Client-driven Transmission of JPEG2000 Image Sequences using Motion Compensated Conditional Replenishment

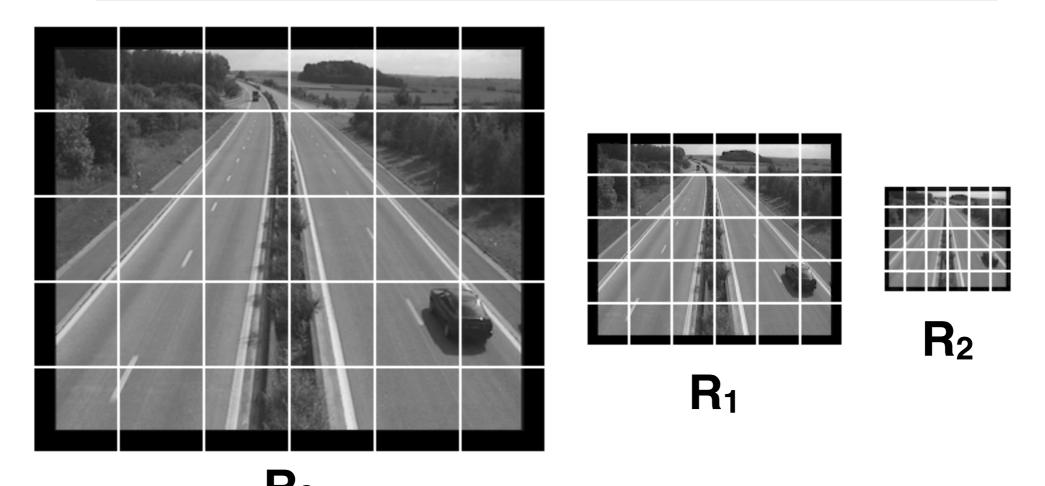
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Image Requirements

The images have to be compressed with the same number of precincts for each resolution level.

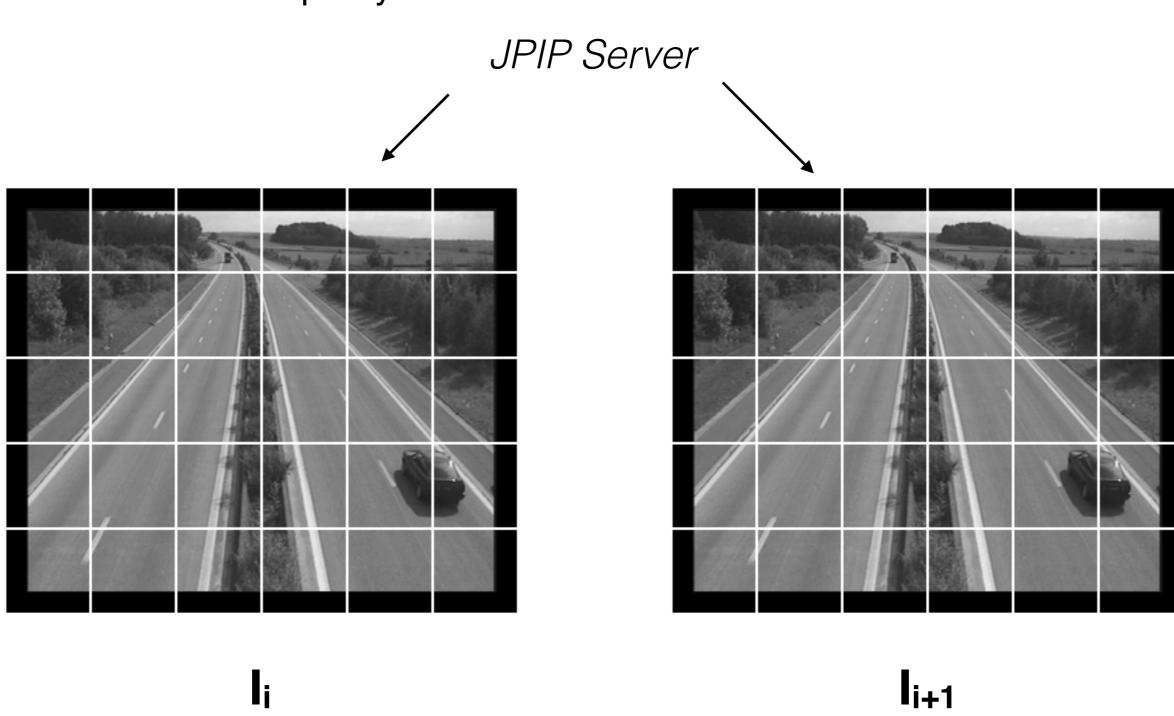
For example: Speedway sequence (384x320)

```
CLEVELS=2
CPRECINCTS="{64,64},{32,32},{16,16}"
CBLK="{16,16}"
```



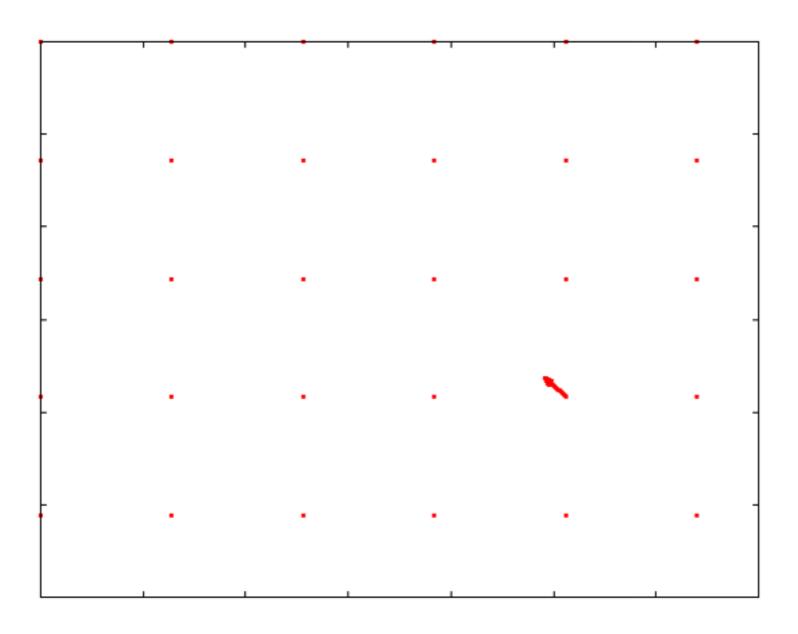
Algorithm

1. Download two consecutive images of the sequence, I_i and I_{i+1} , at maximum quality and maximum resolution.

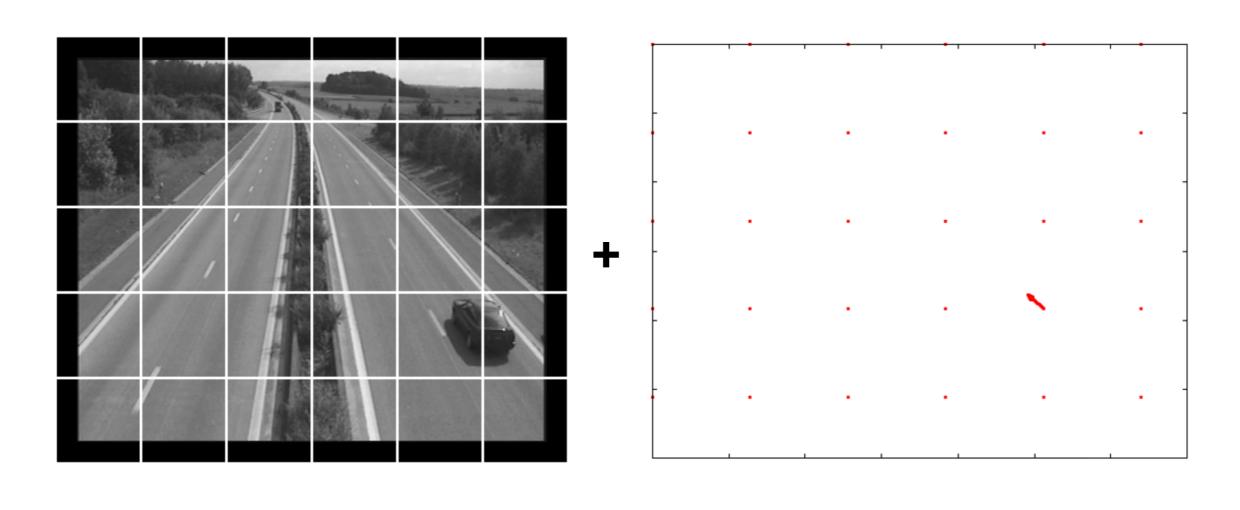


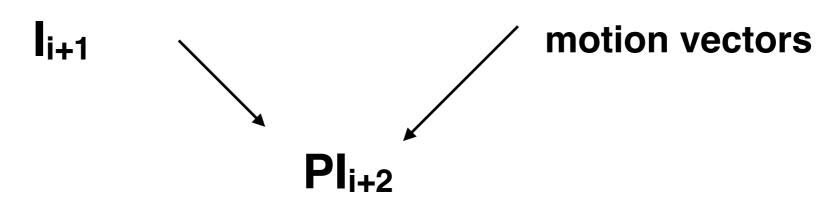
Calculate the motion vectors between the two images, \mathbf{l}_{i} and \mathbf{l}_{i+1} , at maximum quality and maximum resolution.

The block size used in the motion estimation matches with the precinct size.

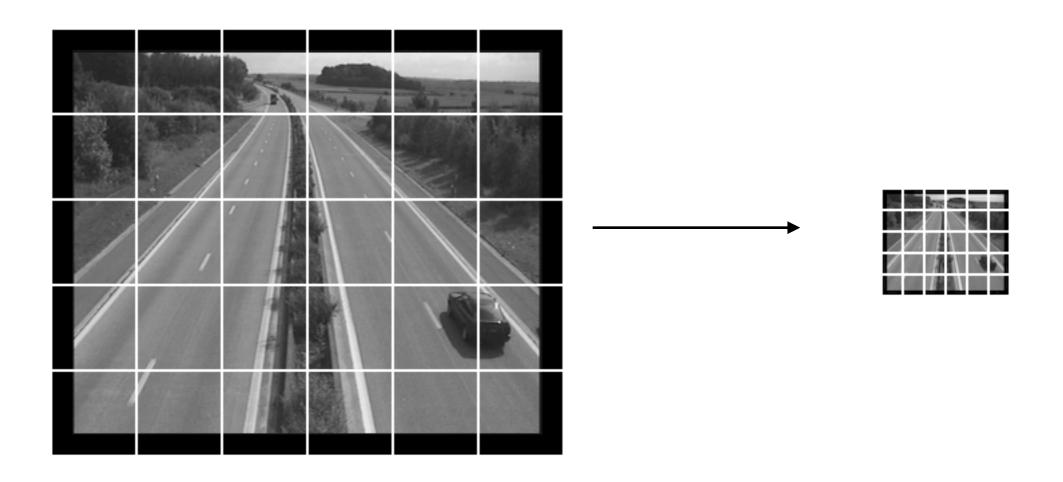


3. Generate a prediction image, Pl_{i+2} from image l_{i+1} and the motion vectors calculated in the previous step.





4. Generate the thumbnail (using a lower resolution level) of the prediction image Pl_{i+2} , Thumbnail(Pl_{i+2}).

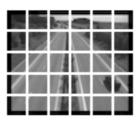


 PI_{i+2}

Thumbnail(Pl_{i+2})

5. Download the thumbnail for the next image of the sequence, Thumbnail(I_{i+2}).

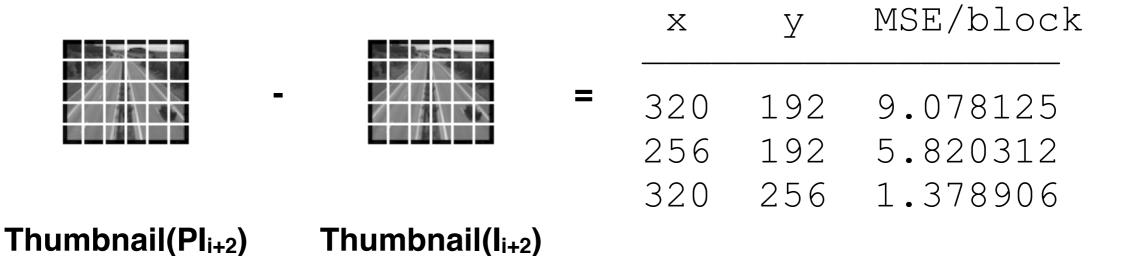
JPIP Server



Thumbnail(I_{i+2})

5. Calculate the difference between the thumbnail prediction image, Thumbnail(Pl_{i+2}) and the thumbnail of the next image of the sequence, Thumbnail(l_{i+2}).

The result of this step give us a list of precincts sorted by distortion.

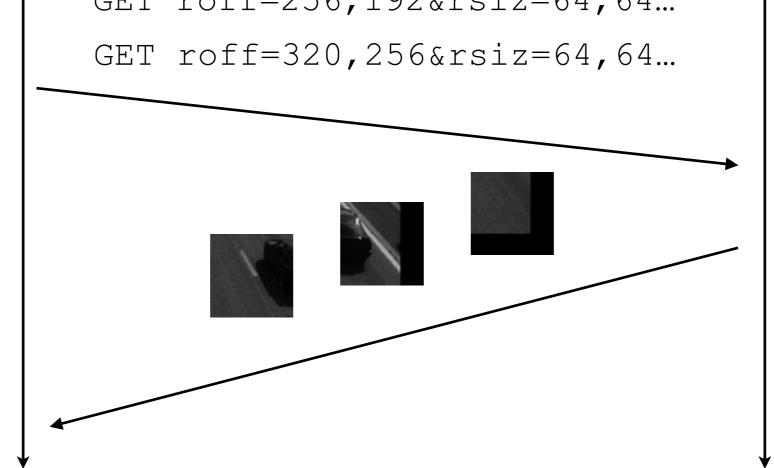


Retrieve from the server the previous list of WOIs for the next image, I_{i+2} . Note that 1 WOI = 1 precinct. The total number of sent WOIs depends on the channel capacity.

Client

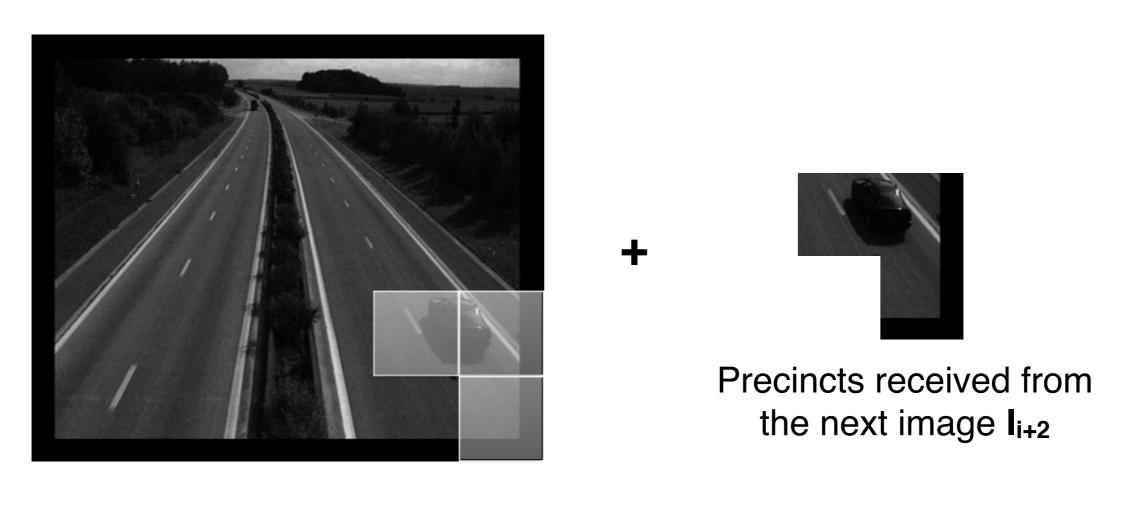
| GET roff=320,192&rsiz=64,64...

| GET roff=256,192&rsiz=64,64... | GET roff=256,192&rsiz=64,64... |



Time

8. Merge the precincts received for the next image I_{i+2} with the prediction image PI_{i+2}.



 PI_{i+2}

9. Update the index of the images and go to step 2.

Experiments

Speedway: sequence of 50 images of 384x320 pixels.

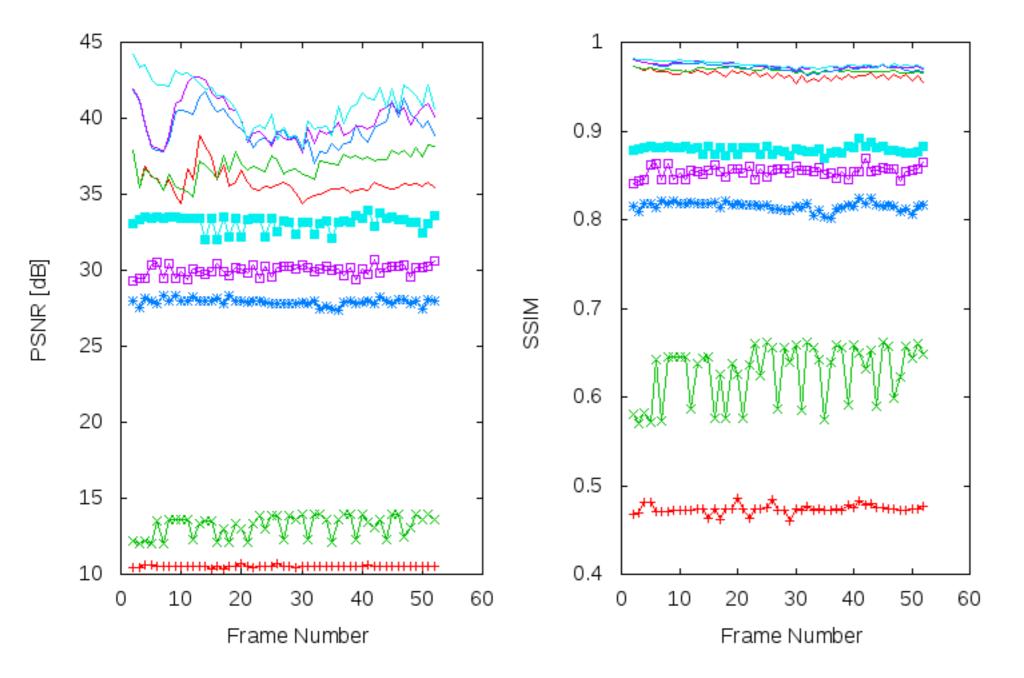
- Compression parameters used in kdu compress

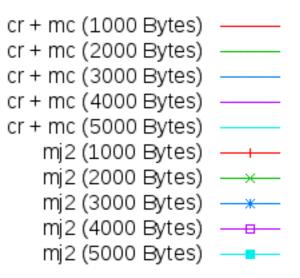
```
CLAYERS=8
CLEVELS=2
CPRECINCTS="{64,64},{32,32},{16,16}"
CBLK="{16,16}"
Corder=LRCP
```

- Motion estimation parameters

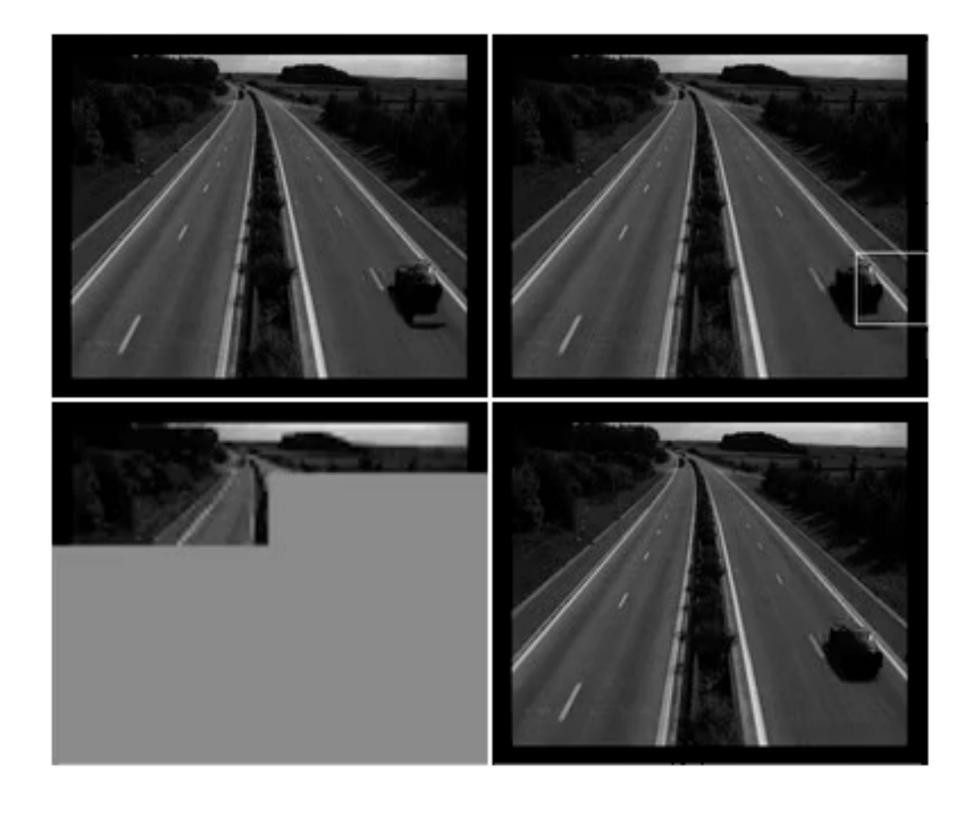
```
B=64  # block size
A=0  # subpixel accuracy
D=0  # border size
S=4  # search range
V=2  # block overlapping
```

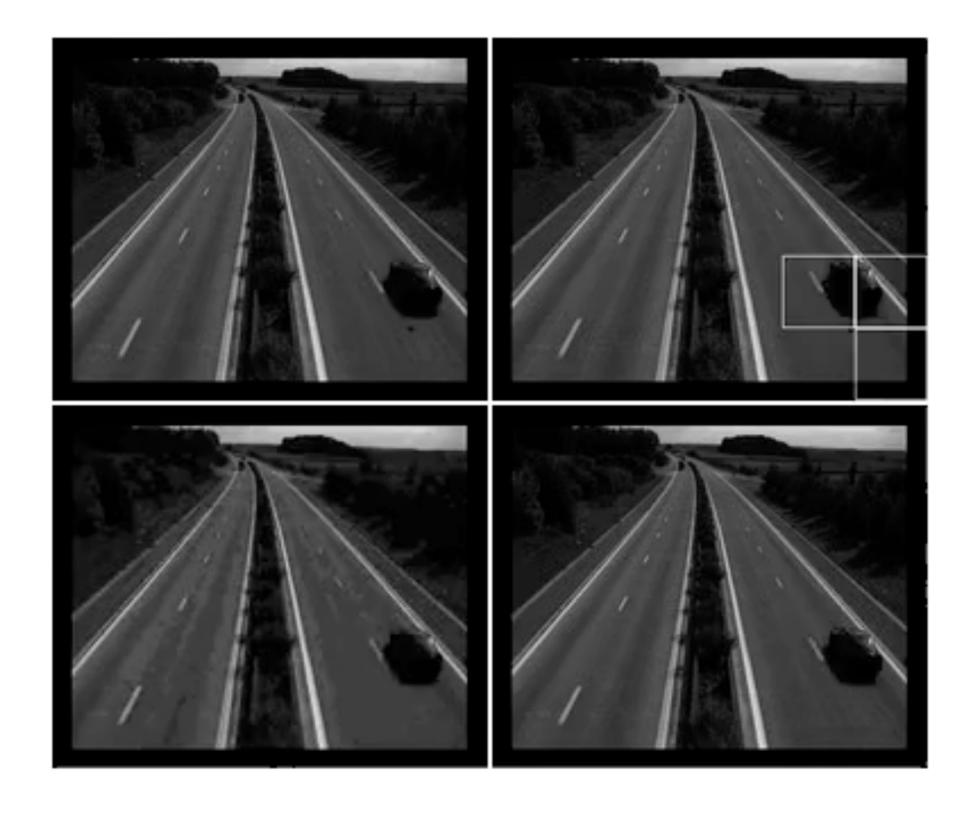
PSNR and SSIM





*Bytes per image





Experiments

Stockholm: sequence of 90 images of 1280x768 pixels.

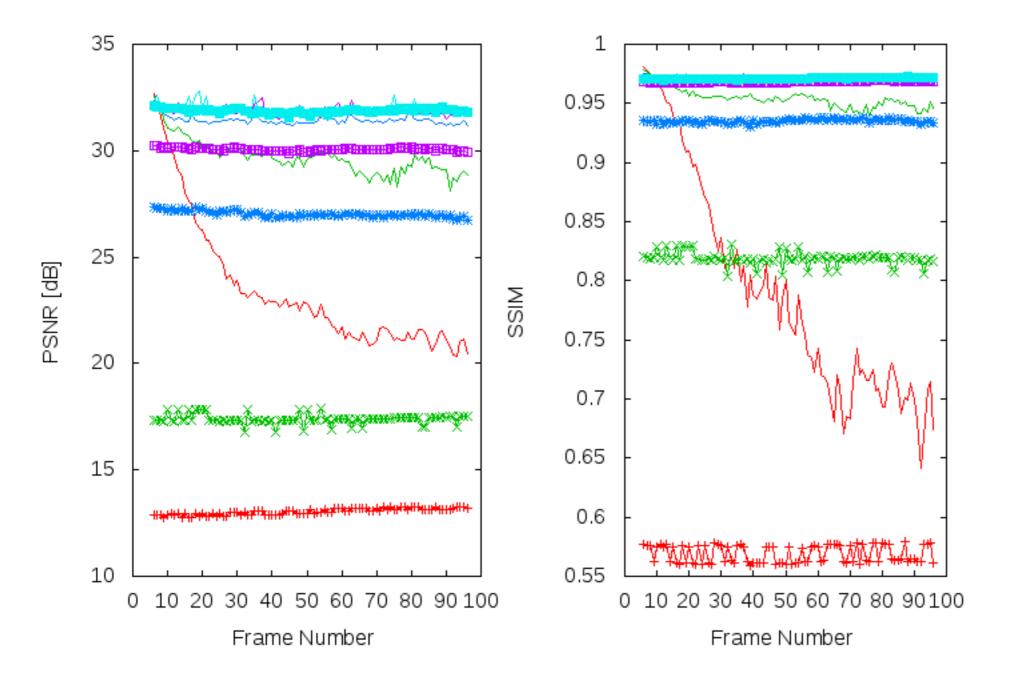
- Compression parameters used in kdu compress

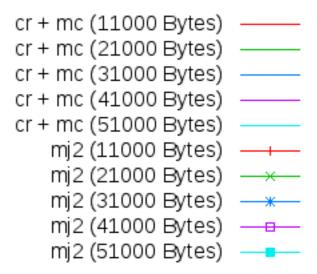
```
CLAYERS=8
CLEVELS=2
CPRECINCTS="{128,128}, {64,64}, {32,32}"
CBLK="{32,32}"
Corder=LRCP
```

- Motion estimation parameters

```
B=128  # block size
A=2  # subpixel accuracy
D=0  # border size
S=4  # search range
V=2  # block overlapping
```

PSNR and SSIM





*Bytes per image







Experiments

Stockholm: sequence of 90 images of 1280x768 pixels.

- Compression parameters used in kdu compress

```
CLAYERS=8
CLEVELS=2
CPRECINCTS="{32,32},{16,16},{8,8}"
CBLK="{8,8}"
Corder=LRCP
```

- Motion estimation parameters

```
B=128  # block size
A=2  # subpixel accuracy
D=0  # border size
S=4  # search range
V=2  # block overlapping
```



