Community Detection

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Setup

Networks

Network's are common ways of visualizing and representing large data. It's common for networks to become quite large very quickly:



Figure: (Abbe, 2017) [1]

This can represent anything from social interactions, to stock trades, to biological processes.

Motivating Example

Over a 2 year period sociologists closely followed a subject, Zachary, to their Karate club of 34 people. Friendships were recorded amongst the members were marked as edges, with individuals being vertices, resulting in the following network:



Figure: (Newman, 2002) [6]

One might desire to identify factions/friend circles and suggest the growth of these factions by recommending two people meet. Think Facebook friend recommendations.

Community Detection: Community

Community Detection

The goal of community detection is to partition a network in such a way as to find the subgraphs that are internally highly connected and externally sparsely connected.

Definition (Community)

Let G = (V, E) be a simple graph, with degree n. A community of $H = (V_H, E_H) \subset G$ is a subgraph of G, such that for any $h \in V_H$, let h_i be the number of internal connections of h in H (that is edges of h in E_H) and h_e be the number of external connections of h (that is, edges of h in $E = E_H$), then

$$h_e << h_i$$
.

This can be generalized to weighted graphs, by considering sums of weights instead of number of connections.

Community Detection: Goal

Goal

Without a priori knowledge of these communities, this is a difficult problem to solve. The goal is to recover structures like this:



Figure: (Abbe, 2017) [1]

Community Detection: Types of Algorithms

There are many different approaches on how to do this, one way to classify these algorithms is by their domain of consideration:

- Node-Centric, seek to solve the problem by rules imposed on individual nodes;
- Network-Centric, these tend to focus on the overall network topology;
- Hierarchy-Centric, these seek to reconstruct the network in such a way that reveals the hierarchical structure.

Community Detection: Node-Centric

k-Distance Communities

One classification technique is by determining communities via paths; for example, we might consider two nodes in the same community if they can be connected by a k-length path.

Formally , we can use this intuition to define a k-community V_s as the set such that:

$$d(v_i, v_j) \leq k \quad \forall v_i, v_j \in V_s,$$

where d(x,y) is some distance function and k is some upper-bound of this function.

Community Detection: Network-Centric

Latent Space Models

Latent space modeling takes the graph partition problem of graphs and maps it to Euclidean space.

That is take your nodes V from a weighted graph G and map them into a Euclidean space using a map determined by the shortest walk between two points. One such embedding is seen in the next slide:

Community Detection: Network-Centric

Latent Space Models

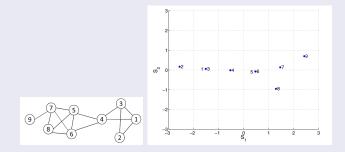


Figure: (Tang and Huan, 2010)[3]

From here, the method of k—means clustering can be employed to determine community structures in the new Euclidean space. We then map this back into our graph to determine our communities.

Community Detection: Hierarchy-Centric

Modularity Optimization

Hierarchical models focus on producing a hierarchy of nodes typically through an optimization of some objective function.

That is, some function of the graph and its communities that identifies community structure in some way.

Community Detection: Modularity

Definition (Modularity)

For a weighted graph G = (V, E) with an adjacency matrix A with N communities, we define the modularity of G:

$$Mod = \sum_{i=1}^{N} (e_{ii} - a_i^2) \qquad Q \in [-\frac{1}{2}, 1]$$

Where

- e_{ii} is the fraction of edges that end in the same community c_i ; $e_{ii} = \sum_{v,w \in c_i} \frac{A_{v,w}}{2m}$
- $2m = \sum_{i,j} A_{i,j};$
- \bullet a_i is the fraction of edges that are attached to a vertex in c_i .

This is measure of the clustering of the communities of G, a high Mod value, means we have a good community structure; meaning the partitions are highly internally connected, and sparsely externally connected.

Community Detection: Modularity

Examples of Modularity

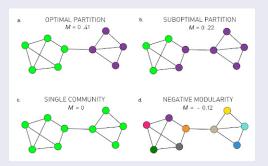


Figure: (Barabasi, 2013) [5], *M* = *Mod*

Community Detection: Modularity Maximization

Modularity Maximization Algorithm

From 4, this is a modified Girvan-Newman model. For a non-directed weighted graph G = (V, E) with |V| = N.

■ Phase 1:

- I (Initialization)
 Each node is assigned to one community; that is, every node v_i is assigned to community c_i . Pick some starting node v_1 .
- 2 (Modularity Testing) For each neighbor v_j , calculate ΔMod for each v_i ; that is, consider moving v_i from c_i and placing it in c_j , where c_j is the community of v_j .
- 3 (Modularity Optimization) Place v_i in the community c_j such that ΔMod is maximized. If necessary, employ a tie-breaking rule.
- 4 (Loop) Repeat for node v_{i+1} .
- 5 (Terminate) Continue iterating over the cells, with possible repeats, until $\Delta Mod = 0$ for all nodes v_i .

Community Detection: Modularity Maximization

Modularity Maximization Algorithm

- Phase 2:
 - I Initialize a non-directed weighted graph G' = (V', E') where each community C_j is now a node in V' and the edges and their weights are determined below;
 - 2 The sum of the inter-connected weights inside the community is weight of the self-loop;
 - 3 The weights of the external-edges, between the nodes, is determined by the sum of the connections between the two communities;
 - 4 Save G', and repeat phase 1 with G'.

References

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- 4 Blondel, Vincent D., et al. "Fast unfolding of communities in large networks." Journal of statistical mechanics: theory and experiment 2008.10 (2008): P10008.
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- 6 Girvan, Michelle, and Mark EJ Newman. "Community structure in social and biological networks." Proceedings of the national academy of sciences 99.12 (2002): 7821-7826.