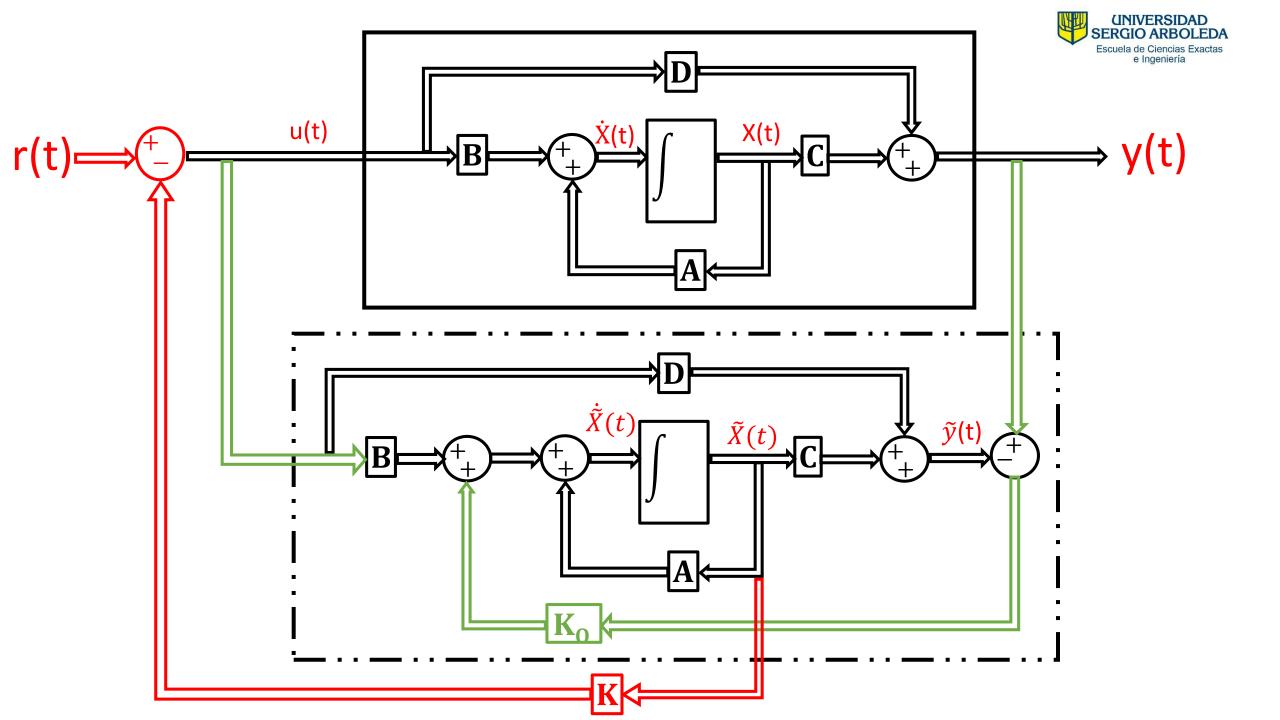


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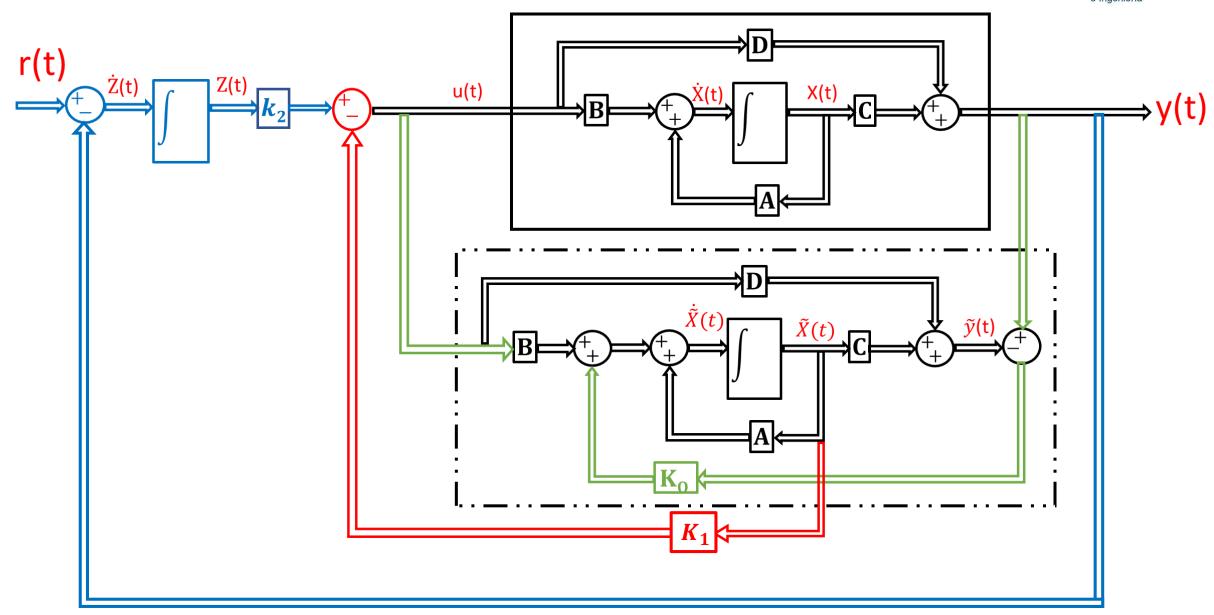




 $P(s) = \det(s \cdot I - A + K_0 \cdot C)$

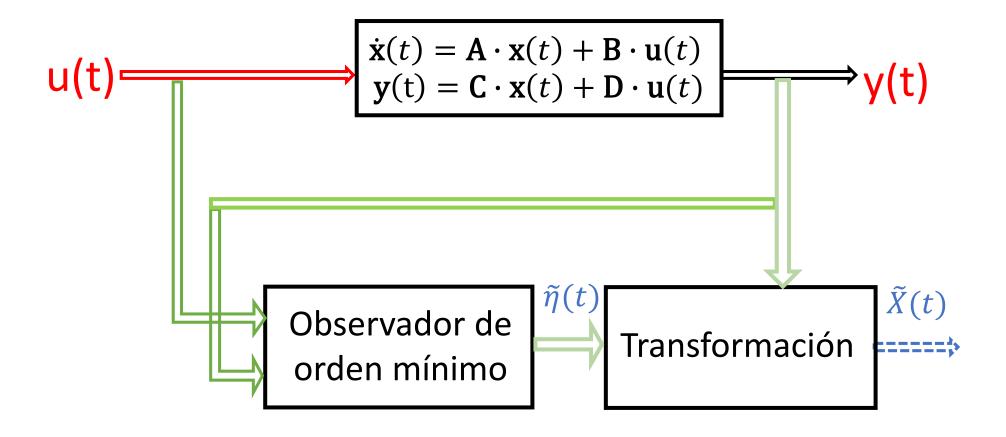








Observadores de orden mínimo



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